

# **HEIDENHAIN**





## **TNC7** series

Overview of the Machine Parameters, Error Numbers and System Data

NC Software 81762x-19

English (en) 09/2024

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#### 1 About this document

This document provides an overview of the following functions of the TNC7 series:

- Machine parameters of the MPs for setters application
- Preassigned error numbers of the FN 14: ERROR NC function (ISO: D14)
- System data readable with the FN 18: SYSREAD (ISO: D18) and SYSSTR NC functions

#### Have you found any errors or would you like to suggest changes?

We are continuously striving to improve our documentation for you. Please help us by sending your suggestions to the following e-mail address:

tnc-userdoc@heidenhain.de

## 2 Machine parameters

The following list shows the machine parameters that you can edit with the code number 123.

## 2.1 List of user parameters



Refer to your machine manual.

- The machine manufacturer can make additional machine-specific parameters available as user parameters, so that you can configure the functions that are available.
- The machine manufacturer can adapt the structure and contents of the user parameters. The display on your machine may be different.

epiction in the configuration editor MP number						
	Display					
		<b>CfgDisplayData</b> Settings for screen dis	splays	100800		
		<b>axisDisplay</b> Display sequ	ence and display rules for axes	100810		
		<u> </u>				
			<b>axisKey</b> Key name of an object in CfgAxis	100810. [Index].01501		
			name Axis designation	100810. [Index].01502		
			rule Display rule for the axis	100810. [Index].01503		
		<b>axisDisplayR</b> Display sequ	Ref ence and rules for REF display	100811		
		<u> </u>				
			<b>axisKey</b> Key name of an object in CfgAxis	100811. [Index].01501		
			name Axis designation	100811. [Index].01502		
			rule Display rule for the axis	100811. [Index].01503		
		<b>positionWinI</b> Type of posit	<b>Display</b> tion display in the position window	100803		
		statusWinDis Type of posit	splay tion display in the status display	100804		
		<b>axisFeedDis</b> Feed rate dis		100806		

n in the	configura	ation editor	MP number
		spindleDisplay	100807
		Display of spindle position in the position display	
		hidePresetTable	100808
		Disable the PRESET MANAGEMENT soft key	
		displayFont	100812
		Font size for program display	
		iconPrioList	100813
	_	Sequence of icons in the display	
		compatibilityBits	100815
		Settings for display behavior	
		axesGridDisplay	100806
		Axes as list or group in the position display.	
		dashbrdWinDisplay	100817
		Type of position display in the status overview of the TNC bar	
	CfgPos	sDisplayPace	101000
	Display	step for the individual axes	
		xx	
		displayPace	101001
		Display step for position display in [mm] or [°]	
		displayPaceInch	101002
		Display step for position display in [inch]	
	CfgUni	itOfMeasure	101100
	Definiti	ion of unit of measure in effect for display	
		unitOfMeasure	101101
		Unit of measure for display and user interface	
	•	ogramMode	101200
	Forma	t of the NC programs and cycle display	
		programInputMode	101201
		MDI: Program entry in HEIDENHAIN Klartext format or ISO format	
	CfgDis	playLanguage	101300
	Definiti	ion of the NC and PLC conversational language	
		ncLanguage	101301
		NC conversational language	
		applyCfgLanguage	101305
		Load the language of the NC control	
		plcDialogLanguage	101302
		PLC conversational language	
		plcErrorLanguage	101303
		PLC error message language	

ion in the	MP number	
	helpLanguage	101304
	Language for online help	
	CfgStartupData	101500
	Behavior during control startup	
	powerInterruptMsg	101501
	Acknowledge the Power interrupted message	
	opMode	101503
	Operating mode that is switched to when the control has fully booted	
	subOpMode	101504
	Submode to be activated for the operating mode entered in 'opMode'	
	CfgClockView	120600
	Display mode for time of day	
	displayMode	120601
	Selection of a display mode for the time of day	
	timeFormat	120602
	Time format of digital clock	
	CfgInfoLine	120700
	Link row on/off	
	infoLineEnabled	120701
	Display settings for link row	
<u></u>	CfgGraphics	124200
	Settings for 3D simulation graphics	
	modelType	124201
	Model type of the 3D simulation graphics	
	modelQuality	124202
	Model quality of the 3D simulation graphics	12 1202
	clearPathAtBlk	124203
	Reset tool paths for new BLK FORM	. 2 . 2 0
	extendedDiagnosis	124204
	Write graphics journal files after restart	12 120 1
<u></u>	CfgPositionDisplay	124500
	Settings for the digital readout	12 1000
	progToolCallDL	124501
	Position display with TOOL CALL DL	124301
		125200
	CfgTableEditor  Table editor configuration	125300
	•	105001
	deleteLoadedTool	125301
	Behavior when deleting tools from the pocket table	105000
	indexToolDelete	125302

in the	configura	ation editor	MP number
	CfgDis	127500	
	Setting	g the coordinate systems for the display	
		transDatumCoordSys	127501
		Coordinate system for the datum shift	
	CfgGlo	balSettings	128700
	GPS di	isplay settings	
		enableOffset	128702
		Offset can/can't be selected in GPS dialog	
		enableBasicRot	128703
		Additive basic rotation can/can't be selected in GPS	
		dialog	100701
		enableShiftWCS	128704
		Shift of W-CS can/can't be selected in GPS dialog	
		enableMirror	128712
		Mirroring can/can't be selected in GPS dialog	
		enableShiftMWCS	128711
		Shift of mW-CS can/can't be selected in GPS dialog	
		enableRotation	128707
		Rotation can/can't be selected in GPS dialog	
		enableFeed	128708
		Feed rate can/can't be selected in GPS dialog	
		enableHwMCS	128709
		Show/Hide M-CS coordinate system	100710
		enableHwWCS	128710
		Show/Hide W-CS coordinate system	100711
		enableHwMWCS	128711
		Show/Hide mW-CS coordinate system	400740
		enableHwWPLCS	128712
		Show/Hide WPL-CS coordinate system	100700
		enableHwAxisU	128709
		U axis can/can't be selected in GPS dialog	100700
		enableHwAxisV	128709
		V axis can/can't be selected in GPS dialog	100700
		enableHwAxisW	128709
_	Of D	W axis can/can't be selected in GPS dialog	100000
	_	moteDesktop gs for Remote Desktop connections	100800
	Jettii lü	<u>'</u>	122501
		<b>connections</b> List of Remote Desktop connections to be displayed	133501
			122505
		autoConnect Start connection automatically	133505

on in the	configura	tion edit	tor		MP number	
		title			133502	
		Name	of the OE	EM operating mode		
			dialog	Res	133502.00501	
			Name	of a text		
			text		00502	
			Langu	age-sensitive text		
		icon			133503	
	_	Path/r	name for	optional icon graphic file		
		locatio	ons		133504	
	_	List wi	th positio	ons where this Remote Desktop		
		conne	ction is d	isplayed		
			X			
				opMode	133504.	
			_ <b>_</b>	Operating mode	[Index].133401	
				subOpMode	133504.	
				Optional submode for the operating	[Index].133402	
				mode specified in 'opMode'		
PalletS	PalletSettings					
	_	etBehav			202100	
	Behavio	or of the	pallet co	ntrol cycle		
		failed(	CheckRe	act	202106	
		Activa	te reactio	n to program check and tool check		
		failed(	CheckIm	pact	202107	
		Effect	of progra	ım check or tool check		
Probes	Settings					
	CfgTT				122700	
_	Configu	ıration o	f the tool	calibration		
		TT140	)_x			
			spindl	eOrientMode	122704	
			M fund	ction for spindle orientation		
			probin	gRoutine	122705	
			_	ng routine		
			probin	ngDirRadial	122706	
			_	ng direction for tool radius measure-		
			ment			
			offset	ToolAxis	122707	
		_		ce from lower edge of tool to upper of stylus		
			rapidF		122708	
			-	traverse in probing cycle for TT tool		
			touch			

n in the	configuration editor		MP number
		probingFeed	122709
		Probing feed rate during tool measurement	
		probingFeedCalc	122710
		Calculation of the probing feed rate	
		spindleSpeedCalc	122711
	· · · · · · · · · · · · · · · · · · ·	Speed determination method	
		maxPeriphSpeedMeas	122712
	<del>-</del>	Maximum permissible surface speed on the tool cutting edge	
		maxSpeed	122714
	_	Maximum permissible speed during tool measurement	
		measureTolerance1	122715
	_	Maximum permissible measurement error during tool measurement	
		measureTolerance2	122716
	_	Maximum permissible measurement error during tool measurement	
		stopOnCheck	122717
		NC stop during tool check	
		stopOnMeasurement	122718
		NC stop during tool measurement	
		adaptToolTable	122719
		Change the tool table during tool check and tool measurement	
	CfgTTRoundStyl	ıs	114200
_	Configuration of a		
	TT140_)	(	
		centerPos	114201
		Coordinates of the probe-contact center	
		point	
		safetyDistToolAx	114203
		Set-up clearance above the stylus for pre- positioning	
		safetyDistStylus	114204
	_	Safety zone around the stylus for prepositioning	
<u></u>	CfgTTRectStylus	· · · · · · · · · · · · · · · · · · ·	114300
	-	a rectangular stylus	
	ر_TT140		
		centerPos	114313
	_	Coordinates of the probe-contact center point	

on in the	contigura	uration editor				
			safetyDistToolAx	114317		
			Set-up clearance above the stylus for pre- positioning			
			safetyDistStylus	114318		
		_ <del>_</del>	Safety zone around the stylus for pre- positioning			
Chanr	nelSettings	<b>i</b>				
	CH_xx					
		-	tivateKinem	204000		
		Active	kinematics			
			kinemToActivate	204001		
			Kinematics to be activated			
			kinemAtStartup	204002		
			The kinematics to be activated during control start-up			
		CfgNc	PgmBehaviour PgmBehaviour	200800		
		Specify	y the behavior of the NC program.			
			operatingTimeReset	200801		
		_	Reset the machining time when program starts.			
			plcSignalCycle	200803		
			PLC signal for the number of the pending machining cycle			
			plcSignalCycState	200805		
			PLC signal for type of current cycle execution			
		_	oTolerance	200900		
		Geome	etry tolerances			
			circleDeviation	200901		
			Permissible deviation of the radius	000000		
			threadTolerance	200902		
			Permissible deviation in successive threads	000000		
			moveBack	200903		
			Reserve for retraction movements	004-7-1		
		_	oCycle	201000		
		Config	uration of the fixed cycles			
			pocketOverlap	201001		
			Overlap factor for pocket milling			
			posAfterContPocket	201007		
			Traverse after machining the contour pocket			
			displaySpindleErr	201002		
			Display the Spindle? error message if M3/M4 is not active			

n in the configura	ation edi	tor	MP number
		<b>displayDepthErr</b> Display the Enter depth as negative error message	201003
		apprDepCylWall  Behavior when moving to wall of slot in the cylinder surface	201004
		mStrobeOrient  M function for spindle orientation in the machining cycles	201005
		<b>suppressPlungeErr</b> Do not show 'Plunging type is not possible' error message	201006
		restoreCoolant Behavior of M7 and M8 with Cycles 202 and 204	201008
		<b>facMinFeedTurnSMAX</b> Automatic feed rate reduction after attaining SMAX	201009
		suppressResMatlWar  Do not show "Residual material" warning	201010
	-	readSpindle al spindle parameters for threads	113600
		<b>sourceOverride</b> Potentiometer for feed rate during thread cutting	113603
		thrdWaitingTime Waiting time at reversal point in thread base	113601
		thrdPreSwitchTime Advanced switching time of spindle	113602
		<b>limitSpindleSpeed</b> Limit of spindle speed with Cycles 17, 207, and 18	113604
<b>CfgEditorSettin</b> Settings for the	_	or	105400
	Backup ate backu	up file	105401
<b>delete</b> Behavi		cursor after deletion of lines	105402
lineBre		IC blocks with more than one line	105404
stdTN/ Activat	-	raphics when entering cycle data	105405
	gAtDEL	rompt when deleting a block	105407

n in the	e configuration editor	MP number
	maxLineGeoSearch	105408
	Line number up to which a test of the NC program is to be run	
	blockIncrement	105409
	ISO programming: Block number increment	
	useProgAxes	105410
	Specify programmable axes	
	enableStraightCut	105411
	Behavior of paraxial positioning blocks	
	noParaxMode	105413
	Hide FUNCTION PARAXCOMP/PARAXMODE	
	quotePaths	105414
	Put all path information in quotation marks	
CfgP	gmMgt	122100
	ngs for the file management	
	dependentFiles	122101
	Display of dependent files	
CfgPı	rogramCheck	129800
_	ngs for tool-usage files	
	autoCheckTimeOut	129803
	Timeout for creation of tool-usage files	
	autoCheckPrg	129801
	Create tool-usage file for NC program	
	autoCheckPal	129802
	Create pallet-usage files	
CfgUs	serPath	102200
•	s for the end user	
	ncDir	102201
	List of drives and/or directories	
	fn16DefaultPath	102202
	FN 16-Ausgabepfad for execution	
	fn16DefaultPathSim	102203
	FN 16 output path for the Programming and Test Run operat-	
	ing modes	
serial	InterfaceRS232	<del></del>
	CfgSerialPorts	106600
	Data record belonging to the serial port	<del>-</del>
	activeRs232	106601
	Enable the RS-232 interface in the program manager	
	baudRateLsv2	106606
	Data transfer rate for LSV2 communication in baud	. 5 5 5 5 5
	CfgSerialInterface	106700
	Definition of data records for the serial ports	100700

on in t	he configura	ition edito	or	MP number
		RSxxx		
			baudRate	106701
		_	Data transfer rate in baud	
			protocol	106702
		_	Communications protocol	
			dataBits	106703
			Data bits in each transferred character	
			parity	106704
		_	Type of parity checking	
			stopBits	106705
			Number of stop bits	
			flowControl	106706
			Specify type of handshake	
			fileSystem	106707
			File system for file operation via serial interface	
			bccAvoidCtrlChar	106708
			No control character in Block Check Character (BCC)	
			rtsLow	106709
		_	Idle state of the RTS line	
			noEotAfterEtx	106710
			Behavior after reception of an ETX	
Mo	nitoring			
	CfgCo	mpMonUs	ser	129400
	User se	ettings for	component monitoring	
		enforce	eReaction	129401
	_	The cor	nfigured error reactions are enforced	
		showW	/arning	129402
	_	Display	warnings of monitoring tasks	
<u></u>	CfgPro	cMonUse	er	141600
	User se	ettings for	process monitoring	
		permit/	AutoExport	141601
	<u> </u>	Automa	atic export allowed	
	CfgPro	cMonSna	aps	140600
	Monito	ring task	templates	
		snapsh	nots	140601
		List of r	monitoring task templates	
			x	
			alias	000.140402
			Name of the monitoring task template	

n	in the configuration editor				MP number
		task			000.140401
	_	Key of	monitori	ng task	
		useAs	Default		000.140405
				for new monitoring	
_		sectio			000.140403
		<b>param</b> Monito		<pre>c parameters</pre>	000.140403
_		rionic	X	· parametero	
-				name	000.05101
				Parameter name	
				value	000.05102
				Parameter value	
		reacti	ons		000.140404
		Monit	oring task	reactions	
			X		
				reactionKey	000.05201
				Key of the	
				reaction enabled	000.05202
_				enabled	
	Congress information of the machine	oporot	or		131700
_	General information of the machine  machineNickname	operat	OI		131701
	Custom name (nickname)	of the r	machine		131/01
-	inventoryNumber	01 (110 1	Tideriiiie		131702
	Inventory number or ID				101702
-	image				131703
	Photo or image of the made	hine			
	location				131704
	Machine location				
	department				131705
_	Department or division				
	responsibility				131706
	Responsible for the machi	ne			
	contactEmail				131707
_	Contact email address				101700
	contact Phone Number				131708
	Contact phone number				

## 2.2 Details about the user parameters



Explanations about the detailed view of user parameters:

- The indicated path corresponds to the machine parameter structure that you see after entering the machine manufacturer code number. With this information you can also find the desired machine parameter in the alternative structure. With the machine parameter numbers you can search for the machine parameters independently of the structure.
- Data objects are not intended for configuration; instead, they structure or group the machine parameters.
- The entry after iTNC shows the machine parameter number on the iTNC 530.

#### 2.2.1 DisplaySettings

CfgDisplayData	100800
Settings for scre	en displays
Path:	System ▶ DisplaySettings ▶ CfgDisplayData
Data objec	t:
axisDisplay	100810
Display sequence	e and display rules for axes
Path:	System ► DisplaySettings ► CfgDisplayData ► axisDisplay
Input:	Specifies the sequence and the rules for the display of axes. The top-most entry corresponds to the top-most position.
axisKey	100810. [Index].01501
Key name of an o	object in CfgAxis
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ axisDisplay ▶ [Index] ▶ axisKey
Input:	Specifies the key name of an object under CfgAxis whose position is to be displayed.

name	100810. [Index].01502
Axis designation	
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ axisDisplay ▶ [Index] ▶ name
Input:	max. 2 Characters
	Specifies the axis designation that is to appear instead of the key of the axis in the display. The alternative is the key of the axis.
rule	100810. [Index].01503
Display rule for the	axis
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ axisDisplay ▶ [Index] ▶ rule
Input:	Defines the condition under which the axis is displayed.
	ShowAlways
	Axis is always shown. The display location remains reserved even if no values for the axis can be displayed, for example if the axis is not contained in the current kinematic model.
	IfKinem
	Axis is shown only if it is used as an axis or a spindle in the active kinematic model.
	IfKinemAxis
	Axis only shown if used as axis in the active kinematics model.
	IfNotKinemAxis
	The axis is only shown if it is not used as an axis in the active kinematics model (e.g. as spindle).
	Never
	The axis is not shown.

axisDispla	ıyRef		100811
Display se	quence and	rules for REF display	
Path	1:	System ► DisplaySettings ► CfgDisplayData ► axisDisplayRef	
Inpu	t:	Specifies the sequence and the rules for the display if the position display is set to REF values (also app when traversing the reference points). If this list is ethe entries from the machine parameter <b>axisDisplay</b> be used. The top-most entry corresponds to the top position.	lies empty, <b>y</b> will

axisKey			100811. [Index].01501
Key name	of an obje	ect in CfgAxis	
Path	•	System ► DisplaySettings ► CfgDisplayData axisDisplayRef ► [Index] ► axisKey	<b>&gt;</b>
Input	t:	Specifies the key name of an object under Cfg position is to be displayed.	gAxis whose
name			100811. [Index].01502
Axis design	nation		
Path	•	System ► DisplaySettings ► CfgDisplayData axisDisplayRef ► [Index] ► name	<b>&gt;</b>
Input	t:	max. 2 Characters	
		Specifies the axis designation that is to appear the key of the axis in the display. The alternatiof the axis.	
rule			100811. [Index].01503
Display rule	e for the a	xis	
Path	•	System ► DisplaySettings ► CfgDisplayData axisDisplayRef ► [Index] ► rule	<b>&gt;</b>
Input	t:	Specifies the condition for displaying the axis.	
		ShowAlways	
		Axis is always shown. The display location rer reserved even if no values for the axis can be example if the axis is not contained in the curr model.	displayed, for
		IfKinem	
		Axis is shown only if it is used as an axis or a active kinematic model.	spindle in the
		IfKinemAxis	
		Axis only shown if used as axis in the active ki model.	inematics
		IfNotKinemAxis	
		The axis is only shown if it is not used as an a active kinematics model (e.g. as spindle).	xis in the
		Never	
		The axis is not shown.	

positionWinDisplay		100803
Type of position disp	lay in the position window	
Path:	System ► DisplaySettings ► CfgDisplayData ► positionWinDisplay	
Input:	Position display in the position window (positions display 1):  NOML.  Nominal position	
	ACTL Actual position	
	REF ACTL Actual position referenced to the machine datum REF NOML Nominal position referenced to the machine datum	
	Following error (servo lag)  ACTDST  Distance-to-go in the input system  REFDST  Distance-to-go in the machine system  M118  Traverse paths that were carried out with handwheel	el suner-
	impositioning (M118)	oupei

**statusWinDisplay** 100804

Type of position of	display in the status display
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ statusWinDisplay
Input:	Position display in the status window (position display 2)
	NOML.
	ACTL
	REF ACTL
	REF NOML
	LAG
	ACTDST
	REFDST
	M118

axisFeedDisplay	the Manual operation / Fleetranic handwheel operating mode
	the Manual operation / Electronic handwheel operating mode
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ axisFeedDisplay
Input:	At axis key:
	Display of axis feed rate through pressing an axis direction key (axis-specific feed rate from MP_CfgFeedLimits/manualFeed.
	always minimum:
	Display of the feed rate for all axes, including before an axis direction key is pressed (lowest value from MP_CfgFeedLimits/ <b>manualFeed</b> ).
iTNC 530:	7270
spindleDisplay	100807
Display of spindle po	osition in the position display
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ spindleDisplay
Input:	during closed loop
	Display of spindle position only if the spindle is servo- controlled
	during closed loop and M5
	Display of spindle position if the spindle is servo-controlled and an M5 is pending
	during closed loop or M5 or tapping
	Display of spindle position if the spindle is servo-controlled or if an M5 is pending, or during a tapping operation
hidePresetTable	100808
Disable the <b>PRESET</b>	MANAGEMENT soft key
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ hidePresetTable
Input:	TRUE
	Access to the preset table is locked; the soft key is dimmed <b>FALSE</b>

The preset table can be accessed via soft key

displayFont		100812
Font size for prog	ram display	
Path:	System ► DisplaySettings ► CfgDisplayData ► displayFont	
Input:	FONT_APPLICATION_SMALL	
	Small font size.	
	FONT_APPLICATION_MEDIUM	
	Big font size.	
iconPrioList		100813
Sequence of icons	s in the display	
Path:	System ► DisplaySettings ► CfgDisplayData ► iconPrioList	
Input:	BASIC_ROT	
	ROT_3D	
	ТСРМ	
	ACC	
	TURNING	
	AFC	
	S_PULSE	
	MIRROR	
	GPS	
	RADCORR	
	PARAXCOMP	
	MON_FS_OVR	

com	patibilityBits		100815
Setti	ngs for display be	ehavior	
	Path:	System ► DisplaySettings ► CfgDisplayData ► compatibilityBits	
	Input:	Bit	

axesGridDisplay		100816
Axes as list or grou	p in the position display.	
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ axesGridDisplay	
Input:	The parameter specifies whether the axes in the podisplay are shown as a list or as a two-column gric Possible settings: 0 to	
	0	
	Axis display as list (default)	
	Quantity (n)	
	Axis display as two-column grid with groups of n x	2 axes
iTNC 530:	7270	
dashbrdWinDisplay	1	100817
Type of position dis	play in the status overview of the TNC bar	
Path:	System ▶ DisplaySettings ▶ CfgDisplayData ▶ dashbrdWinDisplay	
Input:	NOML	
	ACTL	
	REF ACTL	
	REF NOML	
	LAG	
	ACTDST	
	REFDST	
	M118	
CfgPosDisplayPac	e	101000
Display step for the	individual axes	
Path:	System ► DisplaySettings ► CfgPosDisplayPace	
Data object:		

olayPace	::: 1: 1 : [ ] [0]	
	ition display in [mm] or [°]	
Path:	System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPace	
Input:	0.1	
	0.05	
	0.01	
	0.005	
	0.001	
	0.0005	
	0.0001	
	0.00005	
	0.00001	
	0.000005	
	0.000001	
·=		
iTNC 530:  blayPaceInch  blay step for posi	7290.0-8  10  ition display in [inch]	0100
olayPaceInch	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶	0100
playPaceInch play step for posi Path:	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch	0100
playPaceInch	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶	0100
playPaceInch play step for posi Path:	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch  0.005	0100
playPaceInch play step for posi Path:	ition display in [inch]  System ► DisplaySettings ► CfgPosDisplayPace ► [Key name of the axis] ► displayPaceInch  0.005  0.001	0100
playPaceInch play step for posi Path:	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch  0.005  0.001  0.0005	D1002
playPaceInch play step for posi Path:	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch  0.005  0.001  0.0005  0.0001	0100
playPaceInch play step for posi Path:	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch  0.005  0.001  0.0005  0.0001  0.00005	01002
playPaceInch play step for posi Path:	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch  0.005  0.001  0.0005  0.0001  0.00005  0.00001	01002
playPaceInch play step for posi Path:	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch  0.005  0.001  0.0005  0.0001  0.00005  0.00001	0100:
playPaceInch play step for posi Path: Input:	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch  0.005  0.001  0.0005  0.0001  0.00005  0.00001  7290.0-8	
playPaceInch play step for posi Path: Input:  iTNC 530:  UnitOfMeasure	ition display in [inch]  System ▶ DisplaySettings ▶ CfgPosDisplayPace ▶ [Key name of the axis] ▶ displayPaceInch  0.005  0.001  0.0005  0.0001  0.00005  0.00001  7290.0-8	011002

unitOfMeasure		101101
Unit of measure for o	display and user interface	
Path:	System ► DisplaySettings ► CfgUnitOfMeasure ► unitOfMeasure	
Input:	metric	
	Metric measurement system	
	inch	
	Inches	
CfgProgramMode		101200
Format of the NC pro	ograms and cycle display	
Path:	System ▶ DisplaySettings ▶ CfgProgramMode	
Data object:		
programInputMode		101201
MDI: Program entry i	n HEIDENHAIN Klartext format or ISO format	
Path:	System ▶ DisplaySettings ▶ CfgProgramMode ▶ programInputMode	
Input:	HEIDENHAIN	
	Program entry with HEIDENHAIN Klartext	
	ISO	
	Program entry according to ISO	
CfgDisplayLanguage	e	101300
Definition of the NC a	and PLC conversational language	
Path:	System ► DisplaySettings ► CfgDisplayLanguage	
Data object:		

onversational	language
Path:	System ▶ DisplaySettings ▶ CfgDisplayLanguage ▶ ncLanguage
Input:	ENGLISH
	GERMAN
	CZECH
	FRENCH
	ITALIAN
	SPANISH
	PORTUGUESE
	SWEDISH
	DANISH
	FINNISH
	DUTCH
	POLISH
	HUNGARIAN
	JAPANESE
	RUSSIAN
	CHINESE
	CHINESE_TRAD
	SLOVENIAN
	KOREAN
	NORWEGIAN
	ROMANIAN
	SLOVAK
	TURKISH

applyCfgLanguage	101305

appryCrgLangua	je iuis	,00
Load the languag	e of the NC control	
Path:	System ▶ DisplaySettings ▶ CfgDisplayLanguage ▶ applyCfgLanguage	
Input:	When booting, the control checks whether the language settings of the operating system and the NC are the same If the settings differ, the NC applies the language setting of the operating system. If the language defined in the machine parameters of the NC is to be used, then you muthe set the parameter applyCfgLanguage to TRUE.	

	and the form	
uppress the Resta	-	
Path:	System ▶ DisplaySettings ▶ CfgDisplayLanguage ▶ noRebootDialog	
Input:	If this attribute is set to TRUE, the Restart dialog will not appear after changing the language.	
lcDialogLanguage	1013	02
LC conversational	language	
Path:	System ▶ DisplaySettings ▶ CfgDisplayLanguage ▶ plcDialogLanguage	
Input:	ENGLISH	
	GERMAN	
	CZECH	
	FRENCH	
	ITALIAN	
	SPANISH	
	PORTUGUESE	
	SWEDISH	
	DANISH	
	FINNISH	
	DUTCH	
	POLISH	
	HUNGARIAN	
	JAPANESE	
	RUSSIAN	
	CHINESE	
	CHINESE_TRAD	
	SLOVENIAN	
	KOREAN	
	NORWEGIAN	
	ROMANIAN	
	SLOVAK	
	TURKISH	

olcErrorLanguage		101303
PLC error message la	anguage	
Path:	System ▶ DisplaySettings ▶ CfgDisplayLanguage plcErrorLanguage	<b>&gt;</b>
Input:	ENGLISH	
	GERMAN	
	CZECH	
	FRENCH	
	ITALIAN	
	SPANISH	
	PORTUGUESE	
	SWEDISH	
	DANISH	
	FINNISH	
	DUTCH	
	POLISH	
	HUNGARIAN	
	JAPANESE	
	RUSSIAN	
	CHINESE	
	CHINESE_TRAD	
	SLOVENIAN	
	KOREAN	
	NORWEGIAN	
	ROMANIAN	
	SLOVAK	
	TURKISH	
iTNC 530:	7230.2	

helpLanguage

101304

Language for online	e help	
Path:	System ► DisplaySettings ► CfgDisplayLang helpLanguage	juage ▶
Input:	ENGLISH	
	GERMAN	
	CZECH	
	FRENCH	
	ITALIAN	
	SPANISH	
	PORTUGUESE	
	SWEDISH	
	DANISH	
	FINNISH	
	DUTCH	
	POLISH	
	HUNGARIAN	
	JAPANESE	
	RUSSIAN	
	CHINESE	
	CHINESE_TRAD	
	SLOVENIAN	
	KOREAN	
	NORWEGIAN	
	ROMANIAN	
	SLOVAK	
	TURKISH	
iTNC 530:	7230.3	
CfgStartupData		101500
Behavior during cor	ntrol startup	

System ► DisplaySettings ► CfgStartupData

Path:

Data object:

powerInterruptMsg		101501
Acknowledge the <b>Pc</b>	ower interrupted message	
Path:	System ▶ DisplaySettings ▶ CfgStartupData ▶ powerInterruptMsg	
Input:	TRUE	
	Start-up is only continued after the message has b acknowledged.	een
	FALSE	
	The <b>Power interrupted</b> message does not appear	r
opMode		101503
Operating mode tha	t is switched to when the control has fully booted	
Path:	System ▶ DisplaySettings ▶ CfgStartupData ▶ o	pMode
Input:	Enter here the GUI designator of the desired operamode. See the Technical Manual for an overview opermissible GUI designators. max. 500 Characters	f the
subOpMode		101504
Submode to be acti	vated for the operating mode entered in 'opMode'	
Path:	System ▶ DisplaySettings ▶ CfgStartupData ▶ subOpMode	
Input:	Enter here the GUI designator of the desired operasubmode. See the Technical Manual for an overvie permissible GUI designators. max. 500 Characters	w of the
CfgClockView		120600
Display mode for tin	ne of day	
Path:	System ► DisplaySettings ► CfgClockView	
Data object:		

displayMode		120601
Display mode for tin	ne of day on the screen	
Path:	System ▶ DisplaySettings ▶ CfgClockView ▶ dis	playMode
Input:	Analog	
	Analog clock	
	Digital	
	Digital clock	
	Logo	
	OEM logo	
	Analog and logo	
	Analog clock and OEM logo	
	Digital and logo	
	Digital clock and OEM logo	
	Analog on logo	
	Analog clock that superimposes the OEM logo	
	Digital on logo	
	Digital clock that superimposes the OEM logo	
imeFormat		120602
Fime format of digit	al clock	
Path:	System ▶ DisplaySettings ▶ CfgClockView ▶ tim	neFormat
Input:	Possible settings:	
ļ	12 h format	
	Time in 12 hours format	
	24 h format	
	Time in 24 hours format	
CfgInfoLine		120700
_ink row on/off		120700
Path:	System ▶ DisplaySettings ▶ CfgInfoLine	
Data object:	System P DisplaySettings P OrginoLine	
nfoLineEnabled		120701
Enable/disable info	ine	
Path:	System ▶ DisplaySettings ▶ CfgInfoLine ▶ infoLineEnabled	
Input:	OFF	
	The info line is disabled	
	ON	
	The info line below the operating mode display is e	enabled

CfgGraphics	124200
Settings for 3D sir	nulation graphics
Path:	System ► DisplaySettings ► CfgGraphics
Data object:	
modelType	124201
Model type of the	3D simulation graphics
Path:	System ► DisplaySettings ► CfgGraphics ► modelType
Input:	No Model
	The model depiction is deactivated. Only the 3D line graphics are shown (lowest processor load, e.g. for fast testing of the NC program and ascertainment of program run times)
	3D
	Model depiction for complex operations (highest processor load, e.g. for turning or undercuts)
	2.5D
	Model depiction for 3-axis operations (medium processor load)
modelQuality	124202
Model quality of th	ne 3D simulation graphics
Path:	System ► DisplaySettings ► CfgGraphics ► modelQuality
Input:	very high
	Very high model quality, the production result can be precisely judged. This setting requires the highest computing power.
	Block numbers and block end points can only be displayed in the 3D line graphics with this setting.

high

low

medium

High model quality

Low model quality

Medium model quality

) 4 4 1 ··· · 4 !·· · · · ·	DLIZ FODM	
Reset tool paths for		
Path:	System ▶ DisplaySettings ▶ CfgGraphics ▶ clearPathAtBlk	
Input:	ON	
	With a new BLK FORM in the Test Run graphic, the tool paths are reset	
	OFF	
	With a new BLK FORM in the Test Run graphic, the tool paths are not reset	
extendedDiagnosis	1242	204
Write graphics journ	al files after restart	
Path:	System ▶ DisplaySettings ▶ CfgGraphics ▶ modelType	
Input:	Activate diagnostic information for HEIDENHAIN (journal files) for the analysis of graphics problems.	
	OFF	
	Do not create journal files (default).	
	· · · ·	
	ON	
	· · · ·	
CfgPositionDisplay	ON	500
<b>OfgPositionDisplay</b> Settings for the digit	ON Create journal files.	500
<b>OfgPositionDisplay</b> Settings for the digit Path:	ON Create journal files.  1245 al readout	500
Settings for the digit	ON Create journal files.	500
Settings for the digit	ON Create journal files.  1245 al readout	500
Path:  Data object:	ON Create journal files.  1245 al readout	
Path:  Data object:  DrogToolCallDL	ON Create journal files.  1245 cal readout System ▶ DisplaySettings ▶ CfgPositionDisplay	
Path:  Data object:	ON Create journal files.  1245 cal readout System ▶ DisplaySettings ▶ CfgPositionDisplay	
Path:  Data object:  ProgToolCallDL  Position display with  Path:	ON Create journal files.  1245 Tal readout System ▶ DisplaySettings ▶ CfgPositionDisplay  1245 TOOL CALL DL System ▶ DisplaySettings ▶ CfgPositionDisplay ▶ progToolCallDL	
Path:  Data object:  ProgToolCallDL  Position display with	ON Create journal files.  1245 Cal readout System ▶ DisplaySettings ▶ CfgPositionDisplay  1245 TOOL CALL DL System ▶ DisplaySettings ▶ CfgPositionDisplay ▶	501
Path:  Data object:  ProgToolCallDL  Position display with  Path:	ON Create journal files.  1245  Tal readout  System ▶ DisplaySettings ▶ CfgPositionDisplay  1245  TOOL CALL DL  System ▶ DisplaySettings ▶ CfgPositionDisplay ▶ progToolCallDL  As Tool Length  The oversize DL programmed in the TOOL CALL block is taken into account as part of the tool length in the nominal	501

CfgTableEditor		
able editor configu	ration	
Path:	System ▶ TableSettings ▶ CfgTableEditor	
Data object:	Specifies properties and settings for the table editor	r.
leleteLoadedTool		125301
Behavior when delet	ting tools from the pocket table	
Path:	System ► TableSettings ► CfgTableEditor ► deleteLoadedTool	
Input:	Possible settings:  DISABLED	
	Tool deletion is not possible	
	WITH_WARNING	
	Tool deletion is possible; Note must be confirmed	
	WITHOUT_WARNING	
	<del>-</del>	
iTNC 530:	Tool deletion is possible without confirmation 7263 Bit4, 7263 Bit5	
ndexToolDelete	Tool deletion is possible without confirmation 7263 Bit4, 7263 Bit5	125302
ndexToolDelete Behavior when delet	Tool deletion is possible without confirmation 7263 Bit4, 7263 Bit5  ting a tool's index entries	125302
ndexToolDelete	Tool deletion is possible without confirmation 7263 Bit4, 7263 Bit5	125302
ndexToolDelete Behavior when delet	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶	125302
ndexToolDelete Behavior when delet Path:	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶ indexToolDelete	125302
ndexToolDelete Behavior when delet Path:	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶ indexToolDelete  Possible settings:  ALWAYS_ALLOWED  Deletion of index entries is always possible	125302
ndexToolDelete Behavior when delet Path:	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶ indexToolDelete  Possible settings:  ALWAYS_ALLOWED  Deletion of index entries is always possible  TOOL_RULES	
ndexToolDelete Behavior when delet Path:	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶ indexToolDelete  Possible settings:  ALWAYS_ALLOWED  Deletion of index entries is always possible	
ndexToolDelete Behavior when delet Path:	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶ indexToolDelete  Possible settings:  ALWAYS_ALLOWED  Deletion of index entries is always possible  TOOL_RULES  Behavior depends on the setting of the parameter of	
ndexToolDelete Behavior when delete Path: Input:	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶ indexToolDelete  Possible settings:  ALWAYS_ALLOWED  Deletion of index entries is always possible  TOOL_RULES  Behavior depends on the setting of the parameter of LoadedTool  7263 Bit6	125302 delete-
ndexToolDelete  Behavior when delete Path: Input:  iTNC 530:  CfgDisplayCoordSy	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶ indexToolDelete  Possible settings:  ALWAYS_ALLOWED  Deletion of index entries is always possible  TOOL_RULES  Behavior depends on the setting of the parameter of LoadedTool  7263 Bit6	delete-
ndexToolDelete  Behavior when delete Path: Input:  iTNC 530:  CfgDisplayCoordSy	Tool deletion is possible without confirmation  7263 Bit4, 7263 Bit5  ting a tool's index entries  System ▶ TableSettings ▶ CfgTableEditor ▶ indexToolDelete  Possible settings:  ALWAYS_ALLOWED  Deletion of index entries is always possible  TOOL_RULES  Behavior depends on the setting of the parameter of LoadedTool  7263 Bit6	delete-

nsDatumCoordSys		127501
ordinate system fo	r the datum shift	
Path:	System ► DisplaySettings ► CfgDisplayCoordSys transDatumCoordSys	<b>&gt;</b>
Input:	The parameter specifies the coordinate system in v datum shift is displayed.	vhich the
	WorkplaneSystem	
	Datum is displayed in the system of the tilted plane CS)	(WPL-
	WorkpieceSystem	
	Datum is displayed in the workpiece coordinate sys CS)	stem (W-
gGlobalSettings		128700
PS display settings		
Path:	System ▶ DisplaySettings ▶ CfgGlobalSettings	
Data object:		
ableOffset		128702
fset can/can't be se	elected in GPS dialog	
Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableOffset	
Input:	OFF	
	Offset can't be selected (grayed out)	
	ON	
	Offset can be selected	
ableBasicRot		128703
Iditive basic rotation	n can/can't be selected in GPS dialog	
Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableBasicRot	
Input:	OFF	
	Additive basic rotation can't be selected (grayed ou <b>ON</b>	t)
	Additive basic rotation can be selected	
	ON	ou

enableShiftWCS	can't be selected in GPS dialog	
Path:	System ► DisplaySettings ► CfgGlobalSettings ►	
- au і.	enableShiftWCS	
Input:	OFF	
	Shift of W-CS (workpiece coordinate system) can't be selected (grayed out)	oe
	ON	
	Shift of W-CS (workpiece coordinate system) can be ed	e select-
enableMirror		128705
Mirroring can/can't	be selected in GPS dialog	
Path:	System ► DisplaySettings ► CfgGlobalSettings ► enableMirror	
Input:	OFF	
	Mirroring can't be selected (grayed out)	
	ON	
	Mirroring can be selected	
	Mirroring can be selected	
enableShiftMWCS	Mirroring can be selected	128706
	Mirroring can be selected	128706
		128706
Shift of mW-CS car	n/can't be selected in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶	128706
Shift of mW-CS car Path:	n/can't be selected in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableShiftMWCS	
Shift of mW-CS car Path:	n/can't be selected in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableShiftMWCS  OFF  Shift of mW-CS (modified workpiece coordinate sys	
Shift of mW-CS car Path:	n/can't be selected in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableShiftMWCS  OFF  Shift of mW-CS (modified workpiece coordinate syscan't be selected (grayed out)	tem)
Shift of mW-CS car Path:	n/can't be selected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableShiftMWCS  OFF  Shift of mW-CS (modified workpiece coordinate syscan't be selected (grayed out)  ON  Shift of mW-CS (modified workpiece coordinate sys	item)
Path:  Input:  enableRotation	n/can't be selected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableShiftMWCS  OFF  Shift of mW-CS (modified workpiece coordinate syscan't be selected (grayed out)  ON  Shift of mW-CS (modified workpiece coordinate sys	item)
Path:  Input:  enableRotation	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableShiftMWCS  OFF  Shift of mW-CS (modified workpiece coordinate syscan't be selected (grayed out)  ON  Shift of mW-CS (modified workpiece coordinate syscan be selected)	·
Path: Path: Input:  PnableRotation Rotation can/can't	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableShiftMWCS  OFF  Shift of mW-CS (modified workpiece coordinate syscan't be selected (grayed out)  ON  Shift of mW-CS (modified workpiece coordinate syscan be selected)  be selected  be selected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤	item)
Path: Input:  Pathical Path:  Phistory of the path of the path:  Path:  Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableShiftMWCS  OFF  Shift of mW-CS (modified workpiece coordinate syscan't be selected (grayed out)  ON  Shift of mW-CS (modified workpiece coordinate syscan'be selected)  be selected  be selected  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableRotation	item) item)
Path: Input:  Pathical Path:  Phistory of the path of the path:  Path:  Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableShiftMWCS  OFF  Shift of mW-CS (modified workpiece coordinate system't be selected (grayed out)  ON  Shift of mW-CS (modified workpiece coordinate system be selected)  be selected  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableRotation  OFF	item) item)

 $HEIDENHAIN \mid TNC7 \ series \mid Overview \ of \ the \ Machine \ Parameters, Error \ Numbers \ and \ System \ Data \mid 09/2024$ 

ed rate can/can ti	be selected in GPS dialog
Path:	System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableFeed
Input:	OFF
	Feed rate can't be selected (grayed out)
	ON
	Feed rate can be selected
ableHwMCS	12870
ow/hide M-CS co	ordinate system in GPS dialog
Path:	System ► DisplaySettings ► CfgGlobalSettings ► enableHwMCS
Input:	OFF
	M-CS coordinate system (machine coordinate system) is not shown
	ON
	M-CS coordinate system (machine coordinate system) is shown
ableHwWCS	12871
	ordinate system in GPS dialog
ow/hide W-CS co	ordinate system in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶
ow/hide W-CS co Path:	ordinate system in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwWCS
ow/hide W-CS co Path:	ordinate system in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwWCS  OFF  W-CS coordinate system (workpiece coordinate system) is
ow/hide W-CS co Path:	ordinate system in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwWCS  OFF  W-CS coordinate system (workpiece coordinate system) is not shown
ow/hide W-CS co Path:	ordinate system in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwWCS  OFF  W-CS coordinate system (workpiece coordinate system) is not shown  ON  W-CS coordinate system (workpiece coordinate system) is
ow/hide W-CS co-Path: Input:	ordinate system in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwWCS  OFF  W-CS coordinate system (workpiece coordinate system) is not shown  ON  W-CS coordinate system (workpiece coordinate system) is shown
ow/hide W-CS co-Path: Input:	ordinate system in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwWCS  OFF  W-CS coordinate system (workpiece coordinate system) is not shown  ON  W-CS coordinate system (workpiece coordinate system) is shown
ow/hide W-CS co-Path: Input:  ableHwMWCS ow/hide mW-CS co-	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwWCS  OFF  W-CS coordinate system (workpiece coordinate system) is not shown  ON  W-CS coordinate system (workpiece coordinate system) is shown  12871  coordinate system in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤
ow/hide W-CS co-Path: Input:  ableHwMWCS ow/hide mW-CS co-Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwWCS  OFF  W-CS coordinate system (workpiece coordinate system) is not shown  ON  W-CS coordinate system (workpiece coordinate system) is shown  12871  coordinate system in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwMWCS
ow/hide W-CS co-Path: Input:  ableHwMWCS ow/hide mW-CS co-Path:	System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwWCS  OFF  W-CS coordinate system (workpiece coordinate system) is not shown  ON  W-CS coordinate system (workpiece coordinate system) is shown  12871  coordinate system in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwMWCS  OFF  mW-CS coordinate system (modified workpiece coordinate

Show/hide WPL-CS c	oordinate system in GPS dialog	
Path:	System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwWPLCS	
Input:	OFF	
	WPL-CS coordinate system (working plane coordinate system) is not shown	ate
	ON	
	WPL-CS coordinate system (working plane coordinate system) is shown	ate
enableHwAxisU		128713
J axis can/can't be se	elected in GPS dialog	
Path:	System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwAxisU	
Input:	OFF	
	U axis cannot be selected (grayed out)	
	ON	
	U axis can be selected	
enableHwAxisV		128714
/ axis can/can't be se	elected in GPS dialog	
/ axis can/can't be se Path:	elected in GPS dialog  System ▶ DisplaySettings ▶ CfgGlobalSettings ▶ enableHwAxisV	
	System ► DisplaySettings ► CfgGlobalSettings ►	
Path:	System ► DisplaySettings ► CfgGlobalSettings ► enableHwAxisV	
Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF	
Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ► enableHwAxisV  OFF  V axis cannot be selected (grayed out)	
Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON	128715
Path: Input: enableHwAxisW	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON	128715
Path: Input: enableHwAxisW	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON  V axis can be selected	128715
Path: Input: enableHwAxisW V axis can/can't be s	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON  V axis can be selected  elected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤	128715
Path: Input: enableHwAxisW V axis can/can't be s Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON  V axis can be selected  elected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisW	128715
Path: Input: enableHwAxisW V axis can/can't be s Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON  V axis can be selected  elected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisW  OFF	128715
Path: Input: enableHwAxisW V axis can/can't be s Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON  V axis can be selected  elected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisW  OFF  W axis cannot be selected (grayed out)	128715
Path: Input: enableHwAxisW V axis can/can't be s Path:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON  V axis can be selected  elected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisW  OFF  W axis cannot be selected (grayed out)  ON	
Path: Input:  PanableHwAxisW V axis can/can't be s Path: Input:	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON  V axis can be selected  elected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisW  OFF  W axis cannot be selected (grayed out)  ON  W axis can be selected	128715
Path: Input:  Path:  PableHwAxisW  Vaxis can/can't be s  Path:  Input:  CfgRemoteDesktop	System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisV  OFF  V axis cannot be selected (grayed out)  ON  V axis can be selected  elected in GPS dialog  System ➤ DisplaySettings ➤ CfgGlobalSettings ➤ enableHwAxisW  OFF  W axis cannot be selected (grayed out)  ON  W axis can be selected	

connections	13350
List of Remote Des	sktop connections to be displayed
Path:	System ► DisplaySettings ► CfgRemoteDesktop ► connections
Input:	Enter here the name of a RemoteFX connection from Remote Desktop Manager. max. 80 Characters
autoConnect	13350
Start connection a	utomatically
Path:	System ▶ DisplaySettings ▶ CfgRemoteDesktop ▶ autoConnect
Input:	TRUE
	Automatically connect when control boots
	FALSE
	Do not start connection automatically.
title	13350
Name of the OEM	operating mode
Path:	System ▶ DisplaySettings ▶ CfgRemoteDesktop ▶ title
Input:	Specifies the name of the OEM operating mode for display on the TNC and in the information bar.
dialogRes	133502.0050
Name of a text	
Path:	System ▶ DisplaySettings ▶ CfgRemoteDesktop ▶ title ▶ dialogRes
Input:	max. 64 Characters
	The text must be available with this name in a text resource file.
	If the text is not intended to be language-sensitive, leave machine parameter <b>dialogRes</b> (00501) empty. Then enter the text in the machine parameter <b>text</b> (00502).  Starting with software -17:
	If the text comes from a *.po file, the machine parameter <b>poDomain</b> (00504) must also be filled in.

text	00502
_anguage-sensiti	ve text
Path:	System ► DisplaySettings ► CfgRemoteDesktop ► title ► text
Input:	max. 60 Characters
	This text is loaded from a text resource file and should not be changed here.
	If the text is not language-specific, enter it here directly. In this case, do not enter anything in the machine parameter <b>dialogRes</b> (606202).
con	133503
Path/name for op	otional icon graphic file
Path:	System ▶ DisplaySettings ▶ CfgRemoteDesktop ▶ icon
Input:	max. 260 Characters
ocations	133504
_ist with positions	s where this Remote Desktop connection is displayed
Path:	System ▶ DisplaySettings ▶ CfgRemoteDesktop ▶ locations
Input:	
opMode	133504. [Index].133401
Operating mode	
Path:	System ▶ DisplaySettings ▶ CfgRemoteDesktop ▶ locations ▶ [Index] ▶ opMode
Input:	max. 80 Characters
subOpMode	133504 [Index].133402
Optional submod	e for the operating mode specified in 'opMode'
Path:	System ➤ DisplaySettings ➤ CfgRemoteDesktop ➤ locations ► [Index] ► subOpMode

## 2.2.2 PalletSettings

CfgPalletBehaviou	r	202100
Behavior of the pall	et control cycle	
Path:	System ▶ PalletSettings ▶ CfgPalletBehaviour	
Data object:		
failedCheckReact		202106
Specify reaction to	program check and tool check	
Path:	System ▶ PalletSettings ▶ CfgPalletBehaviour ▶ failedCheckReact	
Input:	Never	
	No checking for faulty program or tool calls.	
	OnFailedPgmCheck	
	Check for faulty program calls.	
	OnFailedToolCheck	
	Check for faulty tool calls.	
failedCheckImpact		202107
Specify effect of pro	ogram check or tool check	
Path:	System ▶ PalletSettings ▶ CfgPalletBehaviour ▶ failedCheckImpact	
Input:	SkipPGM	
	Skip faulty programs.	
	SkipFIX	
	Skip fixture setups that contain faulty programs.	
	SkipPAL	
	Skip pallets that contain faulty programs.	

## 2.2.3 ProbeSettings

CfgTT		122700
Configura	tion of the	e tool calibration
Path	h:	System ▶ ProbeSettings ▶ CfgTT
Data	a object:	
spindleOr	ientMode	122704
M function	n for spin	dle orientation
Path	h:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ spindleOrientMode
Inpu	ut:	-1 to 999
		<ul> <li>-1     Spindle orientation directly by NC</li> <li>0     Function inactive</li> </ul>
		1 to 999 Number of the M function for spindle orientation by the PLC
iTN	C 530:	MP6560
probingRo	outine	122705
Probing ro	outine	
Path	h:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ probingRoutine
Inpu	ut:	MultiDirections
		The probe contact is probed from several directions.
		SingleDirection
		The probe contact is probed from one direction.
iTN	C 530:	6500 Bit 8

probingDirRadial	122700
Probing direction for	or tool-radius measurement
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ probingDirRadial
Input:	X_Positive
	Y_Positive
	X_Negative
	Y_Negative
	Z_Positive
	Z_Negative
iTNC 530:	MP6505
offsetToolAxis	122707
Distance from lowe	er edge of tool to upper edge of stylus
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ offsetToolAxis
Input:	0.001 to 99.9999, max. 4 decimal places
iTNC 530:	MP6530
rapidFeed	122708
Rapid traverse in p	robing cycle for TT tool touch probe
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ rapidFeed
Input:	10 to 300000
iTNC 530:	MP6550
probingFeed	122709
Probing feed rate f	or tool measurement with non-rotating tool
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ probingFeed
Input:	1 to 3000
iTNC 530:	6520

Calculation of the p	probing food rate
·	-
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ probingFeedCalc
Input:	ConstantTolerance
	Calculation of the probing feed rate with constant tolerance
	VariableTolerance
	Calculation of the probing feed rate with variable tolerance
	ConstantFeed
	Constant probing feed rate
iTNC 530:	6507
spindleSpeedCalc	12271
Speed determination	on method
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ spindleSpeedCalc
Input:	Automatic
	Automatically determine speed
	MinSpindleSpeed
	Always use minimum spindle speed
iTNC 530:	6500 Bit4
maxPeriphSpeedM	leas 122712
Maximum permiss	ible surface speed of the cutting edge for radius measurement
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ maxPeriphSpeedMeas
Input:	1 to 129, max. 4 decimal places
iTNC 530:	6570
naxSpeed	12271
	ible speed during tool measurement
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ maxSpeed
Input:	0 to 1000

measureTolerance	<b>1</b> 1227
Maximum permissi (first measuring err	ble measuring error for tool measurement with rotating tool or)
Path:	System ► ProbeSettings ► CfgTT ► [Key name of the TT ► measureTolerance1
Input:	0.001 to 0.999, max. 3 decimal places
iTNC 530:	6510.0
measureTolerance	<b>2</b> 1227′
Maximum permissi second measuring	ble measuring error for tool measurement with rotating tool error)
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT ▶ measureTolerance2
Input:	0.001 to 0.999, max. 3 decimal places
iTNC 530:	6510.1
stopOnCheck	1227 <sup>-</sup>
NC Stop during "too	ol check"
Path:	System ► ProbeSettings ► CfgTT ► [Key name of the TT ► stopOnCheck
Input:	TRUE
	If the breakage tolerance is exceeded, the NC program stops and the error message <b>Tool broken</b> is displayed. <b>FALSE</b>
	The NC program does not stop if the breakage tolerance is exceeded.
iTNC 530:	6500 Bit5
stopOnMeasureme	1227 <sup>2</sup>
NC stop during tool	measurement
Path:	System ► ProbeSettings ► CfgTT ► [Key name of the TT ► stopOnMeasurement
Input:	TRUE
	If the breakage tolerance is exceeded, the NC program stops and the error message <b>Touch point inaccessible</b> is displayed.
	FALSE
	The NC program does not stop if the breakage tolerance is exceeded.
iTNC 530:	6500 Bit6

Change the tool tabl	e during tool check and tool measurement
Path:	System ▶ ProbeSettings ▶ CfgTT ▶ [Key name of the TT] ▶ adaptToolTable
Input:	AdaptNever
	The tool table is not changed after tool check and tool measurement.
	AdaptOnBoth
	The tool table is changed after tool check and tool measurement.
	AdaptOnMeasure
	The tool table is changed after tool measurement.
iTNC 530:	6500 Bit11
CfgTTRoundStylus	114200
Configuration of a re	ound stylus
Path:	System ▶ ProbeSettings ▶ CfgTTRoundStylus
Data object:	
centerPos	114201
Coordinates of the p	probe-contact center point
Path:	System ▶ ProbeSettings ▶ CfgTTRoundStylus ▶ [Key name of the TT] ▶ centerPos
Input:	-99999.9999 to 99999.9999 [mm], max. 4 decimal places
	Coordinates of the probe-contact center with respect to the machine datum.
	[0]: X coordinate
	■ [1]: Y coordinate
	■ [2]: Z coordinate
iTNC 530:	6580, 6581, 6582
safetyDistToolAx	114203
salety Dist 1001Ax	
Safety clearance ard	ound the probe contact of the TT tool touch probe for pre- ol-axis direction
	·
Safety clearance are	ol-axis direction  System ▶ ProbeSettings ▶ CfgTTRoundStylus ▶

safetyDistStylus		114204
Safety zone around	d the stylus for pre-positioning	
Path:	System ▶ ProbeSettings ▶ CfgTTRoundStylus ▶ [Key name of the TT] ▶ safetyDistStylus	
Input:	0.001 to 99999.9999 [mm], max. 4 decimal places Safety clearance in the plane perpendicular to the t	ool axis
iTNC 530:	6540.1	
CfgTTRectStylus		114300
Configuration of a	rectangular stylus	
Path:	System ▶ ProbeSettings ▶ CfgTTRectStylus	
Data object:		
centerPos		114313
Coordinates of the	stylus center	
Path:	System ▶ ProbeSettings ▶ CfgTTRectStylus ▶ [Key name of the TT] ▶ centerPos	
Input:	Coordinates of the stylus center with respect to the machine datum -99999.9999 to 99999.9999 [mm], decimal places	
iTNC 530:	6580, 6581, 6582	
safetyDistToolAx		114317
Set-up clearance a	bove the stylus for pre-positioning	
Path:	System ▶ ProbeSettings ▶ CfgTTRectStylus ▶ [Key name of the TT] ▶ safetyDistToolAx	
Input:	0.001 to 99999.9999 [mm], max. 4 decimal places	
	Safety clearance in tool axis direction	
iTNC 530:	6540.0	
safetyDistStylus		114318
Safety zone around	d the stylus for pre-positioning	
Path:	System ▶ ProbeSettings ▶ CfgTTRectStylus ▶ [Key name of the TT] ▶ safetyDistStylus	
Input:	0.001 to 99999.9999 [mm], max. 4 decimal places	
iTNC 530:	6540.1	

# 2.2.4 ChannelSettings

CfgActivateKinem	2040	000
Active kinematics		
Path:	Channels ► ChannelSettings ► CfgActivateKinem	
Data object:		
kinemToActivate	2040	001
Kinematics to be a	ctivated / active kinematics	
Path:	Channels ► ChannelSettings ►  [Key name of the machining channel] ► CfgActivateKinel  kinemToActivate	m
Input:	max. 18 Characters Key names from channels/kinemat- ics/ <b>CfgKinComposModel</b> . Select the key name of the kinematic model to be activat You can also read the currently active kinematic model from this machine parameter.	ed.
kinemAtStartup	2040	002
The kinematics to I	oe activated during control start-up	
Path:	Channels ► ChannelSettings ► CfgActivateKinem ► [Key name of the machining channel] ► kinemAtStartup	
Input:	max. 18 Characters  Enter here the key name of a default kinematic model (from <b>CfgKinComposModel</b> ), that is activated during every control start-up (independently of which key name is entered in the machine parameter <b>kinemToActivate</b> (204001)).	
iTNC 530:	7506	
CfgNcPgmBehavio	our 2008	300
Specify the behavior	or of the NC program.	
Path:	Channels ► ChannelSettings ► CfgNcPgmBehaviour	
Data object:		

pperatingTimeRes		200801
Reset the machini	ng time when program starts.	
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgNcPgmBehaviour ► operatingTimeReset	
Input:	TRUE	
	The machining time is reset at each program start. <b>FALSE</b>	
	The machining time is totaled.	
lcSignalCycle		200803
PLC signal for the	number of the pending machining cycle	
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgNcPgmBehaviour ► plcSignalCycle	
Input:	max. 500 Characters	
	Name or number of a PLC word marker	
olcSignalCycState		200805
LC signal for type	e of current cycle execution	
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgNcPgmBehaviour ► plcSignalCycState	
Input:	The following value is written to the configured ope  0: No machining cycle is being executed  1: Pre-positioning	erand:
	<ul><li>2: Machining</li></ul>	
cfgGeoTolerance		200900
Geometry tolerand	ces	
Path:	Channels ► ChannelSettings ► CfgGeoTolerance	
Data object:		
rcleDeviation		200901
Permissible deviat	ion of the radius	
Path:	Channels ► ChannelSettings ►  [Key name of the machining channel] ► CfgGeoTolerance  ► circleDeviation	
Input:	0.0001 to 0.016 [mm], max. 4 decimal places	
·	Enter the permissible deviation of the radius betwe end point and starting point of the arc.	en the
iTNC 530:	7431	

threadTolerance	2009	02
Permissible deviati	on in successive threads	
Path:	Channels ➤ ChannelSettings ►  [Key name of the machining channel] ► CfgGeoTolerance  threadTolerance	è
Input:	0.0001 to 999.9999 [mm], max. 9 decimal places Permissible deviation of the dynamically smoothed contor from the programmed thread contour.	ur
moveBack	2009	03
Reserve for retracti	on movements	
Path:	Channels ► ChannelSettings ►  [Key name of the machining channel] ► CfgGeoTolerance  moveBack	<u>,</u>
Input:	0.0001 to 10 [mm], max. 9 decimal places With this parameter you specify how far before a limit switch or a collision object a retraction movement should end.	
CfgGeoCycle	2010	00
Configuration of the	e fixed cycles	
Path:	Channels ► ChannelSettings ► CfgGeoCycle	
Data object:		
pocketOverlap	2010	01
Overlap factor for p	pocket milling	
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgGeoCycle ► pocketOverlap	
Input:	0.001 to 1.414, max. 3 decimal places	
iTNC 530:	7430	
oosAfterContPock	et 2010	07
Traverse after mac	hining the contour pocket	
Path:	Channels ► ChannelSettings ►  [Key name of the machining channel] ► CfgGeoCycle ►  posAfterContPocket	
Input:	PosBeforeMachining	
	Move to the position from which the SL cycle was started.	
	ToolAxClearanceHeight	
	Move the tool axis to clearance height.	
iTNC 530:	7420 Bit 4	

displaySpindleErr	201002
Display the <b>Spindle</b>	is not rotating error message if M3/M4 is not active
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgGeoCycle ► displaySpindleErr
Input:	on
	The error message is displayed
	off
	The error message is not displayed
iTNC 530:	7441
displayDepthErr	201003
Display the <b>Check</b> t	the depth sign error message
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgGeoCycle ► displayDepthErr
Input:	on
	Error message is displayed
	off
	Error message is not displayed
iTNC 530:	7441
apprDepCylWall	201004
Behavior when mov	ving to wall of slot in the cylinder surface
Path:	Channels ► ChannelSettings ►  [Key name of the machining channel] ► CfgGeoCycle ►  apprDepCylWall
Input:	Defines the behavior for cutter movements to the wall of a slot in the cylinder surface when machining the slot with a milling cutter whose diameter is less than the slot diameter (e.g. Cycle 28).
	LineNormal
	The slot wall is approached and departed linearly.
	CircleTangential
	The slot wall is approached and departed tangentially; at the beginning and end of the slot a rounding arc with a diameter equal to the slot width is inserted.
iTNC 530:	7680 Bit 12

mStrobeOrient	2010
M function for spind	dle orientation in machining cycles
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgGeoCycle ► mStrobeOrient
Input:	-1 to 999
	<ul><li>-1: Spindle orientation directly through the NC</li><li>0: Function not active</li><li>1 to 999: Number of the M function for spindle orientation through the PLC.</li></ul>
iTNC 530:	7442
suppressPlungeErr	2010
Do not show 'Plungi	ing type is not possible' error message
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgGeoCycle ► suppressPlungeErr
Input:	on
	Error message is not displayed
	off
	Error message is displayed
restoreCoolant	2010
Behavior of M7 and	M8 with Cycles 202 and 204
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgGeoCycle ► restoreCoolant
Input:	TRUE
	At the end of Cycles 202 and 204, the status of M7 and M is restored to that before the cycle call.
	FALSE
	At the end of Cycles 202 and 204, the status of M7 and M is not restored automatically.
iTNC 530:	7682

facMinFeedTurn	<b>SMAX</b> 2010	009
Automatic feed ra	ate reduction after attaining SMAX	
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgGeoCycle ► facMinFeedTurnSMAX	
Input:	1 to 100 [%], max. 1 decimal places	
	If the maximum spindle speed SMAX is reached, the turn operation can no longer maintain the constant cutting speed (VCONST:ON).	ing
	The machine parameter specifies whether the feed rate should be automatically reduced from this point up to the center of rotation.	)
	Settings options:	
	<ul> <li>Factor = 100% (default value):</li> <li>Feed rate reduction deactivated. The feed rate from the turning cycle is used.</li> </ul>	ie
	<ul> <li>0 &lt; factor &lt; 100%:</li> <li>Feed rate reduction is activated. The minimum feed rate fmin is:</li> <li>Fmin = feed rate from turning cycle * factor</li> </ul>	ite

#### suppressResMatlWar

suppressResMat	lWar 2	201010
Do not show "Res	sidual material" warning	
Path:	Channels ► ChannelSettings ► [Key name of the machining channel] ► CfgGeoCycle suppressResMatlWar	•
Input:	Never	
	The "Residual material due to cutter geometry" warnir never suppressed	ng is
	NCOnly	
	The "Residual material due to cutter geometry" warnir suppressed only in the Machine operating modes.	ng is
	Always	
	The "Residual material due to cutter geometry" warnir always suppressed.	ng is

CfgTh	readSpindle		113600
Specia	al spindle parar	neters for threads	
	Path:	Channels ► ChannelSettings ► CfgThreadSpi	ndle
	Data object:		
sourc	eOverride		113603
Effect	ive override pot	entiometer for feed rate during thread cutting	
	Path:	Channels ► ChannelSettings ►  [Key name of machining channel] ► CfgThread sourceOverride	dSpindle ▶
_	Input:	The adjusted potentiometer is effective during cutting for shaft speed and feed rate.	thread
		FeedPotentiometer	
		(previous behavior of the TNC 640) During thread cutting, the potentiometer is effected rate knob. The potentiometer for the spine knob is not active.	
		SpindlePotentiometer	
		(iTNC 530-compatible setting) During thread cutting, the potentiometer is effective spindle speed knob. The potentiometer for the override is disabled.	
thrdW	/aitingTime		113601
Waitin	ng time at rever	sal point in thread base	
	Path:	Channels ➤ ChannelSettings ➤ [Key name of machining channel] ➤ CfgThreadthrdWaitingTime	dSpindle ▶
_	Input:	0 to 1 000 [s], max. 9 decimal places  The spindle stops for this time at the bottom of before starting again in the opposite direction of the starting again.	
_	iTNC 530:	7120.0	
thrdP	reSwitchTime		113602
Advar	nced switching	time of spindle	
	Path:	Channels ► ChannelSettings ►  [Key name of machining channel] ► CfgThread thrdPreSwitchTime	dSpindle ▶
_	Input:	0 to 1 000 [s], max. 9 decimal places  The spindle is stopped at this time before reac bottom of the thread.	hing the
_	iTNC 530:	7120.1	

limit	limitSpindleSpeed 11360-		
Limit	Limit of spindle speed with Cycles 17, 207 and 18		
	Path:	Channels ► ChannelSettings ►  [Key name of machining channel] ► CfgThreadSpindle ►  limitSpindleSpeed	>
	Input:	TRUE	
		Spindle speed is limited so that it runs with constant spe approx. 1/3 of the time	ed
		FALSE	
		Limit not active	
	iTNC 530:	7160, Bit1	

## CfgEditorSettings

CfgEditorSettings	105400
Settings for the NC	editor
Path:	System ► EditorSettings ► CfgEditorSettings
Data object:	
createBackup	105401
Generate a backup	file *.bak
Path:	System ► EditorSettings ► CfgEditorSettings ► createBackup
Input:	TRUE
	After you have edited a file, a backup file *.bak is automatically created before you save the file and exit the NC editor.  FALSE
	No backup file *.bak is created. Select this setting if you do not need any backup files and want to save memory space.
deleteBack	105402
Behavior of the cur	sor after deletion of lines
Path:	System ► EditorSettings ► CfgEditorSettings ► deleteBack
Input:	TRUE
	Behavior as with iTNC 530, the cursor is on the previous line <b>FALSE</b>
	The cursor is on the next line
lineBreak	105404
Line break on NC b	locks with more than one line
Path:	System ▶ EditorSettings ▶ CfgEditorSettings ▶ lineBreak
Input:	ALL
	Always break and display lines completely (multiline) <b>ACT</b>
	Only display the selected NC block completely (multiline) <b>NO</b>
	Only display all lines when the selected NC block is edited
iTNC 530:	7281.0

stdTNChelp		105405
Activate help grap	nics when entering cycle data	
Path:	System ► EditorSettings ► CfgEditorSettings ► stdTNChelp	
Input:	TRUE	
	Behavior as with iTNC 530: the help graphics are di automatically during cycle entry. FALSE	isplayed
	The help graphics have to be called via the <b>CYCLE ON/OFF</b> soft key.	HELP
warningAtDEL		105407
Confirmation requ	est when deleting an NC block.	
Path:	System ► EditorSettings ► CfgEditorSettings ► warningAtDEL	
Input:	TRUE	
	The confirmation request is displayed and must be confirmed by pressing DEL again.	!
	FALSE	
	The NC block is deleted without a confirmation pro	mpt.
iTNC 530:	7246	
blockIncrement		105409
ISO programming:	Block number increment	
Path:	System ▶ EditorSettings ▶ CfgEditorSettings ▶ blockIncrement	
Input:	0 to 250	
iTNC 530:	7220	
useProgAxes		105410
Specify programm	able axes	
Path:	System ► EditorSettings ► CfgEditorSettings ► useProgAxes	
Input:	TRUE	
	Use the axis configuration defined in the CfgChann es/ <b>progAxis</b> parameter (200301). On machines witraverse range switchover, the editor offers all axes included in at least one kinematic model of the ma	th s that are
	<b>FALSE</b> Use the default axis configuration XYZABCUVW.	
	333 the detail and configuration ATZ/1000 VVV.	

low or lock narry	ial positioning blocks
· · · · · · · · · · · · · · · · · · ·	
Path:	System ▶ EditorSettings ▶ CfgEditorSettings ▶ enableStraightCut
Input:	TRUE
	Paraxial positioning blocks are allowed. When an orange axis key is pressed, and in ISO when G07 is programmed, a paraxial positioning block is generated.  FALSE
	Paraxial positioning blocks are locked. When an orange axi key is pressed, the TNC7 generates a straight-line interpolation (L block) instead of a paraxial positioning block.
iTNC 530:	7246
ParaxMode	10541
de <b>FUNCTION P</b>	ARAXCOMP/PARAXMODE
Path:	System ► EditorSettings ► CfgEditorSettings ► noParaxMode
Input:	Use noParaxMode (105413) to hide the FUNCTION PARAX COMP and FUNCTION PARAXMODE functions.  FALSE
	The functions are displayed
	TRUE
	The functions are not displayed
	If the optional machine parameter does not exist in the configuration, the system behaves as if it were set to <b>FALSE</b> .
ıotePaths	10541
ut all path informa	ation in quotation marks
Path:	System ► EditorSettings ► CfgEditorSettings ► quotePaths
Input:	TRUE
	Path information is enclosed in quotation marks.
	FALSE
	Path information is not enclosed in quotation marks.
etPosAxes	10541
kes for actual pos	sition capture
Path:	System ► EditorSettings ► CfgEditorSettings ► actPosAxes
Input:	max. 800 Characters
•	Use this parameter to specify which axes will be considered

## ${\bf CfgProgramCheck}$

CfgProgramChed	ck	129800
Settings for tool-u	usage files	
Path:	System ▶ ToolSettings ▶ CfgProgramCheck	
Data object		
autoCheckTime0	Out	129803
Timeout for creat	tion of tool-usage files	
Path:	System ► ToolSettings ► CfgProgramCheck ► autoCheckTimeOut	
Input:	Automatic creation of the tool-usage file is aborted if time is exceeded. 1 to 500	fthis
autoCheckPrg		129801
Create tool-usage	e file for NC program	
Path:	System ► ToolSettings ► CfgProgramCheck ► autoCheckPrg	
Input:	NoAutoCreate  No tool-usage list will be generated upon selection or program.	f a
	OnProgSelectionIfNotExist	
	A tool-usage list will be generated upon program sele the list does not already exist.	ection if
	OnProgSelectionIfNecessary	
	A tool-usage list will be generated upon program sele the list does not already exist or if it contains obsolet	
	OnProgSelectionAndModify	
	A tool-usage list will be generated upon program sele the list does not already exist, if it contains obsolete if the NC program is modified afterwards by using ar	data, or

autoCheckPal	129802
Create pallet-usage fi	es
Path:	System ► ToolSettings ► CfgProgramCheck ► autoCheckPal
Input:	NoAutoCreate
	No tool-usage files will be generated upon pallet selection.
	OnProgSelectionIfNotExist
	Upon pallet selection, tool-usage lists that do not already exist will be generated.
	OnProgSelectionIfNecessary
	Upon pallet selection, tool-usage lists that do not already exist or that contain obsolete data will be generated.
	OnProgSelectionAndModify
	Upon pallet selection, tool-usage lists will be generated that do not already exist, that contain obsolete data, or whose NC programs are modified using an editor.

### CfgUserPath

Cfgl	<b>JserPath</b>		102200		
Path	Paths for the end user				
	Path:	System ▶ Paths ▶ CfgUserPath	_		
	Data object:				

fn16DefaultPath 102202

Default output path for the **FN 16: F-PRINT** function in the Program Run operating modes

Path:	System ▶ Paths ▶ CfgUserPath ▶ fn16DefaultPath
Input:	max. 260 Characters
	Select the folder in the dialog window and confirm it with the <b>SELECT</b> soft key
	Default path for output with <b>FN 16: F-PRINT</b> . If no path is defined for the FN 16 function in the NC program, the output destination is in the directory specified here.

fn16DefaultPathSim 102203

Default output path for the **FN 16: F-PRINT** function in the Programming and Test Run operating modes

Path:	System ▶ Paths ▶ CfgUserPath ▶ fn16DefaultPathSim
Input:	max. 260 Characters
	Select the folder in the dialog window and confirm it with the <b>SELECT</b> soft key
	Default path for output with <b>FN 16: F-PRINT</b> . If no path is defined for the <b>FN 16</b> function in the NC program, the output lands in the directory specified here.

### 2.2.5 serialInterfaceRS232

CfgSerialPorts		106600
Data record belong	ing to the serial port	
Path:	System ▶ Network ▶ Serial ▶ CfgSerialPorts	
Data object:		
baudRateLsv2		106606
Data transfer rate f	or LSV2 communication in baud	
Path:	System ► Network ► Serial ► CfgSerialPorts ► baudRateLsv2	
Input:	Use a selection menu to define the transfer rate fo the LSV2 communication. Minimum value is 110 b maximum value 115200 baud.	
	BAUD_110	
	BAUD_150	
	BAUD_300	
	BAUD_600	
	BAUD_1200	
	BAUD_2400	
	BAUD_4800	
	BAUD_9600	
	BAUD_19200	
	BAUD_38400	
	BAUD_57600	
	BAUD_115200	

CfgSerialInterface			106700
Defir	nition of data reco	ords for the serial ports	
	Path:	System ► Network ► Serial ► CfgSerialInterface	
	Data object:		

or communication in baud	
System ► Network ► Serial ► CfgSerialInterface ►	
[Key names of the interface parameters] ➤ baudRate	
Use a selection menu to define the transfer rate for the data transmission. Minimum value is 110 baud, maximum value 115200 baud.	
BAUD_110	
BAUD_150	
BAUD_300	
BAUD_600	
BAUD_1200	
BAUD_2400	
BAUD_4800	
BAUD_9600	
BAUD_19200	
BAUD_38400	
BAUD_57600	
BAUD_115200	
5040	
106702	
rotocol	
System ▶ Network ▶ Serial ▶ CfgSerialInterface ▶ [Key names of the interface parameters] ▶ protocol	
STANDARD	
STANDARD Standard data transfer. Data transferred line-by-line.	
Standard data transfer. Data transferred line-by-line. <b>BLOCKWISE</b> Packet-based data transfer, ACK/NAK protocol. The control	
Standard data transfer. Data transferred line-by-line. <b>BLOCKWISE</b> Packet-based data transfer, ACK/NAK protocol. The control characters ACK (Acknowledge) and NAK (not Acknowledge)	
Standard data transfer. Data transferred line-by-line. <b>BLOCKWISE</b> Packet-based data transfer, ACK/NAK protocol. The control characters ACK (Acknowledge) and NAK (not Acknowledge are used to control block-wise data transfer.	

dataBits	106703
Data bits in each tr	ansferred character
Path:	System ► Network ► Serial ► CfgSerialInterface ► [Key names of the interface parameters] ► dataBits
Input:	7 bits
	7 data bits are transferred for each character transferred.
	8 bits
	8 data bits are transferred for each character transferred.
iTNC 530:	5020 Bit0
parity	106704
Type of parity chec	king
Path:	System ▶ Network ▶ Serial ▶ CfgSerialInterface ▶ [Key names of the interface parameters] ▶ parity
Input:	NONE
	No parity
	EVEN
	Even parity
	ODD
	Odd parity
iTNC 530:	5020 Bit4/5
stopBits	106705
Number of stop bit	S
Path:	System ▶ Network ▶ Serial ▶ CfgSerialInterface ▶ [Key names of the interface parameters] ▶ stopBits
Input:	1 stop bit
	1 stop bit is appended after each transferred character.
	2 stop bits
	2 stop bits are appended after each transferred character.
iTNC 530:	5020 Bit6/7

flowControl	106706
Type of data-flow c	hecking
Path:	System ► Network ► Serial ► CfgSerialInterface ► [Key names of the interface parameters] ► flowControl
Input:	Configure here whether there is to be a data-flow check (handshake).  NONE
	No data-flow check; handshake not active
	RTS_CTS
	Hardware handshake. Transmission stop through RTS active
	XON_XOFF
	Software handshake; Transfer stop by DC3 (XOFF) active
iTNC 530:	5020 Bit2/3
fileSystem	106707
File system for file	operation via serial interface
Path:	System ▶ Network ▶ Serial ▶ CfgSerialInterface ▶ [Key names of the interface parameters] ▶ fileSystem
Input:	EXT
	Minimum file system for external devices. Corresponds to the EXT1 and EXT2 modes of earlier TNC controls. Use these settings if you are using printers, punches, or non-HEIDENHAIN data transfer software.
	FE1
	Use this setting for communication with the external HEIDENHAIN FE 401 B or FE 401 floppy disk unit as of software 230626-03, or for communication with the "TNCserver" PC software from HEIDENHAIN.
bccAvoidCtrlChar	106708
Avoid control chara	acters in the block check character (BCC)
Path:	System ► Network ► Serial ► CfgSerialInterface ► [Key names of the interface parameters] ► bccAvoidCtrlChar
Input:	TRUE
	Ensures that the check sum does not correspond to a control character
	FALSE
	Function not active
iTNC 530:	5020 Bit1

rtsLow	106709
Idle state of the RT	S line
Path:	System ▶ Network ▶ Serial ▶ CfgSerialInterface ▶ [Key names of the interface parameters] ▶ rtsLow
Input:	TRUE
	The idle state of the RTS line is logical LOW
	FALSE
	The idle state of the RTS line is at logical HIGH
iTNC 530:	5020 Bit8
<b>noEotAfterEtx</b> Behavior after rece	nd6710 eption of an ETX control character
Behavior after rece Path:	eption of an ETX control character  System ► Network ► Serial ► CfgSerialInterface ►
	[Key names of the interface parameters] ▶ noEotAfterEtx
Input:	TRUE
	No EOT control character is sent after reception of an ETX control character.
	FALSE
	The control sends an EOT control character after reception of an ETX control character.
iTNC 530:	5020 Bit9

### 2.2.6 Monitoring

CfgCompMonUse	er	129400
User settings for	component monitoring	
Path:	System ► Monitoring ► CfgCompMonUser	
Data object	:	
enforcedReactio	าร	129403
Permissible comp	ponent monitoring reactions	
Path:	System ► Monitoring ► CfgCompMonUser ► enforcedReactions	
Input:	Do not permit reactions	
	Do not permit stop reactions	
	Permit all reactions	
CfgProcMonUse		141600
User settings for	process monitoring	
Path:	System ► Monitoring ► CfgProcMonUser	
Data object		
permitAutoExpor	t	141601
Automatic export		
Path:	System ► Monitoring ► CfgProcMonUser ► CfgProcMonUser	
Input:	TRUE	
	FALSE	
autoExportType		141602
File format for au	tomatic export	111002
Path:	System ► Monitoring ► CfgProcMonUser ► CfgProcMonUser	
Input:	max. 32 Characters	
	If an output format is defined, an export file is automatically generated in the folder of the NC after each program run.	program
	Permissible values: HTML, CSV	

## ${\bf CfgMachine Info}$

CfgMachineInfo		131700
General informatio	n of the machine operator	
Path:	System ► CfgMachineInfo	
Data object:	<ul> <li>Defines general information about this machine:</li> <li>Settable by the user of the machine</li> <li>Can be queried (e.g., via the OPC UA NC Server)</li> </ul>	
machineNickname		131701
Custom name (nic	kname) of the machine	
Path:	System ▶ CfgMachineInfo ▶ machineNickname	
Input:	max. 64 Characters  Machine designation freely selectable by the user.	
inventoryNumber		131702
Inventory number	or ID	
Path:	System ► CfgMachineInfo ► inventoryNumber	
Input:	max. 64 Characters Internal inventory number of the operator's machin	e.
image		131703
Photo or image of	the machine	
Path:	System ► CfgMachineInfo ► image	
Input:	max. 260 Characters Path to an image file (*.jpg or *.png).	
location		131704
Machine location		
Path:	System ► CfgMachineInfo ► location	
Input:	max. 64 Characters	
department		131705
Department or divi	sion	
Path:	System ► CfgMachineInfo ► department	
Input:	max. 64 Characters	

responsibility		131706
Responsible for the	ne machine	
Path:	System ► CfgMachineInfo ► responsibility	
Input:	max. 64 Characters	
	Contact partner responsible for the machine, person or a department.	can be a
contactEmail		131707
Contact email add	dress	
Path:	System ► CfgMachineInfo ► contactEmail	
Input:	max. 64 Characters	
	E-mail address of the responsible person or of	department.
contactPhoneNu	mber	131708
Contact phone nu	ımber	
Path:	System ▶ CfgMachineInfo ▶ contactPhone	Number
Input:	max. 32 Characters	
	Telephone number of the responsible persor ment.	or depart-

### 3 Preassigned error numbers for FN 14: ERROR

With the FN 14 function you can issue error messages in the NC program.



Refer to your machine manual.

The error numbers from 0 to 999 as well as those from 3000 to 9999 are defined by the machine manufacturer.

The following error messages are preassigned by HEIDENHAIN:

Fehlernummer	Text
1000	Spindle must be turning
1001	Tool axis is missing
1002	Tool radius too small
1003	Tool radius too large
1004	Range exceeded
1005	Start position incorrect
1006	Rotation not permitted
1007	Scaling factor not permitted
1008	Mirroring not permitted
1009	Datum shift not permitted
1010	Feed rate is missing
1011	Entry value incorrect
1012	Wrong sign programmed
1013	Entered angle not permitted
1014	Touch point inaccessible
1015	Too many points
1016	Contradictory entry
1017	CYCL DEF incomplete
1018	Plane wrongly defined
1019	Wrong axis programmed
1020	Wrong rpm
1021	Radius comp. undefined
1022	Rounding-off not permitted
1023	Rounding radius too large
1024	Program start undefined
1025	Excessive subprogramming
1026	Angle reference missing
1027	No fixed cycle defined
1028	Insufficient slot width
1029	Pocket too small
1030	Q202 not defined
1031	Q205 not defined

Fehlernummer	Text
1032	Q218 must be greater than Q219
1033	Fixed cycle not allowed
1034	CYCL 211 not permitted
1035	Q220 too large
1036	Q222 must be greater than Q223
1037	Q244 must be greater than 0
1038	Q245 must not equal Q246
1039	Angle range must be under 360°
1040	Q223 must be greater than Q222
1041	Q214: 0 not permitted
1042	Traverse direction not defined
1043	No datum table active
1044	Position error: center in axis 1
1045	Position error: center in axis 2
1046	Hole diameter too small
1047	Hole diameter too large
1048	Stud diameter too small
1049	Stud diameter too large
1050	Pocket too small: rework axis 1
1051	Pocket too small: rework axis 2
1052	Pocket too large: scrap axis 1
1053	Pocket too large: scrap axis 2
1054	Stud too small: scrap axis 1
1055	Stud too small: scrap axis 2
1056	Stud too large: rework axis 1
1057	Stud too large: rework axis 2
1058	Meas. cycle: length exceeds max
1059	Meas. cycle: length below min
1060	TCHPROBE 426: length exceeds max
1061	TCHPROBE 426: length below min
1062	TCHPROBE 430: diameter too large
1063	TCHPROBE 430: diameter too small
1064	No measuring axis defined
1065	Tool breakage tolerance exceeded
1066	Enter Q247 unequal 0
1067	Enter Q247 greater than 5
1068	Datum table?
1069	Enter direction Q351 unequal 0
1070	Thread depth too large

Fehlernummer	Text
1071	Missing calibration data
1072	Tolerance exceeded
1073	Mid-program startup active
1074	ORIENTATION not permitted
1075	3-D ROT not permitted
1076	Activate 3DROT
1077	Check the depth sign
1078	Q303 in meas. cycle undefined!
1079	Tool axis not allowed
1080	Calculated values incorrect
1081	Contradictory measuring points
1082	Incorrect clearance height!
1083	Contradictory plunge type!
1084	This fixed cycle not allowed
1085	Line is write-protected
1086	Oversize greater than depth
1087	No point angle defined
1088	Contradictory data
1089	Slot position 0 not allowed!
1090	Enter an infeed not equal to 0
1091	Switchover of Q399 not allowed
1092	Tool not defined
1093	Tool number not allowed
1094	Tool name not allowed
1095	Software option not active
1096	Kinematics cannot be restored
1097	Function not permitted
1098	Contradictory workpc. blank dim.
1099	Measuring position not allowed
1100	Kinematic access not possible
1101	Meas. pos. not in traverse range
1102	Preset compensation not possible
1103	Tool radius too large
1104	Plunging type is not possible
1105	Plunge angle incorrectly defined
1106	Angular length is undefined
1107	Slot width is too large
1108	Scaling factors not equal
1109	Tool data inconsistent

Fehlernummer	Text
1110	MOVE not possible
1111	Presetting not allowed!
1112	Thread angle too small!
1113	3-D ROT status is contradictory!
1114	Configuration is incomplete
1115	No turning tool is active
1116	Tool orientation is inconsistent
1117	Angle not possible!
1118	Radius too small!
1119	Thread runout too short!
1120	Contradictory meas. points
1121	Too many limits
1122	Machining strategy with limits not possible
1123	Machining direction not possible
1124	Check the thread pitch!
1125	Angle cannot be calculated
1126	Eccentric turning not possible
1127	No milling tool is active
1128	Insufficient length of cutting edge
1129	Gear definition is inconsistent or incomplete
1130	No finishing allowance provided
1131	Line does not exist in table
1132	Probing process not possible
1133	Coupling function not possible
1134	Fixed cycle is not supported by this NC software
1135	Touch probe cycle is not supported by this NC software
1136	NC program aborted
1137	Touch probe data incomplete
1138	LAC function not possible
1139	Rounding radius or chamfer is too large!
1140	Axis angle not equal to tilt angle
1141	Character height not defined
1142	Excessive character height
1143	Tolerance error: Workpiece rework
1144	Tolerance error: Workpiece scrap
1145	Faulty dimension definition
1146	Illegal entry in compensation table
1147	Transformation not possible
1148	Tool spindle incorrectly configured

Fehlernummer	Text				
1149	Offset of the turning spindle unknown				
1150	Global program settings are active				
1151	Faulty configuration of OEM macros				
1152	The combination of programmed oversizes is not possible				
1153	Measured value not captured				
1154	Check the monitoring of the tolerance				
1155	Hole is smaller than the stylus tip				
1156	Preset cannot be set				
1157	Alignment of a rotary table is not possible				
1158	Alignment of rotary axes is not possible				
1159	Infeed limited to length of cutting edge				
160	Machining depth defined as 0				
1161	Tool type is unsuitable				
162	Finishing allowance not defined				
163	Machine datum could not be written				
164	Spindle for synchronization could not be ascertained				
165	Function is not possible in the active operating mode				
166	Oversize defined too large				
167	Number of teeth not defined				
168	Machining depth does not increase monotonously				
169	Infeed does not decrease monotonously				
170	Tool radius not defined correctly				
171	Mode for retraction to clearance height not possible				
172	Gear wheel definition incorrect				
173	Probing object contains different types of dimension definition				
174	Dimension definition contains impermissible characters				
175	Actual value in dimension definition faulty				
176	Starting point of hole too deep				
177	Dimension def.: Nominal value missing for manual pre-positioning				
178	A replacement tool is not available				
1179	OEM macro is not defined				
180	Measurement not possible with auxiliary axis				
181	Start position not possible with modulo axis				
182	Function only possible if door is closed				
183	Number of possible records exceeded				
184	Inconsistent machining plane due to axis angle with basic rot.				
1185	Transfer parameter contains an impermissible value				
1186	Tooth width RCUTS is defined too large				
1187	Usable length LU of the tool is too small				

Fehlernummer	Text				
1188	The defined chamfer is too large				
1189	Chamfer angle cannot be machined with the active tool				
1190	The allowances do not define any stock removal				
1191	Spindle angle not unique				
1192	Internal software error: wrong or faulty command				
1193	Probing procedure is not possible				
1194	Type of the object to be probed is not possible				
1195	Input value not permitted				
1196	No data available for processing				
1197	Object to be probed cannot be repeated				
1198	Limitation for island missing				
1199	Cannot process the data				
1200	Rotation of the tool coordinate system not permitted				
1201	NC Start was ignored				
1202	Circle cannot be calculated				
1203	Probing of an extrusion not possible				
1204	Nominal position not defined correctly				
1205	Retraction behavior not possible with multiple plunging				
1206	Basic rotation will be rescinded				
1207	Repeat last measurement?				
1208	Continue with next measurement?				
1209	File not found				
1210	The entire plunging depth is greater than the tooth height				
1211	The entire plunging depth is less than the tooth height				
1212	File cannot be opened				
1213	Insertion point for fixtures missing				
1214	Probing direction is not permitted				
1215	Status of transformations for simultaneous turning is not correct				
1216	Preset cannot be modified after probe objects have been probed				
1217	Tolerance does not match probing direction				
1218	Offset in pallet reference point not permitted				
1219	Global program settings are active				
1220	Global program settings are active				
1221	Cycle can be executed only in the Testing mode				
1222	Bezugspunkt mit Offset aktiv				
1223	Tool carrier can't be monitored correctly				
1224	Probing function doesn't support stylus type				
1225	Slot smaller than stylus tip				
1226	Determination of machine datum with inclination angle not 0				

Fehlernummer	Text				
1227	Feed-rate potentiometer is effective for L stylus!				
1228	Spindle orientation not possible				
1229	Touch point not reached				
1230	Probe cycle started with stylus already deflected				
1231	Not a valid row for a preset				
1232	Offset of a rotary axis differs				
1233	Couldn't start Python process				
1234	TCPM not possible with selected function				
1500	Error in pallet management				
1501	Error in pocket table				
1502	Fixture not activated				
1503	Wrong pallet				
1504	Pallet line locked!				
1505	Datum table missing				
1506	Measuring probe not defined				
1507	Incorrect tool data				
1508	Tool number 0 not permitted				
1509	Tool not defined				
1510	No appropriate tool found				
1511	Calculated tool number too large				
1512	Tool definition is missing				
1513	Tool number already assigned				
1514	Tool definition not permitted				
1515	TOOL DEF w/o length or radius				
1516	Max. tool age expired				
1517	Tool locked				
1518	Tool table is missing				
1519	FN14_1519				
1520	Helical plunging not possible				
1521	FN14_1521				
1522	No touch probe data				
1523	SQL command failed				
1524	FN14_1524				
1525	FN14_1525				
1526	FN14_1526				
1527	Error in pallet management				
1528	Error in preset table				
1529	Incorrect datum table				
1530	Tool change during mid-program startup not possible				

Fehlernummer	Text			
1531	Calibrate touch probe			
1532	Tool axis is missing			
1533	CYCL DEF incomplete			
1534	TOOL.T: Enter number of teeth			
1535	Enter tool radius greater than 0			
1536	Tolerance in the parameter measureTolerance[1;2] is too low			
1537	Tool locked			
1538	Error in tool measurement configuration			
1539	Tool measurement locked			
1540	Tool measurement: Functionality not yet implemented			
1541	Orientation not configured			
1542	Arithmetical error			
1543	Cycle error			
1544	Tool broken			
1545	Calibrate TT in tilted plane			
1546	Calibrate TT in non-tilted plane			
1547	TT not parallel to tool axis			
1548	Tool index not allowed			
1549	Turning tool incompletely defined			
1550	Probing direction not in probe plane			
1551	Unbalance detection failed			
1552	Excessive unbalance			
1553	Configuration for unbalance detection wrong			
1554	Radius of replacement tool not suitable			
1555	Invalid tool axis programmed			
1556	Tool table locked			
1557	Unbalance calculation failed			
1558	Tool must not be altered			
1559	Traverse mode for retraction not possible			
1560	Tool life expired			
1561	Tool life expired			
1562	Feed rate limiting has been canceled			
1563	Pallet line with completed part			
1564	Access to pallet preset table failed			
1565	Automatic continuation of pallet machining not possible			
1566	Strategy for continuing the pallet machining is not supported			
1567	Thread-cutting process was interrupted			
1568	Pallet table locked			
1569	Tool not defined completely			

Fehlernummer	Text				
1570	Row does not exist in preset table				
1571	Row does not exist in pallet preset table				
1572	Preset table not found				
1700	Camera not reacting				
1701	Camera not responding				
1702	File for camera position does not exist				
1703	Line does not exist in the position table				
1704	Communication with camera not possible				
1705	Camera provides no images				
1706	A name for the monitoring point is missing				
1707	Not allowed to call an unbalance cycle in milling mode				
2000	Invalid error consequence				
2001	No space released				
2002	No valid physical space				
2003	Space not released				
2004	Tool is already inserted				
2005	No space released				
2006	No identical space				
2007	No further tool found				
2008	No further tool found				
2009	Invalid tool type				
2010	Tool type not allowed				
2011	Data not loaded				
2012	No entry in table				
2013	Invalid parameter value				
2014	Invalid command				
2015	Error in table access				
2016	No grinding wheel				
2017	Invalid tool number				
2018	Invalid alignment				
2019	No dresser defined				
2020	Dresser not defined				
2021	Not a valid wheel type				
2022	Ref. of dresser to wheel edge				
2023	Relieved wheel not possible				
2024	Chamfer width missing				
2025	Chamfer greater than side len. X				
2026	Angle of the relief is incorrect				
2027	Selected grinding wheel face not permitted				

Fehlernummer	Text				
2028	Selection of grinding wheel face required				
2029	Selection of grinding wheel face contradictory				
2030	Dressing strategy: corner radius not permitted				
2031	Dressing strategy: wheel edge not supported				
2032	Selected dressing strategy is not supported				
2033	Dressing mode already active, tool not allowed				
2034	Type of grinding wheel not allowed, not approved				
2035	Tool is not a dressing wheel or roll				
2040	Calculation of wear on dressing tool not possible				
2041	Wear on dressing tool exceeds breakage tolerance				
2050	Error in definition of the direction for the reciprocating stroke				
2051	Axes not configured for reciprocating stroke				
2052	Configuration of dynamics of axes for reciprocating stroke faulty				
2053	M136 is not supported in cylindrical grinding cycles				
2054	Tool alignment not appropriate for automatic approaching				
2100	Infeed not defined				
2101	Infeed direction not defined				
2102	Undersize				
2103	FN14_2103				
2104	Oversize				
2105	FN14_2105				
2106	Signal already active at start				
2107	FN14_2107				
2108	Signal has not responded				
2109	FN14_2109				
2110	B axis in wrong position				
2111	No grinding wheel				
2112	Dressing location not released				
2113	Wheel edges not released				
2114	Wheel location not occupied				
2115	Wheel location not released				
2116	Dressing location not occupied				
2117	T-call parameter invalid				
2118	Wheel settings not defined				
2119	Wheel data not defined				
2120	Wheel not inserted				
2121	Wheel location changed				
2122	Dressing location changed				
2124	Feed rate not programmed				

Fehlernummer	Text				
2125	Wheel missing				
2126	No valid tool selected				
2127	Invalid position				
2128	Not a valid dresser type				
2130	Not a valid dresser type  No event programmed				
2131	Invalid event programmed				
2132	FN14_2132				
2133	Event happened before movement				
2134	FN14_2134				
2135	FN14_2135				
2136	Event did not happen				
2137	No reciprocating stroke calculated				
2138	No swing stroke				
2139	Jig grinding, reciprocating stroke: tool axis not allowed				
2140	Jig grinding: reciprocating stroke already stopped				
2141	Jig grinding: reciprocating stroke already defined				
2142	Immediate stop only permitted if reciprocation def. gets deleted				
2143	Infeed direction and taper angle are contradictory				
2144	Invalid position for reciprocation				
2145	Reciprocating stroke already active				
2146	Infeed already active				
2147	Feed rate not defined for infeed				
2148	Feed rate not defined for sensor				
2149	No infeed, or infeed is contradictory				
2150	Wrong axis programmed				
2151	No axis programmed				
2152	M command not allowed				
2153	Incorrect machining mode				
2154	Tool orientation is not supported				
2155	A 104x definition cycle needs to be the first grinding cycle				
2156	Sequence of cycles is faulty or not supported				
2157	Inclination angle cannot be determined				
2160	Pitch <= 0				
2161	Rotational speed = 0				
2162	Cutting length = 0				
2163	Velocity = 0				
2164	Signs differ				
2165	Pitch = 0				
2180	Block scan over probe functions not allowed				

Fehlernummer	Text				
2181	Command not allowed during block scan				
2182	Command not executed due to block scan				
2183	Measuring function not executed due to block scan				
2184	Elimination of air grinding was not executed due to block scan				
2185	Block scan is not possible on this block				
2190	Command not allowed in the simulation				
2200	No safety clearance at diameter				
2201	No safety clearance on the outside				
2202	No safety clearance on the inside				
2203	Dresser too wide				
2204	Insufficient diameter				
2205	Insufficient width				
2206	Outer side of wheel incorrect				
2207	Inner side of wheel incorrect				
2208	Dressing roller violates retraction amounts				
2209	Overlapping not possible				
	Intermed. dressing not allowed				
	Wheel edge geometry not supported				
	Invalid shape of grinding wheel on the outer side				
2222	Invalid shape of grinding wheel on the inner side				
2223	Depth of grinding wheel too large				
2224	Dimension of grinding wheel negative				
2225	Minimum value of grinding wheel radius not reached				
2300	FN22 command faulty				
2301	Parameter block does not exist				
2302	Command not allowed				
2303	Command not allowed at this point				
2327	Non-circular channel not active				
2328	Non-circ. channel still active				
2329	Command only allowed in non-circular channel				
2330	Incorrect contour command				
2331	Error in contour machining				
2332	Contour program faulty				
2333	Deselect the tilted state				
2334	Tool axis must be Z				
2335	No touch probe in the spindle				
	Camera not calibrated				
2337	Number not permitted for corner				
2338	Unknown number of teeth				

Fehlernummer	Text				
2339	Incorrect table version				
2340	Job name missing				
2341	Value not in permitted range				
2342	Value not in permitted range				
2343	Breakage tolerance exceeded				
2344	Error in table VTC-TOOLS.TAB				
2345	Error in table VTC-TOOLS.TAB				
2346	Error in table VTC-TOOLS.TAB				
2347	Error in configuration table				
2348	Error in configuration table				
2349	VTC cycle error				
2350	Excessive length offset for tool				
2351	Tool axis X, Y, Z permitted				
2352	Starting spindle angle missing				
2353	Max. tilt angle exceeded				
2354	Spindle speed not possible				
2355	Spindle speed not possible				
2356	Camera data faulty				
2357	Spindle angle unknown				
2358	Option for panorama image is missing				
2359	Spindle name?				
2360	Error in VTC.TAB				
2362	Excessive number of teeth				
2363	Incorrect VTC API version				
2364	Impermissible character in job name				
2365	Tool radius too large				
2366	Incorrect value for contact angle at R2				
2367	Radius R2 greater than radius R				
2368	Contact angle of 0 degrees is not permitted				
2369	Cycle cannot be used with drilling tools				
2373	Tool contact angle Q629 doesn't equal 0				
2374	Selection of view in Q622 doesn't equal 0				
2389	Tool contact angle Q629 equals 0				
2390	Dispersion tolerance exceeded				
2391	Vision system not calibrated for measurement				
2392	Faulty entry: R-OFFS				
2393	Faulty entry: L-OFFS				
2394	Faulty entry in VTC.tab				
2395	Faulty entry: measuring length				

Fehlernummer	Text				
2396	Faulty entry: measuring length				
2397	Incorrect tool data				
2398	Faulty entry: measuring angle				
2399	Maximum measuring length exceeded				
2400	Maximum measuring radius exceeded				
2401	Error while measuring with length zero				
2402	Tool outside of measuring range				
2403	Faulty entry: R-OFFS				
2404	No temperature compensation reference				
2405	Faulty entry: tool length				
2406	Incorrect tool type				
2407	Faulty entry: tolerance				
2408	Incorrect tool data				
2409	Faulty cycle data				
2410	Faulty tool data				
2411	Wear tolerance exceeded				
2412	Calibration failed				
2413	Faulty entry: R-OFFS				

## 4 System data

## 4.1 List of FN functions

The FN 18: SYSREAD (ISO: D18) function can be used to read numeric system data and save the values in numeric parameters (e.g., FN 18: SYSREAD Q25 = ID210 NR4 IDX3).



The control always outputs system data in the metric system with **FN 18: SYSREAD**, regardless of the unit of the NC program.

The SYSSTR function can be used to read alphanumeric system data and save the values in string parameters (e.g., QS25 = SYSSTR( ID 10950 NR1 )).

Group name	Group number ID	System data number NO	Index IDX	Description
Program i	information			
	10	3	-	Number of the active machining cycle
		6	-	Number of the most recently executed touch probe cycle -1 = None
		7	-	Type of calling NC program:  -1 = None 0 = Visible NC program 1 = Cycle/macro, main program is visible 2 = Cycle/macro, there is no visible main program
		8	1	Unit of measure of the directly calling NC program (may also be a cycle). Return codes: 0 = mm 1 = inch -1 = there is no corresponding program
			2	Unit of measure of the NC program visible in the block display from which the current cycle was called directly or indirectly.  Return codes: 0 = mm 1 = inch -1 = there is no corresponding program
		9	-	Within an M function macro: Number of the M function. Otherwise −1
			-	Within an M function macro: Number of the M function. Otherwise −1
		10	-	Repeat counter: Indicates the number of times the current code has been executed since the current NC program call
		103	Q parameter number	Relevant within NC cycles; for inquiry as to whether the Q parameter given under IDX was explicitly stated in the associated CYCLE DEF.
		110	QS parame- ter no.	Is there a file with the name QS(IDX)? 0 = No, 1 = Yes This function resolves relative file paths.
		111	QS parame- ter no.	Is there a directory with the name QS(IDX)?  0 = no, 1 = Yes  Only absolute directory paths are possible.

Group name	Group number ID	System data number NO	Index IDX	Description
System ju	mp addresses			
	13	1	-	Label number or label name (string or QS) jumped to during M2/M30 instead of ending the current NC program.  Value = 0: M2/M30 have the normal effect
		2	-	Number or name (string or QS) of the label to which the NC program will jump if <b>FN 14: ERROR</b> has been programmed with the NC CANCEL reaction, instead of aborting the NC program with an error message. The error number programmed in the <b>FN 14</b> command can be read under ID992 NR14.  Value = 0: <b>FN 14</b> has a normal effect.
		3	-	Label number or label name (string or QS) jumped to in the event of an internal server error (SQL, PLC, CFG) or with erroneous file operations (FUNCTION FILECOPY, FUNCTION FILEMOVE, or FUNCTION FILEDELETE) instead of aborting the NC program with an error message.  Value = 0: Error has the normal effect.
Indexed a	ccess to Q param	eters		
	15	11	Q parameter number	Reads Q(IDX)
		12	QL parame- ter no.	Reads QL(IDX)
		13	QR parame- ter no.	Reads QR(IDX)
Machine s	status			
	20	1	-	Active tool number
		2	-	Prepared tool number
		3	-	Active tool axis 0 = X 6 = U 1 = Y 7 = V 2 = Z 8 = W
		4	-	Programmed spindle speed
		5	-	Active spindle condition -1 = spindle condition not defined 0 = M3 active 1 = M4 active 2 = M5 active after M3 3 = M5 active after M4
		7	-	Active gear range
		8	-	Active coolant status 0 = off, 1 = on

Group name	Group number ID	System data number NO	Index IDX	Description
		9	-	Active feed rate
		10	-	Index of prepared tool
		11	-	Index of active tool
		14	-	Number of active spindle
		20	-	Programmed cutting speed in turning operation
		21	-	Spindle mode in turning mode: 0 = constant speed 1 = constant cutting speed
		22	-	Coolant status M7: 0 = inactive, 1 = active
		23	-	Coolant status M8: 0 = inactive, 1 = active

Group name	Group number ID	System data number NO	Index IDX	Description
Channel d	lata			
	25	1	-	Channel number
Cycle par	ameters			
	30	1	-	Set-up clearance
		2	-	Hole depth / milling depth
		3	-	Plunging depth
		4	-	Feed rate for plunging
		5	-	First side length of pocket
		6	-	Second side length of pocket
		7	-	First side length of slot
		8	-	Second side length of slot
		9	-	Radius of circular pocket
		10	-	Feed rate for milling
		11	-	Rotational direction of the milling path
		12	-	Dwell time
		13	-	Thread pitch for Cycles 17 and 18
		14	-	Finishing allowance
		15	-	Roughing angle
		21	-	Probing angle
		22	-	Probing path
		23	-	Probing feed rate
		48	-	Tolerance
		49	-	HSC mode (Cycle 32 Tolerance)
		50	-	Tolerance for rotary axes (Cycle 32 Toler ance)
		52	Q parameter number	Type of transfer parameter for user cycles:  -1: Cycle parameter not programmed in CYCL DEF  0: Cycle parameter numerically programmed in CYCL DEF (Q parameter)  1: Cycle parameter programmed as strinin CYCL DEF (Q parameter)
		60	-	Clearance height (touch probe cycles 30 to 33)
		61	-	Inspection (touch probe cycles 30 to 33)
		62	-	Cutting edge measurement (touch probe cycles 30 to 33)
		63	-	Q parameter number for the result (touch probe cycles 30 to 33)

Group name	Group number ID	System data number NO	Index IDX	Description
		64	-	Q parameter type for the result (touch probe cycles 30 to 33) 1 = Q, 2 = QL, 3 = QR
		70	-	Multiplier for feed rate (cycles 17 and 18)

Group name	Group number ID	System data number NO	Index IDX	Description
Modal sta	ntus			
	35	1	-	Dimensions: 0 = absolute (G90) 1 = incremental (G91)
		2	-	Radius compensation: 0 = R0 1 = RR/RL 10 = Face milling 11 = Peripheral milling
Data for S	QL tables			
	40	1	-	Result code for the last SQL command. If the last result code was 1 (=error), the error code is transferred as the return code.
Data from	the tool table			
	50	1	Tool no.	Tool length L
		2	Tool no.	Tool radius R
		3	Tool no.	Tool radius R2
		4	Tool no.	Oversize for tool length DL
		5	Tool no.	Tool radius oversize DR
		6	Tool no.	Tool radius oversize DR2
		7	Tool no.	Tool locked TL 0 = not locked, 1 = locked
		8	Tool no.	Number of the replacement tool RT
		9	Tool no.	Maximum tool age TIME1
		10	Tool no.	Maximum tool age TIME2
		11	Tool no.	Current tool age CUR.TIME
		12	Tool no.	PLC status
		13	Tool no.	Maximum tooth length LCUTS
		14	Tool no.	Maximum plunge angle ANGLE
		15	Tool no.	TT: Number of tool teeth CUT
		16	Tool no.	TT: Wear tolerance for length, LTOL
		17	Tool no.	TT: Wear tolerance for radius, RTOL
		18	Tool no.	TT: Direction of rotation DIRECT 0 = positive, -1 = negative
		19	Tool no.	TT: Offset in plane R-OFFS R = 99999.9999
		20	Tool no.	TT: Offset in length L-OFFS
		21	Tool no.	TT: Breakage tolerance for length, LBREAK
		22	Tool no.	TT: Breakage tolerance for radius, RBREAK

Group name	Group number ID	System data number NO	Index IDX	Description
		28	Tool no.	Maximum speed NMAX
		32	Tool no.	Point angle TANGLE
		34	Tool no.	LIFTOFF allowed (0 = No, 1 = Yes)
		35	Tool no.	Wear tolerance for radius R2TOL
		36	Tool no.	Tool type TYPE (miller = 0, grinder = 1, touch probe = 21)
		37	Tool no.	Corresponding line in the touch-probe table
		38	Tool no.	Timestamp of last use
		39	Tool no.	ACC
		40	Tool no.	Pitch for thread cycles
		41	Tool no.	AFC: reference load
		42	Tool no.	AFC: overload early warning
		43	Tool no.	AFC: overload NC stop
		44	Tool no.	Exceeding the tool life
		45	Tool no.	Front-face width of indexable insert (RCUTS)
		46	Tool no.	Usable length of the milling cutter
		47	Tool no.	Neck radius of the milling cutter (RN)

Group name	Group number ID	System data number NO	Index IDX	Description
Data from	the pocket table			
	51	1	Pocket number	Tool number
		2	Pocket number	0 = no special tool 1 = special tool
		3	Pocket number	0 = no fixed pocket 1 = fixed pocket
		4	Pocket number	0 = pocket not locked 1 = pocket locked
		5	Pocket number	PLC status
Determine	e the tool pocket			
	52	1	Tool no.	Pocket number
		2	Tool no.	Tool magazine number
File inforr	nation			
	56	1	-	Number of lines of the tool table
		2	-	Number of lines of the active datum table
		4	-	Number of rows in a freely definable table that has been opened with <b>FN 26: TABOPEN</b>
Tool data	for T and S strobe	es		
	57	1	T code	Tool number IDX0 = T0 strobe (store tool), IDX1 = T1 strobe (load tool), IDX2 = T2 strobe (prepare tool)
		2	T code	Tool index IDX0 = T0 strobe (store tool), IDX1 = T1 strobe (load tool), IDX2 = T2 strobe (prepare tool)
		5	-	Spindle speed IDX0 = T0 strobe (store tool), IDX1 = T1 strobe (load tool), IDX2 = T2 strobe (prepare tool)
Values pr	ogrammed in TOO	L CALL		
	60	1	-	Tool number T
		2	-	Active tool axis 0 = X 1 = Y 2 = Z 6 = U 7 = V 8 = W
		3	-	Spindle speed S
		4	-	Oversize for tool length DL
		5	-	Tool radius oversize DR
		6	-	Automatic TOOL CALL 0 = Yes, 1 = No

Group name	Group number ID	System data number NO	Index IDX	Description
		7	-	Tool radius oversize DR2
		8	-	Tool index
		9	-	Active feed rate
		10	-	Cutting speed [mm/min]
/alues pr	ogrammed in TO	DL DEF		
	61	0	Tool no.	Read the number of the tool change sequence:  0 = Tool already in spindle  1 = Change between external tools  2 = Change from internal to external tool  3 = Change from special tool to external tool  4 = Load external tool  5 = Change from external to internal tool  6 = Change from internal to internal tool  7 = Change from special tool to internal tool  8 = Load internal tool  9 = Change from external tool to special tool  10 = Change from special tool to internal tool  11 = Change from special tool to internal tool  12 = Load special tool  13 = Unload external tool  14 = Unload internal tool  15 = Unload special tool
		1	-	Tool number T
		2	-	Length
		3	-	Radius
		4	-	Index
		5	-	Tool data programmed in TOOL DEF 1 = Yes, 0 = No

Group name	Group number ID	System data number NO	Index IDX	Description
Values pr	ogrammed with F	UNCTION TURN	DATA	
	62	1	-	Tool length oversize DXL
		2	-	Tool length oversize DYL
		3	-	Tool length oversize DZL
		4	-	Cutting radius oversize DRS
/alues fo	r LAC and VSC			
	71	0	0	Index of the NC axis for which the LAC weighing run will be performed or was last performed (X to W = 1 to 9)
			2	Total inertia determined by the LAC weighing run in [kgm²] (with A/B/C rotary axes) or total mass in [kg] (with X/Y/Z linear axes)
		1	0	Cycle 957 Retraction from thread
nformati	on about HEIDEN	HAIN cycles		
	71	20	0	Configuration information for dressing: ( <b>CfgDressSettings</b> ) Maximum search path / set-up clearance
			1	Configuration information for dressing: (CfgDressSettings) Search speed (with acoustic emission sensor)
			2	Configuration information for dressing: ( <b>CfgDressSettings</b> ) Feed-rate factor (contact-free motion)
			3	Configuration information for dressing: ( <b>CfgDressSettings</b> ) Feed-rate factor at wheel side
			4	Configuration information for dressing: ( <b>CfgDressSettings</b> ) Feed-rate factor at wheel radius
			5	Tool information for dressing: ( <b>toolgrind.grd</b> ) Retraction amount in Z (inside)
			6	Tool information for dressing: ( <b>toolgrind.grd</b> ) Retraction amount in Z (outside)
			7	Machining information for dressing: Retraction amount in X (diameter)
			8	Machining information for dressing: Ratio of cutting speed
			9	Machining information for dressing: Programmed number of dressing tool
			10	Machining information for dressing: Programmed number of dressing kinematics

Group name	Group number ID	System data number NO	Index IDX	Description
			11	Machining information for dressing: TCPM active/inactive
			12	Machining information for dressing: Programmed position of rotary axis
			13	Machining information for dressing: Cutting speed of the grinding wheel
			14	Machining information for dressing: Rotational speed of dressing spindle
			15	Machining information for dressing: Magazine number of dresser
			16	Machining information for dressing: Pocket number of dresser
		21	0	Configuration information for grinding: ( <b>CfgGrindSettings</b> ) Infeed velocity (synchronous reciprocation)
			1	Configuration information for grinding: ( <b>CfgGrindSettings</b> ) Search speed (with acoustic emission sensor)
			2	Configuration information for grinding: ( <b>CfgGrindSettings</b> ) Relief amount
			3	Configuration information for grinding: ( <b>CfgGrindSettings</b> ) Dimensional control offset
		22	0	Configuration information for behavior when the sensor has not responded. (CfgGrindEvents/sensorNotReached) IDX: Sensor
		23	0	Configuration information for behavior when the sensor is already active at the start.  (CfgGrindEvents/sensorActiveAtStart) IDX: Sensor
		24	1	Configuration information for the event additionally used by a sensor function: (CfgGrindEvents/sensorSource2) Sensor function = Infeed with touch probe
			2	Configuration information for the event additionally used by a sensor function: (CfgGrindEvents/sensorSource2) Sensor function = Infeed with acoustic emission sensor
			3	Configuration information for the event additionally used by a sensor function: (CfgGrindEvents/sensorSource2) Sensor function = Infeed with dimensional control

Group name	Group number ID	System data number NO	Index IDX	Description
			9	Configuration information for the event additionally used by a sensor function: ( <b>CfgGrindEvents/sensorSource2</b> ) Sensor function = OEM-specific interaction 1
			10	Configuration information for the event additionally used by a sensor function: ( <b>CfgGrindEvents/sensorSource2</b> ) Sensor function = OEM-specific interaction 2
			11	Configuration information for the event additionally used by a sensor function: (CfgGrindEvents/sensorSource2) Sensor function = Intermediate dressing
			12	Configuration information for the event additionally used by a sensor function: (CfgGrindEvents/sensorSource2) Sensor function = Teach button
		25	1	Configuration information for the relief amount of a sensor function (CfgGrindEvents/sensorReleave) Sensor function = Infeed with touch prob
			2	Configuration information for the relief amount of a sensor function (CfgGrindEvents/sensorReleave) Sensor function = Infeed with acoustic emission sensor
			3	Configuration information for the relief amount of a sensor function (CfgGrindEvents/sensorReleave) Sensor function = Infeed with dimension al control
			9	Configuration information for the relief amount of a sensor function (CfgGrindEvents/sensorReleave) Sensor function = OEM-specific interaction 1
			10	Configuration information for the relief amount of a sensor function ( <b>CfgGrindEvents/sensorReleave</b> ) Sensor function = OEM-specific interaction 2
			11	Configuration information for the relief amount of a sensor function (CfgGrindEvents/sensorReleave) Sensor function = Intermediate dressing
			12	Configuration information for the relief amount of a sensor function (CfgGrindEvents/sensorReleave) Sensor function = Teach button

Group name	Group number ID	System data number NO	Index IDX	Description
		26	1	Configuration information for the type of reaction to an event of a sensor function ( <b>CfgGrindEvents/sensorReaction</b> ) Sensor function = Infeed with touch probe
			2	Configuration information for the type of reaction to an event of a sensor function ( <b>CfgGrindEvents/sensorReaction</b> ) Sensor function = Infeed with acoustic emission sensor
			3	Configuration information for the type of reaction to an event of a sensor function (CfgGrindEvents/sensorReaction) Sensor function = Infeed with dimensional control
			9	Configuration information for the type of reaction to an event of a sensor function ( <b>CfgGrindEvents/sensorReaction</b> ) Sensor function = OEM-specific interaction 1
			10	Configuration information for the type of reaction to an event of a sensor function ( <b>CfgGrindEvents/sensorReaction</b> ) Sensor function = OEM-specific interaction 2
			11	Configuration information for the type of reaction to an event of a sensor function ( <b>CfgGrindEvents/sensorReaction</b> ) Sensor function = Intermediate dressing
			12	Configuration information for the type of reaction to an event of a sensor function ( <b>CfgGrindEvents/sensorReaction</b> ) Sensor function = Teach button
		27	1	Configuration information for the event additionally used by a sensor function (CfgGrindEvents/sensorSource) Sensor function = Infeed with touch probe
			2	Configuration information for the event additionally used by a sensor function ( <b>CfgGrindEvents/sensorSource</b> ) Sensor function = Infeed with acoustic emission sensor
			3	Configuration information for the event additionally used by a sensor function (CfgGrindEvents/sensorSource) Sensor function = Infeed with dimensional control

Group name	Group number ID	System data number NO	Index IDX	Description
			9	Configuration information for the event additionally used by a sensor function ( <b>CfgGrindEvents/sensorSource</b> ) Sensor function = OEM-specific interaction 1
			10	Configuration information for the event additionally used by a sensor function: ( <b>CfgGrindEvents/sensorSource</b> ) Sensor function = OEM-specific interaction 2
			11	Configuration information for the event additionally used by a sensor function ( <b>CfgGrindEvents/sensorSource</b> ) Sensor function = Intermediate dressing
			12	Configuration information for the event additionally used by a sensor function ( <b>CfgGrindEvents/sensorSource</b> ) Sensor function = Teach button
		28	0	Configuration information for the assignment of override sources to grinding functions: (CfgGrindOverrides) Cylindrical grinding: override source for reciprocating movement
			1	Configuration information for the assignment of override sources to grinding functions:  (CfgGrindOverrides)  Cylindrical grinding: override source for infeed movement
			2	Configuration information for the assignment of override sources to grinding functions:  (CfgGrindOverrides)  Surface grinding: override source for reciprocating movement
			3	Configuration information for the assignment of override sources to grinding functions: (CfgGrindOverrides) Surface grinding: override source for infeed movement
			4	Configuration information for the assignment of override sources to grinding functions: (CfgGrindOverrides) Special grinding: override source for reciprocating movement
			5	Configuration information for the assignment of override sources to grinding functions:

Group name	Group number ID	System data number NO	Index IDX	Description
				( <b>CfgGrindOverrides</b> ) Special grinding: override source for infeed movement
			6	Configuration information for the assignment of override sources to grinding functions: (CfgGrindOverrides) Jig grinding (reciprocating stroke)
			7	Configuration information for the assignment of override sources to grinding functions: (CfgGrindOverrides) General movements in the infeed generator (example: general movement with/ without sensor)
			8	Configuration information for the assignment of override sources to grinding functions: (CfgGrindOverrides) General movements in the infeed generator (example: movement with acoustic emission sensor)
			9	Configuration information for the assignment of override sources to grinding functions: (CfgGrindOverrides) General movements in the infeed generator (example: movement with touch probe)

Group name	Group number ID	System data number NO	Index IDX	Description
Freely ava	ailable memory a	rea for OEM cycl	es	
	72	0-39	0 to 30	Freely available memory area for OEM cycles. The values are only reset by the control during a control reboot (= 0). With "Cancel," the values are not reset to the value that they had at the time of execution.  Up to and including 597110-11: only NR 0-9 and IDX 0-9  Starting with 597110-12: NR 0-39 and IDX 0-30
Freely ava	ailable memory a	rea for user cycle	es	
	73	0-39	0 to 30	Freely available memory area for user cycles The values are only reset by the control during a control reboot (= 0). With "Cancel," the values are not reset to the value that they had at the time of execution. Up to and including 597110-11: only NR 0-9 and IDX 0-9 Starting with 597110-12: NR 0-39 and IDX 0-30
Read min	imum and maxin	num spindle spee	d	
	90	1	Spindle ID	Minimum spindle speed of the lowest gear stage. If no gear stages are configured, CfgFeedLimits/minFeed of the first parameter set of the spindle is evaluated. Index 99 = active spindle
		2	Spindle ID	Maximum spindle speed from the highest gear stage. If no gear stages are configured, CfgFeedLimits/maxFeed of the first parameter set of the spindle is evaluated. Index 99 = active spindle
Tool com	pensation			
	200	1	1 = without oversize 2 = with oversize 3 = with oversize and oversize from TOOL CALL	Active radius
		2	1 = without oversize 2 = with oversize 3 = with oversize and oversize from TOOL CALL	Active length

Group name	Group number ID	System data number NO	Index IDX	Description
		3	1 = without oversize 2 = with oversize 3 = with oversize and oversize from TOOL CALL	Rounding radius R2
		6	Tool no.	Tool length Index 0= active tool
Coordinat	te transformation	s		
	210	1	-	Basic rotation (manual)
		2	-	Programmed rotation
		3	-	Active mirror axis. Bits 0 to 2 and 6 to 8: Axes X, Y, Z and U, V, W
		4	Axis	Active scaling factor Index: 1 to 9 (X, Y, Z, A, B, C, U, V, W)
		5	Rotary axis	3D-ROT Index: 1 to 3 (A, B, C)
		6	-	Tilt working plane in Program Run operat- ing modes 0 = Not active -1 = Active
		7	-	Tilt working plane in Manual operating modes 0 = Not active -1 = Active
		8	QL parame- ter no.	Angle of misalignment between spindle and tilted coordinate system. Projects the angle specified in the QL parameter from the input coordinate system to the tool coordinate system. If IDX is omitted, the angle 0 is used for projection.
		10	-	Type of definition of the active tilt:  0 = no tilt—is returned if, both in <b>Manual Operation</b> and in the automatic modes, no tilt is active.  1 = axial  2 = spatial angle
		11	-	Coordinate system for manual movements:  0 = Machine coordinate system M-CS  1 = Working plane coordinate system WPL-CS  2 = Tool coordinate system T-CS  4 = Workpiece coordinate system W-CS

Group name	Group number ID	System data number NO	Index IDX	Description
		12	Axis	Correction in working plane coordinate system <b>WPL-CS</b> (FUNCTION TURNDATA CORR WPL or FUNCTION CORRDATA WPL) Index: 1 to 9 (X, Y, Z, A, B, C, U, V, W)

Group name	Group number ID	System data number NO	Index IDX	Description
Active co	ordinate system			
	211	-	-	1 = input system (default) 2 = REF system 3 = tool change system
Special tra	ansformations in	turning mode		<u> </u>
	215	1	-	Angle for the precession of the input system in the XY plane in turning mode. To reset the transformation the value 0 must be entered for the angle. This transformation is used in connection with Cycle 800 (parameter Q497).
		3	1-3	Reading out of the spatial angle written with NR2 Index: 1 to 3 (rotA, rotB, rotC)
Current da	atum shift			
	220	2	Axis	Current datum shift in [mm] Index: 1 to 9 (X, Y, Z, A, B, C, U, V, W)
		3	Axis	Read the difference between reference point and preset. Index: 1 to 9 (X, Y, Z, A, B, C, U, V, W)
		4	Axis	Read OEM offset values Index: 1 to 9 (X_OFFS, Y_OFFS, Z_OF-FS,)
Traverse	range			
	230	2	Axis	Negative software limit switches Index: 1 to 9 (X, Y, Z, A, B, C, U, V, W)
		3	Axis	Positive software limit switches Index: 1 to 9 (X, Y, Z, A, B, C, U, V, W)
		5	-	Software limit switch on or off: 0 = on, 1 = off For modulo axes, either both the upper and lower limits or no limit at all must be set.
Read the	nominal position	in the REF syste	m	
	240	1	Axis	Current nominal position in the REF system
Read the	nominal position	in the REF syste	m, including off	sets (handwheel, etc.)
	241	1	Axis	Current nominal position in the REF system
Nominal p	oositions of the pl	hysical axes in th	ne REF system	
	245	1	Axis	Current nominal positions of the physical axes in the REF system
Read the	current position i	n the active coor	dinate system	
	270	1	Axis	Current nominal position in the input system When called while tool radius compen-

Group name	Group number ID	System data number NO	Index IDX	Description
				sation is active, the function supplies the uncompensated positions for the principal axes X, Y, and Z. If the function is called for a rotary axis and tool radius compensation is active, an error message is issued.  Index: 1 to 9 ( X, Y, Z, A, B, C, U, V, W )
Read the	current position i	n the active coor	dinate system,	including offsets (handwheel, etc.)
	271	1	Axis	Current nominal position in the input system
Read info	rmation to M128			
	280	1	-	M128 active: -1 = Yes, 0 = No
		3	-	Condition of TCPM after Q No.: Q No. + 0: TCPM active, 0 = no, 1 = yes Q No. + 1: AXIS, 0 = POS, 1 = SPAT Q No. + 2: PATHCTRL, 0 = AXIS, 1 = VECTOR Q No. + 3: Feed rate, 0 = F TCP, 1 = F CONT
Machine	kinematics			
	290	5	-	0: Temperature compensation not active 1: Temperature compensation active
		10	-	Index of the machine kinematics from Channels/ChannelSettings/CfgKin- List/kinCompositeModels programmed in FUNCTION MODE MILL or FUNCTION MODE TURN –1 = Not programmed.
Read data	of the machine l	kinematics		
	295	1	QS parame- ter no.	Read the axis names of the active 3-axis kinematics. The axis names are written according to QS(IDX), QS(IDX+1), and QS(IDX+2).  0 = Operation successful
		2	0	Is FACING HEAD POS function active? 1 = Yes, 0 = No
		4	Rotary axis	Read whether the defined rotary axis participates in the kinematic calculation. 1 = Yes, 0 = No (A rotary axis can be excluded from the kinematics calculating using M138.) Index: 4, 5, 6 (A, B, C)
		5	Secondary axis	Read whether the given secondary axis is used in the kinematics model.  -1 = Axis not in the kinematics model 0 = Axis is not included in the kinematics calculation:

Group name	Group number ID	System data number NO	Index IDX	Description
		6	Axis	Angle head: Displacement vector in the basic coordinate system B-CS through angle head Index: 1, 2, 3 ( X, Y, Z )
		7	Axis	Angle head: Direction vector of the tool in the basic coordinate system B-CS Index: 1, 2, 3 ( X, Y, Z )
		10	Axis	Determine programmable axes. Determine the axis ID associated with the specified axis index (index from CfgAxis/axisList).  Index: 1 to 9 ( X, Y, Z, A, B, C, U, V, W )
		11	Axis ID	Determine programmable axes. Determine the index of the axis (X = 1, Y = 2,) for the specified axis ID Index: Axis ID (index from CfgAxis/axis/List)

Group name	Group number ID	System data number NO	Index IDX	Description
Modify th	e geometrical be	havior		
	310	20	Axis	Diameter programming: -1 = on, 0 = off
		126	-	M126: –1 = on, 0 = off
current s	ystem time			
	320	1	0	System time in seconds that have elapsed since 01.01.1970, 00:00:00 (real time).
			1	System time in seconds that have elapsed since 01.01.1970, 00:00:00 (look ahead calculation).
		3	-	Read the processing time of the current NC program.
ormattin	ng of system time	0	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: DD.MM.YYYY hh:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: DD.MM.YYYY hh:mm:ss
	1	1	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YYYY h:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YYYY h:mm:ss
		2	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YYYY h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YYYY h:mm
		3	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YY h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YY h:mm

Group name	Group number ID	System data number NO	Index IDX	Description
		4	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: YYYY-MM-DD hh:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation) Format: YYYY-MM-DD hh:mm:ss
		5	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: YYYY-MM-DD hh:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation) Format: YYYY-MM-DD hh:mm
		6	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: YYYY-MM-DD h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation Format: YYYY-MM-DD h:mm
		7	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: YY-MM-DD h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation Format: YY-MM-DD h:mm
		8	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: DD.MM.YYYY
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation Format: DD.MM.YYYY
		9	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: D.MM.YYYY
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation Format: D.MM.YYYY

Group name	Group number ID	System data number NO	Index IDX	Description
		10	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YY
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YY
		11	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: YYYY-MM-DD
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation) Format: YYYY-MM-DD
		12	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: YY-MM-DD
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation Format: YY-MM-DD
		13	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: hh:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation) Format: hh:mm:ss
		14	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: h:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation) Format: h:mm:ss
		15	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (real time) Format: h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC or January 1, 1970 (look-ahead calculation) Format: h:mm

Group name	Group number ID	System data number NO	Index IDX	Description
		16	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: DD.MM.YYYY hh:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: DD.MM.YYYY hh:mm
		20	0	The current calendar week number according to ISO 8601 (real time)
			1	The current calendar week number according to ISO 8601 (look-ahead calculation)
Slobal Pro	ogram Settings (0	GPS): Global acti	vation status	
	330	0	-	0 = No Global Program Settings active 1 = Any GPS settings active
lobal Pr	ogram Settings (0	GPS): Individual a	activation statu	s
	331	0	-	0 = No Global Program Settings active 1 = Any GPS settings active
		1	-	GPS: Basic rotation 0 = Off, 1 = On
		3	Axis	GPS: Mirroring 0 = Off, 1 = On Index: 1 - 6 (X, Y, Z, A, B, C)
		4	-	GPS: Shift in the modified workpiece system 0 = Off, 1 = On
		5	-	GPS: Rotation in input system 0 = Off, 1 = On
		6	-	GPS: Feed rate factor 0 = Off, 1 = On
		8	-	GPS: Handwheel superimpositioning 0 = Off, 1 = On
		10	-	GPS: Virtual tool axis VT 0 = Off, 1 = On
		15	-	GPS: Selection of the handwheel coordinate system 0 = Machine coordinate system M-CS 1 = Workpiece coordinate system W-CS 2 = Modified workpiece coordinate system mW-CS 3 = Working plane coordinate system WPL-CS
		16	-	GPS: Shift in the workpiece system 0 = Off, 1 = On
		17	-	GPS: Axis offset 0 = Off, 1 = On

Group name	Group number ID	System data number NO	Index IDX	Description
Slobal Pro	ogram Settings (G	GPS)		
	332	1	-	GPS: Angle of a basic rotation
		3	Axis	GPS: Mirroring 0 = Not mirrored, 1 = Mirrored Index: 1 to 6 ( X, Y, Z, A, B, C )
		4	Axis	GPS: Shift in the modified workpiece coordinate system mW-CS Index: 1 to 6 ( X, Y, Z, A, B, C )
		5	-	GPS: Angle of rotation in input coordinate system I-CS
		6	-	GPS: Feed rate factor
		8	Axis	GPS: Handwheel superimpositioning Maximum value Index: 1 to 10 ( X, Y, Z, A, B, C, U, V, W, VT )
		9	Axis	GPS: Value for handwheel superimpositioning Index: 1 to 10 ( X, Y, Z, A, B, C, U, V, W, VT )
		16	Axis	GPS: Shift in the workpiece coordinate system W-CS Index: 1 to 3 ( X, Y, Z )
		17	Axis	GPS: Axis offset Index: 4 to 6 ( A, B, C )
'S touch	trigger probe			
	350	50	1	Touch probe type: 0: TS120, 1: TS220, 2: TS440, 3: TS630, 4: TS632, 5: TS640, 6: TS444, 7: TS740
			2	Line in the touch-probe table
		51	-	Effective length
		52	1	Effective radius of the stylus tip
			2	Rounding radius
		53	1	Center offset (reference axis)
			2	Center offset (minor axis)
		54	-	Spindle-orientation angle in degrees (center offset)
		55	1	Rapid traverse
			2	Measuring feed rate
			3	Feed rate for pre-positioning: FMAX_PROBE or FMAX_MACHINE
		56	1	Maximum measuring range
			2	Set-up clearance
		57	1	Spindle orientation possible 0=No, 1=Yes
			2	Angle of spindle orientation in degrees

Group name	Group number ID	System data number NO	Index IDX	Description
TT tool to	uch probe for too	l measurement		
	350	70	1	TT: Touch probe type
			2	TT: Line in the tool touch probe table
			3	TT: Designation of the active line in the touch-probe table
			4	TT: Touch probe input
		71	1/2/3	TT: Touch probe center (REF system)
		72	-	TT: Touch probe radius
		75	1	TT: Rapid traverse
			2	TT: Measuring feed rate with stationary spindle
			3	TT: Measuring feed rate with rotating spindle
		76	1	TT: Maximum probing path
			2	TT: Safety clearance for linear measurement
			3	TT: Safety clearance for radius measure- ment
			4	TT: Distance from the lower edge of the cutter to the upper edge of the stylus
		77	-	TT: Spindle speed
		78	-	TT: Probing direction
		79	-	TT: Activate radio transmission
			-	TT: Stop probing movement upon stylus deflection
		100	-	Distance after which the probe is deflected during touch probe simulation

Group name	Group number ID	System data number NO	Index IDX	Description
Preset fro	om touch probe cy	/cle (probing resi	ults)	
	360	1	Coordinate	Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (input coordinate system). Compensations: length, radius, and center offset
		2	Axis	Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (machine coordinate system, only axes from the active 3D kinematics are allowed as index).  Compensation: only center offset
		3	Coordinate	Result of measurement in the input system of touch probe Cycles 0 and 1. The measurement result is read out in the form of coordinates. Compensation: only center offset
		4	Coordinate	Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (workpiece coordinate system). The measurement result is read in the form of coordinates.  Compensation: only center offset
		5	Axis	Axis values, not compensated
		6	Coordinate / axis	Readout of the measurement results in the form of coordinates / axis values in the input system from probing operations.  Compensation: only length
		10	-	Oriented spindle stop
		11	-	Error status of probing:  0: Probing was successful  -1: Touch point not reached  -2: Touch probe already deflected at the start of the probing process

Group name	Group number ID	System data number NO	Index IDX	Description
Settings f	or touch probe cy	/cles		
	370	2	-	Rapid traverse for measurement
		3	-	Machine rapid traverse as rapid traverse for measurement
		5	-	Angle tracking on/off
		6	-	Automatic measuring cycles: interruption with info about on/off
		7	-	Reaction when the automatic 14xx measuring cycle does not reach the probing point:  0 = Cancellation  1 = Warning  2 = No message In case of values 1 and 2, the measurement result must be evaluated, and a corresponding reaction is required.
Read valu	es from or write	values to the act	ive datum table	
	500	Row number	Column	Read values
Read valu	es from or write	alues to the pre	set table (basic	transformation)
	507	Row number	1-6	Read values
Read axis	offsets from or v	vrite axis offsets	to the preset ta	ble
	508	Row number	1-9	Read values
Data for p	allet machining			
	510	1	-	Active line
		2	-	Current pallet number. Read value of the NAME column of the last PAL-type entry. If the column is empty or does not contain a numerical value, a value of -1 is returned.
		3	-	Active row of the pallet table.
		4	-	Last line of the NC program for the current pallet.
		5	Axis	Tool-oriented editing: Clearance height is programmed: 0 = No, 1 = Yes Index: 1 - 9 ( X, Y, Z, A, B, C, U, V, W )
		6	Axis	Tool-oriented editing: Clearance height The value is invalid if ID510 NR5 returns the value 0 with the corresponding IDX. Index: 1 - 9 ( X, Y, Z, A, B, C, U, V, W )
		10	-	Row number up to which the pallet table is to be searched during block scan.
		20	-	Type of pallet editing? 0 = Workpiece-oriented 1 = Tool oriented

Group name	Group number ID	System data number NO	Index IDX	Description
		21	-	Automatic continuation after NC error:  0 = Locked  1 = Active  10 = Abort continuation  11 = Continuation with the rows in the pallet table that would have been executed next if not for the NC error  12 = Continuation with the row in the pallet table in which the NC error arose  13 = Continuation with the next pallet

Group name	Group number ID	System data number NO	Index IDX	Description
Read data	from the point t	able		
	520	Row number	10	Read value from active point table.
			11	Read value from active point table.
			1-3 X/Y/Z	Read value from active point table.
Read or w	rite the active pr	eset		
	530	1	-	Number of the active preset in the active preset table.
Active pa	llet preset			
	540	1	-	Number of the active pallet preset. Returns the number of the active preset. If no pallet preset is active, then the function returns the value -1.
		2	-	Number of the active pallet preset. Same as NO1.
Values fo	r the basic transf	formation of the p	pallet preset	
	547	Row number	Axis	Read the basic transformation values from the pallet-preset table Index: 1 to 6 (X, Y, Z, SPA, SPB, SPC)
Axis offse	ets from the palle	et preset table		
	548	Row number	Offset	Read the axis-offset values from the pallet preset table Index: 1 to 9 ( X_OFFS, Y_OFFS, Z_OFFS, )
OEM offs	et			
	558	Row number	Offset	Read values for OEM offset Index: 4 to 9 ( A_OFFS, B_OFFS, C_OF-FS, )
Read and	write the machin	ne status		
	590	2	1-30	Freely available; not deleted during program selection.
		3	1-30	Freely available; not deleted during a power failure (persistent storage).
Read/writ	e look-ahead par	rameter of a sing	le axis (at mach	ine level)
	610	1	-	Minimum feed rate ( <b>MP_minPathFeed</b> ) ir mm/min
		2	-	Minimum feed rate at corners ( <b>MP_min- CornerFeed</b> ) in mm/min
		3	-	Feed-rate limit for high speeds (MP_maxG1Feed) in mm/min
		4	-	Max. jerk at low speeds ( <b>MP_maxPath-</b> <b>Jerk</b> ) in m/s³
		5	-	Max. jerk at high speeds (MP_maxPath- JerkHi) in m/s <sup>3</sup>

Group name	Group number ID	System data number NO	Index IDX	Description
		6	-	Tolerance at low speeds (MP_pathToler- ance) in mm
		7	-	Tolerance at high speeds (MP_pathToleranceHi) in mm
		8	-	Max. derivative of jerk ( <b>MP_maxPa-thYank</b> ) in m/s <sup>4</sup>
		9	-	Tolerance factor for curve machining (MP_curveTolFactor)
		10	-	Factor for max. permissible jerk at curvature changes (MP_curveJerkFactor)
		11	-	Maximum jerk with probing movements (MP_pathMeasJerk)
		12	-	Angle tolerance for machining feed rate (MP_angleTolerance)
		13	-	Angle tolerance for rapid traverse (MP_angleToleranceHi)
		18	-	Radial acceleration with machining feed rate (MP_maxTransAcc)
		19	-	Radial acceleration with rapid traverse (MP_maxTransAccHi)
		20	Index of physical axis	Max. feed rate ( <b>MP_maxFeed</b> ) in mm/ min
		21	Index of physical axis	Max. acceleration (MP_maxAcceleration in m/s <sup>2</sup>
		22	Index of physical axis	Maximum transition jerk of the axis in rapid traverse ( <b>MP_axTransJerkHi</b> ) in mas <sup>2</sup>
		23	Index of physical axis	Maximum transition jerk of the axis during machining free rate ( <b>MP_axTransJerk</b> ) in m/s <sup>3</sup>
		24	Index of physical axis	Acceleration feedforward control (MP_compAcc)
		25	Index of physical axis	Axis-specific jerk at low speeds (MP_ax-PathJerk) in m/s <sup>3</sup>
		26	Index of physical axis	Axis-specific jerk at high speeds (MP_ax- PathJerkHi) in m/s <sup>3</sup>
		27	Index of physical axis	More precise tolerance examination in corners ( <b>MP_reduceCornerFeed</b> ) 0 = deactivated, 1 = activated
		28	Index of physical axis	DCM: Maximum tolerance for linear axes in mm ( <b>MP_maxLinearTolerance</b> )
		29	Index of physical axis	DCM: Maximum angle tolerance in [°] (MP_maxAngleTolerance)
		30	Index of physical axis	Tolerance monitoring for successive threads (MP_threadTolerance)

Group name	Group number ID	System data number NO	Index IDX	Description
		31	Index of physical axis	Form (MP_shape) of the axisCutterLoc filter 0: Off 1: Average 2: Triangle 3: HSC 4: Advanced HSC
		32	Index of physical axis	Frequency (MP_frequency) of the axisCutterLoc filter in Hz
		33	Index of physical axis	Form (MP_shape) of the axisPosition filter 0: Off 1: Average 2: Triangle 3: HSC 4: Advanced HSC
		34	Index of physical axis	Frequency (MP_frequency) of the axisPosition filter in Hz
		35	Index of physical axis	Order of the filter for <b>Manual</b> operating mode ( <b>MP_manualFilterOrder</b> )
		36	Index of physical axis	HSC mode (MP_hscMode) of the axisCutterLoc filter
		37	Index of physical axis	HSC mode (MP_hscMode) of the axisPosition filter
		38	Index of physical axis	Axis-specific jerk for probing movements (MP_axMeasJerk)
		39	Index of physical axis	Weighting of the filter error for calculating filter deviation (MP_axFilterErrWeight)
		40	Index of physical axis	Maximum filter length of position filter (MP_maxHscOrder)
		41	Index of physical axis	Maximum filter length of CLP filter (MP_maxHscOrder)
		42	-	Maximum feed rate of the axis at machining feed rate ( <b>MP_maxWorkFeed</b> )
		43	-	Maximum path acceleration at machining feed rate ( <b>MP_maxPathAcc</b> )
		44	-	Maximum path acceleration at rapid traverse (MP_maxPathAccHi)
		45	-	Shape of the smoothing filter (CfgSmoothingFilter/shape) 0 = Off 1 = Average 2 = Triangle
		46	F	Order of smoothing filter (only odd- numbered values) ( <b>CfgSmoothingFilter/order</b> )

Group name	Group number ID	System data number NO	Index IDX	Description
		49	-	Filter reduction mode (CfgPositionFilter/timeGainAtStop) 0 = Off 1 = NoOvershoot 2 = FullReduction
		51	Index of physical axis	Compensation of following error in the jerk phase ( <b>MP_lpcJerkFact</b> )
		52	Index of physical axis	kv factor of the position controller in 1/s (MP_kvFactor)
		53	Index of physical axis	Radial jerk, normal feed rate ( <b>MP_max- TransJerk</b> )
		54	Index of physical axis	Radial jerk, high feed rate ( <b>MP_maxTran- sJerkHi</b> )
Read or w	rite look-ahead p	parameters of a s	ingle axis (at cy	cle level)
	613	see ID610	see ID610	Same as ID610 but is only in effect at the cycle level. Overwrite values from the machine configuration and values at the machine level. <b>Further information:</b> "FN functions ID610, ID611, ID613", Page
Measure	the maximum util	ization of an axis	3	
	621	0	Index of physical axis	Conclude measurement of the dynamic load and save the result in the specified Q parameter.
Read SIK	contents			
	630	0	Option no.	You can explicitly determine whether the SIK option given under <b>IDX</b> has been set or not.  1 = option is enabled 0 = option is not enabled
		1	-	You can determine whether a Feature Content Level (for upgrade functions) is set, and which one. -1 = No FCL is set <no.> = FCL that is set</no.>
		2	-	Read serial number of the SIK -1 = No valid SIK in the system
		3	-	Read the SIK type (generation) 1 = SIK1 or no SIK 2 = SIK2
		4	Option number (4 digits)	Read the status of a software option (only available with SIK2) 0 = Not enabled 1 or higher = Number of enabled options
		10	-	Define the type of control: 0 = iTNC 530 1 = NCK-based control (TNC7, TNC 640, TNC 620, TNC 320, TNC 128, PNC 610,

Group name	Group number ID	System data number NO	Index IDX	Description
General d	ata of the grindin	g wheel		
	780	2	-	Width
		3	-	Overhang
		4	-	Alpha angle (optional)
		5	-	Gamma angle (optional)
		6	-	Depth (optional)
		7	-	Rounding radius at the "Further" edge (optional)
		8	-	Rounding radius at the "Nearer" edge (optional)
		9	-	Rounding radius at the "Nearest" edge (optional)
		10	-	Active edge:  1 = Further  2 = Nearer  3 = Nearest  4 = Special  5 = FurtherBack  6 = NearerBack  7 = NearestBack  8 = SpecialBack  9 = FurtherWheelRad  10 = NearerWheelRad
		11	-	Type of grinding wheel (straight / angular)
		12	-	External or internal wheel?
		13	-	Compensation angle of the B axis (with respect to the base angle of the location)
		14	-	Type of angular wheel
		15	-	Total length of the grinding wheel
		16	-	Length of the inner edge of the grinding wheel
		17	-	Minimum wheel diameter (wear limit)
		18	-	Minimum wheel width (wear limit)
		19	-	Tool number
		20	-	Cutting speed
		21	-	Maximum permissible cutting speed
		27	-	Wheel basic type: with relief cut
		28	-	Relief cut on the outside
		29	-	Relief cut on the inside
		30	-	Definition status
		31	-	Radius compensation
		32	-	Compensation of total length
		33		Compensation of overhang

Group name	Group number ID	System data number NO	Index IDX	Description
		34	-	Compensation for the length to the innermost edge
		35	-	Radius of the shaft of the grinding wheel
		36	-	Initial dressing performed?
		37	-	Dresser location for initial dressing
		38	-	Dresser tool for initial dressing
		39	-	Has the grinding wheel been measured?
		51	-	Dresser tool for dressing on the diameter
		52	-	Dresser tool for dressing on the outer edge
		53	-	Dresser tool for dressing on the inner edge
		54	-	Dressing of the diameter according to the number of calls
		55	-	Dressing of the outer edge according to the number of calls
		56	-	Dressing of the inner edge according to the number of calls
		57	-	Dressing counter of the diameter
		58	-	Dressing counter of the outer edge
		59	-	Dressing counter of the inner edge
		60	-	Selection of compensation method
		61	-	Inclination angle of dressing tool
		101	-	Radius of grinding wheel

Group name	Group number ID	System data number NO	Index IDX	Description
Datum sh	ift for the grindin	ng wheel		
	781	1	Axis	Datum shift from calibrating the front edges
		2	Axis	Datum shift from calibrating the rear edges
		3	Axis	Datum shift from setup
		4	Axis	Programmed wheel-specific datum shift
		5-9	Axis	Additional wheel-specific datum shift
Geometry	of the grinding v	wheel		
	782	1	-	Wheel shape
		2	-	Overrun on the outer side
		3	-	Overrun on the inner side
		4	-	Overrun diameter
Detailed g	geometry (contou	ır) of the grinding	wheel	
	783	1	1	Chamfer width of the outer side of the wheel
			2	Chamfer width of the inner side of the wheel
		2	1	Chamfer angle of the outer side of the wheel
			2	Chamfer angle of the inner side of the wheel
		3	1	Corner radius of the outer side of the wheel
			2	Corner radius of the inner side of the wheel
		4	1	Side length of the outer side of the wheel
			2	Side length of the inner side of the wheel
		5	1	Relief length of the outer side of the wheel
			2	Relief length of the inner side of the whee
		6	1	Relief angle of the outer side of the wheel
			2	Relief angle of the inner side of the wheel
	7	7	1	Recess length of the outer side of the wheel
			2	Recess length of the inner side of the wheel
		8	1	Departing radius of the outer side of the wheel
			2	Departing radius of the inner side of the wheel
		9	1	Total depth on the outside

Group name	Group number ID	System data number NO	Index IDX	Description
			2	Total depth on the inside
ata for d	lressing the grind	ing wheel		
	784	1	-	Number of safety positions
		5	-	Dressing method
		6	-	Number of the dressing program
		7	-	Amount of infeed for dressing
		8	-	Angle of infeed / infeed direction for dressing
		9	-	Number of repetitions for dressing
		10	-	Number of idle strokes for dressing
		11	-	Feed rate for dressing on the diameter
		12	-	Feed rate factor for dressing the side (with respect to NR11)
		13	-	Feed rate factor for dressing radii (with respect to NR11)
		14	-	Feed rate factor for dressing angular wheels (with respect to NR11)
		15	-	Feed rate outside the wheel, for pre-profiling
		16	-	Feed rate factor inside the wheel (with respect to NR15), for pre-profiling
		25	-	Dressing method for intermediate dressing
		26	-	Number of the program for intermediate dressing
		27	-	Amount of infeed for intermediate dressing
		28	-	Angle of infeed / infeed direction for intermediate dressing
		29	-	Number of repetitions for intermediate dressing
		30	-	Number of idle strokes for intermediate dressing
		31	-	Feed rate for intermediate dressing

Group name	Group number ID	System data number NO	Index IDX	Description
Safety po	sitions for the gri	nding wheel		
	785	1	Axis	Safety position no. 1
		2	Axis	Safety position no. 2
		3	Axis	Safety position no. 3
		4	Axis	Safety position no. 4
Data of th	e dressing tool fo	or the grinding wh	neel	
	789	1	-	Type
		2	-	Length L1
		3	-	Length L2
		4	-	Radius
		5	-	Orientation: 1=RadType1, 2=RadType2, 3=RadType3
		10	-	Rotational speed of the dressing spindle

Group name	Group number ID	System data number NO	Index IDX	Description
Read Fund	ctional Safety (F	S) information		
	820	1	-	FS limitations: 0 = No Functional Safety (FS) 1 = Guard door open (SOM1) 2 = Guard door open (SOM2) 3 = Guard door open (SOM3) 4 = Guard door open (SOM4) 5 = All guard doors closed
Write data	for unbalance r	nonitoring		
	850	10	-	Activate and deactivate unbalance monitoring 0 = unbalance monitoring not active 1 = unbalance monitoring active
Counter				
	920	1	-	Planned workpieces. In <b>Test Run</b> operating mode the counter generally generates the value 0.
		2	-	Already machined workpieces. In <b>Test Run</b> operating mode the counter generally generates the value 0.
		12	-	Workpieces still to be machined. In <b>Test Run</b> operating mode the counter generally generates the value 0.
Read and	write data of cui	rent tool		
	950	1	-	Tool length L
		2	-	Tool radius R
		3	-	Tool radius R2
		4	-	Oversize for tool length DL
		5	-	Tool radius oversize DR
		6		Tool radius oversize DR2
		7	-	Tool locked TL 0 = not locked, 1 = locked
		8	-	Number of the replacement tool RT
		9	-	Maximum tool age TIME1
		10		Maximum tool age TIME2 at TOOL CALL
		11	-	Current tool age CUR.TIME
		12	-	PLC status
		13	-	Tooth length in the tool axis LCUTS
		14	-	Maximum plunge angle ANGLE
		15	-	TT: Number of tool teeth CUT
		16	-	TT: Wear tolerance for length LTOL
		17	-	TT: Wear tolerance for radius RTOL

Group name	Group number ID	System data number NO	Index IDX	Description
		18	-	TT: Direction of rotation DIRECT 0 = positive, –1 = negative
		19	-	TT: Offset in plane R-OFFS R = 99999.9999
		20	-	TT: Offset in length L-OFFS
		21	-	TT: Break tolerance for length LBREAK
		22	-	TT: Break tolerance for radius RBREAK
		28	-	Maximum spindle speed [rpm] NMAX
		32	-	Point angle TANGLE
		34	-	LIFTOFF allowed (0 = No, 1 = Yes)
		35	-	Wear tolerance for radius R2TOL
		36	-	Tool type TYPE (miller = 0, grinder = 1, touch probe = 21)
		37	-	Corresponding line in the touch-probe table
		38	-	Timestamp of last use
		39	-	ACC
		40	-	Pitch for thread cycles
		41	-	AFC: reference load
		42	-	AFC: overload early warning
		43	-	AFC: overload NC stop
		44	-	Exceeding the tool life
		45	-	Front-face width of indexable insert (RCUTS)
		46	-	Usable length of the milling cutter
		47	-	Neck radius of the milling cutter (RN)
		48	-	Radius at the tool tip (R_TIP)

Group name	Group number ID	System data number NO	Index IDX	Description
Read and	write data of curr	ent turning tool		
	951	1	-	Tool number
		2	-	Tool length XL
		3	-	Tool length YL
		4	-	Tool length ZL
		5	-	Tool length oversize DXL
		6	-	Oversize in tool length DYL
		7	-	Tool length oversize DZL
		8	-	Tooth radius (RS)
		9	-	Tool orientation (TO)
		10	-	Angle of spindle orientation (ORI)
		11	-	Tool angle P_ANGLE
		12	-	Point angle T_ANGLE
		13	-	Recessing width CUT_WIDTH
		14	-	Type (e.g. roughing, finishing, threading, recessing or button tool)
		15	-	Length of cutting edge CUT_LENGTH
		16	-	Compensation of workpiece diameter WPL-DX-DIAM in the working plane coordinate system WPL-CS
		17	-	Compensation of workpiece diameter WPL-DZL in the working plane coordinate system WPL-CS
		18	-	Recessing width oversize
		19	-	Cutting radius oversize
		20	-	Rotation around spatial angle B for offset recessing tools

Group name	Group number ID	System data number NO	Index IDX	Description
Data of th	e currently activ	e dresser		
	952	1	-	Tool number
		2	-	Tool length XL
		3	-	Tool length YL
		4	-	Tool length ZL
		5	-	Oversize for tool length DXL
		6	-	Oversize for tool length DYL
		7	-	Oversize for tool length DZL
		8	-	Cutter radius
		9	-	Cutting position
		13	-	Cutter width for plate or roll
		14	-	Type (e.g. diamond, plate, spindle, roll)
		19	-	Cutter radius oversize
		20	-	Shaft speed of a dressing spindle or roll
ransforn	nation data for g	eneral tools		
	960	1	-	Position within the tool system explicitly defined:
		2	-	Position defined by directions:
		3	-	Shift in X
		4	-	Shift in Y
		5	-	Shift in Z
		6	-	X component of the Z direction
		7	-	Y component of the Z direction
		8	-	Z component of the Z direction
		9	-	X component of the X direction
		10	-	Y component of the X direction
		11	-	Z component of the X direction
		12	-	Type of angle definition:
		13	-	Angle 1
		14	-	Angle 2
		15	-	Angle 3

Group name	Group number ID	System data number NO	Index IDX	Description
Tool usag	e and tooling			
	975	1	-	Tool usage test for the current NC program: Result –2: Test not possible, function disabled in the configuration Result –1: Test not possible, tool usage file missing Result 0: Test OK, all tools available Result 1: Test not OK
		2	Line	Check availability of the tools required in the pallet from line IDX in the current pallet table.  -3 = No pallet is defined in row IDX, or function was called outside of pallet editing  -2 / -1 / 0 / 1 see NO1
Touch pro	be cycles and co	ordinate transfo	rmations	
	990	1	-	Approach behavior:  0 = Standard behavior  1 = Approach probing position without compensation. Effective radius, set-up clearance is zero
		2	16	Automatic / Manual machine operating modes
		4	-	0 = Stylus not deflected 1 = Stylus deflected
		6	-	TT tool touch probe active? 1 = Yes 0 = No
		8	-	Momentary spindle angle in [°]
		10	QS parameter no.	Determine the tool number from the tool name. The return value depends on the rules configured for the search of the replacement tool.  If there are multiple tools with the same name, the first tool from the tool table will be selected.  If the tool selected by these rules is locked, a replacement tool will be returned.  -1: No tool with the specified name found in the tool table or all qualifying tools are locked.
		16	0	0 = Transfer control over the channel spindle to the PLC, 1 = Assume control over the channel spindle
			1	0 = Pass tool spindle control to the PLC, 1 = Take control of the tool spindle

Group name	Group number ID	System data number NO	Index IDX	Description
		19	-	Suppress touch prove movement in cycles:  0 = Movement will be suppressed (CfgMachineSimul/simMode parameter not equal to FullOperation or <b>Test Run</b> operating mode is active)  1 = Movement will be performed (CfgMachineSimul/simMode parameter = FullOperation, can be programmed for testing purposes)
		28	-	Read inclination angle of the current tool spindle

Group name	Group number ID	System data number NO	Index IDX	Description
Status of	execution			
	992	10	-	Block scan active 1 = yes, 0 = no
		11	-	Block scan—information on block scan:  0 = NC program started without block scan  1 = Iniprog system cycle is run before block scan  2 = Block scan is running  3 = Functions are being updated  -1 = Iniprog cycle was canceled before block scan  -2 = Cancellation during block scan  -3 = Cancellation of the block scan after the search phase, before or during the update of functions  -99 = Implicit cancellation
		12	-	Type of canceling for interrogation within the OEM_CANCEL macro:  0 = No cancellation  1 = Cancellation due to error or emergency stop  2 = Explicit cancellation with internal stop after stop in the middle of the block  3 = Explicit cancellation with internal stop after stop at the end of a block
		14	-	Number of the last FN 14 error
		16	-	Real execution active? 1 = execution, 0 = simulation
		17	-	2D graphics during programming active? 1 = Yes 0 = No
		18	-	Live programming graphics ( AUTO DRAW soft key) active? 1 = Yes 0 = No
		20	-	Information on combined milling/turning mode of operation:  0 = Milling (after FUNCTION MODE MILL)  1 = Turning (after FUNCTION MODE TURN)  10 = Execute the operations for the turning-to-milling transition  11 = Execute the operations for the milling-to-turning transition
		21	-	Cancellation during dressing operation for querying within the OEM_CANCEL macro: 0 = Cancellation was not during dressing

Group name	Group number ID	System data number NO	Index IDX	Description
				operation 1 = Cancellation during dressing opera- tion
		30	-	Interpolation of multiple axes permitted? 0 = No (e.g. for straight cut control) 1 = yes
		31	-	R+/R- possible/permitted in MDI mode? 0 = No 1 = Yes
		32	Cycle number	Single cycle enabled: 0 = No 1 = Yes
		33	-	Write-access enabled for DNC (Python scripts) for executed entries in the pallet table:  0 = No 1 = Yes
		40	-	Copy tables in <b>Test Run</b> operating mode? Value 1 will be set when a program is selected and when the <b>RESET+START</b> soft key is pressed. The <b>iniprog.h</b> system cycle will then copy the tables and reset the system datum.  0 = no 1 = yes
		41	50	Read units of measure for system datum ID50 (access to tool table). Default: metric units.  0 = Metric 1 = Unit of the active NC program
			507	Reading of the units of measure for accessing the preset table. Default: metric units.  0 = Metric 1 = Unit of the active NC program
		101	-	M101 active (visible condition)? 0 = no 1 = yes
		136	-	M136 active? 0 = no 1 = yes

Group name	Group number ID	System data number NO	Index IDX	Description
Activate r	nachine parame	ter subfile		
	1020	13	QS parame- ter no.	Has a machine parameter subfile with path from QS number (IDX) been loaded?  1 = Yes 0 = No
Configura	ition settings for	cycles		
	1030	1	-	Display the <b>Spindle is not rotating</b> error message (CfgGeoCycle/ <b>displaySpindleErr</b> ) 0 = No, 1 = Yes
		2	-	Display the <b>Check the depth sign</b> error message (CfgGeoCycle/ <b>displayDepthErr</b> ) 0 = No, 1 = Yes
Data trans	sfer between HE	IDENHAIN cycles	and OEM macro	os
	1031	1	0	Component monitoring: counter of the measurement. Cycle 238 Measure machine data automatically increments this counter.
			1	Component monitoring: Type of measure- ment  -1 = No measurement  0 = Circular interpolation test  1 = Waterfall chart test  2 = Frequency response  3 = Envelope curve spectrum  4 = Advanced frequency response
			2	Component monitoring: Index of the axis from CfgAxes\ <b>axisList</b>
			3 – 9	Component monitoring: further arguments depend on the measurement
		2	3 – 9	Component monitoring: further arguments depend on the measurement
		3	0	KinematicsOpt: Read the current cycle number (450-453)
		100	-	Component monitoring: optional names of the monitoring tasks, as specified in <b>System\Monitoring\CfgMonComponent</b> . After completion of the measurement, the monitoring tasks stated here are executed consecutively. When assigning the input parameters, remember to separate the listed monitoring tasks by commas.

Group name	Group number ID	System data number NO	Index IDX	Description
User setti	ings for the user	interface		
	1070	1	-	Feed rate limit of soft key FMAX; 0 = FMAX is inactive
Bit test				
	2300	Number	Bit number	This function checks whether a bit has been set in a number. The number to be checked is transferred as NR, the bit to be searched for as IDX, with IDX0 designating the least significant bit. To call this function for large numbers, make sure to transfer NR as a Q parameter.  0 = Bit not set 1 = Bit set
Program	information (sys	tem string)		
	10010	1	0/1/2/3	IDX0 = Complete path of the current main program of pallet program IDX1 = File path of the directory where the NC program is located IDX2 = Name of the NC program, without the path and file extension IDX3 = File extension of the NC program
		2	0/1/2/3	IDX0 = Complete path of the NC program visible in the block display IDX1 = File path of the directory where the NC program is located IDX2 = Name of the NC program without the path and file extension IDX3 = File extension of the NC program
		3	-	Path of the cycle selected with <b>SEL CYCLE</b> or <b>CYCLE DEF 12 PGM CALL</b> , or path of the currently active cycle
		10	-	Path of the NC program selected with <b>SEL PGM ""</b> .
Indexed a	ccess to QS para	ameters		
	10015	20	QS parame- ter no.	Reads QS(IDX)
		30	QS parame- ter no.	Returns the string that you obtain if you replace anything except for letters and digits in QS(IDX) by '_'.
Read cha	nnel data (syster	n string)		
	10025	1	-	Name of machining channel (key)
Read data	a for SQL tables (	(system string)		
	10040	1	-	Symbolic name of the preset table.
		2	-	Symbolic name of the datum table.
		3	-	Symbolic name of the pallet preset table.
		10	-	Symbolic name of the tool table.

Group name	Group number ID	System data number NO	Index IDX	Description
		11	-	Symbolic name of the pocket table.
		12	-	Symbolic name of the turning tool table
		13	-	Symbolic name of the grinding tool table
		14	-	Symbolic name of the dressing tool table
		21	-	Symbolic name of the compensation table in the T-CS tool coordinate system
		22	-	Symbolic name of the compensation table in the WPL-CS working plane coordinate system

Group name	Group number ID	System data number NO	Index IDX	Description
Values pr	ogrammed in the	tool call (system	n string)	
	10060	1	-	Tool name
Read mad	chine kinematics	(system strings)		
	10290	10	-	Symbolic name of the machine kinematics from Channels/ChannelSettings/CfgKinList/kinCompositeModels programmed in <b>FUNCTION MODE MILL</b> or <b>FUNCTION MODE TURN</b> .
Traverse	range switchove	r (system string)		
	10300	1	-	Key name of the last active range of traverse
Read curr	ent system time	(system string)		
	10321	0 - 16, 20		0: DD.MM.YYYY hh:mm:ss 1: D.MM.YYYY h:mm:ss 2: D.MM.YYYY h:mm 3: D.MM.YY h:mm 4: YYYY-MM-D hh:mm:ss 5: YYYY-MM-DD hh:mm 6: YYYY-MM-DD h:mm 7: YY-MM-DD h:mm 8: DD.MM.YYYY 9: D.MM.YYYY 10: D.MM.YYYY 10: D.MM.YYYY 11: YYYY-MM-DD 12: YY-MM-DD 13: hh:mm:ss 14: h:mm:ss 15: h:mm 16: DD.MM.YYYY hh:mm 20: Calendar week as per ISO 8601 Alternatively, with <b>DAT</b> in <b>SYSSTR()</b> , a system time in seconds can be provided that is to be used for formatting.
Read data	of touch probes	s (TS, TT) (systen	n string)	
	10350	50	-	Type of TS probe from TYPE column of the touch probe table ( <b>tchprobe.tp</b> )
		51	-	Shape of stylus from column STYLUS in the touch probe table ( <b>tchprobe.tp</b> ).
		70	-	Type of TT tool touch probe from CfgTT/type.
		73	-	Key name of the active tool touch probe TT from <b>CfgProbes/activeTT</b> .
		74	-	Serial number of the active tool touch probe TT from <b>CfgProbes/activeTT</b> .
Read the	data for pallet m	achining (system	string)	
	10510	_1	-	Pallet name
		2		Path of the selected pallet table.

Group name	Group number ID	System data number NO	Index IDX	Description
Read versi	on ID of the NC s	oftware (system	string)	
	10630	10	-	The string corresponds to the format of the version ID shown (e.g., <b>340590 09</b> or <b>817601 05 SP1</b> )
General da	nta of the grinding	g wheel		
	10780	1	-	Name of wheel
Read infor	mation on unbala	ance cycle (syste	em string)	
	10855	1	-	Path of the unbalance calibration table belonging to the active kinematics
Read data	of the current to	ol (system string	)	
	10950	1	-	Current tool name
		2	-	Entry from the DOC column of the active tool
		3	-	AFC control setting
		4	-	Tool-carrier kinematics
		5	-	Entry from the DR2TABLE column – file name of the compensation value table for 3D-ToolComp
		6	-	Entry from the TSHAPE column - file name of the 3D tool shape (*.stl)
Read infor	mation from OEN	/ macros and HE	IDENHAIN cycl	les (system string)
	11031	10	-	Returns the selection of the FUNCTION MODE SET <oem mode=""> macro as a string.</oem>
		100	-	Cycle 238: list of key names for component monitoring
		101	-	Cycle 238: file names for log file

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