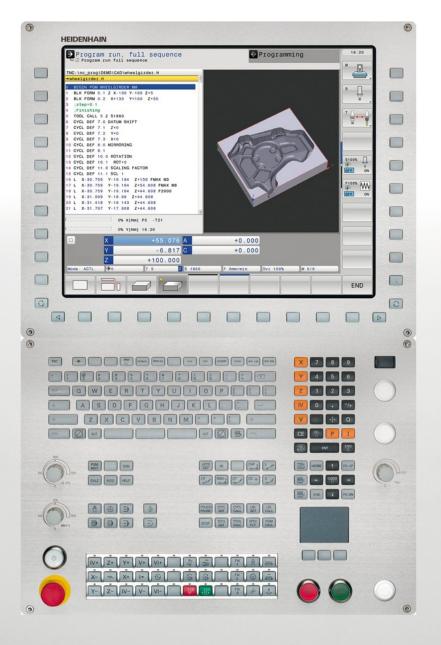


# HEIDENHAIN



# **TNC 640**

User's Manual

# HEIDENHAIN Conversational Programming

NC Software 340590-02 340591-02 340594-02

English (en) 5/2013

# **Controls of the TNC**

#### Keys on visual display unit

Кеу	Function
$\bigcirc$	Select split screen layout
$\bigcirc$	Toggle the display between machining and programming modes
	Soft keys for selecting functions on screen
$\triangleleft \triangleright \triangle$	Shifting between soft-key rows

#### Alphanumeric keyboard

#### Key

Function

()G

File names, comments

DIN/ISO programming S

#### Machine operating modes

Кеу	Function
	Manual operation
	Electronic handwheel
	Positioning with manual data input
	Program run, single block
•	Program run, full sequence

#### **Programming modes**

Кеу	Function
$\Rightarrow$	Programming
$\overline{-}$	Test run

#### Program/file management, **TNC functions**

Кеу	Function
PGM MGT	Select or delete programs and files, external data transfer
PGM CALL	Define program call, select datum and point tables
MOD	Select MOD functions
HELP	Display help text for NC error messages, call TNCguide
ERR	Display all current error messages
CALC	Show calculator

#### **Navigation keys**

Key		Function
t	+	Move highlight
бото П		Go directly to blocks, cycles and parameter functions

#### Potentiometer for feed rate and spindle speed

#### Feed rate

Spindle speed





# Cycles, subprograms and program section repeats

Кеу		Function
TOUCH PROBE		Define touch probe cycles
CYCL DEF	CYCL CALL	Define and call cycles
LBL SET	LBL CALL	Enter and call labels for subprogramming and program section repeats
STOP		Enter program stop in a program

# **Tool functions**

Кеу	Function
TOOL DEF	Define tool data in the program
TOOL	Call tool data

# Programming path movements

Кеу	Function
	Approach/depart contour
FK	FK free contour programming
Lyp	Straight line
ф Ф	Circle center/pole for polar coordinates
𝔔 <sup>c</sup>	Circular arc with center
CR	Circle with radius
CT ?	Circular arc with tangential connection
CHF o: Lo	Chamfer/Corner rounding

# **Special functions**

Кеу		Function
 SPEC FCT		Show special functions
		Select the next tab in forms
 Ħ	<b>I</b>	Up/down one dialog box or button

# Entering and editing coordinate axes and numbers

Кеу	Function
<b>XV</b>	Select coordinate axes or enter them in a program
09	Numbers
• -/+	Decimal point / Reverse algebraic sign
ΡΙ	Polar coordinate input / Incremental values
Q	Q-parameter programming / Q parameter status
	Save actual position or values from calculator
NO ENT	Skip dialog questions, delete words
ENT	Confirm entry and resume dialog
	Conclude block and exit entry
CE	Clear numerical entry or TNC error message
DEL	Abort dialog, delete program section

**Controls of the TNC** 

**Fundamentals** 

# **Fundamentals**

About this manual

# About this manual

The symbols used in this manual are described below.



This symbol indicates that important notes about the function described must be regarded.

This symbol indicates that there is one or more of the following risks when using the described function:

- Danger to workpiece
- Danger to fixtures
- Danger to tool
- Danger to machine
- Danger to operator



This symbol indicates a possibly dangerous situation that may cause light injuries if not avoided.



This symbol indicates that the described function must be adapted by the machine tool builder. The function described may therefore vary depending on the machine.



This symbol indicates that you can find detailed information about a function in another manual.

# Would you like any changes, or have you found any errors?

We are continuously striving to improve our documentation for you. Please help us by sending your requests to the following e-mail address: **tnc-userdoc@heidenhain.de**.

# TNC model, software and features

This manual describes functions and features provided by TNCs as of the following NC software numbers.

TNC model	NC software number
TNC 640	340590-02
TNC 640 E	340591-02
TNC 640 Programming Station	340594-02

The suffix E indicates the export version of the TNC. The export version of the TNC has the following limitations:

Simultaneous linear movement in up to 4 axes

The machine tool builder adapts the usable features of the TNC to his machine by setting machine parameters. Some of the functions described in this manual may therefore not be among the features provided by the TNC on your machine tool.

TNC functions that may not be available on your machine include:

Tool measurement with the TT

Please contact your machine tool builder to become familiar with the features of your machine.

Many machine manufacturers, as well as HEIDENHAIN, offer programming courses for the TNCs. We recommend these courses as an effective way of improving your programming skill and sharing information and ideas with other TNC users.



#### User's Manual for Cycle Programming:

All of the cycle functions (touch probe cycles and fixed cycles) are described in the Cycle Programming User's Manual. Please contact HEIDENHAIN if you require a copy of this User's Manual. ID: 892905-xx

# TNC model, software and features

#### Software options

The TNC 640 features various software options that can be enabled by your machine tool builder. Each option is to be enabled separately and contains the following respective functions:

during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)         •       Keeping the tool normal to the contour         •       Tool radius compensation perpendicular to traversing and tool direct         Interpolation       •         Interpolation number 18)       •         Input resolution and display step       •         Input resolution and display step       •         Input resolution Monitoring (DCM) software option (option number 40)         Collision Monitoring in all machine operating modes       •         •       The machine manufacturer defines objects to be monitored         •       Three warning levels in manual operation         •       Program interrupt during automatic operation         •       Norwegian         •       Slovenian         •       Slovenian         •       Norwegian         •       Korean         •       Estonian         •       Turkish         •       Romanian	Hardware, options		
Software option 1 (option number 08) Rotary table machining Programming of cylindrical contours as if in two axes Feed rate in distance per minute Coordinate transformation Vorking plane, tilting the Interpolation Clicicle in 3 axes with tilted working plane (spacial arc) Software option 2 (option number 09) 3-D machining Motion control with minimum jerk 3-D tool compensation through surface normal vectors Using the electronic handwheel to change the angle of the swivel h during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management) Keeping the tool normal to the contour Tool radius compensation perpendicular to traversing and tool direct Interpolation Linear in 5 axes (subject to export permit) HEIDENHAIN DNC (option number 18) Communication with external PC applications over COM componen Display step (Option number 23) Input resolution and display Linear axes to 0.01 µm Step Donamic Collision Monitoring (DCM) software option (option number 40) Collision monitoring in all The machine manufacturer defines objects to be monitored Three warning levels in manual operation Three warning levels in monual operation Ner locudes monitoring of 5-axis movements Software option for additional conversational languages (option number 41) Additional conversational Slovak Latvian Korean Korean Formation Formati			1st additional axis for 4 axes plus spindle
Rotary table machining       Programming of cylindrical contours as if in two axes         Feed rate in distance per minute         Coordinate transformation       Working plane, tilting the         Interpolation       Circle in 3 axes with tilted working plane (spacial arc)         Software option 2 (option number 09)       3-D machining         3-D machining       Motion control with minimum jerk         3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel h during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)         Keeping the tool normal to the contour         Tool radius compensation perpendicular to traversing and tool direct         Interpolation       Linear in 5 axes (subject to export permit)         HEIDENHAIN DNC (option number 18)       Communication with external PC applications over COM componen         Display step (Option number 23)       Linear axes to 0.01 µm         step       Ether axes to 0.0001°         Dynamic Collision Monitoring (DCM) software option (option number 40)       Three warning levels in manual operation         Collision monitoring in all machine manufacturer defines objects to be monitored       Three warning levels in monual operation         Includes monitoring of 5-axis movements       Software option for additional conversational languages (option number 41)         Ad			2nd additional axis for 5 axes plus spindle
<ul> <li>Feed rate in distance per minute</li> <li>Coordinate transformation</li> <li>Working plane, tilting the</li> <li>Interpolation</li> <li>Circle in 3 axes with tilted working plane (spacial arc)</li> <li>Software option 2 (option number 09)</li> <li>3-D machining</li> <li>Motion control with minimum jerk</li> <li>3-D tool compensation through surface normal vectors</li> <li>Using the electronic handwheel to change the angle of the swivel h during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)</li> <li>Keeping the tool normal to the contour</li> <li>Tool radius compensation perpendicular to traversing and tool direct</li> <li>Interpolation</li> <li>Linear in 5 axes (subject to export permit)</li> <li>HEIDENHAIN DNC (option number 18)</li> <li>Communication with external PC applications over COM componen</li> <li>Display step (Option number 23)</li> <li>Input resolution and display</li> <li>Linear axes to 0.01 µm</li> <li>Rotary axes to 0.0001°</li> <li>Dynamic Collision Monitoring (DCM) software option (option number 40)</li> <li>Collision monitoring in all</li> <li>There warning levels in manual operation</li> <li>Includes monitoring of 5-axis movements</li> <li>Software option for additional conversational languages (option number 41)</li> <li>Additional conversational</li> <li>Slovak</li> <li>Latvian</li> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	Software option 1 (option nur	nber (	)8)
Coordinate transformation       Working plane, tilting the         Interpolation       Circle in 3 axes with tilted working plane (spacial arc)         Software option 2 (option number 09)       3-D machining       Motion control with minimum jerk         3-D machining       Motion control with minimum jerk       3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel he during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)       Keeping the tool normal to the contour         Tool radius compensation perpendicular to traversing and tool direct       Tool radius compensation perpendicular to traversing and tool direct         Interpolation       Linear in 5 axes (subject to export permit)         HEIDENHAIN DNC (option number 18)       Communication with external PC applications over COM componen         Display step (Option number 23)       Elinear axes to 0.01 µm         Rep       Elinear axes to 0.01 µm         Step       The machine manufacturer defines objects to be monitored         Three warning levels in manual operation       Includes monitoring of 5-axis movements         Software option for additional conversational languages (option number 41)       Additional conversational         Rolowaia       Slovakia       Latvian         Norwegian       Slovakia       Estonian         Romanian	Rotary table machining		Programming of cylindrical contours as if in two axes
Interpolation Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Control with minimum jerk Circle in 3 axes with tilted working plane (spacial arc) Software option 2 (option number 09) 3-D machining Circle in 3 axes with tilted working plane (spacial arc) Software option 2 (option number 09) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with tilted working plane (spacial arc) Circle in 3 axes with the during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management) Exception the tool normal to the contour Exception to and display Communication with external PC applications over COM componen Display step (Option number 23) Exception for additional Conversation (option number 40) Collision monitoring in all Circle in a additional conversational languages (option number 41) Additional conversational Conversional Circle additional conversational languages (option number 41) Circle additional conversational Circle add			Feed rate in distance per minute
Software option 2 (option number 09) 3-D machining      A divion control with minimum jerk      3-D tool compensation through surface normal vectors      Using the electronic handwheel to change the angle of the swivel h     during program run without affecting the position of the tool point.     (TCPM = Tool Center Point Management)      Keeping the tool normal to the contour      Tool radius compensation perpendicular to traversing and tool direct Interpolation      Linear in 5 axes (subject to export permit)  HEIDENHAIN DNC (option number 18)      Communication with external PC applications over COM componen  Display step (Option number 23)  Input resolution and display     E Linear axes to 0.01 µm     Rotary axes to 0.00001°  Dynamic Collision Monitoring (DCM) software option (option number 40)  Collision monitoring in all     machine operating modes      The machine manufacturer defines objects to be monitored     Three warning levels in manual operation     Includes monitoring of 5-axis movements  Software option for additional conversational languages (option number 41)  Additional conversational     Slovak     Latvian     Slovak     Latvian     Korean     Estonian     Turkish     Romanian	Coordinate transformation		Working plane, tilting the
3-D machining       Motion control with minimum jerk         3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel he during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)         Keeping the tool normal to the contour         Tool radius compensation perpendicular to traversing and tool direct         Interpolation       Linear in 5 axes (subject to export permit)         HEIDENHAIN DNC (option number 18)       Communication with external PC applications over COM componen         Display step (Option number 23)       Communication with external PC applications over COM componen         Dynamic Collision Monitoring (DCM)       software option (option number 40)         Collision monitoring in all machine manufacturer defines objects to be monitored       Three warning levels in manual operation         Program interrupt during automatic operation       Includes monitoring of 5-axis movements         Software option for additional conversational languages (option number 41)       Norwegian         Additional conversational languages       Slovenian         Extorian       Extorian         Extorian       Extorian         Extorian       Extorian	Interpolation		Circle in 3 axes with tilted working plane (spacial arc)
<ul> <li>3-D machining</li> <li>Motion control with minimum jerk</li> <li>3-D tool compensation through surface normal vectors</li> <li>Using the electronic handwheel to change the angle of the swivel he during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)</li> <li>Keeping the tool normal to the contour</li> <li>Tool radius compensation perpendicular to traversing and tool direct</li> <li>Interpolation</li> <li>Linear in 5 axes (subject to export permit)</li> <li>HEIDENHAIN DNC (option number 18)</li> <li>Communication with external PC applications over COM componen</li> <li>Display step (Option number 23)</li> <li>Input resolution and display</li> <li>Linear axes to 0.01 μm</li> <li>Step</li> <li>Rotary axes to 0.00001°</li> <li>Dynamic Collision Monitoring (DCM) software option (option number 40)</li> <li>Collision monitoring in all</li> <li>The machine manufacturer defines objects to be monitored</li> <li>Three warning levels in manual operation</li> <li>Program interrupt during automatic operation</li> <li>Includes monitoring of 5-axis movements</li> <li>Software option for additional conversational languages (option number 41)</li> <li>Additional conversational</li> <li>Norwegian</li> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	Software option 2 (option nur	nber (	)9)
<ul> <li>Using the electronic handwheel to change the angle of the swivel h during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)</li> <li>Keeping the tool normal to the contour</li> <li>Tool radius compensation perpendicular to traversing and tool direct</li> <li>Interpolation</li> <li>Linear in 5 axes (subject to export permit)</li> <li>HEIDENHAIN DNC (option number 18)</li> <li>Communication with external PC applications over COM componen</li> <li>Display step (Option number 23)</li> <li>Input resolution and display</li> <li>Linear axes to 0.01 µm</li> <li>Rotary axes to 0.0001°</li> <li>Dynamic Collision Monitoring (DCM) software option (option number 40)</li> <li>Collision monitoring in all machine operating modes</li> <li>The machine manufacturer defines objects to be monitored</li> <li>Three warning levels in manual operation</li> <li>Includes monitoring of 5-axis movements</li> <li>Software option for additional conversational languages (option number 41)</li> <li>Additional conversational</li> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>			
during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)         • Keeping the tool normal to the contour         • Tool radius compensation perpendicular to traversing and tool direct         Interpolation       • Linear in 5 axes (subject to export permit)         HEIDENHAIN DNC (option number 18)       • Communication with external PC applications over COM componen         Display step (Option number 23)       • Communication with external PC applications over COM componen         Display step (Option number 23)       • Linear axes to 0.01 µm         Bater       • Rotary axes to 0.0001°         Dynamic Collision Monitoring (DCM) software option (option number 40)       • The machine manufacturer defines objects to be monitored         • Three warning levels in manual operation       • Program interrupt during automatic operation         • Program interrupt during automatic operation       • Slovenian         • Slovenian       • Slovenian         • Slovak       • Latvian         • Korean       • Estonian         • Turkish       • Romanian	Ū		-
<ul> <li>Tool radius compensation perpendicular to traversing and tool direct</li> <li>Interpolation         <ul> <li>Linear in 5 axes (subject to export permit)</li> </ul> </li> <li>HEIDENHAIN DNC (option number 18)         <ul> <li>Communication with external PC applications over COM componen</li> <li>Display step (Option number 23)</li> <li>Input resolution and display                 <ul> <li>Linear axes to 0.01 µm</li> <li>Rotary axes to 0.00001°</li> </ul> </li> </ul> </li> <li>Dynamic Collision Monitoring (DCM) software option (option number 40)</li> <li>Collision monitoring in all machine operating modes         <ul> <li>The machine manufacturer defines objects to be monitored</li> <li>Three warning levels in manual operation</li> <li>Includes monitoring of 5-axis movements</li> </ul> </li> <li>Software option for additional conversational languages (option number 41)</li> <li>Additional conversational</li></ul>		•	
Interpolation       Elinear in 5 axes (subject to export permit)         HEIDENHAIN DNC (option number 18)       Communication with external PC applications over COM componen         Display step (Option number 23)       Elinear axes to 0.01 µm         Input resolution and display       Linear axes to 0.0001°         Dynamic Collision Monitoring (DCM) software option (option number 40)       The machine manufacturer defines objects to be monitored         Collision monitoring in all machine operating modes       The machine manufacturer defines objects to be monitored         By Program interrupt during automatic operation       Includes monitoring of 5-axis movements         Software option for additional conversational languages (option number 41)       Slovenian         Additional conversational languages       Slovenian         By Slovenian       Slovenian         By Slovenian       Slovenian         By Slovenian       Slovak         By Latvian       Korean         By Slovenian       Estonian         By Corean       Estonian			Keeping the tool normal to the contour
HEIDENHAIN DNC (option number 18) Communication with external PC applications over COM componen Display step (Option number 23) Input resolution and display Step Collision Monitoring (DCM) software option (option number 40) Collision monitoring in all machine operating modes The machine manufacturer defines objects to be monitored Three warning levels in manual operation Program interrupt during automatic operation Program interrupt during of 5-axis movements Software option for additional conversational languages (option number 41) Additional conversational languages Slovak Latvian Slovak Latvian Turkish Romanian			Tool radius compensation perpendicular to traversing and tool direction
<ul> <li>Communication with external PC applications over COM component</li> <li>Display step (Option number 23)</li> <li>Input resolution and display step</li> <li>Linear axes to 0.01 µm</li> <li>Rotary axes to 0.00001°</li> <li>Dynamic Collision Monitoring (DCM) software option (option number 40)</li> <li>Collision monitoring in all machine operating modes</li> <li>The machine manufacturer defines objects to be monitored</li> <li>Three warning levels in manual operation</li> <li>Program interrupt during automatic operation</li> <li>Includes monitoring of 5-axis movements</li> <li>Software option for additional conversational languages (option number 41)</li> <li>Additional conversational Isolovak</li> <li>Latvian</li> <li>Slovak</li> <li>Latvian</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	Interpolation		Linear in 5 axes (subject to export permit)
<ul> <li>Communication with external PC applications over COM component</li> <li>Display step (Option number 23)</li> <li>Input resolution and display step</li> <li>Linear axes to 0.01 µm</li> <li>Rotary axes to 0.00001°</li> <li>Dynamic Collision Monitoring (DCM) software option (option number 40)</li> <li>Collision monitoring in all machine operating modes</li> <li>The machine manufacturer defines objects to be monitored</li> <li>Three warning levels in manual operation</li> <li>Program interrupt during automatic operation</li> <li>Includes monitoring of 5-axis movements</li> <li>Software option for additional conversational languages (option number 41)</li> <li>Additional conversational Isolovak</li> <li>Latvian</li> <li>Slovak</li> <li>Latvian</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	HEIDENHAIN DNC (option nur	nber '	18)
Display step (Option number 23) Input resolution and display step			
Input resolution and display step       Linear axes to 0.01 μm         Rotary axes to 0.0001°         Dynamic Collision Monitoring (DCM) software option (option number 40)         Collision monitoring in all machine operating modes         The machine manufacturer defines objects to be monitored         Three warning levels in manual operation         Program interrupt during automatic operation         Includes monitoring of 5-axis movements         Software option for additional conversational languages (option number 41)         Additional conversational languages         Ianguages         Slovenian         Extra Xerian         Korean         Extonian         Turkish         Romanian			
step       Rotary axes to 0.00001°         Dynamic Collision Monitoring (DCM) software option (option number 40)       The machine manufacturer defines objects to be monitored         Collision monitoring in all machine operating modes <ul> <li>The machine manufacturer defines objects to be monitored</li> <li>Three warning levels in manual operation</li> <li>Program interrupt during automatic operation</li> <li>Includes monitoring of 5-axis movements</li> </ul> Software option for additional conversational languages <ul> <li>Slovenian</li> <li>Norwegian</li> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>			
Dynamic Collision Monitoring (DCM) software option (option number 40)         Collision monitoring in all machine operating modes <ul> <li>The machine manufacturer defines objects to be monitored</li> <li>Three warning levels in manual operation</li> <li>Program interrupt during automatic operation</li> <li>Includes monitoring of 5-axis movements</li> </ul> Software option for additional conversational languages <ul> <li>Slovenian</li> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>			
Collision monitoring in all machine operating modes       The machine manufacturer defines objects to be monitored         Three warning levels in manual operation       Three warning levels in manual operation         Program interrupt during automatic operation       Includes monitoring of 5-axis movements         Software option for additional conversational languages (option number 41)       Slovenian         Additional conversational languages       Slovenian         Slovak       Latvian         Estonian       Estonian         Turkish       Romanian	•	÷.,	Notary axes to 0.00001
machine operating modes <ul> <li>Three warning levels in manual operation</li> <li>Program interrupt during automatic operation</li> <li>Includes monitoring of 5-axis movements</li> </ul> Software option for additional conversational languages (option number 41)         Additional conversational languages (option number 41)         Additional conversational languages         Ianguages <ul> <li>Slovenian</li> <li>Norwegian</li> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	Dynamic Collision Monitoring	(DCIV	I) software option (option number 40)
<ul> <li>Program interrupt during automatic operation</li> <li>Program interrupt during automatic operation</li> <li>Includes monitoring of 5-axis movements</li> </ul> Software option for additional conversational languages (option number 41) <ul> <li>Additional conversational languages (option number 41)</li> </ul> Additional conversational languages (option number 41) <ul> <li>Slovenian</li> <li>Nor wegian</li> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	•		The machine manufacturer defines objects to be monitored
<ul> <li>Includes monitoring of 5-axis movements</li> <li>Software option for additional conversational languages (option number 41)</li> <li>Additional conversational anguages</li> <li>Slovenian</li> <li>Norwegian</li> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	machine operating modes		Three warning levels in manual operation
Software option for additional conversational languages (option number 41)         Additional conversational languages         Ianguages         Ianguages         Slovenian         Ianguages         Ianguages <tr< td=""><td></td><td></td><td>Program interrupt during automatic operation</td></tr<>			Program interrupt during automatic operation
Additional conversational languages       Slovenian         Ianguages       Nor wegian         Slovak       Latvian         Korean       Estonian         Turkish       Romanian			Includes monitoring of 5-axis movements
Additional conversational languages       Slovenian         Ianguages       Nor wegian         Slovak       Latvian         Korean       Estonian         Turkish       Romanian	Software option for additional	conv	ersational languages (option number 41)
<ul> <li>Slovak</li> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	-		
<ul> <li>Latvian</li> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>	languages		Norwegian
<ul> <li>Korean</li> <li>Estonian</li> <li>Turkish</li> <li>Romanian</li> </ul>			Slovak
<ul><li>Estonian</li><li>Turkish</li><li>Romanian</li></ul>			Latvian
<ul><li>Estonian</li><li>Turkish</li><li>Romanian</li></ul>			Korean
<ul><li>Turkish</li><li>Romanian</li></ul>			Estonian
Romanian			
Lithuanian		_	

# TNC model, software and features

#### DXF Converter software option (option number 42)

Extracting contour		Supported DXF format: AC1009 (AutoCAD R12)
programs and machining positions from DXF data.		For contours and point patterns
Extracting contour sections from plain-language programs.		Simple and convenient specification of reference points
	•	Select graphical features of contour sections from conversational programs
Adaptive Feed Control (AFC) so	oftwa	re option (option number 45)
Function for adaptive feed-		Recording the actual spindle power by means of a teach-in cut
rate control for optimizing		Defining the limits of automatic feed rate control
the machining conditions during series production	-	Fully automatic feed control during program run
KinematicsOpt software option	n (opt	tion number 48)
Touch-probe cycles for		Backup/restore active kinematics
automatic testing and optimization of the machine		Test active kinematics
kinematics		Optimize active kinematics
Mill-Turning software option (o	ptior	n number 50)
Functions for milling/turning		Switching between Milling/Turning mode of operation
mode		Constant cutting speed
		Tool-tip radius compensation
	•	Turning cycles
Extended Tool Managment sof	tware	e option (option number 93)
		Extended tool management, python-based
Remote Desktop Manager soft	ware	option (option number 133)
Remote operation of		Windows on a separate computer unit
external computer units (e.g. Windows PC) via the TNC user interface	•	Incorporated in the TNC interface

# **Fundamentals**

# TNC model, software and features

) soft	ware option (option number 141)		
•	Determination of dynamically caused position deviation through axis acceleration		
	Compensation of the TCP		
c) sof	tware option (option number 142)		
•	Changing of the control parameters depending on the position of the axes in the working space		
•	Changing of the control parameters depending on the speed or acceleration of an axis		
Load Adaptive Control (LAC) software option (option number 143)			
	Automatic determination of workpiece weight and frictional forces		
•	Continuous adaptation of the parameters of the adaptive precontrolling to the actual weight of the workpiece during machining		
	) soft		

#### T-II- C a a \ • . . . ... .

Fully automatic function for chatter control during machining

### Feature Content Level (upgrade functions)

Along with software options, significant further improvements of the TNC software are managed via the **F**eature **C**ontent **L**evel upgrade functions. Functions subject to the FCL are not available simply by updating the software on your TNC.



All upgrade functions are available to you without surcharge when you receive a new machine.

Upgrade functions are identified in the manual with **FCL n**, where **n** indicates the sequential number of the feature content level.

You can purchase a code number in order to permanently enable the FCL functions. For more information, contact your machine tool builder or HEIDENHAIN.

#### Intended place of operation

The TNC complies with the limits for a Class A device in accordance with the specifications in EN 55022, and is intended for use primarily in industrially-zoned areas.

### Legal information

This product uses open source software. Further information is available on the control under

- Programming and Editing operating mode
- MOD function
- ► LICENSE INFO soft key

# **Fundamentals**

TNC model, software and features

#### **New functions**

#### New functions 34059x-02

DXF files can be opened directly on the TNC in order to extract contours and point patterns (Programming: Data transfer from DXF files or plain-language contours, page 243).

The active tool-axis direction can now be activated in manual mode and during handwheel superimposition as a virtual tool axis (Superimposing handwheel positioning during program run: M118 , page 360).

The machine manufacturer can now define any areas on the machine for collision monitoring (Dynamic Collision Monitoring (software option), page 371).

Writing and reading data in freely definable tables (Freely definable tables, page 402).

The Adaptive Feed Control (AFC) function has been integrated (Adaptive Feed Control Software Option (AFC), page 377)

New touch probe cycle 484 for calibrating the wireless TT 449 tool touch probe (see User's Manual for Cycles).

The new HR 520 and HR 550 FS handwheels are supported (Traverse with electronic handwheels, page 490).

New machining cycle 225 ENGRAVING (see User's Manual for Cycle Programming)

New Active Chatter Control (ACC) software option (Active Chatter Control (ACC; software option), page 389).

New manual probing cycle "Center line as datum" (Setting a center line as datum , page 535).

New function for rounding corners (Rounding corners: M197, page 366).

External access to the TNC can now be blocked with a MOD function (External access, page 584).

#### Modified functions 34059x-02

The maximum number of characters for the NAME and DOC fields in the tool table has been increased from 16 to 32 (Enter tool data into the table, page 160).

The columns AFC and ACC were added to the tool table (Enter tool data into the table, page 160).

Operation and position behavior of the manual probing cycles has been improved (Using 3-D touch probes , page 514).

Predefined values can now be entered into a cycle parameter with the PREDEF function in cycles (see User's Manual for Cycle Programming).

The status display has been expanded with the AFC tab (Additional status displays, page 76).

The FUNCTION TURNDATA SPIN rotational function has been expanded with an input option for maximum speed (Program spindle speed, page 464).

A new optimization algorithm is now used with the KinematicsOpt cycles (see User's Manual for Cycle Programming).

With Cycle 257, circular stud milling, a parameter is now available with which you can determine the approach position on the stud (see User's Manual for Cycle Programming)

With Cycle 256, rectangular stud, a parameter is now available with which you can determine the approach position on the stud (see User's Manual for Cycle Programming).

With the "Basic Rotation" probing cycle, workpiece misalignment can now be compensated for via a table rotation (Compensation of workpiece misalignment by rotating the table, page 528)

# Fundamentals

TNC model, software and features

1	First Steps with the TNC 640	47
2	Introduction	69
3	Programming: Fundamentals, file management	89
4	Programming: Programming aids	131
5	Programming: Tools	155
6	Programming: Programming contours	191
7	Programming: Data transfer from DXF files or plain-language contours	243
8	Programming: Subprograms and program section repeats	261
9	Programming: Q Parameters	.277
10	Programming: Miscellaneous functions	.347
11	Programming: Special functions	367
12	Programming: Multiple Axis Machining	409
13	Programming: Pallet editor	453
14	Programming: Turning Operations	459
15	Manual operation and setup	485
16	Positioning with Manual Data Input	547
17	Test run and program run	553
18	MOD functions	581
19	Tables and overviews	.605

1	First	t Steps with the TNC 640	47
	1.1	Overview	48
	1.2	Machine switch-on	48
	1.2		
		Acknowledging the power interruption and moving to the reference points	
	1.3	Programming the first part	49
		Selecting the correct operating mode	49
		The most important TNC keys	49
		Creating a new program/file management	50
		Defining a workpiece blank	51
		Program layout	52
		Programming a simple contour	53
		Creating a cycle program	56
	1.4	Graphically testing the first part	58
		Selecting the correct operating mode	
		Selecting the tool table for the test run	
		Choosing the program you want to test	59
		Selecting the screen layout and the view	59
		Starting the test run	60
	1.5	Setting up tools	61
		Selecting the correct operating mode	61
		Preparing and measuring tools	
		The tool table TOOL.T	
		The pocket table TOOL_P.TCH	63
	1.6	Workpiece setup	64
		Selecting the correct operating mode	
		Clamping the workpiece	
		Workpiece alignment with 3-D touch probe Datum setting with 3-D touch probe	
	1.7	Running the first program	67
		Selecting the correct operating mode	67
		Choosing the program you want to run	67
		Start the program	67

2	Intro	oduction	69
	2.1	The TNC 640	70
		Programming: HEIDENHAIN conversational and ISO formats	70
		Compatibility	70
	2.2	Visual display unit and operating panel	71
		Display screen	71
		Setting the screen layout	71
		Control Panel	72
	2.3	Modes of Operation	73
		Manual Operation and El. Handwheel	73
		Positioning with Manual Data Input	73
		Programming	73
		Test Run	74
		Program Run, Full Sequence and Program Run, Single Block	74
	2.4	Status displays	75
		"General" status display	75
		Additional status displays	76
	2.5	Window Manager	83
		Task bar	84
	2.6	SELinux security software	85
	2.7	Accessories: HEIDENHAIN 3-D Touch Probes and Electronic Handwheels	86
		3-D touch probes	86
		HR electronic handwheels	

3	Prog	gramming: Fundamentals, file management	89
	3.1	Fundamentals	
		Position encoders and reference marks	
		Reference system	
		Reference system on milling machines	91
		Designation of the axes on milling machines	91
		Polar coordinates	
		Absolute and incremental workpiece positions	
		Selecting the datum	94
	3.2	Opening programs and entering	
		Organization of an NC program in HEIDENHAIN Conversational format	95
		Define the blank: BLK FORM	
		Opening a new part program	
		Programming tool movements in conversational	97
		Actual position capture	
		Editing a program	
		The TNC search function	103
	3.3	File manager: Fundamentals	
		Files	105
		Displaying externally generated files on the TNC	107
		Data Backup	

3.4	Working with the file manager	108
	Directories	108
	Paths	
	Overview: Functions of the file manager	
	Calling the file manager	
	Selecting drives, directories and files	
	Creating a new directory	
	Creating a new file	
	Copying a single file	
	Copying files into another directory	
	Copying a table	. 114
	Copying a directory	. 115
	Choosing one of the last files selected	.115
	Deleting a file	.116
	Deleting a directory	.116
	Tagging files	117
	Renaming a file	. 118
	Sorting files	. 118
	Additional functions	.119
	Additional tools for management of external file types	.120
	Data transfer to/from an external data medium	. 125
	The TNC in a network	.127
	USB devices on the TNC	.128

4	Prog	gramming: Programming aids	. 131
	4.1	Adding comments	132
		Application	132
		Entering comments during programming	132
		Inserting comments after program entry	132
		Entering a comment in a separate block	132
		Functions for editing of the comment	133
	4.2	Display of NC Programs	134
		Syntax highlighting	134
		Scrollbar	134
	4.3	Structuring programs	135
		Definition and applications	135
		Displaying the program structure window / Changing the active window	135
		Inserting a structuring block in the (left) program window	135
		Selecting blocks in the program structure window	135
	4.4	Calculator	136
		Operation	136
	4.5	Programming graphics	138
		Generating / not generating graphics during programming	138
		Generating a graphic for an existing program	
		Block number display ON/OFF	
		Erasing the graphic	
		Showing grid lines	
		Magnification or reduction of details	
		-	

4.6	Error messages	141
	Display of errors	141
	Open the error window	
	Closing the error window	
	Detailed error messages	
	INTERNAL INFO soft key	
	Clearing errors	
	Error log	
	Keystroke log	144
	Informational texts	145
	Saving service files	145
	Calling the TNCguide help system	146
4.7	TNCguide context-sensitive help system	147
	Application	147
	Working with the TNCguide	
	Downloading current help files	

5	Prog	gramming: Tools	155
	5.1	Entering tool-related data	156
		Feed rate F	
		Spindle speed S	157
	5.2	Tool data	158
		Requirements for tool compensation	158
		Tool number, tool name	
		Tool length L	158
		Tool radius R	158
		Delta values for lengths and radii	
		Entering tool data into the program	159
		Enter tool data into the table	160
		Importing tool tables	169
		Pocket table for tool changer	170
		Call tool data	173
		Tool change	175
		Tool usage test	178
		Tool management (software option)	180
	5.3	Tool compensation	
		Introduction	
		Tool length compensation	
		Tool radius compensation	

6	Prog	gramming: Programming contours	191
	6.1	Tool movements	192
		Path functions	192
		FK free contour programming	192
		Miscellaneous functions M	192
		Subprograms and program section repeats	193
		Programming with Q parameters	193
	6.2	Fundamentals of Path Functions	194
		Programming tool movements for workpiece machining	194
	6.3	Approaching and departing a contour	198
		Overview: Types of paths for contour approach and departure	198
		Important positions for approach and departure	199
		Approaching on a straight line with tangential connection: APPR LT	201
		Approaching on a straight line perpendicular to the first contour point: APPR LN	201
		Approaching on a circular path with tangential connection: APPR CT	202
		Approaching on a circular path with tangential connection from a straight line to the contour: APPF	
		LCT	
		Departing in a straight line with tangential connection: DEP LT Departing in a straight line perpendicular to the last contour point: DEP LN	
		Departing in a straight line perpendicular to the last contour point. DEP LN	
		Departing on a circular arc tangentially connecting the contour and a straight line: DEP LCT	
	6.4	Path contours - Cartesian coordinates	206
		Overview of path functions	206
		Straight line L	207
		Inserting a chamfer between two straight lines	208
		Corner rounding RND	209
		Circle center CC	210
		Circular path C around circle center CC	211
		Circle CR with defined radius	212
		Circle CT with tangential connection	214
		Example: Linear movements and chamfers with Cartesian coordinates	215
		Example: Circular movements with Cartesian coordinates	216
		Example: Full circle with Cartesian coordinates	217

6.5	Path contours – Polar coordinates	218
	Overview	218
	Zero point for polar coordinates: pole CC	219
	Straight line LP	219
	Circular path CP around pole CC	
	Circle CTP with tangential connection	220
	Helix	221
	Example: Linear movement with polar coordinates	223
	Example: Helix	224
6.6	Path contours – FK free contour programming	
	Fundamentals	225
	FK programming graphics	
	Initiating the FK dialog	229
	Pole for FK programming	
	Free straight line programming	230
	Free circular path programming	
	Input options	232
	Auxiliary points	
	Relative data	236
	Example: FK programming 1	238
	Example: FK programming 2	239
	Example: FK programming 3	240

7	Prog	gramming: Data transfer from DXF files or plain-language contours	243
	7.1	Processing DXF Files (Software Option)	244
		Application	244
		Opening a DXF file	245
		Working with the DXF converter	245
		Basic settings	246
		Setting layers	248
		Defining the datum	249
		Selecting and saving a contour	251
		Selecting and saving machining positions	255

8	Prog	gramming: Subprograms and program section repeats	
	8.1	Labeling Subprograms and Program Section Repeats	
		Label	
	8.2	Subprograms	263
		Operating sequence	
		Programming notes	
		Programming a subprogram	
		Calling a subprogram	
	8.3	Program-section repeats	265
		Label LBL	
		Operating sequence	
		Programming notes	
		Programming a program section repeat	
		Calling a program section repeat	
	8.4	Any desired program as subprogram	
		Operating sequence	
		Programming notes	267
		Calling any program as a subprogram	
	8.5	Nesting	269
		Types of nesting	269
		Nesting depth	269
		Subprogram within a subprogram	270
		Repeating program section repeats	271
		Repeating a subprogram	272
	8.6	Programming examples	273
		Example: Milling a contour in several infeeds	
		Example: Milling a contour in several infeeds Example: Groups of holes	
			27

9	Prog	gramming: Q Parameters	277
	9.1	Principle and overview of functions	278
		Programming notes	279
		Calling Q parameter functions	
	9.2	Part families – Q parameters in place of numerical values	281
		Application	
_			
	9.3	Describing contours with mathematical functions	282
		Application	282
		Overview	282
		Programming fundamental operations	283
	9.4	Angle functions (trigonometry)	284
		Definitions	284
		Programming trigonometric functions	284
	9.5	Calculation of circles	285
		Application	285
	9.6	If-then decisions with Q parameters	286
		Application	286
		Unconditional jumps	
		Programming if-then decisions	
		Abbreviations used:	287
	9.7	Checking and changing Q parameters	288
		Procedure	288
	9.8	Additional functions	290
		Overview	200
		FN 14: ERROR: Displaying error messages	
		FN 16: F-PRINT: Output of formatted texts and Q parameter values	
		FN 18: SYS-DATUM READ: Reading system data	
		FN 19: PLC: Transfer values to PLC.	
		FN 20: WAIT FOR: NC and PLC synchronization	
		FN 29: PLC: Transfer values to the PLC	
		FN 37: EXPORT	

9.9	Accessing tables with SQL commands	
	Introduction	
	A transaction	
	Programming SQL commands	
	Overview of the soft keys	
	SQL BIND	
	SQL SELECT	
	SQL FETCH	
	SQL UPDATE	
	SQL INSERT	
	SQL COMMIT	
	SQL ROLLBACK	
9.10	Entering formulas directly	
	Entering formulas	
	Rules for formulas	
	Programming example	
0 11	String parameters	225
9.11	String parameters	
	String processing functions	
	Assigning string parameters	
	Chain-linking string parameters	
	Converting a numerical value to a string parameter	
	Copying a substring from a string parameter	
	Converting a string parameter to a numerical value	
	Checking a string parameter	
	Finding the length of a string parameter	
	Comparing alphabetic sequence	
	Reading machine parameters	

9.12	Preassigned Q parameters	. 336
	Values from the PLC: Q100 to Q107	336
	Active tool radius: Q108	336
	Tool axis: Q109	336
	Spindle status: Q110	. 337
	Coolant on/off: Q111	337
	Overlap factor: Q112	. 337
	Unit of measurement for dimensions in the program: Q113	337
	Tool length: Q114	. 337
	Coordinates after probing during program run	338
	Deviation between actual value and nominal value during automatic tool measurement with the TT 130	338
	Tilting the working plane with mathematical angles: rotary axis coordinates calculated by the TNC	338
	Measurement results from touch probe cycles (see also User's Manual for Cycle Programming)	339
9.13	Programming examples	341

Example: Ellipse	. 341
Example: Concave cylinder machined with spherical cutter	. 343
Example: Convex sphere machined with end mill	345

10	Prog	ramming: Miscellaneous functions	347
	10.1	Entering miscellaneous functions M and STOP	348
		Fundamentals	
	10.2	M functions for program run inspection, spindle and coolant	349
		Overview	
	10.3	Miscellaneous functions for coordinate data	350
		Programming machine-referenced coordinates: M91/M92	350
		Moving to positions in a non-tilted coordinate system with a tilted working plane: M130	
	10.4	Miscellaneous functions for path behavior	
		Machining small contour steps: M97	353
		Machining open contour corners: M98	354
		Feed rate factor for plunging movements: M103	
		Feed rate in millimeters per spindle revolution: M136	
		Feed rate for circular arcs: M109/M110/M111	357
		Calculating the radius-compensated path in advance (LOOK AHEAD): M120	358
		Superimposing handwheel positioning during program run: M118	360
		Retraction from the contour in the tool-axis direction: M140	
		Suppressing touch probe monitoring: M141	363
		Deleting basic rotation: M143	364
		Automatically retract tool from the contour at an NC stop: M148	
		Rounding corners: M197	

11	Prog	ramming: Special functions	
	11.1	Overview of special functions	
		Main menu for SPEC FCT special functions	
		Program defaults menu	
		Functions for contour and point machining menu	
		Menu of various conversational functions	
	11.2	Dynamic Collision Monitoring (software option)	
		Function	
		Collision monitoring in the manual operating modes	
		Collision monitoring in Automatic operation	
		Graphic depiction of the protected space	
	11.3	Adaptive Feed Control Software Option (AFC)	
		Application	
		Defining the AFC basic settings	
		Recording a teach-in cut	
		Activating/deactivating AFC	
		Log file	
		Tool breakage/tool wear monitoring	
		Spindle load monitoring	
	11.4	Active Chatter Control (ACC; software option)	
		Application	
		Activating/deactivating ACC	
	11.5	Working with the Parallel Axes U, V and W	
		Overview	
		FUNCTION PARAXCOMP DISPLAY	
		FUNCTION PARAXCOMP MOVE	
		FUNCTION PARAXCOMP OFF	
		FUNCTION PARAXMODE	
		FUNCTION PARAXMODE OFF	
	11.6	File functions	
		Application	
		Defining file functions	

11.7	Definition of a datum shift	
	Overview	395
	TRANS DATUM AXIS	
	TRANS DATUM TABLE	
	TRANS DATUM RESET	
11.8	Creating Text Files	398
11.0		
	Application	
	Opening and exiting text files	398
	Editing texts	399
	Deleting and re-inserting characters, words and lines	
	Editing text blocks	400
	Finding text sections	401
11.9	Freely definable tables	402
	Fundamentals	402
	Creating a freely definable table	402
	Editing the table format	
	Switching between table and form view	
	FN 26: TAPOPEN: Open a freely definable table	405
	FN 27: TAPWRITE: Write to a freely definable table	406
	FN 28: TAPREAD: Read from a freely definable table	407

12	Prog	gramming: Multiple Axis Machining	409
	12.1	Functions for multiple axis machining	410
	12.2	The PLANE Function: Tilting the Working Plane (Software Option 1)	411
		Introduction	411
		Defining the PLANE function	
		Position display	413
		Resetting the PLANE function	414
		Defining the working plane with the spatial angle: PLANE SPATIAL	415
		Defining the working plane with the projection angle: PLANE PROJECTED	417
		Defining the working plane with the Euler angle: PLANE EULER	418
		Defining the working plane with two vectors: PLANE VECTOR	420
		Defining the working plane via three points: PLANE POINTS	422
		Defining the working plane via a single incremental spatial angle: PLANE SPATIAL	424
		Tilting the working plane through axis angle: PLANE AXIAL (FCL 3 function)	425
		Specifying the positioning behavior of the PLANE function	427
	12.3	Inclined-tool machining in a tilted machining plane (software option 2)	432
		Function	432
		Inclined-tool machining via incremental traverse of a rotary axis	432
		Inclined-tool machining via normal vectors	433
	12.4	Miscellaneous functions for rotary axes	434
		Feed rate in mm/min on rotary axes A, B, C: M116 (software option 1)	434
		Shortest-path traverse of rotary axes: M126	435
		Reducing display of a rotary axis to a value less than 360°: M94	436
		Maintaining the position of the tool tip when positioning with tilted axes (TCPM): M128 (software 2)	•
		Selecting tilting axes: M138	440
		Compensating the machine's kinematics configuration for ACTUAL/NOMINAL positions at end of	block:
		M144 (software option 2)	441
	12.5	FUNCTION TCPM (software option 2)	442
		Function	442
		Defining the TCPM FUNCTION	442
		Mode of action of the programmed feed rate	443
		Interpretation of the programmed rotary axis coordinates	443
		Type of interpolation between the starting and end position	445
		Resetting the TCPM FUNCTION	446

12.6	Three-dimensional tool compensation (software option 2)	447
		A A 7
	Introduction	.447
	Definition of a normalized vector	.448
	Permitted tool shapes	449
	Using other tools: Delta values	449
	3-D compensation without TCPM	449
	Face Milling: 3D compensation with TCPM	450
	Peripheral Milling: 3-D radius compensation with TCPM and radius compensation (RL/RR)	.451

13	Prog	ramming: Pallet editor	453
	13.1	Pallet Management	. 454
		Application	. 454
		Select pallet table	. 456
		Exiting the pallet file	. 456
		Run pallet file	. 456

14	Programming: Turning Operations						
	14.1	Turning Operations on Milling Machines (Software Option 50)	460				
		Introduction	460				
	14.2	Basis Functions (Software Option 50)	461				
		Switching between milling/turning mode of operation	461				
		Graphical display of turning operations	463				
		Program spindle speed	. 464				
		Feed rate	465				
		Tool call	465				
		Tool compensation in the program	466				
		Tool data	467				
		Tool tip radius compensation TRC	472				
		Recessing and undercutting	473				
		Inclined turning	479				
	14.3	Unbalance Functions	. 481				
		Unbalance while turning	. 481				
		Measure Unbalance cycle	483				

15	Man	ual operation and setup	485
	15.1	Switch-on, switch-off	
		Switch-on	
		Switch-off	
	15.2	Moving the machine axes	489
	IUL		
		Moving the axis with the machine axis direction buttons Incremental jog positioning	
		Traverse with electronic handwheels	
	15.3	Spindle speed S, feed rate F and miscellaneous function M	500
		Application	
		Entering values	
		Adjusting spindle speed and feed rate	
		Activating feed-rate limitation	501
	15.4	Functional safety FS (option)	502
		Miscellaneous	
		Explanation of terms	
		Checking the axis positions	504
		Overview of permitted feed rates and speeds	
		Activating feed-rate limitation	505
		Additional status displays	
	15.5	Datum setting without a 3-D touch probe	
		Note	
		Preparation	
		Workpiece presetting with axis keys	
		Datum management with the preset table	
	15.6	Using 3-D touch probes	514
		Overview	
		Functions in touch probe cycles	
		Selecting touch probe cycles	
		Recording measured values from the touch-probe cycles	
		Writing measured values from the touch probe cycles in a datum table	
		Writing measured values from the touch probe cycles in the preset table	

45.7		500
15.7	Calibrating a 3-D touch trigger probe	522
	Introduction	522
	Calibrating the effective length	
	Calibrating the effective radius and compensating center misalignment	524
	Displaying calibration values	526
15.8	Compensating workpiece misalignment with 3-D touch probe	
	Identifying basic rotation	
	Saving a basic rotation in the preset table	
	Compensation of workpiece misalignment by rotating the table	
	Displaying a basic rotation	
	Canceling a basic rotation	
15.9	Datum Setting with 3-D Touch Probe	530
	Overview	530
	Datum setting in any axis	530
	Corner as datum	531
	Circle center as datum	
	Setting a center line as datum	
	Measuring workpieces with a 3-D touch probe	536
	Using touch probe functions with mechanical probes or measuring dials	539
15.10	) Tilting the working plane (software option 1)	
	Application, function	
	Traversing reference points in tilted axes	
	Position display in a tilted system	
	Limitations on working with the tilting function	
	To activate manual tilting:	
	Setting the current tool-axis direction as the active machining direction	
	Setting the datum in a tilted coordinate system	545

16	Posit	tioning with Manual Data Input	547
	16.1	Programming and executing simple machining operations	.548
		Positioning with manual data input (MDI)	548
		Protecting and erasing programs in \$MDI	.551

17	Test	run and program run	553
	17.1	Graphics	554
		Application	554
		Speed of the Setting test runs	555
		Overview: Display modes	556
		Plan view	
		Projection in three planes	557
		3-D view	558
		Magnifying details	
		Repeating graphic simulation	
		Tool display	
		Measurement of machining time	562
		3-D line graphics	563
	17.2	Showing the workpiece blank in the working space	565
		Application	
	17.3	Functions for program display	566
		Overview	566
	17.4	Test Run	567
		Application	
	17.5	Program run	570
		Application	570
		Running a part program	
		Interrupt machining	
		Moving the machine axes during an interruption	
		Resuming program run after an interruption	
		Any entry into program (mid-program startup)	
		Returning to the contour	577
	17.6	Automatic program start	578
		Application	578
	17.7	Optional block skip	579
		Application	
		Inserting the "/" character	579
		Erasing the "/" character	

17.8	Optional program-run interruption	580
	Application	580

18	MOE	) functions	581
	18.1	MOD function	582
		Selecting MOD functions	582
		Changing the settings	582
		Exiting MOD functions	582
		Overview of MOD functions	583
	18.2	Machine settings	584
		External access	584
		Select kinematics	586
	18.3	Position Display Types	587
		Application	587
	18.4	Unit of Measurement	588
		Application	588
_	18.5	Displaying operating times.	
	10.5		
		Application	
	18.6	Software numbers	589
		Application	
	18.7	Entering the code number	589
		Application	589
	18.8	Setting up data interfaces	590
		Serial interfaces on the TNC 640	590
		Application	590
		Setting the RS-232 interface	590
		Setting the BAUD RATE (baudRate)	590
		Setting the protocol (protocol)	591
		Setting data bits (dataBits)	591
		Check parity (parity)	591
		Setting the stop bits (stopBits)	591
		Setting handshaking (flowControl)	592
		File system for file operations (fileSystem)	592
		Settings for data transfer with the TNCserver PC software	592
		Setting the operating mode of the external device (fileSystem)	593
		Data transfer software	594

## Contents

18.9	Ethernet interface	596
	Introduction	596
	Connection options	. 596
	Configuring the TNC	. 596
18.10	Configure HR 550 FS wireless handwheel	. 602
	Application	602
	Assigning the handwheel to a specific handwheel holder	. 602
	Setting the transmission channel	603
	Selecting the transmitter power	. 603
	Statistical data	604

19	Table	es and overviews	605
	19.1	Machine-specific user parameters	606
		Application	606
	19.2	Connector pin layout and connection cables for data interfaces	616
		RS-232-C/V.24 interface for HEIDENHAIN devices	616
		Non-HEIDENHAIN devices	618
		Ethernet interface RJ45 socket	618
	19.3	Technical Information	619
	10.0		
	19.4	Overview tables	627
		Fixed cycles	627
		Miscellaneous functions	628
	19.5	Functions of the TNC 640 and the iTNC 530 compared	620
	19.5	Tunctions of the TNC 040 and the TNC 550 compared	
		Comparison: Specifications	
		Comparison: Data interfaces	
		Comparison: Accessories	
		Comparison: PC software	
		Comparison: Machine-specific functions	
		Comparison: User functions	
		Comparison: Cycles	
		Comparison: Miscellaneous functions	
		Comparison: Touch probe cycles in the Manual Operation and El. Handwheel modes	
		Comparison: Touch probe cycles for automatic workpiece inspection	
		Comparison: Differences in programming	
		Comparison: Differences in Test Run, functionality	
		Comparison: Differences in Test Run, operation Comparison: Differences in Manual Operation, functionality	
		Comparison: Differences in Manual Operation, operation Comparison: Differences in Program Run, operation	
		Comparison: Differences in Program Run, operation	
		Comparison: Differences in MDI operation	
		Comparison: Differences in programming station	



1.1 Overview

## 1.1 Overview

This chapter is intended to help TNC beginners quickly learn to handle the most important procedures. For more information on a respective topic, see the section referred to in the text.

The following topics are included in this chapter:

- Machine switch-on
- Programming the first part
- Graphically testing the first part
- Setting up tools
- Workpiece setup
- Running the first program

## 1.2 Machine switch-on

# Acknowledging the power interruption and moving to the reference points



Switch-on and crossing over the reference points can vary depending on the machine tool. Refer to your machine manual.

Switch on the power supply for control and machine. The TNC starts the operating system. This process may take several minutes. Then the TNC will display the message "Power interrupted" in the screen header



- Press the CE key: The TNC compiles the PLC program
- Switch on the control voltage: The TNC checks operation of the emergency stop circuit and goes into the reference run mode
- Cross the reference points manually in the displayed sequence: For each axis press the machine START button. If you have absolute linear and angle encoders on your machine there is no need for a reference run

The TNC is now ready for operation in the **Manual Operation** mode.

- Traversing the reference marks: See "Switch-on", page 486
- Operating modes: See "Programming", page 73

Manua Manua	al operation	tion				📀 Progr	amming	11:05
								" _
Position d	isplay MODE:	NOML .						 s 🗍
	X				+	53.6	67	
	Y				+	61.18	82	\$ A
	Z				-	10.0	00	~ 8 [
	A					+0.00	00	S100%
	С					+0.00	00	÷ -
	<mark>S 1</mark>				+2	86.8	85	F100% W
11								OFF
	1							
(91	)(T 4		S 2000 0% X 0% Y	[Nm]	11:05	Ovr 100%	M 579	
м	s	F	TOUCH PROBE	PRESET TABLE		30 ROT		TOOL TABLE

# **1.3 Programming the first part**

#### Selecting the correct operating mode

You can write programs only in Programming mode:

- (
- Press the Programming operating mode key: The TNC switches to **Programming mode**

#### Further information on this topic

• Operating modes: See "Programming", page 73

### The most important TNC keys

Functions for conversational guidance	Кеу
Confirm entry and activate the next dialog prompt	ENT
Ignore the dialog question	NO ENT
End the dialog immediately	
Abort dialog, discard entries	DEL
Soft keys on the screen with which you select functions appropriate to the active state	

- Writing and editing programs: See "Editing a program", page 100
- Overview of keys: See "Controls of the TNC", page 2

1

PGM MGT

**1.3 Programming the first part** 

#### Creating a new program/file management

- Press the PGM MGT key: The TNC opens the file manager. The file management of the TNC is arranged much like the file management on a PC with the Windows Explorer. The file management enables you to manipulate data on the TNC hard disk
- Use the arrow keys to select the folder in which you want to open the new file
- Enter a file name with the extension .H: The TNC then automatically opens a program and asks for the unit of measure for the new program
- To select the unit of measure, press the MM or INCH soft key: The TNC automatically starts the workpiece blank definition (See "Defining a workpiece blank", page 51)

The TNC automatically generates the first and last blocks of the program. Afterwards you can no longer change these blocks.

- File management: See "Working with the file manager", page 108
- Creating a new program: See "Opening programs and entering", page 95

🕐 Manual operat	ion Programming	11:12
eres PLC: \	TNC: \ne_prog \PGH\'.H:*.I	
DO THC: \	me. mc_progream in, in	
e 😋 config	♦ File name Bytes Status Date Time	
nc_prog	A3803 1.I 426 02-05-2011 10:15:23	
e Sort	BHB 1 3.H 1133 31-07-2012 09:51:49	
DCA CAP	BLK.H 110 02-05-2011 10:15:22	
🕀 🗅 de	BSP Platte.H 4468 27-07-2012 08:27:12	
ma demo	Cycl.h 1271 18-09-2012 13:36:51	
🕀 🗀 drehen	DXF.H 292 27-07-2012 07:05:21	
හත DXF	error.h 554 02-05-2011 10:15:22	
0-0 EM0_2011	FX11.H 1963 07-03-2013 10:54:56	
en en	EX16.H 997 + 02-05-2011 10:15:22	
an⊖a fr	EX16 SL.H 1792 02-05-2011 10:15:22	
et it	EX18.H 796 + 26-07-2012 08:08:18	
PGM2	EX18 SL.H 1513 + 02-05-2011 10:15:22	
DO TABLE	EX4.H 1036 02-05-2011 10:15:22	
BO system	HEBEL.H 541 + 02-05-2011 10:15:22	
n Ca table	koord.h 1596 S + 02-05-2011 10:15:22	
B-Q temp	NEUGL.I 684 + 02-05-2011 10:15:22	
r thequide	PAT.H 152 E 07-03-2013 11:12:38	
o a megarae	PL1.H 2697 + 02-05-2011 10:15:22	
	Ra-Pl.h 6675 18-09-2012 13:06:24	
	RAD6.h 400 + 05-03-2013 11:54:15	
	Rastplatte.h 4837 25-07-2012 10:41:25	
	Reset.H 365 + 06-03-2013 06:39:00	
	Schulter.h 3477 26-07-2012 09:59:00	
	STAT.H 479 M 02-05-2011 10:15:22	
	STAT1.H 623 02-05-2011 10:15:22	
	TCH.h 1320 07-03-2013 11:09:45	
	turbine.H 1971 09-10-2012 07:11:21	
	TURN.H 1078 + 07-03-2013 11:00:02	
	wheel.h 10767 + 18-09-2012 14:02:41	
	wheelgirder.H 12345K 11-01-2013 11:00:49	
	51 file(s) 169.35 GB vacant	
PAGE PAGE	SELECT WINDOW LAST	END
T	- Auc→xy2 CP2 III III K#	END

### Defining a workpiece blank

Immediately after you have created a new program, the TNC starts the dialog for entering the workpiece blank definition. Always define the workpiece blank as a cuboid by entering the MIN and MAX points, each with reference to the selected reference point.

After you have created a new program, the TNC automatically initiates the workpiece blank definition and asks for the required data:

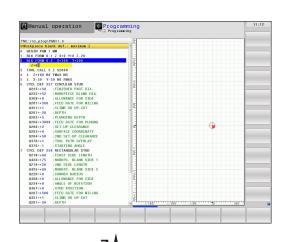
- Working plane in graphic: XY?: Enter the active spindle axis. Z is saved as default setting. Accept with the ENT key
- Workpiece blank def.: minimum X: Smallest X coordinate of the workpiece blank with respect to the reference point, e.g. 0. Confirm with the ENT key
- Workpiece blank def.: minimum Y: Smallest Y coordinate of the workpiece blank with respect to the reference point, e.g. 0. Confirm with the ENT key
- Workpiece blank def.: minimum Z: Smallest Z coordinate of the workpiece blank with respect to the reference point, e.g. -40. Confirm with the ENT key
- Workpiece blank def.: maximum X: Largest X coordinate of the workpiece blank with respect to the reference point, e.g. 100. Confirm with the ENT key
- Workpiece blank def.: maximum Y: Largest Y coordinate of the workpiece blank with respect to the reference point, e.g. 100. Confirm with the ENT key
- Workpiece blank def.: maximum Z: Largest Z coordinate of the workpiece blank with respect to the reference point, e.g. 0. Confirm with the ENT key. The TNC concludes the dialog

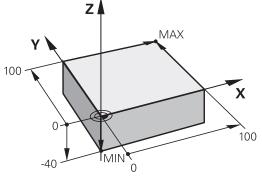
#### Example NC blocks

0 BEGIN PGM NEW MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 END PGM NEW MM	

#### Further information on this topic

Defining the workpiece blank: page 96





**1.3 Programming the first part** 

#### **Program layout**

NC programs should be arranged consistently in a similar manner. This makes it easier to find your place, accelerates programming and reduces errors.

# Recommended program layout for simple, conventional contour machining

- 1 Call tool, define tool axis
- 2 Retract the tool
- 3 Pre-position the tool in the working plane near the contour starting point
- 4 In the tool axis, position the tool above the workpiece, or preposition immediately to workpiece depth. If required, switch on the spindle/coolant
- 5 Contour approach
- 6 Contour machining
- 7 Contour departure
- 8 Retract the tool, end program

#### Further information on this topic

Contour programming: See "Tool movements", page 192

#### Recommended program layout for simple cycle programs

- 1 Call tool, define tool axis
- 2 Retract the tool
- 3 Define the machining positions
- 4 Define the fixed cycle
- 5 Call the cycle, switch on the spindle/coolant
- 6 Retract the tool, end program

#### Further information on this topic

Cycle programming: See User's Manual for Cycles

# Layout of contour machining programs

0 BEGIN PGM BSPCONT MM 1 BLK FORM 0.1 Z X... Y... Z... 2 BLK FORM 0.2 X... Y... Z... 3 TOOL CALL 5 Z S5000 4 L Z+250 R0 FMAX 5 L X... Y... R0 FMAX 6 L Z+10 R0 F3000 M13 7 APPR ... RL F500 ... 16 DEP ... X... Y... F3000 M9 17 L Z+250 R0 FMAX M2

18 END PGM BSPCONT MM

#### Cycle program layout

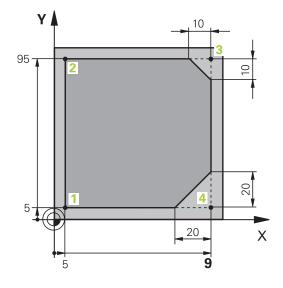
0 BEGIN PGM BSBCYC MM
1 BLK FORM 0.1 Z X Y Z
2 BLK FORM 0.2 X Y Z
3 TOOL CALL 5 Z S5000
4 L Z+250 R0 FMAX
5 PATTERN DEF POS1( X Y Z )
6 CYCL DEF
7 CYCL CALL PAT FMAX M13
8 L Z+250 R0 FMAX M2
9 END PGM BSBCYC MM

## Programming a simple contour

The contour shown to the right is to be milled once to a depth of 5 mm. You have already defined the workpiece blank. After you have initiated a dialog through a function key, enter all the data requested by the TNC in the screen header.



- Call the tool: Enter the tool data. Confirm each of your entries with the ENT key. Do not forget the tool axis
- Retract the tool: Press the orange axis key Z in order to get clear in the tool axis, and enter the value for the position to be approached, e.g. 250. Confirm with the ENT key
- Confirm Radius comp.: RL/RR/no comp? by pressing the ENT key: Do not activate the radius compensation
- Confirm Feed rate F=? with the ENT key: Move at rapid traverse (FMAX)
- Confirm the Miscellaneous function M? with theEND key: The TNC saves the entered positioning block
- Preposition the tool in the working plane: Press the orange X axis key and enter the value for the position to be approached, e.g. –20
- Press the orange Y axis key and enter the value for the position to be approached, e.g. –20. Confirm with the ENT key
- Confirm Radius comp.: RL/RR/no comp? by pressing the ENT key: Do not activate the radius compensation
- Confirm Feed rate F=? with the ENT key: Move at rapid traverse (FMAX)
- Confirm the Miscellaneous function M? with the END key: The TNC saves the entered positioning block
- Move the tool to workpiece depth: Press the orange axis key and enter the value for the position to be approached, e.g. –5. Confirm with the ENT key
- Confirm Radius comp.: RL/RR/no comp? by pressing the ENT key: Do not activate the radius compensation
- Feed rate F=? Enter the positioning feed rate, e.g. 3000 mm/min and confirm with the ENT key
- Miscellaneous function M? Switch on the spindle and coolant, e.g. M13. Confirm with the END key: The TNC saves the entered positioning block
- Move to the contour: Press the APPR/DEP key: The TNC shows a soft-key row with approach and departure functions



APPR DEP

## **1.3 Programming the first part**



Ļ

Ļ

CHF

Ļ

APPR DEP

DEP CT

- Select the approach function APPR CT: Enter the coordinates of the contour starting point 1 in X and Y, e.g. 5/5. Confirm with the ENT key
- Center angle? Enter the approach angle, e.g. 90°, and confirm with the ENT key
- Circle radius? Enter the approach radius, e.g. 8 mm, and confirm with the ENT key
- Confirm the Radius comp.: RL/RR/no comp? with the RL soft key: Activate the radius compensation to the left of the programmed contour
- Feed rate F=? Enter the machining feed rate, e.g. 700 mm/min, and confirm your entry with the END key
- Machine the contour and move to contour point 2: You only need to enter the information that changes. In other words, enter only the Y coordinate 95 and save your entry with the END key
- Move to contour point 3: Enter the X coordinate 95 and save your entry with the END key
- Define the chamfer at contour point 3: Enter the chamfer width 10 mm and save with the END key
- Move to contour point 4: Enter the Y coordinate 5 and save your entry with the END key
- Define the chamfer at contour point 4: Enter the chamfer width 20 mm and save with the END key
- Move to contour point 1: Enter the X coordinate 5 and save your entry with the END key
- Depart the contour
- Select the departure function DEP CT
- Center angle? Enter the departure angle, e.g. 90°, and confirm with the ENT key
- Circle radius? Enter the departure radius, e.g. 8 mm, and confirm with the ENT key
- Feed rate F=? Enter the positioning feed rate, e.g. 3000 mm/min and confirm with the ENT key
- Miscellaneous function M? Switch off the coolant, e.g. M9, with the END key: The TNC saves the entered positioning block

1

- Enter Retract the tool: Press the orange axis key Z in order to get clear in the tool axis, and enter the value for the position to be approached, e.g. 250. Confirm with the ENT key
- Confirm Radius comp.: RL/RR/no comp? by pressing the ENT key: Do not activate the radius compensation
- Confirm Feed rate F=? with the ENT key: Move at rapid traverse (FMAX)
- MISCELLANEOUS FUNCTION M? ENTER M2 to end the program and confirm with the END key: The TNC saves the entered positioning block

#### Further information on this topic

LP

- Complete example with NC blocks: See "Example: Linear movements and chamfers with Cartesian coordinates", page 215
- Creating a new program: See "Opening programs and entering", page 95
- Approaching/departing contours: See " Approaching and departing a contour", page 198
- Programming contours: See "Overview of path functions", page 206
- Programmable feed rates: See "Mögliche Vorschubeingaben"
- Tool radius compensation: See "Tool radius compensation", page 188
- Miscellaneous functions (M): See "M functions for program run inspection, spindle and coolant ", page 349

**1.3 Programming the first part** 

#### Creating a cycle program

The holes (depth of 20 mm) shown in the figure at right are to be drilled with a standard drilling cycle. You have already defined the workpiece blank.

TOOL CALL

1

- Call the tool: Enter the tool data. Confirm each of your entries with the ENT KEY. DO NOT FORGET THE TOOL AXIS
- L
- Retract the tool: Press the orange axis key Z in order to get clear in the tool axis, and enter the value for the position to be approached, e.g. 250. Confirm with the ENT key
- Confirm Radius comp.: RL/RR/no comp? by pressing the ENT key: Do not activate the radius compensation
- Confirm Feed rate F=? with the ENT key: Move at rapid traverse (FMAX)
- Confirm the Miscellaneous function M? with theEND key: The TNC saves the entered positioning block
- CYCL Call the cycle menu



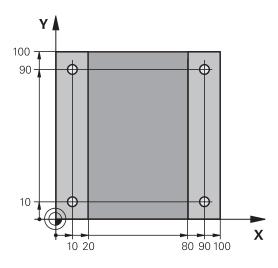
- Display the drilling cycles
- Select the standard drilling cycle 200: The TNC starts the dialog for cycle definition. Enter all parameters requested by the TNC step by step and conclude each entry with the ENT key. In the screen to the right, the TNC also displays a graphic showing the respective cycle parameter
- ► Call the menu for special functions
- CONTOUR + POINT MACHINING

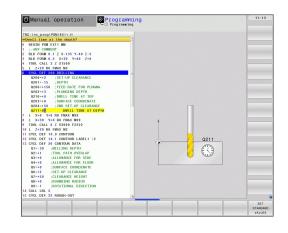
SPEC FCT

- PATTERN DEF POINT
- CYCL CALL

PAT

- Display the functions for point machining
- Select the pattern definition
- Select point entry: Enter the coordinates of the 4 points and confirm each with the ENT key. After entering the fourth point, save the block with the END key
- Display the menu for defining the cycle call
- Run the drilling cycle on the defined pattern:
- Confirm Feed rate F=? with the ENT key: Move at rapid traverse (FMAX)
- Miscellaneous function M? Switch on the spindle and coolant, e.g. M13. Confirm with the END key: The TNC saves the entered positioning block





1

- Enter Retract the tool: Press the orange axis key Z in order to get clear in the tool axis, and enter the value for the position to be approached, e.g. 250. Confirm with the ENT key
- Confirm Radius comp.: RL/RR/no comp? by pressing the ENT key: Do not activate the radius compensation
- Confirm Feed rate F=? with the ENT key: Move at rapid traverse (FMAX)
- Miscellaneous function M? Enter M2 to end the program and confirm with the END key: The TNC saves the entered positioning block

#### **Example NC blocks**

L

0 BEGIN PGM C200 M	Μ					
1 BLK FORM 0.1 Z X+	0 Y+0 Z-40	Definition of workpiece blank				
2 BLK FORM 0.2 X+10	00 Y+100 Z+0					
3 TOOL CALL 5 Z S45	00	Tool call				
4 L Z+250 R0 FMAX		Retract the tool				
5 PATTERN DEF POS1 (X+10 Y+10 Z+0 POS2 (X+10 Y+90 Z+0 POS3 (X+90 Y+90 Z+0 POS4 (X+90 Y+10 Z+0	) ))	Define the machining positions				
6 CYCL DEF 200 DRIL	LING	Define the cycle				
Q200=2	;SET-UP CLEARANCE					
Q201=-20	;DEPTH					
Q206=250	;FEED RATE FOR PLNGNG					
Q202=5	;PLUNGING DEPTH					
Q210=0	;DWELL TIME AT TOP					
Q203=-10	;SURFACE COORDINATE					
Q204=20	;2ND SET-UP CLEARANCE					
Q211=0.2	;DWELL TIME AT BOTTOM					
7 CYCL CALL PAT FMA	AX M13	Spindle and coolant on, call the cycle				
8 L Z+250 R0 FMAX M	12	Retract the tool, end program				
9 END PGM C200 MM						

- Creating a new program: See "Opening programs and entering", page 95
- Cycle programming: See User's Manual for Cycles

Graphically testing the first part 1.4

#### 1.4 Graphically testing the first part

#### Selecting the correct operating mode

You can test programs only in the Test Run mode:

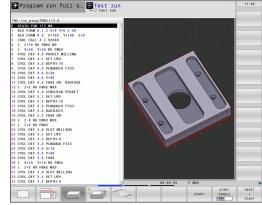


1

Press the Test Run operating mode key: the TNC switches to that mode

#### Further information on this topic

- Operating modes of the TNC: See "Modes of Operation", page 73
- Testing programs: See "Test Run", page 567



#### Selecting the tool table for the test run

You only need to execute this step if you have not activated a tool table in the Test Run mode.



Press the PGM MGT key: The TNC opens the file manager

Press the SELECT TYPE soft key: The TNC shows a soft-key menu for selection of the file type to be



ŧ

- displayed Press the SHOW ALL soft key: The TNC shows all saved files in the right window
- Move the highlight to the left onto the directories ►
- Move the highlight to the TNC:\ directory
- Move the highlight to the right onto the files
- Move the highlight to the file TOOL.T (active tool table) and load with the ENT key: TOOL.T receives the status  ${\boldsymbol{\mathsf{S}}}$  and is therefore active for the test run
- Press the END key: Exit the file manager

#### Further information on this topic

- Tool management: See "Enter tool data into the table", page 160
- Testing programs: See "Test Run", page 567

Program run full s... Program run

1

#### Choosing the program you want to test



- Press the PGM MGT key: The TNC opens the file manager
- Press the LAST FILES soft key: The TNC opens a pop-up window with the most recently selected files
- Use the arrow keys to select the program that you want to test. Load with the ENT key

#### Further information on this topic

 Selecting a program: See "Working with the file manager", page 108

#### Selecting the screen layout and the view



 Press the key for selecting the screen layout. The TNC shows all available alternatives in the soft-key row



- Press the PROGRAM + GRAPHICS soft key: In the left half of the screen the TNC shows the program; in the right half it shows the workpiece blank
- Select the desired view via soft key
- Projection in three planes
- ► 3-D view

Plan view

►

- Graphic functions: See "Graphics ", page 554
- Running a test run: See "Test Run", page 567

Graphically testing the first part 1.4

#### Starting the test run

RESET + START	•	Press the RESET + START soft key: The TNC simulates the active program up to a programmed break or to the program end
	•	While the simulation is running, you can use the soft keys to change views
STOP	•	Press the STOP soft key: The TNC interrupts the test run
START	►	Press the START soft key: The TNC resumes the

- e STOP soft key: The TNC interrupts the
- e START soft key: The TNC resumes the test run after a break

- Running a test run: See "Test Run", page 567
- Graphic functions: See "Graphics ", page 554
- Adjusting the test speed: See "Speed of the Setting test runs", page 555

# 1.5 Setting up tools

## Selecting the correct operating mode

Tools are set up in the Manual Operation mode:

- Press the Manual Operation operating mode key: the TNC switches to that mode

#### Further information on this topic

 Operating modes of the TNC: See "Modes of Operation", page 73

Position dis	splay MODE: NOW	ι.						8
	X				+	53.6	67	
	Y				+	61.1	82	÷.
	Z				-	10.0	00	~ 1
	A					+0.0	00	\$100% () () () () () () () () () () () () ()
	С					+0.0	00	<u>ه</u>
	S1				+2	86.8	85	F100%
1	11							OFF
@1	T 4	Z S	2000	F 3000	ae/ein	Ovr 100%	M 5/9	

## Preparing and measuring tools

- Clamp the required tools in their chucks
- When measuring with an external tool presetter: Measure the tools, note down the length and radius, or transfer them directly to the machine through a transfer program
- When measuring on the machine: Place the tools into the tool changer page 63

## The tool table TOOL.T

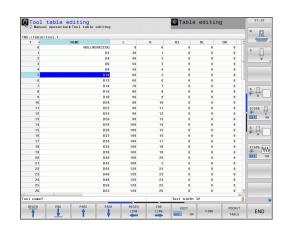
In the tool table TOOL.T (permanently saved under **TNC:\TABLE\**), save the tool data such as length and radius, but also further tool-specific information that the TNC needs to perform its functions.

To enter tool data in the tool table TOOL.T, proceed as follows:



- Display the tool table
- ► Edit the tool table: Set the EDITING soft key to ON
- With the upward or downward arrow keys you can select the tool number that you want to edit
- With the rightward or leftward arrow keys you can select the tool data that you want to edit
- To exit the tool table, press the END key

- Operating modes of the TNC: See "Modes of Operation", page 73
- Working with the tool table: See "Enter tool data into the table", page 160



# The pocket table TOOL\_P.TCH



The function of the pocket table depends on the machine. Refer to your machine manual.

In the pocket table TOOL\_P.TCH (permanently saved under **TNC: \TABLE\**) you specify which tools your tool magazine contains.

To enter data in the pocket table TOOL\_P.TCH, proceed as follows:



Display the tool table

- Display the pocket table
- Edit the pocket table: Set the EDITING soft key to ON
- With the upward or downward arrow keys you can select the pocket number that you want to edit
- With the rightward or leftward arrow keys you can select the data that you want to edit
- ▶ To leave the pocket table, press the END key

- Operating modes of the TNC: See "Modes of Operation", page 73
- Working with the pocket table: See "Pocket table for tool changer", page 170

TNC:\table	\tool_p.tch								EL.
р .	T	TNAME	RSY	ST	F	L	DOC		
0.0	-4	D8							s 🗆
1.1	1	D2							° Ц
1.2	2	D4							¥.
1.3	3	D6							
1.4	5	D10							
1.5	4	Da	R						
1.6	6	D12							
1.7	7	D14							
1.8	8	D16							
1.9	9	D18							A R
1.10	10	D20							
1.11	11	D22							8100%
1.12	12	D24							6
1.13	13	D26							 OFF
1.14	14	D28							
1.15	15	D30							
1.16	16	D32							 6.2
1.17	17	D34							
1.18	18	D36							 F100%
1.19	19	D38							
1.20	20	D40							 OFF
1.21	21	D42							
1.22	22	D44							
1.23	23	D46							
1.24	24	D48							
1.25	25	D50							
1.26	26	D52							
ool numbe		DEA					Nin. 1, max	00000	

1.6 Workpiece setup

## 1.6 Workpiece setup

#### Selecting the correct operating mode

Workpieces are set up in the  $\ensuremath{\text{Manual Operation}}$  or  $\ensuremath{\text{Electronic}}$   $\ensuremath{\text{Handwheel}}$  mode



Press the Manual Operation operating mode key: the TNC switches to that mode

#### Further information on this topic

 Manual Operation mode: See "Moving the machine axes", page 489

#### **Clamping the workpiece**

Mount the workpiece with a fixture on the machine table. If you have a 3-D touch probe on your machine, then you do not need to clamp the workpiece parallel to the axes.

If you do not have a 3-D touch probe available, you have to align the workpiece so that it is fixed with its edges parallel to the machine axes.

## Workpiece alignment with 3-D touch probe

Insert the 3-D touch probe: In the Manual Data Input (MDI) operating mode, run a TOOL CALL block containing the tool axis, and then return to the Manual Operation mode (in MDI mode you can run an individual NC block independently of the others)



 Select the probing functions: The TNC displays the available functions in the soft-key row



- Measure the basic rotation: The TNC displays the basic rotation menu. To identify the basic rotation, probe two points on a straight surface of the workpiece
- Use the axis-direction keys to preposition the touch probe to a position near the first contact point
- Select the probing direction via soft key
- Press NC start: The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point
- Use the axis-direction keys to preposition the touch probe to a position near the second contact point
- Press NC start: The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point
- Then the TNC shows the measured basic rotation
- Press SET BASIC ROTATION soft key to select the displayed value as the active rotation. Press the END soft key to exit the menu

- MDI operating mode: See "Programming and executing simple machining operations", page 548
- Workpiece alignment: See "Compensating workpiece misalignment with 3-D touch probe ", page 527

1.6 Workpiece setup

### Datum setting with 3-D touch probe

Insert the 3-D touch probe: In the MDI mode, run a TOOL CALL block containing the tool axis and then return to the Manual Operation mode



- Select the probing functions: The TNC displays the available functions in the soft-key row
- Set the datum at a workpiece corner, for example
- Position the touch probe near the first touch point on the first workpiece edge
- Select the probing direction via soft key
- Press NC start: The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point
- Use the axis-direction keys to pre-position the touch probe to a position near the second touch point on the first workpiece edge
- Press NC start: The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point
- Use the axis-direction keys to pre-position the touch probe to a position near the first touch point on the second workpiece edge
- Select the probing direction via soft key
- Press NC start: The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point
- Use the axis-direction keys to pre-position the touch probe to a position near the second touch point on the second workpiece edge
- Press NC start: The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point
- Then the TNC shows the coordinates of the measured corner point
- Set to 0: Press the SET DATUM soft key
- Press the END soft key to close the menu

#### Further information on this topic

 Datum setting: See "Datum Setting with 3-D Touch Probe ", page 530

> TNC 640 | User's Manual HEIDENHAIN Conversational Programming | 5/2013

SET

# 1.7 Running the first program

## Selecting the correct operating mode

You can run programs either in the Single Block or the Full Sequence mode:



- Press the operating mode key: The TNC goes into the Program Run, Single Block mode and the TNC executes the program block by block. You have to confirm each block with the NC start key
- Press the Program Run, Full Sequence operating mode key: The TNC switches to that mode and runs the program after NC start up to a program interruption or to the end of the program

#### Further information on this topic

- Operating modes of the TNC: See "Modes of Operation", page 73
- Running programs: See "Program run", page 570

#### Choosing the program you want to run



FILES

- Press the PGM MGT key: The TNC opens the file manager
- Press the LAST FILES soft key: The TNC opens a pop-up window with the most recently selected files
- If desired, use the arrow keys to select the program that you want to run. Load with the ENT key

#### Further information on this topic

 File management: See "Working with the file manager", page 108

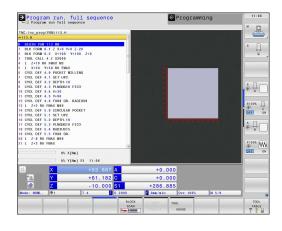
#### Start the program



 Press the NC start key: The TNC runs the active program

#### Further information on this topic

Running programs: See "Program run", page 570





# Introduction

# 2.1 The TNC 640

HEIDENHAIN TNC controls are workshop-oriented contouring controls that enable you to program conventional machining operations right at the machine in an easy-to-use conversational programming language. They are designed for milling and drilling machines, as well as machining centers, with up to 18 axes. You can also change the angular position of the spindle under program control.

An integrated hard disk provides storage for as many programs as you like, even if they were created off-line. For quick calculations you can call up the on-screen pocket calculator at any time.

Keyboard and screen layout are clearly arranged in such a way that the functions are fast and easy to use.

# Programming: HEIDENHAIN conversational and ISO formats

The HEIDENHAIN conversational programming format is an especially easy method of writing programs. Interactive graphics illustrate the individual machining steps for programming the contour. If a production drawing is not dimensioned for NC, the FK free contour programming feature performs the necessary calculations automatically. Workpiece machining can be graphically simulated either during or before actual machining.

It is also possible to program the TNCs in ISO format or DNC mode.

You can also enter and test one program while the control is running another.

## Compatibility

Machining programs created on HEIDENHAIN contouring controls (starting from the TNC 150 B) may not always run on the TNC 640. If NC blocks contain invalid elements, the TNC will mark them as ERROR blocks when the file is opened.



See "Functions of the and the iTNC 530 compared". Please also note the detailed description of the differences between the iTNC 530 and the TNC 640



# 2.2 Visual display unit and operating panel

## **Display screen**

The TNC is shipped with a 19-inch TFT flat-panel display.

1 Header

When the TNC is on, the selected operating modes are shown in the screen header: the machining mode at the left and the programming mode at right. The currently active operating mode is displayed in the larger box, where the dialog prompts and TNC messages also appear (unless the TNC is showing only graphics).

2 Soft keys

In the footer the TNC indicates additional functions in a softkey row. You can select these functions by pressing the keys immediately below them. The lines immediately above the soft-key row indicate the number of soft-key rows that can be called with the black arrow keys to the right and left. The bar representing the active soft-key row is highlighted

- 3 Soft-key selection keys
- 4 Shifting between soft-key rows
- 5 Setting the screen layout
- 6 Shift key for switchover between machining and programming modes
- 7 Soft-key selection keys for machine tool builders
- 8 Switching the soft-key rows for machine tool builders

### Setting the screen layout

You select the screen layout yourself: In the Programming mode of operation, for example, you can have the TNC show program blocks in the left window while the right window displays programming graphics. You could also display the program structure in the right window instead, or display only program blocks in one large window. The available screen windows depend on the selected operating mode.

To change the screen layout:



 Press the screen layout key: The soft-key row shows the available layout options, see "Operating modes", page 62



Select the desired screen layout



# 2 Introduction

# 2.2 Visual display unit and operating panel

### **Control Panel**

The TNC 640 is delivered with an integrated keyboard. The figure to the right shows the operating elements of the operating panel:

- 1 Alphabetic keyboard for entering texts and file names, and for ISO programming.
- **2** File management
  - Calculator
  - MOD function
  - HELP function
- 3 Programming modes
- 4 Machine operating modes
- 5 Initiation of programming dialogs
- 6 Navigation keys and GOTO jump command
- 7 Numerical input and axis selection
- 8 Touchpad
- 9 Mouse function keys
- 10 USB connection

The functions of the individual keys are described on the inside front cover.



Some machine manufacturers do not use the standard operating panel from HEIDENHAIN. Refer to your machine manual.

Machine panel buttons, e.g. NC START or NC STOP, are described in the manual for your machine tool.



## 2.3 Modes of Operation

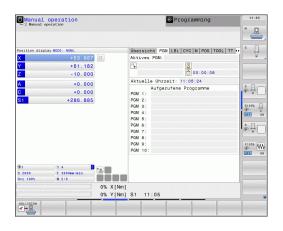
## Manual Operation and El. Handwheel

The Manual Operation mode is required for setting up the machine tool. In this mode of operation, you can position the machine axes manually or by increments, set the datums, and tilt the working plane.

The El. Handwheel mode of operation allows you to move the machine axes manually with the HR electronic handwheel.

## Soft keys for selecting the screen layout (select as described previously)

Window	Soft key
Positions	POSITION
Left: positions, right: status display	POSITION + STATUS

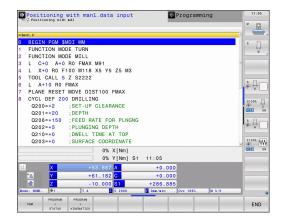


## Positioning with Manual Data Input

This mode of operation is used for programming simple traversing movements, such as for face milling or prepositioning.

#### Soft keys for selecting the screen layout

Window	Soft key
Program	PGM
Left: program blocks, right: status display	PROGRAM + STATUS

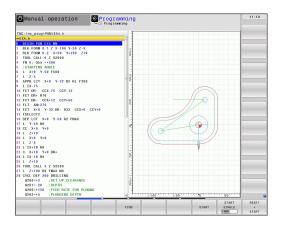


## Programming

In this mode of operation you can write your part programs. The FK free programming feature, the various cycles and the Q parameter functions help you with programming and add necessary information. If desired, you can have the programming graphics show the programmed paths of traverse.

#### Soft keys for selecting the screen layout

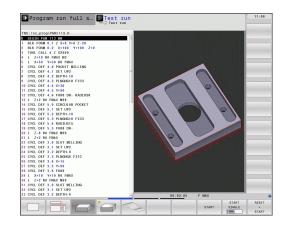
Window	Soft key
Program	PGM
Left: program, right: program structure	PROGRAM + SECTS
Left: program, right: programming graphics	PROGRAM + GRAPHICS



## **Test Run**

In the Test Run mode of operation, the TNC checks programs and program sections for errors, such as geometrical incompatibilities, missing or incorrect data within the program or violations of the working space. This simulation is supported graphically in different display modes.

Soft keys for selecting the screen layout: See "Program Run, Full Sequence and Program Run, Single Block", page 74.



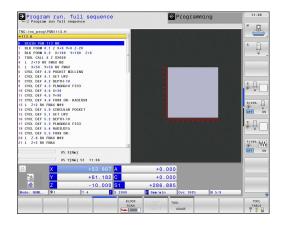
# Program Run, Full Sequence and Program Run, Single Block

In the Program Run, Full Sequence mode of operation the TNC executes a part program continuously to its end or to a manual or programmed stop. You can resume program run after an interruption.

In the Program Run, Single Block mode of operation you execute each block separately by pressing the machine START button.

#### Soft keys for selecting the screen layout

Window	Soft key
Program	PGM
Left: program, right: program structure	PROGRAM + SECTS
Left: program, right: status	PROGRAM + STATUS
Left: program, right: graphics	PROGRAM + GRAPHICS
Graphics	GRAPHICS
Window	Soft key
Pallet table	PALLET
Left: program, right: pallet table	PROGRAM + PALLET
Left: pallet table, right: status	PALLET + STATUS



## 2.4 Status displays

## "General" status display

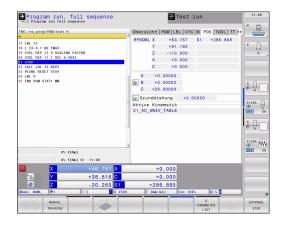
The status display in the lower part of the screen informs you of the current state of the machine tool. It is displayed automatically in the following modes of operation:

- Program Run, Single Block and Program Run, Full Sequence, except if the screen layout is set to display graphics only, and
- Positioning with Manual Data Input (MDI).

In the Manual Operation and El. Handwheel modes the status display appears in the large window.

## Information in the status display

lcon	Meaning
ACTL.	Position display: Actual, nominal or distance-to-go coordinates mode
XYZ	Machine axes; the TNC displays auxiliary axes in lower-case letters. The sequence and quantity of displayed axes is determined by the machine tool builder. Refer to your machine manual for more information
<b>(</b>	Number of the active presets from the preset table. If the datum was set manually, the TNC displays the text <b>MAN</b> behind the symbol
FSM	The displayed feed rate in inches corresponds to one tenth of the effective value. Spindle speed S, feed rate F and active M functions
•	Axis is clamped
$\bigotimes$	Axis can be moved with the handwheel
	Axes are moving under a basic rotation
	Axes are moving in a tilted working plane
TC PM	The M128 function or TCPM FUNCTION is active
ţ,	No active program



## Introduction

2

## 2.4 Status displays

lcon	Meaning
	Program run has started
D	Program run is stopped
×	Program run is being aborted
<b>_</b>	Turning mode is active
* <u>-</u> B	The Dynamic Collision Monitoring function (DCM) is active
* <u>-</u> % T	The Adaptive Feed Function (AFC) is active (software option)

## Additional status displays

The additional status displays contain detailed information on the program run. They can be called in all operating modes except for the Programming and Editing mode of operation.

## To switch on the additional status display:



- Call the soft-key row for screen layout
- Select the screen layout with additional status display: In the right half of the screen, the TNC shows the **OVERVIEW** status form

## To select an additional status display:



- Switch the soft-key rows until the STATUS soft keys appear
   Site of the state of the
- Either select the additional status display directly by soft key, e.g. positions and coordinates, or
- use the switch-over soft keys to select the desired view

The available status displays described below can be selected either directly by soft key or with the switch-over soft keys.

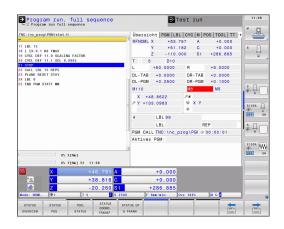


Please note that some of the status information described below is not available unless the associated software option is enabled on your TNC.

## Overview

After switch-on, the TNC displays the **Overview** status form, provided that you have selected the PROGRAM+STATUS screen layout (or POSITION + STATUS). The overview form contains a summary of the most important status information, which you can also find on the various detail forms.

Soft key	Meaning
STATUS OVERVIEW	Position display
	Tool information
	Active M functions
	Active coordinate transformations
	Active subprogram
	Active program section repeat
	Program called with PGM CALL
	Current machining time
	Name of the active main program



General program	m information	(PGM tab)
-----------------	---------------	-----------

Soft key	Meaning
No direct selection possible	Name of the active main program
	Circle center CC (pole)
	Dwell time counter
	Machining time when the program was completely simulated in the <b>Test Run</b> operating mode
	Current machining time in percent
	Current time
	Active programs

Program run, full sequence	Test run	11:08
C) Program Tun Tuli sequence TNC:inc_prog1PGW/stat.H  TV:LL 15 10 LIX-0.1 R0 FMAX 11 cCL LPS FMAX 15 10 CCL DEF 10. SCALING FACTOR	Übersicht         PGM         LBL         GYG         M         POS         TOOL         TT         •           Aktives         PGM:	*
20 CYCL DEF 11.1 SCL 0.9995 21 STOP 22 CALL LBL 15 REP5 23 PLANE RESET STAY	Aktuelle Uhrzeit: 11:08:19 Aufgerufene Programme PGM 1: TNO:\nc prog\PGM\STAT1.H	
24 LBL 0 25 END PGM STATI NM	PGM 2: PGM 3: PGM 4:	*
	PGM 5: PGM 6: PGM 7:	S100%
	PGM 8: PGM 9: PGM 10:	8
Contraction of XINe1	a	
0% Y[Nm] S1 11:08		
X +46.791 A	+0.000	
🛎 Y +38.816 C	+0.000	
Z -20.260 S1	+286.885	
Mode: NONL. #1 T 5 Z S 2500	F 0mm/min Ovr 100% N 5/8	۲
RESTORE MANUAL POSETION TRAVERSE	Q 0 PARAMETER LIST INFO	INTERNAL STOP

## Introduction

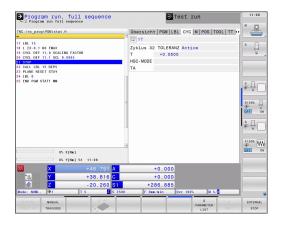
## Program section repeat/Subprograms (LBL tab)

Soft key	Meaning
No direct selection possible	Active program section repeats with block number, label number, and number of programmed repeats/repeats yet to be run
	Active subprogram numbers with block number in which the subprogram was called and the label number that was called

5 END PGM STAT1 NM		Wiederholu Satz-Nr.	ngen LBL-Nr./M	lame	REP	S100%
	_					

#### Information on standard cycles (CYC tab)

Soft key	Meaning
No direct selection possible	Active machining cycle
	Active values of Cycle 32 Tolerance



## Active miscellaneous functions M (M tab)

Soft key	Meaning
No direct selection possible	List of the active M functions with fixed meaning
	List of the active M functions that are adapted

List of the active M functions that are adapted by your machine manufacturer

Program run, full se	quence		∋Test ru	n	11:08
FNC:\nc_prog\PGM\stat.H		Übersicht PGN	LBL CYC M	POS TOOL TT	1 🖳
7 LBL 15 8 L IX-0.1 R0 FMAX 9 CVCL DEF 11.0 SCALING FACTOR 0 CVCL DEF 11.1 SCL 0.3995 1 STOP 2 CALL LBL 15 REPS 30 PLANE REST STAY		M110			\$ _
3 PLANE HESEISIAY 44 EBL 0 55 END PGM STATI NM		M8 M5	OEM		8
		M50			
0% X[Nm] 0% Y[Nm] S1 11	:08				
🙆 🗶 +4	6.791 A	+0.0	00		
	88.816 C	+0.0	00		
Z -2	20.260 S1	+286.8	85 0vr 100%	N 5/8	
PERFORE MANUAL POSITION TRAVERSE	20 ROT	e jr One/min	_	G O RANETER INFO	INTERNAL

#### Positions and coordinates (POS tab)

Soft key	Meaning
STATUS POS.	Type of position display, e.g. actual position
	Tilt angle of the working plane
	Angle of a basic rotation
	Active kinematics

Program run, full sequence	⊇ Test run	11:08
TNG:\nc_prog\PGW\stat.H	Übersicht PGM LBL CYC M POS TOOL TT .	" _
	RFNOML X         +53.767         \$1         +286.865           Y         *61.182         -          -         -<	8
24 IBL 0 25 END PGM STATI HM	A +0.00000 B +0.00000 C +25.00000	* *
	Image: Construint of the second sec	S100%
0% X[Ne]		
X         +46.791         A           ***         Y         +38.816         C           ***         Z         -20.260         S1           ***         T         5         Z         2500	+0.000 +0.000 +286.885 F Descarto Over 100% N 5/0	
PESTORE NANUAL 30 ROT POSITION TRAVERSE	Q 0 PARAMETER LIST INFO	INTERNAL STOP

## Introduction

## 2.4 Status displays

## Information on tools (TOOL tab)

Soft key	Meaning
TOOL	Display of active tool:
STATUS	T: Tool number and name
	RT: Number and name of a replacement tool
	Tool axis
	Tool length and radii
	Oversizes (delta values) from the tool table (TAB) and the <b>TOOL CALL</b> (PGM)
	Tool life, maximum tool life (TIME 1) and maximum tool life for <b>TOOL CALL</b> (TIME 2)
	Display of programmed tool and replacement tool

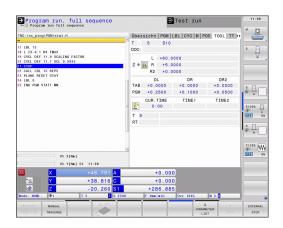
Display of programmed tool and replacement tool

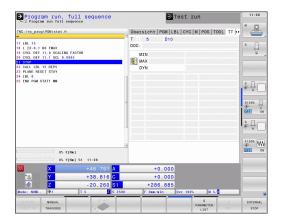
## Tool measurement (TT tab)



The TNC displays the TT tab only if the function is active on your machine.

Soft key	Meaning
No direct selection possible	Number of the tool to be measured
	Display whether the tool radius or the tool length is being measured
	MIN and MAX values of the individual cutting edges and the result of measuring the rotating tool (DYN = dynamic measurement)
	Cutting edge number with the corresponding measured value. If the measured value is followed by an asterisk, the permissible tolerance in the tool table was exceeded





Coordinate	transformations	(TRANS	tab)
------------	-----------------	--------	------

Soft key	Meaning
STATUS COORD. TRANSF.	Name of the active datum table
	Active datum number ( <b>#</b> ), comment from the active line of the active datum number ( <b>DOC</b> ) from Cycle 7
	Active datum shift (Cycle 7); The TNC displays an active datum shift in up to 8 axes
	Mirrored axes (Cycle 8)
	Active basic rotation
	Active rotation angle (Cycle 10)
	Active scaling factor/factors (Cycles 11 / 26); The TNC displays an active scaling factor in up to 6 axes
	Scaling datum

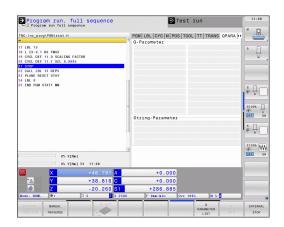
Program run, full sequence ∋Test run PGM LEL OYC M POS TOOL TT TRANS ↔ Nullpunkt-Tab.: # DOC: X +48.8522 ¥ +133.0983 s 🗍 LBL 15 L IX-0.1 R0 FMAX CYCL DEF 11.0 SCALING FACTO CYCL DEF 11.1 SCL 0.9995 STOP CALL LBL 15 REP5 PLANE RESET STAY LBL 0 END PGM STAT1 NM ¶РХҮ +0.00000 \* \* X 0.999500 Y 0.999500 Z 0.999500 5100% ₽ \* \* F100% 0% X[Nm] 0% Y[Nm] S1 11:08 +0.000 +38.816 +286.885 Q PARAVETER INTERNAL STOP MAN

For further information, refer to the User's Manual for Cycles, "Coordinate Transformation Cycles."

#### **Displaying Q parameters (QPARA tab)**

Soft key	Meaning
STATUS OF Q PARAM.	Display the current values of the defined Q parameters

Display the character strings of the defined string parameters



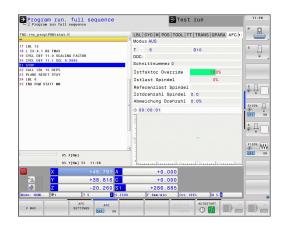
2.4 Status displays

#### Adaptive Feed Control (AFC tab, software option)



The TNC displays the AFC tab only if the function is active on your machine.

Soft key	Meaning
No direct selection possible	Active tool (number and name)
	Cut number
	Current factor of the feed potentiomenter in percent
	Active spindle load in percent
	Reference load of the spindle
	Current spindle speed
	Current deviation of the speed
	Current machining time
	Line diagram, in which the current spindle load and the value commanded by the TNC for the feed-rate override are shown



## 2.5 Window Manager



The machine tool builder determines the scope of function and behavior of the window manager. Refer to your machine manual.

The TNC features the Xfce window manager. Xfce is a standard application for UNIX-based operating systems, and is used to manage graphical user interfaces. The following functions are possible with the window manager:

- Display a task bar for switching between various applications (user interfaces).
- Manage an additional desktop, on which special applications from your machine tool builder can run.
- Control the focus between NC-software applications and those of the machine tool builder.
- The size and position of pop-up windows can be changed. It is also possible to close, minimize and restore the pop-up windows.



The TNC shows a star in the upper left of the screen if an application of the window manager or the window manager itself has caused an error. In this case, switch to the window manager and correct the problem. If required, refer to your machine manual.

## Task bar

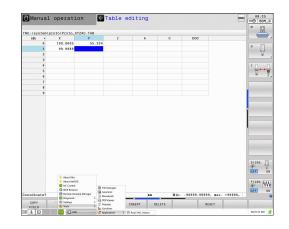
In the task bar you can choose different workspaces by mouse click. The TNC provides the following workspaces:

- Workspace 1: Active mode of operation
- Workspace 2: Active programming mode
- Workspace 3: Manufacturer's applications (optionally available)

In the task bar you can also select other applications that you have started together with the TNC (switch for example to the **PDF viewer** or **TNCguide**)

Click the green HEIDENHAIN symbol to open a menu in which you can get information, make settings or start applications. The following functions are available:

- About Xfce: Information on the Windows manager Xfce
- About HEROS: Information about the operating system of the TNC
- NC Control: Start and stop the TNC software. Only permitted for diagnostic purposes
- Web Browser: Start Mozilla Firefox
- Diagnostics: Available only to authorized specialists to start diagnostic functions
- Settings: Configuration of miscellaneous settings
  - **Date/Time**: Set the date and time
  - Language: Language setting for the system dialogs. During startup the TNC overwrites this setting with the language setting of MP 7230
  - Network: Network setting
  - Reset WM-Conf: Restore basic settings of the Windows Manager. May also reset settings implemented by your machine manufacturer
  - Screensaver: Settings for the screen saver; several are available
  - Shares: Configure network connections
- Tools: Only for authorized users. The applications available under tools can be started directly by selecting the pertaining file type in the file management of the TNC See "File manager: Fundamentals", page 105



## 2.6 SELinux security software

**SELinux** is an extension for Linux-based operating systems. SELinux is an additional security software package based on Mandatory Access Control (MAC) and protects the system against the running of unauthorized processes or functions and therefore protects against viruses and other malware.

MAC means that each action must be specifically permitted otherwise the TNC will not run it. The software is intended as protection in addition to the normal access restriction in Linux. Certain processes and actions can only be executed if the standard functions and access control of SELinux permit it.



The SELinux installation of the TNC is prepared to permit running of only those programs installed with the HEIDENHAIN NC software. Other programs cannot be run with the standard installation.

The access control of SELinux under HEROS 5 is regulated as follows:

- The TNC runs only those applications installed with the HEIDENHAIN NC software.
- Files in connection with the safety of the software (SELinux system files, HEROS 5 boot files etc.) may only be changed by programs that are selected explicitly.
- New files generated by other programs must never be executed.
- There are only two processes that are permitted to execute new files:
  - Starting a software update: A software update from HEIDENHAIN can replace or change system files.
  - Starting the SELinux configuration: The configuration of SELinux is usually password-protected by your machine tool builder. Refer here to the relevant machine tool manual.



HEIDENHAIN generally recommends activating SELinux because it provides additional protection against attacks from outside.

## Introduction

2.7 Accessories: HEIDENHAIN 3-D Touch Probes and Electronic Handwheels

## 2.7 Accessories: HEIDENHAIN 3-D Touch Probes and Electronic Handwheels

## 3-D touch probes

The various HEIDENHAIN 3-D touch probes enable you to:

- Automatically align workpieces
- Quickly and precisely set datums
- Measure the workpiece during program run
- Measure and inspect tools

All of the cycle functions (touch probe cycles and fixed cycles) are described in the Cycle Programming User's Manual. Please contact HEIDENHAIN if you require a copy of this User's Manual. ID: 892905-xx

## TS 220, TS 440, TS 444, TS 640 und TS 740 touch trigger probes

These touch probes are particularly effective for automatic workpiece alignment, datum setting and workpiece measurement. The TS 220 transmits the triggering signals to the TNC via cable and is a cost-effective alternative for applications where digitizing is not frequently required.

The TS 640 (see figure) and the smaller TS 440 feature infrared transmission of the triggering signal to the TNC. This makes them highly convenient for use on machines with automatic tool changers.

Principle of operation: HEIDENHAIN triggering touch probes feature a wear resisting optical switch that generates an electrical signal as soon as the stylus is deflected. This signal is transmitted to the control, which stores the current position of the stylus as the actual value.

## TT 140 tool touch probe for tool measurement

The TT 140 is a triggering 3-D touch probe for tool measurement and inspection. Your TNC provides three cycles for this touch probe with which you can measure the tool length and radius automatically either with the spindle rotating or stopped. The TT 140 features a particularly rugged design and a high degree of protection, which make it insensitive to coolants and swarf. The triggering signal is generated by a wear-resistant and highly reliable optical switch.



## Accessories: HEIDENHAIN 3-D Touch Probes and Electronic 2.7 Handwheels

## **HR** electronic handwheels

Electronic handwheels facilitate moving the axis slides precisely by hand. A wide range of traverses per handwheel revolution is available. Apart from the HR 130 and HR 150 panel-mounted handwheels, HEIDENHAIN also offers the HR 410 portable handwheel.





3.1 Fundamentals

3

## 3.1 Fundamentals

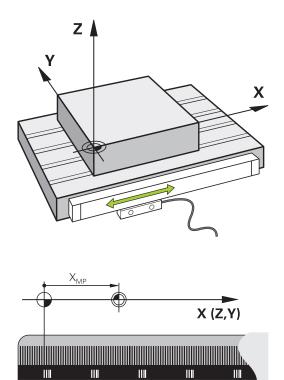
## Position encoders and reference marks

The machine axes are equipped with position encoders that register the positions of the machine table or tool. Linear axes are usually equipped with linear encoders, rotary tables and tilting axes with angle encoders.

When a machine axis moves, the corresponding position encoder generates an electrical signal. The TNC evaluates this signal and calculates the precise actual position of the machine axis.

If there is a power interruption, the calculated position will no longer correspond to the actual position of the machine slide. To recover this association, incremental position encoders are provided with reference marks. The scales of the position encoders contain one or more reference marks that transmit a signal to the TNC when they are crossed over. From that signal the TNC can re-establish the assignment of displayed positions to machine positions. For linear encoders with distance-coded reference marks, the machine axes need to move by no more than 20 mm, for angle encoders by no more than 20°.

With absolute encoders, an absolute position value is transmitted to the control immediately upon switch-on. In this way the assignment of the actual position to the machine slide position is re-established directly after switch-on.

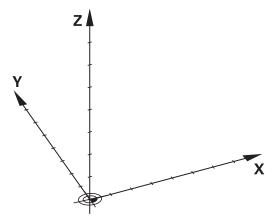


## **Reference system**

A reference system is required to define positions in a plane or in space. The position data are always referenced to a predetermined point and are described through coordinates.

The Cartesian coordinate system (a rectangular coordinate system) is based on the three coordinate axes X, Y and Z. The axes are mutually perpendicular and intersect at one point called the datum. A coordinate identifies the distance from the datum in one of these directions. A position in a plane is thus described through two coordinates, and a position in space through three coordinates.

Coordinates that are referenced to the datum are referred to as absolute coordinates. Relative coordinates are referenced to any other known position (reference point) you define within the coordinate system. Relative coordinate values are also referred to as incremental coordinate values.

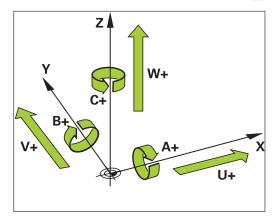


## **Reference system on milling machines**

When using a milling machine, you orient tool movements to the Cartesian coordinate system. The illustration at right shows how the Cartesian coordinate system describes the machine axes. The figure illustrates the right-hand rule for remembering the three axis directions: the middle finger points in the positive direction of the tool axis from the workpiece toward the tool (the Z axis), the thumb points in the positive X direction, and the index finger in the positive Y direction.

The TNC 640 can control up to 18 axes optionally. The axes U, V and W are secondary linear axes parallel to the main axes X, Y and Z, respectively. Rotary axes are designated as A, B and C. The illustration at lower right shows the assignment of secondary axes and rotary axes to the main axes.

# +Z +X +Z +X +Y +Z +X



## Designation of the axes on milling machines

The X, Y and Z axes on your milling machine are also referred to as tool axis, principal axis (1st axis) and secondary axis (2nd axis). The assignment of the tool axis is decisive for the assignment of the principal and secondary axes.

Tool axis	Principal axis	Secondary axis
Х	Y	Z
Y	Z	Х
Z	Х	Y

3.1 Fundamentals

## **Polar coordinates**

3

If the production drawing is dimensioned in Cartesian coordinates, you also write the NC program using Cartesian coordinates. For parts containing circular arcs or angles it is often simpler to give the dimensions in polar coordinates.

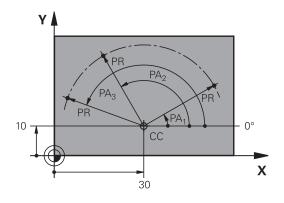
While the Cartesian coordinates X, Y and Z are three-dimensional and can describe points in space, polar coordinates are twodimensional and describe points in a plane. Polar coordinates have their datum at a circle center (CC), or pole. A position in a plane can be clearly defined by the:

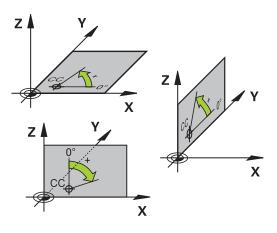
- Polar Radius, the distance from the circle center CC to the position, and the
- Polar Angle, the value of the angle between the angle reference axis and the line that connects the circle center CC with the position.

#### Setting the pole and the angle reference axis

The pole is set by entering two Cartesian coordinates in one of the three planes. These coordinates also set the reference axis for the polar angle PA.

Coordinates of the pole (plane)	Reference axis of the angle
X/Y	+X
Y/Z	+Y
Z/X	+Z





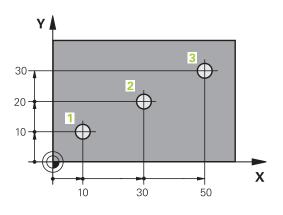
## Absolute and incremental workpiece positions

## Absolute workpiece positions

Absolute coordinates are position coordinates that are referenced to the datum of the coordinate system (origin). Each position on the workpiece is uniquely defined by its absolute coordinates.

Example 1: Holes dimensioned in absolute coordinates

Hole 1	Hole 2	Hole 3
X = 10 mm	X = 30 mm	X = 50 mm
Y = 10 mm	Y = 20 mm	Y = 30 mm



5

20

6

20

Х

Υ

0

0

 $\bigcirc$ 

4

## Incremental workpiece positions

Incremental coordinates are referenced to the last programmed nominal position of the tool, which serves as the relative (imaginary) datum. When you write an NC program in incremental coordinates, you thus program the tool to move by the distance between the previous and the subsequent nominal positions. This is why they are also referred to as chain dimensions.

Example 2: Holes dimensioned in incremental coordinates

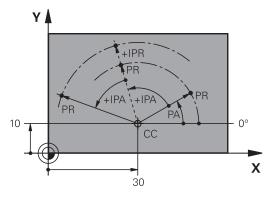
## Absolute coordinates of hole 4

X = 10 mm	
Y = 10 mm	
Hole 5, with respect to 4	Hole 6, with respect to 5
Hole 5, with respect to 4 X = 20 mm	Hole 6, with respect to 5 X = 20 mm

## Absolute and incremental polar coordinates

Absolute polar coordinates always refer to the pole and the angle reference axis.

Incremental polar coordinates always refer to the last programmed nominal position of the tool.



3.1 Fundamentals

3

## Selecting the datum

A production drawing identifies a certain form element of the workpiece, usually a corner, as the absolute datum. When setting the datum, you first align the workpiece along the machine axes, and then move the tool in each axis to a defined position relative to the workpiece. Set the display of the TNC either to zero or to a known position value for each position. This establishes the reference system for the workpiece, which will be used for the TNC display and your part program.

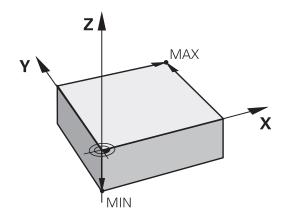
If the production drawing is dimensioned in relative coordinates, simply use the coordinate transformation cycles (see User's Manual for Cycles, Cycles for Coordinate Transformation).

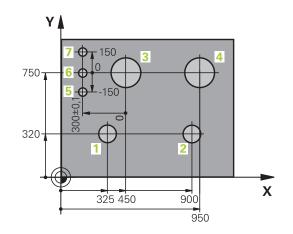
If the production drawing is not dimensioned for NC, set the datum at a position or corner on the workpiece from which the dimensions of the remaining workpiece positions can be most easily measured.

The fastest, easiest and most accurate way of setting the datum is by using a 3-D touch probe from HEIDENHAIN. See "Setting the Datum with a 3-D Touch Probe" in the Cycle Programming User's Manual.

#### Example

The workpiece drawing shows holes (1 to 4) whose dimensions are shown with respect to an absolute datum with the coordinates X=0 Y=0. Holes 5 to 7 are dimensioned with respect to a relative datum with the absolute coordinates X=450, Y=750. With the **DATUM** SHIFT cycle you can temporarily set the datum to the position X=450, Y=750, to be able to program holes 5 to 7 without further calculations.





**Opening programs and entering** 

## 3.2 Opening programs and entering

# Organization of an NC program in HEIDENHAIN Conversational format

A part program consists of a series of program blocks. The figure at right illustrates the elements of a block.

The TNC numbers the blocks in ascending sequence.

The first block of a program is identified by  $\ensuremath{\text{BEGIN PGM}}$  , the program name and the active unit of measure.

The subsequent blocks contain information on:

- The workpiece blank
- Tool calls
- Approaching a safe position
- Feed rates and spindle speeds, as well as
- Path contours, cycles and other functions

The last block of a program is identified by **END PGM** the program name and the active unit of measure.

After each tool call, HEIDENHAIN recommends always traversing to a safe position from which the TNC can position the tool for machining without causing a collision!

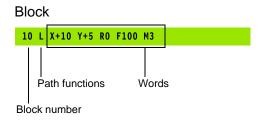
## Define the blank: BLK FORM

Immediately after initiating a new program, you define a cuboid workpiece blank. If you wish to define the blank at a later stage, press the SPEC FCT key, the PROGRAM DEFAULTS soft key, and then the BLK FORM soft key. This definition is needed for the TNC's graphic simulation feature. The sides of the workpiece blank lie parallel to the X, Y and Z axes and can be up to 100 000 mm long. The workpiece blank is defined by two of its corner points:

- MIN point: the smallest X, Y and Z coordinates of the blank form, entered as absolute values
- MAX point: the largest X, Y and Z coordinates of the blank form, entered as absolute or incremental values



You only need to define the workpiece blank if you wish to run a graphic test for the program!



3.2

3.2 Opening programs and entering

## Opening a new part program

You always enter a part program in the **PROGRAMMING AND EDITING** mode of operation. An example of program initiation:





3

Call the file manager: Press the PGM MGT key

Select the directory in which you wish to store the new program:

## FILE NAME = ALT.H



MM

- Enter the new program name and confirm your entry with the ENT key.
- Select the unit of measure: Press the MM or INCH soft key. The TNC switches the screen layout and initiates the dialog for defining the **BLK FORM** (workpiece blank)

#### WORKING PLANE IN GRAPHIC: XY



► Enter spindle axis, e.g. Z

#### WORKPIECE BLANK DEF .: MINIMUM

Enter in sequence the X, Y and Z coordinates of the MIN point and confirm each of your entries with the ENT key

#### WORKPIECE BLANK DEF .: MAXIMUM

ENT

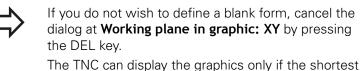
ENT

Enter in sequence the X, Y and Z coordinates of the MAX point and confirm each of your entries with the ENT key

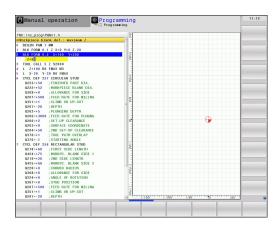
#### Example: Display the BLK form in the NC program

O BEGIN PGM NEW MM	Program begin, name, unit of measure
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	Spindle axis, MIN point coordinates
2 BLK FORM 0.2 X+100 Y+100 Z+0	MAX point coordinates
3 END PGM NEW MM	Program end, name, unit of measure

The TNC automatically generates the block numbers as well as the **BEGIN** and **END** blocks.



side is at least 50  $\mu$ m long and the longest side is no longer than 99 999.999 mm.



## Programming tool movements in conversational

To program a block, initiate the dialog by pressing a function key. In the screen headline, the TNC then asks you for all the information necessary to program the desired function.

If you enter DIN/ISO functions via a connected USB keyboard, make sure that capitalization is active.

#### Example of a positioning block



Open block

#### **COORDINATES ?**



10 (Enter the target coordinate for the X axis)



20 (Enter the target coordinate for the Y axis)



go to the next question with ENT.

#### RADIUS COMP.: RL/RR/NO COMP.?



 Enter "No radius compensation" and go to the next guestion with ENT.

#### FEED RATE F=? / F MAX = ENT

▶ 100 (Enter a feed rate of 100 mm/min for this path contour)



▶ go to the next question with ENT.

#### **MISCELLANEOUS FUNCTION M ?**

Enter 3 (miscellaneous function M3 "Spindle ON").



► The TNC ends this dialog by pressing the ENT key.

#### The program-block window displays the following line:

3 L X+10 Y+5 R0 F100 M3

## 3.2 Opening programs and entering

#### Possible feed rate input

3

Functions for setting the feed rate	Soft key
Rapid traverse, non-modal. Exception: If defined before an <b>APPR</b> block, <b>FMAX</b> is also in effect for moving to an auxiliary point (See "Important positions for approach and departure", page 199)	F MAX
Traverse feed rate automatically calculated in <b>TOOL CALL</b>	F AUTO
Move at the programmed feed rate (unit of measure is mm/min or 1/10 inch/min). With rotary axes, the TNC interprets the feed rate in degrees/min, regardless of whether the program is written in mm or inches	F
Define the feed per revolution (units in mm/ rev or inch/rev). Caution: In inch-programs, FU cannot be combined with M136	FU
Define the tooth feed (units in mm/tooth or inch/tooth). The number of teeth must be defined in the tool table in the <b>CUT.</b> column	FZ
Functions for conversational guidance	Кеу
Ignore the dialog question	NO
End the dialog immediately	
Abort the dialog and erase the block	

## Actual position capture

The TNC enables you to transfer the current tool position into the program, for example during

- Positioning-block programming
- Cycle programming

To transfer the correct position values, proceed as follows:

Place the input box at the position in the block where you want to insert a position value



 Select the actual-position-capture function: In the soft-key row the TNC displays the axes whose positions can be transferred

- AXIS Z
- Select the axis: The TNC writes the current position of the selected axis into the active input box

In the working plane the TNC always captures the coordinates of the tool center, even though tool radius compensation is active.

In the tool axis the TNC always captures the coordinates of the tool tip and thus always takes the active tool length compensation into account.

The TNC keeps the soft-key row for axis selection active until you deactivate it by pressing the actualposition-capture key again. This behavior remains in effect even if you save the current block and open a new one with a path function key. If you select a block element in which you must choose an input alternative via soft key (e.g. for radius compensation), then the TNC also closes the soft-key row for axis selection.

The actual-position-capture function is not allowed if the tilted working plane function is active.

3.2 Opening programs and entering

## Editing a program



3

You cannot edit a program while it is being run by the TNC in a machine operating mode.

While you are creating or editing a part program, you can select any desired line in the program or individual words in a block with the arrow keys or the soft keys:

Function	Soft key/Keys
Go to previous page	
Go to next page	
Go to beginning of program	BEGIN
Go to end of program	
Change the position of the current block on the screen. Press this soft key to display additional program blocks that are programmed before the current block	ŀ
Change the position of the current block on the screen. Press this soft key to display additional program blocks that are programmed after the current block	
Move from one block to the next	↑
Select individual words in a block	<ul> <li>→</li> <li>→</li> </ul>
To select a certain block, press the GOTO key, enter the desired block number, and confirm with the ENT key. Or: Enter the block number step and press the N LINES soft key to jump over the entered number of lines unward or downward	бото

of lines upward or downward

Function	Soft key/Key
Set the selected word to zero	CE
Erase an incorrect number	CE
Clear a (non-blinking) error message	CE
Delete the selected word	NO
Delete the selected block	DEL
Erase cycles and program sections	DEL
Insert the block that you last edited or deleted	INSERT LAST NC BLOCK

#### Inserting blocks at any desired location

 Select the block after which you want to insert a new block and initiate the dialog

#### Editing and inserting words

- Select a word in a block and overwrite it with the new one. The plain-language dialog is available while the word is highlighted
- ▶ To accept the change, press the END key

If you want to insert a word, press the horizontal arrow key repeatedly until the desired dialog appears. You can then enter the desired value.

#### Looking for the same words in different blocks

Set the AUTO DRAW soft key to OFF.



 Select a word in a block: Press the arrow key repeatedly until the highlight is on the desired word



Select a block with the arrow keys

The word that is highlighted in the new block is the same as the one you selected previously.



If you have started a search in a very long program, the TNC shows a progress display window. You then have the option of canceling the search via soft key.

## 3.2 Opening programs and entering

#### Finding any text

3

- Select the search function: Press the FIND soft key. The TNC displays the Find text: dialog prompt
- Enter the text that you wish to find
- ▶ Find the text: Press the EXECUTE soft key

#### Marking, copying, deleting and inserting program sections

The TNC provides certain functions for copying program sections within an NC program or into another NC program—see the table below.

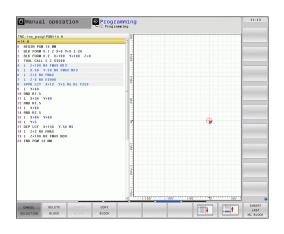
To copy a program section, proceed as follows:

- Select the soft-key row containing the marking functions
- Select the first (last) block of the section you wish to copy
- To mark the first (last) block, press the SELECT BLOCK soft key. The TNC then highlights the first character of the block and the CANCEL SELECTION soft key appears
- Move the highlight to the last (first) block of the program section you wish to copy or delete. The TNC shows the marked blocks in a different color. You can end the marking function at any time by pressing the CANCEL SELECTION soft key
- To copy the selected program section, press the COPY BLOCK soft key. To delete the selected section, press the DELETE BLOCK soft key. The TNC stores the selected block
- Using the arrow keys, select the block after which you wish to insert the copied (deleted) program section



To insert the section into another program, select the corresponding program using the file manager and then mark the block after which you wish to insert the copied block.

- ▶ To insert the block, press the INSERT BLOCK soft key
- To end the marking function, press the CANCEL SELECTION soft key



Function	Soft key
Switch the marking function on	SELECT BLOCK
Switch the marking function off	CANCEL SELECTION
Delete the marked block	CUT OUT BLOCK
Insert the block that is stored in the buffer memory	INSERT BLOCK
Copy the marked block	COPY BLOCK

## The TNC search function

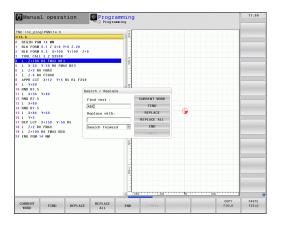
The search function of the TNC enables you to search for any text within a program and replace it by a new text, if required.

## Finding any text

END

If required, select the block containing the word you wish to find

FIND	<ul> <li>Select the search function: The TNC superimposes the search window and displays the available search functions in the soft-key row (see table of search functions)</li> </ul>
X	<ul> <li>+40 (Enter the text to be searched for. The search is case-sensitive.)</li> </ul>
FIND	<ul> <li>Start the search process: The TNC moves to the next block containing the text you are searching for</li> </ul>
FIND	<ul> <li>Repeat the search process: The TNC moves to the next block containing the text you are searching for</li> </ul>
END	End the search function



## 3.2 Opening programs and entering

#### Finding/Replacing any text



3

- The find/replace function is not possible if
- a program is protected
- the program is currently being run by the TNC

When using the REPLACE ALL function, ensure that you do not accidentally replace text that you do not want to change. Once replaced, such text cannot be restored.

► If required, select the block containing the word you wish to find



7

FIND

REPLACE

- Select the Search function: The TNC superimposes the search window and displays the available search functions in the soft-key row
- Enter the text to be searched for. Please note that the search is case-sensitive. Then confirm with the ENT key
- Enter the text to be inserted. Please note that the entry is case-sensitive
- Start the search process: The TNC moves to the next occurrence of the text you are searching for
- To replace the text and then move to the next occurrence of the text, press the REPLACE soft key. To replace all text occurrences, press the REPLACE ALL soft key. To skip the text and move to its next occurrence press the FIND soft key
- END
- ► End the search function

## 3.3 File manager: Fundamentals

## Files

Files in the TNC	Туре
Programs in HEIDENHAIN format	.н .I
in DIN/ISO format	.1
Tables forToolsTool changersDatumsPointsPresetsTouch probesBackup filesDependent data (e.g. structure items)PalletsTurning tools	.T .TCH .D .PNT .PR .TP .BAK .DEP .P .TRN
<b>Texts as</b> ASCII files Protocol files Help files	.A .TXT .CHM

## 3.3 File manager: Fundamentals

When you write a part program on the TNC, you must first enter a program name. The TNC saves the program to the hard disk as a file with the same name. The TNC can also save texts and tables as files.

The TNC provides a special file management window in which you can easily find and manage your files. Here you can call, copy, rename and erase files.

You can manage an almost unlimited number of files with the TNC. The available memory is at least **21 GB**. A single NC program can be up to **2 GB** in size.



Depending on the setting, the TNC generates a backup file (\*.bak) after editing and saving of NC programs. This can reduce the memory space available to you.

#### **File names**

When you store programs, tables and texts as files, the TNC adds an extension to the file name, separated by a point. This extension indicates the file type.

File name	File type
PROG20	.Н

File names should not exceed 25 characters, otherwise the TNC cannot display the entire file name.

File names on the TNC must comply with this standard: The Open Group Base Specifications Issue 6 IEEE Std 1003.1, 2004 Edition (Posix-Standard). Accordingly, the file names may include the characters below:

A B C D E F G H I J K L M N O P Q R S T U V W X Y Z a b c d e f g h i j k l m n o p q r s t u v w x y z 0 1 2 3 4 5 6 7 8 9 . \_ -

You should not use any other characters in file names in order to prevent any file transfer problems.



The maximum limit for the path and file name together is 82 characters, See "Paths".

## Displaying externally generated files on the TNC

The TNC features several additional tools which you can use to display the files shown in the table below. Some of the files can also be edited.

File types	Туре
PDF files	pdf
Excel tables	xls
	CSV
Internet files	html
Text files	t×t
	ini
Graphics files	bmp
	gif
	gqi
	png

For further information about displaying and editing the listed file types: See page 120

## Data Backup

We recommend saving newly written programs and files on a PC at regular intervals.

The TNCremoNT data transmission freeware from HEIDENHAIN is a simple and convenient method for backing up data stored on the TNC.

You additionally need a data medium on which all machinespecific data, such as the PLC program, machine parameters, etc., are stored. Ask your machine manufacturer for assistance, if necessary.



Saving the contents of the entire hard disk (2GB) can take up to several hours. In this case, it is a good idea to save the data outside of work hours, e.g. during the night.

Take the time occasionally to delete any unneeded files so that the TNC always has enough hard-disk space for system files (such as the tool table).



Depending on operating conditions (e.g., vibration load), hard disks generally have a higher failure rate after three to five years of service. HEIDENHAIN therefore recommends having the hard disk inspected after three to five years.

3.4 Working with the file manager

## 3.4 Working with the file manager

## **Directories**

3

To ensure that you can easily find your files, we recommend that you organize your hard disk into directories. You can divide a directory into further directories, which are called subdirectories. With the -/+ key or ENT you can show or hide the subdirectories.

## Paths

A path indicates the drive and all directories and subdirectories under which a file is saved. The individual names are separated by a backslash "\".



The path, including all drive characters, directory and the file name, including the extension, must not exceed 82 characters!

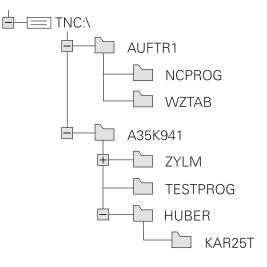
Drive designations must not include more than 8 uppercase letters.

#### Example

The directory AUFTR1 was created on the **TNC:**\ drive. Then, in the **AUFTR1** directory, the subdirectory NCPROG was created and the part program PROG1.H was copied into it. The part program now has the following path:

#### TNC:\AUFTR1\NCPROG\PROG1.H

The chart at right illustrates an example of a directory display with different paths.



## **Overview: Functions of the file manager**

Function	Soft key	Page
Copy a single file		112
Display a specific file type	SELECT	111
Create new file	NEW FILE	112
Display the last 10 files that were selected	LAST FILES	115
Delete a file or directory	DELETE	116
Tag a file	TAG	117
Rename a file		118
Protect a file against editing and erasure		119
Cancel file protection		119
Importing tool tables	IMPORT TABLE	180
Manage network drives	NET	127
Select the editor	SELECT EDITOR	119
Sort files by properties	SORT	118
Copy a directory		115
Delete directory with all its subdirectories	DELETE ALL	
Display all the directories of a particular drive		
Rename a directory		
Create a new directory		

3.4 Working with the file manager

## Calling the file manager

 Press the PGM MGT key: The TNC displays the file management window (see figure for default setting. If the TNC displays a different screen layout, press the WINDOW soft key)

The narrow window on the left shows the available drives and directories. Drives designate devices with which data are stored or transferred. One drive is the hard disk of the TNC. Other drives are the interfaces (RS232, Ethernet), which can be used, for example, for connecting a personal computer. A directory is always identified by a folder symbol to the left and the directory name to the right. Subdirectories are shown to the right of and below their parent directories. A triangle in front of the folder symbol indicates that there are further subdirectories, which can be shown with the –/+ or ENT keys.

The wide window on the right shows you all files that are stored in the selected directory. Each file is shown with additional information, illustrated in the table below.

Display	Meaning
File name	Name with max. 25 characters
Туре	File type
Bytes	File size in bytes
Status	File properties:
E	Program is selected in the Programming mode of operation
S	Program is selected in the Test Run mode of operation
Μ	Program is selected in a Program Run mode of operation
<b>a</b>	File is protected against erasing and editing
<b>a</b>	File is protected against erasing and editing, because it is being run
Date	Date that the file was last edited
Time	Time that the file was last edited

🙆 Manual operat	ion Programming	11:12
e-a PLC: \	TNC: \nc. prog\PGH\*.H;*.I	-
D-CO TNC: \	The the program the tr	
Ba config	✿ File name Bytes Status Date Time	-
⊐ <b>⊡</b> nc_prog	A3803 1.I 426 02-05-2011 10:15:2	2
Ba Sort	BHB 1 3.H 1133 31-07-2012 09:51:4	
DC CAP	BLK.H 110 02-05-2011 10:15:2	
⊕⊖ de	BSP Platte.H 4468 27-07-2012 08:27:1	
n 🗅 demo	Cvcl.h 1271 18-09-2012 13:36:5	
🕀 🗀 drehen	DXF.H 292 27-07-2012 07:05:2	
DXF	error.h 554 02-05-2011 10:15:2	
9-20 EMO_2011	EX11.H 1963 07-03-2013 10:54:5	
en en en	EX16.H 997 + 02-05-2011 10:15:2	2
ma it	EX16 SL.H 1792 02-05-2011 10:15:2	2
PGI PGI	EX18.H 796 + 26-07-2012 08:08:1	8
PGN PGN2	EX18 SL.H 1513 + 02-05-2011 10:15:2	2
DO TABLE	EX4.H 1036 02-05-2011 10:15:2	2
BO system	HEBEL.H 541 + 02-05-2011 10:15:2	2
p table	koord.h 1596 S + 02-05-2011 10:15:2	2
BO tesp	NEUGL.I 684 + 02-05-2011 10:15:2	
no incavide	PAT.H 152 E 07-03-2013 11:12:3	
o 🖬 thega tae	PL1.H 2697 + 02-05-2011 10:15:2	2
	Ra-P1.h 6675 18-09-2012 13:06:2	
	RAD6.h 400 + 05-03-2013 11:54:1	
	Rastplatte.h 4837 25-07-2012 10:41:2	
	Reset.H 365 + 06-03-2013 06:39:0	
	Schulter.h 3477 26-07-2012 09:59:0	
	STAT.H 479 M 02-05-2011 10:15:2	
	STAT1.H 623 02-05-2011 10:15:2	
	TCH.h 1320 07-03-2013 11:09:4	
	turbine.H 1971 09-10-2012 07:11:2	
	TURN.H 1078 + 07-03-2013 11:00:0	
	wheel.h 10767 + 18-09-2012 14:02:4	
	wheelgirder.H 12345K 11-01-2013 11:00:4	2
	51 file(s) 169.35 GB vacant	
PAGE PAGE	SELECT COPY SELECT WINDOW LAST	CNIC
1 1		END

PGM MGT

## Selecting drives, directories and files



Call the file manager

Use the arrow keys or the soft keys to move the highlight to the desired position on the screen:



Moves the highlight from the left to the right window, and vice versa



¥

Moves the highlight up and down within a window



 Moves the highlight one page up or down within a window

#### Step 1: Select drive

Move the highlight to the desired drive in the left window ►



▶ To select a drive, press the SELECT soft key, or



Press the ENT key

#### Step 2: Select a directory

Move the highlight to the desired directory in the left-hand window-the right-hand window automatically shows all files stored in the highlighted directory

#### Step 3: Select a file



- Press the SELECT TYPE soft key
- Press the soft key for the desired file type, or
- ▶ To display all files, press the SHOW ALL soft key or
- Move the highlight to the desired file in the right window



- Press the SELECT soft key, or
- Press the ENT key

The TNC opens the selected file in the operating mode from which you called the file manager

3.4 Working with the file manager

## Creating a new directory

Move the highlight in the left window to the directory in which you want to create a subdirectory

NEW (enter the new directory name)



3

Press the ENT key

#### **DIRECTORY \CREATE NEW ?**



Press the YES soft key to confirm, or



Abort with the NO soft key.

## Creating a new file

Select the directory in which you wish to create the new file.



- ▶ **NEW** Enter the new file name with the file extension, and confirm with ENT, or
- Open a dialog to create a new file, NEW Enter the new file name with the file extension, and confirm with ENT.

## Copying a single file

Move the highlight to the file you wish to copy



Press the COPY soft key to select the copy function. The TNC opens a pop-up window



Enter the name of the target file and confirm your entry with the ENT key or OK soft key: the TNC copies the file to the active directory or to the selected target directory. The original file is retained, or



Press the Target Directory soft key to call a popup window in which you select the target directory by pressing the ENT key or the OK soft key: the TNC copies the file to the selected directory. The original file is retained.



When the copying process has been started with ENT or the OK soft key, the TNC displays a pop-up window with a progress indicator.

3

## Copying files into another directory

- Select a screen layout with two equally sized windows
- ▶ To display directories in both windows, press the PATH soft key
- In the right window
- Move the highlight to the directory into which you wish to copy the files, and display the files in this directory with the ENT key

In the left window

 Select the directory containing the files that you wish to copy and press ENT to display them



- Call the file tagging functions
- Move the highlight to the file you want to copy and tag it. You can tag several files in this way, if desired



• Copy the tagged files into the target directory

Additional tagging functions: See "Tagging files", page 117. If you have tagged files in both the left and right windows, the TNC copies from the directory in which the highlight is located.

#### **Overwriting files**

If you copy files into a directory in which other files are stored under the same name, the TNC will ask whether the files in the target directory should be overwritten:

- To overwrite all files ("Existing files" check box selected), press the OK soft key, or
- Press the CANCEL soft key if no file is to be overwritten

If you wish to overwrite a protected file, you need to select the "Protected files" check box or cancel the copying process.

3.4 Working with the file manager

## **Copying a table**

3

#### Importing lines to a table

If you are copying a table into an existing table, you can overwrite individual lines with the REPLACE FIELDS soft key. Prerequisites:

- The target table must already exist
- The file to be copied must only contain the lines you want to replace
- Both tables must have the same file extension



The **REPLACE FIELDS** function is used to overwrite lines in the target table. To avoid losing data, create a backup copy of the original table.

#### Example

With a tool presetter you have measured the length and radius of ten new tools. The tool presetter then generates the TOOL\_Import.T tool table with 10 lines (for the 10 tools).

- Copy this table from the external data medium to any directory
- Copy the externally created table to the existing table using the TNC file management. The TNC asks if you wish to overwrite the existing TOOL.T tool table:
- If you press the YES soft key, the TNC will completely overwrite the current TOOL.T tool table. After the copying process the new TOOL.T table consists of 10 lines.
- Or press the REPLACE FIELDS soft key for the TNC to overwrite the 10 lines in the TOOL.T file. The data of the other lines is not changed.

#### Extracting lines from a table

You can select one or more lines in a table and save them in a separate table.

- Open the table from which you want to copy lines
- Use the arrow keys to select the first line to be copied
- Press the MORE FUNCTIONS soft key
- Press the TAG soft key
- Select additional lines, if required
- Press the SAVE AS soft key
- Enter a name for the table in which the selected lines are to be saved

## **Copying a directory**

- Move the highlight in the right window onto the directory you want to copy
- Press the COPY soft key: the TNC opens the window for selecting the target directory
- Select the target directory and confirm with ENT or the OK soft key: The TNC copies the selected directory and all its subdirectories to the selected target directory

## Choosing one of the last files selected



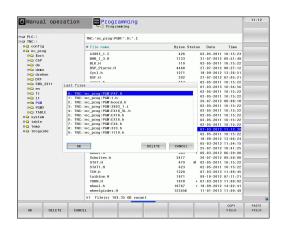
- Call the file manager
- FILES
- Display the last 10 files selected: Press the LAST FILES soft key

Use the arrow keys to move the highlight to the file you wish to select:

- Moves the highlight up and down within a window
- ► To select the file, press the OK soft key, or
- ENT

ок

Press the ENT key



3.4 Working with the file manager

## **Deleting a file**

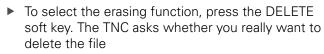


3

#### Caution: Data may be lost!

Once you delete files they cannot be restored!

Move the highlight to the file you want to delete



- ▶ To confirm the deletion, press the OK soft key, or
- ▶ To cancel deletion, press the CANCEL soft key

## **Deleting a directory**



#### Caution: Data may be lost!

Once you delete files they cannot be restored!

Move the highlight to the directory you want to delete



- To select the erasing function, press the DELETE soft key. The TNC inquires whether you really intend to delete the directory and all its subdirectories and files
- ▶ To confirm the deletion, press the OK soft key, or
- ▶ To cancel deletion, press the CANCEL soft key

## **Tagging files**

Tagging function	Soft key
Tag a single file	TAG FILE
Tag all files in the directory	TAG ALL FILES
Untag a single file	UNTAG FILE
Untag all files	UNTAG ALL FILES
Copy all tagged files	COPY TAG LAST→LAST

Some functions, such as copying or erasing files, can not only be used for individual files, but also for several files at once. To tag several files, proceed as follows:

Move the highlight to the first file

TAG
TAG FILE
Î
Î
TAG FILE
COPY TAG
END
DELETE

- To display the marking functions, press the TAG soft key.
- Tag a file by pressing the TAG FILE soft key.
- Move the highlight to the next file you wish to tag: Only works via soft keys. Do not use the arrow keys!
- To tag further files, press the TAG FILES soft key, etc.
- To copy the tagged files, press the COPY TAG soft key, or
- Delete the tagged files by pressing the END soft key to end the tagging functions, and then the DELETE soft key to delete the tagged files

3.4 Working with the file manager

## **Renaming a file**

Move the highlight to the file you wish to rename



- Select the renaming function
- Enter the new file name; the file type cannot be changed
- ▶ To rename: Press the OK soft key or the ENT key

## Sorting files

Select the folder in which you wish to sort the files



- Select the SORT soft key
- Select the soft key with the corresponding display criterion

## **Additional functions**

#### Protecting a file / Canceling file protection

Move the highlight to the file you want to protect

	MORE FUNCTIONS
1	UNPROTECT

5

- To select the additional functions, press the MORE FUNCTIONS soft key
- To activate file protection, press the PROTECT soft key. The file now has status P
- To cancel file protection, press the UNPROTECT soft key

#### Selecting the editor

 Move the highlight in the right window onto the file you want to open



EDITOR

 To select the additional functions, press the MORE FUNCTIONS soft key

To select the additional functions, press the MORE

- To select the editor with which to open the selected file, press the SELECT EDITOR soft key
- Mark the desired editor
- Press the OK soft key to open the file

#### Connecting/removing a USB device

Move the highlight to the left window



- FUNCTIONS soft keyShift the soft-key row
- Search for a USB device
- In order to remove the USB device, move the highlight to the USB device



Remove the USB device

For more information: See "USB devices on the TNC", page 128.

3.4 Working with the file manager

## Additional tools for management of external file types

The additional tools enable you to display or edit various externally created file types on the TNC.

Description
page 120
page 121
page 121
page 122
page 123
page 124



3

If you transfer files from a PC to the control by means of TNCremoNT, you must have entered the file name extension pdf, xls, zip, bmp gif, jpg and png in the list of the file types for binary transmission (menu item **Extras >Configuration >Mode** in TNCremoNT).

#### **Displaying PDF files**

To open PDF files directly on the TNC, proceed as follows:



ENT

- ► Call the file manager
- Select the directory in which the PDF file is saved
- Move the highlight to the PDF file
- Press ENT: The TNC opens the PDF file in its own application using the **PDF viewer** additional tool

With the key combination ALT+TAB you can always return to the TNC user interface while leaving the PDF file open. Alternatively, you can also click the corresponding symbol in the taskbar to switch back to the TNC interface.

If you position the mouse pointer over a button, a brief tooltip explaining the function of this button will be displayed. More information on how to use the **PDF viewer** is provided under **Help**.

To exit the **PDF viewer**, proceed as follows:

- Use the mouse to select the File menu item
- Select the menu item Close: The TNC returns to the file manager



TNC 640 | User's Manual HEIDENHAIN Conversational Programming | 5/2013

## Working with the file manager 3.4

## Displaying and editing Excel files

Proceed as follows to open and edit Excel files with the extension **xls** or **csv** directly on the TNC:



- Select the directory in which the Excel file is saved
- Move the highlight to the Excel file
- ENT

PGM MGT

> Press ENT: The TNC opens the Excel file in its own application using the **Gnumeric** additional tool

With the key combination ALT+TAB you can always return to the TNC user interface while leaving the Excel file open. Alternatively, you can also click the corresponding symbol in the taskbar to switch back to the TNC interface.

If you position the mouse pointer over a button, a brief tooltip explaining the function of this button will be displayed. More information on how to use the **Gnumeric** function is provided under **Help**.

To exit **Gnumeric**, proceed as follows:

- Use the mouse to select the File menu item
- Select the menu item Quit: The TNC returns to the file manager

#### **Displaying Internet files**

To open Internet files with the extension **htm** or **html** directly on the TNC, proceed as follows:



ENT

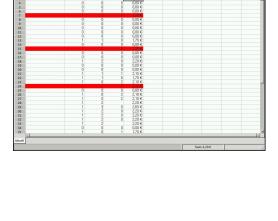
- Call the file manager
- Select the directory in which the Internet file is saved
- Move the highlight to the Internet file
- Press ENT: The TNC opens the Internet file in its own application using the Mozilla Firefox additional tool

With the key combination ALT+TAB you can always return to the TNC user interface while leaving the PDF file open. Alternatively, you can also click the corresponding symbol in the taskbar to switch back to the TNC interface.

If you position the mouse pointer over a button, a brief tooltip explaining the function of this button will be displayed. More information on how to use **Mozilla Firefox** is provided under **Help**.

To exit **Mozilla Firefox**, proceed as follows:

- Use the mouse to select the File menu item
- Select the menu item Quit: The TNC returns to the file manager





3.4 Working with the file manager

#### Working with ZIP archives

To open ZIP archives with the extension **zip** directly on the TNC, proceed as follows:



ENT

3

- Call the file manager
- Select the directory in which the archive file is saved
- Move the highlight to the archive file
- Press ENT: The TNC opens the archive file in its own application using the Xarchiver additional tool

With the key combination ALT+TAB you can always return to the TNC user interface while leaving the archive file open. Alternatively, you can also click the corresponding symbol in the taskbar to switch back to the TNC interface.

If you position the mouse pointer over a button, a brief tooltip explaining the function of this button will be displayed. More information on how to use the **Xarchiver** function is provided under **Help**.



Please note that the TNC does not carry out any binary-to-ASCII conversion or vice versa when compressing or decompressing NC programs and NC tables. When such files are transferred to TNC controls using other software versions, the TNC may not be able to read them.

To exit **Xarchiver**, proceed as follows:

- Use the mouse to select the Archive menu item
- Select the menu item Quit: The TNC returns to the file manager

×			FKPROG.2	ZIP -			r 0.5.2				
Archive Agtion Help											
9 🕒 i 🔶 🕯	• 🖷 🗐	👌 🤫 i 🛽	1								
ecation:						1					
Archive tree	Files	ame	Permissions	Version	OS 0	Original	Compressed	Method	Date	Time	
		flex2.h	-64-8	2.0	fat 2	103	324	defX	10-Mar-97	07:05	
		FK-SL-KOMBLH	-04-2	2.0	fat 2	268	744	defX	16-May-01	13:50	
		femus.c	-14-2	2.0	fat 2	643	1012	detK	6-Apr-99	16:31	
		fict.h	-66-80-	2.0	fat 6	505869	94167	defX	5-Mar-99	10:55	
		6.h	-rw-a	2.0	fat 5	59265	83261	defX	5-Mar-99	10:41	
		FKS.H	-111-11-	2.0	tat 6	155	309	defX	16-May-01	13:50	
		FK4.H	-6-10-	2.0	Sat 5	148	394	defX	16-May-01	13:50	
		FK3.H	-199-2	2.0	fat 4	149	241	defX	16-May-01	13:50	
		FK1.H	-64-40-	2.0	fat 3	148	189	detX	18-Sep-03	13:39	
		farresa.h	-64-30-	2.0	fat 2	66	169	defX	16-May-01	13:50	
		country.h	-14-2	2.0	tat 5	609	252	defX	16-May-01	13:50	
		bsplk1.h	-6-10-	2.0	fat 3	183	239	defX	16-May-01	13:50	
		bri.h	-06-2	2.0	fat 5	38	261	defX	27-Apr-01	10:36	
		appricth	-111-11	2.0	tat 6	501	325	defX	13-Jun-97	13.06	
		appr2.h	-68-20-	2.0	fat é	500	327	defX	30-Jul-99	08:49	
		ANKER.H	-14-2	2.0	fat 5	680	310	defX	16-May-01	13:50	
		ANKER2 H	-08-1	2.0	ter 1	253	601	d+fX	16-May-01	1150	

#### Displaying and editing text files

To open and edit text files (ASCII files, e.g. with the extension  $\mathbf{txt}$  or  $\mathbf{ini}$ ), proceed as follows:



ENT

► Call the file manager

- Select the drive and the directory in which the text file is saved
- Move the highlight to the text file
- Press the ENT key: The TNC displays a window for selection of the editor
- Press ENT to select the **Mousepad** application. Alternatively, you can also open the TXT files with the TNC's internal text editor
- The TNC opens the text file in its own application using the **Mousepad** additional tool



If you open an H or I file on an external drive and save it on the TNC drive using **Mousepad**, the programs are not converted automatically to the internal control format. Programs that are saved in this way cannot be run or opened with the TNC editor.

With the key combination ALT+TAB you can always return to the TNC user interface while leaving the text file open. Alternatively, you can also click the corresponding symbol in the taskbar to switch back to the TNC interface.

The shortcuts you are familiar with from Windows, which you can use to edit texts quickly (CTRL+C, CTRL+V,...), are available within Mousepad.

To exit Mousepad, proceed as follows:

- Use the mouse to select the File menu item
- Select the menu item Quit: The TNC returns to the file manager

Textdatei_en.txt	<ul> <li>•</li> </ul>
le Edit Search Options Help	
uracy requirements are becoming increasingly stringent, particularly in the area of 3-axis machining. apple parts are required to be manifestured with precision and reproducible accuracy even over long periods. menticidy is an important component that helps you to really fulfil 11 these complex requirements: couch probe cycle measures the rotary axes on your machine fully automatically, galless of whether they are in the form of tables or spinale heads.	
alibration sphere (such as the KOM from <u>SURMANNE</u> ) is fixed at any position on the machine table, I messared with a resolution that you define. In the cycle definition you specify the areas to be sured for each rotary axis individually kith this version of the software you can also measure misalignment of a rotary axis cipanial head or table.	
: head asses the rotary axis must be measured twice, each time with a styles of a different length, icr exchanging the stylus between the two measurements, the touch probe must be recalibrated. new calibration cycle 400 automatically calibrates the touch probe using the KBO calibration sphere an HEIRDBARMA starbay in place.	
poor for the measurement of Hirth-coupled gaindle bash has also been improved. Hirth-coupled based can see be performed via an KN tance that the suchine tool builder tegrates in the calibration system. The second seco	

## 3.4 Working with the file manager

#### **Displaying graphic files**

To open graphics files with the extension bmp, gif, jpg or png directly on the TNC, proceed as follows:



ENT

► Call the file manager

- Select the directory in which the graphics file is saved
- Move the highlight to the graphics file
- Press ENT: The TNC opens the graphics file in its own application using the **ristretto** additional tool

With the key combination ALT+TAB you can always return to the TNC user interface while leaving the graphics file open. Alternatively, you can also click the corresponding symbol in the taskbar to switch back to the TNC interface.

More information on how to use the **ristretto** function is provided under **Help**.

To exit **ristretto**, proceed as follows:

- Use the mouse to select the File menu item
- Select the menu item Quit: The TNC returns to the file manager

ristretto - Probe.bmp [4/4] Die Ede View Ge Hein		
(n: 2n: yee (n: 9n: ■ ◆ ◆		<i>ૡ ૡ</i> વ
	a 🔹 🖏	

## Data transfer to/from an external data medium

Before you can transfer data to an external data medium, you must set up the data interface, See "Setting up data interfaces".

Depending on the data transfer software you use, problems can occur occasionally when you transmit data over a serial interface. They can be overcome by repeating the transmission.



Call the file manager

Select the screen layout for data transfer: press the WINDOW soft key. In the left half of the screen the TNC shows all files in the current directory. In the right half of the screen it shows all files saved in the root directory (TNC:\).

Use the arrow keys to highlight the file(s) that you want to transfer:

window, and vice versa

Moves the highlight up and down within a window

Moves the highlight from the right to the left

 
 Manual opszation
 Programming Trogramming
 TL:12

 The::nsc.roog:RMN:\*H:\*I.
 The::\*JE:\*I.

 Pfilm max
 Bytes State

 Programming
 The::\*JE:\*I.

 Pfilm max
 Bytes State

 Bit.A
 1136

 Bit.A
 1136

 Dorse
 State

 Programming
 The::\*JE:\*L

 Pfilm max
 Bytes State

 Dit.A
 1324

 Operation
 State

 State

## 3.4 Working with the file manager

If you wish to copy from the TNC to the external data medium, move the highlight in the left window to the file to be transferred. If you wish to copy from the external data medium to the TNC, move the highlight in the right window to the file to be transferred.



To select another drive or directory: Press the soft key for choosing the directory. The TNC opens a pop-up window. Select the desired directory in the pop-up window by using the arrow keys and the ENT key.



- ► Transfer a single file: Press the COPY soft key, or
- To transfer several files, press the TAG soft key (in the second soft-key row, see "Tagging files", page 111)
- Confirm with the OK or with the ENT key. A status window appears on the TNC, informing about the copying progress, or



 To end data transfer, move the highlight into left window and then press the WINDOW soft key. The standard file manager window is displayed again



To select another directory in the split-screen display, press the SHOW TREE soft key. If you press the SHOW FILES soft key, the TNC shows the content of the selected directory!

## The TNC in a network



To connect the Ethernet card to your network, See "Ethernet interface".

The TNC logs error messages during network operation, See "Ethernet interface".

If the TNC is connected to a network, the directory window displays additional drives (see figure). All the functions described above (selecting a drive, copying files, etc.) also apply to network drives, provided that you have been granted the corresponding rights.

#### Connecting and disconnecting a network drive

- PGM MGT
- To select the program management: Press the PGM MGT key. If necessary, press the WINDOW soft key to set up the screen as it is shown at the upper right
  - NET
- To select the network settings: Press the NETWORK soft key (second soft key row).
- To manage the network drives: Press the DEFINE NETWORK CONNECTN. soft key. In a window the TNC shows the network drives available for access. The soft keys described below are used to define the connection for each drive

Function	Soft key
Establish the network connection. If the connection is active, the TNC marks the <b>Mount</b> column.	Connect
Disconnect the network connection	Unmount
Automatically establish network connection whenever the TNC is switched on. The TNC marks the <b>Auto</b> column if the connection is established automatically	Auto
Set up new network connection	Add
Delete existing network connection	Remove
Copy network connection	Сору
Edit network connection	Machining
Clear status window	Clear

TNC: \	п	NC:\*												-
8-C #suell	*	File name					Byt	es Stat	us	Date	T	ne	8	
BC 20111122TNC620_final	6	tmuell							07-	03-2013	08:	0:46	8	L
BACKE - LIEGL		201111221	INC620_f	final						10-2012				1
8-C Bildverarbeitung		AFC								10-2012				
m 🖬 config.bak		BACKE-LIE Bildveras								01-2013			T	
8- Leitner		config.ba		,						10-2012			1	
n C lost+found		Leitner								01-2012			_	
Bia nc_prog tria system		lost+four	nd							02-2011				
B- table		nc_prog								03-2013			-	
nunt Setun		system							08	01-2013	10.	11-04		
	delinil3 delinil3	0 scatchive 0 scat	User ku19901 ku19901	Password yes yes	Ask for pass		Options							
96 97 ch world: 2			ku10001	Ae2 Ae2		Bern				Geor				Eco
96 96 ch world: 2	delini)		ku19901 ku19901	yes						Çası				Ece
V V ch work: 2 Unweat Unweat  Unweat  Discussion  Disc	delini)		ku19901 ku19901	yes ini						Çavı				Ect

3.4 Working with the file manager

## **USB devices on the TNC**

Backing up data from or loading onto the TNC is especially easy with USB devices. The TNC supports the following USB block devices:

- Floppy disk drives with FAT/VFAT file system
- Memory sticks with the FAT/VFAT file system
- Hard disks with the FAT/VFAT file system
- CD-ROM drives with the Joliet (ISO 9660) file system

The TNC automatically detects these types of USB devices when connected. The TNC does not support USB devices with other file systems (such as NTFS). The TNC displays the **USB: TNC does not support device** error message when such a device is connected.



3

The TNC also displays the **USB: TNC does not support device** error message if you connect a USB hub. In this case, simply acknowledge the message with the CE key.

In theory, you should be able to connect all USB devices with the file systems mentioned above to the TNC. It may happen that a USB device is not identified correctly by the control. In such cases, use another USB device.

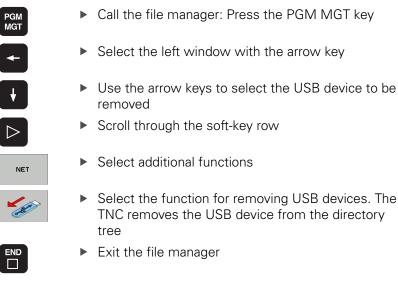
The USB devices appear as separate drives in the directory tree, so you can use the file-management functions described in the earlier chapters correspondingly.



Your machine tool builder can assign permanent names for USB devices. Refer to your machine manual.

3

To remove a USB device, proceed as follows:



In order to re-establish a connection with a USB device that has been removed, press the following soft key:



+

¥

Select the function for reconnection of USB devices

# 

## Programming: Programming aids

4.1 Adding comments

## 4.1 Adding comments

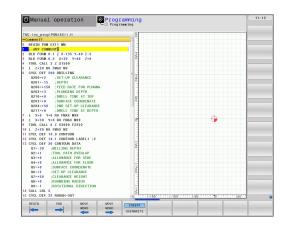
## Application

You can add comments to a part program to explain program steps or make general notes.



If the TNC cannot show the entire comment on the screen, the >> sign is displayed. The last character in a comment block must not have any tilde (~).

There are three possibilities for adding comments.



## Entering comments during programming

- Enter the data for a program block, then press the semicolon key ";" on the alphabetic keyboard—the TNC displays the dialog prompt COMMENT?
- Enter your comment and conclude the block by pressing the END key

#### Inserting comments after program entry

- Select the block to which a comment is to be added
- Select the last word in the block with the right arrow key: A semicolon appears at the end of the block and the TNC displays the dialog prompt COMMENT?
- Enter your comment and conclude the block by pressing the END key

#### Entering a comment in a separate block

- Select the block after which the comment is to be inserted
- Initiate the programming dialog with the semicolon key (;) on the alphabetic keyboard
- Enter your comment and conclude the block by pressing the END key

## Functions for editing of the comment

Function	Soft key
Jump to beginning of comment	BEGIN
Jump to end of comment	
Jump to the beginning of a word. Words must be separated by a space	
Jump to the end of a word. Words must be separated by a space	
Switch between insert mode and overwrite mode	INSERT OVERWRITE

4.2 Display of NC Programs

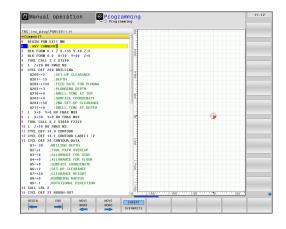
## 4.2 Display of NC Programs

## Syntax highlighting

The TNC displays syntax elements with various colors according to their meaning. Programs are made more legible and clear with color-highlighting.

#### Color highlighting of syntax elements

Use	Color
Standard color	Black
Display of comments	Green
Display of numerical values	Blue
Block number	Purple



## Scrollbar

You can move the screen content with the mouse via the scrollbar on the right edge of the program window. In addition, the size and position of the scrollbar indicates program length and cursor position.

## 4.3 Structuring programs

## **Definition and applications**

This TNC function enables you to comment part programs in structuring blocks. Structuring blocks are short texts with up to 37 characters and are used as comments or headlines for the subsequent program lines.

With the aid of appropriate structuring blocks, you can organize long and complex programs in a clear and comprehensible manner.

This function is particularly convenient if you want to change the program later. Structuring blocks can be inserted into the part program at any point. They can also be displayed in a separate window, and edited or added to, as desired.

The inserted structure items are managed by the TNC in a separate file (extension: .SEC.DEP). This speeds navigation in the program structure window.

# Displaying the program structure window / Changing the active window

PROGRAM
+
SECTS

\_\_\_\_

- To display the program structure window, select the screen display PROGRAM+SECTS
- To change the active window, press the "Change window" soft key

# Inserting a structuring block in the (left) program window

- Select the block after which the structuring block is to be inserted
- INSERT SECTION
- Press the INSERT SECTION soft key or the \* key on the ASCII keyboard
- Enter the structuring text with the alphabetic keyboard
- If necessary, change the structure depth with the soft key

## Selecting blocks in the program structure window

If you are scrolling through the program structure window block by block, the TNC at the same time automatically moves the corresponding NC blocks in the program window. This way you can quickly skip large program sections.

Manual operation Served	gramming gramming	
Control (1997)     Control	<ul> <li>Beckfulle for the ME</li> <li>Beckfulle for the ME</li> <li>Parameter definition</li> <li>Beckfulle for the ME</li> </ul>	
0212-40 _DECREMENT 0213-40 _INK OF BREAKS 0205-40 _HKN.P.LUNGTHO DEPTH 0210-40 _HKN.P.LUNGTHO DEPTH 0210-40 _FKL TIME AF DEPTH 0208-580 _RETRACTION FEED RATE 10 L X-50 Y-50 R0 FMAX SELECT	700	INSERT LAST NC. BLOCK

4.4 Calculator

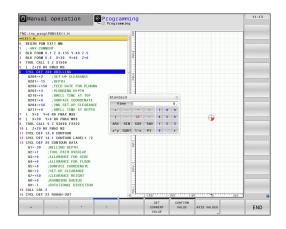
## 4.4 Calculator

## Operation

The TNC features an integrated calculator with the basic mathematical functions.

- ▶ Use the CALC key to show and hide the on-line calculator
- Selecting the calculator: The calculator is operated with short commands via soft key or through the alphabetic keyboard.

Mathematical function	Command (key)				
Addition	+				
Subtraction	_				
Multiplication	*				
Division	/				
Calculations in parentheses	()				
Arc cosine	ARC				
Sine	SIN				
Cosine	COS				
Tangent	TAN				
Powers of values	Х^Ү				
Square root	SQRT				
Inversion	1/x				
pi (3.14159265359)	PI				
Add value to buffer memory	M+				
Save the value to buffer memory	MS				
Recall from buffer memory	MR				
Delete buffer memory contents	MC				
Natural logarithm	LN				
Logarithm	LOG				
Exponential function	e^x				
Check the algebraic sign	SGN				
Form the absolute value	ABS				
Truncate decimal places	INT				
Truncate integers	FRAC				
Modulus operator	MOD				
Select view	View				
Delete value	CE				
Unit of measure	MM or INCH				
Display mode for angle values	DEG (degree) or RAD (radian measure)				
Display mode of the numerical value	DEC (decimal) or HEX (hexadecimal)				



4

#### Transferring the calculated value into the program

- Use the arrow keys to select the word into which the calculated value is to be transferred
- Superimpose the on-line calculator by pressing the CALC key and perform the desired calculation
- Press the actual-position-capture key or the APPLY VALUE soft key for the TNC to transfer the calculated value into the active input box and to close the calculator.



You can also transfer values from a program into the calculator. When you press the FETCH VALUE soft key the TNC transfers the value from the active input field to the calculator.

#### Adjusting the position of the calculator

Press the ADDITIONAL FUNCTIONS soft key to get to the settings for shifting the calculator:

Function		Soft key
Move calcu	ulator in the direction of the arrow	1
Adjust the	increment for movement	STEP SLOW FAST
Position the	e calculator in the center	- <del> </del> -
	You can also shift the calculator wit on your keyboard. If you have conne	,

you can also position the calculator with this.

4.5 **Programming graphics** 

## 4.5 **Programming graphics**

# Generating / not generating graphics during programming

While you are writing the part program, you can have the TNC generate a 2-D pencil-trace graphic of the programmed contour.

To switch the screen layout to displaying program blocks to the left and graphics to the right, press the SPLIT SCREEN key and PROGRAM + GRAPHICS soft key



4

Set the AUTO DRAW soft key to ON. While you are entering the program lines, the TNC generates each path contour you program in the graphics window in the right screen half

If you do not wish to have the TNC generate graphics during programming, set the AUTO DRAW soft key to OFF.

Even when AUTO DRAW ON is active, graphics are not generated for program section repeats.

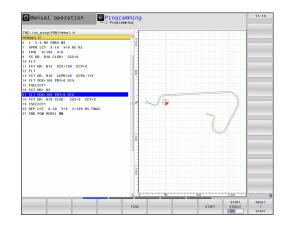
## Generating a graphic for an existing program

Use the arrow keys to select the block up to which you want the graphic to be generated, or press GOTO and enter the desired block number

To generate graphics, press the RESET + START soft key

#### Additional functions:

Function	Soft key
Generate a complete graphic	RESET + START
Generate programming graphic blockwise	START SINGLE
Generate a complete graphic or complete it after RESET + START	START
Stop the programming graphics. This soft key only appears while the TNC is generating the interactive graphics	STOP



RESET + START

## **Block number display ON/OFF**



- ► Shift the soft-key row: see figure
- Show block numbers: Set the SHOW OMIT BLOCK NR. soft key to SHOW
- Hide block numbers: Set the SHOW OMIT BLOCK NR. soft key to OMIT

## **Erasing the graphic**



- ► Shift the soft-key row: see figure
- CLEAR GRAPHICS
- ► Erase graphic: Press CLEAR GRAPHICS soft key

## Showing grid lines



- ► Shift the soft-key row: see figure
- Show grid lines: Press the "SHOW GRID LINES" soft key

4.5 **Programming graphics** 

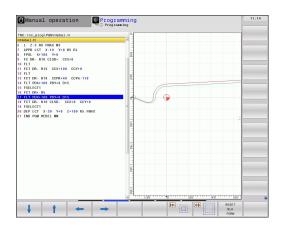
## Magnification or reduction of details

You can select the graphics display by selecting a detail with the frame overlay. You can now magnify or reduce the selected detail.

 Select the soft-key row for detail magnification/reduction (second row, see figure)

#### The following functions are available:

Function	Soft key
Show and move the frame overlay. Press and hold the desired soft key to move the frame	← <b>↑</b>
overlay	↓ →
Shrink the frame overlay – Press soft key for shrinking	
Enlarge the frame overlay – Press soft key	
Confirm the selected area with	



WINDOW DETAIL

4

 Confirm the selected area with the WINDOW DETAIL soft key

The RESET WORKPIECE BLANK soft key is used to restore the original section.



If you have connected a mouse you can draw a frame overlay with the left mouse button for the area to be magnified. You can also use the mouse to magnify or shrink the graphics.

140

## 4.6 Error messages

## **Display of errors**

The TNC generates error messages when it detects problems such as:

- Incorrect data input
- Logical errors in the program
- Contour elements that are impossible to machine
- Incorrect use of touch probes

When an error occurs, it is displayed in red type in the header. Long and multi-line error messages are displayed in abbreviated form. If an error occurs in the background mode, the word "Error" is displayed in red type. Complete information on all pending errors is shown in the error window.

If a rare "processor check error" should occur, the TNC automatically opens the error window. You cannot remove such an error. Shut down the system and restart the TNC.

The error message is displayed in the header until it is cleared or replaced by a higher-priority error.

An error message that contains a program block number was caused by an error in the indicated block or in the preceding block.

## Open the error window



 Press the ERR key. The TNC opens the error window and displays all accumulated error messages.

## Closing the error window



ERR

- Press the END soft key—or
- Press the ERR key. The TNC closes the error window.

4.6 Error messages

#### **Detailed error messages**

The TNC displays possible causes of the error and suggestions for solving the problem:

- Open the error window
  - MORE INFO
- Information on the error cause and corrective action: Position the highlight on the error message and press the MORE INFO soft key. The TNC opens a window with information on the error cause and corrective action
- Exit Info: Press the MORE INFO soft key again

Prog	ram run '	ruii s	Test	run					11:14
Number	Type Text		LO FK pr	ogramming: 1	[llegal posit	ioning bloc	k		
402-0009	FK progr	amming: Ill	legal positio	ning block				1	
								_	
			10	_	_	DELETE	1		
MORE	INTERNAL	LOG	MORE		CHANGE				

## **INTERNAL INFO soft key**

The INTERNAL INFO soft key supplies information on the error message. This information is only required if servicing is needed.

Open the error window.

INTERNAL INFO

- Detailed information about the error message: Position the highlight on the error message and press the INTERNAL INFO soft key. The TNC opens a window with internal information about the error
- To exit Details, press the INTERNAL INFO soft key again

## **Clearing errors**

#### Clearing errors outside of the error window



 Clear the error/message in the header: Press the CE key



In some operating modes (such as the Editing mode), the CE button cannot be used to clear the error, since the button is reserved for other functions.

#### Clearing more than one error

Open the error window



- Clear individual errors: Position the highlight on the error message and press the DELETE soft key
- Clear all errors: Press the DELETE ALL soft key



If the cause of the error has not been removed, the error message cannot be deleted. In this case, the error message remains in the window.

## **Error log**

The TNC stores errors and important events (e.g. system startup) in an error log. The capacity of the error log is limited. If the log is full, the TNC uses a second file. If this is also full, the first error log is deleted and written to again, and so on. To view the error history, switch between CURRENT FILE and PREVIOUS FILE.

• Open the error window.



- Press the LOG FILES soft key.
- Open the error log file: Press the ERROR LOG soft key.
- If you need the previous log file: Press the PREVIOUS FILE soft key.
- If you need the current log file: Press the CURRENT FILE soft key.

The oldest entry is at the beginning of the error log file, and the most recent entry is at the end.

4.6 Error messages

## **Keystroke** log

The TNC stores keystrokes and important events (e.g. system startup) in a keystroke log. The capacity of the keystroke log is limited. If the keystroke log is full, the control switches to a second keystroke log. If this second file becomes full, the first keystroke log is cleared and written to again, and so on. To view the keystroke history, switch between CURRENT FILE and PREVIOUS FILE.

LOG FILES
KEYSTROKE LOG
PREVIOUS FILE

- Press the LOG FILES soft key
- Open the keystroke log file: Press the KEYSTROKE LOG FILE soft key
- If you need the previous log file: Press the PREVIOUS FILE soft key
- If you need the current log file: Press the CURRENT FILE soft key

The TNC saves each key pressed during operation in a keystroke log. The oldest entry is at the beginning, and the most recent entry is at the end of the file.

### Overview of the buttons and soft keys for viewing the log files

Function	Soft key/Keys
Go to beginning of log file	BEGIN
Go to end of log file	
Current log file	CURRENT
Previous log file	PREVIOUS FILE
Up/down one line	<b>↑</b>
Return to main menu	·····

# **Informational texts**

After a faulty operation, such as pressing a key without function or entering a value outside of the valid range, the TNC displays a (green) text in the header, informing you that the operation was not correct. The TNC clears this informational text upon the next valid input.

# Saving service files

If necessary, you can save the "Current status of the TNC," and make it available to a service technician for evaluation. A group of service files is saved (error and keystroke log files, as well as other files that contain information about the current status of the machine and the machining).

If you repeat the "Save service files" function with the same file name, the previously saved group of service data files is overwritten. To avoid this, use another file name when you repeat the function.

### Saving service files

• Open the error window.



- Press the LOG FILES soft key.
- Press the SAVE SERVICE FILES soft key: The TNC opens a pop-up window in which you can enter a name for the service file.
- Save the service files: Press the OK soft key.

4

# Programming: Programming aids

4.6 Error messages

# Calling the TNCguide help system

You can call the TNC's help system via soft key. Immediately the help system shows you the same error explanation that you receive by pressing the HELP soft key.



4

If your machine manufacturer also provides a help system, the TNC shows an additional MACHINE MANUFACTURER soft key with which you can call this separate help system. There you will find further, more detailed information on the error message concerned.



- ► Call the help for HEIDENHAIN error messages
- Call the help for HEIDENHAIN error messages, if available

# 4.7 TNCguide context-sensitive help system

# Application



Before you can use the TNCguide, you need to download the help files from the HEIDENHAIN home page See "Downloading current help files".

The **TNCguide** context-sensitive help system includes the user documentation in HTML format. The TNCguide is called with the HELP key, and the TNC often immediately displays the information specific to the condition from which the help was called (context-sensitive call). Even if you are editing an NC block and press the HELP key, you are usually brought to the exact place in the documentation that describes the corresponding function.



The TNC always tries to start the TNCguide in the language that you have selected as the conversational language on your TNC. If the files with this language are not yet available on your TNC, it automatically opens the English version.

The following user documentation is available in the TNCguide:

- Conversational Programming User's Manual (BHBKlartext.chm)
- DIN/ISO User's Manual (BHBIso.chm)
- User's Manual for Cycle Programming (BHBtchprobe.chm)
- List of All Error Messages (errors.chm)

In addition, the **main.chm** "book" file is available, with the contents of all existing .chm files.



As an option, your machine tool builder can embed machine-specific documentation in the **TNCguide**. These documents then appear as a separate book in the **main.chm** file.

FNCguide				
inhalt lindex Soches	Handbetrieb and Enrichten J 30-Techystem verwenden (So	fteme-Option Tout	probe functione)	
Wilkonmen				
EHB Klarské Dialog	Übersicht			
P Tastenübersicht	In der Betriebsert Manzeller Betrieb stehen ihnen folgende Tastsystem-Zyklen zur Verfügung:			
D Gundlegendes				
Erste Schritte mit der TNC 628	Funktion	Sottory	Selte	
EinKhung	Wirksame Länge kallarieren	an	Kellsteren der wirksemen Länze	
Programmieren Grundlagen, Datei-Verwaltung		+.**		
Programmieren Programmierhillen	Widsamen Radius kalibrieren	[an a]	Wirksamen Radius kalkrieren und Tastsystem-Miterversatz	
D Programmieren Werkzeuge		•	suspected	
Programmieren: Kontaren programmieren		Contractor of the local division of the loca		
Programmieves: Unterprogramme and Programmed Wec	Grunddreitung über eine Gerade ermitteln	107 41 101	Grundstrehung ermitteln	
Programmieren Q.Pasameter		1 <u></u>		
Programmieren Zusatz-Funktionen	Bezugspunkt Setzen in einer wählbaren	(average)	Recupsourid-Setzen in einer beliebinen Achse	
Programmieren Sonderlanktionen	Adhse	P00		
Programmieren: Mehrachsbearbeitung V Handbesteh und Einsichten		Laurenter		
<ul> <li>Handbetieb and Einichten</li> <li>Pinnchalms Zasschalms</li> </ul>	Edve als Bezugspunkt setzen		Eole als Bezugspunkt	
P Dirschalten, Aasschalten P Verfahren der Maschinenachsen		a land		
<ul> <li>Venamen der Maschinessonsen</li> <li>Soindeldrekzahl 5. Vorschub F and Zasabfanktion M</li> </ul>	Kreismittelpunkt als Bezugspunkt setzen	DOCUMENTS OF	Kreisnittelpunkt als Bezugspunkt	
<ul> <li>P. Spreadwitten S, vorunue F and residentiation M</li> <li>Becaussivally Server alone 3D Taxturgers</li> </ul>		60 66		
✓ 3D Tastaster vervenden (Sofware Option Tauch pro.)		Long Street		
<ul> <li>30 Isospice vervence consume option roughpic</li> </ul>	Verwaltung der Tastsystemdaten	TANKLUE	siehe BHB Zyklen	
Tautoster-Zólas wählen				
Messagere aus den Tagtasten-Zahlen in eine Nally				
Messwerte aus den Tastastem Zaklen in die Prese				
5 10-Taxitaxistem kalibrieren (Software-Option Touch pro	<ul> <li>Bei Ausführung der Tastsysten Zyl</li> </ul>	len sürfen kein	re Zyklen zur Koordineten-Unirednnung (Zyklus 7 NULLPUNKT, 2 d 26 MASSFAKTOR und Zyklus 19 BEARBEITUNGSEBENE) with	41.5
Workstück Schieflage mit 1D-Tastastem kompensiere	Shedetoria, zyozi to unenow	D, 29405 HUH	a solveyou with the share to be wrect to wrote before the	54511
P. Bequesternito Sergere mit 1D. Tastrovstern (Software-Oct.)				
Bearbeitungsebene schwenken (Software Option I)	Walters Internationan aur Tastaut	an Tabala first	en Sie in Benutzer-Handbach Zwierprogrammienung	
Positionieren mit Handeingabe				
Programm-Test and Programmlauf				
MOD-Funktionee				
Tabelles and Übersichten				
Übersichtstabellen Zyklen und Mitfunktionen				
DHD Zyklen				
EHEDIN/SO				
F NC-Fehlesseldungen				
ZURÜCK VORWARTS SEITE	SEITE VERZEICHN, FEN	TER .		
			NCGUIDE TNCGUIDE	
I			ERLASSEN BEENDEN	

# Programming: Programming aids

# 4.7 TNCguide context-sensitive help system

# Working with the TNCguide

### Calling the TNCguide

4

There are several ways to start the TNCguide:

- Press the HELP key if the TNC is not already showing an error message
- Click the help symbol at the lower right of the screen beforehand, then click the appropriate soft keys
- Use the file manager to open a help file (.chm file). The TNC can open any .chm file, even if it is not saved on the TNC's hard disk

If one or more error messages are waiting for your attention, the TNC shows the help directly associated with the error messages. To start the **TNCguide**, you first have to acknowledge all error messages.

When the help system is called on the programming station, the TNC starts the internally defined standard browser (usually the Internet Explorer), or otherwise a browser adapted by HEIDENHAIN.

For many soft keys there is a context-sensitive call through which you can go directly to the description of the soft key's function. This functionality requires using a mouse. Proceed as follows:

- Select the soft-key row containing the desired soft key
- Click with the mouse on the help symbol that the TNC displays just above the soft-key row: The mouse pointer turns into a question mark
- Move the question mark to the soft key for which you want an explanation, and click: The TNC opens the TNCguide. If no specific part of the help is assigned to the selected soft key, the TNC opens the book file **main.chm**, in which you can use the search function or the navigation to find the desired explanation manually

Even if you are editing an NC block, context-sensitive help is available:

- Select any NC block
- Use the arrow keys to move the cursor to the block
- Press the HELP key: The TNC starts the help system and shows a description for the active function (does not apply to miscellaneous functions or cycles that were integrated by your machine tool builder)

<ul> <li>Terration Control Control</li></ul>	Serfware-Option Touch probe Kanciliane)	Software-Option Touch	Handbetrieb and Enrichten J 30-Techystem verwenden (So	nhalt lidex Sothen
<ul> <li>Instruments</li> <li< td=""><td></td><td></td><td>Observation</td><td></td></li<></ul>			Observation	
<ul> <li>Configure 1. Second Seco</li></ul>				
<ul> <li>Particle State St</li></ul>	In der Betriebsert Merseller Betrieb stehen ihnen folgende Testsystem-Zyklen zur Verfügung:			
<ul> <li>J. Linker</li> <li>J.</li></ul>				
<ul> <li>Processor solution (as the transmission of tr</li></ul>				
<ul> <li>P. Harris Throughand P. S. S.</li></ul>			the charge can be an	
<ul> <li>Process minunge</li> <li>Pro</li></ul>		10000		
<ul> <li>P. Access resonance strands registrations of the second strands of the seco</li></ul>		10. T	Wrksenen Radius kalibrieren	
<ul> <li>Province intervieweigen ein Proveeting ein Province intervieweigen eine Province Province</li></ul>	. and a control			
<ul> <li>Present of Process</li> <li>Present of Process</li> <li>Present of Process</li> <li>Present Manufacture (Process Manufacture)</li></ul>	Constitution and take	. Income	On existence (her size Garate archite).	
<ul> <li>Province standardization</li> <li>Province standardization</li></ul>		100		Programmieren O.Pasameter
Portuge Service S	Lawrence of the second s			Programmieren Zasatz-Funktionen
Version (Second Second Sec	wranne Sabugapurol-Satzen in einer ladiebigen Achne	ALCONOM .	Bezugspunkt-Setzen in einer wählbaren Artrait	Programmieren Sonderlanktionen
I Construction     I Constr	4	4		Programmieren Melvachsbearbeitung
Person Pers	Terrerer Ecke als Becumpunkt	(WENTON)	Edia als Decugaqueixt setzen	
	+ 300	- 3		
Benefitter et et Statuer     De Deservationer de Contraction de Contraction     Deservationer de Contraction     Deservationer de Contraction     Deservationer de Contraction     Deservationer de Contractioner de Contraction     Deservationer de Contractioner de Contraction     Deservationer de Contractioner d	Martin Andreas and American American		North Martin and Area	
Beneral encoder diversifier failed for the first set of the s		APR #1101	Anestrisepuno, es dezagipuno secon	
Name         Name of the second s	Defection of the second s	1.00.111		
Known can be been a four an behavior a four and a second sec	verserer sinte GHG Zyklern	THELLS	Verweitung der Testsystendeten	Obevsicht
Reserve a dar hangen sjon in de lander en bunde Bonanstantes en binner sjon in de lander en bunde Bonanstantes en binner sjon en bunder en bunde Bonanstantes en binner sjon en bunder en bunde Bonanstantes en bunder en bund	London d	-		
E) De lange statuer de bane de ba				
Descriptions of the Description of Description of Descriptions of Descrip	Alen sürfen keine Zyklen zur Koordineten-Unrechnung (Zyklus 7 NULLPUNKT, Zyklus 1	yklen stärfen kein	Gel Ausführung der Tastsystem-Zyl	
Paragrammentaria nel banance Albana de California de	NG, Zykka 11 und 26 MASSEAKTOR und Zyklus 18 BEÄPBEITUNGSEBENE) aktiv sein.	NG, Zykka 11unc	SPIEGELUNG, Zyklus 10 DREHUN	
Eustration of the set of the				
Policie information intercepte     Policie information     Policie     Policie information     Policie     Po				
) Program Relativity presentation Micro Delationes 1 Table and Callmandation 2 Delationes Johan and Microlationes 1 Delationes 1 Delation	Ren-Tabele finden Sie im benutzer-Handbuch zyklenprogrammerung.	sten laste ins	Weitere Informationen zur Lastsyst	
Vicio Antonee     Vicio A				
Userstmaanden Zuite und Minutanee     Userstmaanden Zuite und Minutanee     Userstmann     Userstmann     Userstmann				
b tHtR2/den b telt DNISO				Tabelles and übersichten
BHEDINISO				Disersichtstabellen Zuklen und MirFunktionen
				b BHB Zyklen
<ul> <li>Sc. Februardulague</li> </ul>				
				b NC-Feblemeldungen
ZURÜCK VORMARTS SEITE SEITE VERZEICHN. FENSTER TNOGUIDE TNOGUIDE	ISTER TNOGUTOF TNOGUTOF	NSTER T	SEITE VERZEICHN. FEN	ZURÜCK VORWARTS SEITE
				+

### Navigating in the TNCguide

It's easiest to use the mouse to navigate in the TNCguide. A table of contents appears on the left side of the screen. By clicking the rightward pointing triangle you open subordinate sections, and by clicking the respective entry you open the individual pages. It is operated in the same manner as the Windows Explorer.

Linked text positions (cross references) are shown underlined and in blue. Clicking the link opens the associated page.

Of course you can also operate the TNCguide through keys and soft keys. The following table contains an overview of the corresponding key functions.

Function	Soft key
<ul> <li>If the table of contents at left is active:</li> <li>Select the entry above it or below it</li> </ul>	<b>f</b>
If the text window at right is active: Move the page downward or upward if texts or graphics are not shown completely	Ŧ
<ul> <li>If the table of contents at left is active:</li> <li>Open up the table of contents If the branch is at its end, jump into the window at right</li> </ul>	+
If the text window at right is active: No function	
<ul> <li>If the table of contents at left is active:</li> <li>Close the table of contents</li> </ul>	-
If the text window at right is active: No function	
If the table of contents at left is active: Use the cursor key to show the selected page	ENT
If the text window at right is active: If the cursor is on a link, jump to the linked page	
If the table of contents at left is active: Switch the tab between the display of the table of contents, display of the subject index, and the full-text search function and switching to the screen half at right	
If the text window at right is active: Jump back to the window at left	
<ul> <li>If the table of contents at left is active:</li> <li>Select the entry above it or below it</li> </ul>	<b>∎</b> ↑
<ul> <li>If the text window at right is active: Jump to next link</li> </ul>	Ē
Select the page last shown	ВАСК
Page forward if you have used the "select page last shown" function	
Move up by one page	
Move down by one page	

# Programming: Programming aids

# 4.7 TNCguide context-sensitive help system

Function	Soft key
Display or hide table of contents	
Switch between full-screen display and reduced display. With the reduced display you can see some of the rest of the TNC window	
The focus is switched internally to the TNC application so that you can operate the control when the TNCguide is open. If the full screen is active, the TNC reduces the window size automatically before the change of focus	TNCGUIDE QUIT
Exiting TNCguide	TNCGUIDE EXIT

### Subject index

The most important subjects in the Manual are listed in the subject index (**Index** tab). You can select them directly by mouse or with the cursor keys.

The left side is active.

È

4

- Select the **Index** tab
- Activate the Keyword input field
- Enter the word for the desired subject and the TNC synchronizes the index and creates a list in which you can find the subject more easily, or
- Use the arrow key to highlight the desired keyword
- Use the ENT key to call the information on the selected keyword



You can enter the search word only with a keyboard connected via USB.

NCguide				
nhalt Index Suches	Handbell (id) and Emilden J 32-Tectystem ververden (Certiverv Epton Touty prote Emclane)			
Schlaselwort 3.0 compensation				
Face Milling	Übersicht			
Normieter Vektor	in der Betriebsert Menzeller Betrieb stehen ihnen folgende Testsystem-Zylden zur Verlägung:			
Petabecal Milling				
Werkzeug Famen	Funktion Wrissene Lieze kallzieren		Seite Gellarieren der wirksemen Lienze	
Workzoug-Orienterang	wexsenie Lange vandheren		AND REAL OR ANY ARTICLE OF	
1D-Tantovninere		+ **		
	Wirksamen Radius kalibrieren	[en. x] ¥	Wrisamen Radius kalitrieren und Tastsystemh	01en-ersez
schultendes		• •	wagialahan	
Anti-off-editories extres wit exchange has Taskes over Messah				
Aetustvanchub	Grunddrehung über eine Gerade ermitteln		Irundshehung ermitteln	
Antastive te in Nullcanio Tabelle scheelben		1		
Antastwete in Preset Tabelle schreiben	Bezugspunkt-Setzen in einer wählbaren	[mentant]	Rezupspunkt-Setzen in einer beliebigen Achne	
Antastzyklen	Adase			
Detriebuart Margell		Laurenter and		
Eir den Automatik-Bestieb	Edia als Bezugspunkt setzen		icke ein Bezugspunkt	
Anwenderparameter		+ 3+++		
∇ alternative	Kreismittelpunkt als Bezugspunkt setzen	(ACALINE )	reismittelpunkt als Dezugspunkt	
Kir 3D-Taxteysterse		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
maschinesspezifische		In the local division of the local divisiono		
Arbeitssaum Überwachung	Verweitung der Tastnystendaten	TATE-LEEK S	lehe SHB Zyklen	
Ausdrahum				
Assochalten				
Automatische Werkzeug-Vermessung				
Automatischer Programmslart	Bei Ausführung der Tastsysten-Zyl	den släfen keine 2	ykien zur Koordineten-Untrechnung (Zyklus 71	AJLUPUNKT, Zyklus B
Bahnbewegangen	- SPIEGELOWG, ZYNUS TU UHEHUN	G, Zykius Trund 2	6MASSEAKTOR and 2yklus 19 BEARBEITUN	SEBERAE) 800/ 5601
Polaskaordinaten				
Gerade	Weitere Informationen zur Tastavst		Sie in Berutzer-Handbuch Zwienprogrammier	
Kreisbahn mit tangetialem Anschluß	· weisre insmatchen zur raksyst	Eth ladele inden	sie in benuzer nandouch zykenprogrammer	292
Knisbahn um Pol C.C.				
Übersicht				
💎 rechtwinklige Koordinaten				
Gerade				
Kreinbahn mit lentgelegtern Radius				
Kreisbahn mit tangentialem Anschluss				
Kreisbahn um Kreismittelpunkt CC				
Obersicht.				
Eahnfunktionen				
9 Guedagee				
Kreise und Kreisbilgen				
These definitions and the second seco				
ZURÜCK VORUNRTS SEITE SEITE VERZEICHN. FENSTER				
ZUROUR VURMERTS SEITE	BEITE VENZEICHN. FEN	TNO	GUIDE TNOGUIDE	
		0	LOSSEN BEENDEN	

### **Full-text search**

In the  $\ensuremath{\textit{Find}}$  tab you can search the entire TNC guide for a specific word.

The left side is active.



- Select the Find tab
- Activate the **Find:** input field
- Enter the desired word and confirm with the ENT key: The TNC lists all sources containing the word
- Use the arrow key to highlight the desired source
- Press the ENT key to go to the selected source

You can enter the search word only with a keyboard connected via USB.

The full-text search only works for single words.

If you activate the **Search only in titles** function (by mouse or by using the cursor and the space key), the TNC searches only through headings and ignores the body text.

# Programming: Programming aids

4.7 TNCguide context-sensitive help system

# Downloading current help files

You'll find the help files for your TNC software on the HEIDENHAIN homepage **www.heidenhain.de** under:

- Documentation and information
- User Documentation
- ► TNCguide

4

- Select the desired language
- TNC Controls
- Series, e.g. TNC 600 Series
- Desired NC software number, e.g. TNC 640 (34059x-01)
- Select the desired language version from the TNCguide online help table
- Download the ZIP file and unzip it
- Move the unzipped CHM files to the TNC in the TNC:\tncguide \en directory or into the respective language subdirectory (see also the following table)



If you want to use TNCremoNT to transfer the CHM files to the TNC, then in the **Extras** >**Configuration** >**Mode** >**Transfer in binary format** menu item you have to enter the extension **.CHM**.

Language	TNC directory
German	TNC:\tncguide\de
English	TNC:\tncguide\en
Czech	TNC:\tncguide\cs
French	TNC:\tncguide\fr
Italian	TNC:\tncguide\it
Spanish	TNC:\tncguide\es
Portuguese	TNC:\tncguide\pt
Swedish	TNC:\tncguide\sv
Danish	TNC:\tncguide\da
Finnish	TNC:\tncguide\fi
Dutch	TNC:\tncguide\nl
Polish	TNC:\tncguide\pl
Hungarian	TNC:\tncguide\hu
Russian	TNC:\tncguide\ru
Chinese (simplified)	TNC:\tncguide\zh
Chinese (traditional)	TNC:\tncguide\zh-tw
Slovenian (software option)	TNC:\tncguide\sl
Norwegian	TNC:\tncguide\no
Slovak	TNC:\tncguide\sk
Latvian	TNC:\tncguide\lv
Korean	TNC:\tncguide\kr
Estonian	TNC:\tncguide\et
Turkish	TNC:\tncguide\tr
Romanian	TNC:\tncguide\ro
Lithuanian	TNC:\tncguide\lt

Programming: Tools

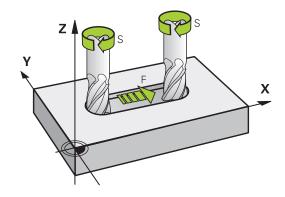
# 5.1 Entering tool-related data

# 5.1 Entering tool-related data

# Feed rate F

5

The feed rate  $\mathbf{F}$  is the speed (in millimeters per minute or inches per minute) at which the tool center point moves. The maximum feed rates can be different for the individual axes and are set in machine parameters.



#### Input

You can enter the feed rate in the **TOOL CALL** block and in every positioning block (See "Creating the program blocks with the path function keys", page 196). In millimeter-programs you enter the feed rate in mm/min, and in inch-programs, for reasons of resolution, in 1/10 inch/min.

### **Rapid traverse**

If you wish to program rapid traverse, enter **F MAX.** To enter **FMAX,** press the ENT key or the FMAX soft key when the dialog question **FEED RATE F = ?** appears on the control's screen.

To move your machine at rapid traverse, you can also program the corresponding numerical value, e.g. **F30000**. Unlike **FMAX**, this rapid traverse remains in effect not only in the individual block but in all blocks until you program a new feed rate.

### **Duration of effect**

A feed rate entered as a numerical value remains in effect until a block with a different feed rate is reached. **FMAX** is only effective in the block in which it is programmed. After the block with **FMAX** is executed, the feed rate will return to the last feed rate entered as a numerical value.

### Changing during program run

You can adjust the feed rate during program run with the feed-rate override knob  $\ensuremath{\mathsf{F}}$ 

# Spindle speed S

The spindle speed S is entered in revolutions per minute (rpm) in a **TOOL CALL** block. Instead, you can also define the cutting speed Vc in m/min.

### Programmed change

TOOL CALL

In the part program, you can change the spindle speed in a **TOOL CALL** block by entering the spindle speed only:

- Program a tool call: Press the TOOL CALL key
- Ignore the dialog question for Tool number ? with the NO ENT key
- Ignore the dialog question for Working spindle axis X/Y/Z ? with the NO ENT key
- Enter the new spindle speed for the dialog question Spindle speed S= ?, and confirm with END, or switch via the VC soft key to entry of the cutting speed.

#### Changing during program run

You can adjust the spindle speed during program run with the spindle speed override knob S.

5.2 Tool data

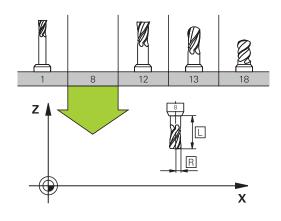
5

# 5.2 Tool data

# **Requirements for tool compensation**

You usually program the coordinates of path contours as they are dimensioned in the workpiece drawing. To allow the TNC to calculate the tool center path—i.e. the tool compensation—you must also enter the length and radius of each tool you are using.

Tool data can be entered either directly in the part program with **TOOL DEF** or separately in a tool table. In a tool table, you can also enter additional data for the specific tool. The TNC will consider all the data entered for the tool when executing the part program.



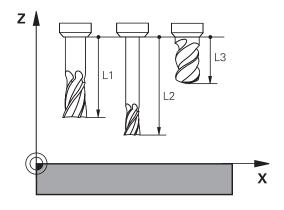
### Tool number, tool name

Each tool is identified by a number between 0 and 32767. If you are working with tool tables, you can also enter a tool name for each tool. Tool names can have up to 32 characters.

The tool number 0 is automatically defined as the zero tool with the length L=0 and the radius R=0. In tool tables, tool T0 should also be defined with L=0 and R=0.

# **Tool length L**

You should always enter the tool length L as an absolute value based on the tool reference point. The entire tool length is essential for the TNC in order to perform numerous functions involving multi-axis machining.



# **Tool radius R**

You can enter the tool radius R directly.

# Delta values for lengths and radii

Delta values are offsets in the length and radius of a tool.

A positive delta value describes a tool oversize (**DL**, **DR**, **DR2**>0). If you are programming the machining data with an allowance, enter the oversize value in the **TOOL CALL** block of the part program.

A negative delta value describes a tool undersize (**DL**, **DR**, **DR2**<0). An undersize is entered in the tool table for wear.

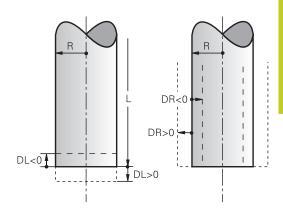
Delta values are usually entered as numerical values. In a **TOOL CALL** block, you can also assign the values to Q parameters.

Input range: You can enter a delta value with up to  $\pm$  99.999 mm.



Delta values from the tool table influence the graphical representation of the **tool**. The representation of the **workpiece** remains the same in the simulation.

Delta values from the **TOOL CALL** block change the represented size of the **workpiece** during the simulation. The simulated **tool size** remains the same.



# Entering tool data into the program

The number, length and radius of a specific tool is defined in the **TOOL DEF** block of the part program.

Select the tool definition: Press the TOOL DEF key



- Tool number: Each tool is uniquely identified by its tool number
- ► **Tool length**: Compensation value for the tool length
- ► **Tool radius**: Compensation value for the tool radius



In the programming dialog, you can transfer the value for tool length and tool radius directly into the input line by pressing the desired axis soft key.

#### Example

4 TOOL DEF 5 L+10 R+5

5.2 Tool data

5

# Enter tool data into the table

You can define and store up to 9999 tools and their tool data in a tool table. Also see the Editing Functions later in this Chapter. In order to be able to assign various compensation data to a tool (indexing tool number), insert a line and extend the tool number by a dot and a number from 1 to 9 (e.g. **T 5.2**).

You must use tool tables if

- you wish to use indexed tools such as stepped drills with more than one length compensation value
- your machine tool has an automatic tool changer
- you want to rough-mill the contour with Cycle 22, (see "User's Manual for Cycle Programming, ROUGH-OUT")
- you want to work with Cycles 251 to 254 (see "User's Manual for Cycle Programming," Cycles 251 to 254)



If you create or manage further tool tables, the file name has to start with a letter.

You can select either list view or form view for tables via the "Screen layout" key.

When you open the tool table you can also change its layout.

5

Abbr.	Inputs	Dialog
Т	Number by which the tool is called in the program (e.g. 5, indexed: 5.2)	-
NAME	Name by which the tool is called in the program (no more than 32 characters, all capitals, no spaces)	Tool name?
L	Compensation value for tool length L	Tool length?
R	Compensation value for the tool radius R	Tool radius R?
R2	Tool radius R2 for toroid cutters (only for 3-D radius compensation or graphical representation of a machining operation with spherical or toroid cutters)	Tool radius R2?
DL	Delta value for tool length L	Tool length oversize?
DR	Delta value for tool radius R	Tool radius oversize?
DR2	Delta value for tool radius R2	Tool radius oversize R2?
LCUTS	Tooth length of the tool for Cycle 22	Tooth length in the tool axis?
ANGLE	Maximum plunge angle of the tool for reciprocating plunge-cut in Cycles 22 and 208	Maximum plunge angle?
TL	Set tool lock (TL: for Tool Locked	Tool locked? Yes = ENT / No = NO ENT
RT	Number of a replacement tool, if available ( <b>RT</b> : for Replacement Tool; see also <b>TIME2</b> ).	Replacement tool?
TIME1	Maximum tool life in minutes. This function can vary depending on the individual machine tool. Your machine manual provides more information	Maximum tool age?
TIME2	Maximum tool life in minutes during <b>TOOL CALL</b> : If the current tool life reaches or exceeds this value, the TNC changes the tool during the next <b>TOOL CALL</b> (see also <b>CUR_TIME</b> ).	Maximum tool age for TOOL CALL?
CUR_TIME	Current age of the tool in minutes: The TNC automatically counts the current tool life ( <b>CUR_TIME</b> : for <b>CUR</b> rent <b>TIME</b> . A starting value can be entered for used tools	Current tool age?

### Tool table: Standard tool data

# 5.2 Tool data

5

Abbr.	Inputs	Dialog
TYPE	Tool type: Press the SELECT TYPE (3rd soft-key row); the TNC superimposes a window where you can select the type of tool you want. You can assign tool types to specify the display filter settings such that only the selected type is visible in the table	Tool type?
DOC	Comment on tool (up to 32 characters)	Tool comment?
PLC	Information on this tool that is to be sent to the PLC	PLC status?
РТҮР	Tool type for evaluation in the pocket table	Tool type for pocket table?
NMAX	Limit the spindle speed for this tool. The programmed value is monitored (error message) as well as an increase in the shaft speed via the potentiometer. Function inactive: Enter	Maximum speed [rpm]?
	Input range: 0 to +999999, if function not active: enter -	
LIFTOFF	Definition of whether the TNC should retract the tool in the direction of the positive tool axis at an NC stop in order to avoid leaving dwell marks on the contour. If <b>Y</b> is defined, the TNC retracts the tool from the contour, provided that this function was activated in the NC program with M148 See "Automatically retract tool from the contour at an NC stop: M148", page 365.	Retract tool Y/N ?
TP_NO	Reference to the number of the touch probe in the touch- probe table	Number of the touch probe
T_ANGLE	Point angle of the tool. Is used by the Centering cycle (Cycle 240) in order to calculate the centering depth from the diameter entry	Point angle?
AFC	Control setting for the adaptive feed control AFC that you have defined in the <b>NAME</b> column of the AFC.TAB table. Apply the feedback-control strategy with the ASSIGN AFC CONTROL SETTING soft key (3rd soft-key row) <b>Input range</b> : 10 characters max.	Feedback-control strategy?
LAST_USE	Date and time that the tool was last inserted via <b>TOOL CALL</b>	LAST_USE
	<b>Input range</b> : Max. 16 characters, format specified internally: Date = yyyy.mm.dd, time = hh.mm	
ACC	Activate or deactivate active chatter control for the respective tool (page 389).	ACC status 1=active/0=inactive
	respective tool (page 560).	I-active/0-mactive

### Tool table: Tool data required for automatic tool measurement

$\Rightarrow$
---------------

For a description of the cycles for automatic tool measurement, see the User's Manual for Cycle Programming.

Abbr.	Inputs	Dialog
CUT	Number of teeth (20 teeth maximum)	Number of teeth?
LTOL	Permissible deviation from tool length L for wear detection. If the entered value is exceeded, the TNC locks the tool (status <b>L</b> ). Input range: 0 to 0.9999 mm	Wear tolerance: length?
RTOL	Permissible deviation from tool radius R for wear detection. If the entered value is exceeded, the TNC locks the tool (status <b>L</b> ). Input range: 0 to 0.9999 mm	Wear tolerance: radius?
R2TOL	Permissible deviation from tool radius R2 for wear detection. If the entered value is exceeded, the TNC locks the tool (status <b>L</b> ). Input range: 0 to 0.9999 mm	Wear tolerance: Radius 2?
DIRECT.	Cutting direction of the tool for measuring the tool during rotation	Cutting direction (M3 = -)?
R_OFFS	Tool radius measurement: Tool offset between stylus center and tool center. Default setting: No value entered (offset = tool radius)	Tool offset: radius?
L_OFFS	Tool length measurement: Tool offset in addition to <b>offsetToolAxis</b> (114104) between upper surface of stylus and lower surface of tool. Default: 0	Tool offset: length?
LBREAK	Permissible deviation from tool length <b>L</b> for breakage detection. If the entered value is exceeded, the TNC locks the tool (status <b>L</b> ). Input range: 0 to 0.9999 mm	Breakage tolerance: length?
RBREAK	Permissible deviation from tool radius R for breakage detection. If the entered value is exceeded, the TNC locks the tool (status L). Input range: 0 to 0.9999 mm	Breakage tolerance: radius?

5.2 Tool data

### Edit the tool table

The tool table that is active during execution of the part program is designated TOOL.T and must be saved in the **TNC:\table** directory.

Other tool tables that are to be archived or used for test runs are given any other names with the extension T. By default, for Test Run and Programming modes the TNC uses the "simtool.t" table, which is also stored in the "table" directory. In the Test Run mode, press the TOOL TABLE soft key to edit it.

To open the tool table TOOL.T:

Select any machine operating mode



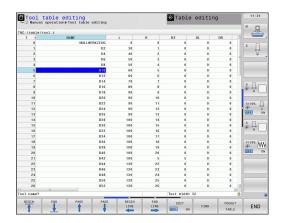
Select the tool table: Press the TOOL TABLE soft key
Set the EDIT soft key to ON

# Displaying only specific tool types (filter setting)

- Press the TABLE FILTER soft key (fourth soft-key row)
- Select the tool type by pressing a soft key: The TNC only shows tools of the type selected
- Cancel filter: Press the previously selected tool type again or select another tool type



The machine tool builder adapts the features of the filter function to the requirements of your machine. Refer to your machine manual.



### Hiding or sorting the tool table columns

You can adapt the layout of the tool table to your needs. Columns that should not be displayed can be hidden:

- Press the SORT/HIDE COLUMNS soft key (fourth soft-key row)
- Select the appropriate column name with the arrow key
- Press the HIDE COLUMN soft key to remove this column from the table layout

You can also modify the sequence of columns in the table:

► You can also modify the sequence of columns in the table with the "Move to" dialog. The entry highlighted in **Available columns** is moved in front of this column

You can use a connected mouse or the TNC keyboard to navigate in the form. Navigation using the TNC keyboard:



 Press the navigation keys to go to the input fields. Use the arrow keys to navigate within an input field. To open pop-down menus, press the GOTO key.



With the Fix number of columns function, you can define how many columns (0 -3) are fixed to the left screen edge. These columns are also displayed if you navigate in the table to the right.

5.2 Tool data

### Opening any other tool table



5

- Select the Programming mode of operation
  - Call the file manager
  - Press the SELECT TYPE soft key to select the file type
  - Show type .T files: Press the SHOW .T soft key
  - Select a file or enter a new file name. Conclude your entry with the ENT key or the SELECT soft key

When you have opened the tool table, you can edit the tool data by moving the cursor to the desired position in the table with the arrow keys or the soft keys. You can overwrite the stored values, or enter new values at any position. The available editing functions are illustrated in the table below.

If the TNC cannot show all positions in the tool table in one screen page, the highlight bar at the top of the table will display the symbol ">>" or "<<".

Editing functions for tool tables	Soft key
Select beginning of table	BEGIN
Select end of table	
Select previous page in table	
Select next page in table	
Find the text or number	FIND
Move to beginning of line	BEGIN LINE
Move to end of line	
Copy highlighted field	COPY FIELD
Insert copied field	PASTE
Add the entered number of lines (tools) at the end of the table	APPEND N LINES
Adding a row with tool number for entering	INSERT
Delete current line (tool)	DELETE
Sort the tools according to the content of a column	SORT
Show all drills in the tool table	DRILL
Show all cutters in the tool table	CUTTER
Show all taps/thread cutters in the tool table	TAP/ THREAD CUTTER
Show all touch probes in the tool table	TOUCH PROBE

5.2 Tool data

### Exiting the tool table

 Call the file manager and select a file of a different type, such as a part program

### Tool table for turning tools

With the management of turning tools, other geometric descriptions are considered than with milling or drilling tools. To be able to execute tool radius compensation, for example, you have to define the tool radius. To support these definitions, the TNC provides a special tool management for turning tools, See "Tool data", page 467.

# Importing tool tables



The machine manufacturer can adapt the IMPORT TABLE function. Refer to your machine manual.

If you export a tool table from an iTNC 530 and import it into a TNC 640, you have to adapt its format and content before you can use the tool table. On the TNC 640, you can adapt the tool table conveniently with the IMPORT TABLE function. The TNC converts the contents of the imported tool table to a format valid for the TNC 640 and saves the changes to the selected file. Follow this procedure:

- Save the tool table of the iTNC 530 to the TNC:\table directory
- Select the Programming mode of operation
- Call the file manager: Press the PGM MGT key
- Move the highlight to the tool table you want to import
- Press the MORE FUNCTIONS soft key
- Select the IMPORT TABLE soft key: The TNC inquires whether you really want to overwrite the selected tool table
- Press the CANCEL soft key if you do not want to overwrite the file, or
- Press the ADAPT TABLE FORMAT soft key to overwrite the file
- Open the converted table and check its contents



The following characters are permitted in the **Name** column of the tool table: "ABCDEFGHIJKLMNOPQRSTUVWXYZ0123456789# \$&-.\_". The TNC changes a comma in the tool name to a period during import.

The TNC overwrites the selected tool table when running the IMPORT TABLE function. The TNC also creates a backup file with the extension **.t.bak**. To avoid losing data, be sure to make a backup copy of your original tool table before importing it!

The procedure for copying tool tables using the TNC file manager is described in the section on file management (See "Copying a table").

When tool tables of the iTNC 530 are imported, the TYPE column is not imported.

5.2 Tool data

# Pocket table for tool changer



The machine tool builder adapts the features of the pocket table to the requirements of your machine. Refer to your machine manual.

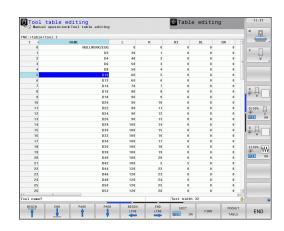
For automatic tool changing you need the a pocket table. You manage the assignment of your tool changer in the pocket table. The pocket table is in the **TNC:\TABLE** directory. The machine tool builder can adapt the name, path and content of the pocket table. You can also select various layouts using soft keys in the **TABLE FILTER** menu.

### Editing a pocket table in a Program Run operating mode



EDIT

- Select the tool table: Press the TOOL TABLE soft key
- Select the pocket table: Press the POCKET TABLE soft key
- Set the EDIT soft key to ON. On your machine this might not be necessary or even possible. Refer to your machine manual



### Selecting a pocket table in the Programming mode of operation



- Call the file manager
- Display the file types: Press the SHOW ALL soft key
- Select a file or enter a new file name. Conclude your entry with the ENT key or the SELECT soft key

Abbr.	Inputs	Dialog
Р	Pocket number of the tool in the tool magazine	-
т	Tool number	Tool number?
RSV	Pocket reservation for box magazines	Pocket reserv.: Yes = ENT / No = NOENT
ST	Special tool ( <b>ST</b> ); If your special tool blocks pockets in front of and behind its actual pocket, these additional pockets need to be locked in column L (status L).	Special tool?
F	The tool is always returned to the same pocket in the tool magazine	Fixed pocket? Yes = ENT / No = NO ENT
L	Locked pocket (see also column ST)	Pocket locked Yes = ENT / No = NO ENT
DOC	Display of the comment to the tool from TOOL.T	-
PLC	Information on this tool pocket that is to be sent to the PLC	PLC status?
P1 P5	Function is defined by the machine tool builder. The machine tool documentation provides further information	Value?
РТҮР	Tool type. Function is defined by the machine tool builder. The machine tool documentation provides further information	Tool type for pocket table?
LOCKED_ABOVE	Box magazine: Lock the pocket above	Lock the pocket above?
LOCKED_BELOW	Box magazine: Lock the pocket below	Lock the pocket below?
LOCKED_LEFT	Box magazine: Lock the pocket at left	Lock the pocket at left?
LOCKED_RIGHT	Box magazine: Lock the pocket at right	Lock the pocket at right?

5.2 Tool data

5

Editing functions for pocket tables	Soft key	
Select beginning of table		
Select end of table		
Select previous page in table		
Select next page in table		
Reset pocket table	RESET POCKET TABLE	
Reset tool number column T	RESET COLUMN T	
Go to beginning of the line	BEGIN LINE	
Go to end of the line		
Simulate a tool change	SIMULATED TOOL CHANGE	
Select a tool from the tool table: The TNC shows the contents of the tool table. Use the arrow keys to select a tool, press OK to transfer it to the pocket table		
Edit the current field	EDIT CURRENT FIELD	
Sort the view	SORT	
The machine manufacturer defines the features, properties and designations of the various display filters. Refer to your machine manual.		

# Call tool data

A TOOL CALL block in the part program is defined with the following data:

- Select the tool call function with the TOOL CALL key
- TOOL CALL
- Tool number: Enter the number or name of the tool. The tool must already be defined in a TOOL DEF block or in the tool table. Press the TOOL NAME soft key to enter the name. The TNC automatically places the tool name in quotation marks. The tool name always refers to the entry in the active tool table TOOL.T. If you wish to call a tool with other compensation values, also enter the index you defined in the tool table after the decimal point. There is a SELECT soft key for calling a window from which you can select a tool defined in the tool table TOOL.T directly without having to enter the number or name.
- Working spindle axis X/Y/Z: Enter the tool axis
- Spindle speed S: Enter the spindle speed in rpm Alternatively, you can define the cutting speed Vc in m/min. Press the VC soft key
- Feed rate F: F [mm/min or 0.1 inch/min] is effective until you program a new feed rate in a positioning or TOOL CALL block
- ► Tool length oversize DL: Enter the delta value for the tool length
- **Tool radius oversize DR**: Enter the delta value for the tool radius
- ► Tool radius oversize DR2: Enter the delta value for the tool radius 2

5.2 Tool data

5

### Example: Tool call

Call tool number 5 in the tool axis Z with a spindle speed of 2500 rpm and a feed rate of 350 mm/min. The tool length is to be programmed with an oversize of 0.2 mm, the tool radius 2 with an oversize of 0.05 mm, and the tool radius with an undersize of 1 mm.

# 20 TOOL CALL 5.2 Z S2500 F350 DL+0.2 DR-1 DR2+0.05

The character **D** preceding **L** and **R** designates delta values.

### Tool preselection with tool tables

If you are working with tool tables, use **TOOL DEF** to preselect the next tool. Simply enter the tool number or a corresponding Q parameter, or type the tool name in quotation marks.

# **Tool change**



The tool change function can vary depending on the individual machine tool. Refer to your machine manual.

### **Tool change position**

The tool change position must be approachable without collision. Use the miscellaneous functions **M91** and **M92** to enter machinebased (rather than workpiece-based) coordinates for the tool change position. If **TOOL CALL 0** is programmed before the first tool call, the TNC moves the tool spindle in the tool axis to a position that is independent of the tool length.

#### Manual tool change

To change the tool manually, stop the spindle and move the tool to the tool change position:

- Move to the tool change position under program control
- Interrupt program run (See "Interrupt machining", page 572)
- Change the tool
- Resume program run (See "Resuming program run after an interruption", page 573)

### Automatic tool change

If your machine tool has automatic tool changing capability, the program run is not interrupted. When the TNC reaches a **TOOL CALL** it replaces the inserted tool by another from the tool magazine.

### Automatic tool change if the tool life expires: M101



The function of **M101** can vary depending on the individual machine tool. Refer to your machine manual.

When the specified tool life has expired, the TNC can automatically insert a replacement tool and continue machining with it. Activate the miscellaneous function **M101** for this. **M101** is reset with **M102.** 

# 5.2 Tool data

5

Enter the respective tool life after which machining is to be continued with a replacement tool in the **TIME2** column of the tool table. In the **CUR\_TIME** column the TNC enters the current tool life. If the current tool life is higher than the value entered in the **TIME2** column, a replacement tool will be inserted at the next possible point in the program no later than one minute after expiration of the tool life. The change is made only after the NC block has been completed.

The TNC performs the automatic tool change at a suitable point in the program. The automatic tool change is not performed:

- During execution of machining cycles
- While radius compensation is active (RR/RL)
- Directly after an approach function **APPR**
- Directly before a departure function **DEP**
- Directly before and after CHF and RND
- During execution of macros
- During execution of a tool change
- Directly after a TOOL CALL or TOOL DEF
- During execution of SL cycles

**Caution: Danger to the workpiece and tool!** Switch off the automatic tool change with **M102** if you are working with special tools (e.g. side mill cutter) because the TNC at first always moves the tool away from the workpiece in tool axis direction.

Depending on the NC program, the machining time can increase as a result of the tool life verification and calculation of the automatic tool change. You can influence this with the optional input element **BT** (block tolerance)

If you enter the **M101** function, the TNC continues the dialog by requesting the **BT**. Here you define the number of NC blocks (1 - 100) by which the automatic tool change may be delayed. The resulting time period by which the tool change is delayed depends on the content of the NC blocks (e.g. feed rate, path). If you do not define **BT**, the TNC uses the value 1 or, if applicable, a default value defined by the machine manufacturer.

The more you increase the value of **BT**, the smaller will be the effect of an extended program duration through **M101**. Please note that this will delay the automatic tool change!

To calculate a suitable initial value for **BT**, use the following formula: **BT = 10 : average machining time of an NC block in seconds**. Round up to the next odd integer. If the calculated result is greater than 100, use the maximum input value of 100.

If you want to reset the current age of a tool (e.g. after changing the indexable inserts), enter the value 0 in the CUR\_TIME column.

The **M101** function is not available for turning tools and in turning mode.

# Prerequisites for NC blocks with surface-normal vectors and 3-D compensation

The active radius  $(\mathbf{R} + \mathbf{DR})$  of the replacement tool must not differ from the radius of the original tool. You can enter the delta values  $(\mathbf{DR})$  either in the tool table or in the **TOOL CALL** block. If there are any deviations, the TNC displays an error message and does not replace the tool. You can suppress this message with the M function **M107**, and reactivate it with **M108**.See also: Threedimensional tool compensation (software option 2), page 447.

5.2 Tool data

# Tool usage test



5

The tool usage test function must be enabled by your machine manufacturer. Refer to your machine manual.

In order to run a tool usage test, the complete plain-language program must have been simulated in the **Test Run** mode.

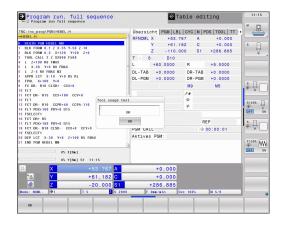
### Applying the tool usage test

Before starting a program in the Program Run mode of operation, you can use the TOOL USAGE and TOOL USAGE TEST soft keys to check whether the tools being used in the selected program are available and have sufficient remaining service life. The TNC then compares the actual service-life values in the tool table with the nominal values from the tool usage file.

After you have pressed the TOOL USAGE TEST soft key, the TNC displays the result of the tool usage test in a pop-up window. To close the pop-up window, press the ENT key.

The TNC saves the tool usage times in a separate file with the extension **pgmname.H.T.DEP**. The generated tool usage file contains the following information:

Column	Meaning	
TOKEN	<ul> <li>TOOL: Tool usage time per TOOL CALL. The entries are listed in chronological order.</li> </ul>	
	TTOTAL: Total usage time of a tool	
	<ul> <li>STOTAL: Call of a subprogram; the entries are listed in chronological order</li> </ul>	
	<ul> <li>TIMETOTAL: The total machining time of the NC program is entered in the WTIME column. In the PATH column the TNC saves the path name of the corresponding NC programs. The TIME column shows the sum of all TIME entries (without rapid traverse). The TNC sets all other columns to 0</li> <li>TOOLFILE: In the PATH column, the TNC saves the path name of the tool table with which you conducted the Test Run. This enables the TNC during the actual tool usage test to detect whether you performed the test run with the TOOL.T</li> </ul>	
TNR	Tool number ( <b>-1</b> : No tool inserted yet)	
IDX	Tool index	
NAME	Tool name from the tool table	
TIME	Tool-usage time in seconds (feed time)	
WTIME	Tool-usage time in seconds (total usage time between tool changes)	



HEIDENHAIN Conversational Programming | 5/2013

178

Column	Meaning
RAD	<b>Tool radius R + Oversize of tool radius</b> <b>DR</b> from the tool table. (in mm)
BLOCK	Block number in which the <b>TOOL CALL</b> block was programmed
PATH	TOKEN = TOOL: Path name of the active main program or subprogram
	TOKEN = STOTAL: Path name of the subprogram
т	Tool number with tool index
OVRMAX	Maximum feed rate override that occurred during machining. During Test Run the TNC enters the value 100 (%)
OVRMIN	Minimum feed rate override that occurred during machining. During Test Run the TNC enters the value –1
NAMEPROG	<ul><li>0: The tool number is programmed</li><li>1: The tool name is programmed</li></ul>

There are two ways to run a tool usage test for a pallet file:

- The highlight in the pallet file is on a pallet entry: The TNC runs the tool usage test for the entire pallet
- The highlight in the pallet file is on a pallet entry: The TNC runs the tool usage test for the entire pallet

# 5.2 Tool data

# Tool management (software option)

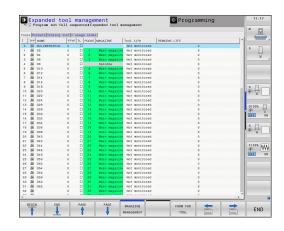


5

Tool management is a machine-dependent function, which can be partly or completely deactivated. The machine tool builder defines the exact range of functions. Refer to your machine manual.

With the tool management, your machine tool builder can provide many functions with regard to tool handling. Examples:

- Easily readable and, if you desired, adaptable representation of the tool data in fillable forms
- Any description of the individual tool data in the new table view
- Mixed representation of data from the tool table and the pocket table
- Fast sorting of all tool data by mouse
- Use of graphic aids, e.g. color coding of tool or magazine status
- Program-specific list of all available tools
- Program-specific usage sequence of all tools
- Copying and pasting of all tool data pertaining to a tool
- Graphic depiction of tool type in the table view and in the detail view for a better overview of the available tool types



## Calling the tool management



TOOL TABLE

 $\triangleright$ 

TOOL

MANAGEMEN'

The tool management call can differ as described below. Refer to your machine manual.

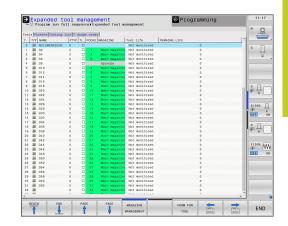
- Select the tool table: Press the TOOL TABLE soft key
- Scroll through the soft-key row
- Select the TOOL MANAGEMENT soft key: The TNC goes into the new table view (see figure at right)

In the new view, the TNC presents all tool information in the following four tabs:

- **Tools**: Tool specific information
- Pockets: Pocket-specific information
- Assembly list: List of all tools in the NC program that is selected in the Program Run mode (only if you have already created a tool usage file, See "Werkzeug-Einsatzprüfung")
- T usage sequence: List of the sequence of all tools that are inserted in the program selected in the Program Run mode (only if you have already made a tool usage file, See "Werkzeug-Einsatzprüfung")

You can edit the tool data only in the form view, which you can activate by pressing the FORM FOR TOOL soft key or the ENT key for the currently highlighted tool.

If you use tool management without a mouse, then you can activate and deactivate functions with the "-/+" check box.



# **Programming: Tools**

5.2 **Tool data** 

## **Operating the tool management**

The tool management can be operated by mouse or with the keys and soft keys:

Editing functions of tool management	Soft key
Select beginning of table	BEGIN
Select end of table	
Select previous page in table	
Select next page in table	PAGE
Call the fillable form view for the tool or magazine pocket highlighted in the table. Alternative function: Press the ENT key	FORM FOR TOOL
Go to the next tab: Tools, Pockets, Tooling list, T usage order	
Search function (Find): Here you can select the column to be searched and the search term via a list or by entering it	FIND
Show programmed-tools column (if <b>Pockets</b> tab is active)	PROG. TOOL DISPLAY HIDE
Define the settings:	COLUMN
<ul> <li>SORT COLUMN active: Click the column header to sort the content of the column</li> </ul>	MOVE
<ul> <li>MOVE COLUMN active: The column can be moved by drag and drop</li> </ul>	
Reset the manually changed settings (moved	RESET

Expande	d tool mana	gement Expanded	tool management	Programming	11:17
Weikzeug-Index	•				
Informationen					
NAME NULLWERK2	reug	т	0	1.11	s 🚽
DOC		TP_NO			T I
Ρ		PTYP	0		
RT 0		TYP	MILL	1	
Basisdaten	Verschle15-Date	n	Zusatz-Daten	Standzeit-Daten	
L +0	₹ DL +0		A LCUTS +0	© TEME1 0	8 A -
R +0	T OR +0		Te ANGLE +60	© TIME2 0	@ 🖶
R2 +0	T 0R2 +0		T-ANGLE +0	G CUR TIME 0	
	₹ ACC F		3 NMAX	X TL F	STOPA
Sonderfunktion AFC	en	×.	PLC-Daten PLC-Bit 0 F PLC-Bit 1 F PLC-Bit 2 F		
LIFTOFF	F		PLC-Bit 3 F		
TT-Daten			PLC-Bit 4 F PLC-Bit 5 F		
L-OFFS +0	T LEBEAK 0		PLC-BIT 5 F		
R-OFFS	T REREAK O		PLC-BIT 7 F		
L LTOL 0	A CUT 0				
T RTOL 0	A DIRECT +				
	. orneor .				
TOOL	TOOL INDEX	INDE			END

Reset the manually changed settings (moved columns) to original condition

RESET SETTINGS

5

In addition, you can perform the following functions by mouse:

- Sorting function. You can sort the data in ascending or descending order (depending on the active setting) by clicking a column of the table head.
- Arrange columns. You can arrange the columns in any sequence you want by clicking a column of the table head and then moving it with the mouse key pressed down. The TNC does not save the current column sequence when you exit the tool management (depending on the active setting).
- Show miscellaneous information in the form view. The TNC displays tool tips when you leave the mouse pointer on an active input field for more than a second and when you have set the EDIT ON/OFF soft key to ON.

If the form view is active, the following functions are available to you:

Editing functions form view	Soft key
Select the tool data of the previous tool	TOOL
Select the tool data of the next tool	TOOL
Select previous tool index (only active if indexing is enabled)	
Select the next tool index (only active if indexing is enabled)	
Discard all changes made since the form was last called ("Undo" function)	DISCARD CHANGES
Insert a line (tool index) (2nd soft-key row)	INSERT LINE
Delete a line (tool index) (2nd soft-key row)	DELETE
Copy the tool data of the selected tool (2nd soft-key row)	COPY DATA RECORD
Insert the copied tool data in the selected tool (2nd soft-key row)	INSERT DATA REC.

5.2 Tool data

5

#### Importing tool data

Using this function you can simply import tool data that you have measured externally on a presetting device, for example. The file to be imported must have the CSV format (Comma Separated Values). The **CSV** file format describes the structure of a text file for exchanging simply structured data. Accordingly, the import file must have the following structure:

- **Row 1**: In the first line you define the column names in which the data defined in the subsequent lines is to be placed. The column names are separated from each other by commas.
- **Other lines**: All the other lines contain the data that you wish to import into the tool table. The order of the data must match the order of the column names in Line 1. The data is separated by commas, decimal numbers are to be defined with a decimal point.

Follow the steps outlined below for importing:

- Copy the tool table to be imported to the hard disk of the TNC in the TNC:\systems\tooltab directory
- Start Extended Tool Management
- Select the IMPORT TOOL soft key in the Tool Management: The TNC shows a pop-up window with the CSV files stored in the TNC:\systems\tooltab directory
- Use the arrow keys or mouse to select the file to be imported and confirm with the ENT key: The TNC shows the content of the CSV file in a pop-up window
- Start import procedure with START soft key



The CSV file to be imported must be stored in the TNC:\system\tooltab directory.

- If you import the tool data of tools whose numbers are in the pocket table, the TNC issues an error message. You can then decide whether you want to skip this data record or insert a new tool. The TNC inserts a new tool into the first empty line of the tool table.
- Make sure that the column designations are specified correctly, See "Werkzeug-Tabelle: Standard Werkzeug-Daten".
- You can import any tool data, the associated data record does not have to contain all the columns (or data) of the tool table.
- The column names can be in any order, the data must be defined in the corresponding order.

### Sample import file:

T,L,R,DL,DR	Line 1 with column names
4,125.995,7.995,0,0	Line 2 with tool data
9,25.06,12.01,0,0	Line 3 with tool data
28,196.981,35,0,0	Line 4 with tool data

## **Exporting tool data**

Using this function you can simply export tool data to read it into the tool database of your CAM system, for example. The TNC stores the exported file in the CSV format (Comma Separated Values). The **CSV** file format describes the structure of a text file for exchanging simply structured data. The export file has the following structure:

- Line 1: In the first line the TNC stores the column names of all the relevant tool data to be defined. The column names are separated from each other by commas.
- **Further lines**: All the other lines contain the data of the tools that you have exported. The order of the data matches the order of the column names in Line 1. The data is separated by commas, the TNC outputs decimal numbers with a decimal point.

Follow the steps outlined below for exporting:

- In the tool management you use the arrow keys or mouse to mark the tool data that you wish to export
- Select the EXPORT TOOL soft key, the TNC shows a pop-up window: specify the name for the CSV file, confirm with the ENT key
- Press the START soft key to start the export process: The TNC shows the status of the delete export process in a pop-up window
- Terminate the export process by pressing the END key or soft key



The TNC always stores the exported CSV file in the **TNC:\system\tooltab** directory.

## Programming: Tools

5.2 Tool data

5

### Deleting marked tool data

Using this function you can simply delete tool data that you no longer need.

Follow the steps outlined below for deleting:

- In the tool management you use the arrow keys or mouse to mark the tool data that you wish to delete
- Select the DELETE MARKED TOOLS soft key and the TNC shows a pop-up window listing the tool data to be deleted
- Press the START soft key to start the delete process: The TNC shows the status of the delete process in a pop-up window
- Terminate the delete process by pressing the END key or soft key



The TNC deletes all the data of all the tools selected. Make sure that you really no longer need the tool data, because there is no Undo function available.

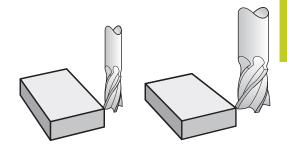
 You cannot delete the tool data of tools still stored in the pocket table. First remove the tool from the magazine.

# 5.3 Tool compensation

## Introduction

The TNC adjusts the spindle path in the spindle axis by the compensation value for the tool length. In the working plane, it compensates the tool radius.

If you are writing the part program directly on the TNC, the tool radius compensation is effective only in the working plane. The TNC accounts for the compensation value in up to five axes including the rotary axes.



## **Tool length compensation**

Length compensation becomes effective automatically as soon as a tool is called. To cancel length compensation, call a tool with the length L=0.

Danger of collision!
If you cancel a positive length compensation with
TOOL CALL 0 the distance between tool and workpiece will be reduced.
After TOOL CALL the path of the tool in the spindle axis, as entered in the part program, is adjusted by the difference between the length of the previous

For tool length compensation, the control takes the delta values from both the **TOOL CALL** block and the tool table into account:

Compensation value =  $L + DL_{TOOL CALL} + DL_{TAB}$  with

tool and that of the new one.

- L: Tool length L from the TOOL DEF block or tool table
- $\textbf{DL}_{\text{TOOL CALL}}$ : Oversize for length DL in the **TOOL CALL 0** block
- **DL**<sub>TAB</sub>: Oversize for length **DL** in the tool table

# Programming: Tools

5.3 Tool compensation

## **Tool radius compensation**

The block for programming a tool movement contains:

- RL or RR for radius compensation
- **RO** if there is no radius compensation

Radius compensation becomes effective as soon as a tool is called and is moved with a straight line block in the working plane with RL or RR.



The TNC automatically cancels radius compensation if you:

- program a straight line block with R0
- depart the contour with the **DEP** function
- program a PGM CALL
- Select a new program with PGM MGT

For radius compensation, the TNC takes the delta values from both the **TOOL CALL** block and the tool table into account:

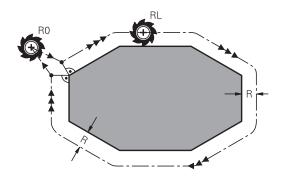
Compensation value =  $\mathbf{R} + \mathbf{D}\mathbf{R}_{\text{TOOL CALL}} + \mathbf{D}\mathbf{R}_{\text{TAB}}$  where

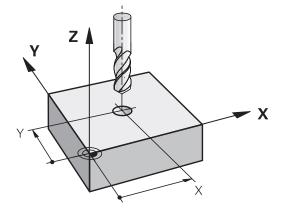
- R: Tool radius R from the TOOL DEF block or tool table
- **DR**<sub>TOOL CALL</sub>: Oversize for radius **DR** in the **TOOL CALL** block
- **DR**<sub>TAB</sub>: Oversize for radius **DR** in the tool table

## Contouring without radius compensation: R0

The tool center moves in the working plane along the programmed path or to the programmed coordinates.

Applications: Drilling and boring, pre-positioning





#### TNC 640 | User's Manual HEIDENHAIN Conversational Programming | 5/2013

5

## Contouring with radius compensation: RR and RL

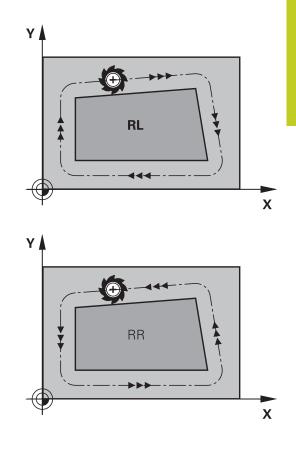
- **RR**: The tool moves to the right of the programmed contour
- **RL**: The tool moves to the left of the programmed contour

The tool center moves along the contour at a distance equal to the radius. "Right" or "left" are to be understood as based on the direction of tool movement along the workpiece contour. See figures.

> Between two program blocks with different radius compensations **RR** and **RL** you must program at least one traversing block in the working plane without radius compensation (that is, with **RO**).

The TNC does not put radius compensation into effect until the end of the block in which it is first programmed.

In the first block in which radius compensation is activated with **RR/RL** or canceled with **R0** the TNC always positions the tool perpendicular to the programmed starting or end position. Position the tool at a sufficient distance from the first or last contour point to prevent the possibility of damaging the contour.



## **Entering radius compensation**

Radius compensation is entered in an  ${\rm L}$  block. Enter the coordinates of the target point and confirm your entry with ENT

## RADIUS COMP.: RL/RR/NO COMP.?

R L R R

ENT

- Select tool movement to the left of the contour: Press the RL soft key, or
- Select tool movement to the right of the contour: Press the RR soft key, or
- Select tool movement without radius compensation or cancel radius compensation: Press the ENT key
- ► Terminate the block: Press the END key

# Programming: Tools

5

## 5.3 Tool compensation

#### **Radius compensation: Machining corners**

Outside corners:

If you program radius compensation, the TNC moves the tool around outside corners on a transitional arc. If necessary, the TNC reduces the feed rate at outside corners to reduce machine stress, for example at very great changes of direction.

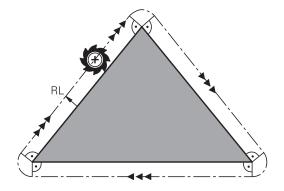
Inside corners:

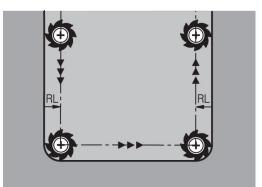
The TNC calculates the intersection of the tool center paths at inside corners under radius compensation. From this point it then starts the next contour element. This prevents damage to the workpiece at the inside corners. The permissible tool radius, therefore, is limited by the geometry of the programmed contour.



## Danger of collision!

To prevent the tool from damaging the contour, be careful not to program the starting or end position for machining inside corners at a corner of the contour.





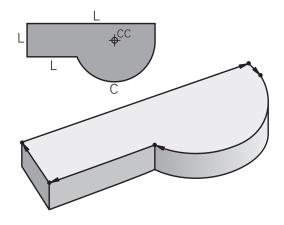


6.1 Tool movements

## 6.1 Tool movements

## **Path functions**

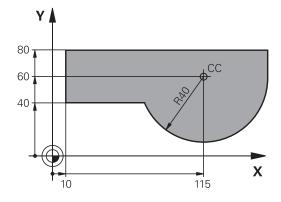
A workpiece contour is usually composed of several contour elements such as straight lines and circular arcs. With the path functions, you can program the tool movements for **straight lines** and **circular arcs**.



## FK free contour programming

If a production drawing is not dimensioned for NC and the dimensions given are not sufficient for creating a part program, you can program the workpiece contour with the FK free contour programming. The TNC calculates the missing data.

With FK programming, you also program tool movements for **straight lines** and **circular arcs**.



## **Miscellaneous functions M**

With the TNC's miscellaneous functions you can affect

- the program run, e.g., a program interruption
- the machine functions, such as switching spindle rotation and coolant supply on and off
- the path behavior of the tool

6

## Subprograms and program section repeats

If a machining sequence occurs several times in a program, you can save time and reduce the chance of programming errors by entering the sequence once and then defining it as a subprogram or program section repeat. If you wish to execute a specific program section only under certain conditions, you also define this machining sequence as a subprogram. In addition, you can have a part program call a separate program for execution.

Programming with subprograms and program section repeats is described in Chapter 7.

## Programming with Q parameters

Instead of programming numerical values in a part program, you enter markers called Q parameters. You assign the values to the Q parameters separately with the Q parameter functions. You can use the Q parameters for programming mathematical functions that control program execution or describe a contour.

In addition, parametric programming enables you to measure with the 3-D touch probe during program run.

Programming with Q parameters is described in Chapter 8.

6.2 Fundamentals of Path Functions

# 6.2 Fundamentals of Path Functions

# Programming tool movements for workpiece machining

You create a part program by programming the path functions for the individual contour elements in sequence. You usually do this by entering **the coordinates of the end points of the contour elements** given in the production drawing. The TNC calculates the actual path of the tool from these coordinates, and from the tool data and radius compensation.

The TNC moves all axes programmed in a single block simultaneously.

## Movement parallel to the machine axes

The program block contains only one coordinate. The TNC thus moves the tool parallel to the programmed axis.

Depending on the individual machine tool, the part program is executed by movement of either the tool or the machine table on which the workpiece is clamped. Nevertheless, you always program path contours as if the tool were moving and the workpiece remaining stationary.

## Example:

6

50 L X+100	
50	Block number
L	Path function "straight line "
X+100	Coordinate of the end point
The tool ret	ains the Y and 7 coordinates and moves to the position

The tool retains the Y and Z coordinates and moves to the position X=100. See figure.

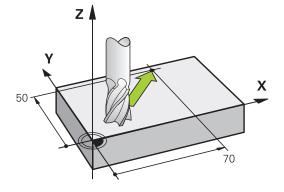
## Movement in the main planes

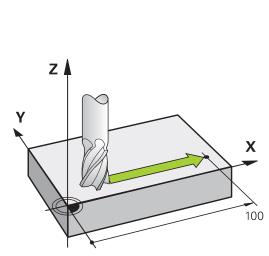
The program block contains two coordinates. The TNC thus moves the tool in the programmed plane.

## Example

## L X+70 Y+50

The tool retains the Z coordinate and moves in the XY plane to the position X=70, Y=50 (see figure).



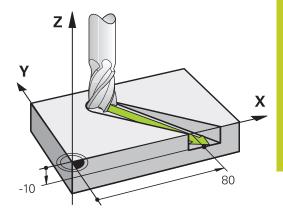


## **Three-dimensional movement**

The program block contains three coordinates. The TNC thus moves the tool in space to the programmed position.

## Example

L X+80 Y+0 Z-10

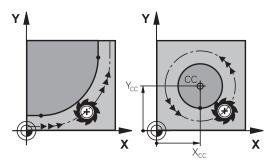


## **Circles and circular arcs**

The TNC moves two axes simultaneously on a circular path relative to the workpiece. You can define a circular movement by entering the circle center CC.

When you program a circle, the control assigns it to one of the main planes. This plane is defined automatically when you set the spindle axis during a TOOL CALL:

Spindle axis	Main plane
Z	<b>XY</b> , also UV, XY, UY
Y	<b>ZX</b> , also WU, ZU, WX
X	<b>YZ</b> , also VW, YW, VZ



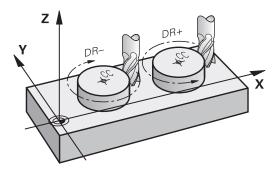
You can program circles that do not lie parallel to a main plane by using the function for tilting the working plane (see User's Manual for Cycles, Cycle 19, WORKING PLANE) or Q parameters (See "Principle and overview of functions").

## Direction of rotation DR for circular movements

When a circular path has no tangential transition to another contour element, enter the direction of rotation as follows:

Clockwise direction of rotation: DR-

Counterclockwise direction of rotation: DR+



6.2 Fundamentals of Path Functions

## **Radius compensation**

The radius compensation must be in the block in which you move to the first contour element. You cannot activate radius compensation in a circle block. Activate it beforehand in a straightline block (See "Path contours - Cartesian coordinates", page 206) or approach block (APPR block, See " Approaching and departing a contour", page 198).

#### **Pre-position**

6

Danger of collision!

Before running a part program, always pre-position the tool to prevent the possibility of damaging it or the workpiece.

## Creating the program blocks with the path function keys

The gray path function keys initiate the plain-language dialog. The TNC asks you successively for all the necessary information and inserts the program block into the part program.

Manual operation Service Progra	amming		11:09
HD::Ins_progIP@VI4.h           PBLockInscore. function #7           PBLOCKING #1           PBLOCKING #1           PBLOCKING #1		•	B3
M M94 M103 M118	M120	M128	M140

## Example – programming a straight line

- L
- Initiate the programming dialog, e.g. for a straight line

## **COORDINATES ?**



Enter the coordinates of the straight-line end point, e.g. –20 in X

## **COORDINATES ?**



Enter the coordinates of the straight-line end point, e.g. 30 in Y, and confirm with the ENT key

## Radius comp.: RL/RR/no comp.?



 Select the radius compensation (here, press the R0 soft key—the tool moves without compensation)

Enter 100 (feed rate e.g. 100 mm/min), and

## Feed rate F=? / F MAX = ENT

ENT	
F MAX	
F AUTO	

inches, enter 100 for a feed rate of 10 ipm. Or,
Move at rapid traverse: Press the FMAX soft key, or

confirm your entry with ENT. For programming in

Traverse with the feed rate defined in the TOOL CALL block: Press the F AUTO soft key.

## MISCELLANEOUS FUNCTION M ?



Enter 3 (miscellaneous function e.g. M3), and terminate the dialog with ENT.

## The part program now contains the following line:

L X-20 Y+30 R0 FMAX M3

6

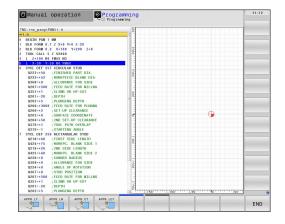
6.3 Approaching and departing a contour

# 6.3 Approaching and departing a contour

# Overview: Types of paths for contour approach and departure

The functions for contour approach APPR and departure DEP are activated with the APPR/DEP key. You can then select the desired path function with the corresponding soft key:

Function	Approach	Departure
Straight line with tangential connection	APPR LT	DEP LT
Straight line perpendicular to a contour point	APPR LN	DEP LN
Circular arc with tangential connection	APPR CT	DEP CT
Circular arc with tangential connection to the contour. Approach and departure to an auxiliary point	APPR LCT	



## Approaching and departing a helix

outside the contour on a tangentially

connecting line

The tool approaches and departs a helix on its extension by moving in a circular arc that connects tangentially to the contour. You program helical approach and departure with the APPR CT and DEP CT functions.

## Important positions for approach and departure

Starting point P<sub>s</sub>

You program this position directly before the APPR block.  ${\sf P}_{\sf S}$  lies outside the contour and is approached without radius compensation (R0).

Auxiliary point P<sub>H</sub>

Some of the paths for approach and departure go through an auxiliary point P<sub>H</sub> that the TNC calculates from your input in the APPR or DEP block. The TNC moves from the current position to the auxiliary point P<sub>H</sub> at the feed rate last programmed. If you have programmed **FMAX** (positioning at rapid traverse) in the last positioning block before the approach function, the TNC also approaches the auxiliary point P<sub>H</sub> at rapid traverse.

 First contour point P<sub>A</sub> and last contour point P<sub>E</sub> You program the first contour point P<sub>A</sub> in the APPR block. The last contour point P<sub>E</sub> can be programmed with any path function. If the APPR block also contains a Z axis coordinate, the TNC will first move the tool to P<sub>H</sub> in the working plane, and then move it to the entered depth in the tool axis.

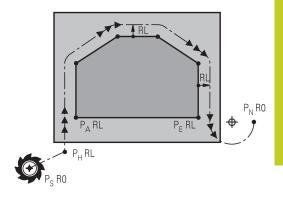
#### End point PN

The position  $\mathsf{P}_{\mathsf{N}}$  lies outside of the contour and results from your input in the DEP block. If the DEP block also contains a Z axis coordinate, the TNC will first move the tool to  $\mathsf{P}_{\mathsf{N}}$  in the working plane, and then move it to the entered depth in the tool axis.

Abbreviation	Meaning
APPR	Approach
DEP	Departure
L	Line
С	Circle
Т	Tangential (smooth connection)
Ν	Normal (perpendicular)

The TNC does not check whether the programmed contour will be damaged when moving from the actual position to the auxiliary point  $P_{H}$ . Use the test graphics to check.

With the APPR LT, APPR LN and APPR CT functions, the TNC moves the tool from the actual position to the auxiliary point  $P_H$  at the feed rate/rapid traverse that was last programmed. With the APPR LCT function, the TNC moves to the auxiliary point  $P_H$  at the feed rate programmed with the APPR block. If no feed rate is programmed before the approach block, the TNC generates an error message.



6.3 Approaching and departing a contour

## **Polar coordinates**

6

You can also program the contour points for the following approach/ departure functions over polar coordinates:

- APPR LT becomes APPR PLT
- APPR LN becomes APPR PLN
- APPR CT becomes APPR PCT
- APPR LCT becomes APPR PLCT
- DEP LCT becomes DEP PLCT

Select by soft key an approach or departure function, then press the orange P key.

## **Radius compensation**

The tool radius compensation is programmed together with the first contour point PA in the APPR block. The DEP blocks automatically discard the tool radius compensation.

Contour approach without radius compensation: If you program the APPR block with R0, the TNC will calculate the tool path for a tool radius of 0 mm and a radius compensation RR! The radius compensation is necessary to set the direction of contour approach and departure in the APPR/DEP LN and APPR/DEP CT functions. In addition, you must program both coordinates in the working plane in the first traverse block after APPR.

# Approaching on a straight line with tangential connection: APPR LT

The tool moves on a straight line from the starting point  $P_{\rm S}$  to an auxiliary point  $P_{\rm H}.$  It then moves to the first contour point  $P_{\rm A}$  on a straight line that connects tangentially to the contour. The auxiliary point  $P_{\rm H}$  is separated from the first contour point  $P_{\rm A}$  by the distance LEN.

- Use any path function to approach the starting point Ps
- ▶ Initiate the dialog with the APPR/DEP key and APPR LT soft key:
  - Coordinates of the first contour point P<sub>A</sub>
  - LEN: Distance from the auxiliary point P<sub>H</sub> to the first contour point P<sub>A</sub>
  - Radius compensation RR/RL for machining

## **Example NC blocks**

APPR LT

7 L X+40 Y+10 R0 FMAX M3	Ps without radius compensation
8 APPR LT X+20 Y+20 Z-10 LEN15 RR F100	$P_{A}$ with radius comp. RR, distance $P_{H}$ zu $P_{A}$ : LEN=15
9 L X+35 Y+35	End point of the first contour element
10 L	Next contour element

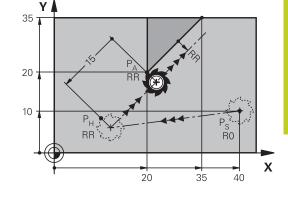
# Approaching on a straight line perpendicular to the first contour point: APPR LN

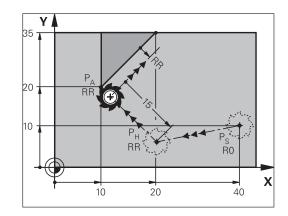
The tool moves on a straight line from the starting point  $P_{\rm S}$  to an auxiliary point  $P_{\rm H}$ . It then moves to the first contour point  $P_{\rm A}$  on a straight line perpendicular to the first contour element. The auxiliary point  $P_{\rm H}$  is separated by the distance LEN plus the tool radius from the first contour point  $P_{\rm A}$ .

- $\blacktriangleright$  Use any path function to approach the starting point  $\mathsf{P}_{\mathsf{S}}$
- Initiate the dialog with the APPR/DEP key and APPR LN soft key:
- APPR LN
- Coordinates of the first contour point P<sub>A</sub>
- Length: Distance to the auxiliary point P<sub>H</sub>. Always enter LEN as a positive value!
- Radius compensation RR/RL for machining

## **Example NC blocks**

7 L X+40 Y+10 R0 FMAX M3	Approach PS without radius compensation
8 APPR LN X+10 Y+20 Z-10 LEN15 RR F100	PA with radius comp. RR
9 L X+20 Y+35	End point of the first contour element
10 L	Next contour element





6.3 Approaching and departing a contour

# Approaching on a circular path with tangential connection: APPR CT

The tool moves on a straight line from the starting point  $P_s$  to an auxiliary point  $P_H$ . It then moves from PH to the first contour point PA following a circular arc that is tangential to the first contour element.

The arc from  $P_H$  to  $P_A$  is determined through the radius R and the center angle CCA. The direction of rotation of the circular arc is automatically derived from the tool path for the first contour element.

- Use any path function to approach the starting point Ps
- Initiate the dialog with the APPR/DEP key and APPR CT soft key:

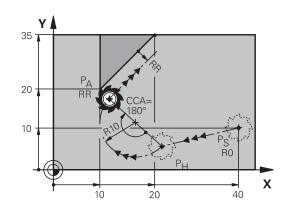


6

- Coordinates of the first contour point P<sub>A</sub>
- ▶ Radius R of the circular arc
  - If the tool should approach the workpiece in the direction defined by the radius compensation: Enter R as a positive value.
  - If the tool should approach from the workpiece side:
  - Enter R as a negative value.
- Center angle CCA of the arc
  - CCA can be entered only as a positive value.
  - Maximum input value 360°
- Radius compensation RR/RL for machining

## Example NC blocks

7 L X+40 Y+10 R0 FMAX M3	Approach PS without radius compensation
8 APPR CT X+10 Y+20 Z-10 CCA180 R+10 RR F100	PA with radius compensation RR, radius R=10
9 L X+20 Y+35	End point of the first contour element
10 L	Next contour element



# Approaching on a circular path with tangential connection from a straight line to the contour: APPR LCT

The tool moves on a straight line from the starting point  $P_S$  to an auxiliary point  $P_H$ . It then moves to the first contour point  $P_A$  on a circular arc. The feed rate programmed in the APPR block is effective for the entire path that the TNC traversed in the approach block (path  $P_S$  to  $P_A$ ).

If you have programmed the coordinates of all three principal axes X, Y and Z in the approach block, the TNC moves the tool from the position defined before the APPR block simultaneously in all three axes to the auxiliary point PH and then, only in the working plane, from  $P_{\rm H}$  to  $P_{\rm A}.$ 

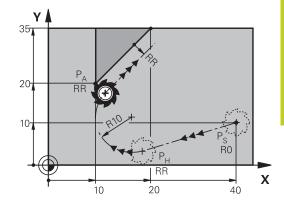
The arc is connected tangentially both to the line  $\mathsf{P}_{\mathsf{S}}\text{-}\mathsf{P}_{\mathsf{H}}$  as well as to the first contour element. Once these lines are known, the radius then suffices to completely define the tool path.

- Use any path function to approach the starting point P<sub>s</sub>
- Initiate the dialog with the APPR/DEP key and APPR LCT soft key:
  - Coordinates of the first contour point P<sub>A</sub>
    - Radius R of the circular arc. Enter R as a positive value
    - Radius compensation RR/RL for machining

## Example NC blocks

APPR LCT

7 L X+40 Y+10 R0 FMAX M3	Approach PS without radius compensation	
8 APPR LCT X+10 Y+20 Z-10 R10 RR F100	PA with radius compensation RR, radius R=10	
9 L X+20 Y+35	End point of the first contour element	
10 L	Next contour element	



6.3 Approaching and departing a contour

# Departing in a straight line with tangential connection: DEP LT

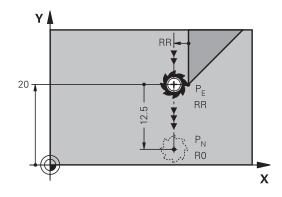
The tool moves on a straight line from the last contour point  $P_E$  to the end point  $P_N$ . The line lies on the extension of the last contour element.  $P_N$  is separated from  $P_E$  by the distance LEN.

- Program the last contour element with the end point P<sub>E</sub> and radius compensation
- ▶ Initiate the dialog with the APPR/DEP key and DEP LT soft key:



6

 LEN: Enter the distance from the last contour element P<sub>E</sub> to the end point P<sub>N</sub>



## **Example NC blocks**

23 L Y+20 RR F100 Last contour element: PE with radius compensation	
24 DEP LT LEN12.5 F100     Depart contour by LEN=12.5 mm	
25 L Z+100 FMAX M2	Retract in Z, return to block 1, end program

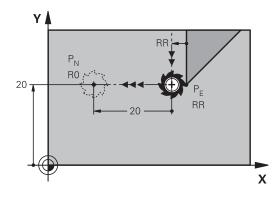
# Departing in a straight line perpendicular to the last contour point: DEP LN

The tool moves on a straight line from the last contour point  $\mathsf{P}_{\mathsf{E}}$  to the end point  $\mathsf{P}_{\mathsf{N}}.$  The line departs on a perpendicular path from the last contour point  $\mathsf{P}_{\mathsf{E}}.$   $\mathsf{P}_{\mathsf{N}}$  is separated from  $\mathsf{P}_{\mathsf{E}}$  by the distance LEN plus the tool radius.

- Program the last contour element with the end point P<sub>E</sub> and radius compensation
- ▶ Initiate the dialog with the APPR/DEP key and DEP LN soft key:



 LEN: Enter the distance from the last contour element to P<sub>N</sub>. Important: Enter LEN with a positive value.



## Example NC blocks

23 L Y+20 RR F100 Last contour element: PE with radius compensat	
24 DEP LN LEN+20 F100	Depart perpendicular to contour by LEN=20 mm
25 L Z+100 FMAX M2	Retract in Z, return to block 1, end program

Υ

20 -

P<sub>N</sub>

RR

Х

## Departing on a circular path with tangential connection: DEP CT

The tool moves on a circular arc from the last contour point P<sub>F</sub> to the end point  $P_N$ . The circular arc connects tangentially to the last contour element.

- Program the last contour element with the end point P<sub>F</sub> and radius compensation
- Initiate the dialog with the APPR/DEP key and DEP CT soft key:



- Center angle CCA of the arc
- Radius R of the circular arc
  - If the tool should depart the workpiece in the direction of the radius compensation (i.e. to the right with RR or to the left with RL): Enter R as a positive value.
  - If the tool should depart the workpiece in the direction **opposite** to the radius compensation: Enter R as a negative value.

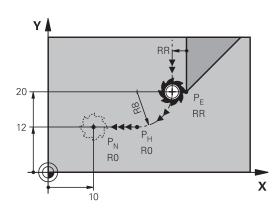
## **Example NC blocks**

23 L Y+20 RR F100	Last contour element: PE with radius compensation	
24 DEP CT CCA 180 R+8 F100	Center angle=180°,	
	arc radius=8 mm	
25 L Z+100 FMAX M2	Retract in Z, return to block 1, end program	

## Departing on a circular arc tangentially connecting the contour and a straight line: DEP LCT

The tool moves on a circular arc from the last contour point  $P_E$  to an auxiliary point  $P_{H}$ . It then moves on a straight line to the end point  $P_N$ . The arc is tangentially connected both to the last contour element and to the line from  $P_H$  to  $P_N$ . Once these lines are known, the radius R suffices to unambiguously define the tool path.

- Program the last contour element with the end point  $P_F$  and radius compensation
- Initiate the dialog with the APPR/DEP key and DEP LCT soft key:
  - Enter the coordinates of the end point  $P_N$ 
    - Radius R of the circular arc. Enter R as a positive ► value



#### **Example NC blocks**

DEP LCT

3

23 L Y+20 RR F100	Last contour element: PE with radius compensation
24 DEP LCT X+10 Y+12 R+8 F100 Coordinates PN, arc radius=8 mm	
25 L Z+100 FMAX M2 Retract in Z, return to block 1, end program	

6.4 Path contours - Cartesian coordinates

# 6.4 Path contours - Cartesian coordinates

## **Overview of path functions**

Function	Path function key	Tool movement	<b>Required input</b>	Page
Straight line <b>L</b>	LAD	Straight line	Coordinates of the end point of the straight line	207
Chamfer: CHF	CHF c.Lo	Chamfer between two straight lines	Chamfer side length	208
Circle center <b>CC</b>	<b>S</b>	None	Coordinates of the circle center or pole	210
Circular arc <b>C</b>	2°	Circular arc around a circle center CC to an arc end point	Coordinates of the arc end point, direction of rotation	211
Circular arc <b>CR</b>	CR o	Circular arc with a certain radius	Coordinates of the arc end point, arc radius, direction of rotation	212
Kreisbogen <b>CT</b>	СТ9	Circular arc with tangential connection to the preceding and subsequent contour elements	Coordinates of the arc end point	214
Corner rounding <b>RND</b>		Circular arc with tangential connection to the preceding and subsequent contour elements	Rounding radius R	209
<b>FK</b> free contour programming	FK	Straight line or circular path with any connection to the preceding contour element	See "Path contours – FK free contour programming ", page 225	229

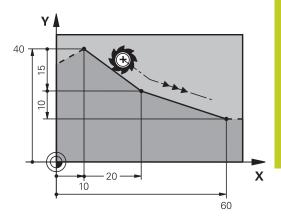
## Straight line L

The TNC moves the tool in a straight line from its current position to the straight-line end point. The starting point is the end point of the preceding block.



 Coordinates of the end point of the straight line, if necessary

- Radius compensation RL/RR/R0
- Feed rate F
- Miscellaneous function M



## Example NC blocks

7 L X+10 Y+40 RL F200 M3
8 L IX+20 IY-15
9 L X+60 IY-10

## **Capture actual position**

You can also generate a straight-line block (L block) by using the ACTUAL-POSITION-CAPTURE key:

- In the Manual Operation mode, move the tool to the position you want to capture
- Switch the screen display to Programming and Editing
- Select the program block after which you want to insert the L block



 Press the ACTUAL-POSITION-CAPTURE key: The TNC generates an L block with the actual position coordinates.

6.4 Path contours - Cartesian coordinates

## Inserting a chamfer between two straight lines

The chamfer enables you to cut off corners at the intersection of two straight lines.

- The line blocks before and after the **CHF** block must be in the same working plane as the chamfer.
- The radius compensation before and after the CHF block must be the same
- The chamfer must be machinable with the current tool



6

Chamfer side length: Length of the chamfer, and if necessary:

Feed rate F (effective only in CHF block)

## **Example NC blocks**

## 7 L X+0 Y+30 RL F300 M3

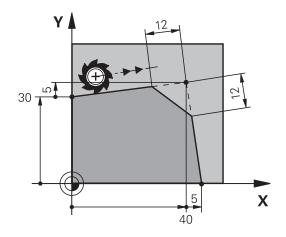
8 L X+40 IY+5	
9 CHF 12 F250	
10 L IX+5 Y+0	

 $\Rightarrow$ 

You cannot start a contour with a CHF block.

A chamfer is possible only in the working plane. The corner point is cut off by the chamfer and is not part of the contour.

A feed rate programmed in the CHF block is effective only in that block. After the **CHF** block, the previous feed rate becomes effective again.



## **Corner rounding RND**

The **RND** function is used for rounding off corners.

The tool moves on an arc that is tangentially connected to both the preceding and subsequent contour elements.

The rounding arc must be machinable with the called tool.

RND o:

- Rounding radius: Enter the radius, and if necessary:
- Feed rate F (effective only in RND block)

## **Example NC blocks**

5 L X+10 Y+40 RL F300 M3

## 6 L X+40 Y+25

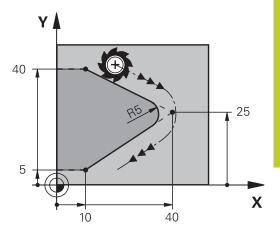
- 7 RND R5 F100
- 8 L X+10 Y+5

In the preceding and subsequent contour elements, both coordinates must lie in the plane of the rounding arc. If you machine the contour without tool-radius compensation, you must program both coordinates in the working plane.

The corner point is cut off by the rounding arc and is not part of the contour.

A feed rate programmed in the **RND** block is effective only in that **RND** block. After the **RND** block, the previous feed rate becomes effective again.

You can also use an **RND** block for a tangential contour approach.



## 6.4 Path contours - Cartesian coordinates

## **Circle center CC**

You can define a circle center for circles that you have programmed with the C key (circular path C) , or function. This is done in the following ways:

- Entering the Cartesian coordinates of the circle center in the working plane, or
- Using the circle center defined in an earlier block, or
- Capturing the coordinates with the ACTUAL-POSITION-CAPTURE key



6

 Enter coordinates for the circle center or, if you want to use the last programmed position, enter no coordinates

## Example NC blocks

## 5 CC X+25 Y+25

or

## 10 L X+25 Y+25

11 CC

The program blocks 10 and 11 do not refer to the illustration.

## Validity

The circle center definition remains in effect until a new circle center is programmed.

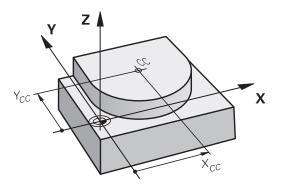
## Entering the circle center incrementally

If you enter the circle center with incremental coordinates, you have programmed it relative to the last programmed position of the tool.



The only effect of CC is to define a position as circle center: The tool does not move to this position. The circle center is also the pole for polar

coordinates.



## Circular path C around circle center CC

Before programming a circular arc, you must first enter the circle center **CC**. The last programmed tool position will be the starting point of the arc.

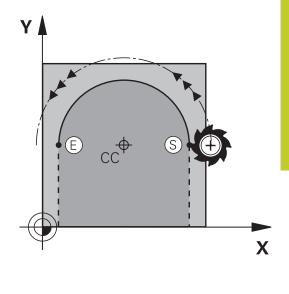
Move the tool to the circle starting point

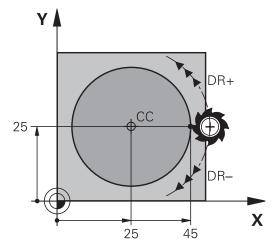
- ¢
- Enter the coordinates of the circle center
- Enter the coordinates of the arc end point, and if necessary:
- Direction of rotation DR
- Feed rate F
- Miscellaneous function M

The TNC normally makes circular movements in the active working plane. If you program circular arcs that do not lie in the active working plane, for example **C Z... X... DR+** with a tool axis Z, and at the same time rotate this movement, then the TNC moves the tool in a spatial arc, which means a circular arc in 3 axes (software option 1).

## Example NC blocks

- 5 CC X+25 Y+25
- 6 L X+45 Y+25 RR F200 M3
- 7 C X+45 Y+25 DR+





## Full circle

For the end point, enter the same point that you used for the starting point.

The starting and end points of the arc must lie on the circle.

Input tolerance: up to 0.016 mm (selected through the **circleDeviation** machine parameter).

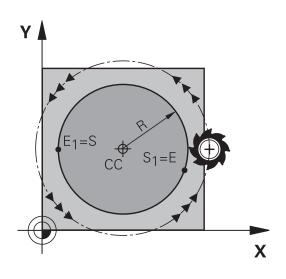
Smallest possible circle that the TNC can traverse: 0.0016  $\mu m.$ 

6.4 Path contours - Cartesian coordinates

## **Circle CR with defined radius**

The tool moves on a circular path with the radius R.

- CR
- Coordinates of the arc end point
- Radius R (the algebraic sign determines the size of the arc)
- Direction of rotation DR Note: The algebraic sign determines whether the arc is concave or convex.
- Miscellaneous function M
- Feed rate F



## Full circle

For a full circle, program two blocks in succession:

The end point of the first semicircle is the starting point of the second. The end point of the second semicircle is the starting point of the first.

## Central angle CCA and arc radius R

The starting and end points on the contour can be connected with four arcs of the same radius:

Smaller arc: CCA<180°

Enter the radius with a positive sign R>0

Larger arc: CCA>180°

Enter the radius with a negative sign R<0

The direction of rotation determines whether the arc is curving outward (convex) or curving inward (concave):

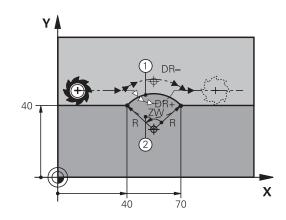
Convex: Direction of rotation **DR-** (with radius compensation **RL**) Concave: Direction of rotation **DR+** (with radius compensation **RL**)



The distance from the starting and end points of the arc diameter cannot be greater than the diameter of the arc.

The maximum radius is 99.9999 m.

You can also enter rotary axes A, B and C.



## Example NC blocks

10 L X+40 Y+40 RL F200 M3 11 CR X+70 Y+40 R+20 DR- (ARC 1)

or

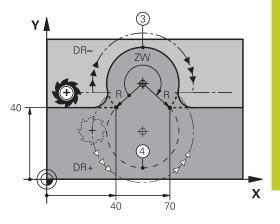
11 CR X+70 Y+40 R+20 DR+ (ARC 2)

or

11 CR X+70 Y+40 R-20 DR- (ARC 3)

or

11 CR X+70 Y+40 R-20 DR+ (ARC 4)



6.4 Path contours - Cartesian coordinates

## **Circle CT with tangential connection**

The tool moves on an arc that starts tangentially to the previously programmed contour element.

A transition between two contour elements is called tangential when there is no kink or corner at the intersection between the two contours—the transition is smooth.

The contour element to which the tangential arc connects must be programmed immediately before the **CT** block. This requires at least two positioning blocks.



6

Coordinates of the arc end point, and if necessary:

- Feed rate F
- Miscellaneous function M



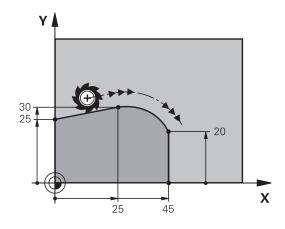
7 L X+0 Y+25 RL F300 M3

8 L X+25 Y+30

9 CT X+45 Y+20

10 L Y+0

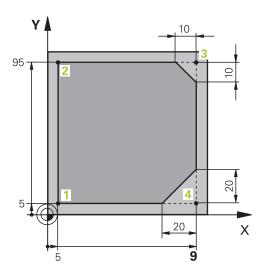
A tangential arc is a two-dimensional operation: the coordinates in the **CT** block and in the contour element preceding it must be in the same plane of the arc!



214

6

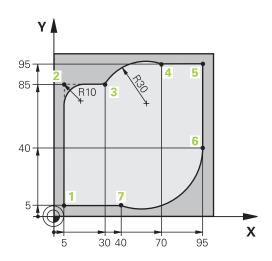
# Example: Linear movements and chamfers with Cartesian coordinates



0 BEGIN PGM LINEAR MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank for graphic workpiece simulation
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL CALL 1 Z S4000	Call the tool in the spindle axis and with the spindle speed S
4 L Z+250 R0 FMAX	Retract the tool in the spindle axis at rapid traverse FMAX
5 L X-10 Y-10 R0 FMAX	Pre-position the tool
6 L Z-5 R0 F1000 M3	Move to working depth at feed rate F = 1000 mm/min
7 APPR LT X+5 Y+5 LEN10 RL F300	Approach the contour at point 1 on a straight line with tangential connection
8 L Y+95	Move to point 2
9 L X+95	Point 3: first straight line for corner 3
10 CHF 10	Program a chamfer with length 10 mm
11 L Y+5	Point 4: 2nd straight line for corner 3, 1st straight line for corner 4
12 CHF 20	Program a chamfer with length 20 mm
13 L X+5	Move to last contour point 1, second straight line for corner 4
14 DEP LT LEN10 F1000	Depart the contour on a straight line with tangential connection
15 L Z+250 R0 FMAX M2	Retract the tool, end program
16 END PGM LINEAR MM	

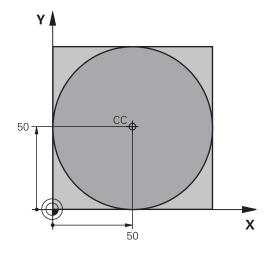
6.4 Path contours - Cartesian coordinates

Example: Circular movements with Cartesian coordinates



0 BEGIN PGM CIRCULAR MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank for graphic workpiece simulation
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL CALL 1 Z \$4000	Call the tool in the spindle axis and with the spindle speed S
4 L Z+250 R0 FMAX	Retract the tool in the spindle axis at rapid traverse FMAX
5 L X-10 Y-10 R0 FMAX	Pre-position the tool
6 L Z-5 R0 F1000 M3	Move to working depth at feed rate F = 1000 mm/min
7 APPR LCT X+5 Y+5 R5 RL F300	Approach the contour at point 1 on a circular arc with tangential connection
8 L X+5 Y+85	Point 2: First straight line for corner 2
9 RND R10 F150	Insert radius with $R = 10 \text{ mm}$ , feed rate: 150 mm/min
10 L X+30 Y+85	Move to point 3: Starting point of the arc with CR
11 CR X+70 Y+95 R+30 DR-	Move to point 4: End point of the arc with CR, radius 30 mm
12 L X+95	Move to point 5
13 L X+95 Y+40	Move to point 6
14 CT X+40 Y+5	Move to point 7: End point of the arc, circular arc with tangential connection to point 6, TNC automatically calculates the radius
15 L X+5	Move to last contour point 1
16 DEP LCT X-20 Y-20 R5 F1000	Depart the contour on a circular arc with tangential connection
17 L Z+250 R0 FMAX M2	Retract the tool, end program
18 END PGM CIRCULAR MM	

### Example: Full circle with Cartesian coordinates



0 BEGIN PGM C-CC MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Definition of workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL CALL 1 Z S3150	Tool call
4 CC X+50 Y+50	Define the circle center
5 L Z+250 R0 FMAX	Retract the tool
6 L X-40 Y+50 R0 FMAX	Pre-position the tool
7 L Z-5 R0 F1000 M3	Move to working depth
8 APPR LCT X+0 Y+50 R5 RL F300	Approach the starting point of the circle on a circular arc with tangential connection
9 C X+0 DR-	Move to the circle end point (= circle starting point)
10 DEP LCT X-40 Y+50 R5 F1000	Depart the contour on a circular arc with tangential connection
11 L Z+250 R0 FMAX M2	Retract the tool, end program
12 END PGM C-CC MM	

TNC 640 | User's Manual

6.5 Path contours – Polar coordinates

### 6.5 Path contours – Polar coordinates

#### **Overview**

With polar coordinates you can define a position in terms of its angle **PA** and its distance **PR** relative to a previously defined pole **CC**.

Polar coordinates are useful with:

- Positions on circular arcs
- Workpiece drawing dimensions in degrees, e.g. bolt hole circles

#### Overview of path functions with polar coordinates

Function	Path function key	Tool movement	Required input	Page
Straight line <b>LP</b>		Straight line	Polar radius, polar angle of the straight-line end point	219
Circular arc <b>CP</b>	°℃ + P	Circular path around circle center/pole to arc end point	Polar angle of the arc end point, direction of rotation	220
Circular arc <b>CTP</b>		Circular arc with tangential connection to the preceding contour element	Polar radius, polar angle of the arc end point	220
Helical interpolation		Combination of a circular and a linear movement	Polar radius, polar angle of the arc end point, coordinate of the end point in the tool axis	221

### Zero point for polar coordinates: pole CC

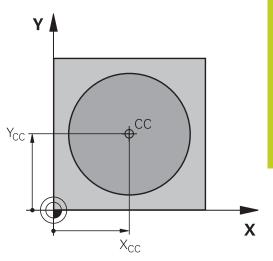
You can define the pole CC anywhere in the part program before blocks containing polar coordinates. Set the pole in the same way as you would program the circle center.



Coordinates: Enter Cartesian coordinates for the pole or, if you want to use the last programmed position, enter No coordinates. Before programming polar coordinates, define the pole. You can only define the pole in Cartesian coordinates. The pole remains in effect until you define a new pole.

#### **Example NC blocks**

12 CC X+45 Y+25



6

### Straight line LP

The tool moves in a straight line from its current position to the straight-line end point. The starting point is the end point of the preceding block.



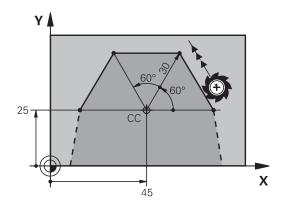
- Polar coordinate radius PR: Enter the distance from the pole CC to the straight-line end point
- Polar coordinate angle PA: Angular position of the straight-line end point between –360° and +360°

The sign of  $\ensuremath{\text{PA}}$  depends on the angle reference axis:

- If the angle from the angle reference axis to PR is counterclockwise: PA>0
- If the angle from the angle reference axis to **PR** is clockwise: **PA**<0

#### **Example NC blocks**

12 CC X+45 Y+25
13 LP PR+30 PA+0 RR F300 M3
14 LP PA+60
15 LP IPA+60
16 LP PA+180



6.5 Path contours – Polar coordinates

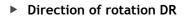
### Circular path CP around pole CC

The polar coordinate radius **PR** is also the radius of the arc. **PR** is defined by the distance from the starting point to the pole **CC**. The last programmed tool position will be the starting point of the arc.



6

 Polar-coordinates angle PA: Angular position of the arc end point between –99 999.9999° and +99 999.9999°



#### **Example NC blocks**

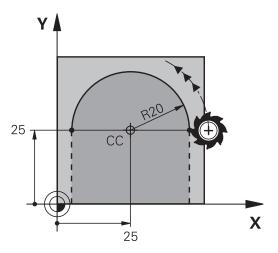
### 18 CC X+25 Y+25

19 LP PR+20 PA+0 RR F250 M3

20 CP PA+180 DR+



For incremental coordinates, enter the same sign for DR and PA.



### **Circle CTP with tangential connection**

The tool moves on a circular path, starting tangentially from a preceding contour element.



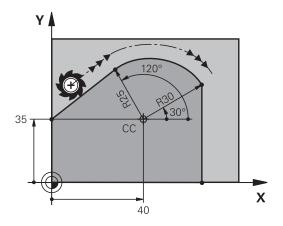
- Polar coordinate radius PR: Enter the distance from are end point to the pole CC
- Polar coordinates angle PA: Angular position of the arc end point



The pole is **not** the center of the contour arc!



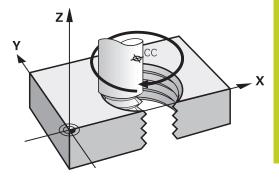
12 CC X+40 Y+35
13 L X+0 Y+35 RL F250 M3
14 LP PR+25 PA+120
15 CTP PR+30 PA+30
16 L Y+0



#### Helix

A helix is a combination of a circular movement in a main plane and a linear movement perpendicular to this plane. You program the circular path in a main plane.

A helix is programmed only in polar coordinates.



#### Application

- Large-diameter internal and external threads
- Lubrication grooves

#### **Calculating the helix**

To program a helix, you must enter the total angle through which the tool is to move on the helix in incremental dimensions, and the total height of the helix.

Thread revolutions n:	Thread revolutions + overrun at start and end of thread
Total height h:	Thread pitch P times thread revolutions n
Incremental total angle IPA:	Thread revolutions x 360° + angle for beginning of thread + angle for thread overrun
Starting coordinate Z:	Pitch P times (thread revolutions + thread overrun at start of thread)

#### Shape of the helix

The table below illustrates in which way the shape of the helix is determined by the work direction, direction of rotation and radius compensation.

Internal thread	Work direction	Direction of rotation	Radius compensation
Right-hand	Z+	DR+	RL
Left-hand	Z+	DR-	RR
Right-hand	Z–	DR-	RR
Left-hand	Z–	DR+	RL
External thread			
Right-hand	Z+	DR+	RR
Left-hand	Z+	DR-	RL
Right-hand	Z–	DR-	RL
Left-hand	Z–	DR+	RR

6.5 Path contours – Polar coordinates

#### **Programming a helix**

Always enter the same algebraic sign for the direction of rotation and the incremental total angle **IPA**. The tool may otherwise move in a wrong path and damage the contour.

For the total angle **IPA** you can enter a value of -99 999.9999° to +99 999.9999°.



Polar coordinates angle: Enter the total angle of tool traverse along the helix in incremental dimensions. After entering the angle, specify the tool axis with an axis selection key.

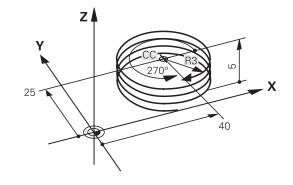
- **Coordinate**: Enter the coordinate for the height of the helix in incremental dimensions
- Direction of rotation DR

Clockwise helix: DR– Counterclockwise helix: DR+

Enter the radius compensation according to the table

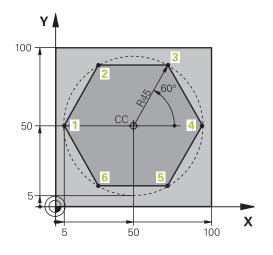
#### Example NC blocks: Thread M6 x 1 mm with 5 revolutions

12 CC X+40 Y+25	
13 L Z+0 F100 M3	
14 LP PR+3 PA+270 RL F50	
15 CP IPA-1800 IZ+5 DR-	



6

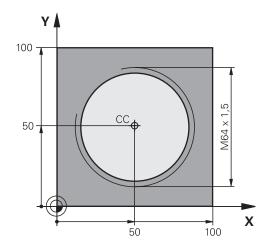
### Example: Linear movement with polar coordinates



0 BEGIN PGM LINEARPO MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Definition of workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL CALL 1 Z S4000	Tool call
4 CC X+50 Y+50	Define the datum for polar coordinates
5 L Z+250 R0 FMAX	Retract the tool
6 LP PR+60 PA+180 R0 FMAX	Pre-position the tool
7 L Z-5 R0 F1000 M3	Move to working depth
8 APPR PLCT PR+45 PA+180 R5 RL F250	Approach the contour at point 1 on a circular arc with tangential connection
9 LP PA+120	Move to point 2
10 LP PA+60	Move to point 3
11 LP PA+0	Move to point 4
12 LP PA-60	Move to point 5
13 LP PA-120	Move to point 6
14 LP PA+180	Move to point 1
15 DEP PLCT PR+60 PA+180 R5 F1000	Depart the contour on a circular arc with tangential connection
16 L Z+250 R0 FMAX M2	Retract the tool, end program
17 END PGM LINEARPO MM	

6.5 Path contours – Polar coordinates

### Example: Helix



O BEGIN PGM HELIX MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Definition of workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL CALL 1 Z S1400	Tool call
4 L Z+250 R0 FMAX	Retract the tool
5 L X+50 Y+50 R0 FMAX	Pre-position the tool
6 CC	Transfer the last programmed position as the pole
7 L Z-12,75 R0 F1000 M3	Move to working depth
8 APPR PCT PR+32 PA-182 CCA180 R+2 RL F100	Approach the contour on a circular arc with tangential connection
9 CP IPA+3240 IZ+13.5 DR+ F200	Helical interpolation
10 DEP CT CCA180 R+2	Depart the contour on a circular arc with tangential connection
11 L Z+250 R0 FMAX M2	Retract the tool, end program
12 END PGM HELIX MM	

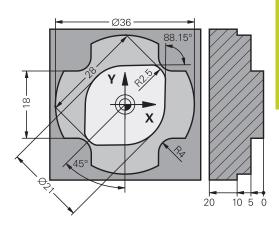
# 6.6 Path contours – FK free contour programming

#### **Fundamentals**

Workpiece drawings that are not dimensioned for NC often contain unconventional coordinate data that cannot be entered with the gray path function keys. For example:

- Known coordinates on the contour element or in its proximity
- Coordinate data can be referenced to another contour element
- Directional data and data regarding the course of the contour

You can enter such dimensional data directly by using the FK free contour programming function. The TNC derives the contour from the known coordinate data and supports the programming dialog with the interactive programming graphics. The figure at upper right shows a workpiece drawing for which FK programming is the most convenient programming method.



### 6.6 Path contours – FK free contour programming



6

## The following prerequisites for FK programming must be observed:

The FK free contour programming feature can only be used for programming contour elements that lie in the working plane.

The working plane for FK programming is defined according to the following hierarchy:

- 1. By the plane defined in a **FPOL** block
- 2. In the Z/X plane if the FK sequence is run in turning mode
- 3. By the working plane pre-defined in
   TOOL CALL (e.g. TOOL CALL 1 Z = X/Y plane)
- 4. The standard X/Y plane is active if none of these applies

The display of the FK soft keys depends on the spindle axis in **BLK FORM** If for example you enter spindle axis **Z** in the **BLK FORM**, the TNC only shows FK soft keys for the X/Y plane.

You must enter all available data for every contour element. Even the data that does not change must be entered in every block—otherwise it will not be recognized.

Q parameters are permissible in all FK elements, except in elements with relative references (e.g. **RX** or **RAN**), or in elements that are referenced to other NC blocks.

If both FK blocks and conventional blocks are entered in a program, the FK contour must be fully defined before you can return to conventional programming.

The TNC needs a fixed point from which it can calculate the contour elements. Use the gray path function keys to program a position that contains both coordinates of the working plane immediately before programming the FK contour. Do not enter any  $\Omega$  parameters in this block.

If the first block of an FK contour is an **FCT** or **FLT** block, you must program at least two NC blocks with the gray path function keys to fully define the direction of contour approach.

Do not program an FK contour immediately after an **LBL** command.

### **FK** programming graphics



If you wish to use graphic support during FK programming, select the PROGRAM + GRAPHICS screen layout, See "Programming"

Incomplete coordinate data often is not sufficient to fully define a workpiece contour. In this case, the TNC indicates the possible solutions in the FK graphic. You can then select the contour that matches the drawing. The FK graphic displays the elements of the workpiece contour in different colors:

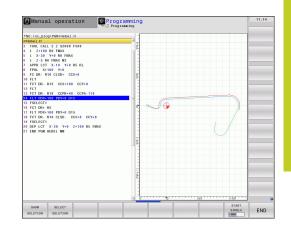
- **Blue**: The contour element is fully defined
- **Green**: The entered data describe a limited number of possible solutions: select the correct one
- **Red**: The entered data are not sufficient to determine the contour element: enter further data

If the entered data permit a limited number of possible solutions and the contour element is displayed in green, select the correct contour element as follows:



Press the SHOW SOLUTION soft key repeatedly until the correct contour element is displayed. Use the zoom function (2nd soft-key row) if you cannot distinguish possible solutions in the standard setting

SELECT SOLUTION  If the displayed contour element matches the drawing, select the contour element with SELECT SOLUTION



### 6.6 Path contours – FK free contour programming

If you do not yet wish to select a green contour element, press the END SELECT soft key to continue the FK dialog.

6

Select the green contour elements as soon as possible with the SELECT SOLUTION soft key. This way you can reduce the ambiguity of subsequent elements.

The machine tool builder may use other colors for the FK graphics.

NC blocks from a program that you called with PGM CALL are displayed in another color.

#### Showing block numbers in the graphic window

To show a block number in the graphic window:



 Set the SHOW OMIT BLOCK NR. soft key to SHOW (soft-key row 3)

#### Initiating the FK dialog

If you press the gray FK button, the TNC displays the soft keys you can use to initiate an FK dialog—see the following table. Press the FK button a second time to deselect the soft keys.

If you initiate the FK dialog with one of these soft keys, the TNC shows additional soft-key rows that you can use for entering known coordinates, directional data and data regarding the course of the contour.

FK element	Soft key
Straight line with tangential connection	FLT
Straight line without tangential connection	FL
Circular arc with tangential connection	FCT
Circular arc without tangential connection	FC
Pole for FK programming	FPOL

#### Pole for FK programming



- To display the soft keys for free contour programming, press the FK key
- To initiate the dialog for defining the pole, press the FPOL soft key. The TNC then displays the axis soft keys of the active working plane
- Enter the pole coordinates using these soft keys



The pole for FK programming remains active until you define a new one using FPOL.

229

6

### 6.6 Path contours – FK free contour programming

#### Free straight line programming

#### Straight line without tangential connection



6

- To display the soft keys for free contour programming, press the FK key
- To initiate the dialog for free programming of straight lines, press the FL soft key. The TNC displays additional soft keys
- Enter all known data in the block by using these soft keys. The FK graphic displays the programmed contour element in red until sufficient data is entered. If the entered data describes several solutions, the graphic will display the contour element in green (See "FK programming graphics", page 227)

#### Straight line with tangential connection

If the straight line connects tangentially to another contour element, initiate the dialog with the FLT soft key:

- FK
- To display the soft keys for free contour programming, press the FK key
- ► To initiate the dialog, press the FLT soft key
- Enter all known data in the block by using the soft keys

#### Free circular path programming

#### Circular arc without tangential connection



- To display the soft keys for free contour programming, press the FK key
- To initiate the dialog for free programming of circular arcs, press the FC soft key. The TNC displays soft keys with which you can directly enter data on the circular arc or the circle center
- Enter all known data in the block by using these soft keys. The FK graphic displays the programmed contour element in red until sufficient data is entered. If the entered data describes several solutions, the graphic will display the contour element in green (See "FK programming graphics", page 227)

#### Circular arc with tangential connection

If the circular arc connects tangentially to another contour element, initiate the dialog with the FCT soft key:



- To display the soft keys for free contour programming, press the FK key
- ▶ To initiate the dialog, press the FCT soft key
- Enter all known data in the block by using the soft keys

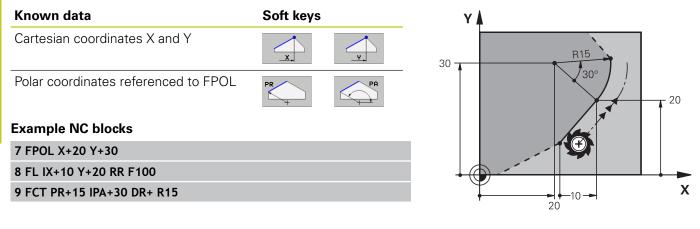
6

6.6 Path contours – FK free contour programming

#### Input options

6

#### End point coordinates



#### Direction and length of contour elements

Known data	Soft keys	Y
Length of a straight line		IAN
Gradient angle of a straight line	AN	ANLEN
Chord length LEN of an arc	LEN	
Gradient angle AN of an entry tangent	AN	
Center angle of an arc	CCA	Y
Courtians Dammar to the sucrimit		

#### Caution: Danger to the workpiece and tool!

Gradient angles that you defined incrementally (**IAN**) are referenced to the direction of the last positioning block by the TNC. Programs that contain incremental gradient angles and were created on an iTNC 530 or on earlier TNCs are not compatible.

#### **Example NC blocks**

27 FLT X+25 LEN 12.5 AN+35 RL F200
28 FC DR+ R6 LEN 10 AN-45
29 FCT DR- R15   FN 15

. 25 ′45°

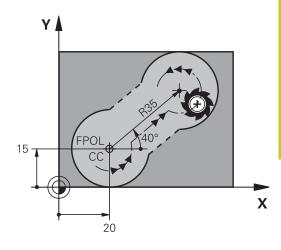
Х

## Circle center CC, radius and direction of rotation in the FC/FCT block

The TNC calculates a circle center for free-programmed arcs from the data you enter. This makes it possible to program full circles in an FK program block.

If you wish to define the circle center in polar coordinates you must use FPOL, not CC, to define the pole. FPOL is entered in Cartesian coordinates and remains in effect until the control encounters a block in which another FPOL is defined.

> A circle center that was calculated or programmed conventionally is then no longer valid as a pole or circle center for the new FK contour: If you enter conventional polar coordinates that refer to a pole from a CC block you have defined previously, then you must enter the pole again in a CC block after the FK contour.



Known data	Soft keys
Circle center in Cartesian coordinates	
Center point in polar coordinates	
Rotational direction of the arc	DR- DR+
Radius of an arc	R
Example NC blocks	

10 FC CCX+20 CCY+15 DR+ R15
11 FPOL X+20 Y+15
12 FL AN+40
13 FC DR+ R15 CCPR+35 CCPA+40

### 6.6 Path contours – FK free contour programming

#### **Closed contours**

You can identify the beginning and end of a closed contour with the CLSD soft key. This reduces the number of possible solutions for the last contour element.

Enter CLSD as an addition to another contour data entry in the first and last blocks of an FK section.



Beginning of CLSD+ contour:

End of contour: CLSD-

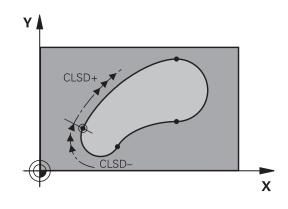
#### **Example NC blocks**

12 L X+5 Y+35 RL F500 M3

13 FC DR- R15 CLSD+ CCX+20 CCY+35

•••

17 FCT DR- R+15 CLSD-

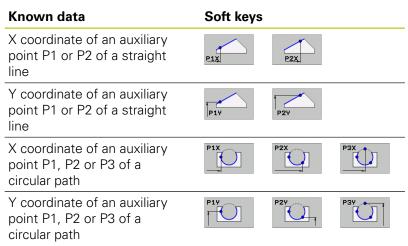


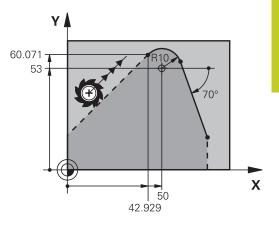
#### **Auxiliary points**

For both free-programmed straight lines and free-programmed circular arcs, you can enter the coordinates of auxiliary points that are located on the contour or in its proximity.

#### Auxiliary points on a contour

The auxiliary points are located on the straight line, the extension of the straight line, or on the circular arc.





#### Auxiliary points near a contour

Known data	Soft keys	
X and Y coordinates of the auxiliary point near a straight line	PDX	PDY
Distance of auxiliary point to straight line		
X and Y coordinates of an auxiliary point near a circular arc	PDX	PDY
Distance of auxiliary point to circular arc		
Example NC blocks		

13 FC DR- R10 P1X+42.929 P1Y+60.071
14 FLT AN-70 PDX+50 PDY+53 D10

6.6 Path contours – FK free contour programming

#### **Relative data**

6

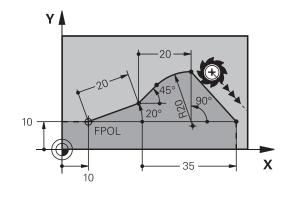
Data whose values are based on another contour element are called relative data. The soft keys and program words for entries begin with the letter **R** for **R**elative. The figure at right shows the entries that should be programmed as relative data.



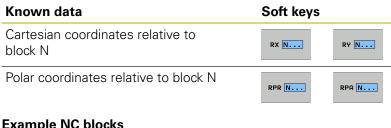
The coordinates and angles for relative data are always programmed in incremental dimensions. You must also enter the block number of the contour element on which the data are based.

The block number of the contour element on which the relative data are based can only be located up to 64 positioning blocks before the block in which you program the reference.

If you delete a block on which relative data are based, the TNC will display an error message. Change the program first before you delete the block.



#### Data relative to block N: End point coordinates



#### **Example NC blocks**

12 FPOL X+10 Y+10
13 FL PR+20 PA+20
14 FL AN+45
15 FCT IX+20 DR- R20 CCA+90 RX 13
16 FL IPR+35 PA+0 RPR 13

## Data relative to block N: Direction and distance of the contour element

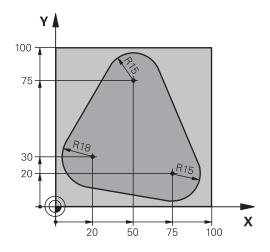
Known data		Soft key
Angle between a straight line and anoth element or between the entry tangent and another element		RAN N
Straight line parallel to another contour	element	PAR N
Distance from a straight line to a paralle element	əl contour	DP
Example NC blocks		
17 FL LEN 20 AN+15		
18 FL AN+105 LEN 12.5		
19 FL PAR 17 DP 12.5		
20 FSELECT 2		
21 FL LEN 20 IAN+95		
22 FL IAN+220 RAN 18		
Data relative to block N: Circle center	CC	
Known data	Soft key	
Cartesian coordinates of the circle center relative to block N	RCCX N	RCCY N
Polar coordinates of the circle center relative to block N	RCCPR N	RCCPA N
Example NC blocks		
12 FL X+10 Y+10 RL		
13 FL		
14 FL X+18 Y+35		

17 FC DR- R10 CCA+0 ICCX+20 ICCY-15 RCCX12 RCCY14

15 FL ... 16 FL ...

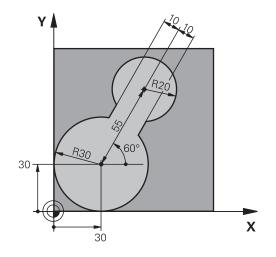
6.6 Path contours – FK free contour programming

### Example: FK programming 1



0 BEGIN PGM FK1 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Definition of workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL CALL 1 Z S500	Tool call
4 L Z+250 R0 FMAX	Retract the tool
5 L X-20 Y+30 R0 FMAX	Pre-position the tool
6 L Z-10 R0 F1000 M3	Move to working depth
7 APPR CT X+2 Y+30 CCA90 R+5 RL F250	Approach the contour on a circular arc with tangential connection
8 FC DR- R18 CLSD+ CCX+20 CCY+30	FK contour section:
9 FLT	Program all known data for each contour element
10 FCT DR- R15 CCX+50 CCY+75	
11 FLT	
12 FCT DR- R15 CCX+75 CCY+20	
13 FLT	
14 FCT DR- R18 CLSD- CCX+20 CCY+30	
15 DEP CT CCA90 R+5 F1000	Depart the contour on a circular arc with tangential connection
16 L X-30 Y+0 R0 FMAX	
17 L Z+250 R0 FMAX M2	Retract the tool, end program
18 END PGM FK1 MM	

### Example: FK programming 2

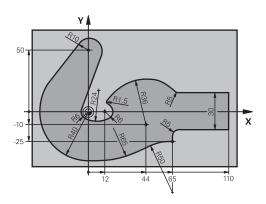


0 BEGIN PGM FK2 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Definition of workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL CALL 1 Z \$4000	Tool call
4 L Z+250 R0 FMAX	Retract the tool
5 L X+30 Y+30 R0 FMAX	Pre-position the tool
6 L Z+5 R0 FMAX M3	Pre-position the tool in the tool axis
7 L Z-5 R0 F100	Move to working depth
8 APPR LCT X+0 Y+30 R5 RR F350	Approach the contour on a circular arc with tangential connection
9 FPOL X+30 Y+30	FK contour section:
10 FC DR- R30 CCX+30 CCY+30	Program all known data for each contour element
11 FL AN+60 PDX+30 PDY+30 D10	
12 FSELECT 3	
13 FC DR- R20 CCPR+55 CCPA+60	
14 FSELECT 2	
15 FL AN-120 PDX+30 PDY+30 D10	
16 FSELECT 3	
17 FC X+0 DR- R30 CCX+30 CCY+30	
18 FSELECT 2	
19 DEP LCT X+30 Y+30 R5	Depart the contour on a circular arc with tangential connection
20 L Z+250 R0 FMAX M2	Retract the tool, end program
21 END PGM FK2 MM	

6

6.6 Path contours – FK free contour programming

### Example: FK programming 3



0 BEGIN PGM FK3 MM	
1 BLK FORM 0.1 Z X-45 Y-45 Z-20	Definition of workpiece blank
2 BLK FORM 0.2 X+120 Y+70 Z+0	
3 TOOL CALL 1 Z \$4500	Tool call
4 L Z+250 R0 FMAX	Retract the tool
5 L X-70 Y+0 R0 FMAX	Pre-position the tool
6 L Z-5 R0 F1000 M3	Move to working depth
7 APPR CT X-40 Y+0 CCA90 R+5 RL F250	Approach the contour on a circular arc with tangential connection
8 FC DR- R40 CCX+0 CCY+0	FK contour section:
9 FLT	Program all known data for each contour element
10 FCT DR- R10 CCX+0 CCY+50	
11 FLT	
12 FCT DR+ R6 CCX+0 CCY+0	
13 FCT DR+ R24	
14 FCT DR+ R6 CCX+12 CCY+0	
15 FSELECT 2	
16 FCT DR- R1.5	
17 FCT DR- R36 CCX+44 CCY-10	
18 FSELECT 2	
19 FCT DR+ R5	
20 FLT X+110 Y+15 AN+0	
21 FL AN-90	
22 FL X+65 AN+180 PAR21 DP30	
23 RND R5	
24 FL X+65 Y-25 AN-90	
25 FC DR+ R50 CCX+65 CCY-75	
26 FCT DR- R65	
27 FSELECT 1	
28 FCT Y+0 DR- R40 CCX+0 CCY+0	
29 FSELECT 4	
30 DEP CT CCA90 R+5 F1000	Depart the contour on a circular arc with tangential connection
31 L X-70 R0 FMAX	

32 L Z+250 R0 FMAX M2

33 END PGM FK3 MM

Retract the tool, end program

Programming: Data transfer from DXF files or plainlanguage contours

### Programming: Data transfer from DXF files or plain-language contours

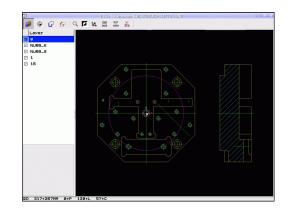
7.1 Processing DXF Files (Software Option)

### 7.1 Processing DXF Files (Software Option)

### Application

DXF files created in a CAD system can be opened directly by the TNC, in order to extract contours or machining positions, and save them as conversational programs or as point files. Plain-language programs acquired in this manner can also be run by older TNC controls, since these contour programs contain only **L** and **CC/C** blocks.

If you process DXF files in the **Programming** operating mode, the TNC generates contour programs with the file extension **.H** and point files with the extension **.PNT** by default. If you process DXF files in the smarT.NC operating mode, the TNC generates contour programs with the file extension **.HC** and point files with the extension **.HP** by default. However, you can choose the desired file type in the saving dialog. Furthermore, you can also save the selected contour or the selected machining positions to the clipboard of the TNC and then insert them directly in an NC program.





The DXF files to be processed must be stored on the hard disk of your TNC.

Before loading the file to the TNC, ensure that the name of the DXF file does not contain any blank spaces or illegal special charactersSee "File names", page 106.

The DXF file to be opened must contain at least one layer.

The TNC supports the most common DXF format, R12 (equivalent to AC1009).

The TNC does not support binary DXF format. When generating the DXF file from a CAD or drawing program, make sure that you save the file in ASCII format.

The following DXF elements can be selected as contours:

- LINE (straight line)
- CIRCLE (complete circle)
- ARC (circular arc)
- POLYLINE

#### **Opening a DXF file**



- Select the Programming and Editing operating mode
- Call the file manager
- SELE TYP

A. DXF

- In order to see the soft-key menu for selecting the file type to be displayed, press the SELECT TYPE soft key
- In order to show all DXF files, press the SHOW DXF soft key
- Select the directory in which the DXF file is saved
- Select the desired DXF file, and load it with the ENT key. The TNC starts the DXF converter and shows the contents of the DXF file on the screen. The TNC shows the layers in the left window, and the drawing in the right window

#### Working with the DXF converter



A mouse is required to use the DXF converter. Operating modes and functions as well as contours and machining positions can only be selected with the mouse.

The DXF converter runs as a separate application on the third desktop of the TNC. This enables you to use the screen switchover key to switch between the machine operating modes, the programming modes and the DXF converter as desired. This is especially useful if you want to insert contours or machining positions in a plain-language program by copying through the clipboard.

### Programming: Data transfer from DXF files or plain-language contours

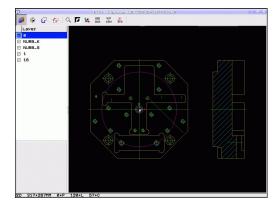
7.1 **Processing DXF Files (Software Option)** 

### **Basic settings**

7

The basic settings specified below are selected using the icons in the toolbar. The icons displayed may vary depending on the operating mode of the TNC.

Setting	Button
Set the zoom to the largest possible view	Q
Change colors (change the background color)	
Switch between 2-D and 3-D mode. If 3-D mode is active, you can rotate and tilt the view with the right mouse button	4
Set the unit of measure (mm or inches) of the DXF file. The TNC then outputs the contour program and the machining positions in this unit of measure	mm inch
The resolution specifies how many decimal places the TNC should use when generating the contour program. Default setting: 4 decimal places (equivalent to resolution of 0.1 µm when the unit of measure MM is active).	0,01 0,001



		Button
tolerance contour el You can us inaccuraci was made	ransfer mode, set the tolerance: The specifies how far apart neighboring ements may be from each other. se the tolerance to compensate for es that occurred when the drawing e. The default setting depends on the the entire DXF file	
circle segr automatic when sele click (OFF)	e for point transfer on circles and ments determines whether the TNC ally loads the circle center point ecting machining positions via mouse ), or if additional points on the circle shown as well.	$\odot$
the circ directly ON <b>She</b>	<b>not show</b> additional points on le. Assume the circle center point when a circle or arc is clicked <b>ow</b> additional points on the circle. e each desired circle point by clicking	
the TNC s	point assumption: Specify whether hould display the tool path during of machining positions.	$\mathcal{W}$
$\Rightarrow$	Please note that you must set the c measure, since the DXF file does no such information.	
	If you want to generate programs for controls, you must limit the resolution decimal places. In addition, you must	on to three
	comments that the DXF converter in contour program. The TNC displays the active basic se	

### Programming: Data transfer from DXF files or plain-language contours

7.1 Processing DXF Files (Software Option)

#### **Setting layers**

As a rule, DXF files contain multiple layers, with which the designer organizes the drawings. The designer uses the layers to create groups of various types of elements, such as the actual workpiece contour, dimensions, auxiliary and design lines, shadings, and texts.

So that as little unnecessary information as possible appears on the screen during selection of the contours, you can hide all excessive layers contained in the DXF file.

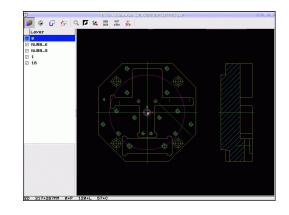


The DXF file to be processed must contain at least one layer.

You can even select a contour if the designer has saved it on different layers.



- If it has not already been activated, select the mode for the layer settings. In the left window the TNC shows all layers contained in the active DXF file
- To hide a layer, select the layer with the left mouse button, and click its check box to hide it
- To show a layer, select the layer with the left mouse button, and click its check box again to show it



### Defining the datum

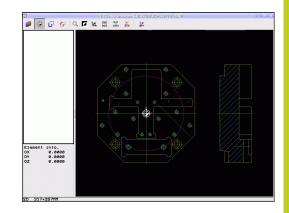
The datum of the drawing for the DXF file is not always located in a manner that lets you use it directly as a reference point for the workpiece. Therefore, the TNC has a function with which you can shift the drawing datum to a suitable location by clicking an element.

You can define a reference point at the following locations:

- At the beginning, end or center of a straight line
- At the beginning or end of a circular arc
- At the transition between quadrants or at the center of a complete circle
- At the intersection between:
  - A straight line and a straight line, even if the intersection is actually on the extension of one of the lines
  - Straight line circular arc
  - Straight line full circle
  - Circle circle (regardless of whether a circular arc or a full circle)

You must use the touchpad on the TNC keyboard or a mouse attached via the USB port in order to specify a reference point.

You can also change the reference point once you have already selected the contour. The TNC does not calculate the actual contour data until you save the selected contour in a contour program.



### Programming: Data transfer from DXF files or plain-language contours

7.1 Processing DXF Files (Software Option)

#### Selecting a reference point on a single element

- ► Select the mode for specifying the reference point
- Click the element on which you want to set the reference point with the left mouse button: The TNC indicates possible locations for reference points on the selected element with stars
- Click the star you want to select as reference point: The TNC sets the reference-point symbol to the selected location. Use the zoom function if the selected element is too small

#### Selecting a reference point on the intersection of two elements



۲

- Select the mode for specifying the reference point
- Click the first element (straight line, complete circle or circular arc) with the left mouse button: The TNC indicates possible locations for reference points on the selected element with stars
- Click the second element (straight line, complete circle or circular arc) with the left mouse button: The TNC sets the reference-point symbol on the intersection

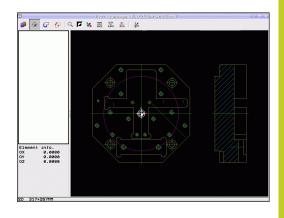
The TNC calculates the intersection of two elements even if it is on the extension of one of these elements.

If the TNC calculates multiple intersections, it selects the intersection nearest the mouse-click on the second element.

If the TNC cannot calculate an intersection, it rescinds the marking of the first element.

#### **Element information**

At the bottom left of the screen, the TNC shows how far the reference point you haven chosen is located from the drawing datum.



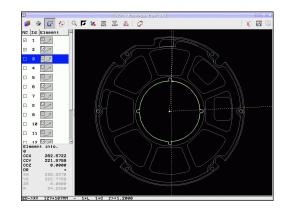
#### Selecting and saving a contour

You must use the touchpad on the TNC keyboard or a mouse attached via the USB port in order to select a contour.

If you are not using the contour program in the operating mode, you must specify the machining sequence when selecting the contour that it matches the desired machining direction.

Select the first contour element such that approach without collision is possible.

If the contour elements are very close to one another, use the zoom function.



### Programming: Data transfer from DXF files or plain-language contours

7.1 Processing DXF Files (Software Option)



- Select the mode for choosing a contour. The TNC hides the layers shown in the left window, and the right window becomes active for contour selection
- To select a contour element, click the desired contour element with the left mouse button. The selected contour element turns blue. At the same time, the TNC marks the selected element with a symbol (circle or line) in the left window
- ► To select the next contour element, click the desired contour element with the left mouse button. The selected contour element turns blue. If further contour elements in the selected machining sequence are clearly selectable, these elements turn green. Click on the last green element to assume all elements into the contour program. The TNC shows all selected contour elements in the left window. The TNC displays elements that are still green in the NC column without a check mark. The TNC does not save these elements to the contour program. You can also include the marked elements in the contour program by clicking in the left window.
- If necessary you can also deselect elements that you already selected, by clicking the element in the right window again, but this time while pressing the CTRL key. You can deselect all selected elements by clicking the recycle bin icon

If you have selected polylines, the TNC shows a twolevel ID number in the left window. The first number is the serial contour element number, the second element is the element number of the respective polyline from the DXF file.

- Save the selected contour elements to the clipboard of the TNC so that you can then insert the contour in a plain-language program, or
- ► To save the selected contour elements in a plainlanguage program, enter any file name and the target directory in the pop-up window displayed by the TNC. Default setting: Name of the DXF file. If the name of the DXF file contains special characters or spaces, the TNC replaces the characters with underscores. As an alternative, you can also select the file type: Plain-language program (.H) or contour description (.HC)



- Confirm the entry: The TNC saves the contour program to the selected directory
- If you want to select more contours, press the Cancel Selected Elements soft key and select the next contour as described above.



The TNC also transfers two workpiece-blank definitions () to the contour program. The first definition contains the dimensions of the entire DXF file. The second one, which is the active one, contains only the selected contour elements, so that an optimized size of the workpiece blank results. The TNC only saves elements that have actually been

selected (blue elements), which means that they have been given a check mark in the left window.

# Programming: Data transfer from DXF files or plain-language contours

7.1 Processing DXF Files (Software Option)

#### Dividing, extending and shortening contour elements

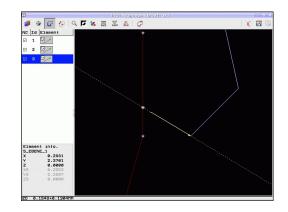
If contour elements to be selected in the drawing connect poorly, then you must first divide the contour element. This function is automatically available if you are in the mode for selecting a contour.

Proceed as follows:

- The poorly connecting contour element is selected, so it is colored blue
- Click the contour element to be divided: The TNC shows the point of intersection with a star in a circle, and the selectable end points with simple stars
- Press the CTRL key and click the point of intersection: The TNC divides the contour element at the point of intersection and the stars disappear. If there is a gap, or the elements overlap, the TNC extends or shortens these poorly connecting contour elements to the point of intersection of the two elements
- Click the divided contour element again: The TNC shows the end points and points of intersection again
- Click the desired end point: The TNC now colors the divided element blue
- Select the next contour element

If the contour element to be extended or shortened is a straight line, then the TNC extends/shortens the contour element along the same line. If the contour element to be extended or shortened is a circular arc, then the TNC extends/shortens the contour element along the same arc.

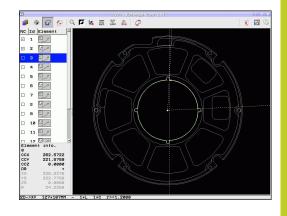
In order to use this function, at least two contour elements must already be selected, so that the direction is clearly determined.



#### **Element information**

At the bottom left of the screen, the TNC displays information about the contour element that you last selected via mouse click in the left or right window.

- End point of the straight line, and the starting point is grayed out.
- Circle center point, circle end point, and direction of rotation.
   Grayed out: the starting point and circle radius



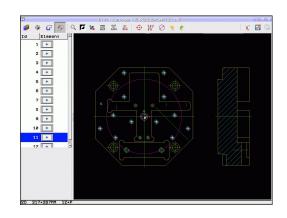
### Selecting and saving machining positions

You must use the touchpad on the TNC keyboard or a mouse attached via the USB port in order to select a machining position. If the positions to be selected are very close to one another, use the zoom function.

If required, configure the basic settings so that the TNC shows the tool paths, See "Basic settings", page 246.

Three possibilities are available in the pattern generator for defining machining positions:

- Single selection: You select the desired machining position through individual mouse clicks (See "Single selection", page 256)
- Rapid selection of hole positions with the mouse area: By dragging the mouse to define an area, you can select all the hole positions within it (Rapid selection of hole positions with the mouse area).
- Rapid selection of hole positions by entering a diameter: By entering a hole diameter, you can select all hole positions with that diameter in the DXF file (Rapid selection of hole positions by entering a diameter).



# Programming: Data transfer from DXF files or plain-language contours

7.1 Processing DXF Files (Software Option)

#### **Single selection**

	5	Ŀ,		
H	F			
			r	

 Select the mode for choosing a machining position. The TNC hides the layers shown in the left window, and the right window becomes active for position selection

- In order to select a machining position, click the desired element with the left mouse button. The TNC indicates possible locations for machining positions on the selected element with stars. Click one of the stars: The TNC loads the selected position into the left window (displays a point symbol). If you click a circle, the TNC adopts the circle center as machining position
- If necessary you can also deselect elements that you already selected, by clicking the element in the right window again, but this time while pressing the CTRL key (click inside the marked area)
- If you want to specify the machining position at the intersection of two elements, click the first element with the left mouse button: the TNC displays stars at the selectable machining positions
- Click the second element (straight line, complete circle or circular arc) with the left mouse button. The TNC loads the intersection of the elements into the left window (displays a point symbol)
- Save the selected machining positions to the clipboard of the TNC so that you can then insert them as a positioning block with cycle call in a plain-language program, or
- To save the selected machining positions to a point file, enter the target directory and any file name in the pop-up window displayed by the TNC. Default setting: Name of the DXF file. If the name of the DXF file contains special characters or spaces, the TNC replaces the characters with underscores. As an alternative, you can also select the file type: Point table (.PNT), pattern generator table (.HP) or plain-language program (.H). If you save the machining positions to a plain-language program, the TNC creates a separate linear block with cycle call for every machining position (L X... Y... M99). You can also transfer this program to old TNC controls and run it there.

Confirm the entry: The TNC saves the contour

program to the directory in which the DXF file is

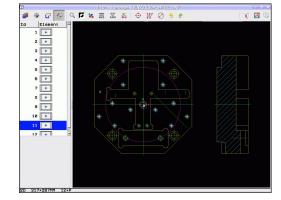
If you want to select more machining positions in order to save them to a different file, press the Cancel selected elements icon and select as

ENT

also saved

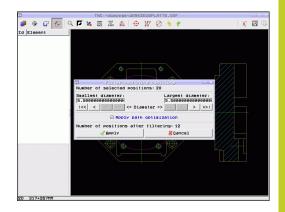
described above





#### Rapid selection of hole positions with the mouse area

- ۲
- Select the mode for choosing a machining position. The TNC hides the layers shown in the left window, and the right window becomes active for position selection
- Press the shift key on the keyboard and drag the left mouse button to define an area in which the TNC is to adopt all included circle centers as hole positions: the TNC opens a window in which you can filter the holes by size
- Configure the filter settings See "" and click the Use button to confirm: The TNC loads the selected positions into the left window (displays a point symbol)
- If necessary you can also deselect elements that you already selected, by dragging an area open again, but this time while pressing the CTRL key
- Save the selected machining positions to the clipboard of the TNC so that you can then insert them as a positioning block with cycle call in a plain-language program, or
- To save the selected machining positions to a point file, enter the target directory and any file name in the pop-up window displayed by the TNC. Default setting: Name of the DXF file. If the name of the DXF file contains special characters or spaces, the TNC replaces the characters with underscores. As an alternative, you can also select the file type: Point table (.PNT), pattern generator table (.HP) or plain-language program (.H). If you save the machining positions to a plain-language program, the TNC creates a separate linear block with cycle call for every machining position (L X... Y... M99). You can also transfer this program to old TNC controls and run it there.
- Confirm the entry: The TNC saves the contour program to the directory in which the DXF file is also saved
- If you want to select more machining positions in order to save them to a different file, press the Cancel selected elements icon and select as described above





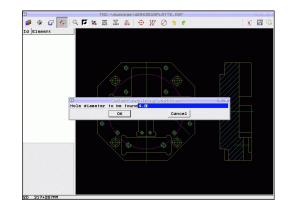
# Programming: Data transfer from DXF files or plain-language contours

7.1 Processing DXF Files (Software Option)

#### Rapid selection of hole positions by entering a diameter



- Select the mode for choosing a machining position. The TNC hides the layers shown in the left window, and the right window becomes active for position selection
- Open the dialog for diameter input: enter any diameter in the pop-up window displayed by the TNC
- Enter the desired diameter and confirm it with the ENT key: the TNC searches the DXF file for the entered diameter and then shows a popup window with the diameter selected that is closest to the diameter you entered. Also, you can retroactively filter the holes according to size
- If required, configure the filter settings See "" and click the Use button to confirm: The TNC loads the selected positions into the left window (displays a point symbol)
- If necessary you can also deselect elements that you already selected, by dragging an area open again, but this time while pressing the CTRL key
- Save the selected machining positions to the clipboard of the TNC so that you can then insert them as a positioning block with cycle call in a plain-language program, or
- To save the selected machining positions to a point file, enter the target directory and any file name in the pop-up window displayed by the TNC. Default setting: Name of the DXF file. If the name of the DXF file contains special characters or spaces, the TNC replaces the characters with underscores. As an alternative, you can also select the file type: Point table (.PNT), pattern generator table (.HP) or plain-language program (.H). If you save the machining positions to a plain-language program, the TNC creates a separate linear block with cycle call for every machining position (L X... Y... M99). You can also transfer this program to old TNC controls and run it there.
- Confirm the entry: The TNC saves the contour program to the directory in which the DXF file is also saved
- If you want to select more machining positions in order to save them to a different file, press the Cancel selected elements icon and select as described above







ENT



# Processing DXF Files (Software Option) 7.1

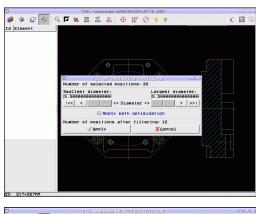
# Filter settings

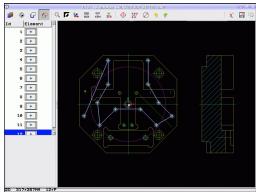
After you have used the quick selection function to mark hole positions, a pop-up window appears in which the smallest diameter found is to the left and the largest diameter to the right. With the buttons just below the diameter display you can adjust the smallest diameter in the left area and largest in the right area so that you can load the hole diameters that you want.

#### The following buttons are available:

Filter setting of smallest diameter	Button
Display the smallest diameter found (default setting)	1<<
Display the next smaller diameter found	<
Display the next larger diameter found	>
Display the largest diameter found. The TNC sets the filter for the smallest diameter to the value set for the largest diameter	>>
Filter setting of largest diameter	Button
<b>Filter setting of largest diameter</b> Display the smallest diameter found. The TNC sets the filter for the largest diameter to the value set for the smallest diameter	Button
Display the smallest diameter found. The TNC sets the filter for the largest diameter to the	Button <<
Display the smallest diameter found. The TNC sets the filter for the largest diameter to the value set for the smallest diameter	Button << </td

With the **apply path optimization** option on (default setting), the TNC sorts the selected machining positions for the most efficient possible tool path. You can have the tool path displayed by clicking the Show tool path icon, See "Basic settings", page 246.



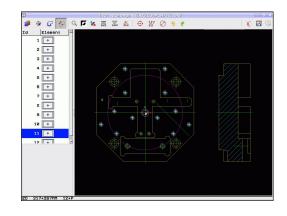


# Programming: Data transfer from DXF files or plain-language contours

7.1 Processing DXF Files (Software Option)

#### **Element information**

At the bottom left of the screen, the TNC displays the coordinates of the machining position that you last selected via mouse click in the left or right window



#### **Undoing actions**

You can undo the four most recent actions that you have taken in the mode for selecting machining positions. The following icons are available:

#### Function

Button

Undo the most recently conducted action	<b>1</b>
Repeat the most recently conducted action	<i>è</i>

#### **Mouse functions**

Use the mouse for magnifying and reducing as follows:

- Define the zoom area by dragging the mouse with the left button depressed
- If you have a wheel mouse, you can use it to zoom in and out. The zooming center is the location of the mouse pointer
- Click the magnifying glass icon or double-click with the right mouse button to reset the view to the default setting

You can move the current view by depressing the center mouse button.

If 3-D mode is active, you can rotate and tilt the view by depressing the right mouse button.



8.1 Labeling Subprograms and Program Section Repeats

# 8.1 Labeling Subprograms and Program Section Repeats

Subprograms and program section repeats enable you to program a machining sequence once and then run it as often as necessary.

# Label

8

The beginnings of subprograms and program section repeats are marked in a part program by labels **(LBL)**.

A LABEL is identified by a number between 1 and 999 or by a name you define. Each LABEL number or LABEL name can be set only once in the program with the LABEL SET. The number of label names you can enter is only limited by the internal memory.



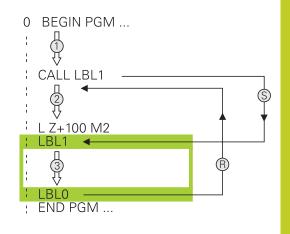
Do not use a label number or label name more than once!

Label 0 (**LBL 0**) is used exclusively to mark the end of a subprogram and can therefore be used as often as desired.

# 8.2 Subprograms

# **Operating sequence**

- 1 The TNC executes the part program up to calling a subprogram, **CALL LBL**.
- 2 The subprogram is then executed from beginning to end,  $\mbox{LBL 0}.$
- 3 The TNC then resumes the part program from the block after the subprogram call **CALL LBL**



### **Programming notes**

- A main program can contain up to 254 subprograms
- You can call subprograms in any sequence and as often as desired
- A subprogram cannot call itself
- Write subprograms at the end of the main program (behind the block with M2 or M30)
- If subprograms are located before the block with M2 or M30, they will be executed at least once even if they are not called

# Programming a subprogram

- LBL SET
- To mark the beginning, press the LBL SET key
- Enter the subprogram number. If you want to use a label name, press the LBL NAME soft key to switch to text entry
- To mark the end, press the LBL SET key and enter the label number "0"

8.2 Subprograms

#### Calling a subprogram



- ▶ To call a subprogram, press the LBL CALL key
- Label number: Enter the label number of the subprogram you wish to call. If you want to use a label name, press the LBL NAME soft key to switch to text entry. If you want to enter the number of a string parameter as target address: Press the QS soft key; the TNC will then jump to the label name that is specified in the string parameter defined
- Repeat REP: Ignore the dialog question with the NO ENT key. Repeat REP is used only for program section repeats.

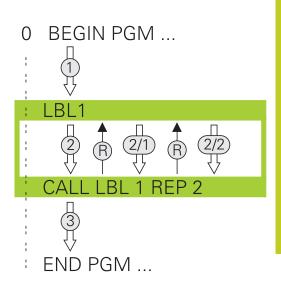


**CALL LBL 0** is not permitted (Label 0 is only used to mark the end of a subprogram).

# 8.3 **Program-section repeats**

### Label LBL

The beginning of a program section repeat is marked by the label LBL. The end of a program section repeat is identified by CALL LBL n REPn.



### **Operating sequence**

- 1 The TNC executes the part program up to the end of the program section (CALL LBL n REPn)
- 2 Then the program section between the called LABEL and the label call **CALL LBL n REPn** is repeated the number of times entered after **REP**
- 3 The TNC resumes the part program after the last repetition.

### **Programming notes**

- You can repeat a program section up to 65 534 times in succession
- The total number of times the program section is executed is always one more than the programmed number of repeats

### Programming a program section repeat

- LBL SET
- To mark the beginning, press the LBL SET key and enter a LABEL NUMBER for the program section you wish to repeat. If you want to use a label name, press the LBL NAME soft key to switch to text entry
- ▶ Enter the program section

8

8.3 Program-section repeats

#### Calling a program section repeat



- Press the LBL CALL key
- ► To call subprograms/section repeats: Enter the label number of the subprogram to be called, then confirm with the ENT key. If you want to use a label name, press the " key to switch to text entry If you want to enter the number of a string parameter as target address: Press the QS soft key; the TNC will then jump to the label name that is specified in the string parameter defined
- Repeat REP: Enter the number of repeats, then confirm with the ENT key

# 8.4 Any desired program as subprogram

### **Operating sequence**

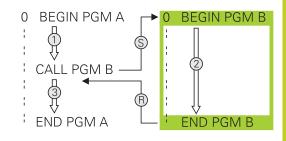


If you want to program variable program calls in connection with string parameters, use the SEL PGM function.

- 1 The TNC executes the part program up to the block in which another program is called with **CALL PGM**.
- 2 Then the other program is run from beginning to end.
- 3 The TNC then resumes the first part program (i.e. the calling program) with the block after the program call.

### **Programming notes**

- No labels are needed to call any program as a subprogram
- The called program must not contain the miscellaneous functions M2 or M30. If you have defined subprograms with labels in the called program, you can then use M2 or M30 with the FN 9: IF +0 EQU +0 GOTO LBL 99 jump function to force a jump over this program section
- The called program must not contain a CALL PGM call into the calling program, otherwise an infinite loop will result



8.4 Any desired program as subprogram

### Calling any program as a subprogram



8

- Select the functions for program call: Press the PGM CALL key
- PROGRAM
- Press the PROGRAM soft key for the TNC to start the dialog for defining the program to be called. Use the screen keyboard to enter the path name (GOTO key), or

SELECT PROGRAM

 press the SELECT PROGRAM soft key for the TNC to display a selection window in which you can select the program to be called. Confirm with the END key

If the program you want to call is located in the same directory as the program you are calling it from, then you only need to enter the program name.

If the called program is not located in the same directory as the program you are calling it from, you must enter the complete path, e.g. **TNC: \ZW35\SCHRUPP\PGM1.H** 

If you want to call a DIN/ISO program, enter the file type .I after the program name.

You can also call a program with Cycle **12 PGM CALL**.

As a rule, Q parameters are effective globally with a **PGM CALL**. So please note that changes to Q parameters in the called program can also influence the calling program.



### Danger of collision!

Coordinate transformations that you define in the called program remain in effect for the calling program too, unless you reset them.

# 8.5 Nesting

## **Types of nesting**

- Subprograms within a subprogram
- Program section repeats within a program section repeat
- Subprograms repeated
- Program section repeats within a subprogram

# Nesting depth

The nesting depth is the number of successive levels in which program sections or subprograms can call further program sections or subprograms.

- Maximum nesting depth for subprograms: 19
- Maximum nesting depth for main program calls: 19, where a CYCL CALL acts like a main program call
- You can nest program section repeats as often as desired

8.5 Nesting

8

### Subprogram within a subprogram

Example NC blocks

0 BEGIN PGM UPGMS MM		
17 CALL LBL "UP1"	Call the subprogram marked with LBL SP1	
35 L Z+100 R0 FMAX M2	Last program block of the main program (with M2)	
36 LBL "UP1"	Beginning of subprogram SP1	
39 CALL LBL 2	Call the subprogram marked with LBL 2	
45 LBL 0	End of subprogram 1	
46 LBL 2	Beginning of subprogram 2	
62 LBL 0	End of subprogram 2	
63 END PGM UPGMS MM		

#### **Program execution**

- 1 Main program UPGMS is executed up to block 17.
- 2 Subprogram SP1 is called, and executed up to block 39.
- 3 Subprogram 2 is called, and executed up to block 62. End of subprogram 2 and return jump to the subprogram from which it was called.
- 4 Subprogram 1 is called, and executed from block 40 up to block 45. End of subprogram 1 and return jump to the main program UPGMS.
- 5 Main program UPGMS is executed from block 18 up to block 35. Return jump to block 1 and end of program.

# **Repeating program section repeats**

#### **Example NC blocks**

0 BEGIN PGM REPS MM	
15 LBL 1	Beginning of program section repeat 1
20 LBL 2	Beginning of program section repeat 2
27 CALL LBL 2 REP 2	The program section between LBL 2 and this block
	(block 20) is repeated twice
35 CALL LBL 1 REP 1	The program section between LBL 1 and this block
	(block 15) is repeated once
50 END PGM REPS MM	

#### **Program execution**

- 1 Main program REPS is executed up to block 27.
- 2 Program section between block 27 and block 20 is repeated twice.
- 3 Main program REPS is executed from block 28 to block 35.
- 4 Program section between block 35 and block 15 is repeated once (including the program section repeat between 20 and block 27).
- 5 Main program REPS is executed from block 36 to block 50 (end of program).

8.5 Nesting

8

# Repeating a subprogram

### Example NC blocks

0 BEGIN PGM UPGREP MM	
10 LBL 1	Beginning of program section repeat 1
11 CALL LBL 2	Subprogram call
12 CALL LBL 1 REP 2	The program section between LBL 1 and this block
	(block 10) is repeated twice
19 L Z+100 R0 FMAX M2	Last block of the main program with M2
20 LBL 2	Beginning of subprogram
28 LBL 0	End of subprogram
29 END PGM UPGREP MM	

#### **Program execution**

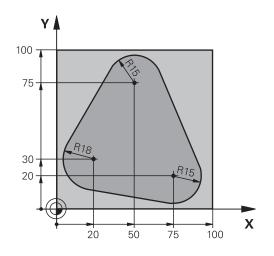
- 1 Main program UPGREP is executed up to block 11.
- 2 Subprogram 2 is called and executed.
- 3 Program section between block 12 and block 10 is repeated twice. This means that subprogram 2 is repeated twice.
- 4 Main program UPGREP is executed from block 13 to block 19. End of program.

# 8.6 Programming examples

# Example: Milling a contour in several infeeds

Program sequence:

- Pre-position the tool to the workpiece surface
- Enter the infeed depth in incremental values
- Contour milling
- Repeat infeed and contour-milling



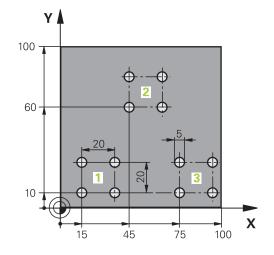
0 BEGIN PGM PGMWDH MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL CALL 1 Z S500	Tool call
4 L Z+250 R0 FMAX	Retract the tool
5 L X-20 Y+30 R0 FMAX	Pre-position in the working plane
6 L Z+0 RO FMAX M3	Pre-position to the workpiece surface
7 LBL 1	Set label for program section repeat
8 L IZ-4 R0 FMAX	Infeed depth in incremental values (in space)
9 APPR CT X+2 Y+30 CCA90 R+5 RL F250	Contour approach
10 FC DR- R18 CLSD+ CCX+20 CCY+30	Contour
11 FLT	
12 FCT DR- R15 CCX+50 CCY+75	
13 FLT	
14 FCT DR- R15 CCX+75 CCY+20	
15 FLT	
16 FCT DR- R18 CLSD- CCX+20 CCY+30	
17 DEP CT CCA90 R+5 F1000	Contour departure
18 L X-20 Y+0 R0 FMAX	Retract tool
19 CALL LBL 1 REP 4	Return jump to LBL 1; section is repeated a total of 4 times
20 L Z+250 R0 FMAX M2	Retract the tool, end program
21 END PGM PGMWDH MM	

8.6 **Programming examples** 

## **Example: Groups of holes**

Program sequence:

- Approach the groups of holes in the main program
- Call the group of holes (subprogram 1)
- Program the group of holes only once in subprogram 1

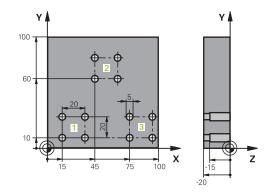


0 BEGIN PGM UP1	MM		
1 BLK FORM 0.1 Z X+0 Y+0 Z-20			
2 BLK FORM 0.2 X+100 Y+100 Z+0			
3 TOOL CALL 1 Z S5000		Tool call	
4 L Z+250 R0 FMAX		Retract the tool	
5 CYCL DEF 200 DRILLING		Define the DRILLING cycle	
Q200=2	;SET-UP CLEARANCE		
Q201=-10	;DEPTH		
Q206=250	;FEED RATE FOR PLNGNG		
Q202=5	;PLUNGING DEPTH		
Q210=0	;DWELL TIME AT TOP		
Q203=+0	;SURFACE COORDINATE		
Q204=10	;2ND SET-UP CLEARANCE		
Q211=0.25	;DWELL TIME AT BOTTOM		
6 L X+15 Y+10 R0	FMAX M3	Move to starting point for group 1	
7 CALL LBL 1		Call the subprogram for the group	
8 L X+45 Y+60 R0	FMAX	Move to starting point for group 2	
9 CALL LBL 1		Call the subprogram for the group	
10 L X+75 Y+10 R	0 FMAX	Move to starting point for group 3	
11 CALL LBL 1		Call the subprogram for the group	
12 L Z+250 R0 FM	AX M2	End of main program	
13 LBL 1		Beginning of subprogram 1: Group of holes	
14 CYCL CALL		Hole 1	
15 L IX+20 R0 FMAX M99		Move to 2nd hole, call cycle	
16 L IY+20 R0 FM	AX M99	Move to 3rd hole, call cycle	
17 L IX-20 R0 FM4	AX M99	Move to 4th hole, call cycle	
18 LBL 0		End of subprogram 1	
19 END PGM UP1	MM		

# Example: Group of holes with several tools

Program sequence:

- Program the fixed cycles in the main program
- Call the entire hole pattern (subprogram 1)
- Approach the groups of holes in subprogram 1, call group of holes (subprogram 2)
- Program the group of holes only once in subprogram
   2



0 BEGIN PGM UP2 A	MM		
1 BLK FORM 0.1 Z X+0 Y+0 Z-20			
2 BLK FORM 0.2 X+100 Y+100 Z+0			
3 TOOL CALL 1 Z S5000		Call tool: center drill	
4 L Z+250 R0 FMAX		Retract the tool	
5 CYCL DEF 200 DRILLING		Define the CENTERING cycle	
Q200=2	;SET-UP CLEARANCE		
Q202=-3	;DEPTH		
Q206=250	;FEED RATE FOR PLNGNG		
Q202=3	;PLUNGING DEPTH		
Q210=0	;DWELL TIME AT TOP		
Q203=+0	;SURFACE COORDINATE		
Q204=10	;2ND SET-UP CLEARANCE		
Q211=0.25	;DWELL TIME AT BOTTOM		
6 CALL LBL 1		Call subprogram 1 for the entire hole pattern	
7 L Z+250 R0 FMAX	( M6	Tool change	
8 TOOL CALL 2 Z S	4000	Call tool: drill	
9 FN 0: Q201 = -25		New depth for drilling	
10 FN 0: Q202 = +5		New plunging depth for drilling	
11 CALL LBL 1		Call subprogram 1 for the entire hole pattern	
12 L Z+250 R0 FMAX M6		Tool change	
13 TOOL CALL 3 Z S500		Call tool: reamer	

# 8.6 **Programming examples**

14 CYCL DEF 201 RE	AMING	Cycle definition: REAMING	
Q200=2	;SET-UP CLEARANCE		
Q201=-15	;DEPTH		
Q206=250	;FEED RATE FOR PLNGNG		
Q211=0.5	;DWELL TIME AT DEPTH		
Q208=400	;RETRACTION FEED RATE		
Q203=+0	;SURFACE COORDINATE		
Q204=10	;2ND SET-UP CLEARANCE		
15 CALL LBL 1		Call subprogram 1 for the entire hole pattern	
16 L Z+250 R0 FMAX	ά M2	End of main program	
17 LBL 1		Beginning of subprogram 1: Entire hole pattern	
18 L X+15 Y+10 R0 F	FMAX M3	Move to starting point for group 1	
19 CALL LBL 2		Call subprogram 2 for the group	
20 L X+45 Y+60 R0 FMAX		Move to starting point for group 2	
21 CALL LBL 2		Call subprogram 2 for the group	
22 L X+75 Y+10 R0 FMAX		Move to starting point for group 3	
23 CALL LBL 2		Call subprogram 2 for the group	
24 LBL 0		End of subprogram 1	
25 LBL 2		Beginning of subprogram 2: Group of holes	
26 CYCL CALL		1st hole with active fixed cycle	
27 L IX+20 R0 FMAX	M99	Move to 2nd hole, call cycle	
28 L IY+20 R0 FMAX	M99	Move to 3rd hole, call cycle	
29 L IX-20 R0 FMAX	M99	Move to 4th hole, call cycle	
30 LBL 0		End of subprogram 2	
31 END PGM UP2 MM			

Programming: Q Parameters

# Programming: Q Parameters

9.1 Principle and overview of functions

# 9.1 Principle and overview of functions

You can program entire families of parts in a single part program. You do this by entering variables called Q parameters instead of fixed numerical values.

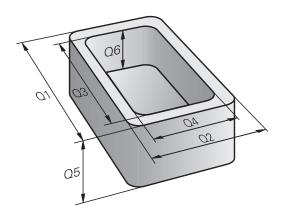
Q parameters can represent information such as:

- Coordinate values
- Feed rates
- Spindle speeds
- Cycle data

Q parameters also enable you to program contours that are defined with mathematical functions. You can also use Q parameters to make the execution of machining steps depend on logical conditions. In conjunction with FK programming you can also combine contours that do not have NC-compatible dimensions with Q parameters.

Q parameters are designated by letters and a number between 0 and 1999. Parameters that take effect in different manners are available. Please refer to the following table:

Meaning	Range
Freely applicable parameters, as long as no overlapping with SL cycles can occur. They are globally effective for all programs stored in the TNC memory.	<b>Q0</b> to <b>Q99</b>
Parameters for special TNC functions	Q100 to Q199
Parameters that are primarily used for cycles, globally effective for all programs stored in the TNC memory	Q200 to Q1199
Parameters that are primarily used for OEM cycles, and are globally effective for all programs stored in the TNC memory. This may require coordination with the machine manufacturer or supplier	Q1200 to Q1399
Parameters that are primarily used for <b>call-active</b> OEM cycles, globally effective for all programs that are stored in the TNC memory	Q1400 to Q1499
Parameters that are primarily used for <b>Def-active</b> OEM cycles, globally effective for all programs that are stored in the TNC memory	Q1500 to Q1599



9

Meaning	Range
Freely applicable parameters, globally effective for all programs stored in the TNC memory	Q1600 to Q1999
Freely usable <b>QL</b> parameters, only effective locally (within a program)	<b>QL0</b> to <b>QL499</b>
Freely usable <b>QR</b> parameters that are nonvolatile, i.e. they <b>r</b> emain in effect even after a power interruption	<b>QR0</b> to <b>QR499</b>

**QS** parameters (the **S** stands for string) are also available on the TNC and enable you to process texts. In principle, the same ranges are available for **QS** parameters as for Q parameters (see table above).



Note that for the **QS** parameters the **QS100** to **QS199** range is reserved for internal texts.

Local parameters QL are only effective within the respective program, and are not applied as part of program calls or macros.

### **Programming notes**

You can mix Q parameters and fixed numerical values within a program.

Q parameters can be assigned numerical values between -999 999 999 and +999 999 999. The input range is limited to 15 digits, of which 9 may be before the decimal point. Internally the TNC calculates numbers up to a value of 10<sup>10</sup>.

You can assign a maximum of 254 characters to **QS** parameters.



Some Q and QS parameters are always assigned the same data by the TNC. For example, **Q108** is always assigned the current tool radius (See "Preassigned Q parameters").

The TNC saves numerical values internally in a binary number format (standard IEEE 754). Due to this standardized format some decimal numbers do not have an exact binary representation (round-off error). Keep this in mind especially when you use calculated Q-parameter contents for jump commands or positioning movements.

# Programming: Q Parameters

9

9.1 Principle and overview of functions

### **Calling Q parameter functions**

When you are writing a part program, press the "Q" key (in the numeric keypad for numerical input and axis selection, below the +/- key). The TNC then displays the following soft keys:

Function group	Soft key	Page
Basic arithmetic (assign, add, subtract, multiply, divide, square root)	BASIC ARITHM.	282
Trigonometric functions	TRIGO- NOMETRY	284
Function for calculating circles	CIRCLE CALCU- LATION	285
lf/then conditions, jumps	JUMP	286
Other functions	DIVERSE	290
Entering formulas in the part program	FORMULA	321
Function for machining complex contours	CONTOUR FORMULA	See User's Manual for Cycles

The TNC shows the soft keys Q, QL and QR when you are defining or assigning a Q parameter. First press one of these soft keys to select the desired type of parameter, and then enter the parameter number.

If you have a USB keyboard connected, you can press the Q key to open the dialog for entering a formula.

# 9.2 Part families—Q parameters in place of numerical values

### Application

The Q parameter function **FN 0: ASSIGN** assigns numerical values to Q parameters. This enables you to use variables in the program instead of fixed numerical values.

#### **Example NC blocks**

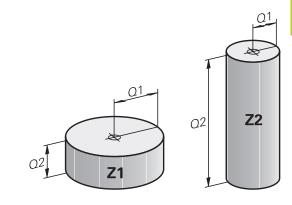
15 FN 0: Q10=25	Assign
	Q10 is assigned the value 25
25 L X +Q10	Means L X +25

You need write only one program for a whole family of parts, entering the characteristic dimensions as Q parameters.

To program a particular part, you then assign the appropriate values to the individual Q parameters.

#### Example: Cylinder with Q parameters

Cylinder radius:	R = Q1
Cylinder height:	H = Q2
Cylinder Z1:	Q1 = +30 Q2 = +10
Cylinder Z2:	Q1 = +10 Q2 = +50



# Programming: Q Parameters

9.3 Describing contours with mathematical functions

# 9.3 Describing contours with mathematical functions

# Application

9

The  $\ensuremath{\Omega}$  parameters listed below enable you to program basic mathematical functions in a part program:

- Select a Q-parameter function: Press the Q key (in the numerical keypad at right). The Q-parameter functions are displayed in a soft-key row
- Select the mathematical functions: Press the BASIC ARITHMETIC soft key. The TNC then displays the following soft keys:

### **Overview**

Function	Soft key
FN 0: ASSIGN e.g. FN 0: Q5 = +60 Directly assign value	FNØ X = Y
<b>FN 1</b> : ADDITION z.B. <b>FN 1: Q1 = -Q2 + -5</b> Form and assign sum from two values	FN1 X + Y
<b>FN 2</b> : SUBTRACTION e.g. <b>FN 2: Q1 = +10 - +5</b> Form and assign difference between two values	FN2 X - Y
FN 3: MULTIPLICATION e.g. FN 3: Q2 = +3 * +3 Form and assign the product of two values	FN3 X * Y
<b>FN 4</b> : DIVISION e.g. <b>FN 4</b> : <b>Q4 = +8 DIV +Q2</b> Form and assign the quotient of two values <b>Not</b> <b>permitted:</b> Division by 0	FN4 X / Y
<b>FN 5</b> : SQUARE ROOT e.g. <b>FN 5</b> : <b>Q20 = SQRT 4</b> Form and assign the square root of a value <b>Not</b> <b>permitted:</b> Square root from negative value	FN5 SQRT

To the right of the "=" character you can enter the following:

- Two numbers
- Two Q parameters
- A number and a Q parameter

The Q parameters and numerical values in the equations can be entered with positive or negative signs.

### **Programming fundamental operations**

### Example 1



- Select the Q parameter functions: Press the Q key
- Select the mathematical functions: Press the BASIC ARITHMETIC soft key
- Select the Q parameter function ASSIGN: Press the FN0 X = Y soft key

#### PARAMETER NUMBER FOR RESULT?



 12 Enter the Q parameter number and confirm with the ENT key

#### FIRST VALUE / PARAMETER?

- ENT
- Enter 10: Assign the numerical value 10 to Q5 and confirm with the ENT soft key.

#### Example 2



- Select the Q parameter functions: Press the Q key
- BASIC ARITHM. FN3

X \* Y

- Select the mathematical functions: Press the BASIC ARITHMETIC soft key
- To select the Q parameter function MULTIPLICATION, press the FN3 X \* Y soft key

#### PARAMETER NUMBER FOR RESULT?



12 Enter the Q parameter number and confirm with the ENT key

#### FIRST VALUE / PARAMETER?



Enter Q5 as the first value and confirm with the ENT key.

#### SECOND VALUE / PARAMETER?



Enter 7 as the second value and confirm with the ENT key.

#### Program blocks in the TNC

16	FN	0:	Q5 = +10
17	FN	3.	012 = +05 * +7

# **Programming: Q Parameters**

**Angle functions (trigonometry)** 9.4

#### **Angle functions (trigonometry)** 9.4

 $\tan \alpha = a / b = \sin \alpha / \cos \alpha$ 

### **Definitions**

Sine:  $\sin \alpha = a / c$ 

Cosine:

Tangent:

 $\cos \alpha = b / c$ 

9

where

- c is the side opposite the right angle
- a is the side opposite the angle  $\alpha$
- b is the third side.

The TNC can find the angle from the tangent:  $\alpha$  = arctan (a / b) = arctan (sin  $\alpha$  / cos  $\alpha$ )

#### **Example:**

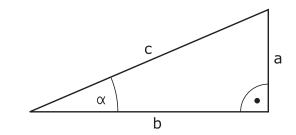
a = 25 mm b = 50 mm  $\alpha$  = arctan (a / b) = arctan 0.5 = 26.57° Furthermore:  $a^{2} + b^{2} = c^{2}$  (where  $a^{2} = a \times a$ )  $c = \sqrt{(a^2 + b^2)}$ 

# **Programming trigonometric functions**

Press the ANGLE FUNCTION soft key to call the trigonometric functions. The TNC then displays the soft keys below. Programming: Compare "Example: Programming fundamental operations."

Function	Soft key
FN 6: SINE e.g. FN 6: Q20 = SIN-Q5 Define and assign the sine of an angle in degrees (°)	FN6 SIN(X)
<b>FN 7</b> : COSINE e.g. <b>FN 7: Q21 = COS-Q5</b> Define and assign the cosine of an angle in degrees (°)	D7 COS(X)
<b>FN 8</b> : SQUARE ROOT FROM SQUARE SUM e.g. <b>FN 8: Q10 = +5 LEN +4</b> Form and assign length from two values	FN8 X LEN Y
<b>FN 13</b> : ANGLE e.g. <b>FN 13</b> : <b>Q20 = +25 ANG-Q1</b> Form and assign an angle with arctan from two sides or with sine and cosine of the angle (0 <	FN13 X ANG Y

angle < 360°)



#### Calculation of circles 9.5

# Application

The TNC can use the functions for calculating circles to calculate the circle center and the circle radius from three or four given points on the circle. The calculation is more accurate if four points are used.

Application: These functions can be used if you wish to determine the location and size of a hole or a pitch circle using the programmable probing function.

#### Function

Soft key FN23 3 POINTS

CIRCLE

FN23: Determining the CIRCLE DATA from three points

#### e.g. FN 23: Q20 = CDATA Q30

The coordinate pairs of three points on a circle must be saved in Q30 and the following five parameters—in this case, up to Q35.

The TNC then saves the circle center in the reference axis (X if spindle axis is Z) in parameter Q20, the circle center in the minor axis (Y if spindle axis is Z) in parameter Q21, and the circle radius in parameter Q22.

Function	Soft key
FN24: Determining the CIRCLE DATA from four points	FN24 4 POINTS OF CIRCLE
e.g. FN 24: Q20 = CDATA Q30	

The coordinate pairs of four points on a circle must be saved in Q30 and the following seven parameters-in this case, up to Q37.

The TNC then saves the circle center in the reference axis (X if spindle axis is Z) in parameter Q20, the circle center in the minor axis (Y if spindle axis is Z) in parameter Q21, and the circle radius in parameter Q22.



Note that FN 23 and FN 24 automatically overwrite the resulting parameter and the two following parameters.

# Programming: Q Parameters

9.6 If-then decisions with Q parameters

# 9.6 If-then decisions with Q parameters

### Application

9

The TNC can make logical if-then decisions by comparing a Q parameter with another Q parameter or with a numerical value. If the condition is fulfilled, the TNC continues the program at the label that is programmed after the condition (for information on labels, See "Labeling Subprograms and Program Section Repeats", page 262). If it is not fulfilled, the TNC continues with the next block.

To call another program as a subprogram, enter a **PGM CALL** program call after the block with the target label.

### **Unconditional jumps**

An unconditional jump is programmed by entering a conditional jump whose condition is always true. Example:

FN 9: IF+10 EQU+10 GOTO LBL1

### **Programming if-then decisions**

Press the JUMP soft key to call the if-then conditions. The TNC then displays the following soft keys:

Function	Soft key
FN 9: IF EQUAL TO, JUMP e.g. FN 9: IF +Q1 EQU +Q3 GOTO LBL "UPCAN25" If both values or parameters are equal, jump to specified label	FN9 IF X EQ Y GOTO
<b>FN 10</b> : IF NOT EQUAL TO, JUMP e.g. <b>FN 10: IF +10 NE -Q5 GOTO LBL 10</b> If both values or parameters are not equal, jump to specified label	FN10 IF X NE Y GOTO
<b>FN 11</b> : IF GREATER, JUMP e.g. <b>FN 11: IF+Q1 GT+10 GOTO LBL 5</b> If the first value or parameter is greater than the second value or parameter, jump to specified label	FN11 IF X GT Y GOTO
<b>FN 12</b> : IF SMALLER, JUMP e.g. <b>FN 12</b> : <b>IF+Q5 LT+0 GOTO LBL "ANYNAME"</b> If the first value or parameter is smaller than the second value or parameter, jump to specified label	FN12 IF X LT Y GOTO

#### If-then decisions with Q parameters 9.6

# Abbreviations used:

IF	:	lf
EQU	:	Equal to
NE	:	Not equal
GT	:	Greater than
LT	:	Less than
GOTO	:	Go to

# Programming: Q Parameters

9.7 Checking and changing Q parameters

# 9.7 Checking and changing Q parameters

### Procedure

9

You can check Q parameters in all operating modes (when writing, testing and running programs) and also edit them.

If you are in a program run, interrupt it if required (for example, by pressing the machine STOP button and the INTERNAL STOP soft key). If you are in a test run, interrupt it.

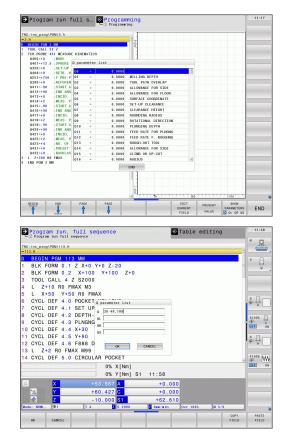


- Call Q-parameter functions: Press the Q INFO soft key or the Q key.
- The TNC lists all parameters and their current values. Use the arrow keys or the GOTO key to select the desired parameter.
- If you would like to change the value, press the EDIT CURRENT FIELD soft key, enter the new value, and confirm with the ENT key.
- To leave the value unchanged, press the PRESENT VALUE soft key or end the dialog with the END key.



The parameters used by the TNC internally or in cycles are provided with comments.

If you want to check or edit local, global or string parameters, press the SHOW PARAMETERS Q QL QR QS soft key. The TNC then displays the specific parameter type. The functions previously described also apply.



You can have the Q parameters be shown in the additional status display in the Manual, El. Handwheel, Single Block, Full Sequence and Test Run operating modes.

If you are in a program run, interrupt it if required (for example, by pressing the machine STOP button and the INTERNAL STOP soft key). If you are in a test run, interrupt it.



- Call the soft-key row for screen layout
- PROGRAM + STATUS
- Select the screen layout with additional status display: In the right half of the screen, the TNC shows the **Overview** status form
- STATUS OF Q PARAM. Q PARAMETER LIST
- Press the STATUS OF Q PARAM. soft key
- Press the Q PARAMETER LIST soft key
- The TNC opens a pop-up window in which you can enter the desired range for display of the Q parameters or string parameters. Multiple Q parameters are entered separated by commas (e.g. Q 1,2,3,4). To define display ranges, enter a hyphen (e.g. Q 10-14).

9.8 Additional functions

# 9.8 Additional functions

### **Overview**

Press the DIVERSE FUNCTION soft key to call the additional functions. The TNC then displays the following soft keys:

Function	Soft key	Page
<b>FN 14:ERROR</b> Displaying error messages	FN14 ERROR=	291
<b>FN 16:F-PRINT</b> Output of formatted texts or Q parameter values	FN16 F-PRINT	295
FN 18:SYS-DATUM READ Reading system data	FN18 SYS-DATUM READ	299
<b>FN 19:PLC</b> Transfer values to the PLC	FN19 PLC=	308
<b>FN 20:WAIT FOR</b> NC and PLC synchronization	FN20 WAIT FOR	308
<b>FN 29:PLC</b> Transfer up to eight values to the PLC	FN29 PLC LIST=	310
<b>FN 37:EXPORT</b> Export local Q parameters or QS parameters into a calling program	FN37 EXPORT	310
<b>FN 26:TABOPEN</b> Opening a freely definable table	FN26 OPEN TABLE	405
<b>FN 27:TABWRITE</b> Write to a freely definable table	FN27 WRITE TO TABLE	406
FN 28:TABREAD Read from a freely definable table	FN28 READ FROM TABLE	407

### FN 14: ERROR: Displaying error messages

With the function **FN 14: ERROR** you can call messages under program control. The messages are predefined by the machine tool builder or by HEIDENHAIN. Whenever the TNC comes to a block with **FN 14** in the Program Run or Test Run mode, it interrupts the program run and displays a message. The program must then be restarted. The error numbers are listed in the table below.

Range of error numbers	Standard dialog text
0 999	Machine-dependent dialog
1000 1199	Internal error messages (see table at right)

#### **Example NC block**

The TNC is to display the text stored under error number 254:

180 FN 14:ERROR = 254

#### Error message predefined by HEIDENHAIN

Error number	Text		
1000	Spindle?		
1001	Tool axis is missing		
1002	Tool radius too small		
1003	Tool radius too large		
1004	Range exceeded		
1005	Start position incorrect		
1006	ROTATION not permitted		
1007	SCALING FACTOR not permitted		
1008	MIRROR IMAGE not permitted		
1009	Datum shift not permitted		
1010	Feed rate is missing		
1011	Input value incorrect		
1012	Incorrect sign		
1013	Entered angle not permitted		
1014	Touch point inaccessible		
1015	Too many points		
1016	Contradictory input		
1017	CYCL incomplete		
1018	Plane wrongly defined		
1019	Wrong axis programmed		
1020	Wrong rpm		
1021	Radius comp. undefined		
1022	Rounding-off undefined		
1023	Rounding radius too large		
1024	Program start undefined		
1025	Excessive nesting		

Error number	Text		
1026	Angle reference missing		
1027	No fixed cycle defined		
1028	Slot width too small		
1029	Pocket too small		
1030	Q202 not defined		
1031	Q205 not defined		
1032	Q218 must be greater than Q219		
1033	CYCL 210 not permitted		
1034	CYCL 211 not permitted		
1035	Q220 too large		
1036	Q222 must be greater than Q223		
1037	Q244 must be greater than 0		
1038	Q245 must not equal Q246		
1039	Angle range must be under 360°		
1040	Q223 must be greater than Q222		
1041	Q214: 0 not permitted		
1042	Traverse direction not defined		
1043	No datum table active		
1044	Position error: center in axis 1		
1045	Position error: center in axis 2		
1046	Hole diameter too small		
1047	Hole diameter too large		
1048	Stud diameter too small		
1049	Stud diameter too large		
1050	Pocket too small: rework axis 1		
1051	Pocket too small: rework axis 2		
1052	Pocket too large: scrap axis 1		
1053	Pocket too large: scrap axis 2		
1054	Stud too small: scrap axis 1		
1055	Stud too small: scrap axis 2		
1056	Stud too large: rework axis 1		
1057	Stud too large: rework axis 2		
1058	TCHPROBE 425: length exceeds max		
1059	TCHPROBE 425: length below min		
1060	TCHPROBE 426: length exceeds max		
1061	TCHPROBE 426: length below min		
1062	TCHPROBE 430: diameter too large		
1063	TCHPROBE 430: diameter too small		
1064	No measuring axis defined		
1065	Tool breakage tolerance exceeded		

Error number	Text		
1066	Enter Q247 unequal to 0		
1067	Enter Q247 greater than 5		
1068	Datum table?		
1069	Enter Q351 unequal to 0		
1070	Thread depth too large		
1071	Missing calibration data		
1072	Tolerance exceeded		
1073	Block scan active		
1074	ORIENTATION not permitted		
1075	3-D ROT not permitted		
1076	Activate 3-D ROT		
1077	Enter depth as negative		
1078	Q303 in meas. cycle undefined!		
1079	Tool axis not allowed		
1080	Calculated values incorrect		
1081	Contradictory meas. points		
1082	Incorrect clearance height		
1083	Contradictory plunge type		
1084	This fixed cycle not allowed		
1085	Line is write-protected		
1086	Oversize greater than depth		
1087	No point angle defined		
1088	Contradictory data		
1089	Slot position 0 not allowed		
1090	Enter an infeed not equal to 0		
1091	Switchover of Q399 not allowed		
1092	Tool not defined		
1093	Tool number not allowed		
1094	Tool name not allowed		
1095	Software option not active		
1096	Kinematics cannot be restored		
1097	Function not permitted		
1098	Contradictory workpc. blank dim.		
1099	Measuring position not allowed		
1100	Kinematic access not possible		
1101	Meas. pos. not in traverse range		
1102	Preset compensation not possible		
1103	Tool radius too large		
1104	Plunging type is not possible		
1105	Plunge angle incorrectly defined		

Error number	Text		
1106	Angular length is undefined		
1107	Slot width is too large		
1108	Scaling factors not equal		
1109	Tool data inconsistent		

# FN 16: F-PRINT: Output of formatted texts and Q parameter values



With **FN 16** you can also output to the screen any messages from the NC program. Such messages are displayed by the TNC in a pop-up window.

The function **FN 16: F-PRINT** transfers Q parameter values and texts in a selectable format. If you send the values, the TNC saves the data in the file that you defined in the **FN 16** block.

To output the formatted texts and Q-parameter values, create a text file with the TNC's text editor. In this file you then define the output format and Q parameters you want to output.

Example of a text file to define the output format:

"MEASURING LOG OF IMPELLER CENTER OF GRAVITY";

"DATE: %2d-%2d-%4d",DAY,MONTH,YEAR4;

"TIME: %2d:%2d:%2d",HOUR,MIN,SEC;

"NO. OF MEASURED VALUES: = 1";

"X1 = %9.3LF", Q31;

"Y1 = %9.3LF", Q32;

"Z1 = %9.3LF", Q33;

When you create a text file, use the following formatting functions:

Special characters	Function
""	Define output format for texts and variables between the quotation marks
%9.3LF	Define the format for Q parameters: 9 total characters (incl. decimal point), of which 3 are after the decimal, Long, Floating (decimal number)
%S	Format for text variable
%d	Format for integer
,	Separation character between output format and parameter
;	End of block character
\n	Line break

# 9.8 Additional functions

The following functions allow you to include the following additional information in the protocol log file:

Keyword	Function		
CALL_PATH	Indicates the path for the NC program where you will find the FN16 function. Example: "Measuring program: %S",CALL_PATH;		
M_CLOSE	Closes the file to which you are writing with FN16. Example: M_CLOSE;		
M_APPEND	Upon renewed output, appends the log to the existing log. Example: M_APPEND;		
M_APPEND_MAX	Upon renewed output, appends the log to the existing log until the maximum specified file size in kilobytes is exceeded. Example: M_APPEND_MAX1024;		
M_TRUNCATE	Overwrites the log upon renewed output. Example: M_TRUNCATE;		
L_ENGLISH	Outputs text only for English conversational language		
L_GERMAN	Outputs text only for German conversational language		
L_CZECH	Outputs text only for Czech conversational language		
L_FRENCH	Outputs text only for French conversational language		
L_ITALIAN	Outputs text only for Italian conversational language		
L_SPANISH	Outputs text only for Spanish conversational language		
L_SWEDISH	Outputs text only for Swedish conversational language		
L_DANISH	Outputs text only for Danish conversational language		
L_FINNISH	Outputs text only for Finnish conversational language		
L_DUTCH	Outputs text only for Dutch conversational language		
L_POLISH	Outputs text only for Polish conversational language		
L_PORTUGUE	Outputs text only for Portuguese conversational language		
L_HUNGARIA	Outputs text only for Hungarian conversational language		
L_SLOVENIAN	Outputs text only for Slovenian conversational language		
L_ALL	Outputs text independently of the conversational language		

ge\_\_\_\_\_

9

Keyword	Function
HOUR	Number of hours from the real-time clock
MIN	Number of minutes from the real-time clock
SEC	Number of seconds from the real-time clock
DAY	Day from the real-time clock
MONTH	Month as a number from the real-time clock
STR_MONTH	Month as a string abbreviation from the real-time clock
YEAR2	Two-digit year from the real-time clock
YEAR4	Four-digit year from the real-time clock

# In the part program, program FN 16: F-PRINT to activate the output:

#### 96 FN 16: F-PRINT TNC:\MASKE\MASKE1.A/ TNC:\PROT1.TXT

The TNC then creates the file PROT1.TXT:

MEASURING LOG OF IMPELLER CENTER OF GRAVITY DATE: 27:11:2001 TIME: 8:56:34 NO. OF MEASURED VALUES : = 1 X1 = 149.360 Y1 = 25.509 Z1 = 37.000

> program, the TNC appends all texts to the end of the texts already output within the target file. If you use **FN 16** more than once in the program, the TNC saves all texts in the file that you defined in the FN 16 function. The file is not output until the TNC reads the END PGM block, or you press the NC stop button, or you close the file with M\_CLOSE. In the **FN 16** block, program the format file and the log file with their respective extensions. If you enter only the file name for the path of the log file, the TNC saves the log file in the directory in which the NC program with the FN 16 function is located. You can define a standard path for outputting protocol files via the user parameters fn16DefaultPath and fn16DefaultPathSim (Program

Test).

9

9.8 Additional functions

#### Displaying messages on the TNC screen

You can also use the function **FN 16** to display any messages from the NC program in a pop-up window on the TNC screen. This makes it easy to display explanatory texts, including long texts, at any point in the program in a way that the user has to react to them. You can also display Q parameter contents if the protocol description file contains such instructions.

For the message to appear on the TNC screen, you need only enter **SCREEN:** as the name of the protocol file.

#### 96 FN 16: F-PRINT TNC:\MASKE\MASKE1.A/SCREEN:

If the message has more lines than fit in the pop-up window, you can use the arrow keys to page in the window.

To close the pop-up window, press the CE key. To have the program close the window, program the following NC block:

#### 96 FN 16: F-PRINT TNC:\MASKE\MASKE1.A/SCLR:



All the previously described conventions apply to the protocol description file.

If you output the same file more than once in the program, the TNC appends all texts to the end of the texts already output within the target file.

#### **Exporting messages**

You can also use the FN~16 function in the NC program in order to externally save the files generated with FN~16. Two possibilities are available for this:

Enter the complete target path in the **FN 16** function:

#### 96 FN 16: F-PRINT TNC:\MSK\MSK1.A / PC325:\LOG\PRO1.TXT



All the previously described conventions apply to the protocol description file.

If you output the same file more than once in the program, the TNC appends all texts to the end of the texts already output within the target file.

TNC 640 | User's Manual

HEIDENHAIN Conversational Programming | 5/2013

## FN 18: SYS-DATUM READ: Reading system data

With the **FN 18: SYS-DATUM READ** function you can read system data and store them in Q parameters. You select the system data through a group name (ID number), and additionally through a number and an index.

Group name, ID no.	Number	Index	Meaning
Program information, 10	3	-	Number of the active fixed cycle
	103	Q parameter number	Relevant within NC cycles; for inquiry as to whether the Q parameter given under IDX was explicitly stated in the associated CYCLE DEF.
System jump addresses, 13	1	-	Label jumped to during M2/M30 instead of ending the current program. Value = 0: M2/ M30 has the normal effect
	2	-	Label jumped to if FN14: ERROR after the NC CANCEL reaction instead of aborting the program with an error. The error number programmed in the FN14 command can be read under ID992 NR14. Value = 0: FN14 has the normal effect.
	3	-	Label jumped to in the event of an internal server error (SQL, PLC, CFG) instead of aborting the program with an error message. Value = 0: Server error has the normal effect.
Machine status, 20	1	-	Active tool number
	2	-	Prepared tool number
	3	-	Active tool axis 0=X, 1=Y, 2=Z, 6=U, 7=V, 8=W
	4	-	Programmed spindle speed
	5	-	Active spindle condition: -1=not defined, 0=M3 active, 1=M4 active, 2=M5 after M3, 3=M5 after M4
	7	-	Gear range
	8	-	Coolant status: 0=off, 1=on
	9	-	Active feed rate
	10	-	Index of prepared tool
	11	-	Index of active tool
Channel data, 25	1	-	Channel number

Group name, ID no.	Number	Index	Meaning
Cycle parameter, 30	1	-	Set-up clearance of active fixed cycle
	2	-	Drilling depth / milling depth of active fixed cycle
	3	-	Plunging depth of active fixed cycle
	4	-	Feed rate for pecking in active fixed cycle
	5	-	1st side length for rectangular pocket cycle
	6	-	2nd side length for rectangular pocket cycle
	7	-	1st side length for slot cycle
	8	-	2nd side length for slot cycle
	9	-	Radius for circular pocket cycle
	10	-	Feed rate for milling in active fixed cycle
	11	-	Direction of rotation for active fixed cycle
	12	-	Dwell time for active fixed cycle
	13	-	Thread pitch for Cycles 17, 18
	14	-	Finishing allowance for active fixed cycle
	15	-	Direction angle for rough out in active fixed cycle
	21	-	Probing angle
	22	-	Probing path
	23	-	Probing feed rate
Modal condition, 35	1	-	Dimensions: 0 = absolute (G90) 1 = incremental (G91)
Data for SQL tables, 40	1	-	Result code for the last SQL command
Data from the tool table, 50	1	Tool no.	Tool length
	2	Tool no.	Tool radius
	3	Tool no.	Tool radius R2
	4	Tool no.	Oversize for tool length DL
	5	Tool no.	Tool radius oversize DR
	6	Tool no.	Tool radius oversize DR2
	7	Tool no.	Tool locked (0 or 1)

Group name, ID no.	Number	Index	Meaning
	9	Tool no.	Maximum tool age TIME1
	10	Tool no.	Maximum tool age TIME2
	11	Tool no.	Current tool age CUR. TIME
	12	Tool no.	PLC status
	13	Tool no.	Maximum tooth length LCUTS
	14	Tool no.	Maximum plunge angle ANGLE
	15	Tool no.	TT: Number of tool teeth CUT
	16	Tool no.	TT: Wear tolerance for length LTOL
	17	Tool no.	TT: Wear tolerance for radius RTOL
	18	Tool no.	TT: Rotational direction DIRECT (0=positive/- 1=negative)
	19	Tool no.	TT: Offset in plane R-OFFS
	20	Tool no.	TT: Offset in length L-OFFS
	21	Tool no.	TT: Break tolerance for length LBREAK
	22	Tool no.	TT: Break tolerance for radius RBREAK
	28	Tool no.	Maximum rpm NMAX
	32	Tool no.	Point angle TANGLE
	34	Tool no.	LIFTOFF allowed (0= No, 1= Yes)
	35	Tool no.	Wear tolerance for radius R2TOL
	37	Tool no.	Corresponding line in the touch-probe table
	38	Tool no.	Timestamp of last use
Pocket table data, 51	1	Pocket number	Tool number
	2	Pocket number	Special tool: 0=No, 1=Yes
	3	Pocket number	Fixed pocket: 0=No, 1=Yes
	4	Pocket number	Locked pocket: 0=No, 1=Yes
	5	Pocket number	PLC status
Pocket number of a tool in the tool-pocket table, 52	1	Tool no.	Pocket number
	2	Tool no.	Tool magazine number

Group name, ID no.	Number	Index	Meaning
Values programmed immediately after TOOL CALL, 60	1	-	Tool number T
	2	-	Active tool axis 0 = X 6 = U 1 = Y 7 = V 2 = Z 8 = W
	3	-	Spindle speed S
	4	-	Oversize for tool length DL
	5	-	Tool radius oversize DR
	6	-	Automatic TOOL CALL 0 = Yes, 1 = No
	7	-	Tool radius oversize DR2
	8	-	Tool index
	9	-	Active feed rate
Values programmed immediately after TOOL DEF, 61	1	-	Tool number T
	2	-	Length
	3	-	Radius
	4	-	Index
	5	-	Tool data programmed in TOOL DEF 1 = Yes, 0 = No
Active tool compensation, 200	1	1 = without oversize 2 = with oversize 3 = with oversize and Oversize from TOOL CALL	Active radius
	2	1 = without oversize 2 = with oversize 3 = with oversize and Oversize from TOOL CALL	Active length
	3	1 = without oversize 2 = with oversize 3 = with oversize and Oversize from TOOL CALL	Rounding radius R2

Group name, ID no.	Number	Index	Meaning
Active transformations, 210	1	-	Basic rotation in MANUAL OPERATION mode
	2	-	Programmed rotation with Cycle 10
	3	-	Active mirrored axis
			0: Mirroring not active
			+1: X axis mirrored
			+2: Y axis mirrored
			+4: Z axis mirrored
			+64: U axis mirrored
			+128: V axis mirrored
			+256: W axis mirrored
			Combinations = Sum of individual axes
	4	1	Active scaling factor in X axis
	4	2	Active scaling factor in Y axis
	4	3	Active scaling factor in Z axis
	4	7	Active scaling factor in U axis
	4	8	Active scaling factor in V axis
	4	9	Active scaling factor in W axis
	5	1	3-D ROT A axis
	5	2	3-D ROT B axis
	5	3	3-D ROT C axis
	6	-	Tilted working plane active / inactive (–1/0) in a Program Run operating mode
	7	-	Tilted working plane active / inactive (–1/0) in a Manual operating mode
Active datum shift, 220	2	1	X axis
		2	Y axis
		3	Z axis
		4	A axis
		5	B axis
		6	C axis
		7	U axis
		8	V axis
		9	W axis

Group name, ID no.	Number	Index	Meaning
Traverse range, 230	2	1 to 9	Negative software limit switch in axes 1 to 9
	3	1 to 9	Positive software limit switch in axes 1 to 9
	5	-	Software limit switch on or off: 0 = on, 1 = off
Nominal position in the REF system, 240	1	1	X axis
		2	Y axis
		3	Z axis
		4	A axis
		5	B axis
		6	C axis
		7	U axis
		8	V axis
		9	W axis
Current position in the active coordinate system, 270	1	1	X axis
		2	Y axis
		3	Z axis
		4	A axis
		5	B axis
		6	C axis
		7	U axis
		8	V axis
		9	W axis

Group name, ID no.	Number	Index	Meaning
TS triggering touch probe, 350	50	1	Touch probe type
		2	Line in the touch-probe table
	51	-	Effective length
	52	1	Effective ball radius
		2	Rounding radius
	53	1	Center offset (reference axis)
		2	Center offset (minor axis)
	54	-	Spindle-orientation angle in degrees (center offset)
	55	1	Rapid traverse
		2	Measuring feed rate
	56	1	Maximum measuring range
		2	Safety clearance
	57	1	Spindle orientation possible: 0=No, 1=Yes
		2	Spindle-orientation angle
TT tool touch probe	70	1	Touch probe type
		2	Line in the touch-probe table
	71	1	Center point in reference axis (REF system)
		2	Center point in minor axis (REF system)
		3	Center point in tool axis (REF system)
	72	-	Probe contact radius
	75	1	Rapid traverse
		2	Measuring feed rate for stationary spindle
		3	Measuring feed rate for rotating spindle
	76	1	Maximum measuring range
		2	Safety clearance for linear measurement
		3	Safety clearance for radial measurement
	77	-	Spindle speed
	78	-	Probing direction

manual touch point from Cycle mpensation but isation (workpiece manual touch point from Cycle probe radius oordinate system) f the touch probe obe radius or probe manual touch point from Cycle stylus probe coordinate system)
point from Cycle probe radius oordinate system) f the touch probe obe radius or probe manual touch point from Cycle stylus probe
bbe radius or probe manual touch point from Cycle stylus probe
point from Cycle stylus probe
ation of a preset
preset
ctive preset
L
nt tool RT
ЛЕ

Group name, ID no.	Number	Index	Meaning
	13	-	Maximum tooth length LCUTS
	14	-	Maximum plunge angle ANGLE
	15	-	TT: Number of tool teeth CUT
	16	-	TT: Wear tolerance for length LTOL
	17	-	TT: Wear tolerance for radius RTOL
	18	-	TT: Direction of rotation DIRECT 0 = positive, -1 = negative
	19	-	TT: Offset in plane R-OFFS
	20	-	TT: Offset in length L-OFFS
	21	-	TT: Break tolerance for length LBREAK
	22	-	TT: Break tolerance for radius RBREAK
	23	-	PLC value
	24	-	Tool type TYP 0 = milling cutter, 21 = touch probe
	27	-	Corresponding line in the touch-probe table
	32	-	Point angle
	34	-	Lift off
Touch probe cycles, 990	1	-	Approach behaviour: 0 = standard behavior 1 = effective radius, safety clearance zero
	2	-	0 = Pushbutton monitoring off 1 = Pushbutton monitoring on
	4	-	0 = Stylus not deflected 1 = Stylus deflected
Execution status, 992	10	-	Mid-program startup active 1 = yes, 0 = no
	11	-	Search phase
	14	-	Number of the last FN14 error
	16	-	Real execution active 1 = execution , 2 = simulation

# Example: Assign the value of the active scaling factor for the Z axis to Q25.

55 FN 18: SYSREAD Q25 = ID210 NR4 IDX3

9

9.8 Additional functions

### FN 19: PLC: Transfer values to PLC

The **FN 19: PLC** function transfers up to two numerical values or Q parameters to the PLC. Increments and units:  $0.1 \ \mu m$  or  $0.0001^{\circ}$ 

Example: Transfer the numerical value 10 (which means 1  $\mu m$  or 0.001°) to the PLC

#### 56 FN 19: PLC=+10/+Q3

### FN 20: WAIT FOR: NC and PLC synchronization

This function may only be used with the permission of your machine tool builder.

With the **FN 20: WAIT FOR** function you can synchronize the NC and PLC during a program run. The NC stops machining until the condition that you have programmed in the FN 20: WAIT FORblock is fulfilled. The TNC can check the following PLC operands:

PLC operand	Abbreviation	Address range
Markers	Μ	0 to 4999
Input	I	0 to 31, 128 to 152 64 to 126 (first PL 401 B) 192 to 254 (second PL 401 B)
Output	0	0 to 30 32 to 62 (first PL 401 B) 64 to 94 (second PL 401 B)
Counter	С	48 to 79
Timer	т	0 to 95
Byte	В	0 to 4095
Word	W	0 to 2047
Double word	D	2048 to 4095

The TNC 640 uses an extended interface for communication between the PLC and NC. This is a new, symbolic Application Programmer Interface (**API**). The familiar previous PLC-NC interface is also available and can be used if desired. The machine tool builder decides whether the new or old TNC API is used. Enter the name of the symbolic operand as string to wait for the defined condition of the symbolic operand.

The following conditions are permitted in the FN 20 block:

Condition	Abbreviation
Equal to	==
Less than	<
Greater than	>
Less than or equal	<=
Greater than or equal	>=

In addition, the **FN20: WAIT FOR SYNC** function is available. **WAIT FOR SYNC** is used whenever you read, for example, system data via **FN18** that require synchronization with real time. The TNC stops the look-ahead calculation and executes the subsequent NC block only when the NC program has actually reached that block.

Example: Stop program run until the PLC sets marker 4095 to 1

32 FN 20: WAIT FOR M4095==1

Example: Stop program run until the PLC sets the symbolic operand to 1

32 FN 20: APISPIN[0].NN\_SPICONTROLINPOS==1

Example: Pause internal look-ahead calculation, read current position in the X axis

#### 32 FN 20: WAIT FOR SYNC

33 FN 18: SYSREAD Q1 = ID270 NR1 IDX1

9

9.8 Additional functions

### FN 29: PLC: Transfer values to the PLC

The FN 29: PLC function transfers up to eight numerical values or Q parameters to the PLC. Increments and units:  $0.1 \,\mu m$  or  $0.0001^\circ$ 

Example: Transfer the numerical value 10 (which means 1  $\mu m$  or 0.001°) to the PLC

56 FN 29: PLC=+10/+Q3/+Q8/+7/+1/+Q5/+Q2/+15

### FN 37: EXPORT

You need the FN 37: EXPORT function if you want to create your own cycles and integrate them in the TNC. The Q parameters 0 to 99 are effective only locally. This means that the Q parameters are effective only in the program in which they were defined. With the FN 37: EXPORT function you can export locally effective Q parameters into another (calling) program.



The TNC exports the value that the parameter has at the time of the EXPORT command.

The parameter is exported only to the presently calling program.

#### Example: The local Q parameter Q25 is exported

56 FN37: EXPORT Q25

Example: The local Q parameters Q25 to Q30 are exported 56 FN37: EXPORT Q25 - Q30

# 9.9 Accessing tables with SQL commands

### Introduction

Accessing of tables is programmed on the TNC with SQL commands in **transactions**. A transaction consists of multiple SQL commands that guarantee an orderly execution of the table entries.



Tables are configured by the machine manufacturer. Names and designations required as parameters for SQL commands are also specified.

The following **terms** are used:

- **Table**: A table consists of x columns and y rows. It is saved as a file in the File Manager of the TNC, and is addressed with the path and file name (=table name). Synonyms can also be used for addressing, as an alternative to the path and file name.
- Columns: The number and names of the columns are specified when configuring the table. In some SQL commands the column name is used for addressing.
- Rows: The number of rows is variable. You can insert new rows. There are no row numbers or other designators. However, you can select rows based on the contents of a column. Rows can only be deleted in the table editor, not by an NC program.
- Cell: The part of a column in a row.
- **Table entry**: Content of a cell.
- Result set: During a transaction, the selected columns and rows are managed in the result set. You can view the result set as a sort of "intermediate memory," which temporarily assumes the set of selected columns and rows. Result set
- Synonym: This term defines a name used for a table instead of its path and file name. Synonyms are specified by the machine manufacturer in the configuration data.

### 9.9 Accessing tables with SQL commands

#### A transaction

In principle, a transaction consists of the following actions:

- Address the table (file), select rows and transfer them to the result set.
- Read rows from the result set, change rows or insert new rows.
- Conclude transaction: If changes/insertions were made, the rows from the result set are placed in the table (file).

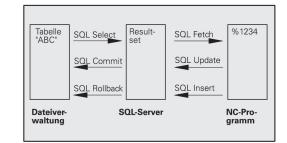
Other actions are also necessary so that table entries can be edited in an NC program and to ensure that other changes are not made to copies of the same table rows at the same time. This results in the following **transaction sequence**:

- 1 A Q parameter is specified for each column to be edited. The Q parameter is assigned to a column—it is "bound" (SQL BIND...
- 2 Address the table (file), select rows and transfer them to the result set. In addition, you define which columns are transferred to the result set (SQL SELECT...). You can lock the selected rows. Other processes can then read these rows, but cannot change the table entries. You should always lock the selected rows when you are going to make changes (SQL SELECT ... FOR UPDATE).
- 3 Read rows from the result set, modify and/or add new rows: – Adopt one row of the result set into the Q parameters of your NC program (SQL FETCH...) – Prepare changes in the Q parameters and transfer to a row in the result set (SQL UPDATE...) – Prepare new table row in the Q parameters and transfer as a new row to the result set (SQL INSERT...)
- 4 Conclude transaction: If changes/insertions were made, the data from the result set is placed in the table (file). The data is now saved in the file. Any locks are canceled, and the result set is released (SQL COMMIT...). – If table entries were **not** changed or inserted (only read access), any locks are canceled and the result set is released (SQL ROLLBACK... WITHOUT INDEX).

Multiple transactions can be edited at the same time.



You must conclude a transaction, even if it consists solely of read accesses. Only this guarantees that changes/insertions are not lost, that locks are canceled, and that result sets are released.



#### **Result set**

The selected rows are numbered in ascending order within the result set, starting from 0. This numbering is referred to as the **index.** The index is used for read- and write-accesses, enabling a row of the result set to be specifically addressed.

It can often be advantageous to sort the rows in the result set. Do this by specifying the table column containing the sorting criteria. Also select ascending or descending order (**SQL SELECT ... ORDER BY ...**).

The selected rows that were transferred to the result set are addressed with the **HANDLE**. All following SQL commands use the handle to refer to this "set of selected columns and rows."

When concluding a transaction, the handle is released (SQL COMMIT... or SQL ROLLBACK...). It is then no longer valid.

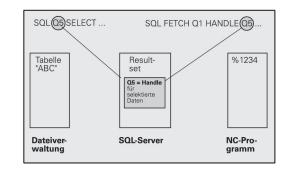
You can edit more than one result set at the same time. The SQL server assigns a new handle for each "Select" command.

#### "Binding" Q parameters to columns

The NC program does not have direct access to the table entries in the result set. The data must be transferred in Q parameters. In the other direction, the data is first prepared in the Q parameters and then transferred to the result set.

Specify with **SQL BIND**... which table columns are mapped to which Q parameters. The Q parameters are "bound" (assigned) to the columns. Columns that are not bound to Q parameters are not included in the read-/write-processes.

If a new table row is generated with **SQL INSERT...**, the columns not bound to Q parameters are filled with default values.



9.9 Accessing tables with SQL commands

### **Programming SQL commands**



SQL

9

This function can only be programmed if you have entered the code number 555343.

Program SQL commands in the Programming mode:

- Call the SQL functions by pressing the SQL soft key
- Select an SQL command via soft key (see overview) or press the SQL EXECUTE soft key and program the SQL command

#### Overview of the soft keys

Function	Soft key
<b>SQL EXECUTE</b> Program a Select command.	SQL EXECUTE
<b>SQL BIND</b> Bind a Q parameter to a table column.	SQL BIND
<b>SQL FETCH</b> Read table rows from the result set and save them in Q parameters.	SQL FETCH
<b>SQL UPDATE</b> Save data from the Q parameters in an existing table row in the result set.	SQL UPDATE
<b>SQL INSERT</b> Save data from the Q parameters in a new table row in the result set.	SQL INSERT
<b>SQL COMMIT</b> Transfer table rows from the result set into the table and conclude the transaction.	SQL Commit
<ul> <li>SQL ROLLBACK</li> <li>If INDEX is not programmed: Discard any changes/insertions and conclude the transaction.</li> </ul>	SQL Rollback

If INDEX is programmed: The indexed row remains in the result set. All other rows are deleted from the result set. The transaction is not concluded.

### **SQL BIND**

**SQL BIND** binds a Q parameter to a table column. The SQL commands "Fetch," "Update" and "Insert" evaluate this binding (assignment) during data transfer between the result set and the NC program.

An **SQL BIND** command without a table or column name cancels the binding. Binding remains effective at most until the end of the NC program or subprogram.

- $\Rightarrow$
- You can program any number of bindings. Read and write processes only take into account the columns that were entered in the "Select" command.
  - SQL BIND... must be programmed before "Fetch," "Update" or "Insert" commands are programmed. You can program a "Select" command without a preceding "Bind" command.
  - If in the "Select" command you include columns for which no binding is programmed, an error occurs during read/write processes (program interrupt).
- SQL BIND

Parameter no. for result: Q parameter that is bound (assigned) to the table column.

Database: Column name: Enter the table name and column name separated by a . (period)
 Table name: Synonym or path and file name of this table. The synonym is entered directly, whereas the path and file name are entered in single quotation marks

**Column designation**: Designation of the table column as given in the configuration data

#### Bind a Q parameter to a table column

11SQL BIND Q881 "TAB\_EXAMPLE.MEAS\_NO"

12SQL BIND Q882 "TAB\_EXAMPLE.MEAS\_X"

13SQL BIND Q883 "TAB\_EXAMPLE.MEAS\_Y"

14SQL BIND Q884 "TAB\_EXAMPLE.MEAS\_Z"

Cancel binding

91 SQL BIND Q881

92 SQL BIND Q882

93 SQL BIND Q883

94 SQL BIND Q884

9.9 Accessing tables with SQL commands

### SQL SELECT

9

**SQL SELECT** selects table rows and transfers them to the result set.

The SQL server places the data in the result set row-by-row. The rows are numbered in ascending order, starting from 0. This row number, called the **INDEX**, is used in the SQL commands "Fetch" and "Update."

Enter the selection criteria in the **SQL SELECT...WHERE...** function. This lets you restrict the number of rows to be transferred. If you do not use this option, all rows in the table are loaded.

Enter the sorting criteria in the **SQL SELECT...ORDER BY...** function. Enter the column designation and the keyword for ascending/ descending order. If you do not use this option, the rows are placed in random order.

Lock out the selected rows for other applications with the **SQL SELECT...FOR UPDATE** function. Other applications can continue to read these rows, but cannot change them. We strongly recommend using this option if you are making changes to the table entries.

**Empty result set**: If no rows match the selection criteria, the SQL server returns a valid handle but no table entries.

SQL EXECUTE  Parameter no. for result: Q parameter for the handle. The SQL server returns the handle for the group of columns and rows selected with the current "Select" command.
 With an error (selection could not be executed) the SQL server returns a 1. Code 0 identifies an invalid handle.

Database: SQL command text: with the following elements:

SELECT (keyword):

Name of the SQL command, names of the table columns to be transferred. Separate column names with a , (comma) (see examples). Q parameters must be bound to all columns entered here.

FROM table name:

Synonym or path and file name of this table. The synonym is entered directly: the path name and table name are entered in single quotation marks (see examples of the SQL command); names of the table columns to be transferred—separate several columns by a comma (see examples). Q parameters must be bound to all columns entered here.

Select all table rows

11SQL BIND Q881 "TAB\_EXAMPLE.MEAS\_NO"

12SQL BIND Q882 "TAB\_EXAMPLE.MEAS\_X"

13SQL BIND Q883 "TAB\_EXAMPLE.MEAS\_Y"

14SQL BIND Q884 "TAB\_EXAMPLE.MEAS\_Z"

•••

20SQL Q5 "SELECT MEAS\_NO,MEAS\_X,MEAS\_Y, MEAS\_Z FROM TAB\_EXAMPLE"

# Selection of table rows with the WHERE function

• • •

20SQL Q5 "SELECT MEAS\_NO,MEAS\_X,MEAS\_Y, MEAS\_Z FROM TAB\_EXAMPLE WHERE MEAS\_NO<20"

# Selection of table rows with the WHERE function and Q parameters

•••

20SQL Q5 "SELECT MEAS\_NO,MEAS\_X,MEAS\_Y, MEAS\_Z FROM TAB\_EXAMPLE WHERE MEAS\_NO==:'Q11'''

Table name defined with path and file name

• • •

20SQL Q5 "SELECT MEAS\_NO,MEAS\_X,MEAS\_Y, MEAS\_Z FROM 'V:\TABLE\TAB\_EXAMPLE' WHERE MEAS\_NO<20" Optional:

WHERE selection criteria: A selection criterion consists of a column name, condition (see table) and comparator. Link selection criteria with logical AND or OR. Program the comparator directly or with a Q parameter. A Q parameter is introduced with a colon and placed in single quotation marks (see example).

Optional:

**ORDER BY** column name **ASC** for ascending sorting, or **ORDER BY** column name **DESC** for descending sorting. If you program neither ASC nor DESC, ascending sorting is executed by default. The TNC places the selected rows in the indicated column.

Optional:

**FOR UPDATE** (keyword): The selected rows are locked against write-accesses from other processes.

Condition	Programming
Equal to	= ==
Not equal to	!= <>
Less than	<
Less than or equal to	<=
Greater than	>
Greater than or equal to	>=
Linking multiple conditions:	
Logical AND	AND
Logical OR	OR

### SQL FETCH

**SQL FETCH** reads the row addressed with **INDEX** from the result set, and places the table entries in the bound (assigned) Q parameters. The result set is addressed with the **HANDLE**.

**SQL FETCH** takes into account all columns entered in the "Select" command.

SQL FETCH Parameter no. for result: Q parameter in which the SQL server reports the result:
 0: no error
 1: error occurred (erroneous handle or index too large)

- Database: SQL access ID: Q parameter with the handle for identifying the result set (also see SQL SELECT)
- Database: Index for SQL result: Row number within the result set. The table entries of this row are read and are transferred into the bound Q parameters. If you do not enter an index, the first row is read (n=0).

Either enter the row number directly or program the Q parameter containing the index.

# Row number is transferred in a Q parameter

11SQL BIND Q881 "TAB\_EXAMPLE.MEAS\_NO"

12SQL BIND Q882 "TAB\_EXAMPLE.MEAS\_X"

13SQL BIND Q883 "TAB\_EXAMPLE.MEAS\_Y"

14SQL BIND Q884 "TAB\_EXAMPLE.MEAS\_Z"

• • •

20SQL Q5 "SELECT MEAS\_NO,MEAS\_X,MEAS\_Y, MEAS\_Z FROM TAB\_EXAMPLE"

#### • • •

30 SQL FETCH Q1HANDLE Q5 INDEX +Q2

Row number is programmed directly

• • •

30 SQL FETCH Q1HANDLE Q5 INDEX5

. . .

### SQL UPDATE

**SQL UPDATE** transfers the data prepared in the Q parameters into the row of the result set addressed with **INDEX.** The existing row in the result set is completely overwritten.

**SQL UPDATE** takes into account all columns entered in the "Select" command.

- SQL UPDATE
- Parameter no. for result: Q parameter in which the SQL server reports the result:
   0: no error
   1: error occurred (erroneous handle, index too large,
  - value range exceeded/fallen below or erroneous data format)
- Database: SQL access ID: Q parameter with the handle for identifying the result set (also see SQL SELECT)
- Database: Index for SQL result: Row number within the result set. The table entries prepared in the Q parameters are written to this row. If you do not enter an index, the first row is written to (n=0). Either enter the row number directly or program the Q parameter containing the index.

### **SQL INSERT**

**SQL INSERT** generates a new row in the result set and transfers the data prepared in the Q parameters into the new row.

**SQL INSERT** takes into account all columns entered in the "Select" command. Table columns not entered in the "Select" command are filled with default values.

SQL INSERT Parameter no. for result: Q parameter in which the SQL server reports the result: 0: no error

1: error occurred (erroneous handle, value range exceeded/fallen below or erroneous data format)

 Database: SQL access ID: Q parameter with the handle for identifying the result set (also see SQL SELECT)

#### Row number is programmed directly

40 SQL UPDATEQ1 HANDLE Q5 INDEX5

# Row number is transferred in a Q parameter

11SQL BIND Q881 "TAB\_EXAMPLE.MEAS\_NO"

12SQL BIND Q882 "TAB\_EXAMPLE.MEAS\_X"

13SQL BIND Q883 "TAB\_EXAMPLE.MEAS\_Y"

14SQL BIND Q884 "TAB\_EXAMPLE.MEAS\_Z"

• • •

20SQL Q5 "SELECT MEAS\_NO,MEAS\_X,MEAS\_Y, MEAS\_Z FROM TAB\_EXAMPLE"

40 SQL INSERTQ1 HANDLE Q5

•••

## 9.9 Accessing tables with SQL commands

### **SQL COMMIT**

**SQL COMMIT** transfers all rows in the result set back to the table. A lock set with **SELECT...FOR UPDATE** is canceled.

The handle given in the SQL SELECT command loses its validity.

SQL COMMIT

9

 Parameter no. for result: Q parameter in which the SQL server reports the result: 0: no error

1: error occurred (erroneous handle or identical entries in columns in which unique entries are required)

 Database: SQL access ID: Q parameter with the handle for identifying the result set (also see SQL SELECT) 11SQL BIND Q881

"TAB\_EXAMPLE.MEAS\_NO" 12SQL BIND Q882

"TAB\_EXAMPLE.MEAS\_X"

13SQL BIND Q883 "TAB\_EXAMPLE.MEAS\_Y"

14SQL BIND Q884 "TAB\_EXAMPLE.MEAS\_Z"

20SQL Q5 "SELECT

MEAS\_NO, MEAS\_X, MEAS\_Y, MEAS\_Z FROM TAB\_EXAMPLE"

•••

. . .

30 SQL FETCH Q1HANDLE Q5 INDEX +Q2

• • •

40 SQL UPDATEQ1 HANDLE Q5 INDEX +Q2

. . .

50 SQL COMMITQ1 HANDLE Q5

### SQL ROLLBACK

How **SQL ROLLBACK** is executed depends on whether **INDEX** is programmed:

If INDEX is not programmed: The result set is not written back to the table (any changes/insertions are discarded). The transaction is closed and the handle given in the SQL SELECT command loses its validity. Typical application: Ending a transaction solely containing read-accesses.

If INDEX is programmed: The indexed row remains. All other rows are deleted from the result set. The transaction is **not** concluded. A lock set with **SELECT...FOR UPDATE** remains for the indexed row. For all other rows it is reset.



 Parameter no. for result: Q parameter in which the SQL server reports the result:
 0: no error
 1: error occurred (erroneous handle)

- Database: SQL access ID: Q parameter with the handle for identifying the result set (also see SQL SELECT)
- Database: Index for SQL result: Row that is to remain in the result set. Either enter the row number directly or program the Q parameter containing the index

11SQL BIND Q881 "TAB\_EXAMPLE.MEAS\_NO"

12SQL BIND Q882 "TAB\_EXAMPLE.MEAS\_X"

13SQL BIND Q883 "TAB\_EXAMPLE.MEAS\_Y"

14SQL BIND Q884 "TAB\_EXAMPLE.MEAS\_Z"

. . .

20SQL Q5 "SELECT MEAS\_NO,MEAS\_X,MEAS\_Y, MEAS\_Z FROM TAB\_EXAMPLE"

•••

. . .

30 SQL FETCH Q1HANDLE Q5 INDEX +Q2

50 SQL ROLLBACKQ1 HANDLE Q5

# 9.10 Entering formulas directly

### **Entering formulas**

You can enter mathematical formulas that include several operations directly into the part program by soft key.

Press the FORMULA soft key to call the mathematical functions. The TNC displays the following soft keys in several soft-key rows:

The five displays the following soft keys in several soft	
Mathematical function	Soft key
<b>Addition</b> e.g. <b>Q10 = Q1 + Q5</b>	•
<b>Subtraction</b> e.g. <b>Q25 = Q7 - Q108</b>	-
Multiplication e.g. Q12 = 5 * Q5	*
<b>Division</b> e.g. <b>Q25 = Q1 / Q2</b>	/
<b>Open parentheses</b> e.g. <b>Q12 = Q1 * (Q2 + Q3)</b>	¢
Close parentheses e.g. Q12 = Q1 * (Q2 + Q3)	>
Square value e.g. Q15 = SQ 5	50
Square root e.g. Q22 = SQRT 25	SORT
Sine of an angle e.g. Q44 = SIN 45	SIN
Cosine of an angle e.g. Q45 = COS 45	cos
Tangent of an anglee.g. Q46 = TAN 45	TAN
Arc sine Inverse function of the sine; determine the angle from the ratio of the opposite side to the hypotenuse e.g. Q10 = ASIN 0.75	ASIN
Arc cosine Inverse function of the cosine; determine the angle	ACOS
from the ratio of the adjacent side to the hypotenuse e.g. <b>Q11 = ACOS Q40</b>	
Arc tangent Inverse function of the tangent; determine the	ATAN
angle from the ratio of the opposite side to the adjacent side	
e.g. Q12 = ATAN Q50	

# 9.10 Entering formulas directly

Mathematical function	Soft key
<b>Powers</b> e.g. <b>Q15 = 3^3</b>	^
<b>Constant "pi" (3,14159)</b> e.g. <b>Q15 = PI</b>	PI
Natural logarithm (LN) of a number	LN
Base 2.7183 e.g. <b>Q15 = LN Q11</b>	
Logarithm of a number, base 10 e.g. Q33 = LOG Q22	LOG
Exponential function, 2.7183n e.g. Q1 = EXP Q12	EXP
Negate (multiplication by -1) e.g. Q2 = NEG Q1	NEG
Truncate digits after the decimal point	INT
Form an integer e.g. <b>Q3 = INT Q42</b>	
Absolute value	ABS
e.g. <b>Q4 = ABS Q22</b>	
<b>Truncate digits before the decimal point</b> Form a fraction e.g. <b>Q5 = FRAC Q23</b>	FRAC
<b>Check the algebraic sign of a digit</b> e.g. <b>Q12 = SGN Q50</b> When return value Q12 = 1, then Q50 >= 0	SGN
When return value $Q12 = -1$ , then $Q50 < 0$	
Calculate modulo value (division rest) e.g. Q12 = 400 % 360 Result: Q12 = 40	*

## **Rules for formulas**

Mathematical formulas are programmed according to the following rules:

### Higher-level operations are performed first

### 12 Q1 = 5 \* 3 + 2 \* 10 = 35

- 1 Calculation 5 \* 3 = 15
- 2 Calculation 2 \* 10 = 20
- 3 Calculation 15 + 20 = 35

#### or

### 13 Q2 = SQ 10 - 3^3 = 73

- 1 Calculation step 10 squared = 100
- 2 Calculation step 3 to the third power = 27
- 3 Calculation 100 27 = 73

#### **Distributive law**

Law of distribution with parentheses calculation a \* (b + c) = a \* b + a \* c

9.10 Entering formulas directly

### **Programming example**

Calculate an angle with the arc tangent from the opposite side (Q12) and adjacent side (Q13); then store in Q25.



FORMULA

9

- To select the formula entering function, press the Q key and the FORMULA soft key, or use the shortcut:
- Q

▶ Press the Q key on the ASCII keyboard

#### PARAMETER NUMBER FOR RESULT?

Enter parameter number 25 and press the ENT ENT key. Shift the soft-key row and select the arc tangent  $\triangleright$ function ATAN Shift the soft-key row and open the parentheses  $\triangleleft$ ( Enter Q parameter number 12 Q Select division Enter Q parameter number 13 Q Close parentheses and conclude formula entry > ENC 

Example NC block 37 Q25 = ATAN (Q12/Q13)

## 9.11 String parameters

### String processing functions

You can use the **QS** parameters to create variable character strings. You can output such character strings for example through the **FN 16:F-PRINT** function to create variable logs.

You can assign a linear sequence of characters (letters, numbers, special characters and spaces) up to a length of 256 characters to a string parameter. You can also check and process the assigned or imported values by using the functions described below. As in Q-parameter programming, you can use a total of 2000 QS parameters (See "Principle and overview of functions", page 278). The STRING FORMULA and FORMULA Q-parameter functions contain various functions for processing the string parameters.

STRING FORMULA functions	Soft key	Page
Assigning string parameters	STRING	326
Chain-linking string parameters		326
Converting a numerical value to a string parameter	TOCHAR	327
Copy a substring from a string parameter	SUBSTR	328
FORMULA string functions	Soft key	Page
FORMULA string functions Converting a string parameter to a numerical value	Soft key	<b>Page</b> 329
Converting a string parameter to a	-	-
Converting a string parameter to a numerical value	толимв	329



When you use a STRING FORMULA, the result of the arithmetic operation is always a string. When you use the FORMULA function, the result of the arithmetic operation is always a numeric value.

9.11 String parameters

#### Assigning string parameters

You have to assign a string variable before you use it. Use the **DECLARE STRING** command to do so.



Show the soft-key row with special functions

Select the menu for defining various plain-

- PROGRAM FUNCTIONS
- language functionsSelect string functions

FUNCTIONS DECLARE STRING

Select the DECLARE STRING function

#### Example NC block

37 DECLA	ARE STRING	QS10 = "W	VORKPIECE"
----------	------------	-----------	------------

#### **Chain-linking string parameters**

With the concatenation operator (string parameter || string parameter) you can make a chain of two or more string parameters.

- SPEC FCT
- Show the soft-key row with special functions
- PROGRAM

 Select the menu for defining various plainlanguage functions

STRING FUNCTIONS

> STRING FORMULA

Select the STRING FORMULA function

Select string functions

- Enter the number of the string parameter in which the TNC is to save the concatenated string. Confirm with the ENT key
- Enter the number of the string parameter in which the **first** substring is saved. Confirm with the ENT key: The TNC displays the concatenation symbol
   ||
- Confirm your entry with the ENT key
- Enter the number of the string parameter in which the second substring is saved. Confirm with the ENT key
- Repeat the process until you have selected all the required substrings. Conclude with the END key

String paran

## Example: QS10 is to include the complete text of QS12, QS13 and QS14

#### 37 QS10 = QS12 || QS13 || QS14

Parameter contents:

- QS12: Workpiece
- QS13: Status:
- QS14: Scrap
- QS10: Workpiece Status: Scrap

#### Converting a numerical value to a string parameter

With the **TOCHAR** function, the TNC converts a numerical value to a string parameter. This enables you to chain numerical values with string variables.

FCT	
PROGRAM FUNCTIONS	
STRING FUNCTIONS	
STRING FORMULA	
TOCHAR	

SPEC

Show the soft-key row with special functions

- Select the menu for defining various plainlanguage functions
- Select string functions
- Select the STRING FORMULA function
- Select the function for converting a numerical value to a string parameter
- Enter the number or the desired Q parameter to be converted, and confirm with the ENT key
- If desired, enter the number of decimal places that the TNC should convert, and confirm with the ENT key
- Close the parenthetical expression with the ENT key and confirm your entry with the END key

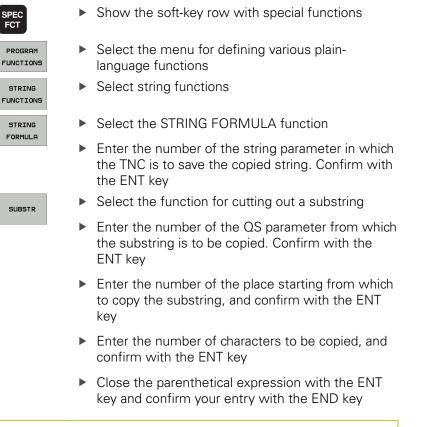
## Example: Convert parameter Q50 to string parameter QS11, use 3 decimal places

37 QS11 = TOCHAR ( DAT+Q50 DECIMALS3 )

9.11 String parameters

#### Copying a substring from a string parameter

The **SUBSTR** function copies a definable range from a string parameter.





Remember that the first character of a text sequence starts internally with the zeroth place.

Example: A four-character substring (LEN4) is read from the string parameter QS10 beginning with the third character (BEG2)

37 QS13 = SUBSTR ( SRC\_QS10 BEG2 LEN4 )

#### Converting a string parameter to a numerical value

The **TONUMB** function converts a string parameter to a numerical value. The value to be converted should be only numerical.



The QS parameter must contain only one numerical value. Otherwise the TNC will output an error message.

	Q	
I		

FORMULA

 $\triangleleft$ 

TONUMB

- Select Q-parameter functions
- Select the FORMULA function
  - Enter the number of the parameter in which the TNC is to save the numerical value. Confirm with the ENT key
- Shift the soft-key row
- Select the function for converting a string parameter to a numerical value
- Enter the number of the Q parameter to be converted, and confirm with the ENT key
- Close the parenthetical expression with the ENT key and confirm your entry with the END key

## Example: Convert string parameter QS11 to a numerical parameter Q82

37 Q82 = TONUMB ( SRC\_QS11 )

9.11 String parameters

#### Checking a string parameter

The INSTR function checks whether a string parameter is contained in another string parameter.



Select Q-parameter functions

FORMULA

Select the FORMULA function

- Enter the number of the Q parameter in which the TNC is to save the place at which the search text begins. Confirm with the ENT kev
- Shift the soft-key row
- INSTR

 $\triangleleft$ 

- Select the function for checking a string parameter
- Enter the number of the QS parameter in which the text to be searched for is saved. Confirm with the ENT key
- Enter the number of the QS parameter to be searched, and confirm with the ENT key
- Enter the number of the place starting from which the TNC is to search the substring, and confirm with the ENT key
- Close the parenthetical expression with the ENT key and confirm your entry with the END key

Remember that the first character of a text sequence starts internally with the zeroth place.

If the TNC cannot find the required substring, it will save the total length of the string to be searched (counting starts at 1) in the result parameter.

If the substring is found in more than one place, the TNC returns the first place at which it finds the substring.

Example: Search through QS10 for the text saved in parameter QS13. Begin the search at the third place.

37 Q50 = INSTR ( SRC\_QS10 SEA\_QS13 BEG2 )

## Finding the length of a string parameter

The STRLEN function returns the length of the text saved in a selectable string parameter.

Q	<ul> <li>Select Q-parameter functions</li> </ul>
FORMULA	<ul> <li>Select the FORMULA function</li> </ul>
	<ul> <li>Enter the number of the Q par the TNC is to save the ascerta Confirm with the ENT key</li> </ul>
$\bigcirc$	<ul> <li>Shift the soft-key row</li> </ul>
STRLEN	<ul> <li>Select the function for finding string parameter</li> </ul>
	<ul> <li>Enter the number of the QS pa length the TNC is to ascertain, the ENT key</li> </ul>

- Select the FORMULA function
- Enter the number of the Q parameter in which the TNC is to save the ascertained string length. Confirm with the ENT key
- Shift the soft-key row
- Select the function for finding the text length of a string parameter
- Enter the number of the QS parameter whose length the TNC is to ascertain, and confirm with the ENT key
- Close the parenthetical expression with the ENT key and confirm your entry with the END key

#### Example: Find the length of QS15

#### 37 Q52 = STRLEN ( SRC\_QS15 )

9.11 String parameters

#### **Comparing alphabetic sequence**

The **STRCOMP** function compares string parameters for alphabetic priority.

Q	<ul> <li>Select Q-parameter functions</li> </ul>
FORMULA	<ul> <li>Select the FORMULA function</li> </ul>
	Enter the number of the Q parameter in which the TNC is to save the result of comparison. Confirm with the ENT key
$\triangleleft$	<ul> <li>Shift the soft-key row</li> </ul>
STRCOMP	<ul> <li>Select the function for comparing string parameters</li> </ul>
	<ul> <li>Enter the number of the first QS parameter to be compared, and confirm with the ENT key</li> </ul>
	<ul> <li>Enter the number of the second QS parameter to be compared, and confirm with the ENT key</li> </ul>
	<ul> <li>Close the parenthetical expression with the ENT key and confirm your entry with the END key</li> </ul>
	The TNC returns the following results:
<b>~</b>	<ul> <li>0: The compared QS parameters are identical</li> </ul>
	<ul> <li>-1: The first QS parameter precedes the second QS parameter alphabetically</li> </ul>
	+1: The first QS parameter follows the second

Example: QS12 and QS14 are compared for alphabetic priority

QS parameter alphabetically

37 Q52 = STRCOMP ( SRC\_QS12 SEA\_QS14 )

### **Reading machine parameters**

Use the **CFGREAD** function to read out TNC machine parameters as numerical values or as strings.

In order to read out a machine parameter, you must use the TNC's configuration editor to determine the parameter name, parameter object, and, if they have been assigned, the group name and index

Туре	Meaning	Example	lcon
Кеу	Group name of the machine parameter (if assigned)	CH_NC	æ₿
Entity	Parameter object (the name starts with " <b>Cfg</b> ")	CfgGeoCycle	₽₽ <mark>₽</mark>
Attribute	Name of the machine parameter	displaySpindleErr	
Index	List index of a machine parameter (if assigned)	[0]	₽ <mark>€⊐</mark>
	If you are in the configuration editor for the user parameters, you can change the display of the existing parameters. In the default setting, the parameters are displayed with short, explanatory		

existing parameters. In the default setting, the parameters are displayed with short, explanatory texts. To display the actual system names of the parameters, press the key for the screen layout and then the SHOW SYSTEM NAME soft key. Follow the same procedure to return to the standard display.

Each time you want to interrogate a machine parameter with the **CFGREAD** function, you must first define a QS parameter with attribute, entity and key.

The following parameters are read in the CFGREAD function's dialog:

- **KEY\_QS**: Group name (key) of the machine parameter
- **TAG\_QS**: Object name (entity) of the machine parameter
- ATR\_QS: Name (attribute) of the machine parameter
- **IDX**: Index of the machine parameter

### 9.11 String parameters

#### Reading a string of a machine parameter

In order to store the content of a machine parameter as a string in a QS parameter:



- Show the soft-key row with special functions
- Select the menu for defining various plainlanguage functions
- STRING FUNCTIONS STRING

FORMULA

- ► Select the STRING FORMULA function
- Enter the number of the string parameter in which the TNC is to save the machine parameter. Confirm with the ENT key
- Select the CFGREAD function

Select string functions

- Enter the numbers of the string parameters for the key, entity and attribute, then confirm with the ENT key
- Enter the number for the index, or skip the dialog with NO ENT, whichever applies
- Close the parenthetical expression with the ENT key and confirm your entry with the END key

## Example: Read as a string the axis designation of the fourth axis

#### Parameter settings in the configuration editor

DisplaySettings CfgDisplayData axisDisplayOrder [0] to [5]

14 DECLARE STRINGQS11 = ""	Assign string parameter for key
15 DECLARE STRINGQS12 = "CFGDISPLAYDATA"	Assign string parameter for entity
16 DECLARE STRINGQS13 = "AXISDISPLAYORDER"	Assign string parameter for parameter name
17 QS1 = CFGREAD( KEY_QS11 TAG_QS12 ATR_QS13 IDX3 )	Read out machine parameter

#### Reading a numerical value of a machine parameter

In order to store the value of a machine parameter as a numerical value in a  $\ensuremath{\mathsf{Q}}$  parameter:



- Select Q-parameter functions
- FORMULA
- ► Select the FORMULA function
- Enter the number of the Q parameter in which the TNC is to save the machine parameter. Confirm with the ENT key
- Select the CFGREAD function
- Enter the numbers of the string parameters for the key, entity and attribute, then confirm with the ENT key
- Enter the number for the index, or skip the dialog with NO ENT, whichever applies
- Close the parenthetical expression with the ENT key and confirm your entry with the END key

#### Example: Read overlap factor as Q parameter

#### Parameter settings in the configuration editor

ChannelSettings

CH\_NC

CfgGeoCycle

pocketOverlap

14 DECLARE STRINGQS11 = "CH_NC"	Assign string parameter for key
15 DECLARE STRINGQS12 = "CFGGEOCYCLE"	Assign string parameter for entity
16 DECLARE STRINGQS13 = "POCKETOVERLAP"	Assign string parameter for parameter name
17 Q50 = CFGREAD( KEY_QS11 TAG_QS12 ATR_QS13 )	Read out machine parameter

9.12 Preassigned Q parameters

## 9.12 Preassigned Q parameters

The Q parameters Q100 to Q199 are assigned values by the TNC. The following types of information are assigned to Q parameters:

- Values from the PLC
- Tool and spindle data
- Data on operating status
- Results of measurements from touch probe cycles etc.

The TNC saves the values for the preassigned Q parameters Q108, Q114 and Q115 to Q117 in the unit of measure used by the active program.



9

Do not use preassigned Q parameters (or QS parameters) between **Q100** and **Q199 (QS100** and **QS199)** as calculation parameters in NC programs. Otherwise you might receive undesired results.

#### Values from the PLC: Q100 to Q107

The TNC uses the parameters Q100 to Q107 to transfer values from the PLC to an NC program.

#### Active tool radius: Q108

The active value of the tool radius is assigned to Q108. Q108 is calculated from:

- Tool radius R (tool table or TOOL DEF block)
- Delta value DR from the tool table
- Delta value DR from the TOOL CALL block



The TNC remembers the current tool radius even if the power is interrupted.

### Tool axis: Q109

The value of Q109 depends on the current tool axis:

Tool axis	Parameter value
No tool axis defined	Q109 = -1
X axis	Q109 = 0
Y axis	Q109 = 1
Z axis	Q109 = 2
U axis	Q109 = 6
V axis	Q109 = 7
W axis	Q109 = 8

## Spindle status: Q110

The value of the parameter Q110 depends on the M function last programmed for the spindle.

M function	Parameter value
No spindle status defined	Q110 = -1
M3: Spindle ON, clockwise	Q110 = 0
M4: Spindle ON, counterclockwise	Q110 = 1
M5 after M3	Q110 = 2
M5 after M4	Q110 = 3

## Coolant on/off: Q111

M function	Parameter value
M8: Coolant ON	Q111 = 1
M9: Coolant OFF	Q111 = 0

## Overlap factor: Q112

The overlap factor for pocket milling (pocketOverlap) is assigned to Q112.

# Unit of measurement for dimensions in the program: Q113

During nesting with PGM CALL, the value of the parameter Q113 depends on the dimensional data of the program from which the other programs are called.

Dimensional data of the main program	Parameter value
Metric system (mm)	Q113 = 0
Inch system (inches)	Q113 = 1

## Tool length: Q114

The current value for the tool length is assigned to Q114.



The TNC remembers the current tool length even if the power is interrupted.

9

9.12 Preassigned Q parameters

#### Coordinates after probing during program run

The parameters Q115 to Q119 contain the coordinates of the spindle position at the moment of contact during programmed measurement with the 3-D touch probe. The coordinates refer to the datum point that is active in the Manual Operation mode.

The length of the stylus and the radius of the ball tip are not compensated in these coordinates.

Coordinate axis	Parameter value
X axis	Q115
Y axis	Q116
Z axis	Q117
4th Axis Machine-dependent	Q118
V. axis Machine-dependent	Q119

# Deviation between actual value and nominal value during automatic tool measurement with the TT 130

Deviation of actual from nominal value	Parameter value
Tool length	Q115
Tool radius	Q116

# Tilting the working plane with mathematical angles: rotary axis coordinates calculated by the TNC

Coordinates	Parameter value
A axis	Q120
B axis	Q121
C axis	Q122

# Measurement results from touch probe cycles (see also User's Manual for Cycle Programming)

Measured actual values	Parameter value
Angle of a straight line	Q150
Center in reference axis	Q151
Center in minor axis	Q152
Diameter	Q153
Pocket length	Q154
Pocket width	Q155
Length of the axis selected in the cycle	Q156
Position of the centerline	Q157
Angle in the A axis	Q158
Angle in the B axis	Q159
Coordinate of the axis selected in the cycle	Q160
Measured deviation	Parameter value
Center in reference axis	Q161
Center in minor axis	Q162
Diameter	Q163
Pocket length	Q164
Pocket width	Q165
Measured length	Q166
Position of the centerline	Q167
Determined space angle	Parameter value
Rotation about the A axis	Q170
Rotation about the B axis	Q171
Rotation about the C axis	Q172
Workpiece status	Parameter value
Good	Q180
Rework	Q181
Scrap	Q182

## 9.12 Preassigned Q parameters

Tool measurement with the BLUM laser	Parameter value
Reserved	Q190
Reserved	Q191
Reserved	Q192
Reserved	Q193
Reserved for internal use	Parameter value
Marker for cycles	Q195
Marker for cycles	Q196
Marker for cycles (machining patterns)	Q197
Number of the last active measuring cycle	Q198
Status of tool measurement with TT	Parameter value
Tool within tolerance	Q199 = 0.0
Tool is worn (LTOL/RTOL is exceeded)	Q199 = 1.0
Tool is broken (LBREAK/RBREAK is exceeded)	Q199 = 2.0

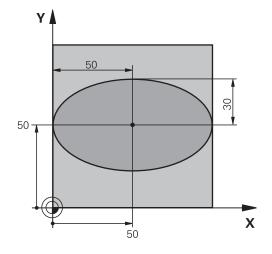
TNC 640 | User's Manual HEIDENHAIN Conversational Programming | 5/2013

## 9.13 Programming examples

## Example: Ellipse

Program sequence

- The contour of the ellipse is approximated by many short lines (defined in Q7). The more calculation steps you define for the lines, the smoother the curve becomes.
- The milling direction is determined with the starting angle and end angle in the plane : Machining direction is clockwise: Starting angle > end angle Machining direction is counterclockwise: Starting angle < end angle</li>
- The tool radius is not taken into account.



0 BEGIN PGM ELLIPSE MM	
1 FN 0: Q1 = +50	Center in X axis
2 FN 0: Q2 = +50	Center in Y axis
3 FN 0: Q3 = +50	Semiaxis in X
4 FN 0: Q4 = +30	Semiaxis in Y
5 FN 0: Q5 = +0	Starting angle in the plane
6 FN 0: Q6 = +360	End angle in the plane
7 FN 0: Q7 = +40	Number of calculation steps
8 FN 0: Q8 = +0	Rotational position of the ellipse
9 FN 0: Q9 = +5	Milling depth
10 FN 0: Q10 = +100	Feed rate for plunging
11 FN 0: Q11 = +350	Feed rate for milling
12 FN 0: Q12 = +2	Set-up clearance for pre-positioning
13 BLK FORM 0.1 Z X+0 Y+0 Z-20	Definition of workpiece blank
14 BLK FORM 0.2 X+100 Y+100 Z+0	
15 TOOL CALL 1 Z S4000	Tool call
16 L Z+250 R0 FMAX	Retract the tool
17 CALL LBL 10	Call machining operation
18 L Z+100 R0 FMAX M2	Retract the tool, end program
19 LBL 10	Subprogram 10: Machining operation
20 CYCL DEF 7.0 DATUM SHIFT	Shift datum to center of ellipse
21 CYCL DEF 7.1 X+Q1	
22 CYCL DEF 7.2 Y+Q2	
23 CYCL DEF 10.0 ROTATION	Account for rotational position in the plane
24 CYCL DEF 10.1 ROT+Q8	
25 Q35 = (Q6 -Q5) / Q7	Calculate angle increment
26 Q36 = Q5	Copy starting angle
27 Q37 = 0	Set counter

TNC 640 | User's Manual HEIDENHAIN Conversational Programming | 5/2013

## 9.13 **Programming examples**

28 Q21 = Q3 *COS Q36	Calculate X coordinate for starting point
29 Q22 = Q4 *SIN Q36	Calculate Y coordinate for starting point
30 L X+Q21 Y+Q22 R0 FMAX M3	Move to starting point in the plane
31 L Z+Q12 RO FMAX	Pre-position in spindle axis to set-up clearance
32 L Z-Q9 R0 FQ10	Move to working depth
33 LBL 1	
34 Q36 = Q36 +Q35	Update the angle
35 Q37 = Q37 +1	Update the counter
36 Q21 = Q3 *COS Q36	Calculate the current X coordinate
37 Q22 = Q4 *SIN Q36	Calculate the current Y coordinate
38 L X+Q21 Y+Q22 R0 FQ11	Move to next point
39 FN 12: IF +Q37 LT +Q7 GOTO LBL 1	Unfinished? If not finished, return to LBL 1
40 CYCL DEF 10.0 ROTATION	Reset the rotation
41 CYCL DEF 10.1 ROT+0	
42 CYCL DEF 7.0 DATUM SHIFT	Reset the datum shift
43 CYCL DEF 7.1 X+0	
44 CYCL DEF 7.2 Y+0	
45 L Z+Q12 R0 FMAX	Move to set-up clearance
46 LBL 0	End of subprogram
47 END PGM ELLIPSE MM	

#### **Example: Concave cylinder machined with spherical** cutter

Program sequence

- This program functions only with a spherical cutter. The tool length refers to the sphere center.
- The contour of the cylinder is approximated by many short line segments (defined in Q13). The more line segments you define, the smoother the curve becomes.
- The cylinder is milled in longitudinal cuts (here: parallel to the Y axis).
- The milling direction is determined with the starting angle and end angle in space : Machining direction clockwise: Starting angle > end angle Machining direction counterclockwise: Starting angle < end angle
- The tool radius is compensated automatically.

1 FN 0: Q1 = +50	Center in X axis
2 FN 0: Q2 = +0	Center in Y axis
3 FN 0: Q3 = +0	Center in Z axis
4 FN 0: Q4 = +90	Starting angle in space (Z/X plane)
5 FN 0: Q5 = +270	End angle in space (Z/X plane)
6 FN 0: Q6 = +40	Cylinder radius
7 FN 0: Q7 = +100	Length of the cylinder
8 FN 0: Q8 = +0	Rotational position in the X/Y plane
9 FN 0: Q10 = +5	Allowance for cylinder radius
10 FN 0: Q11 = +250	Feed rate for plunging
11 FN 0: Q12 = +400	Feed rate for milling
12 FN 0: Q13 = +90	Number of cuts

Definition of workpiece blank

Tool call

Retract the tool

Reset allowance

Call machining operation

Call machining operation

Retract the tool, end program

## **0 BEGIN PGM CYLIN MM**

13 BLK FORM 0.1 Z X+0 Y+0 Z-50

15 TOOL CALL 1 Z S4000

20 L Z+100 R0 FMAX M2

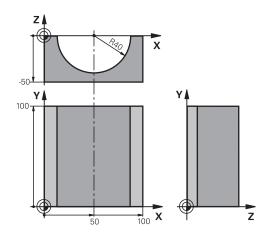
16 L Z+250 R0 FMAX

17 CALL LBL 10

19 CALL LBL 10

18 FN 0: Q10 = +0

14 BLK FORM 0.2 X+100 Y+100 Z+0



## 9.13 **Programming examples**

21 LBL 10	Subprogram 10: Machining operation
22 Q16 = Q6 -Q10 - Q108	Account for allowance and tool, based on the cylinder radius
23 FN 0: Q20 = +1	Set counter
24 FN 0: Q24 = +Q4	Copy starting angle in space (Z/X plane)
25 Q25 = (Q5 -Q4) / Q13	Calculate angle increment
26 CYCL DEF 7.0 DATUM SHIFT	Shift datum to center of cylinder (X axis)
27 CYCL DEF 7.1 X+Q1	
28 CYCL DEF 7.2 Y+Q2	
29 CYCL DEF 7.3 Z+Q3	
30 CYCL DEF 10.0 ROTATION	Account for rotational position in the plane
31 CYCL DEF 10.1 ROT+Q8	
32 L X+0 Y+0 R0 FMAX	Pre-position in the plane to the cylinder center
33 L Z+5 R0 F1000 M3	Pre-position in the spindle axis
34 LBL 1	
35 CC Z+0 X+0	Set pole in the Z/X plane
36 LP PR+Q16 PA+Q24 FQ11	Move to starting position on cylinder, plunge-cutting obliquely into the material
37 L Y+Q7 R0 FQ12	Longitudinal cut in Y+ direction
38 FN 1: Q20 = +Q20 + +1	Update the counter
39 FN 1: Q24 = +Q24 + +Q25	Update solid angle
40 FN 11: IF +Q20 GT +Q13 GOTO LBL 99	Finished? If finished, jump to end
41 LP PR+Q16 PA+Q24 FQ11	Move in an approximated "arc" for the next longitudinal cut
42 L Y+0 R0 FQ12	Longitudinal cut in Y- direction
43 FN 1: Q20 = +Q20 + +1	Update the counter
44 FN 1: Q24 = +Q24 + +Q25	Update solid angle
45 FN 12: IF +Q20 LT +Q13 GOTO LBL 1	Unfinished? If not finished, return to LBL 1
46 LBL 99	
47 CYCL DEF 10.0 ROTATION	Reset the rotation
48 CYCL DEF 10.1 ROT+0	
49 CYCL DEF 7.0 DATUM SHIFT	Reset the datum shift
50 CYCL DEF 7.1 X+0	
51 CYCL DEF 7.2 Y+0	
52 CYCL DEF 7.3 Z+0	
53 LBL 0	End of subprogram
54 END PGM CYLIN	

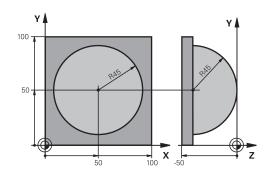
9

#### Example: Convex sphere machined with end mill

Program sequence

This program requires an end mill.

- The contour of the sphere is approximated by many short lines (in the Z/X plane, defined in Q14). The smaller you define the angle increment, the smoother the curve becomes.
- You can determine the number of contour cuts through the angle increment in the plane (defined in Q18).
- The tool moves upward in three-dimensional cuts.
- The tool radius is compensated automatically.



0 BEGIN PGM SPHERE MM	
1 FN 0: Q1 = +50	Center in X axis
2 FN 0: Q2 = +50	Center in Y axis
3 FN 0: Q4 = +90	Starting angle in space (Z/X plane)
4 FN 0: Q5 = +0	End angle in space (Z/X plane)
5 FN 0: Q14 = +5	Angle increment in space
6 FN 0: Q6 = +45	Sphere radius
7 FN 0: Q8 = +0	Starting angle of rotational position in the X/Y plane
8 FN 0: Q9 = +360	End angle of rotational position in the X/Y plane
9 FN 0: Q18 = +10	Angle increment in the X/Y plane for roughing
10 FN 0: Q10 = +5	Allowance in sphere radius for roughing
11 FN 0: Q11 = +2	Set-up clearance for pre-positioning in the spindle axis
12 FN 0: Q12 = +350	Feed rate for milling
13 BLK FORM 0.1 Z X+0 Y+0 Z-50	Definition of workpiece blank
14 BLK FORM 0.2 X+100 Y+100 Z+0	
15 TOOL CALL 1 Z S4000	Tool call
16 L Z+250 R0 FMAX	Retract the tool
17 CALL LBL 10	Call machining operation
18 FN 0: Q10 = +0	Reset allowance
19 FN 0: Q18 = +5	Angle increment in the X/Y plane for finishing
20 CALL LBL 10	Call machining operation
21 L Z+100 R0 FMAX M2	Retract the tool, end program
22 LBL 10	Subprogram 10: Machining operation
23 FN 1: Q23 = +Q11 + +Q6	Calculate Z coordinate for pre-positioning
24 FN 0: Q24 = +Q4	Copy starting angle in space (Z/X plane)
25 FN 1: Q26 = +Q6 + +Q108	Compensate sphere radius for pre-positioning
26 FN 0: Q28 = +Q8	Copy rotational position in the plane
27 FN 1: Q16 = +Q6 + -Q10	Account for allowance in the sphere radius
28 CYCL DEF 7.0 DATUM SHIFT	Shift datum to center of sphere
29 CYCL DEF 7.1 X+Q1	
30 CYCL DEF 7.2 Y+Q2	
31 CYCL DEF 7.3 Z-Q16	
32 CYCL DEF 10.0 ROTATION	Account for starting angle of rotational position in the plane

## 9.13 **Programming examples**

33 CYCL DEF 10.1 ROT+Q8	
34 LBL 1	Pre-position in the spindle axis
35 CC X+0 Y+0	Set pole in the X/Y plane for pre-positioning
36 LP PR+Q26 PA+Q8 R0 FQ12	Pre-position in the plane
37 CC Z+0 X+Q108	Set pole in the Z/X plane, offset by the tool radius
38 L Y+0 Z+0 FQ12	Move to working depth
39 LBL 2	
40 LP PR+Q6 PA+Q24 FQ12	Move upward in an approximated "arc"
41 FN 2: Q24 = +Q24 - +Q14	Update solid angle
42 FN 11: IF +Q24 GT +Q5 GOTO LBL 2	Inquire whether an arc is finished. If not finished, return to LBL 2
43 LP PR+Q6 PA+Q5	Move to the end angle in space
44 L Z+Q23 R0 F1000	Retract in the spindle axis
45 L X+Q26 R0 FMAX	Pre-position for next arc
46 FN 1: Q28 = +Q28 + +Q18	Update rotational position in the plane
47 FN 0: Q24 = +Q4	Reset solid angle
48 CYCL DEF 10.0 ROTATION	Activate new rotational position
49 CYCL DEF 10.0 ROT+Q28	
50 FN 12: IF +Q28 LT +Q9 GOTO LBL 1	
51 FN 9: IF +Q28 EQU +Q9 GOTO LBL 1	Unfinished? If not finished, return to LBL 1
52 CYCL DEF 10.0 ROTATION	Reset the rotation
53 CYCL DEF 10.1 ROT+0	
54 CYCL DEF 7.0 DATUM SHIFT	Reset the datum shift
55 CYCL DEF 7.1 X+0	
56 CYCL DEF 7.2 Y+0	
57 CYCL DEF 7.3 Z+0	
58 LBL 0	End of subprogram
59 END PGM SPHERE MM	

10

Programming: Miscellaneous functions

## **10** Programming: Miscellaneous functions

**10.1 Entering miscellaneous functions M and STOP** 

# 10.1 Entering miscellaneous functions M and STOP

#### **Fundamentals**

With the TNC's miscellaneous functions—also called M functions —you can affect

- the program run, e.g., a program interruption
- the machine functions, such as switching spindle rotation and coolant supply on and off
- the path behavior of the tool



The machine tool builder may add some M functions that are not described in this User's Manual. Refer to your machine manual.

You can enter up to two M functions at the end of a positioning block or in a separate block. The TNC displays the following dialog question: **Miscellaneous function M**?

You usually enter only the number of the M function in the programming dialog. Some M functions can be programmed with additional parameters. In this case, the dialog is continued for the parameter input.

In the Manual Operation and El. Handwheel modes of operation, the M functions are entered with the M soft key.



Please note that some M functions become effective at the start of a positioning block, and others at the end, regardless of their position in the NC block.

M functions come into effect in the block in which they are called.

Some M functions are effective only in the block in which they are programmed. Unless the M function is only effective blockwise, either you must cancel it in a subsequent block with a separate M function, or it is automatically canceled by the TNC at the end of the program.

#### Entering an M function in a STOP block

If you program a STOP block, the program run or test run is interrupted at the block, for example for tool inspection. You can also enter an M function in a STOP block:



- To program an interruption of program run, press the STOP key.
- Enter a miscellaneous function M

#### **Example NC blocks**

87 STOP M6

# 10.2 M functions for program run inspection, spindle and coolant

#### **Overview**



The machine tool builder can influence the behavior of the miscellaneous functions described below. Refer to your machine manual.

М	Effect	Effective at block	Start	End
M0	Program STOP Spindle STOP			-
M1	Optional program STOP Spindle STOP if necessary Coolant OFF if necessary (not effective during Test Run, function determined by the machine tool builder)			•
M2	STOP program run Spindle STOP Coolant OFF Return jump to block 1 CLEAR status display (depending on machine parameter <b>clearMode</b> )			•
M3	Spindle ON clo	ockwise		
M4	Spindle ON co	unterclockwise		
M5	Spindle STOP			
M6	Tool change Spindle STOP Program STOP			•
M8	Coolant ON			
M9	Coolant OFF			
M13	Spindle ON clo Coolant ON	ockwise	•	
M14	Spindle ON co Coolant ON	unterclockwise	•	
M30	Same as M2			-

349

## **10** Programming: Miscellaneous functions

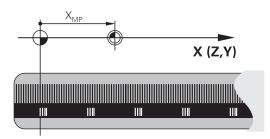
**10.3** Miscellaneous functions for coordinate data

# 10.3 Miscellaneous functions for coordinate data

#### Programming machine-referenced coordinates: M91/ M92

#### Scale reference point

On the scale, a reference mark indicates the position of the scale reference point.



#### Machine datum

The machine datum is required for the following tasks:

- Defining the limits of traverse (software limit switches)
- Approach machine-referenced positions (such as tool change positions)
- Set a workpiece datum

The distance in each axis from the scale reference point to the machine datum is defined by the machine tool builder in a machine parameter.

#### Standard behavior

The TNC references coordinates to the workpiece datum (See "Datum setting without a 3-D touch probe", page 507).

#### Behavior with M91-Machine datum

If you want the coordinates in a positioning block to be referenced to the machine datum, end the block with M91.



If you program incremental coordinates in an M91 block, enter them with respect to the last programmed M91 position. If no M91 position is programmed in the active NC block, then enter the coordinates with respect to the current tool position.

The coordinate values on the TNC screen are referenced to the machine datum. Switch the display of coordinates in the status display to REF (See "Status displays", page 75).

#### Behavior with M92–Additional machine datum

•

In addition to the machine datum, the machine tool builder can also define an additional machine-based position as a reference point.

For each axis, the machine tool builder defines the distance between the machine datum and this additional machine datum. Refer to your machine manual.

If you want the coordinates in a positioning block to be based on the additional machine datum, end the block with M92.



Radius compensation remains the same in blocks that are programmed with M91 or M92. The tool length, however, is **not** compensated.

#### Effect

M91 and M92 are effective only in the blocks in which they are programmed.

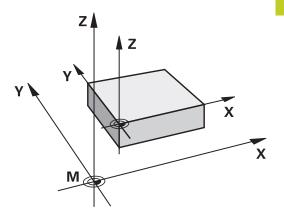
M91 and M92 take effect at the start of block.

#### Workpiece datum

If you want the coordinates to always be referenced to the machine datum, you can inhibit datum setting for one or more axes.

If datum setting is inhibited for all axes, the TNC no longer displays the SET DATUM soft key in the Manual Operation mode.

The figure shows coordinate systems with the machine datum and workpiece datum.



#### M91/M92 in the Test Run mode

In order to be able to graphically simulate M91/M92 movements, you need to activate working space monitoring and display the workpiece blank referenced to the set datum (See "Showing the workpiece blank in the working space ", page 565).

## **10** Programming: Miscellaneous functions

**10.3** Miscellaneous functions for coordinate data

# Moving to positions in a non-tilted coordinate system with a tilted working plane: M130

#### Standard behavior with a tilted working plane

The TNC places the coordinates in the positioning blocks in the tilted coordinate system.

#### **Behavior with M130**

The TNC places coordinates in straight line blocks in the untilted coordinate system.

The TNC then positions the (tilted) tool to the programmed coordinates of the untilted system.



#### Danger of collision!

Subsequent positioning blocks or fixed cycles are carried out in a tilted coordinate system. This can lead to problems in fixed cycles with absolute prepositioning.

The function M130 is allowed only if the tilted working plane function is active.

#### Effect

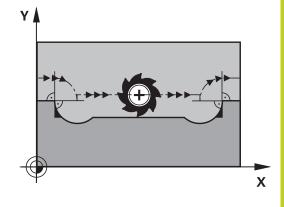
M130 functions blockwise in straight-line blocks without tool radius compensation.

# 10.4 Miscellaneous functions for path behavior

#### Machining small contour steps: M97

#### Standard behavior

The TNC inserts a transition arc at outside corners. If the contour steps are very small, however, the tool would damage the contour In such cases the TNC interrupts program run and generates the error message "Tool radius too large."

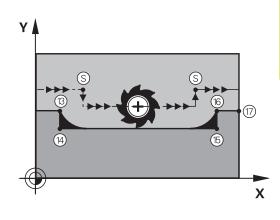


#### **Behavior with M97**

The TNC calculates the intersection of the contour elements—as at inside corners—and moves the tool over this point.

Program M97 in the same block as the outside corner.

Instead of **M97** you should use the much more powerful function **M120 LA**,See "Calculating the radius-compensated path in advance (LOOK AHEAD): M120 (Miscellaneous Functions software option)"



#### Effect

M97 is effective only in the blocks in which it is programmed.



A corner machined with M97 will not be completely finished. You may wish to rework the contour with a smaller tool.

#### Example NC blocks

5 TOOL DEF L R+20	Large tool radius
13 L X Y R F M97	Move to contour point 13
14 L IY-0.5 R F	Machine small contour step 13 to 14
15 L IX+100	Move to contour point 15
16 L IY+0.5 R F M97	Machine small contour step 15 to 16
17 L X Y	Move to contour point 17

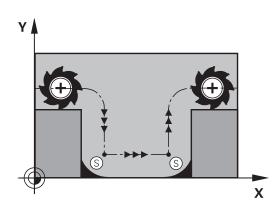
## **10** Programming: Miscellaneous functions

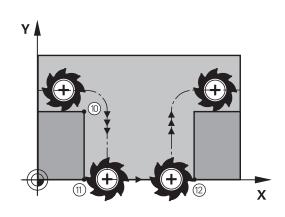
**10.4** Miscellaneous functions for path behavior

#### Machining open contour corners: M98

#### Standard behavior

The TNC calculates the intersections of the cutter paths at inside corners and moves the tool in the new direction at those points. If the contour is open at the corners, however, this will result in incomplete machining.





#### **Behavior with M98**

With the miscellaneous function M98, the TNC temporarily suspends radius compensation to ensure that both corners are completely machined:

#### Effect

M98 is effective only in the blocks in which it is programmed. M98 takes effect at the end of block.

#### **Example NC blocks**

Move to the contour points 10, 11 and 12 in succession:

10 L X Y RL F	
11 L X IY M98	
12 L IX+	

#### Feed rate factor for plunging movements: M103

#### **Standard behavior**

The TNC moves the tool at the last programmed feed rate, regardless of the direction of traverse.

#### **Behavior with M103**

The TNC reduces the feed rate when the tool moves in the negative direction of the tool axis. The feed rate for plunging FZMAX is calculated from the last programmed feed rate FPROG and a factor F%:

FZMAX = FPROG x F%

#### **Programming M103**

If you enter M103 in a positioning block, the TNC continues the dialog by asking you the factor  $\ensuremath{\mathsf{F}}$ 

#### Effect

M103 becomes effective at the start of block. To cancel M103, program M103 once again without a factor.



M103 is also effective in an active tilted working plane. The feed rate reduction is then effective during traverse in the negative direction of the **tilted** tool axis.

#### **Example NC blocks**

The feed rate for plunging is to be 20% of the feed rate in the plane.

	Actual contouring feed rate (mm/min):
17 L X+20 Y+20 RL F500 M103 F20	500
18 L Y+50	500
19 L IZ-2.5	100
20 L IY+5 IZ-5	141
21 L IX+50	500
22 L Z+5	500

## **10** Programming: Miscellaneous functions

**10.4** Miscellaneous functions for path behavior

#### Feed rate in millimeters per spindle revolution: M136

#### **Standard behavior**

The TNC moves the tool at the programmed feed rate F in mm/min

#### Behavior with M136



In inch-programs, M136 is not permitted in combination with the new alternate feed rate FU. The spindle is not permitted to be controlled when M136 is active.

With M136, the TNC does not move the tool in mm/min, but rather at the programmed feed rate F in millimeters per spindle revolution. If you change the spindle speed by using the spindle override, the TNC changes the feed rate accordingly.

#### Effect

M136 becomes effective at the start of block. You can cancel M136 by programming M137.

#### Feed rate for circular arcs: M109/M110/M111

#### Standard behavior

The TNC applies the programmed feed rate to the path of the tool center.

#### Behavior at circular arcs with M109

The TNC adjusts the feed rate for circular arcs at inside and outside contours so that the feed rate at the tool cutting edge remains constant.



#### Caution: Danger to the workpiece and tool!

On very small outside corners the TNC may increase the feed rate so much that the tool or workpiece can be damaged. Avoid **M109** with small outside corners.

#### Behavior at circular arcs with M110

The TNC keeps the feed rate constant for circular arcs at inside contours only. At outside contours, the feed rate is not adjusted.



If you define M109 or M110 before calling a machining cycle with a number greater than 200, the adjusted feed rate is also effective for circular arcs within these machining cycles. The initial state is restored after finishing or aborting a machining cycle.

#### Effect

M109 and M110 become effective at the start of block. To cancel M109 or M110, enter M111.

## **10** Programming: Miscellaneous functions

10.4 Miscellaneous functions for path behavior

# Calculating the radius-compensated path in advance (LOOK AHEAD): M120

#### **Standard behavior**

If the tool radius is larger than the contour step that is to be machined with radius compensation, the TNC interrupts program run and generates an error message. M97 (See "Machining small contour steps: M97", page 353) inhibits the error message, but this results in dwell marks and will also move the corner.

If the programmed contour contains undercut features, the tool may damage the contour.

#### Behavior with M120

The TNC checks radius-compensated paths for contour undercuts and tool path intersections, and calculates the tool path in advance from the current block. Areas of the contour that might be damaged by the tool are not machined (dark areas in figure). You can also use M120 to calculate the radius compensation for digitized data or data created on an external programming system. This means that deviations from the theoretical tool radius can be compensated.

Use LA (Look Ahead) behind M120 to define the number of blocks (maximum: 99) that you want the TNC to calculate in advance. Note that the larger the number of blocks you choose, the higher the block processing time will be.



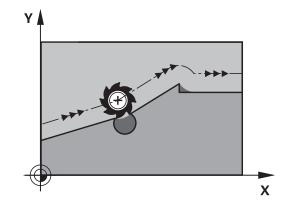
If you enter M120 in a positioning block, the TNC continues the dialog for this block by asking you the number of blocks LA that are to be calculated in advance.

#### Effect

M120 must be located in an NC block that also contains radius compensation **RL** or **RR**. M120 is then effective from this block until

- radius compensation is canceled with RO
- M120 LA0 is programmed, or
- M120 is programmed without LA, or
- another program is called with PGM CALL
- the working plane is tilted with Cycle 19 or the PLANE function

M120 becomes effective at the start of block.



10

#### Restrictions

- After an external or internal stop, you can only re-enter the contour with the function RESTORE POS. AT N. Before you start the block scan, you must cancel M120, otherwise the TNC will output an error message.
- When using the path functions RND and CHF, the blocks before and after RND or CHF must contain only coordinates in the working plane.
- If you want to approach the contour on a tangential path, you must use the function APPR LCT. The block with APPR LCT must contain only coordinates of the working plane
- If you want to depart the contour on a tangential path, use the function DEP LCT. The block with DEP LCT must contain only coordinates of the working plane
- Before using the functions listed below, you have to cancel M120 and the radius compensation:
  - Cycle 32 Tolerance
  - Cycle 19 Working plane
  - PLANE function
  - M114
  - M128
  - TCPM FUNCTION

## **10** Programming: Miscellaneous functions

10.4 Miscellaneous functions for path behavior

# Superimposing handwheel positioning during program run: M118

#### Standard behavior

In the program run modes, the TNC moves the tool as defined in the part program.

#### **Behavior with M118**

M118 permits manual corrections by handwheel during program run. Just program M118 and enter an axis-specific value (linear or rotary axis) in millimeters.



The handwheel superimpositioning function with M118 in combination with collision monitoring is only possible in stopped condition. To be able to use M118 without limitations, you have to deselect DCM either by soft key in the menu, or activate a kinematics model without collision monitored objects (CMOs)

#### Input

If you enter M118 in a positioning block, the TNC continues the dialog for this block by asking you the axis-specific values. The coordinates are entered with the orange axis direction buttons or the ASCII keyboard.

#### Effect

Cancel handwheel positioning by programming M118 once again without coordinate input.

M118 becomes effective at the start of block.

#### **Example NC blocks**

You want to be able to use the handwheel during program run to move the tool in the working plane X/Y by  $\pm 1$  mm and in the rotary axis B by  $\pm 5^{\circ}$  from the programmed value:

#### L X+0 Y+38.5 RL F125 M118 X1 Y1 B5



M118 is effective in a tilted coordinate system if you activate the tilted working plane function for the Manual Operation mode. If the tilted working plane function is not active for the Manual Operation mode, the original coordinate system is effective.

M118 also functions in the Positioning with MDI mode of operation!

If M118 is active, the MANUAL TRAVERSE function is not available after a program interruption!

10

#### Virtual tool axis VT



Your machine tool builder must have prepared the TNC for this function. Refer to your machine manual.

With the virtual tool axis you can also traverse in the direction of a sloping tool with the handwheel with machines with swivel heads. To traverse in a virtual tool axis direction select the VT axis on the display of your handwheel, See "Traverse with electronic handwheels", page 490. With an HR 5xx handwheel you can select the virtual axis directly with the orange VI axis key if required (refer to your machine manual).

You can also carry out handwheel superimpositioning in the currently active tool axis direction with the M118 function. For this purpose, you must at least define the spindle axis with the permitted traverse range (e.g. M118 Z5) in the M118 function and select the VT axis on the handwheel.

# **10** Programming: Miscellaneous functions

**10.4** Miscellaneous functions for path behavior

# Retraction from the contour in the tool-axis direction: M140

#### **Standard behavior**

In the program run modes, the TNC moves the tool as defined in the part program.

#### **Behavior with M140**

With M140 MB (move back) you can enter a path in the direction of the tool axis for departure from the contour.

#### Input

If you enter M140 in a positioning block, the TNC continues the dialog and asks for the desired path of tool departure from the contour. Enter the requested path that the tool should follow when departing the contour, or press the MB MAX soft key to move to the limit of the traverse range.

In addition, you can program the feed rate at which the tool traverses the entered path. If you do not enter a feed rate, the TNC moves the tool along the entered path at rapid traverse.

#### Effect

M140 is effective only in the block in which it is programmed. M140 becomes effective at the start of block.

#### **Example NC blocks**

Block 250: Retract the tool 50 mm from the contour.

Block 251: Move the tool to the limit of the traverse range.

# 250 L X+0 Y+38.5 F125 M140 MB 50 F750

#### 251 L X+0 Y+38.5 F125 M140 MB MAX



M140 is also effective if the tilted-working-plane function is active. On machines with tilting heads, the TNC then moves the tool in the tilted coordinate system.

With **M140 MB MAX** you can only retract in the positive direction.

Always define a TOOL CALL with a tool axis before entering **M140**, otherwise the direction of traverse is not defined.



#### Danger of collision!

When dynamic collision monitoring (DCM) is active, the TNC might move the tool only until it detects a collision and, from there, complete the NC program without any error message. This can result in tool paths different from those programmed!

# Suppressing touch probe monitoring: M141

#### **Standard behavior**

When the stylus is deflected, the TNC outputs an error message as soon as you attempt to move a machine axis.

#### **Behavior with M141**

The TNC moves the machine axes even if the touch probe is deflected. This function is required if you wish to write your own measuring cycle in connection with measuring cycle 3 in order to retract the stylus by means of a positioning block after it has been deflected.



#### Danger of collision!

If you use M141, make sure that you retract the touch probe in the correct direction. M141 functions only for movements with straightline blocks.

#### Effect

M141 is effective only in the block in which it is programmed. M141 becomes effective at the start of block.

# **10** Programming: Miscellaneous functions

**10.4** Miscellaneous functions for path behavior

# **Deleting basic rotation: M143**

#### Standard behavior

The basic rotation remains in effect until it is reset or is overwritten with a new value.

#### **Behavior with M143**

The TNC erases a programmed basic rotation from the NC program.



The function **M143** is not permitted during midprogram startup.

## Effect

M143 is effective only in the block in which it is programmed. M143 becomes effective at the start of the block.

# Automatically retract tool from the contour at an NC stop: M148

## Standard behavior

At an NC stop the TNC stops all traverse movements. The tool stops moving at the point of interruption.

## Behavior with M148



The M148 function must be enabled by the machine tool builder. The machine tool builder defines in a machine parameter the path that the TNC is to traverse for a **LIFTOFF** command.

The TNC retracts the tool by up to 2 mm in the direction of the tool axis if, in the LIFTOFF column of the tool table, you set the parameter  $\mathbf{Y}$  for the active tool See "Enter tool data into the table", page 160.

LIFTOFF takes effect in the following situations:

- An NC stop triggered by you
- An NC stop triggered by the software, e.g. if an error occurred in the drive system
- When a power interruption occurs

#### Danger of collision!

Remember that, especially on curved surfaces, the surface can be damaged during return to the contour. Retract the tool before returning to the contour!

In the **CfgLiftOff** machine parameter, define the value by which the tool is to be retracted. In the **CfgLiftOff** machine parameter you can also switch the function off.

# Effect

M148 remains in effect until deactivated with M149.

M148 becomes effective at the start of block, M149 at the end of block.

# **10** Programming: Miscellaneous functions

**10.4** Miscellaneous functions for path behavior

### **Rounding corners: M197**

#### **Standard behavior**

The TNC inserts a transition arc at outside corners with active radius compensation. This my lead to grinding of the edge.

#### **Behavior with M197**

With Function M197 the contour at the corner is tangentially extended and a smaller transition arc is then inserted. When you program Function M197 and then press the ENT key, the TNC opens the **DL** input field. In **DL** you define the length with which the TNC extends the contour elements. With M197 the corner radius is reduced, the corner grinds less and the traverse movement is still tangential.

#### Effect

The Function M197 is effective blockwise and is only effective on outside corners.

**Example NC blocks** 

L X... Y... RL M197 DL0.876

# 

Programming: Special functions

11.1 Overview of special functions

# **11.1** Overview of special functions

The TNC provides the following powerful special functions for a large number of applications:

Function	Description
Dynamic Collision Monitoring (DCM— software option)	page 371
Adaptive Feed Control Software Option (AFC —software option)	page 377
Active Chatter Control (ACC—software option)	page 389
Working with text files	page 398
Working with freely definable tables	page 402

Press the SPEC FCT and the corresponding soft keys to access further special functions of the TNC. The following tables will give you an overview of which functions are available.

# Main menu for SPEC FCT special functions

- SPEC FCT
- Press the special functions key

Function	Soft key	Description
Define program defaults	PROGRAM DEFAULTS	page 369
Functions for contour and point machining	CONTOUR + POINT MACHINING	page 369
Define the <b>PLANE</b> function	TILT MACHINING PLANE	page 413
Define different conversational functions	PROGRAM FUNCTIONS	page 370
Define turning functions	TURNING PROGRAM FUNCTIONS	page 461
Define structure items	INSERT SECTION	page 135

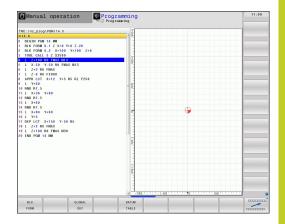
After pressing the SPEC FCT key, you can open the **smartSelect** selection window with the GOTO key. The TNC displays a structure overview with all available functions. You can rapidly navigate with the cursor or mouse and select functions in the tree diagram. The TNC displays online help for the specific functions in the window on the right.

# Program defaults menu



Select the program defaults menu

Function	Soft key	Description
Define workpiece blank	BLK FORM	page 95
Select datum table	DATUM TABLE	See User's Manual for Cycles



# Functions for contour and point machining menu

	CONTOUR
L	+ POINT
	MACHINING

 Select the menu for functions for contour and point machining

Function	Soft key	Description
Assign contour description	DECLARE	See User's Manual for Cycles
Define a simple contour formula	CONTOUR DEF	See User's Manual for Cycles
Select a contour definition	SEL CONTOUR	See User's Manual for Cycles
Define a complex contour formula	CONTOUR FORMULA	See User's Manual for Cycles
Define regular machining pattern	PATTERN DEF	See User's Manual for Cycles
Select the point file with machining positions	SEL PATTERN	See User's Manual for Cycles

Manual operation SProg	ramming rawning	11:09
C regi     C rer		
DECLARE CONTOUR SEL SEL PROFILE CONTOUR DEF CONTOUR CONTOUR	CONTOUR PATTERN SEL FORMULA DEF PATTERN	

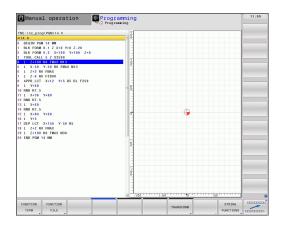
**11.1** Overview of special functions

# Menu of various conversational functions

FUNCTIONS

 Select the menu for defining various conversational functions

Function	Soft key	Description
Define the positioning behavior for rotary axes	ТСРМ	page 442
Define file functions	FUNCTION FILE	page 394
Define the positioning behavior for parallel axes U, V, W	FUNCTION PARAX	page 390
Define coordinate transformations	TRANSFORM	page 395
Define string functions	STRING FUNCTIONS	page 325
Add comments	INSERT COMMENT	page 132



# 11.2 Dynamic Collision Monitoring (software option)

# Function

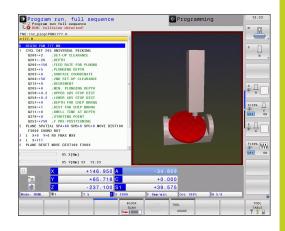


The Dynamic Collision Monitoring **DCM** must be adapted by the machine manufacturer for the TNC and for the machine. Refer to your machine manual.

The machine manufacturer can define any objects that are monitored by the TNC during all machining operations. If two objects monitored for collision come within a defined distance of each other, the TNC outputs an error message.

The TNC can display the defined collision objects graphically in all machine modes of operation, See "Graphic depiction of the protected space", page 376.

The TNC also monitors the current tool with the length and radius entered in the tool table for collision (assuming a cylindrical tool). TNC likewise monitors the stepped tools according to the definition in the tool table and also displays it accordingly.



# 11.2 Dynamic Collision Monitoring (software option)



#### Keep these constraints in mind:

- DCM helps to reduce the danger of collision. However, the TNC cannot consider all possible constellations in operation.
- Collisions of defined machine components and the tool with the workpiece are not detected by the TNC.
- DCM can only protect those machine components from collision that your machine tool builder has correctly defined with regard to dimensions, orientation and position.
- The TNC can monitor the tool only if a **positive tool radius** has been defined in the tool table. The TNC cannot monitor tools with a radius of 0 (as is often used in drilling tools) and therefore issues an appropriate warning.
- The TNC can only monitor tools for which you have defined **positive tool lengths**.
- When a touch probe cycle starts, the TNC no longer monitors the stylus length and ball-tip diameter so that you can also probe in collision objects.
- For certain tools (such as face milling cutters), the diameter that would cause a collision can be greater than the dimensions defined in the toolcompensation data.
- The handwheel superimpositioning function with M118 in combination with collision monitoring is only possible in stopped condition. To be able to use M118 without limitations, you have to deselect DCM either by soft key in the Collision Monitoring (DCM) menu, or activate a kinematics model without collision monitored objects (CMOs).
- For tapping with a floating tap holder only the basic setting of the floating tap holder is taken into account.
- The tool oversizes **DL** and **DR** from the tool table are taken into account by the TNC. Tool oversizes in the **TOOL CALL** are not taken into account.



The TNC cannot implement collision monitoring if with an axis-direction key or the handwheel you carry out a movement over several axes simultaneously. For example such a movement with several axes is implemented as follows:

- In the tilted working plane on a machine with swivel head (sloping tool).
- With active TCPM

This monitoring is first supported with software 34059x-03.

# Collision monitoring in the manual operating modes

In the **Manual Operation** and **El. Handwheel** operating modes, the TNC stops a motion if two objects monitored for collision approach each other within a distance of 1 to 2 mm. In this case, the TNC displays an error message naming the two objects causing collision.

If you have selected a screen layout in which positions are displayed on the left and collision objects on the right, then the TNC additionally marks the colliding objects in red.



Once a collision warning is displayed, machine motions via the direction keys or handwheel are possible only if the motion increases the distance between the collision objects. For example, by pressing the axis direction key for the opposite direction.

Motions that reduce the distance or leave it unchanged are not allowed as long as collision monitoring is active. 11

# 11.2 Dynamic Collision Monitoring (software option)

#### **Deactivating collision monitoring**

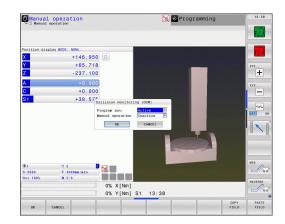
If you have to reduce the distance between collision-monitored objects for lack of space, the collision monitoring function can be deactivated.



## Danger of collision!

If you deactivate collision monitoring, the TNC does not output an error message with a pending collision. With inactive collision monitoring the symbol for collision monitoring in the operating mode bar starts to blink:

In addition, the TNC shows a corresponding symbol in the position display (see the table below).



Symbols in the status display show the condition of collision monitoring:

Function	Symbol
Collision monitoring active	<b>*</b> - <u>u</u>
Collision monitoring is not available	$\times$
Collision monitoring is not active	



Shift the soft-key row if necessary



- Select the menu for deactivating collision monitoring
- Select the Manual Operation menu item
- To deactivate collision monitoring, press the ENT key, and the symbol for collision monitoring in the operating mode display starts to blink
- Move axes manually, pay attention to traverse direction
- ▶ To reactivate the collision monitor: Press the ENT key

# **Collision monitoring in Automatic operation**

The handwheel superimpositioning function with M118 in combination with collision monitoring is only possible in stopped condition.

If collision monitoring is on, the TNC shows the

symbol  $^{\sim}$  in the position display.

If you have deactivated collision monitoring, the symbol for collision monitoring flashes in the operating-mode bar.



#### Danger of collision!

The M140 (See "Retraction from the contour in the tool-axis direction: M140") and M150 (See "") functions might cause non-programmed movements if the TNC detects a collision when executing these functions!

The TNC monitors motions blockwise, i.e. it outputs a warning in the block which would cause a collision, and interrupts program run. A reduction of the feed rate, as with Manual Operation, does not occur. The TNC outputs a collision warning if two objects monitored for collision approach each other within a distance of 5 mm. 11

11

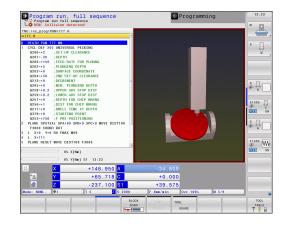
# 11.2 Dynamic Collision Monitoring (software option)

## Graphic depiction of the protected space

You can use the split-screen layout key to have the machinebased collision objects and measured fixtures be shown in three dimensions See "Program Run, Full Sequence and Program Run, Single Block", page 74.

You can switch between the various views via soft key:

Function	Soft key
Switch between wire-frame and solid-object view	
Switch between solid and transparent view	
Display/hide the coordinate systems that result from transformations in the kinematics description	
Functions for rotating in the X and Z axes, and magnifying/reducing	EZ Q



You can also use the mouse for the graphics. The following functions are available:

- In order to rotate the wire model shown in three dimensions you hold the right mouse button down and move the mouse. After you release the right mouse button, the TNC orients the workpiece to the defined orientation
- In order to shift the model shown: Hold the center mouse button or the wheel button down and move the mouse. The TNC shifts the model in the corresponding direction. After you release the center mouse button, the TNC shifts the model to the defined position
- In order to zoom in on a certain area with the mouse: Draw a rectangular zoom area while holding the left mouse button down. You can shift the zoom area by moving the mouse horizontally and vertically as required. After you release the left mouse button, the TNC zooms in on the defined area of the workpiece
- In order to quickly zoom in and out with the mouse: Rotate the wheel button forward or backward
- Double-click with the right mouse button: Select standard view

# 11.3 Adaptive Feed Control Software Option (AFC)

# Application



This feature must be enabled and adapted by the machine tool builder.

Refer to your machine manual.

Your machine tool builder may also have specified whether the TNC uses the spindle power or any other value as the input value for the feed control.

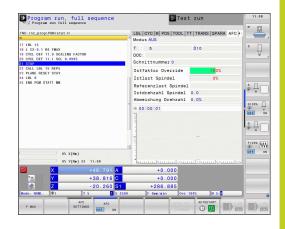
Adaptive feed control is not intended for tools with diameters less than 5 mm. This limit diameter might also be greater if the spindle's rated power is very high.

Do not work with adaptive feed control in operations in which the feed rate and spindle speed must be adapted to each other, such as tapping.

In adaptive feed control the TNC automatically controls the feed rate during program run as a function of the current spindle power consumption. The spindle power required for each machining step is to be recorded in a teach-in cut and saved by the TNC in a file belonging to the part program. When each machining step is started, which is normally when the spindle is switched on, the TNC controls the feed rate so that it remains within the limits that you have defined.

This makes it possible to avoid negative effects on the tool, the workpiece, and the machine that might be caused by changing cutting conditions. Cutting conditions are changed particularly by:

- Tool wear
- Fluctuating cutting depths that occur especially with cast parts
- Fluctuating hardness caused by material flaws



# **11.3 Adaptive Feed Control Software Option (AFC)**

Adaptive feed control (AFC) offers the following benefits:

Optimization of machining time

By controlling the feed rate, the TNC tries to maintain the recorded maximum spindle power during the entire machining time. It shortens the machining time by increasing the feed rate in machining zones with little material removal.

Tool monitoring

If the spindle power exceeds the recorded maximum value, the TNC decreases the feed rate until the reference spindle power is reattained. If the maximum spindle power is exceeded during machining and at the same time the feed rate falls below the minimum that you defined, the TNC reacts by shutting down. This helps to prevent further damage after a tool breaks or is worn out.

 Protection of the machine's mechanical elements
 Timely feed rate reduction and shutdown responses help to avoid machine overload

# Defining the AFC basic settings

You make the control settings for the TNC feed rate control in the table **AFC.TAB**, which must be saved in the root directory **TNC: \table**.

The data in this table are default values that were copied during a teach-in cut into a file belonging to the respective program and serve as the basis for control. The following data are to be defined in this table:

Column	Function
NR	Consecutive line number in the table (has no further functions)
AFC	Name of the control setting. You enter this name in the <b>AFC</b> column of the tool table. It specifies the assignment of control parameters to the tool.
FMIN	Feed rate at which the TNC is to conduct a shutdown response. Enter the value in percent with respect to the programmed feed rate. Input range: 50 to 100 %
FMAX	Maximum feed rate in the material up to which the TNC can automatically increase the feed rate. Enter the value in percent of the programmed feed rate.
FIDL	Feed rate for traverse when the tool is not cutting (feed rate in the air). Enter the value in percent of the programmed feed rate.
FENT	Feed rate for traverse when the tool moves into or out of the material. Enter the value in percent with respect to the programmed feed rate. Maximum input value: 100 %

11

# **11.3 Adaptive Feed Control Software Option (AFC)**

Column	Function
OVLD	<ul> <li>Desired reaction of the TNC to overload:</li> <li>M: Execution of a macro defined by the machine tool builder</li> <li>S: Immediate NC stop</li> <li>F: NC stop if the tool has been retracted</li> <li>E: Just display an error message on the screen</li> <li>-: No overload reaction</li> </ul>
	The TNC conducts a shutdown response if the maximum spindle power is exceeded for more than one second and at the same time the feed rate falls below the minimum you defined. Enter the desired function via the ASCII keyboard.
POUT	Spindle power at which the TNC is to detect tool exit from the workpiece. Enter the value in percent of the learned reference load. Recommended input value: 8 %
SENS	Sensitivity (aggressiveness) of feedback control. A value between 50 and 200 can be entered. 50 is for slow control, 200 for a very aggressive control. An aggressive control reacts quickly and with strong changes to the values, but it tends to overshoot. Recommended value: 100
PLC	Value that the TNC is to transfer to the PLC at the beginning of a machining step. The machine tool builder defines the function, so refer to your machine manual.
⇒	In the <b>AFC.TAB</b> table you can define as many control settings (lines) as desired. If there is no AFC.TAB table in the <b>TNC:\table</b> directory, the TNC uses permanently defined internal control settings for the teach-in cut. It is best, however, to work with the AFC.TAB table.

Proceed as follows to create the AFC.TAB file (only necessary if the file does not yet exist):

- Select the **Programming and Editing** operating mode
- ► Call the file manager: Press the PGM MGT key
- ► Select the **TNC:**\ directory
- Make the new file AFC.TAB and confirm with the ENT key: The TNC shows a list of table formats
- Select the AFC.TAB table format and confirm with the ENT key: The TNC creates a table with the Standard control settings

11

11.3 Adaptive Feed Control Software Option (AFC)

# Recording a teach-in cut

0 - 1 - - - - - -

With a teach-in cut the TNC firstly copies the basic settings defined in the AFC.TAB table into the file **<name>.H.AFC.DEP** for each machining step. **<name>** is the name of the NC program for which you have recorded the teach-in cut. In addition, the TNC measures the maximum spindle power consumed during the teach-in cut and saves this value in the table.

Each line in the **<name>.H.AFC.DEP** file stands for a machining step that you start with **M3** or **M4** and end with **M5**. You can edit all data of the **<name>.H.AFC.DEP** file if you wish to optimize them. If you have optimized the values in comparison with the values in the AFC.TAB table, the TNC places an asterisk **\*** in front of the control settings in the AFC column. Besides the data from the AFC.TAB table See "Defining the AFC basic settings", page 379, the TNC saves the following additional information in the **<name>.H.AFC.DEP** file:

Column	Function
NR	Number of the machining step
TOOL	Number or name of the tool with which the machining step was made (not editable)
IDX	Index of the tool with which the machining step was made (not editable)
Ν	<ul><li>Difference for tool call:</li><li><b>0</b>: Tool was called by its tool number</li></ul>
	<ul> <li>1: Tool was called by its tool name</li> </ul>
PREF	Reference load of the spindle. The TNC measures the value in percent with respect to the rated power of the spindle
ST	<ul> <li>Status of the machining step:</li> <li>L: In the next program run, a teach-in cut is recorded for this machining step. The TNC overwrites any existing values in this line</li> <li>C: The teach-in cut was successfully completed. The next program run can be conducted with automatic feed control</li> </ul>
AFC	Name of the control setting

Remember the following before you record a teach-in cut:

- If required, adapt the control settings in the AFC.TAB table
- Enter the desired control setting for all tools in the AFC column of the tool table TOOL.T
- Select the program for teach-in
- Activate the adaptive feed control by soft key, See "Activating/ deactivating AFC", page 385



When you are performing a teach-in cut, the TNC shows the spindle reference power determined until this time in a pop-up window.

You can reset the reference power at any time by pressing the PREF RESET soft key. The TNC then restarts the learning phase.

When you record a teach-in cut, the TNC internally sets the spindle override to 100 %. Then you can no longer change the spindle speed.

During the teach-in cut, you can influence the measured reference load by using the feed rate override to make any changes to the contouring feed rate.

You do not have to run the entire machining step in the learning mode. If the cutting conditions do not change significantly, you can switch to the control mode immediately. Press the EXIT LEARNING soft key, and the status changes from L to C.

You can repeat a teach-in cut as often as desired. Manually change the status from **ST** back to **L**. It may be necessary to repeat the teach-in cut if the programmed feed rate is far too fast, and forces you to sharply decrease the feed rate override during the machining step.

The TNC changes the status from teach-in **(L)** to controlling **(C)** only when the recorded reference load is greater than 2 %. Adaptive feed control is not possible for smaller values.

11

#### **Adaptive Feed Control Software Option (AFC)** 11.3

•	You can teach any number of machining steps for a tool. Your machine tool builder will either make a function available for this, or will integrate this possibility in the functions for switching on the spindle. Refer to your machine manual.
	You machine tool builder can provide a feature with which the teach-in cut can be automatically ended after a selectable time. Refer to your machine manual.
	In addition, your machine tool builder can integrate a function with which you can directly enter the reference power of the spindle, if it is known. In this case a teach-in step is not required.
	The functions for starting and ending a machining step are machine-dependent. Refer to your machine manual.
	follows to select and, if required, edit the <b>AFC.DEP</b> file:
<b>-</b>	<ul> <li>Select the Program Run, Full Sequence operating mode</li> </ul>
$\triangleleft$	<ul> <li>Shift the soft-key row</li> </ul>
AFC SETTINGS	<ul> <li>Select the table of AFC settings</li> </ul>
	<ul> <li>Make optimizations if required</li> </ul>
$\Rightarrow$	Note that the <b><name>.H.AFC.DEP</name></b> file is locked against editing as long as the NC program <b><name>.H</name></b>

is running. The TNC removes the editing lock if one of the following functions has been executed:

- M02
- M30
- END PGM

You can also edit the <name>.H.AFC.DEP file in the Programming and Editing mode of operation. If necessary, you can even delete a machining step (entire line) there.



In order to edit the <name>.H.AFC.DEP file, you must first set the file manager so that all file types can be displayed (SELECT TYPE soft key) Also see: Files, page 105

# Activating/deactivating AFC



- Select the Program Run, Full Sequence operating mode
- Shift the soft-key row



AFC

- To activate the adaptive feed control: Set the soft key to ON, and the TNC displays the AFC symbol in the position display, See "Status displays", page 75
- To deactivate the adaptive feed control: Set the soft key to OFF

The adaptive feed control remains active until you deactivate it by soft key. The TNC remembers the setting of the soft key even if the power is interrupted.

If the adaptive feed control is active in the **control** mode, the TNC internally sets the spindle override to 100 %. Then you can no longer change the spindle speed.

If the adaptive feed control is active in the **control** mode, the TNC takes over the feed rate override function:

- If you increase the feed rate override, it has no influence on the control.
- If you decrease the feed rate override by more than 10 % with respect to the maximum setting, the TNC switches the adaptive feed control off. In this case the TNC displays a window to inform you.

In NC blocks containing **FMAX**, the adaptive feed control is **not active**.

Mid-program startup is allowed during active feed control and the TNC takes the cut number of the startup point into account.

In the additional status display, the TNC displays various information when the adaptive feed control is active, See "Additional status displays". In addition, the TNC shows the symbol

**≪**₊ ∏ % Ţ

in the position display.

Program run, full sequence	→ Test run	11:08
TNG:\nc_prog\PGM\stat.H =	LBL CYC M POS TOOL TT TRANS OPARA AFC Modus AUS T : 5 D10	* <u>.</u>
19 CYCL DEF 11.0 SCALING FACTOR 20 CYCL DEF 11.1 SCL 0.9995 21 STOP	DOC: Schnittnummer 0	
21 STOP 22 CALL LBL 15 REP5 23 PLANE RESET STAY 24 LBL 0	Istfaktor Override 100%	_
25 END PGM STATI HM	Referenzlast Spindel Istdrehzahl Spindel 0.0	÷.
	Abweichung Drehzahl 0.0% © 00:00:01	S100%
		\$ •
05 X[Ne]	8	
0% Y[Nm] S1 11:08	Inner hundred and same barreds	
🙆 X +46.791 A	+0.000	
😤 Y +38.816 C	+0.000	
	+286.885 F 0as/ain Ovr 100% M 5/8	
F MAX SETTINGS AFC		

**11.3 Adaptive Feed Control Software Option (AFC)** 

# Log file

The TNC stores various pieces of information for each machining step of a teach-in cut in the **<name>.H.AFC2.DEP** file. **<name>** is the name of the NC program for which you have recorded the teach-in cut. During control, the TNC updates the data and makes various evaluations. The following data are to be saved in this table:

Number of the machining step
Number or name of the tool with which the machining step was made
Index of the tool with which the machining step was made
Nominal spindle speed [rpm]
Maximum difference of the spindle speed in % of the nominal speed
Machining time for the teach-in cut
Machining time for the control cut
Time difference in % between the machining time during teach-in and control
Maximum recorded spindle power during machining. The TNC shows the value as a percent of the spindle's rated power.
Reference load of the spindle. The TNC shows the value as a percent of the spindle's rated power.
Smallest occurring feed factor. The TNC shows the value as a percentage of the programmed feed rate
<ul> <li>Reaction by the TNC to overload:</li> <li>M: A macro defined by the machine tool builder has been run</li> <li>S: Immediate NC stop was conducted</li> <li>F: NC stop was conducted after the tool was retracted</li> <li>E: An error message was displayed</li> <li>-: There was no overload reaction</li> </ul>

**BLOCK** Block number at which the machining step begins



The TNC records the total machining time for all teach-in cuts (LTIME), all control cuts (CTIME) and the total time difference (TDIFF), and enters it after the keyword TOTAL in the last line of the log file. The TNC can only calculate the time difference (TDIFF) if you have completed the teach-in step.

Otherwise the column remains empty.

#### Proceed as follows to select the <name>.H.AFC2.DEP file:

Select the table of AFC settings



Select the Program Run, Full Sequence operating mode

Shift the soft-key row



Show the log file

# Tool breakage/tool wear monitoring



TNC 640 | User's Manual

This feature must be enabled and adapted by the machine tool builder.

Refer to your machine manual.

With the breakage/wear monitor, a cut-based tool breakage detection during active AFC can be realized.

Through the functions that can be defined by the machine tool builder you can define a percentage value for wear or breakage detection with respect to the rated power.

When the defined limit spindle power range is not maintained, the TNC conducts an NC stop.

11

**11.3 Adaptive Feed Control Software Option (AFC)** 

# Spindle load monitoring



This feature must be enabled and adapted by the machine tool builder. Refer to your machine manual.

With the spindle load monitoring function you can easily have the spindle load monitored in order, for example, to detect overloading the spindle power.

The function is independent of AFC, i.e. it is not cut-based and does not depend on teach-in steps. Through the functions that can be defined by the machine tool builder, you only need to define the percentage value for spindle limit power with respect to the rated power.

When the defined limit spindle power range is not maintained, the TNC conducts an NC stop.

# 11.4 Active Chatter Control (ACC; software option)

# Application



This feature must be enabled and adapted by the machine tool builder.

Refer to your machine manual.

Strong forces come into play during roughing (power milling). Depending on the tool spindle speed, the resonances in the machine tool and the chip volume (metal-removal rate during milling), the tool can sometimes begin to "chatter." This chattering places heavy strain on the machine, and causes ugly marks on the workpiece surface. The tool, too, is subject to heavy and irregular wear from chattering. In extreme cases it can result in tool breakage.

To reduce the inclination to chattering, HEIDENHAIN now offers an effective antidote with **ACC** (Active Chatter Control). The use of this control function is particularly advantageous during heavy cutting. ACC makes substantially higher metal removal rates possible. This makes it possible to increase your metal removal rate by up to 25 % and more, depending on the type of machine. You reduce the mechanical load on the machine and increase the life of your tools at the same time.

Please note that ACC was developed especially for heavy cutting and is particularly effective in this area. You need to conduct appropriate tests to ensure whether ACC is also advantageous during standard roughing.

When you use the ACC feature, you must enter the number of tool cuts **CUT** for the corresponding tool in the TOOL.T tool table.

# Activating/deactivating ACC

In order to activate ACC you need to set the column **ACC** for the respective tool in the tool table TOOL.T to 1. Other settings are not required.

In order to deactivate ACC, you need to set the column ACC to 0.

11

11.5 Working with the Parallel Axes U, V and W

# 11.5 Working with the Parallel Axes U, V and W

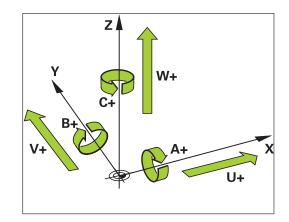
## **Overview**



Your machine must be configured by the machine manufacturer if you want to use parallel-axis functions.

The axes U, V and W are secondary axes parallel to the principal axes X, Y and Z, respectively. Principal axes and parallel axes are permanently assigned to each other.

Principal axis	Parallel axis	Rotary axis
Х	U	А
Y	V	В
Z	W	С



The TNC provides the following functions for machining with the parallel axes U, V and W:

Function	Meaning	Soft key	Page
PARAXCOMP	Define the TNC's behavior when positioning parallel axes	FUNCTION PARAXCOMP	392
PARAXMODE	Define the axes the TNC is to use for machining	FUNCTION PARAXMODE	392
F	After the TNC is started up, configuration is always effec Parallel-axis functions are res unctions:	tive.	

- Selection of a program
- End of program
- M2 or M30
- Program cancelation (**PARAXCOMP** remains active)
- PARAXCOMP OFF or PARAXMODE OFF

You must deactivate the parallel-axis functions before switching the machine kinematics.

#### Working with the Parallel Axes U, V and W 11.5

# FUNCTION PARAXCOMP DISPLAY

Use the **PARAXCOMP DISPLAY** function to activate the display function for parallel axis movements. The TNC considers the traverse movements of the parallel axis in the position display of the associated principal axis (sum display). Therefore, the position display of the principal axis always displays the relative distance from the tool to the workpiece, regardless of whether you move the principal axis or the minor axis.

Proceed as follows for the definition:

- Show the soft-key row with special functions
- Select the menu for defining various plain-language functions
- FUNCTION PARAX

FUNCTION PARAXCOMP FUNCTION

PARAXCOM DISPLAY

FCT

PROGRAM

FUNCTIONS

Select FUNCTION PARAXCOMP

Select FUNCTION PARAX

- Select FUNCTION PARAXCOMP DISPLAY
- Define the parallel axis whose movements the TNC is to take into account in the position display of the associated principal axis

# FUNCTION PARAXCOMP MOVE

SPEC FCT

FUNCTION PARAXCOMP FUNCTION

PARAXCOMP MOVE

The PARAXCOMP MOVE function can be used only in connection with straight-line blocks (L).

The TNC uses the PARAXCOMP MOVE function to compensate for the movement of a parallel axis by performing a compensation movement in the associated principal axis.

For example, if a parallel axis moves in the negative W-axis direction, the principal axis Z simultaneously moves in the positive direction by the same value. The relative distance from the tool to the workpiece remains the same. Application in gantry-type milling machine: Retract the spindle sleeve to move the cross beam down simultaneously.

Proceed as follows for the definition:

- Show the soft-key row with special functions Select the menu for defining various plain-language PROGRAM FUNCTIONS functions Select FUNCTION PARAX FUNCTION PARAX
  - Select FUNCTION PARAXCOMP
  - Select FUNCTION PARAXCOMP MOVE ►
  - Define the parallel axis ►

# **NC block**

**13 FUNCTION PARAXCOMP MOVE W** 

NC block

**13 FUNCTION PARAXCOMP DISPLAY W** 

11.5 Working with the Parallel Axes U, V and W

# FUNCTION PARAXCOMP OFF

Use the **PARAXCOMP OFF** function to switch off the parallel-axis functions **PARAXCOMP DISPLAY** and **PARAXCOMP MOVE**. Proceed as follows for the definition:



- Show the soft-key row with special functions
- Select the menu for defining various plain-language functions
- Select FUNCTION PARAX
- FUNCTION

FUNCTION

PARAXCOM

OFF

- Select FUNCTION PARAXCOMP
- Select FUNCTION PARAXCOMP OFF. If you want to switch off the parallel-axis functions only for individual parallel axes, then the respective axis must be specifically indicated.

# FUNCTION PARAXMODE



To activate the **PARAXMODE** function, you must always define three axes.

If you combine the **PARAXMODE** and PARAXCOMP functions, the TNC deactivates the PARAXCOMP function for an axis that was defined in both functions. When you deactivate PARAXMODE, the PARAXcomp function becomes active again.

Use the **PARAXMODE** function to define the axes the TNC is to use for machining. You program all traverse movements and contour descriptions in the principal axes X, Y and Z, independent of your machine.

Define the three axes in the **PARAXMODE** function (e.g. **FUNCTION PARAXMODE X Y W**), which the TNC is to use to execute the programmed traverse movements.

Proceed as follows for the definition:



FUNCTION PARAXMODE

FUNCTION PARAXMODE

- Show the soft-key row with special functions
- Select the menu for defining various plain-language functions
- Select FUNCTION PARAX
- Select FUNCTION PARAXMODE
- Select FUNCTION PARAXMODE
- Define the axes for machining

#### NC blocks

**13 FUNCTION PARAXCOMP OFF** 

**13 FUNCTION PARAXCOMP OFF W** 

#### NC block

**13 FUNCTION PARAXMODE X Y W** 

#### Move the principal axis and the parallel axis simultaneously

If the **PARAXMODE** function is active, the TNC uses the axes defined in the function to execute the programmed traverse movements. If the TNC is to traverse a parallel axis simultaneously with the associated principal axis, you can identify the respective axis by additionally entering the character "**&**". The axis with the **&** character then refers to the principal axis.

> The syntax element "**&**" is only permitted in L blocks. Additional positioning of a principal axis with the "**&**" command is done in the REF system. If you have set the position display to "actual value", this movement will not be shown. If necessary, switch the position display to "REF value".

# FUNCTION PARAXMODE OFF

Use the **PARAXCOMP OFF** function to switch off the parallel-axis function. The TNC then uses the principal axes defined by the machine manufacturer. Proceed as follows for the definition:

- SPEC FCT
- Show the soft-key row with special functions

Select the menu for defining various plain-language

- PROGRAM FUNCTIONS
- functions
- PARAX FUNCTION PARAXMODE
- FUNCTION PARAXMODE OFF
- Select FUNCTION PARAX
- Select FUNCTION PARAXMODE
- Select FUNCTION PARAXMODE OFF

#### NC block

13 FUNCTION PARAXMODE X Y W 14 L Z+100 &Z+150 R0 FMAX

NC block 13 FUNCTION PARAXCOMP OFF

**11.6 File functions** 

# 11.6 File functions

# Application

The **FILE FUNCTION** features are used to copy, move and delete files from within the part program.



You must not use **FILE** functions on programs or files, to which you have previously made reference with functions such as **CALL PGM** or **CYCL DEF 12 PGM CALL**.

# **Defining file functions**

SPEC	
OF LO	
ECT	

Press the special functions key

PROGRAM
FUNCTION

Select the program functions

FUNCTION FILE  Select the file functions: The TNC displays the available functions

Function	Meaning	Soft key
FILE COPY	Copy file: Enter the name and path of the file to be copied, as well as the target path.	FILE COPY
FILE MOVE	Move file: Enter the name and path of the file to be moved, as well as the target path.	FILE MOVE
FILE DELETE	Delete file: Enter the path and name of the file to be deleted	FILE DELETE

# 11.7 Definition of a datum shift

# Overview

As an alternative to the coordinate transformation Cycle 7 **DATUM SHIFT,** you can use the **TRANS DATUM** plain-language function. Just as in Cycle 7, you can use **TRANS DATUM** to directly program shift values or activate a line from a selectable datum table. In addition, there is also the **TRANS DATUM RESET** function, which you can easily use to reset a datum shift.

# TRANS DATUM AXIS

You can define a datum shift by entering values in the respective axes with the **TRANS DATUM AXIS** function. You can define up to nine coordinates in one block, and incremental entries are possible. Proceed as follows for the definition:

SPEC FCT	Show the soft-key row with special functions
PROGRAM FUNCTIONS	<ul> <li>Select the menu for defining various plain-language functions</li> </ul>
TRANSFORM	<ul> <li>Select transformations</li> </ul>
TRANS DATUM	Select datum shifting with TRANS DATUM
VALUES	<ul> <li>Select the value input soft key</li> </ul>
	Enter the datum shift in the affected axes, confirming with the ENT key each time
$\Rightarrow$	Values entered as absolute values refer to the workpiece datum, which is specified either by datum setting or with a preset from the preset table.
	Incremental values always refer to the datum which was last valid (this may be a datum which has already been shifted).

NC block

13 TRANS DATUMAXIS X+10 Y+25 Z+42

11.7 Definition of a datum shift

# TRANS DATUM TABLE

You can define a datum shift by selecting a datum number from a datum table with the **TRANS DATUM TABLE** function. Proceed as follows for the definition:



- Show the soft-key row with special functions
- Select the menu for defining various plain-language functions
- Select transformations
- Select datum shifting with TRANS DATUM
- Press the arrow key to move to TRANS AXIS
- Select datum shifting with TRANS DATUM TABLE
- If desired, enter the name of the datum table from which you want to activate the datum number, and confirm with the ENT key. If you do not want to define a datum table, confirm with the NO ENT key
- Enter the line number to be activated by the TNC, and confirm with the ENT key

If you did not define a datum table in the **TRANS DATUM TABLE** block, then the TNC uses the datum table already selected in the NC program with **SEL TABLE,** or the datum table with status M selected in one of the Program Run modes. NC block 13 TRANS DATUMTABLE TABLINE25

### TRANS DATUM RESET

Use the **TRANS DATUM RESET** function to cancel a datum shift. How you previously defined the datum is irrelevant. Proceed as follows for the definition:



- Show the soft-key row with special functions
- Select the menu for defining various plain-language functions
- Select transformations
- Select datum shifting with TRANS DATUM
- Press the arrow key to move to TRANS AXIS
- Select the TRANS DATUM RESET datum shift

NC block 13 TRANS DATUM RESET

### **11** Programming: Special functions

11.8 Creating Text Files

### 11.8 Creating Text Files

### Application

You can use the TNC's text editor to write and edit texts. Typical applications:

- Recording test results
- Documenting working procedures
- Creating formula collections

Text files are type .A files (ASCII files). If you want to edit other types of files, you must first convert them into type .A files.

### Opening and exiting text files

- Select the Programming and Editing mode of operation
- Call the file manager: Press the PGM MGT key
- Display type .A files: Press the SELECT TYPE and then the SHOW .A soft keys
- Select a file and open it with the SELECT soft key or ENT key, or create a new file by entering the new file name and confirming your entry with the ENT key

To leave the text editor, call the file manager and select a file of a different file type, for example a part program

Cursor movements	Soft key
Move cursor one word to the right	
Move cursor one word to the left	
Go to next screen page	
Go to previous screen page	PAGE
Go to beginning of file	BEGIN
Go to end of file	

### **Editing texts**

Above the first line of the text editor, there is an information field showing the file name, location and line information:

- File: Name of the text file
- Line: Line in which the cursor is presently located

**Column**: Column in which the cursor is presently located

The text is inserted or overwritten at the location of the cursor. You can move the cursor to any desired position in the text file by pressing the arrow keys.

The line in which the cursor is presently located is depicted in a different color. You can insert a line break with the Return or ENT key.

### Deleting and re-inserting characters, words and lines

With the text editor, you can erase words and even lines, and insert them at any desired location in the text.

- Move the cursor to the word or line that you wish to erase and insert at a different place in the text
- Press the DELETE WORD or DELETE LINE soft key. The text is placed in the buffer memory
- Move the cursor to the location where you wish to insert the text, and press the RESTORE LINE/WORD soft key

Function	Soft key
Delete and temporarily store a line	DELETE
Delete and temporarily store a word	DELETE WORD
Delete and temporarily store a character	DELETE CHAR
Insert a line or word from temporary storage	INSERT LINE / WORD

### **11** Programming: Special functions

11.8 Creating Text Files

### **Editing text blocks**

SELECT BLOCK

You can copy and erase text blocks of any size, and insert them at other locations. Before any of these actions, you must first select the desired text block:

- To select a text block, move the cursor to the first character of the text you wish to select
  - Press the SELECT BLOCK soft key
    - Move the cursor to the last character of the text you wish to select. You can select whole lines by moving the cursor up or down directly with the arrow keys—the selected text is shown in a different color

After selecting the desired text block, you can edit the text with the following soft keys:

Function	Soft key
Delete the selected block and store temporarily	CUT OUT BLOCK
Store the selected block temporarily without erasing (copy)	INSERT BLOCK

If desired, you can now insert the temporarily stored block at a different location:

 Move the cursor to the location where you want to insert the temporarily stored text block



 Press the INSERT BLOCK soft key for the text block to be inserted

You can insert the temporarily stored text block as often as desired

### Transferring the selected block to a different file

Select the text block as described previously



- Press the APPEND TO FILE soft key. The TNC displays the dialog prompt Destination file =
- Enter the path and name of the destination file. The TNC appends the selected text to the specified file. If no target file with the specified name is found, the TNC creates a new file with the selected text.

### Inserting another file at the cursor position

Move the cursor to the location in the text where you wish to insert another file



- Press the READ FILE soft key. The TNC displays the dialog prompt File name =
- Enter the path and name of the file you want to insert

11

### Finding text sections

With the text editor, you can search for words or character strings in a text. Two functions are available:

### Finding the current text

The search function is used for finding the next occurrence of the word in which the cursor is presently located:

- Move the cursor to the desired word.
- Select the search function: Press the FIND soft key
- ▶ Press the FIND CURRENT WORD soft key
- Exit the search function: Press the END soft key

### Finding any text

- Select the search function: Press the FIND soft key. The TNC displays the dialog prompt Find text:
- Enter the text that you wish to find
- ▶ Find the text: Press the EXECUTE soft key
- ► Exit the search function: Press the END soft key

### **11** Programming: Special functions

11.9 Freely definable tables

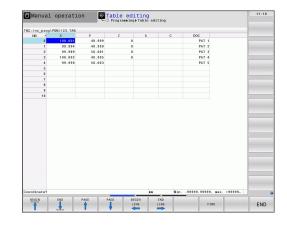
### 11.9 Freely definable tables

### **Fundamentals**

In freely definable tables you can read and save any information from the NC program. The Q parameter functions **FN 26** to **FN 28** are provided for this purpose.

You can change the format of freely definable tables, i.e. the columns and their properties, by using the structure editor. They enable you to make tables that are exactly tailored to your application.

You can also switch between table view (default setting) and form view.



### Creating a freely definable table

- ▶ To call the file manager, press the PGM MGT key
- Enter any file name with the .TAB extension and confirm with the ENT key. The TNC displays a pop-up window with permanently saved table formats
- Use the arrow key to select the table template EXAMPLE.TAB and confirm with the ENT key. The TNC opens a new table in the predefined format
- To adapt the table to your requirements you have to edit the table format, See "Editing the table format", page 403



Machine tool builders may define their own table templates and save them in the TNC. When you create a new table, the TNC opens a pop-up window listing all available table templates.

А
r

You can also save your own table templates in the TNC. To do this, you create a new table, change the table format and save the table in the **TNC:\system \proto** directory. Then your template will also be available in the list box for table templates when you create a new table.

### Editing the table format

Press the EDIT FORMAT soft key (2nd soft-key level): The TNC opens the editor form, in which the table structure is shown. The meanings of the structure commands (header entries) are shown in the following table.

Structure command	Meaning
Available columns:	List of all columns contained in the table
Move before:	The entry highlighted in <b>Available</b> <b>columns</b> is moved in front of this column
Name	Column name: Is displayed in the header
Column type	TEXT: Text entry SIGN: Sign + or - BIN: Binary number DEC: Decimal, positive, complete number (cardinal number) HEX: Hexadecimal number INT: Complete number LENGTH: Length (is converted in inch programs) FEED: Feed rate (mm/min or 0.1 inch/ min) IFEED: Feed rate (mm/min or inch/min) FLOAT: Floating-point number BOOL: Logical value INDEX: Index TSTAMP: Fixed format for date and time
Default value	Default value for the fields in this column
Width	Width of the column (number of characters)
Primary key	First table column
Language- sensitive column name	Language-sensitive dialogs

🔿 Manua	1 operat:	ion 🙋	Table Progra	edit	<mark>ing</mark> able edit	ing						11:18
ING:\nc nto	g\PGW\123.TAB										10	
NB +	X	Y	z		A	с		DOC				
	100.001	49.999		0				PAT	1		-	
1	99.994	49.999		0				PAT	2			
2	99.989	50.001		0				PAT	3			
3	100.002	49.995		0				PAT	4		_	
4	99.990	50.003						PAT	5			
5											100	
6		Edit table	characte	ristics			52					
7		Available			n proper						_	
8		AVa11able	COTONNS :	Name	or brober	NB						
9		X			an type	DEC	192					
10		Y					8					
		z			ult value							
		A.		Widt		9	_				100	
		Nove befor	e:	Deci		0						
		x		IN Pr	imary key						_	
		Language - e										
			censitive	COTURN	name:		10					
		en					4				_	
		de										
		cs fr									100	
		lfr					3					
											_	
cordinate?							Win91	9999.99	399, max.	+99999		
		1	1	-		_	_			1		
		INSERT	DELETE									

### **11** Programming: Special functions

### 11.9 Freely definable tables

You can use a connected mouse or the TNC keyboard to navigate in the form. Navigation using the TNC keyboard:



Press the navigation keys to go to the input fields. Use the arrow keys to navigate within an input field. To open pop-down menus, press the GOTO key.



In a table that already has lines, you cannot change the table properties **Name** and **Column type**. Once you have deleted all lines, you can change these properties. If required, create a backup copy of the table beforehand.

### Exiting the structure editor

Press the OK soft key The TNC closes the editor form and applies the changes. All changes are discarded by pressing the CANCEL soft key.

### Switching between table and form view

All tables with the file extension  $\ensuremath{\textbf{.TAB}}$  can be opened in either list view or form view.



 Press the key for setting the screen layout. Select the respective soft key for list view or form view (form view: with or without dialog texts)

In the form view the TNC lists the line numbers with the contents of the first column in the left half of the screen.

In the right half you can change the data.

- Press the ENT key or the arrow key to move to the next input field.
- To select another line, press the green navigation key (folder symbol). This moves the cursor to the left window, and you can select the desired line with the arrow keys. Press the green navigation key to switch back to the input window.

🖰 Manuai	l operati	on 🝳	Table edit	ing Table editing			11	: 18
TNC:\nc proc	\PGM\123.TAB		NR: 0				-	
TNC: \nc_pros NR - 0 1 2 3 4 5 6 7 8 9 10	X X 100.001 99.934 99.989 100.002 99.990	Y 49.999 50.001 49.995 50.003	NR: 0 NR Coordinate Coordinate Coordinate Coordinate Remark			0 100 45.1 0	199	
C. mm Hin.	-99999.99999,	max. +99999.	Coordinate	[88]	_		E 171 E	
	HIDE/ SORT/ COLUMNS	EDIT	MOR FUNCT3				EDIT URRENT SC FIELD	RT

### FN 26: TAPOPEN: Open a freely definable table

With the function **FN 26: TABOPEN** you open a freely definable table to be written to with **FN 27** or to be read from with **FN 28**.



Only one table can be open in an NC program. A new block with **TABOPEN** automatically closes the last opened table.

The table to be opened must have the file name extension .TAB.

# Example: Open the table TAB1.TAB, which is saved in the directory TNC:\DIR1.

56 FN 26: TABOPEN TNC:\DIR1\TAB1.TAB

### **11** Programming: Special functions

11.9 Freely definable tables

### FN 27: TAPWRITE: Write to a freely definable table

After you have opened a table with **FN 26: TABOPEN** you can use the function **FN 27: TABWRITE** to write to it.

You can define and write to several column names in a **TABWRITE** block. The column names must be written between quotation marks and separated by a comma. You define the values that the TNC is to write to the respective column with Q parameters.



Note that by default the **FN 27: TABWRITE** function writes values to the currently open table also in the Test Run mode. The **FN18 ID992 NR16** function enables you to query in which operating mode the program is to be run. If the **FN27** function is to be run only in the Program Run operating modes, you can skip the respective program section by using a jump command If-then decisions with Q parameters.

You can write only to numerical table fields.

If you wish to write to more than one column in a block, you must save the values under successive Q parameter numbers.

### Example

You wish to write to the columns "Radius," "Depth" and "D" in line 5 of the presently opened table. The values to be written to the table must be saved in the Q parameters Q5, Q6 and Q7.

54 Q6 = -5

55 Q7 = 7.5

56 FN 27: TABWRITE 5/"RADIUS, DEPTH, D" = Q5

### FN 28: TAPREAD: Read from a freely definable table

After you have opened a table with **FN 26: TABOPEN** you can use the function **FN 28: TABREAD** to read from it.

You can define and read several column names in a **TABREAD** block. The column names must be written between quotation marks and separated by a comma. In the **FN 28** block you can define the Q parameter number in which the TNC is to write the value that is first read.



You can read only numerical table fields.

If you wish to read from more than one column in a block, the TNC will save the values under successive Q parameter numbers.

### Example

You wish to read the values of the columns "Radius," "Depth" and "D" from line 6 of the presently opened table. Save the first value in Q parameter Q10 (second value in Q11, third value in Q12).

### 56 FN 28: TABREAD Q10 = 6/"RADIUS, DEPTH, D"



12.1 Functions for multiple axis machining

### 12.1 Functions for multiple axis machining

The TNC functions for multiple axis machining are described in this chapter.

TNC function	Description	Page
PLANE	Define machining in the tilted working plane	411
M116	Feed rate of rotary axes	434
PLANE/M128	Inclined-tool machining	432
FUNCTION TCPM	Define the behavior of the TNC when positioning the rotary axes (improvement of M128)	442
M126	Shortest-path traverse of rotary axes	435
M94	Reduce display value of rotary axes	436
M128	Define the behavior of the TNC when positioning the rotary axes	437
M138	Selection of tilted axes	440
M144	Calculate machine kinematics	441
LN blocks	Three-dimensional tool compensation	447

### 12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)

### Introduction

The machine manufacturer must enable the functions for tilting the working plane!

You can only use the **PLANE** function in its entirety on machines which have at least two rotary axes (head and/or table). Exception: **PLANE AXIAL** can also be used if only a single rotary axis is present or active on your machine.

The **PLANE** function is a powerful function for defining tilted working planes in various manners.

All **PLANE** functions available on the TNC describe the desired working plane independently of the rotary axes actually present on your machine. The following possibilities are available:

Function	Required parameters	Soft key	Page
SPATIAL	Three spatial angles: SPA, SPB, and SPC	SPATIAL	415
PROJECTED	Two projection angles: <b>PROPR</b> and <b>PROMIN</b> and a rotation angle <b>ROT</b>	PROJECTED	417
EULER	Three Euler angles: precession (EULPR), nutation (EULNU) and rotation (EULROT)	EULER	418
VECTOR	Normal vector for defining the plane and base vector for defining the direction of the tilted X axis	VECTOR	420

**12.2** The PLANE Function: Tilting the Working Plane (Software Option 1)

Required parameters	Soft key	Page
Coordinates of any three points in the plane to be tilted	POINTS	422
Single, incrementally effective spatial angle	REL. SPA.	424
Up to three absolute or incremental axis angles <b>A,B,C</b>	AXIAL	425
Reset the PLANE function	RESET	414
<ul> <li>separated into two parts:</li> <li>The geometric definition is different for each of the functions.</li> <li>The positioning behavior which is independent of identical for all <b>PLANE</b> full</li> </ul>	n of the plane, he available <b>Pl</b> r of the <b>PLAN</b> the plane def unctions, See	which ANE E function, finition and is "Specifying
with an active tilted working If you use the <b>PLANE</b> funct active, the TNC automatica compensation, which also r function. Always use <b>PLANE RESET</b> t Entering 0 in all <b>PLANE</b> para completely reset the function	g plane. ion when <b>M12</b> lly rescinds the <b>M</b> rescinds the <b>M</b> to reset <b>PLAN</b> ameters does on.	20 is le radius A120 E functions. not
	Coordinates of any three points in the plane to be tilted Single, incrementally effective spatial angle Up to three absolute or incremental axis angles <b>A,B,C</b> Reset the PLANE function The parameter definition of separated into two parts: The geometric definition is different for each of th functions. The positioning behavior which is independent of identical for all <b>PLANE</b> fu the positioning behavior page 427 The actual-position-capture with an active tilted working If you use the <b>PLANE</b> funct active, the TNC automatica compensation, which also r function. Always use <b>PLANE RESET</b> t Entering 0 in all <b>PLANE</b> para	Coordinates of any three points in the plane to be tilted Single, incrementally effective spatial angle Up to three absolute or incremental axis angles <b>A,B,C</b> Reset the PLANE function The parameter definition of the <b>PLANE</b> function The parameter definition of the <b>PLANE</b> functions The geometric definition of the plane, is different for each of the available <b>PL</b> functions. The positioning behavior of the <b>PLANE</b> functions. The positioning behavior of the <b>PLANE</b> functions. The positioning behavior of the <b>PLANE</b> which is independent of the plane definition of the plane defi

TNC 640 | User's Manual HEIDENHAIN Conversational Programming | 5/2013

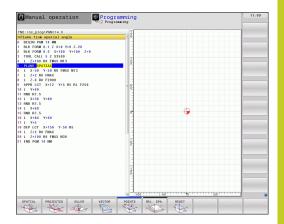
### **Defining the PLANE function**



MACHINING

PLANE

- Show the soft-key row with special functions
- Select the PLANE function: Press the TILT MACHINING PLANE soft key: The TNC displays the available definition possibilities in the soft-key row



### **Selecting functions**

 Select the desired function by soft key. The TNC continues the dialog and requests the required parameters

### **Position display**

As soon as a **PLANE** function is active, the TNC shows the calculated spatial angle in the additional status display (see figure). As a rule, the TNC internally always calculates with spatial angles, independent of which **PLANE** function is active.

During tilting (**MOVE** or **TURN** mode) in the Distance-To-Go mode (**DIST**), the TNC shows (in the rotary axis) the distance to go (or calculated distance) to the final position of the rotary axis.

Manual	l operation				😒 Pro	gramming	11:05
- G Handar	operation				_		" 🖉
Position dis	play MODE: NOML.		Übe:	sicht P	GM LBL	CYC M POS TOOL	TT 💽 S 🔒
X	+53.667		Akti	ves PGM			- V
Y	+61.182		(í,				
Z A C S1	-10.000					00:00:08	
٨	+0.000		Akti	elle Uh	rzeit: 1	1:05:24	
<u> </u>	+0.000			Aufg	erufene	Programme	\$
			PGM				~ × _
S1	+286.885		PGM				S100% []
			PGM				\$100% U
			PGM	5:			OFF OF
			PGM	6:			÷
			PGM				(e.) <u>.</u>
			PGM				
			PGM PGM				F100% W
			PGM	10:			OFF. OF
Ð1	T 4 🛛 🖉	2					
S 2000	P 30008/818						
Ovr 100%	H 5/9						
		0% X[Nm]					
		0% Y[Nm]	S1	11:05			
KOLLISION							

**12.2** The PLANE Function: Tilting the Working Plane (Software Option 1)

### **Resetting the PLANE function**

SPEC FCT	Show the soft-key row with special functions
SPECIAL TNC FUNCTIONS	<ul> <li>Select special TNC functions: Press the SPECIAL TNC FUNCT. soft key</li> </ul>
TILT MACHINING PLANE	<ul> <li>Select the PLANE function: Press the TILT MACHINING PLANE soft key: The TNC displays the available definition possibilities in the soft-key row</li> </ul>
RESET	<ul> <li>Select the Reset function. This internally resets the PLANE function, but does not change the current axis positions</li> </ul>
MOVE	<ul> <li>Specify whether the TNC should automatically move the rotary axes to the default setting (MOVE or TURN) or not (STAY)See "Automatic positioning: MOVE/TURN/STAY (entry is mandatory)", page 427.</li> </ul>
	<ul> <li>Terminate the entry: Press the END key</li> </ul>
	The <b>PLANE RESET</b> function resets the current <b>PLANE</b> function—or an active cycle <b>19</b> —completely (angles

defined more than once.

= 0 and function is inactive). It does not need to be

NC block

25 PLANE RESET MOVE ABST50 F1000

# Defining the working plane with the spatial angle: PLANE SPATIAL

### Application

Spatial angles define a working plane using up to three rotations of the coordinate system; two perspectives that have always the same result are available for this purpose.

- Rotations about the machine-based coordinate system: The sequence of the rotations is first around the machine axis C, then around the machine axis B, and then around the machine axis A.
- Rotations about the respectively tilted coordinate system: The sequence of rotations is first around the machine axis C, then around the rotated axis B, and then around the rotated axis A. This perspective is usually easier to understand, because one rotary axis is fixed so that the rotations of the coordinate system are easier to comprehend.

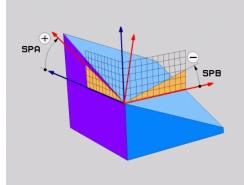


### Before programming, note the following

You must always define the three spatial angles **SPA**, **SPB**, and **SPC**, even if one of them = 0.

This operation corresponds to Cycle19 if the entries in Cycle 19 are defined as spatial angles on the machine side.

Parameter description for the positioning behavior: See "Specifying the positioning behavior of the PLANE function", page 427.

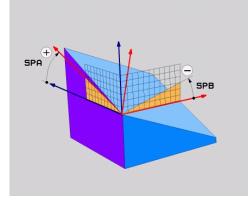


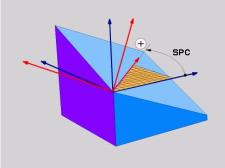
### **12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)**

### **Input parameters**



- Spatial angle A?: Rotational angle SPA around the fixed machine axis X (see figure at top right). Input range from -359.9999° to +359.9999°
- Spatial angle B?: Rotational angle SPB around the fixed machine axis Y (see figure at top right). Input range from –359.9999° to +359.9999°
- Spatial angle C?: Rotational angle SPC around the fixed machine axis Z (see figure at center right). Input range from -359.9999° to +359.9999°
- Continue with the positioning properties, See "Specifying the positioning behavior of the PLANE function", page 427







### Abbreviations used

Abbreviation	Meaning
SPATIAL	In space
SPA	<b>Sp</b> atial <b>A</b> : Rotation around the X axis
SPB	<b>Sp</b> atial <b>B</b> : Rotation around the Y axis
SPC	<b>Sp</b> atial <b>C</b> : Rotation around the Z axis

# Defining the working plane with the projection angle: PLANE PROJECTED

### Application

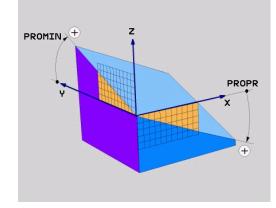
Projection angles define a machining plane through the entry of two angles that you determine by projecting the first coordinate plane (Z/X plane with tool axis Z) and the second coordinate plane (Y/Z with tool axis Z) onto the machining plane to be defined.



### Before programming, note the following

You can only use projection angles if the angle definitions are given with respect to a rectangular cuboid. Otherwise there will be deformations on the workpiece.

Parameter description for the positioning behavior: See "Specifying the positioning behavior of the PLANE function", page 427.



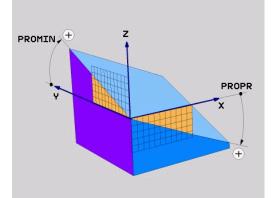
### Input parameters

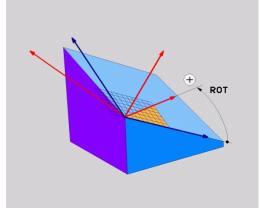


- Proj. angle 1st coordinate plane?: Projected angle of the tilted machining plane in the 1st coordinate plane of the fixed machine coordinate system (Z/X for tool axis Z, see figure at top right). Input range: from -89.9999° to +89.9999°. The 0° axis is the principal axis of the active working plane (X for tool axis Z. See figure at top right for positive direction)
- Proj. angle 2nd coordinate plane?: Projected angle in the 2nd coordinate plane of the fixed machine coordinate system (Y/Z for tool axis Z, see figure at top right). Input range from – 89.9999° to +89.9999°. The 0° axis is the minor axis of the active machining plane (Y for tool axis Z)
- ROT angle of the tilted plane?: Rotation of the tilted coordinate system around the tilted tool axis (corresponds to a rotation with Cycle 10 ROTATION). The rotation angle is used to simply specify the direction of the principal axis of the working plane (X for tool axis Z, Z for tool axis Y; see figure at bottom right). Input range: -360° to +360°
- Continue with the positioning properties, See "Specifying the positioning behavior of the PLANE function", page 427

### NC block

### 5 PLANE PROJECTED PROPR+24 PROMIN+24 PROROT+30 .....





### **12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)**

Abbreviations used:	
PROJECTED	

PROPRPrinciple planePROMINMinor planePROMINRotation

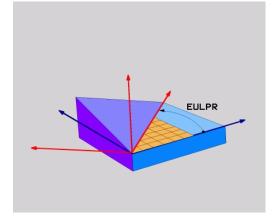
# Defining the working plane with the Euler angle: PLANE EULER

Projected

### Application

Euler angles define a machining plane through up to three **rotations about the respectively tilted coordinate system**. The Swiss mathematician Leonhard Euler defined these angles. When applied to the machine coordinate system, they have the following meanings:

Precession angle: EULPR	Rotation of the coordinate system around the Z axis
Nutation angle: <b>EULNU</b>	Rotation of the coordinate system around the X axis already shifted by the precession angle
Rotation angle: EULROT	Rotation of the tilted machining plane around the tilted Z axis





### Before programming, note the following

Parameter description for the positioning behavior: See "Specifying the positioning behavior of the PLANE function", page 427.

### Input parameters



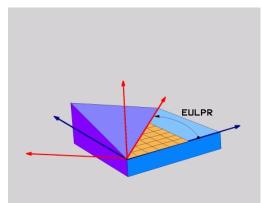
Rot. angle main coordinate plane?: Rotary angle EULPR around the Z axis (see figure at top right). Please note:

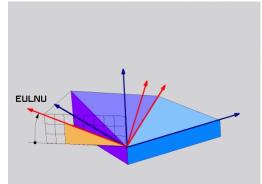
■ Input range: -180.0000° to +180.0000°

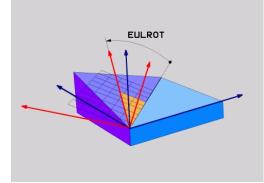
- The 0° axis is the X axis
- Swivel angle of tool axis?: Tilting angle EULNU of the coordinate system around the X axis shifted by the precession angle (see figure at center right). Please note:
  - Input range: 0° to +180.0000°
  - The 0° axis is the Z axis
- ROT angle of the tilted plane?: Rotation EULROT of the tilted coordinate system around the tilted Z axis (corresponds to a rotation with Cycle 10 ROTATION). Use the rotation angle to simply define the direction of the X axis in the tilted machining plane (see figure at bottom right). Please note:
  - Input range: 0° to 360.0000°
  - The 0° axis is the X axis
- Continue with the positioning properties, See "Specifying the positioning behavior of the PLANE function", page 427

### NC block

5 PLANE EULER EULPR45 EULNU20 EULROT22 .....







### 12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)

### Abbreviations used

Abbreviation	Meaning
EULER	Swiss mathematician who defined these angles
EULPR	<b>Pr</b> ecession angle: angle describing the rotation of the coordinate system around the Z axis
EULNU	<b>Nu</b> tation angle: angle describing the rotation of the coordinate system around the X axis shifted by the precession angle
EULROT	<b>Rot</b> ation angle: angle describing the rotation of the tilted machining plane around the tilted Z axis

# Defining the working plane with two vectors: PLANE VECTOR

### Application

You can use the definition of a working plane via **two vectors** if your CAD system can calculate the base vector and normal vector of the tilted machining plane. A normalized input is not necessary. The TNC calculates the normal, so you can enter values between -9.999999 and +9.999999.

The base vector required for the definition of the machining plane is defined by the components **BX**, **BY** and **BZ** (see figure at right). The normal vector is defined by the components **NX**, **NY** and **NZ**.

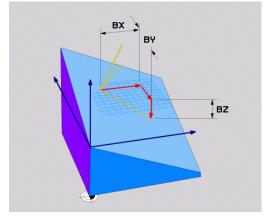


### Before programming, note the following

The base vector defines the direction of the principal axis in the tilted machining plane, and the normal vector determines the orientation of the tilted machining plane, and at the same time is perpendicular to it.

The TNC calculates standardized vectors from the values you enter.

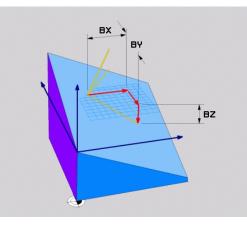
Parameter description for the positioning behavior: See "Specifying the positioning behavior of the PLANE function".

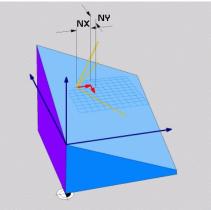


### Input parameters



- ► X component of base vector?: X component BX of the base vector B (see figure at top right). Input range: -9.9999999 to +9.9999999
- ► Y component of base vector?: Y component BY of the base vector B (see figure at top right). Input range: -9.99999999 to +9.9999999
- Z component of base vector?: Z component BZ of the base vector B (see figure at top right). Input range: -9.9999999 to +9.9999999
- X component of normal vector?: X component NX of the normal vector N (see figure at center right). Input range: -9.99999999 to +9.99999999
- Y component of normal vector?: Y component NY of the normal vector N (see figure at center right). Input range: -9.9999999 to +9.9999999
- Z component of normal vector?: Z component NZ of the normal vector N (see figure at lower right). Input range: -9.99999999 to +9.99999999
- Continue with the positioning properties, See "Specifying the positioning behavior of the PLANE function", page 427



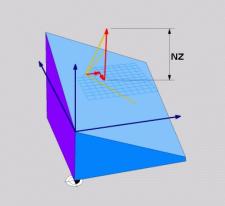


### NC block

### 5 PLANE VECTOR BX0.8 BY-0.4 BZ-0.42 NX0.2 NY0.2 NZ0.92 ..

### Abbreviations used

Abbreviation	Meaning	
VECTOR	Vector	
<b>BX, BY, BZ</b> Base vector: <b>X</b> , <b>Y</b> and <b>Z</b> components		
NX, NY, NZ	Normal vector: X, Y and Z components	



**12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)** 

# Defining the working plane via three points: PLANE POINTS

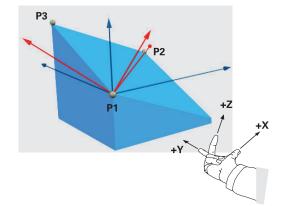
### Application

A working plane can be uniquely defined by entering **any three points P1 to P3 in this plane**. This possibility is realized in the **PLANE POINTS** function.

# Before programming, note the following The connection from Point 1 to Point 2 determines the direction of the tilted main axis (X for tool axis Z). The direction of the tilted tool axis is determined by the position of Point 3 relative to the connecting line between Point 1 and Point 2. Use the right-hand rule (thumb = X axis, index finger = Y axis, middle finger = Z axis (see figure at right)) to remember: thumb (X axis) points from Point 1 to Point 2, index finger (Y axis) points parallel to the tilted Y axis in the direction of Point 3. Then the middle finger points in the direction of the tilted tool axis.

The three points define the slope of the plane. The position of the active datum is not changed by the TNC.

Parameter description for the positioning behavior: See "Specifying the positioning behavior of the PLANE function", page 427.



### Input parameters



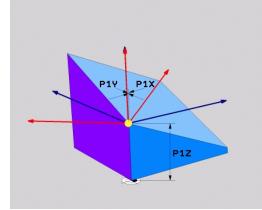
- X coordinate of 1st plane point?: X coordinate
   P1X of the 1st plane point (see figure at top right)
- Y coordinate of 1st plane point?: Y coordinate
   P1Y of the 1st plane point (see figure at top right)
- Z coordinate of 1st plane point?: Z coordinate
   P1Z of the 1st plane point (see figure at top right)
- X coordinate of 2nd plane point?: X coordinate P2X of the 2nd plane point (see figure at center right)
- Y coordinate of 2nd plane point?: Y coordinate P2Y of the 2nd plane point (see figure at center right)
- Z coordinate of 2nd plane point?: Z coordinate P2Z of the 2nd plane point (see figure at center right)
- X coordinate of 3rd plane point?: X coordinate P3X of the 3rd plane point (see figure at bottom right)
- Y coordinate of 3rd plane point?: Y coordinate P3Y of the 3rd plane point (see figure at bottom right)
- Z coordinate of 3rd plane point?: Z coordinate
   P3Z of the 3rd plane point (see figure at bottom right)
- Continue with the positioning properties See "Positionierverhalten der PLANE-Funktion festlegen"

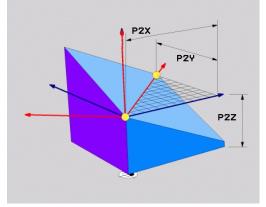
### NC block

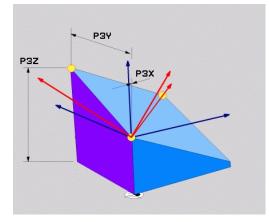
5 PLANE POINTS P1X+0 P1Y+0 P1Z+20 P2X+30 P2Y+31 P2Z+20 P3X +0 P3Y+41 P3Z+32.5 .....

### Abbreviations used

Abbreviation	Meaning
POINTS	Points







12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)

# Defining the working plane via a single incremental spatial angle: PLANE SPATIAL

### Application

Use an incremental spatial angle when an already active tilted working plane is to be tilted by **another rotation**. Example: machining a 45° chamfer on a tilted plane.

### Before programming, note the following

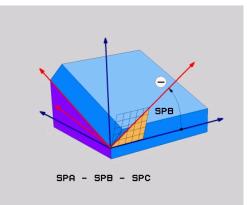
The defined angle is always in effect in respect to the active working plane, regardless of the function you have used to activate it.

You can program any number of **PLANE RELATIVE** functions in a row.

If you want to return to the working plane that was active before the **PLANE RELATIVE** function, define the **PLANE RELATIVE** function again with the same angle but with the opposite algebraic sign.

If you use the **PLANE RELATIVE** function in a nontilted working plane, then you simply rotate the nontilted plane about the spatial angle defined in the **PLANE** function.

Parameter description for the positioning behavior: See "Specifying the positioning behavior of the PLANE function", page 427.



### Input parameters



- Incremental angle?: Spatial angle about which the active machining plane is to be rotated additionally (see figure at right). Use a soft key to select the axis to be rotated about. Input range: -359.9999° to +359.9999°
- Continue with the positioning properties, See "Specifying the positioning behavior of the PLANE function", page 427

# SPA - SPB - SPC



### Abbreviations used

Abbreviation	Meaning
RELATIVE	Relative to

# Tilting the working plane through axis angle: PLANE AXIAL (FCL 3 function)

### Application

The **PLANE AXIAL** function defines both the position of the working plane and the nominal coordinates of the rotary axes. This function is particularly easy to use on machines with Cartesian coordinates and with kinematics structures in which only one rotary axis is active.



**PLANE AXIAL** can also be used if you have only one rotary axis active on your machine.

You can use the **PLANE RELATIVE** function after **PLANE AXIAL** if your machine allows spatial angle definitions. Refer to your machine manual.



### Before programming, note the following

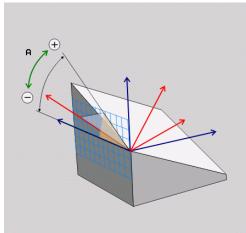
Enter only axis angles that actually exist on your machine. Otherwise the TNC generates an error message.

Rotary axis coordinates defined with **PLANE AXIAL** are modally effective. Successive definitions therefore build on each other. Incremental input is allowed.

Use **PLANE RESET** to reset the **PLANE AXIAL** function. Resetting by entering 0 does not deactivate **PLANE AXIAL**.

**SEQ. TABLE ROT** and **COORD ROT** have no function in conjunction with **PLANE AXIAL**.

Parameter description for the positioning behavior: See "Specifying the positioning behavior of the PLANE function", page 427.

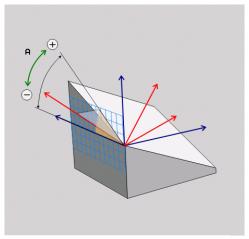


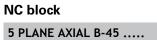
### **12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)**

### Input parameters



- Axis angle A?: Axis angle to which the A axis is to be tilted. If entered incrementally, it is the angle by which the A axis is to be tilted from its current position. Input range: -99999.9999° to +99999.9999°
- Axis angle B?: Axis angle to which the B axis is to be tilted. If entered incrementally, it is the angle by which the B axis is to be tilted from its current position. Input range: -99999.9999° to +99999.9999°
- Axis angle C?: Axis angle to which the C axis is to be tilted. If entered incrementally, it is the angle by which the C axis is to be tilted from its current position. Input range: -99999.9999° to +99999.9999°
- Continue with the positioning properties, See "Specifying the positioning behavior of the PLANE function", page 427





### Abbreviations used

Abbreviation	Meaning
AXIAL	In the axial direction

# Specifying the positioning behavior of the PLANE function

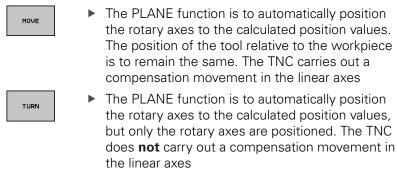
### Overview

Independently of which PLANE function you use to define the tilted machining plane, the following functions are always available for the positioning behavior:

- Automatic positioning
- Selection of alternate tilting possibilities (not with PLANE AXIAL)
- Selection of the type of transformation (not with **PLANE AXIAL**)

### Automatic positioning: MOVE/TURN/STAY (entry is mandatory)

After you have entered all parameters for the plane definition, you must specify how the rotary axes will be positioned to the calculated axis values:



 You will position the rotary axes later in a separate positioning block

If you have selected the **MOVE** option (**PLANE** function is to position the axes automatically), the following two parameters must still be defined: **Dist. tool tip - center of rot.** and **Feed rate? F=**.

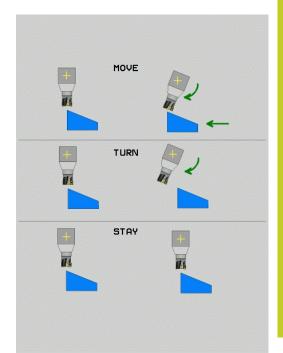
If you have selected the **TURN** option (**PLANE** function is to position the axes automatically without any compensating movement), the following parameter must still be defined: **Feed rate? F=**.

As an alternative to defining a feed rate **F** directly by numerical value, you can also position with **FMAX** (rapid traverse) or **FAUTO** (feed rate from the **TOOL CALLT** block).



STAY

If you use **PLANE AXIAL** together with **STAY**, you have to position the rotary axes in a separated block after the **PLANE** function.

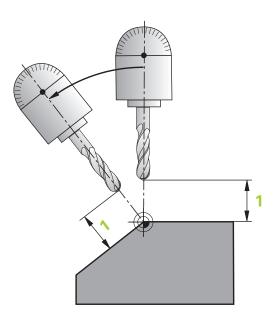


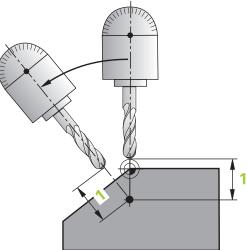
### 12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)

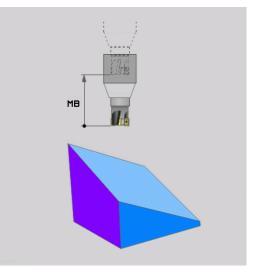
Dist. tool tip - center of rot. (incremental): The TNC tilts the tool (or table) relative to the tool tip. The DIST parameter shifts the center of rotation of the positioning movement relative to the current position of the tool tip.

Note:

- If the tool is already at the given distance to the workpiece before positioning, then relatively speaking the tool is at the same position after positioning (see figure at center right, 1 = DIST).
- If the tool is not at the given distance to the workpiece before positioning, then relatively speaking the tool is offset from the original position after positioning (see figure at bottom right, 1=DIST).
- Feed rate? F=: Contour speed at which the tool should be positioned
- Retraction length in the tool axis?: Retraction path MB is effective incrementally from the current tool position in the active tool axis direction that the TNC approaches before tilting. MB MAX positions the tool just before the software limit switch.







### Positioning the rotary axes in a separate block

Proceed as follows if you want to position the rotary axes in a separate positioning block (option **STAY** selected):

### Danger of collision!

Pre-position the tool to a position where there is no danger of collision with the workpiece (clamping devices) during positioning.

- Select any PLANE function, and define automatic positioning with the STAY option. During program execution the TNC calculates the position values of the rotary axes present on the machine, and stores them in the system parameters Q120 (A axis), Q121 (B axis) and Q122 (C axis)
- Define the positioning block with the angular values calculated by the TNC

### NC example blocks: Position a machine with a rotary table C and a tilting table A to a space angle of B+45°

•••		
12 L Z+250 R0 FMAX	Position at clearance height	
13 PLANE SPATIAL SPA+0 SPB+45 SPC+0 STAY	Define and activate the PLANE function	
14 L A+Q120 C+Q122 F2000	Position the rotary axis with the values calculated by the TNC	
	Define machining in the tilted working plane	

### 12.2 The PLANE Function: Tilting the Working Plane (Software Option 1)

# Selection of alternate tilting possibilities: SEQ +/- (entry optional)

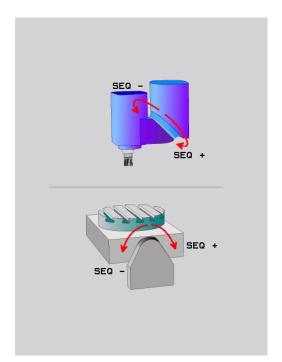
The position you define for the working plane is used by the TNC to calculate the appropriate positioning of the rotary axes present on the machine. In general there are always two solution possibilities.

Use the  $\ensuremath{\text{SEQ}}$  switch to specify which possibility the TNC should use:

- SEQ+ positions the master axis so that it assumes a positive angle. The master axis is the 1st rotary axis from the tool, or the last rotary axis from the table (depending on the machine configuration (see figure at top right)).
- **SEQ-** positions the master axis so that it assumes a negative angle.

If the solution you chose with **SEQ** is not within the machine's range of traverse, the TNC displays the **Entered angle not permitted** error message.

When the **PLANE AXIS** function is used, the **SEQ** switch is nonfunctional.



- 1 The TNC first checks whether both solution possibilities are within the traverse range of the rotary axes.
- 2 If they are, then the TNC selects the shortest possible solution.
- 3 If only one solution is within the traverse range, the TNC selects this solution
- 4 If neither solution is within the traverse range, the TNC displays the **Entered angle not permitted** error message.

If you do not define  $\ensuremath{\text{SEQ}}$  , the TNC determines the solution as follows:

# Example for a machine with a rotary table C and a tilting table A. Programmed function: PLANE SPATIAL SPA+0 SPB+45 SPC+0

•			
Limit switch	Starting position	SEQ	Resulting axis position
None	A+0, C+0	not prog.	A+45, C+90
None	A+0, C+0	+	A+45, C+90
None	A+0, C+0	-	A–45, C–90
None	A+0, C–105	not prog.	A–45, C–90
None	A+0, C–105	+	A+45, C+90
None	A+0, C–105	-	A–45, C–90
-90 < A < +10	A+0, C+0	not prog.	A–45, C–90
-90 < A < +10	A+0, C+0	+	Error message
None	A+0, C–135	+	A+45, C+90

### Selecting the type of transformation (entry optional)

On machines with C-rotary tables, a function is available for specifying the type of transformation:



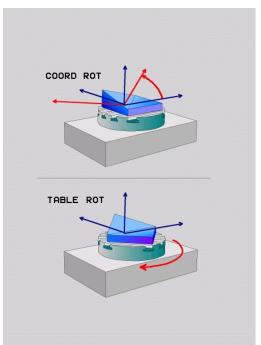
 $\mathbb{D}$ 

- COORD ROT specifies that the PLANE function should only rotate the coordinate system to the defined tilting angle. The rotary table is not moved; the compensation is purely mathematical.
- TABLE ROT specifies that the PLANE function should position the rotary table to the defined tilting angle. Compensation results from rotating the workpiece.

!

When the **PLANE AXIAL** function is used, **COORD ROT** and **TABLE ROT** are nonfunctional.

If you use the **TABLE ROT** function in conjunction with a basic rotation and a tilting angle of 0, then the TNC tilts the table to the angle defined in the basic rotation.



12.3 Inclined-tool machining in a tilted machining plane (software option 2)

# 12.3 Inclined-tool machining in a tilted machining plane (software option 2)

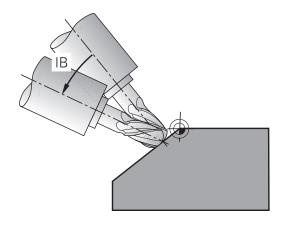
### Function

In combination with **M128** and the new **PLANE** functions, **inclined-tool machining** in a tilted machining plane is now possible. Two possibilities are available for definition:

- Inclined-tool machining via incremental traverse of a rotary axis
- Inclined-tool machining via normal vectors



Inclined-tool machining in a tilted machining plane only functions with spherical cutters. With 45° swivel heads and tilting tables you can also define the incline angle as a space angle. Use the **TCPM FUNCTION**, See "FUNCTION TCPM (software option 2)".



# Inclined-tool machining via incremental traverse of a rotary axis

- Retract the tool
- Activate M128
- ▶ Define any PLANE function; consider the positioning behavior
- Via a straight-line block, traverse to the desired incline angle in the appropriate axis incrementally

### **Example NC blocks**

12 L Z+50 R0 FMAX M128	Position at clearance height, activate M128
13 PLANE SPATIAL SPA+0 SPB-45 SPC+0 MOVE ABST50 F1000	Define and activate the PLANE function
14 L IB-17 F1000	Set the incline angle
	Define machining in the tilted working plane

# Inclined-tool machining in a tilted machining plane (software 12.3 option 2)

## Inclined-tool machining via normal vectors



Only one directional vector can be defined in the **LN** block. This vector defines the incline angle (normal vector **NX**, **NY**, **NZ**, or tool direction vector **TX**, **TY**, **TZ**).

- Retract the tool
- ► Activate M128
- Define any PLANE function; consider the positioning behavior
- Execute program with LN block in which the tool direction is defined by a vector

#### **Example NC blocks**

12 L Z+50 R0 FMAX M128	Position at clearance height, activate M128
13 PLANE SPATIAL SPA+0 SPB+45 SPC+0 MOVE ABST50 F1000	Define and activate the PLANE function
14 LN X+31.737 Y+21.954 Z+33.165 NX+0.3 NY+0 NZ +0.9539 F1000 M3	Set the incline angle with the normal vector
	Define machining in the tilted working plane

12.4 Miscellaneous functions for rotary axes

# 12.4 Miscellaneous functions for rotary axes

# Feed rate in mm/min on rotary axes A, B, C: M116 (software option 1)

#### Standard behavior

The TNC interprets the programmed feed rate of a rotary axis in degrees/min (in mm programs and also in inch programs). The feed rate therefore depends on the distance from the tool center to the center of axis rotation.

The larger this distance becomes, the greater the contouring feed rate.

## Feed rate in mm/min on rotary axes with M116



The machine geometry must be specified by the machine tool builder in the description of kinematics.

M116 works only on rotary tables. M116 cannot be used with swivel heads. If your machine is equipped with a table/head combination, the TNC ignores the swivel-head rotary axes.

**M116** is also effective in an active tilted working plane and in combination with M128 if you used the **M138** function to select rotary axes, See "Selecting tilting axes: M138". Then **M116** affects only those rotary axes that were not selected with **M138**.

The TNC interprets the programmed feed rate of a rotary axis in degrees/min (or 1/10 inch/min). In this case, the TNC calculates the feed for the block at the start of each block. With a rotary axis, the feed rate is not changed during execution of the block even if the tool moves toward the center of the rotary axis.

#### Effect

M116 is effective in the working plane. To reset M116, enter M117. M116 is also canceled at the end of the program.

M116 becomes effective at the start of block.

## Shortest-path traverse of rotary axes: M126

#### Standard behavior



The behavior of the TNC when positioning the rotary axes depends on the machine tool. Refer to your machine manual.

The standard behavior of the TNC while positioning rotary axes whose display has been reduced to values less than 360° is dependent on machine parameter **shortestDistance** (300401). This machine parameter defines whether the TNC should consider the difference between nominal and actual position, or whether it should always (even without M126) choose the shortest path to the programmed position. Examples:

Actual position	Nominal position	Traverse
350°	10°	-340°
10°	340°	+330°

#### **Behavior with M126**

With M126, the TNC will move the axis on the shorter path of traverse for rotary axes whose display is reduced to values less than 360°. Examples:

Actual position	Nominal position	Traverse
350°	10°	+20°
10°	340°	-30°

## Effect

M126 becomes effective at the start of block.

To cancel M126, enter M127. At the end of program, M126 is automatically canceled.

12.4 Miscellaneous functions for rotary axes

# Reducing display of a rotary axis to a value less than 360°: M94

#### **Standard behavior**

The TNC moves the tool from the current angular value to the programmed angular value.

#### Example:

Current angular value:	538°
Programmed angular value:	180°
Actual distance of traverse:	-358°

## **Behavior with M94**

At the start of block, the TNC first reduces the current angular value to a value less than 360° and then moves the tool to the programmed value. If several rotary axes are active, M94 will reduce the display of all rotary axes. As an alternative you can enter a rotary axis after M94. The TNC then reduces the display only of this axis.

## **Example NC blocks**

To reduce display of all active rotary axes:

#### L M94

To reduce display of the C axis only:

#### L M94 C

To reduce display of all active rotary axes and then move the tool in the C axis to the programmed value:

#### L C+180 FMAX M94

## Effect

M94 is effective only in the block in which it is programmed. M94 becomes effective at the start of block.

## Maintaining the position of the tool tip when positioning with tilted axes (TCPM): M128 (software option 2)

## Standard behavior

The TNC moves the tool to the positions given in the part program. If the position of a tilted axis changes in the program, the resulting offset in the linear axes must be calculated, and traversed in a positioning block.

## Behavior with M128 (TCPM: Tool Center Point Management)



The machine geometry must be specified by the machine tool builder in the description of kinematics.

If the position of a controlled tilted axis changes in the program, the position of the tool tip to the workpiece remains the same.

#### Caution: Danger to the workpiece!

For tilted axes with Hirth coupling: Do not change the position of the tilted axis until after retracting the tool. Otherwise you might damage the contour when disengaging from the coupling.

After **M128** you can program another feed rate, at which the TNC will carry out the compensation movements in the linear axes.

If you wish to use the handwheel to change the position of the tilted axis during program run, use **M128** in conjunction with **M118**. Handwheel positioning in a machine-based coordinate system is possible when **M128** is active.

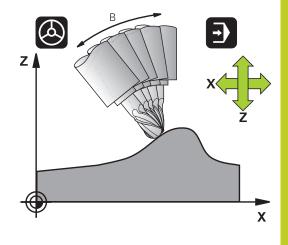


Before positioning with **M91** or **M92** and before a **TOOL CALL**, **RESET M128**.

To avoid contour gouging you must use only spherical cutters with **M128**.

The tool length must refer to the spherical center of the tool tip.

If **M128** is active, the TNC shows the TCPM symbol in the status display.



12.4 Miscellaneous functions for rotary axes

#### M128 on tilting tables

If you program a tilting table movement while **M128** is active, the TNC rotates the coordinate system accordingly. If, for example, you rotate the C axis by 90° (through a positioning command or datum shift) and then program a movement in the X axis, the TNC executes the movement in the machine axis Y.

The TNC also transforms the defined datum, which has been shifted by the movement of the rotary table.

#### M128 with 3-D tool compensation

If you carry out a 3-D tool compensation with active **M128** and active radius compensation **RL/RR**/, the TNC will automatically position the rotary axes for certain machine geometrical configurations (Peripheral milling, See "Three-dimensional tool compensation (software option 2)", page 447).

#### Effect

**M128** becomes effective at the start of block, **M129** at the end of block. **M128** is also effective in the manual operating modes and remains active even after a change of mode. The feed rate for the compensation movement will be effective until you program a new feed rate or until you cancel **M128** with **M129**.

Enter **M129** to cancel **M128**. The TNC also cancels **M128** if you select a new program in a program run operating mode.

#### **Example NC blocks**

Feed rate of 1000 mm/min for compensation movements:

L X+0 Y+38.5 IB-15 RL F125 M128 F1000

12

#### Inclined machining with noncontrolled rotary axes

If you have noncontrolled rotary axes (counting axes) on your machine, then in combination with M128 you can also perform inclined machining operations with these axes.

- 1 Manually traverse the rotary axes to the desired positions. M128 must not be active!
- 2 Activate M128: The TNC reads the actual values of all rotary axes present, calculates from this the new position of the tool center point, and updates the position display
- 3 The TNC performs the necessary compensating movement in the next positioning block
- 4 Carry out the machining operation
- 5 At the end of program, reset M128 with M129, and return the rotary axes to the initial positions

Proceed as follows:



As long as M128 is active, the TNC monitors the actual positions of the noncontrolled rotary axes. If the actual position deviates from the nominal position by a value greater than that defined by the machine manufacturer, the TNC outputs an error message and interrupts program run.

## **12.4** Miscellaneous functions for rotary axes

## Selecting tilting axes: M138

#### Standard behavior

The TNC performs M128 and TCPM, and tilts the working plane, only in those axes for which the machine tool builder has set the appropriate machine parameters.

#### **Behavior with M138**

The TNC performs the above functions only in those tilting axes that you have defined using M138.



If you restrict the number of tilting axes with the **M138** function, your machine may provide only limited tilting possibilities.

#### Effect

M138 becomes effective at the start of block.

You can reset M138 by reprogramming it without entering any axes.

#### Example NC blocks

Perform the above-mentioned functions only in the tilting axis C:

L Z+100 R0 FMAX M138 C

12

## Compensating the machine's kinematics configuration for ACTUAL/NOMINAL positions at end of block: M144 (software option 2)

## Standard behavior

The TNC moves the tool to the positions given in the machining program. If the position of a tilted axis changes in the program, the resulting offset in the linear axes must be calculated, and traversed in a positioning block.

## **Behavior with M144**

The TNC calculates into the position value any changes in the machine's kinematics configuration which result, for example, from adding a spindle attachment. If the position of a controlled tilted axis changes, the position of the tool tip to the workpiece is also changed. The resulting offset is calculated in the position display.



Positioning blocks with M91/M92 are permitted if M144 is active.

The position display in the operating modes FULL SEQUENCE and SINGLE BLOCK does not change until the tilting axes have reached their final position.

## Effect

M144 becomes effective at the start of the block. M144 does not function in connection with M128 or a tilted working plane. You can cancel M144 by programming M145.



The machine geometry must be specified by the machine tool builder in the description of kinematics.

The machine tool builder determines the behavior in the automatic and manual operating modes. Refer to your machine manual. 12.5 FUNCTION TCPM (software option 2)

## 12.5 **FUNCTION TCPM (software option 2)**

## Function



The machine geometry must be specified by the machine tool builder in the description of kinematics.



## For tilted axes with Hirth coupling:

Only change the position of the tilted axis after retracting the tool. Otherwise you might damage the contour when disengaging from the coupling.

Before positioning with **M91** or **M92** and before a **TOOL CALL**: Reset **TCPM FUNCTION**.

To avoid contour gouging you must use only spherical cutters with **TCPM FUNCTION**.

The tool length must refer to the spherical center of the tool tip.

If **TCPM FUNCTION** is active, the TNC shows the symbol **TCPM** in the position display.

**TCPM FUNCTION** is an improvement on the **M128** function, with which you can define the behavior of the TNC when positioning the rotary axes. In contrast to **M128**, with **TCPM FUNCTION** you can define the mode of action of various functions:

- Mode of action of the programmed feed rate: F TCP / F CONT
- Interpretation of the rotary axis coordinates programmed in the NC program: AXIS POS / AXIS SPAT
- Type of interpolation between start and target position: PATHCTRL AXIS / PATHCTRL VECTOR

## **Defining the TCPM FUNCTION**



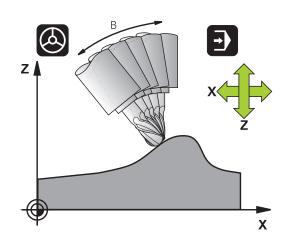
Press the special functions key



- Press the Programming Aids soft key

FUNCTION TCPM

Select TCPM FUNCTION



## Mode of action of the programmed feed rate

The TNC provides two functions for defining the mode of action of the programmed feed rate:



► **F TCP** determines that the programmed feed rate is interpreted as the actual relative velocity between the tool point (tool center point) and the workpiece.



F CONT determines that the programmed feed rate is interpreted as the contouring feed rate of the axis programmed in the respective NC block.

#### **Example NC blocks**

•••		
13 FUN	NCTION TCPM F TCP	Feed rate refers to the tool tip
14 FUI	NCTION TCPM F CONT	Feed rate is interpreted as the speed of the tool along the contour

•••

# Interpretation of the programmed rotary axis coordinates

Up to now, machines with 45° swivel heads or 45° tilting tables could not easily set the angle of inclination or a tool orientation with respect to the currently active coordinate system (spatial angle). This function could only be realized through specially written programs with normal vectors (LN blocks).

The TNC now provides the following function:



 AXIS POS determines that the TNC interprets the programmed coordinates of rotary axes as the nominal position of the respective axis

AXIS SPATIAL  AXIS SPAT determines that the TNC interprets the programmed coordinates of rotary axes as the spatial angle

## 12.5 FUNCTION TCPM (software option 2)

**AXIS POS** should be used primarily if your machine is equipped with Cartesian rotary axes. You can also use **AXIS POS** with 45°-swivel heads/ tilting tables if it is ensured that the programmed rotary axis coordinates define the desired orientation of the working plane correctly (this can be accomplished with a CAM system, for example).

**AXIS SPAT:** The rotary axis coordinates entered in the positioning block are space angles that are given with respect to the currently active (perhaps tilted) coordinate system (incremental space angle).

After you switch on **FUNCTION TCPM** with **AXIS SPAT**, in the first positioning block you should always program all three spatial angles in the inclination angle definition. This also applies if one or more spatial angles are 0°. **AXIS SPAT:** The rotary axis coordinates entered in the positioning block are space angles that are given with respect to the currently active (perhaps tilted) coordinate system (incremental space angle).

#### **Example NC blocks**

•••	
13 FUNCTION TCPM F TCP AXIS POS	Rotary axis coordinates are axis angles
18 FUNCTION TCPM F TCP AXIS SPAT	Rotary axis coordinates are spatial angles
20 L A+0 B+45 C+0 F MAX	Set tool orientation to B+45 degrees (spatial angle). Define spatial angles A and C with 0 $$

# Type of interpolation between the starting and end position

The TNC provides two functions for defining the type of interpolation between the starting and end position:



- PATHCTRL AXIS determines that the tool point between the starting and end position of the respective NC block moves on a straight line (Face Milling). The direction of the tool axis at the starting and end positions corresponds to the respective programmed values, but the tool circumference does not describe a defined path between the starting and end positions. The surface produced by milling with the tool circumference (Peripheral Milling) depends on the machine geometry
- PATH CONTROL VECTOR
- PATHCTRL VECTOR determines that the tool tip between the starting and end position of the respective NC block moves on a straight line and also that the direction of the tool axis between starting and end position is interpolated so that a plane results from machining at the tool circumference (Peripheral Milling)



## With PATHCTRL VECTOR, remember:

Any defined tool orientation is generally accessible through two different tilting angle positions. The TNC uses the solution over the shortest available path—starting from the current position. Therefore, with 5-axis machining it may happen that the TNC moves in the rotary axes to end positions that are not programmed.

To attain the most continuous multiaxis movement possible, define Cycle 32 with a **tolerance for rotary axes** (see Touch Probe Cycles User's Manual, Cycle 32 TOLERANCE). The tolerance of the rotary axes should be about the same as the tolerance of the contouring deviation that is also defined in Cycle 32. The greater the tolerance for the rotary axes is defined, the greater are the contour deviations during peripheral milling.

## Example NC blocks

13 FUNCTION TCPM F TCP AXIS SPAT PATHCTRL AXIS

14 FUNCTION TCPM F TCP AXIS POS PATHCTRL VECTOR

Tool tip moves along a straight line

Tool tip and tool directional vector move in one plane

•••

...

12.5 FUNCTION TCPM (software option 2)

## **Resetting the TCPM FUNCTION**



• **FUNCTION RESET TCPM** is to be used if you want to purposely reset the function within a program.



The TNC automatically resets **TCPM FUNCTION** if you select a new program in a program run mode. You can reset the **TCPM FUNCTION** only if the **PLANE** function is inactive. If required, run **PLANE RESET** before **FUNCTION RESET TCPM**.

#### **Example NC blocks**

**25 FUNCTION RESETTCPM** 

Reset TCPM FUNCTION

•••

••••

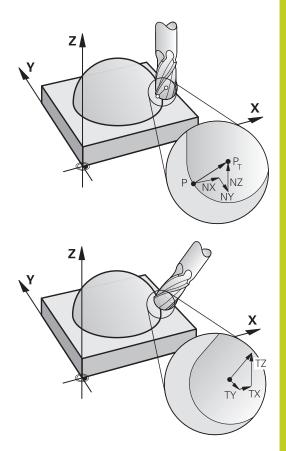
# 12.6 Three-dimensional tool compensation (software option 2)

## Introduction

The TNC can carry out a three-dimensional tool compensation (3-D compensation) for straight-line blocks. Apart from the X, Y and Z coordinates of the straight-line end point, these blocks must also contain the components NX, NY and NZ of the surface-normal vector See "Definition of a normalized vector", page 448.

If you want to carry out a tool orientation, these blocks need also a normalized vector with the components TX, TY and TZ, which determines the tool orientation See "Definition of a normalized vector", page 448.

The straight-line end point, the components for the surface-normal vector as well as those for the tool orientation must be calculated by a CAM system.



## Application possibilities

TNC 640 | User's Manual

HEIDENHAIN Conversational Programming | 5/2013

- Use of tools with dimensions that do not correspond with the dimensions calculated by the CAM system (3-D compensation without definition of the tool orientation).
- Face milling: compensation of the cutter geometry in the direction of the surface-normal vector (3-D compensation with and without definition of the tool orientation). Cutting is usually with the end face of the tool.
- Peripheral milling: compensation of the cutter radius perpendicular to the direction of movement and perpendicular to the tool direction (3D radius compensation with definition of the tool orientation). Cutting is usually with the lateral surface of the tool.

## 12.6 Three-dimensional tool compensation (software option 2)

## Definition of a normalized vector

A normalized vector is a mathematical quantity with a value of 1 and any direction. The TNC requires up to two normalized vectors for LN blocks, one to determine the direction of the surface-normal vector, and another (optional) to determine the tool orientation direction. The direction of a surface-normal vector is determined by the components NX, NY and NZ. With an end mill and a radius mill, this direction is perpendicular from the workpiece surface to be machined to the tool datum PT, and with a toroid cutter through PT' or PT (see figure). The direction of the tool orientation is determined by the components TX, TY and TZ.

The coordinates for the X, Y, Z positions and the surface-normal components NX, NY, NZ, as well as TX, TY, TZ must be in the same sequence in the NC block.

Always indicate all of the coordinates and all of the surface-normal vectors in an LN block, even if the values have not changed from the previous block.

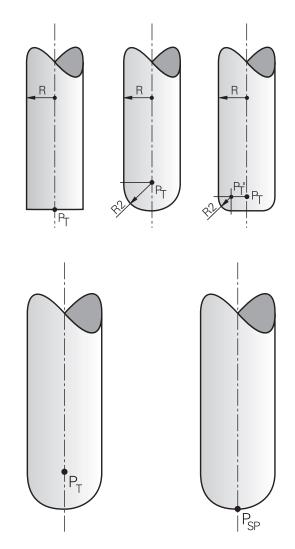
TX, TY and TZ must always be defined with numerical values. You cannot use Q parameters.

Calculate the normal vectors as exactly as possible and output them with a sufficient number of decimal places, in order to avoid interruptions in the feed rate during machining.

3-D compensation with surface-normal vectors is only effective for coordinates in the main axes X, Y, Z. If you insert a tool with oversize (positive delta value), the TNC outputs an error message. You can suppress the error message with the M function **M107** (See "Definition of a normalized vector").

The TNC will not display an error message if an entered tool oversize would cause damage to the contour.

Machine parameter **toolRefPoint** defines whether the CAD system has calculated the tool length compensation from the center of sphere PT or the south pole of the sphere PSP (see figure).



## **Permitted tool shapes**

You can describe the permissible tool shapes in the tool table via tool radii  ${\bf R}$  and  ${\bf R2}$  (see figure):

- Tool radius R: Distance from the tool center to the tool circumference
- Tool radius 2 R2: Radius of the curvature between tool tip and tool circumference

The ratio of **R** to **R2** determines the shape of the tool:

- **R2** = 0: End mill
- R2 = R : Radius cutter
- 0 < **R2** < **R**: Toroid cutter

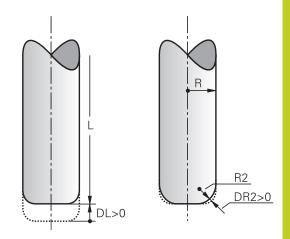
These data also provide the coordinates of the tool datum PT.

## Using other tools: Delta values

If you want to use tools that have different dimensions than the ones you originally programmed, you can enter the difference between the tool lengths and radii as delta values in the tool table or **TOOL CALL**:

- Positive delta value DL, DR, DR2: The tool is larger than the original tool (oversize)
- Negative delta value DL, DR, DR2: The tool is smaller than the original tool (undersize)

The TNC then compensates the tool position by the sum of the delta values from the tool table and the tool call.



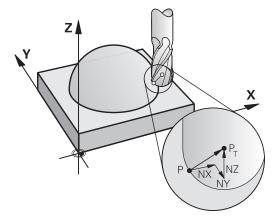
## **3-D compensation without TCPM**

The TNC carries out a 3-D compensation for three-dimensional machining operations if the NC program contains surface-normal vectors. In this case, the **RL/RR** radius compensation and **TCPM** or **M128** must be inactive. The TNC displaces the tool in the direction of the surface-normal vectors by the sum of the delta values (tool table and **TOOL CALL**).

#### Example: Block format with surface-normal vectors

## 1 LN X+31.737 Y+21.954 Z+33.165NX+0.2637581 NY+0.0078922 NZ-0.8764339 F1000 M3

LN:	Straight line with 3-D compensation
X, Y, Z:	Compensated coordinates of the straight-line end point
NX, NY, NZ:	Components of the surface-normal vector
F:	Feed rate
M:	Miscellaneous function



## 12.6 Three-dimensional tool compensation (software option 2)

## Face Milling: 3D compensation with TCPM

Face milling is a machining operation carried out with the front face of the tool. A three-dimensional compensation is carried out during five-axis machining if the NC program contains surface-normal vectors and **TCPM** or **M128** is active. In this case, the RL/RR radius compensation must not be active. The TNC displaces the tool in the direction of the surface-normal vectors by the sum of the delta values (tool table and **TOOL CALL**).

If **TCPM** (See "Maintaining the position of the tool tip when positioning with tilted axes (TCPM): M128 (software option 2)", page 437) is active, the TNC maintains the tool perpendicular to the workpiece contour if no tool orientation is programmed in the **LN** block.

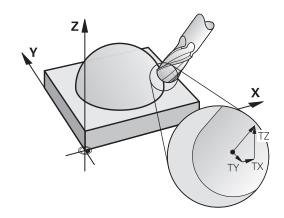
If there is a tool orientation **T** defined in the **LN** block and M128 (or **TCPM FUNCTION**) is active at the same time, then the TNC will position the rotary axes automatically so that the tool can reach the defined orientation. If you have not activated **M128** (or **TCPM FUNCTION**), then the TNC ignores the direction vector **T**, even if it is defined in the **LN** block.

The TNC is not able to automatically position the rotary axes on all machines. Refer to your machine manual.



## Danger of collision!

On machines whose rotary axes only allow limited traverse, sometimes automatic positioning can require the table to be rotated by 180°. In this case, make sure that the tool head does not collide with the workpiece or the clamps.



# Example: Block format with surface normals without tool orientation

LN X+31.737 Y+21.954 Z+33.165 NX+0.2637581 NY+0.0078922 NZ-0.8764339 F1000 M128

#### Example: Block format with surface normals and tool orientation

LN X+31.737 Y+21.954 Z+33.165 N	X+0.2637581 NY+0.0078922
NZ-0.8764339 TX+0.0078922 TY-0	.8764339 TZ+0.2590319 F1000
M128	

LN:	Straight line with 3-D compensation
X, Y, Z:	Compensated coordinates of the straight-line end point
NX, NY, NZ:	Components of the surface-normal vector
<b>ΤΧ, ΤΥ, ΤΖ</b> :	Components of the normalized vector for workpiece orientation
F:	Feed rate
<b>M</b> :	Miscellaneous function

# Peripheral Milling: 3-D radius compensation with TCPM and radius compensation (RL/RR)

The TNC displaces the tool perpendicular to the direction of movement and perpendicular to the tool direction by the sum of the delta values **DR** (tool table and **TOOL CALL**). Determine the compensation direction with radius compensation **RL/RR** (see figure, traverse direction Y+). For the TNC to be able to reach the set tool orientation, you need to activate the function **M128**, See "Maintaining the position of the tool tip when positioning with tilted axes (TCPM): M128 (software option 2)", page 437. The TNC then positions the rotary axes automatically so that the tool can reach the defined orientation with the active compensation.



This function is possible only on machines for which you can define spatial angles for the tilting axis configuration. Refer to your machine manual.

The TNC is not able to automatically position the rotary axes on all machines.

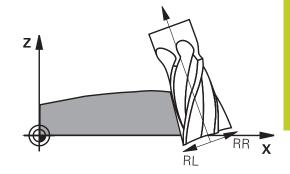
Refer to your machine manual.

Note that the TNC makes a compensating movement by the defined **delta values**. The tool radius R defined in the tool table has no effect on the compensation.



## Danger of collision!

On machines whose rotary axes only allow limited traverse, sometimes automatic positioning can require the table to be rotated by 180°. In this case, make sure that the tool head does not collide with the workpiece or the clamps.



## **12.6** Three-dimensional tool compensation (software option 2)

There are two ways to define the tool orientation:

- In an LN block with the components TX, TY and TZ
- In an L block by indicating the coordinates of the rotary axes

#### Example: Block format with tool orientation

## 1 LN X+31.737 Y+21.954 Z+33.165 TX+0.0078922 TY-0.8764339 TZ+0.2590319 RR F1000 M128

LN:	Straight line with 3-D compensation
X, Y, Z:	Compensated coordinates of the straight-line end point
<b>TX, TY, TZ</b> :	Components of the normalized vector for workpiece orientation
RR:	Tool radius compensation
F:	Feed rate
<b>M</b> :	Miscellaneous function

#### Example: Block format with rotary axes

1 L X+31.737 Y+21.954 M128	¥ Z+33.165 B+12.357 C+5.896 RL F1000
L: St	raight line
	ompensated coordinates of the straight-line ad point
	pordinates of the rotary axes for tool ientation
RL: Ra	adius compensation
F: Fe	ed rate
<b>M</b> : M	iscellaneous function



Programming: Pallet editor

## 13 Programming: Pallet editor

13.1 Pallet Management

## 13.1 Pallet Management

## Application



Pallet table management is a machine-dependent function. The standard functional range is described below. Refer to your machine manual.

Pallet tables are used for machining centers with pallet changers: The pallet table calls the part programs that are required for the different pallets, and activates presets, datum shifts and datum tables.

You can also use pallet tables to run in succession several programs that have different reference points.



If you want to create or manage pallet tables, the name of the file must begin with a letter.

Pallet tables contain the following information:

- TYPE (entry obligatory): Identification for pallet or NC program (select with ENT)
- NAME (entry obligatory): Pallet or program name. The machine tool builder determines the pallet name (see your machine tool manual). The program name must be stored in the same directory as the pallet table. Otherwise you must enter the full path name for the program
- **PRESET** (entry optional): Preset number from the preset table. The preset number defined here is interpreted by the TNC as a workpiece datum.
- DATUM (entry optional): Name of the datum table. The datum table must be stored in the same directory as the pallet table. Otherwise you must enter the full path name for the datum table. Datums from the datum table can be activated in the NC program with Cycle 7 DATUM SHIFT
- LOCATION (entry obligatory): The entry "MA" indicates that the machine is loaded with a pallet or fixture that can be machined. The TNC only machines pallets or fixtures identified by "MA". To enter "MA", press the ENT key. Press the NO ENT key to remove the entry.
- LOCK (entry optional): Lock execution of a pallet line. Press the ENT key to mark the execution of a pallet line as locked (the affected line will be identified by "\*"). Press the NO ENT key to cancel the lock. You can lock the execution for individual programs, fixtures or entire pallets. Non-locked lines (e.g. PGM) of a locked pallet will also not be executed.

NR	- T		NAME			DATUM	PRESET	LOCATION	L0-	
	0	PAL			L100			NA	- 6	
	1	PGM			16.H		1		-1	
	2	PGM		32	17.H		2	NA	-1	
	type?						_			

Editing function	Soft key
Select beginning of table	BEGIN
Select end of table	
Select previous page in table	
Select next page in table	
Insert as last line in the table	INSERT LINE
Delete the last line in the table	DELETE LINE
Add the number of lines that can be entered at the end of the table	APPEND N LINES
Copy highlighted field	COPY FIELD
Insert copied field	PASTE FIELD
Select beginning of line	BEGIN LINE
Select end of line	END LINE
Copy the current value	COPY FIELD
Insert the current value	PASTE FIELD
Edit the current field	EDIT CURRENT FIELD
Sort by content of column	SORT
Additional functions, e.g. saving	MORE FUNCTIONS

## 13 Programming: Pallet editor

13.1 Pallet Management

## Select pallet table

- Call the file manager in the Programming and Editing or Program Run mode: Press the PGM MGT key
- Display all type .P files: Press the SELECT TYPE and SHOW ALL soft keys
- Select a pallet table with the arrow keys, or enter a new file name to create a new table
- Confirm your entry with the ENT key

## Exiting the pallet file

- ▶ Call the file manager: Press the PGM MGT key
- Select a different type of file: Press the SELECT TYPE soft key and the soft key for the desired file type, for example SHOW.H
- Select the desired file

## **Run pallet file**



MP7683 defines whether the pallet table is to be executed blockwise or continuously.

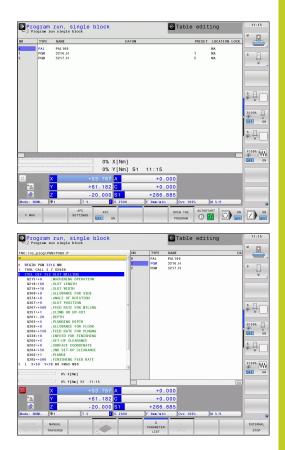
Use the screen layout button to switch between table view and form view.

- Select the file manager in the Program Run, Full Sequence or Program Run, Single Block operating modes: Press the PGM MGT key
- Display all type .P files: Press the SELECT TYPE and SHOW P. soft keys
- Select the pallet table with the arrow keys and confirm with ENT
- Execute the pallet table: Press the NC start key

## Screen layout for executing pallet tables

You can have the TNC display the program contents and pallet file contents on the screen together by selecting the screen layout PGM + PALLET. During execution, the TNC then shows program blocks to the left and the pallet to the right. To check the program contents before execution, proceed as follows:

- Select a pallet table
- With the arrow keys, choose the program you would like to check
- Press the OPEN PGM soft key: the TNC displays the selected program on the screen. You can now page through the program with the arrow keys
- ▶ To return to the pallet table, press the END PGM soft key



Programming: Turning Operations

## **14** Programming: Turning Operations

14.1 Turning Operations on Milling Machines (Software Option 50)

## 14.1 Turning Operations on Milling Machines (Software Option 50)

## Introduction

Special types of milling machines allow performing both milling and drilling operations. A workpiece can thus be machined completely on one machine without rechucking, even if complex milling and turning applications are required.

Turning operations are machining processes by which workpieces are rotated, thus implementing the cutting movements. A fixed tool carries out infeed and feed movements. Turning applications, depending on machining direction and task, are subdivided into various production processes, e.g. longitudinal turning, face turning, groove turning or thread turning. The TNC offers you several cycles for each of the various production processes (see User's Manual, Cycles, "Turning" chapter).

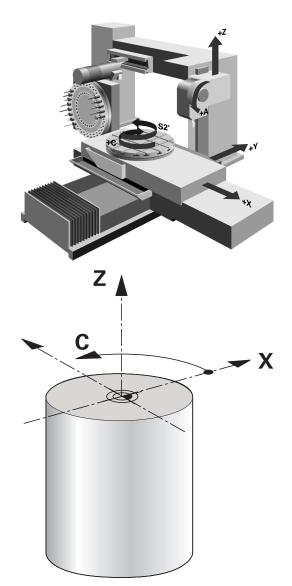
On the TNC you can simply switch between Milling and Turning mode within the NC program. In Turning mode, the rotary table serves as turning spindle, whereas the milling spindle with the tool is fixed. This enables rotationally symmetric contours to be created. The preset must be in the center of the turning spindle.

With the management of turning tools, other geometric descriptions are considered than with milling or drilling tools. To be able to execute tool radius compensation, for example, you have to define the tool radius. To support these definitions, the TNC provides a special tool management for turning tools, See "Tool data", page 467.

Different cycles are available for machining. These can also be used with additionally inclined swivel axes: page 479

The assignment of the axes with turning is defined so that the X coordinates describe the diameter of the workpiece and the Z coordinates the longitudinal positions.

Programming is thus always done in the XZ coordinate plane. The machine axes to be used for the required motions depend on the respective machine kinematics and are determined by the machine manufacturer. This makes NC programs with turning functions largely exchangeable and independent of the machine model.



14

## **14.2** Basis Functions (Software Option 50)

## Switching between milling/turning mode of operation



The machine has to have been adapted by the machine manufacturer for turning operations and switching the mode of operation. Refer to your machine manual.

To switch between milling and turning operations you must switch to the specific mode.

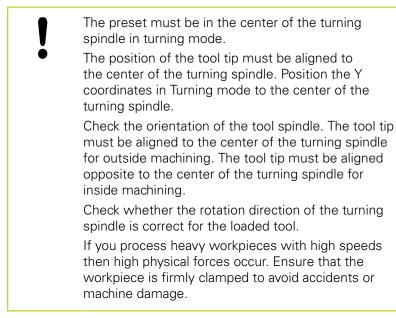
You can switch these operating modes with the NC functions FUNCTION MODE TURN and FUNCTION MODE MILL.

The TNC shows a symbol in the status display when the turning mode is active

Mode of operation	Symbol
Turning mode active: FUNCTION MODE TURN	<b>_</b>

Milling mode active: FUNCTION MODE MILL No symbol

When the modes of operation are switched between, the TNC executes a macro that defines the machine-specific settings for the specific mode of operation.



## **14** Programming: Turning Operations

## 14.2 Basis Functions (Software Option 50)

In Turning mode, diameter values are displayed on the X axis position display. The TNC then shows a diameter symbol on the position display.

In Turning mode, the spindle potentiometer is effective on the turning spindle (rotary table). Switching mode is not possible if "Tilting the working plane" or TCPM is active.

In Turning mode, no coordinate conversions are permitted except for the datum shift cycle.

You can also use the smartSelect function for defining the turning functions, See "Overview of special functions".

Entering the operation mode:

SPEC	
FCT	

Show the soft-key row with special functions

- TURNING PROGRAM FUNCTIONS
- Select the menu for TURNING PROGRAM FUNCTIONS



FUNCTION MODE Select FUNCTION MODE

Select BASIC FUNCTIONS

Select the function for Turning or Milling mode

## NC syntax

11 FUNCTION MODE TURN; ACTIVATE TURNING MODE 12 FUNCTION MODE MILL; ACTIVATE MILLING MODE

40.000

## Graphical display of turning operations

You can graphically simulate turning processes with the line graphic in Programming operating mode. The requirement for this is a workpiece blank definition suitable for the turning process.

The assignment of the axes with turning is defined so that the X coordinates describe the diameter of the workpiece and the Z coordinates the longitudinal positions. To display the traverse movements in Turning mode you must use a workpiece blank definition with the spindle axis  $\mathbf{Y}$ .

Even when turning occurs in a 2D plane (X and Z coordinates) you must still program the Y values when defining the workpiece blank. The TNC requires the Y expansion for calculating the workpiece blank cuboid. It is sufficient when you enter small values here such as -1 and +1, as the Y coordinates in Turning mode are not considered as the operating axis.

20.000



In the Program Test operating mode, you can only use the 3D line graphic for simulating processing in Turning mode.

## NC syntax

O BEGIN PGM SHOULDER MM	
1 BLK FORM 0.1Y X+0 Y-1 Z-50	Definition of workpiece blank
2 BLK FORM 0.2 X+87 Y+1 Z+2	
3 TOOL CALL 12	Tool call
4 M140 MB MAX	Retract the tool
5 FUNCTION MODE TURN	Activate Turning mode

## **14** Programming: Turning Operations

14.2 Basis Functions (Software Option 50)

## **Program spindle speed**



If you machine at constant cutting speed, the selected gear range limits the possible spindle speed range. The possible gear ranges (if applicable) depend on your machine.

With turning you can machine both at constant spindle speed and constant cutting speed.

If you machine at constant cutting speed **VCONST:ON**, the TNC modifies speed according to the distance of the tool tip to the center of the turning spindle. The TNC increases table speed with positioning in the direction of the turning center and reduces speed with movements away from the turning center.

For processing with constant spindle speed **VCONST:OFF**, speed is independent of the tool position.

Use FUNCTION TURNDATA SPIN to define the speed. The TNC now provides the following entry elements:

- VCONST: Constant cutting speed on/off (obligatory)
- VC: Cutting speed (optional)
- S: Nominal speed when no constant cutting speed is active (optional)
- S MAX: Maximum speed with constant cutting speed (optional), is reset with S MAX 0
- gearrange: Gear range for the turning spindle (optional)

#### Defining the speed:

Show the soft-key row with special functions

TURNING
PROGRAM
FUNCTIONS

SPEC FCT

#### Select the menu for TURNING PROGRAM FUNCTIONS

FUNCTION TURNDATA

> TURNDATA SPIN

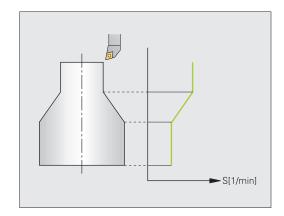
VCONST : ON Select TURNDATA SPIN

Select FUNCTION TURNDATA

Select the function for speed entry VCONST:

#### NC syntax

3 FUNCTION TURNDATA SPIN VCONST:ON VC:100 GEARRANGE:2	Definition of a constant cutting speed in gear range 2
3 FUNCTION TURNDATA SPIN VCONST: OFF S550	Definition of a constant spindle speed



X

## Basis Functions (Software Option 50) 14.2

## Feed rate

With turning, feed rates are often specified in millimeters per revolution. The TNC moves the tool according to a defined value for each spindle revolution. The resulting contouring feed rate is thus dependent on the speed of the turning spindle. With high speeds the TNC increases the feed rate and with low speeds reduces the feed rate. With uniform cutting depth you can machine with constant cutting force to achieve a constant cut thickness.

The programmed feed rate on a TNC is by default always interpreted in millimeters per minute (mm/min). If you wish to define feed rate in millimeters per revolution (mm/rev.), you must program **M136**. The TNC then interprets all subsequent feed rate specifications in mm/rev. until **M136** is canceled.

**M136** is effective modally at the beginning of the block and can be canceled with **M137**.

# for **Z**

## NC syntax

10 L X+102 Z+2 R0 FMAX	Movement at rapid traverse
15 L Z-10 F200	Movement at a feed rate of 200 mm/min
19 M136	Feed rate in millimeters per revolution
20 L X+154 F0.2	Movement at a feed rate of 0.2 mm/rev.

## Tool call

...

Just as in Milling mode, turning tools are called with the **TOOL CALL** function. You merely have to enter the tool number or tool name in the **TOOL CALL** block.



You can call and insert a turning tool both in Milling mode and in Turning mode.

#### NC syntax

1 FUNCTION MODE TURN	Turning mode selection
2TOOL CALL "TRN_ROUGH"	Tool call
•••	

## **14** Programming: Turning Operations

14.2 Basis Functions (Software Option 50)

## Tool compensation in the program

With **FUNCTION TURNDATA CORR** you can define additional compensation values for the active tool. In **FUNCTION TURNDATA CORR** you can enter delta values for tool lengths in the X direction **DXL** and in the Z direction **DZL**. The compensation values have an additive effect on the compensation values from the turning tool table. **FUNCTION TURNDATA CORR** is always effective for the active tool. A renewed **TOOL CALL** deactivates compensation again. When you exit the program (e.g. PGM MGT), the TNC automatically resets the compensation values.



Tool compensation is always effective in the tool coordinate system, even during inclined machining.

Defining tool compensation:



Show the soft-key row with special functions

- TURNING PROGRAM FUNCTIONS
- Select the menu for TURNING PROGRAM FUNCTIONS
- Select FUNCTION TURNDATA
- FUNCTION TURNDATA

CORR

► Select TURNDATA CORR

## NC syntax

21 FUNCTION TURNDATA CORR-TCS:Z/X DZL:0.1 DXL:0.05

•••

## Tool data

You define turning-specific tool data in the turning tool table **TOOLTURN.TRN**.

The tool number saved in column **T** refers to the number of the turning tool in the TOOL.T. geometry values, e.g. **L** and **R** from TOOL.T are not effective with turning tools.

In addition you must identify turning tools in the tool table TOOL.T as turning tools. For this, in column TYP select the tool type **TURN** for the appropriate tool. If you require additional geometric data for a tool you can create further indexed tools for this.

The tool number in TOOLTURN.TRN must match the tool number of the turning tool in TOOL.T. If you enter or copy a new line you can then enter the corresponding number.

Below the table window the TNC displays dialog text, unit specification and entry area for the specific input field.



## **14** Programming: Turning Operations

14.2 Basis Functions (Software Option 50)

Tool data in the turning tool table	е
-------------------------------------	---

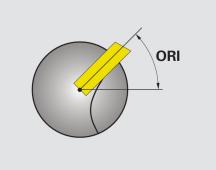
Input element	Application	Input
Т	Tool number must match the tool number of the turning tool in TOOL.T	-
ZL	Compensation value for tool length 1 (Z direction)	-99999.9999+99999.9999
XL	Compensation value for tool length 2 (X direction)	-99999.9999+99999.9999
DZL	Delta value for tool length 1 (Z direction), additive effect on zL	-99999.9999+99999.9999
DXL	Delta value for tool length 2 (X direction), additive effect on XL	-99999.9999+99999.9999
RS	Tool tip radius: The TNC considers the tool tip radius in turning cycles and implements tool tip radius compensation when contours with radius compensation <b>RL</b> or <b>RR</b> were programmed	-99999.9999+99999.9999
то	Tool orientation: Direction of tool tip	19
ANGLE OF ORIENTATION (ORI)	Spindle orientation angle: Angle of the milling spindle for aligning the turning tool to the machining position	-360.0+360.0
T-ANGLE	Setting angle for roughing and finishing tools	0.0000+179.9999
P-ANGLE	Point angle for roughing and finishing tools	0.0000+179.9999
CUTLENGTH	Cutting length of recessing tool	0.0000+99999.9999
CUTWIDTH	Width of recessing tool	0.0000+99999.9999
ТҮРЕ	Type of turning tool: Roughing tool <b>ROUGH</b> , finishing tool <b>FINISH</b> , thread tool <b>THREAD</b> , recessing tool <b>RECESS</b> , button tool <b>BUTTON</b> , groove turning tool <b>RECTURN</b>	ROUGH, FINISH, THREAD, RECESS, BUTTON, RECTURN

With the spindle orientation angle **ORI** you define the angle position of the milling spindle for the turning tool. Orient the tool tip depending on the tool orientation **TO** to the rotary table center or in the opposite direction.



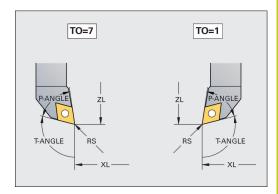
The tool must be clamped and measured in the correct position.

Check the tool orientation after definition of a tool.



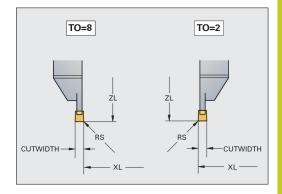
# Tool data for turning tool Required and optional tool data for turning tool

Input element	Application	Input
ZL	Tool length 1	Required
XL	Tool length 2	Required
DZL	Wear compensation <b>ZL</b>	Optional
DXL	Wear compensation <b>XL</b>	Optional
RS	Cutting radius	Required
то	Tool orientation	Required
ORI	Orientation angle	Required
T-ANGLE	Tool angle	Required
P-ANGLE	Point angle	Required
ТҮРЕ	Tool type	Required



# Tool data for recessing tools Required and optional tool data for recessing tools

Input element	Application	Input
ZL	Tool length 1	Required
XL	Tool length 2	Required
DZL	Wear compensation <b>ZL</b>	Optional
DXL	Wear compensation <b>XL</b>	Optional
RS	Cutting radius	Required
то	Tool orientation	Required
ORI	Orientation angle	Required
CUTWIDTH	Width of recessing tool	Required
ТҮРЕ	Tool type	Required

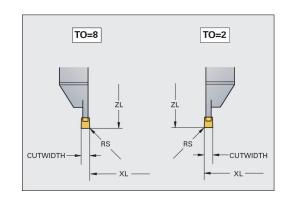


14.2 Basis Functions (Software Option 50)

# Tool data for groove turning tools

Required and optional tool data for groove turning tools

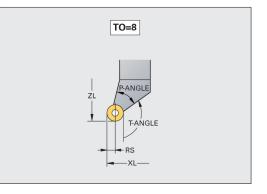
• •	•	•
Input element	Application	Input
ZL	Tool length 1	Required
XL	Tool length 2	Required
DZL	Wear compensation <b>ZL</b>	Optional
DXL	Wear compensation <b>XL</b>	Optional
RS	Cutting radius	Required
ТО	Tool orientation	Required
ORI	Orientation angle	Required
CUTLENGTH	Cutting length of recessing tool	Required
CUTWIDTH	Width of recessing tool	Required
ТҮРЕ	Tool type	Required



### Tool data for button tools

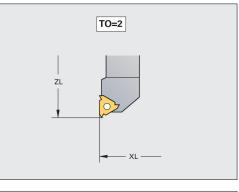
### Required and optional tool data for button tools

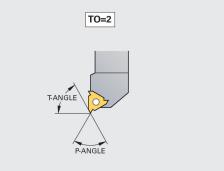
Input element	Application	Input
ZL	Tool length 1	Required
XL	Tool length 2	Required
DZL	Wear compensation <b>ZL</b>	Optional
DXL	Wear compensation <b>XL</b>	Optional
RS	Cutting radius	Required
то	Tool orientation	Required
ORI	Orientation angle	Required
T-ANGLE	Tool angle	Required
P-ANGLE	Point angle	Required
ТҮРЕ	Tool type	Required



# Tool data for threading tools Required and optional tool data for threading tools

• •	•	
Input element	Application	Input
ZL	Tool length 1	Required
XL	Tool length 2	Required
DZL	Wear compensation <b>ZL</b>	Optional
DXL	Wear compensation <b>XL</b>	Optional
то	Tool orientation	Required
ORI	Orientation angle	Required
T-ANGLE	Tool angle	Required
P-ANGLE	Point angle	Required
ТҮРЕ	Tool type	Required





14.2 Basis Functions (Software Option 50)

# Tool tip radius compensation TRC

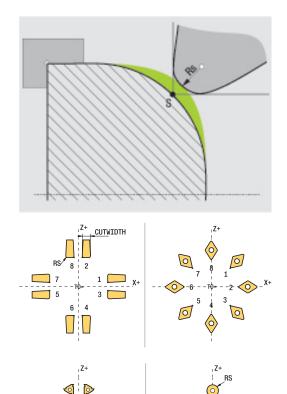
Turning tools have a radius at the tool tip (**RS**). When machining tapers, chamfers and radii, this results in inaccuracies on the contour because programmed traverse paths are always referenced to the theoretical tool tip S (see figure at upper right). TRC prevents the resulting deviations.

In turning cycles the TNC automatically carries out tool tip radius compensation. In specific traversing blocks and within programmed contours, activate TRC with **RL** or **RR**.

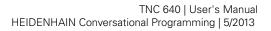
In turning cycles the TNC checks the cutting geometry with the point angle **P-ANGLE** and the setting angle **T-ANGLE**. Contour elements in the cycle are processed by the TNC only as far as this is possible with the specific tool. The TNC outputs a warning when residual material is left behind.

When the position of the cutting edge is neutral (**TO=2;4;6;8**), the direction of the radius compensation is ambiguous. In this case, TRC is only possible within cycles.

The TNC can also run tool tip radius compensation during inclined processing. The following limitation applies here: if you activate inclined processing with M128 then tool tip radius compensation without a cycle, i.e. in traversing blocks with **RL/RR**, is not possible. If you activate inclined processing with **M144** this limitation does not apply.



 $\overline{\mathbf{0}}$ 



# **Recessing and undercutting**

Some cycles machine contours that you have written in a subprogram. You program these contours with plain-language path functions or FK functions. Further special contour elements are available to you for writing turning contours. In this way you can program complete recessing and undercutting as complete contour elements with a single NC block.



Recessing and undercutting always reference a previously defined linear contour element.

Recessing elements GRV and undercut elements UDC can only be used in contour subprograms that are called by a turning cycle (see User's Manual, Cycles, Turning).

You have various input possibilities when defining recessing and undercutting. Some of these inputs are mandatory, and others you can leave out (optional). The mandatory inputs are symbolized as such in the help graphics. In some elements you can select between two different definitions. The TNC has soft keys with the corresponding selection possibilities.

Programming recessing and undercutting:



Show the soft-key row with special functions

Select the menu for TURNING PROGRAM

TURNING PROGRAM FUNCTIONS

RECESS/

GRU

Select RECESS/UNDERCUT

**FUNCTIONS** 

Select GRV (recess) or UDC (undercut)

14.2 Basis Functions (Software Option 50)

#### **Programming recessing**

Recessing is the machining of recesses in round components, usually for accommodation of locking rings and seals or as lubricating grooves. You can program recessing around the circumference or on the face ends of the turned part. For this you have two separate contour elements:

- **GRV RADIAL**: Recess in circumference of component
- **GRV AXIAL**: Recess on face end of component

#### Input elements in recessing GRV

Input element	Application	Input
CENTER	Center of recess	Required
R	Corner radius of both inner corners	Optional
DEPTH / DIAM	Recess depth (pay attention to the algebraic sign!) / diameter of recess base	Required
BREADTH	Recess width	Required
ANGLE / ANG_WIDTH	Edge angle / aperture angle of both edges	Optional
RND / CHF	Curve / chamfer corner of contour near to starting point	Optional
FAR_RND / FAR_CHF	Curve / chamfer corner of contour away from starting point	Optional

The algebraic sign for the recess depth specifies the machining position of the recess (inside/outside machining).

Algebraic sign of recess depth for outside machining:

- Use a negative sign when the contour element runs in a negative direction to the Z coordinate
- Use a positive sign when the contour element runs in a positive direction to the Z coordinate

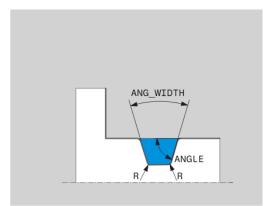
Algebraic sign of recess depth for inside machining:

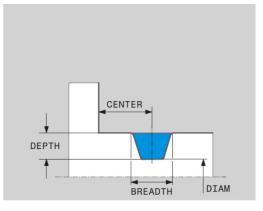
- Use a positive sign when the contour element runs in a negative direction to the Z coordinate
- Use a negative sign when the contour element runs in a positive direction to the Z coordinate

#### Radial recess: depth=5, width=10, Pos.= Z-15

# 21 L X+40 Z+0 22 L Z-30

23 GRV RADIAL CENTER-15 DEPTH-5 BREADTH10 CHF1 FAR\_CHF1 24 L X+60





14

### Programming undercutting

Undercutting is usually required for the flush connection of counterparts. In addition undercutting can help to reduce the notch effect at corners. Threads and fits are often machined with an undercut. You have various contour elements for defining the different undercuts:

- **UDC TYPE\_E**: Undercut for cylindrical surface to be further processed in compliance with DIN 509
- UDC TYPE\_F: Undercut for plan and cylindrical surface for further processing in compliance with DIN 509
- UDC TYPE\_H: Undercut for more rounded transition in compliance with DIN 509
- **UDC TYPE\_K**: Undercut in face and cylindrical surface
- **UDC TYPE\_U**: Undercut in cylindrical surface
- **UDC THREAD**: Thread undercut in compliance with DIN 76



The TNC always interprets undercuts as form elements in the longitudinal direction. No undercuts are possible in the plane direction.

14.2 Basis Functions (Software Option 50)

## Undercut DIN 509 UDC TYPE \_E Input elements in undercut DIN 509 UDC TYPE\_E

Input element	Application	Input
R	Corner radius of both inner corners	Optional
DEPTH	Undercut depth	Optional
BREADTH	Undercut width	Optional
ANGLE	Undercut angle	Optional

#### Undercut: depth = 2, width = 15

21 L X+40 Z+0

22 L Z-30

23 UDC TYPE\_E R1 DEPTH2 BREADTH15

#### 24 L X+60

# Undercut DIN 509 UDC TYPE\_F Input elements in undercut DIN 509 UDC TYPE\_F

Input element	Application	Input
R	Corner radius of both inner corners	Optional
DEPTH	Undercut depth	Optional
BREADTH	Undercut width	Optional
ANGLE	Undercut angle	Optional
FACEDEPTH	Depth of face	Optional
FACEANGLE	Contour angle of face	Optional

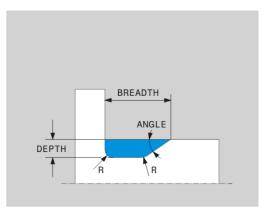
### Undercut form F: depth = 2, width = 15, depth of face = 1

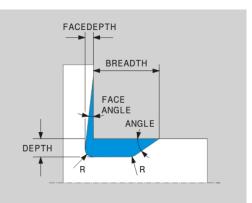
21 L X+40 Z+0

22 L Z-30

23 UDC TYPE\_F R1 DEPTH2 BREADTH15 FACEDEPTH1

24 L X+60





# Undercut DIN 509 UDC TYPE\_H Input elements in undercut DIN 509 UDC TYPE\_H

Input element	Application	Input
R	Corner radius of both inner corners	Required
BREADTH	Undercut width	Required
ANGLE	Undercut angle	Required

### Undercut form H: depth = 2, width = 15, angle = 10°

21 L X+40 Z+0

22 L Z-30

23 UDC TYPE\_H R1 BREADTH10 ANGLE10

### 24 L X+60

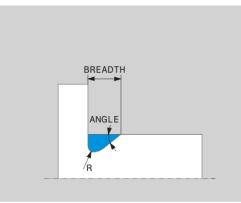
### Undercut UDC TYPE\_K

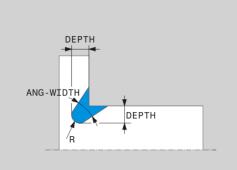
### Input elements in undercut UDC TYPE\_K

Input element	Application	Input
R	Corner radius of both inner corners	Required
DEPTH	Undercut depth (paraxially)	Required
ROT	Angle to longitudinal axis (default: 45°)	Optional
ANG_WIDTH	Opening angle of undercut	Required

# Undercut form K: depth = 2, width = 15, opening angle = 30°

21 L X+40 Z+0 22 L Z-30 23 UDC TYPE\_K R1 DEPTH3 ANG\_WIDTH30 24 L X+60





14.2 Basis Functions (Software Option 50)

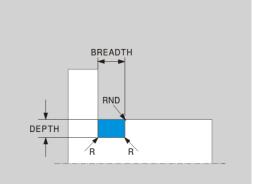
# Undercut UDC TYPE\_U

# Input elements in undercut UDC TYPE\_U

Input element	Application	Input
R	Corner radius of both inner corners	Required
DEPTH	Undercut depth	Required
BREADTH	Undercut width	Required
RND / CHF	Curve / chamfer of outer corner	Required

### Undercut form U: depth = 3, width = 8

21 L X+40 Z+0
22 L Z-30
23 UDC TYPE_U R1 DEPTH3 BREADTH8 RND1
24 L X+60



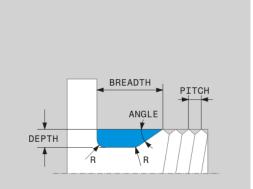
### Undercut UDC THREAD

#### Input elements in undercut DIN 76 UDC THREAD

Input element	Application	Input
PITCH	Thread pitch	Optional
R	Corner radius of both inner corners	Optional
DEPTH	Undercut depth	Optional
BREADTH	Undercut width	Optional
ANGLE	Undercut angle	Optional

### Thread undercut according to DIN 76: Thread pitch = 2

	•	•
21 L X+40 Z+0		
22 L Z-30		
23 UDC THREAD PITCH2		
24 L X+60		



# Basis Functions (Software Option 50) 14.2

# **Inclined turning**

It may sometimes be necessary for you to bring the swivel axes into a specific position to machine a specific process. This can be necessary for example when you can only machine contour elements according to a specific position due to tool geometry. Inclining a swivel axis creates an offset from tool to tool. The function **M144** considers the position of the inclined axes and compensates this offset. In addition the function **M144** aligns the Z direction of the workpiece coordinate system to the direction of the centerline of the tool. If an inclined axis is a tilting table, so that the workpiece is sloping, the TNC runs traverse movements in the displaced workpiece coordinate system. If the inclined axis is a swivel head (tool is sloping) the workpiece coordinate system is not displaced.

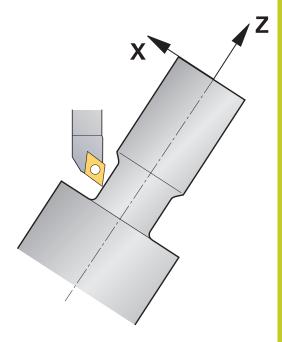
After inclining the swivel axis you may have to again pre-position the tool in the Y coordinates and orient the position of the tool tip with the cycle 800.

Alternatively to function **M144** you can also use function **M128**. The effect is identical, but the following limitation applies: The TNC can also run tool tip radius compensation during inclined processing. If you activate inclined processing with M128 then tool tip radius compensation without a cycle, i.e. in traversing blocks with **RL/RR**, is not possible. If you activate inclined processing with **M144** this limitation does not apply.

If the turning cycles are executed with **M144**, the angles of the tool to the contour change. The TNC automatically takes these modifications into account and thus also monitors the machining in inclined state.

If you process in inclined state you cannot use recessing cycles or thread cycles.

Tool compensation is always effective in the tool coordinate system, even during inclined machining.



T

14.2 Basis Functions (Software Option 50)

#### Example NC blocks: Inclined machining on a machine with a rotary table C and a tilting table A

•••			
12 M144		Activate inclined machining	
13 L A-25 RO FMAX		Position swivel axis	
14 CYCL DEF 800 ADAPT ROTARY COORDINATE SYSTEM		Workpiece coordinate system and align tool	
Q497=+90	;PRECISION ANGLE		
Q498=+0	;REVERSE TOOL		
15 L X+165 Y+0 R0 FMAX		Pre-position the tool	
16 L Z+2 R0 FMAX		Tool at starting position	
		Machining with inclined axis	

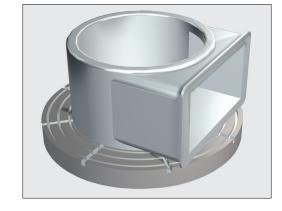
# 14.3 Unbalance Functions

# Unbalance while turning

# General information

The machine has to have been adapted by the machine manufacturer for monitoring and measuring unbalance. Not all machine types require the unbalance functions, so these features might not be available on your machine tool. Refer to your machine manual.

The unbalance functions described here are basic functions that are set up and adapted to the machine by the machine manufacturer. The scope and effect of the described functions may therefore vary from machine to machine. The machine manufacturer may also provide different unbalance functions. Refer to your machine manual.



In a turning operation, the tool is in a fixed position, whereas the rotary table and the clamped workpiece rotate. Depending on the size of the workpiece, the mass that is set in rotation can be very large. As the workpiece rotates, it creates an outward centrifugal force.

The centrifugal force that occurs basically depends on the rotational speed, the mass and the unbalance of the workpiece. An unbalance occurs if an object with a rotationally nonsymmetrical mass distribution is set in rotation. The rotation of the mass object creates outward-directed centrifugal forces. If the rotating mass is evenly distributed, the centrifugal forces cancel each other out.

Unbalance is significantly influenced by the structural shape of the workpiece (e.g. nonsymmetrical pump body) and by the chucking equipment. As these factors frequently cannot be changed, you should compensate any existing unbalance by means of balancing weights. The TNC provides the "Measure Unbalance" cycle for this purpose. The cycle determines the existing unbalance and calculates the mass and position of the required balancing weight.

# 14.3 Unbalance Functions



The rotation of the workpiece creates centrifugal forces that can cause vibration (resonance), depending on the unbalance. This vibration has a negative effect on the machining process and reduces the tool life. High centrifugal forces can damage the machine or push the workpiece out of the fixture.

Check the unbalance whenever you clamp a new workpiece. If required, use balancing weights to compensate any unbalance.

The removal of material during machining will change the mass distribution within the workpiece. This may also have an influence on workpiece unbalance. Therefore, unbalance checks should also be carried out between machining steps.

Keep in mind the mass and unbalance of the workpiece when choosing the speed. Do not use high speeds with heavy workpieces or high unbalance loads.

### **Unbalance Monitor function**

The Unbalance Monitor function monitors the unbalance of a workpiece in Turning mode. If a maximum unbalance limit specified by the machine manufacturer is exceeded, the TNC issues an error message and initiates an emergency stop. In addition, you can further decrease the permissible unbalance limit by setting the machine parameter **limitUnbalanceUsr**. If this limit is exceeded, the TNC will display an error message, but the table rotation will not be stopped. The TNC automatically activates the Unbalance Monitor function when you switch to Turning mode. The unbalance monitor is effective until you switch back to Milling mode.

14

# Measure Unbalance cycle

To ensure maximum safety and minimum strain on the machine and workpiece during turning, you should check the unbalance of the clamped workpiece and compensate it with a balancing weight. The TNC provides the Measure Unbalance cycle for this purpose. The Measure Unbalance cycle determines the unbalance of the workpiece and calculates the mass and position of a balancing weight.

To determine unbalance:

- $\triangleright$
- Shift the soft-key row in the Manual Operation mode
- MANUAL CYCLES TURNING UBALANSE MALE
- Select the MANUAL CYCLES soft key
- Select the TURNING soft key
- Select the MEASURE UNBALANCE soft key
- Enter the speed for unbalance detection
- Press the NC Start button: The cycle starts rotating the table at a low speed and gradually increases the speed up to the defined value. The TNC displays a window that shows the calculated mass and radial position of the balancing weight.

If you wish to use a different radial position or mass for the balancing weight, you can overwrite one value and have the other value recalculated automatically.



Repeat the unbalance measurement after you have clamped a balancing weight.

In some cases, you may need to place two or more balancing weights at different positions in order to compensate unbalance.

15

Manual operation and setup

15.1 Switch-on, switch-off

# 15.1 Switch-on, switch-off

# Switch-on



Switch-on and crossing over the reference points can vary depending on the machine tool.

Refer to your machine manual.

Switch on the power supply for TNC and machine. The TNC then displays the following dialog:

### SYSTEM STARTUP

TNC is started

### POWER INTERRUPTED



 TNC message that the power was interrupted clear the message

### COMPILE A PLC PROGRAM

▶ The PLC program of the TNC is automatically compiled

### RELAY EXT. DC VOLTAGE MISSING



Switch on external dc voltage. The TNC checks the functioning of the EMERGENCY STOP circuit

# MANUAL OPERATION TRAVERSE REFERENCE POINTS



 Cross the reference points manually in the displayed sequence: For each axis press the machine START button, or



 Cross the reference points in any sequence: Press and hold the machine axis direction button for each axis until the reference point has been traversed



If your machine is equipped with absolute encoders, you can leave out crossing the reference marks. In such a case, the TNC is ready for operation immediately after the machine control voltage is switched on.

The TNC is now ready for operation in the Manual Operation mode.



The reference points need only be crossed if the machine axes are to be moved. If you intend only to edit or test programs, you can select the Programming and Editing or Test Run modes of operation immediately after switching on the control voltage.

You can cross the reference points later. by pressing the PASS OVER REFERENCE soft key in the Manual Operation mode.

### Crossing the reference point in a tilted working plane

#### Danger of collision!

Make sure that the angle values entered in the menu for tilting the working plane match the actual angles of the tilted axis.

Deactivate the "Tilt Working Plane" function before you cross the reference points. Take care that there is no collision. Retract the tool from the current position first, if necessary.

The TNC automatically activates the tilted working plane if this function was enabled when the control was switched off. Then the TNC moves the axes in the tilted coordinate system when an axis-direction key is pressed. Position the tool in such a way that a collision is excluded during the subsequent crossing of the reference points. To cross the reference points you have to deactivate the "Tilt Working Plane" function, See "To activate manual tilting:", page 543.



If you use this function, then for non-absolute encoders you must confirm the positions of the rotary axes, which the TNC displays in a pop-up window. The position displayed is the last active position of the rotary axes before switch-off.

If one of the two functions that were active before is active now, the NC START button has no function. The TNC outputs a corresponding error message.

15.1 Switch-on, switch-off

# Switch-off

To prevent data from being lost at switch-off, you need to shut down the operating system of the TNC as follows:

Select the Manual Operation mode



- Select the function for shutting down, confirm again with the YES soft key
- When the TNC displays the message NOW IT IS SAFE TO TURN POWER OFF in a pop-up window, you may cut off the power supply to the TNC



#### Caution: Data may be lost!

Inappropriate switch-off of the TNC can lead to data loss!

Remember that pressing the END key after the control has been shut down restarts the control. Switch-off during a restart can also result in data loss!

# 15.2 Moving the machine axes

# Note



Traversing with the machine axis direction buttons can vary depending on the machine tool. Refer to your machine manual.

# Moving the axis with the machine axis direction buttons



- Select the Manual Operation mode
- Press the machine axis direction button and hold it as long as you wish the axis to move, or
- Move the axis continuously: Press and hold the machine axis direction button, then press the machine START button
- ► To stop the axis, press the machine STOP button.

You can move several axes at a time with these two methods. You can change the feed rate at which the axes are traversed with the F soft key, See "Spindle speed S, feed rate F and miscellaneous function M", page 500.

# Incremental jog positioning

With incremental jog positioning you can move a machine axis by a preset distance.



 Select the Manual Operation or El. Handwheel mode

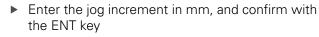


- Shift the soft-key row
- INCRE-MENT OFF ON

ENT

 Select incremental jog positioning: Switch the INCREMENT soft key to ON

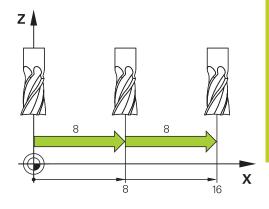
### JOG INCREMENT =



 Press the machine axis direction button as often as desired



The maximum permissible value for infeed is 10 mm.



**15.2 Moving the machine axes** 

# Traverse with electronic handwheels

The TNC supports traversing with the following new electronic handwheels:

- HR 520: Handwheel compatible for connection to HR 420 with display, data transfer per cable
- HR 550 FS: Handwheel with display, radio data transmission

In addition to this, the TNC continues to support the cable handwheels HR 410 (without display) and HR 420 (with display).



Caution: Danger to the operator and handwheel!

All of the handwheel connectors may only be removed by authorized service personnel, even if it is possible without any tools!

Ensure that the handwheel is plugged in before you switch on the machine!

If you wish to operate your machine without the handwheel, disconnect the cable from the machine and secure the open socket with a cap!



Your machine tool builder can make additional functions of the HR 5xx available. Refer to your machine manual.



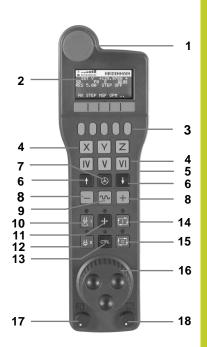
A HR 5xx handwheel is recommended if you want to use the handwheel superimposition in virtual axis function See "Virtual tool axis VT".

The portable HR 5xx handwheels feature a display on which the TNC shows information. In addition, you can use the handwheel soft keys for important setup functions, e.g. datum setting or entering and running M functions.

As soon as you have activated the handwheel with the handwheel activation key, the operating panel is locked. This is indicated by a pop-up window on the TNC screen.



- 1 EMERGENCY STOP button
- **2** Handwheel display for status display and function selection, for further information,
- 3 Soft keys
- **4** Axis selection keys; can be exchanged by the machine manufacturer depending on the axis configuration
- **5** Permissive key
- 6 Arrow keys for defining handwheel sensitivity
- 7 Handwheel activation key
- 8 Key for TNC traverse direction of the selected axis
- **9** Rapid traverse superimposition for direction key
- **10** Spindle switch-on (machine-dependent function, key can be exchanged by the machine manufacturer)
- **11** "Generate NC block" key (machine-dependent function, key can be exchanged by the machine manufacturer)
- **12** Spindle switch-off (machine-dependent function, key can be exchanged by the machine manufacturer)
- **13** CTRL key for special functions (machine-dependent function, key can be exchanged by the machine manufacturer)
- **14** NC start (machine-dependent function, key can be exchanged by the machine manufacturer)
- **15** NC stop (machine-dependent function, key can be exchanged by the machine manufacturer)
- 16 Handwheel
- 17 Spindle speed potentiometer
- **18** Feed rate potentiometer
- **19** Cable connection, not available with the HR 550 FS wireless handwheel



15.2 Moving the machine axes

#### Handwheel display

- **1 Only with wireless handwheel HR 550 FS**: Shows whether the handwheel is in the docking station or whether wireless operation is active
- 2 Only with wireless handwheel HR 550 FS: Shows the field strength, 6 bars = maximum field strength
- **3 Only with wireless handwheel HR 550 FS:** Shows the charge status of the rechargeable battery, 6 bars = fully charged A bar moves from the left to the right during recharging
- **4 ACTL**: Type of position display
- 5 Y+129.9788: Position of the selected axis
- 6 \*: STIB (control in operation); program run has been started or axis is in motion
- 7 SO:: Current spindle speed
- 8 F0: Feed rate at which the selected axis is moving
- 9 E: Error message
- 10 3D: Tilted-working-plane function is active
- **11 2D**: Basic rotation function is active
- **12 RES 5.0:** Active handwheel resolution. Distance in mm/rev (°/rev for rotary axes) that the selected axis moves for one handwheel revolution
- **13 STEP ON** or **OFF:** Incremental jog active or inactive. If the function is active, the TNC also displays the active jog increment
- **14** Soft-key row: Selection of various functions, described in the following sections



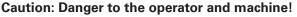
#### Special features of the HR 550 FS wireless handwheel

Due to various potential sources of interference, a wireless connection is not as reliable as a cable connection. Before you use the wireless handwheel it must therefore be checked whether there are any other radio users in the surroundings of the machine. This inspection for presence of radio frequencies or channels is recommended for all industrial radio systems.

When the HR550 is not needed, always put it in the handwheel holder. This way you can ensure that the handwheel batteries are always ready for use thanks to the contact strip on the rear side of the wireless handwheel and the recharge control, and that there is a direct contact connection for the emergency stop circuit.

If an error (interruption of the radio connection, poor reception quality, defective handwheel component) occurs, the handwheel always reacts with an emergency stop.

Please read the notes on the configuration of the HR 550 FS wireless handwheel See "Configure HR 550 FS wireless handwheel"



Due to safety reasons you must switch off the wireless handwheel and the handwheel holder after an operating time of 120 hours at the latest so that the TNC can run a functional test when it is restarted!

If you use several machines with wireless handwheels in your workshop you have to mark the handwheels and holders that belong together so that their respective associations are clearly identifiable (e.g. by color stickers or numbers). The markings on the wireless handwheel and the handwheel holder must be clearly visible to the user!

Before every use, make sure that the correct handwheel for your machine is active.



# 15.2 Moving the machine axes

The HR 550 FS wireless handwheel features a rechargeable battery. The battery is recharged when you put the handwheel in the holder (see figure).

You can operate the HR 550 FS with the accumulator for up to 8 hours before it must be recharged again. It is recommended, however, that you always put the handwheel in its holder when you are not using it.

As soon as the handwheel is in its holder, it switches internally to cable operation. In this way you can use the handwheel even if it were completely discharged. The functions are the same as with wireless operation.



When the handwheel is completely discharged, it takes about 3 hours until it is fully recharged in the handwheel holder.

Clean the contacts **1** in the handwheel holder and of the handwheel regularly to ensure their proper functioning.

The transmission range is amply dimensioned. If you should nevertheless happen to come near the edge of the transmission area, which is possible with very large machines, the HR 550 FS warns you in time with a plainly noticeable vibration alarm. If this happens you must reduce the distance to the handwheel holder, into which the radio receiver is integrated.



### Caution: Danger to the workpiece and tool!

If interruption-free operation is no longer possible within the transmission range the TNC automatically triggers an emergency stop. This can also happen during machining. Try to stay as close as possible to the handwheel holder and put the handwheel in its holder when you are not using it.



If the TNC has triggered an emergency stop you must reactivate the handwheel. Proceed as follows:

- Select the Programming and Editing mode of operation
- Press the MOD key to select the MOD function
- Scroll through the soft-key row



- Select the configuration menu for the wireless handwheel: Press the SET UP WIRELESS HANDWHEEL soft key
  - Click the Start handwheel button to reactivate the wireless handwheel
  - To save the configuration and exit the configuration menu, press the END button

The MOD mode of operation includes a function for initial operation and configuration of the handwheel See "Configure HR 550 FS wireless handwheel", page 602.

#### Selecting the axis to be moved

You can activate directly through the axis address keys the principal axes X, Y, Z and three other axes defined by the machine tool builder. Your machine tool builder can also place the virtual axis VT directly on one of the free axis keys. If the virtual axis VT is not on one of the axis selection keys, proceed as follows:

- Press the handwheel soft key F1 (AX): The TNC displays all active axes on the handwheel display. The currently active axis blinks
- Select the desired axis with the handwheel soft keys F1 (->) or F2 (<-) and confirm with the handwheel soft key F3 (OK)</li>

#### Setting the handwheel sensitivity

The handwheel sensitivity specifies the distance an axis moves per handwheel revolution. The sensitivity levels are pre-defined and are selectable with the handwheel arrow keys (only when incremental jog is not active).

Selectable sensitivity levels: 0.01/0.02/0.05/0.1/0.2/0.5/1/2/5/10/20 [mm/revolution or degrees/revolution]

15.2 Moving the machine axes

# Moving the axes



Χ

- Activate the handwheel: Press the handwheel key on the HR 5xx: Now you can only operate the TNC via the HR 5xx; the TNC shows a pop-up window containing information on the TNC screen
  - Select the desired operating mode via the OPM soft key if necessary
  - If required, press and hold the permissive button
- Use the handwheel to select the axis to be moved. Select the additional axes via soft key, if required
- Move the active axis in the positive direction, or
- Move the active axis in the negative direction
- Deactivate the handwheel: Press the handwheel key on the HR 5xx : Now you can operate the TNC again via the operating panel

### **Potentiometer settings**

The potentiometers of the machine operating panel continue to be active after you have activated the handwheel. If you want to use the potentiometers on the handwheel, proceed as follows:

- Press the CTRL and Handwheel keys on the HR 5xx. The TNC shows the soft-key menu for selecting the potentiometers on the handwheel display
- Press the HW soft key to activate the handwheel potentiometers

If you have activated the potentiometers on the handwheel, you must reactivate the potentiometers of the machine operating panel before deselecting the handwheel. Proceed as follows:

- Press the CTRL and Handwheel keys on the HR 5xx. The TNC shows the soft-key menu for selecting the potentiometers on the handwheel display
- Press the KBD soft key to activate the potentiometers of the machine operating panel



#### Incremental jog positioning

With incremental jog positioning the TNC moves the currently active handwheel axis by a preset distance defined by you:

- Press the handwheel soft key F2 (STEP)
- Activate incremental jog positioning: Press handwheel soft key 3 (ON)
- Select the desired jog increment by pressing the F1 or F2 key. If you press and hold the respective key, each time it reaches a decimal value 0 the TNC increases the counting increment by a factor of 10. If in addition you press the CTRL key, the counting increment increases to 1. The smallest possible jog increment is 0.0001 mm. The largest possible is 10 mm
- Confirm the selected jog increment with soft key 4 (OK)
- With the + or handwheel key, move the active handwheel axis in the corresponding direction

#### **Entering miscellaneous functions M**

- Press the handwheel soft key F3 (MSF)
- Press the handwheel soft key F1 (M)
- Select the desired M function number by pressing the F1 or F2 key
- Execute the M function with the NC start key

#### Entering the spindle speed S

- Press the handwheel soft key F3 (MSF)
- Press the handwheel soft key F2 (S)
- Select the desired speed by pressing the F1 or F2 key. If you press and hold the respective key, each time it reaches a decimal value 0 the TNC increases the counting increment by a factor of 10. If in addition you press the CTRL key, the counting increment increases to 1000
- Activate the new speed S with the NC start key

15.2 Moving the machine axes

#### Entering the feed rate F

- Press the handwheel soft key F3 (MSF)
- ▶ Press the handwheel soft key F3 (F)
- Select the desired feed rate by pressing the F1 or F2 key. If you press and hold the respective key, each time it reaches a decimal value 0 the TNC increases the counting increment by a factor of 10. If in addition you press the CTRL key, the counting increment increases to 1000
- Confirm the new feed rate F with the handwheel soft key F3 (OK)

#### **Datum setting**

- Press the handwheel soft key F3 (MSF)
- Press the handwheel soft key F4 (PRS)
- If required, select the axis in which the datum is to be set.
- Reset the axis with the handwheel soft key F3 (OK), or with F1 and F2 set the desired value and then confirm with F3 (OK) By also pressing the CTRL key, you can increase the counting increment to 10

#### **Changing modes of operation**

With the handwheel soft key F4 (**OPM**), you can use the handwheel to switch the mode of operation, provided that the current status of the control allows a mode change.

- Press the handwheel soft key F4 (OPM)
- Select the desired operating mode by handwheel soft key
  - MAN: Manual Operation MDI: Positioning with manual data input SGL: Program run, single block RUN: Program run, full sequence

#### Generating a complete L Block



Your machine tool builder can assign any function to the "Generate NC block" handwheel key. Refer to your machine manual.

- Select the Positioning with MDI operating mode
- If required, use the arrow keys on the TNC keyboard to select the NC block after which the new L block is to be inserted
- Activate the handwheel
- Press the "Generate NC block" handwheel key: The TNC inserts a complete L block containing all axis positions selected through the MOD function

### Features in the program run modes of operation

You can use the following functions in the Program Run modes of operation:

- NC start (handwheel NC-start key)
- NC stop (handwheel NC-stop key)
- After the NC-stop key has been pressed: Internal stop (handwheel soft keys MOP and then STOP)
- After the NC-stop key has been pressed: Manual axis traverse (handwheel soft keys MOP and then MAN)
- Returning to the contour after the axes were moved manually during a program interruption (handwheel soft keys MOP and then REPO). Operation is by handwheel soft keys, which function similarly to the control-screen soft keys, See "Returning to the contour", page 577
- On/off switch for the Tilted Working Plane function (handwheel soft keys MOP and then 3D)

15.3 Spindle speed S, feed rate F and miscellaneous function M

# 15.3 Spindle speed S, feed rate F and miscellaneous function M

# Application

In the Manual Operation and El. Handwheel operating modes, you can enter the spindle speed S, feed rate F and the miscellaneous functions M with soft keys. The miscellaneous functions are described in Chapter 7 "Programming: Miscellaneous functions."



The machine tool builder determines which miscellaneous functions M are available on your control and what effects they have.

# **Entering values**

### Spindle speed S, miscellaneous function M

S

• Enter the spindle speed: Press the S soft key

### SPINDLE SPEED S=



Enter 1000 (spindle speed) and confirm your entry with the machine START button.

The spindle speed S with the entered rpm is started with a miscellaneous function M. Proceed in the same way to enter a miscellaneous function M.

### Feed rate F

After entering a feed rate F, you must confirm your entry with the ENT key instead of the machine START button.

The following is valid for feed rate F:

- If you enter F=0, then the lowest feed rate from the machine parameter manualFeed is effective.
- If the feed rate entered exceeds the value defined in the machine parameter **maxFeed**, then the parameter value is effective.
- F is not lost during a power interruption

# Adjusting spindle speed and feed rate

With the override knobs you can vary the spindle speed S and feed rate F from 0% to 150% of the set value.



The override knob for spindle speed is only functional on machines with infinitely variable spindle drive.



# Activating feed-rate limitation



The feed-rate limit depends on the machine. Refer to your machine manual.

When the F LIMITED soft key is set to ON, the TNC limits the maximum permissible axis speed to the safely limited speed specified by the machine manufacturer.



- Select the Manual Operation mode



Switch on/off feed rate limit

Scroll to the last soft-key row

15.4 Functional safety FS (option)

# 15.4 Functional safety FS (option)

# Miscellaneous

Every machine tool operator is exposed to certain risks. Although protective devices can prevent access to dangerous points, the operator must also be able to work on the machine without this protection (e.g. protective door opened). Several guidelines and regulations to minimize these risks have been developed within the last few years.

The HEIDENHAIN safety concept integrated in the TNC controls complies with **Performance Level d** as per EN 13849-1 and SIL 2 as per IEC 61508, features safety-related modes of operation in accordance with EN 12417, and assures extensive operator protection.

The basis of the HEIDENHAIN safety concept is the dual-channel processor structure, which consists of the main computer (MC) and one or more drive controller modules (CC= control computing unit). All monitoring mechanisms are designed redundantly in the control systems. Safety-relevant system data are subject to a mutual cyclic data comparison. Safety-relevant errors always lead to safe stopping of all drives through defined stop reactions.

Defined safety functions are triggered and safe operating statuses are achieved via safety-relevant inputs and outputs (dual-channel implementation), which have an influence on the system in all operating modes.

In this chapter you will find explanations of the functions that are additionally available on a TNC with functional safety.



You machine tool builder adapts the HEIDENHAIN safety concept to your machine. Refer to your machine manual.

15

# **Explanation of terms**

### Safety-related operating modes

Description	Brief description	
SOM_1	Safe operating mode 1: automatic operation, production mode	
SOM_2	Safe operating mode 2: set-up mode	
SOM_3	Safe operating mode 3: manual intervention; only for qualified operators	
SOM_4	Safe operating mode 4: Advanced manual intervention, process monitoring	

### **Safety functions**

Description	Brief description
SSO, SS1, SS1F, SS2	Safe stop: safe stopping of all drives using different methods
STO	Safe torque off: energy supply to the motor is interrupted. Provides protection against unexpected start of the drives
SOS	Safe operating stop. Provides protection against unexpected start of the drives
SLS	Safely-limited speed. Prevents the drives from exceeding the specified speed limits when the protective door is opened

15.4 Functional safety FS (option)

# Checking the axis positions



This function must be adapted to the TNC by your machine manufacturer. Refer to your machine manual.

After switch-on the TNC checks whether the position of an axis matches the position directly after switch-off. If a deviation occurs this axis is displayed red in the position display. Axes that are marked red can no longer be moved while the door is opened.

In such cases you must approach a test position for the axes in question. Proceed as follows:

- Select the Manual Operation mode
- Execute the approach with NC Start to move the axes in the sequence shown
- When the test position has been reached, the TNC asks whether the position was approached correctly: Confirm with the YES soft key if the TNC approached the test position correctly, and with NO if the position was not approached correctly
- If you confirmed with YES, you must confirm the correctness of the test position again with the permissive button on the machine operating panel
- Repeat this procedure for all axes that you want to move to the test position

#### Danger of collision!

Approach the test positions in such a way that no collision between tool and the workpiece or the clamping devices can occur. If necessary, preposition the axes manually.



The location of the test position is specified by your machine tool builder. Refer to your machine manual.

15

#### Overview of permitted feed rates and speeds

The TNC provides an overview of the permitted speeds and feed rates for all axes depending on the active mode of operation.

Select the Manual Operation mode

$\bigcirc$	
$\triangleleft$	

INFO ON SOM Scroll to the last soft-key row

 Press the INFO SOM soft key: The TNC opens the window containing the overview of permitted speeds and feed rates

Column	Meaning
SLS2	Safely limited speeds in the safety- related operating mode 2 ( <b>SOM_2</b> ) for the respective axes
SLS3	Safely limited speeds in the safety- related operating mode 3 ( <b>SOM_3</b> ) for the respective axes
SLS4	Safely limited speeds in the safety- related operating mode 4 ( <b>SOM_4</b> ) for the respective axes

#### Activating feed-rate limitation

When the F LIMITED soft key is set to ON, the TNC limits the maximum permissible axis speeds to the specified, safely limited speed. The valid speeds for the active mode of operation are shown in the **Safety-MP** table, See "Overview of permitted feed rates and speeds", page 505.



 $\triangleleft$ 

Select the Manual Operation mode

Scroll to the last soft-key row



Switch on/off feed rate limit

15.4 Functional safety FS (option)

#### Additional status displays

On a control with functional safety FS, the general status display contains additional information about the current status of safety functions. The TNC shows this information as operating statuses of the status displays **T**, **S** and **F** 

Status display	Brief description
STO	Energy supply to the spindle or a feed drive is interrupted.
SLS	Safely-limited speed: A safely limited speed is active.
SOS	Safe operating stop: Safe operating stop is active.
STO	Safe torque off: Energy supply to the motor is interrupted.

The TNC shows the active safety-related mode of operation with an icon in the header to the right of the operating mode text. If the **SOM\_1** mode is active, the TNC does not display any icon.

Button	Safety-related operating mode
SOM 2	SOM_2 mode active
SOM	SOM_3 mode active
SOM	SOM_4 mode active

15

# 15.5 Datum setting without a 3-D touch probe

#### Note



Setting the datum with a 3-D touch probe: See "Datum Setting with 3-D Touch Probe (Touch Probe Function Software Option)".

You fix a datum by setting the TNC position display to the coordinates of a known position on the workpiece.

#### Preparation

- Clamp and align the workpiece
- Insert the zero tool with known radius into the spindle
- Ensure that the TNC is showing the actual position values

#### Workpiece presetting with axis keys



If the workpiece surface must not be scratched, you can lay a metal shim of known thickness d on it. Then enter a tool axis datum value that is larger than the desired datum by the value d.



Select the MANUAL OPERATION mode

 Move the tool slowly until it touches (scratches) the workpiece surface

Select the axis

#### DATUM SETTING Z=



Ζ

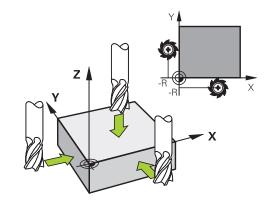
Zero tool in spindle axis: Set the display to a known workpiece position (here, 0) or enter the thickness d of the shim. In the tool axis, offset the tool radius

Repeat the process for the remaining axes.

If you are using a preset tool, set the display of the tool axis to the length L of the tool or enter the sum Z=L+d



The TNC automatically saves the datum set with the axis keys in line 0 of the preset table.



#### 15.5 Datum setting without a 3-D touch probe

#### Datum management with the preset table

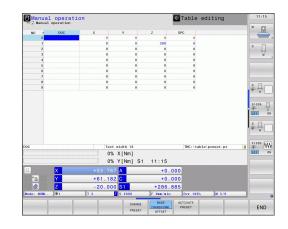
_	7

You should definitely use the preset table if:

- Your machine is equipped with rotary axes (tilting table or swivel head) and you work with the function for tilting the working plane
- Your machine is equipped with a spindle-head changing system
- Up to now you have been working with older TNC controls with REF-based datum tables
- You wish to machine identical workpieces that are differently aligned

The preset table can contain any number of lines (datums). To optimize the file size and the processing speed, you should use only as many lines as you need for datum management.

For safety reasons, new lines can be inserted only at the end of the preset table.



#### Saving the datums in the preset table

The preset table has the name **PRESET.PR**, and is saved in the directory **TNC:\table**. **PRESET.PR** is editable in the **Manual Operation** and **EI. Handwheel** modes only if the **CHANGE PRESET** soft key was pressed.

It is permitted to copy the preset table into another directory (for data backup). Lines that were written by your machine tool builder are also always write-protected in the copied tables. You therefore cannot edit them.

Never change the number of lines in the copied tables! That could cause problems when you want to reactivate the table.

To activate the preset table copied to another directory you have to copy it back to the directory **TNC:**\table\.

There are several methods for saving datums and/or basic rotations in the preset table:

- Through probing cycles in the Manual Operation or El. Handwheel modes (see Chapter 14)
- Through the probing cycles 400 to 402 and 410 to 419 in automatic mode (see User's Manual, Cycles, Chapters 14 and 15)
- Manual entry (see description below)



Basic rotations from the preset table rotate the coordinate system about the preset, which is shown in the same line as the basic rotation.

Remember to ensure that the position of the tilting axes matches the corresponding values of the 3-D ROT menu when setting the datum. Therefore:

- If the "Tilt working plane" function is not active, the position display for the rotary axes must be = 0° (zero the rotary axes if necessary).
- If the "Tilt working plane" function is active, the position displays for the rotary axes must match the angles entered in the 3-D ROT menu.

The line 0 in the preset table is write protected. In line 0, the TNC always saves the datum that you most recently set manually via the axis keys or via soft key. If the datum set manually is active, the TNC displays the text **PR MAN(0)** in the status display.

## 15.5 Datum setting without a 3-D touch probe

#### Manually saving the datums in the preset table

In order to set datums in the preset table, proceed as follows:

in order to s	et datums in the preset table, pro	ceed as follows:
	Select the MANUAL OPERATI	ON mode
X Y Z	<ul> <li>Move the tool slowly until it t the workpiece surface, or posi dial correspondingly</li> </ul>	
PRESET TABLE	<ul> <li>Display the preset table: The preset table and sets the currow</li> </ul>	
CHANGE PRESET	<ul> <li>Select functions for entering displays the available possibil soft-key row. See the table be of the entry possibilities</li> </ul>	ities for entry in the
+	<ul> <li>Select the line in the preset t change (the line number is th</li> </ul>	
-	<ul> <li>If needed, select the column table that you want to change</li> </ul>	•
CORRECT THE PRESET	<ul> <li>Use the soft keys to select or entry possibilities (see the for</li> </ul>	
Function		Soft key
tool (the me This functio	asfer the actual position of the pasuring dial) as the new datum: n only saves the datum in the axis rently highlighted	
tool (the me saves the d	value to the actual position of the easuring dial): This function only atum in the axis which is currently Enter the desired value in the po	
the table: The in the axis v the desired sign in the p	ly shift a datum already stored in his function only saves the datum which is currently highlighted. Ente corrective value with the correct pop-up window. If inch display is r the value in inches, and the TNC	

will internally convert the entered values to

mm

Function	Soft key
Directly enter the new datum without calculation of the kinematics (axis-specific). Only use this function if your machine has a rotary table, and you want to set the datum to the center of the rotary table by entering 0. This function only saves the datum in the axis which is currently highlighted. Enter the desired value in the pop-up window. If inch display is active: Enter the value in inches, and the TNC will internally convert the entered values to mm	EDIT CURRENT FIELD
Select the BASIC TRANSFORMATION/AXIS OFFSET view. The BASIC TRANSFORMATION view shows the X, Y and Z columns. Depending on the machine, the SPA, SPB and SPC columns are displayed additionally. Here, the TNC saves the basic rotation (for the Z tool axis, the TNC uses the SPC column). The OFFSET view shows the offset values for the preset	BASE TRANSFORM. OFFSET
Write the currently active datum to a selectable line in the table: This function saves the datum in all axes, and then activates the appropriate row in the table automatically. If inch display is active: Enter the value in inches, and the TNC will internally convert the entered values to mm	SAVE PRESET

**15.5** Datum setting without a 3-D touch probe

#### Editing the preset table

Editing function in table mode	Soft key
Select beginning of table	BEGIN
Select end of table	
Select previous page in table	
Select next page in table	
Select the functions for preset entry	CHANGE PRESET
Display the "Basic Transformation/Axis Offset" selection	BASE TRANSFORM. OFFSET
Activate the datum of the selected line of the preset table	ACTIVATE PRESET
Add the entered number of lines to the end of the table (2nd soft-key row)	APPEND N LINES
Copy the highlighted field (2nd soft-key row)	COPY FIELD
Insert the copied field (2nd soft-key row)	PASTE
Reset the selected line: The TNC enters - in all columns (2nd soft-key row)	RESET
Insert a single line at the end of the table (2nd soft-key row)	INSERT LINE
Delete a single line at the end of the table (2nd soft-key row)	DELETE

## Activating a datum from the preset table in the Manual Operation mode

⇒	When activating a datum from the preset table, the TNC resets the active datum shift, mirroring, rotation and scaling factor. However, a coordinate transformation that was programmed in Cycle 19 Tilted Working Plane, or through the PLANE function, remains active.
	Select the MANUAL OPERATION mode
PRESET TABLE	<ul> <li>Display the preset table</li> </ul>
t	<ul> <li>Select the datum number you want to activate, or</li> </ul>
сото □ 4	With the GOTO key, select the datum number that you want to activate. Confirm with the ENT key
ENT	
ACTIVATE PRESET	<ul> <li>Activate the datum</li> </ul>
EXECUTE	<ul> <li>Confirm activation of the datum. The TNC sets the display and—if defined—the basic rotation</li> </ul>
	<ul> <li>Exit the preset table</li> </ul>

#### Activating a datum from the preset table in an NC program

To activate datums from the preset table during program run, use Cycle 247. In Cycle 247 you define the number of the datum that you want to activate (see User's Manual, Cycles, Cycle 247 SET DATUM). 15

15.6 Using 3-D touch probes

## 15.6 Using 3-D touch probes

#### **Overview**

The following touch probe cycles are available in the Manual Operation mode:



HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.



The TNC must be specially prepared by the machine tool builder for the use of a 3-D touch probe. Refer to your machine manual.

Function	Soft key	Page
Calibrating the effective length	CAL L	523
Calibrating the effective radius	CAL R	524
Measuring a basic rotation using a line	PROBING	528
Setting a datum in any axis	PROBING POS	530
Setting a corner as datum	PROBING P	531
Setting a circle center as datum	PROBING CC	533
Setting the centerline as datum	PROBING	535
Touch probe system data management	TASTSYST. TABLE	See User's Manual for Cycles

You can also use all manual touch probe cycles, except the corner probing cycle, in Turning mode. Observe that in Turning mode all measured data in the X coordinate are calculated and displayed as diameter values.

To use the touch probe in Turning mode you should separately calibrate the touch probe in Turning mode. Because the basic setting of the turning spindle in Milling mode and Turning mode may deviate, you should calibrate the touch probe without center offset. You can create additional tool data for this purpose, e.g. as an indexed tool.

_	

For more information about the touch probe table, refer to the User's Manual for Cycle Programming.

15.6 Using 3-D touch probes

#### Functions in touch probe cycles

Soft keys that are used to select the probing direction or a probing routine are displayed in the manual touch probe cycles. The soft keys displayed vary depending on the respective cycle:

Soft key	Function
X +	Select the probing direction
	Capture the actual position
	Probe hole (inside circle) automatically
	Probe stud (outside circle) automatically

#### Automatic probing routine for holes and studs

<ul> <li>If you use a function for probing a circle automatically, the TNC automatically positions the touch probe to the respective touch points.</li> <li>Ensure that the positions can be approached without collision.</li> </ul>	ıt
---	----

If you use a probing routine for probing a hole or a stud automatically, the TNC opens a form with the required input fields.

#### Input fields in the Measure stud and Measure hole forms

Input field	Function
Stud diameter? or Hole diameter?	Diameter of probe contact (optional for holes)
Safety clearance?	Distance to the probe contact in the plane
Incr. clearance height?	Positioning of touch probe in spindle axis direction (starting from the current position)
Starting angle?	Angle for the first probing operation ( $0^\circ$ = Positive direction of principal axis, i.e. in X+ for spindle axis Z). All other probe angles result from the number of touch points.
Number of touch points?	Number of probing operations (3 to 8)
Angular length?	Probing a full circle (360°) or a circle segment (angular length<360°)

Position the touch probe approximately in the center of the hole (inside circle) or near the first touch point on the stud (outside circle), and select the soft key for the first probing direction. Once you press the machine START button to start the touch probe cycle, the TNC automatically performs all prepositioning movements and probing operations.

The TNC positions the touch probe to the individual touch points, taking the safety clearance into account. If a clearance height has been defined, the TNC positions the touch probe to clearance height in the spindle axis beforehand.

The TNC approaches the position at the feed rate **FMAX** defined in the touch probe table. The defined probing feed rate **F** is used for the actual probing operation.

Before starting the automatic probing routine, you need to preposition the touch probe near the first touch point. Offset the touch probe by approximately the safety clearance (value from touch probe table + value from input form) opposite to the probing direction.

For an inside circle with a large diameter, the TNC can also preposition the touch probe on a circular arc at the positioning feed rate FMAX. This requires that you enter a safety clearance for prepositioning and the hole diameter in the input form. Position the touch probe inside the hole at a position that is offset by approximately the safety clearance from the wall. For prepositioning, keep in mind the starting angle for the first probing operation (with an angle of 0°, the TNC probes in the positive direction of the principal axis).

15.6 Using 3-D touch probes

#### Selecting touch probe cycles

 Select the Manual Operation or El. Handwheel mode of operation



 Select the touch probe functions by pressing the TOUCH PROBE soft key. The TNC displays additional soft keys (see overview table).



 Select the touch probe cycle by pressing the appropriate soft key, for example PROBING POS, for the TNC to display the associated menu



When you select a manual probing function, the TNC opens a form displaying all data required. The content of the forms varies depending on the respective function.

You can also enter values in some of the fields. Use the arrow keys to move to the desired input field. You can position the cursor only in fields that can be edited. Fields that cannot be edited appear dimmed.

# Recording measured values from the touch-probe cycles



The TNC must be specially prepared by the machine tool builder for use of this function. Refer to your machine manual.

After executing any selected touch probe cycle, the TNC displays the soft key WRITE LOG TO FILE. If you press this soft key, the TNC will record the current values determined in the active touch probe cycle.

If you store the measuring results, the TNC creates the text file TCHPRMAN.TXT. Unless you define a specific path in the machine parameter **fn16DefaultPath**, the TNC will store the TCHPRMAN.TXT file in the main directory **TNC:**\.



When you press the WRITE LOG TO FILE soft key, the TCHPRMAN.TXT file must not be active in the **Programming** mode of operation. The TNC will otherwise display an error message.

The TNC stores the measured data in the TCHPRMAN.TXT file only. If you execute several touch probe cycles in succession and want to store the resulting measured data, you must make a backup of the contents stored in TCHPRMAN.TXT between the individual cycles by copying or renaming the file.

Format and content of the TCHPRMAN.TXT file are preset by the machine tool builder.

15.6 Using 3-D touch probes

## Writing measured values from the touch probe cycles in a datum table



Use this function if you want to save measured values in the workpiece coordinate system. If you want to save measured values in the machine-based coordinate system (REF coordinates), press the ENTER IN PRESET TABLE SOFT KEY, See "Writing measured values from the touch probe cycles in the preset table".

With the ENTER IN DATUM TABLE soft key, the TNC can write the values measured during a touch probe cycle in a datum table:

- Select any probe function
- Enter the desired coordinates of the datum in the appropriate input boxes (depends on the touch probe cycle being run)
- Enter the datum number in the **Number in table=** input box
- Press the ENTER IN DATUM TABLE soft key. The TNC saves the datum in the indicated datum table under the entered number

# Writing measured values from the touch probe cycles in the preset table



Use this function if you want to save measured values in the machine-based coordinate system (REF coordinates). If you want to save measured values in the workpiece coordinate system, use the ENTER IN DATUM TABLE SOFT KEY, See "Writing measured values from the touch probe cycles in a datum table".

With the ENTER IN PRESET TABLE soft key, the TNC can write the values measured during a probe cycle in the preset table. The measured values are then stored referenced to the machine-based coordinate system (REF coordinates). The preset table has the name PRESET.PR, and is saved in the directory TNC:\table\.

- Select any probe function
- Enter the desired coordinates of the datum in the appropriate input boxes (depends on the touch probe cycle being run)
- Enter the preset number in the **Number in table:** input box
- Press the ENTER IN PRESET TABLE soft key. The TNC saves the datum in the preset table under the entered number

15.7 Calibrating a 3-D touch trigger probe

## 15.7 Calibrating a 3-D touch trigger probe

#### Introduction

In order to precisely specify the actual trigger point of a 3-D touch probe, you must calibrate the touch probe, otherwise the TNC cannot provide precise measuring results.



Always calibrate a touch probe in the following cases:

- Commissioning
- Stylus breakage
- Stylus exchange
- Change in the probe feed rate
- Irregularities caused, for example, when the machine heats up
- Change of active tool axis

When you press the OK soft key after calibration, the calibration values are applied to the active touch probe. The updated tool data become effective immediately, and a new tool call is not necessary.

During calibration, the TNC finds the "effective" length of the stylus and the "effective" radius of the ball tip. To calibrate the 3-D touch probe, clamp a ring gauge or a stud of known height and known radius to the machine table.

The TNC provides calibration cycles for calibrating the length and the radius:

Press the TOUCH PROBE soft key

- Display the calibration cycles: Press CALIBRATE TS
- Select the calibration cycle

#### Calibration cycles of the TNC

Soft key	Function	Page
TS KALIBR.	Calibrating the length	523
CAL R	Measure the radius and the center offset using a calibration ring	524
KAL. R	Measure the radius and the center offset using a stud or a calibration pin	524
KAL.	Measure the radius and the center offset using a calibration sphere	524

TS KALIBR.

#### Calibrating the effective length



HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.

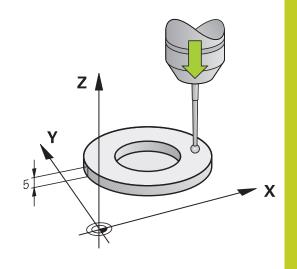


The effective length of the touch probe is always referenced to the tool datum. The machine tool builder usually defines the spindle tip as the tool datum.

 Set the datum in the spindle axis such that for the machine tool table Z=0.



- Select the calibration function for the touch probe length: Press the CAL. L soft key. The TNC opens a menu window with input fields
- Datum for length: Enter the height of the ring gauge
- New cal. spindle angle: Spindle angle that is used for the calibration. The TNC uses CAL\_ANG from the touch probe table as a default value. If you change the value, the TNC saves the value to the touch probe table during calibration
- Move the touch probe to a position just above the ring gauge
- To change the traverse direction (if necessary), press a soft key or an arrow key
- To probe the upper surface of the ring gauge, press the machine START button
- Check the results (change the values if required)
- Press the OK soft key for the values to take effect
- Press the END soft key to terminate the calibrating function



15.7 Calibrating a 3-D touch trigger probe

## Calibrating the effective radius and compensating center misalignment



HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.

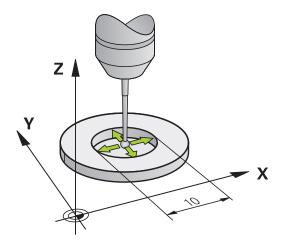
The center offset can be determined only with a suitable touch probe.

If you want to calibrate using the outside of an object, you need to preposition the touch probe above the center of the calibration sphere or calibration pin. Ensure that the touch points can be approached without collision.

When calibrating the ball tip radius, the TNC executes an automatic probing routine. During the first probing cycle, the TNC determines the center of the calibration ring or stud (coarse measurement) and positions the touch probe in the center. Then the ball tip radius is determined during the actual calibration process (fine measurement). If the touch probe allows probing from opposite orientations, the center offset is determined during another cycle.

The characteristic of whether and how your touch probe can be oriented is already defined in HEIDENHAIN touch probes. Other touch probes are configured by the machine tool builder.

After the touch probe is inserted, it normally needs to be aligned exactly with the spindle axis. The calibration function can determine the offset between touch-probe axis and spindle axis by probing from opposite orientations (rotation by 180°) and can compute the compensation.



The calibration routine varies depending on how your touch probe can be oriented:

- No orientation possible or orientation possible in only one direction: The TNC executes one approximate and one fine measurement and determines the effective ball tip radius (column R in tool.t)
- Orientation possible in two directions (e.g. HEIDENHAIN touch probes with cable): The TNC executes one approximate and one fine measurement, rotates the touch probe by 180° and then executes four more probing operations. The center offset (CAL\_OF in tchprobe.tp) is determined in addition to the radius by probing from opposite orientations.
- Any orientation possible (e.g. HEIDENHAIN infrared touch probes): For probing routine, see "orientation possible in two directions."

Proceed as follows for manual calibration using a calibration ring:

 In the Manual Operation mode, position the ball tip inside the bore of the ring gauge

CF	۹L	R
	$\bigcirc$	

- Select the calibration function: Press the CAL. R soft key
- Enter the diameter of the ring gauge
- Enter the safety clearance
- New cal. spindle angle: Spindle angle that is used for the calibration. The TNC uses CAL\_ANG from the touch probe table as a default value. If you change the value, the TNC saves the value to the touch probe table during calibration
- Start the probing procedure: Press the machine START button. The 3-D touch probe probes all required touch points in an automatic probing routine and calculates the effective ball-tip radius. If probing from opposite orientations is possible, the TNC calculates the center offset
- Check the results (change the values if required)
- Press the OK soft key for the values to take effect
- Press the END soft key to terminate the calibrating function



In order to be able to determine the ball-tip center misalignment, the TNC needs to be specially prepared by the machine manufacturer. Refer to your machine manual.

### 15.7 Calibrating a 3-D touch trigger probe

Proceed as follows for manual calibration with a stud or calibration pin:

▶ In the Manual Operation mode, position the ball tip above the center of the calibration pin



- Select the calibration function: Press the CAL. R soft key
- Enter the diameter of the stud
- ► Enter the safety clearance
- New cal. spindle angle: Spindle angle that is used for the calibration. The TNC uses CAL\_ANG from the touch probe table as a default value. If you change the value, the TNC saves the value to the touch probe table during calibration
- Start the probing procedure: Press the machine START button. The 3-D touch probe probes all required touch points in an automatic probing routine and calculates the effective ball-tip radius. If probing from opposite orientations is possible, the TNC calculates the center offset
- Check the results (change the values if required)
- Press the OK soft key for the values to take effect
- Press the END soft key to terminate the calibrating function



In order to be able to determine the ball-tip center misalignment, the TNC needs to be specially prepared by the machine manufacturer.

Refer to your machine manual.

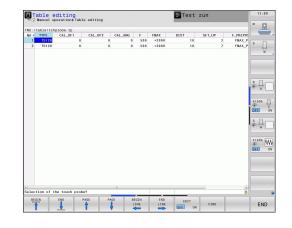
#### **Displaying calibration values**

The TNC saves the effective length and effective radius of the touch probe in the tool table. The TNC saves the ball-tip center offset of the touch probe in the touch-probe table in the CAL\_OF1 (principal axis) and CAL\_OF2 (secondary axis) columns. You can display the values on the screen by pressing the TOUCH PROBE TABLE soft key.



Make sure that you have activated the correct tool number before using the touch probe, regardless of whether you wish to run the touch probe cycle in automatic mode or manual mode.

For more information about the touch probe table, refer to the User's Manual for Cycle Programming.



## 15.8 Compensating workpiece misalignment with 3-D touch probe

#### Introduction



HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.

The TNC electronically compensates workpiece misalignment by computing a "basic rotation."

For this purpose, the TNC sets the rotation angle to the desired angle with respect to the reference axis in the working plane. See figure at right.

The TNC saves the basic rotation, depending on the tool axis, in the columns SPA, SPB or SPC of the preset table.

To identify the basic rotation, probe two points on the side of the workpiece. The sequence of probing the points is not important. You can also identify the basic rotation by holes or studs.

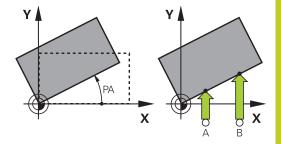


Select the probe direction perpendicular to the angle reference axis when measuring workpiece misalignment.

To ensure that the basic rotation is calculated correctly during program run, program both coordinates of the working plane in the first positioning block.

You can also use a basic rotation in conjunction with the PLANE function. In this case, first activate the basic rotation and then the PLANE function.

You can also activate a basic rotation without probing a workpiece. For this purpose enter a value in the basic rotation menu and press the SET BASIC ROTATION soft key.



### **15.8 Compensating workpiece misalignment with 3-D touch probe**

#### Identifying basic rotation



- Select the probe function by pressing the PROBING ROT soft key
- Position the touch probe at a position near the first touch point
- Select the probe direction perpendicular to the angle reference axis: Select the axis by soft key
- Start the probing procedure: Press the machine START button
- Position the touch probe at a position near the second touch point
- To probe the workpiece, press the machine START button. The TNC determines the basic rotation and displays the angle after the dialog **Rotation angle**
- Activate basic rotation: Press the SET BASIC ROTATION soft key
- Terminate the probe function by pressing the END soft key

#### Saving a basic rotation in the preset table

- After the probing process, enter the preset number in which the TNC is to save the active basic rotation in the Number in table: input box
- Press the BASIC ROT. IN PRESETTAB. soft key to save the basic rotation in the preset table

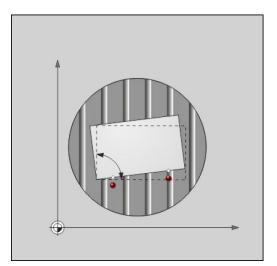
## Compensation of workpiece misalignment by rotating the table

To compensate the identified misalignment by a rotary table position, press the ALIGN ROTARY TABLE soft key after the probing process



Position all axes to avoid a collision before table rotation. The TNC outputs an additional warning before table rotation.

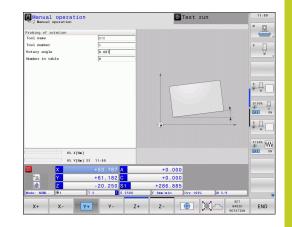
- If you want to set the datum in the rotary table axis, press the SET TABLE ROTATION soft key.
- ➤ You can also save the misalignment of the rotary table in any line of the Preset table. Enter the line number and press the TABLEROT IN PRESETTAB. soft key. The TNC saves the angle in the offset column of the rotary table, e.g. in the C\_OFFS column with a C axis. If necessary, the view in the Preset table has to be changed with the BASIS-TRANSFORM./OFFSET soft key to display this column.



#### Displaying a basic rotation

When you select the PROBING ROT function, the TNC displays the active angle of basic rotation in the dialog **Rotation angle**. The TNC also displays the rotation angle in the additional status display (STATUS POS.).

In the status display a symbol is shown for a basic rotation whenever the TNC is moving the axes according to a basic rotation.



#### **Canceling a basic rotation**

- Select the probe function by pressing the PROBING ROT soft key
- Enter a rotation angle of zero and confirm with the SET BASIC ROTATION soft key
- ▶ Terminate the probe function by pressing the END soft key

15.9 Datum Setting with 3-D Touch Probe

## 15.9 Datum Setting with 3-D Touch Probe

#### **Overview**

The following soft-key functions are available for setting the datum on an aligned workpiece:

Soft key	Function	Page
PROBING POS	Datum setting in any axis with	530
PROBING P	Setting a corner as datum	531
PROBING CC	Setting a circle center as datum	533
PROBING	Center line as datum	533

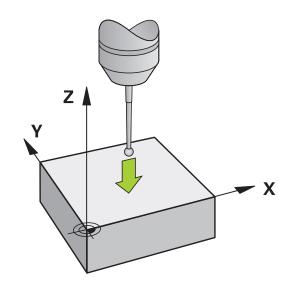
#### Datum setting in any axis



- Select the probing function: Press the PROBING POS soft key
- Move the touch probe to a position near the touch point
- Use the soft keys to select the probe axis and direction in which you want to set the datum, such as Z in direction Z-
- Start the probing procedure: Press the machine START button
- Datum: Enter the nominal coordinate and confirm your entry with the SET DATUM soft key, See "Writing measured values from the touch probe cycles in a datum table", page 520
- To terminate the probe function, press the END soft key



HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.



#### **Corner as datum**

F	ROBING
Р	•

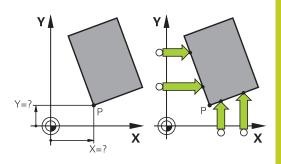
- Select the touch probe function: Press the PROBING P soft key
- Position the touch probe near the first touch point on the first workpiece edge
- Select the probe direction by soft key
- Start the probing procedure: Press the machine START button
- Position the touch probe near the second touch point on the same workpiece edge
- Start the probing procedure: Press the machine START button
- Position the touch probe near the first touch point on the second workpiece edge
- Select the probe direction by soft key
- Start the probing procedure: Press the machine START button
- Position the touch probe near the second touch point on the same workpiece edge
- Start the probing procedure: Press the machine START button
- Datum: Enter both datum coordinates into the menu window, and confirm your entry with the SET DATUM soft key, or See "Writing measured values from the touch probe cycles in the preset table", page 521
- To terminate the probe function, press the END soft key



HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.



You can identify the intersection of two straight lines by holes or studs and set this as the datum. For each straight line however, probing must only be with two identical touch probe functions (e.g. two holes).



### 15.9 Datum Setting with 3-D Touch Probe

The "Corner as datum" probing cycle identifies the angle and intersection of two straight lines. In addition to datum setting, the cycle can also activate a basic rotation. The TNC has two soft keys for you to decide which straight line you wish to use for this. The soft key ROT 1 activates the angle of the first straight line as basic rotation and the soft key ROT 2 the angle of the second straight line.

If you wish to activate the basic rotation in the cycle, you must always do this before datum setting. After you set a datum or write to a zero point or preset table the ROT 1 and ROT 2 soft keys are no longer displayed.

#### Circle center as datum

With this function, you can set the datum at the center of bore holes, circular pockets, cylinders, studs, circular islands, etc.

#### Inside circle:

The TNC probes the inside wall of a circle in all four coordinate axis directions.

For incomplete circles (circular arcs) you can choose the appropriate probing direction.

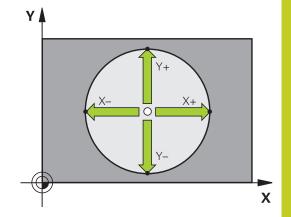
Position the touch probe approximately in the center of the circle



 Select the touch probe function: Press the PROBING CC soft key

- Select the probing direction or press the soft key for the automatic probing routine
- ► To probe the workpiece, press the machine START button. The touch probe probes the inside wall of the circle in the selected direction. If you are not using the automatic probing routine, you need to repeat this procedure. After the third probing operation, you can have the TNC calculate the center (four touch points are recommended).
- Terminate the probing procedure and switch to the evaluation menu: Press the EVALUATE soft key
- Datum: In the menu window, enter both coordinates of the circle center, confirm with the SET DATUM soft key, or write the values to a table (See "Writing measured values from the touch probe cycles in a datum table", page 520, or See "Writing measured values from the touch probe cycles in the preset table", page 521)
- Terminate the probing function: Press the END soft key

The TNC needs only three touch points to calculate outside or inside circles, e.g. for circle segments. More precise results are obtained if you measure circles using four touch points, however. You should always preposition the touch probe in the center, or as close to the center as possible.



### 15.9 Datum Setting with 3-D Touch Probe

#### **Outside circle:**

- Position the ball tip at a position near the first touch point outside of the circle
- Select the probe direction by soft key
- To probe the workpiece, press the machine START button. If you are not using the automatic probing routine, you need to repeat this procedure. After the third probing operation, you can have the TNC calculate the center (four touch points are recommended).
- Terminate the probing procedure and switch to the evaluation menu: Press the EVALUATE soft key
- Datum: Enter the coordinates of the datum and confirm your entry with the SET DATUM soft key, or write the values to a table (See "Writing measured values from the touch probe cycles in a datum table", page 520, or See "Writing measured values from the touch probe cycles in the preset table", page 521)
- ▶ To terminate the probe function, press the END soft key

After the probing procedure is completed, the TNC displays the current coordinates of the circle center and the circle radius PR.

#### Setting the datum using multiple holes/cylindrical studs

A second soft-key row provides a soft key for using multiple holes or cylindrical studs to set the datum. You can set the intersection of two or more elements as datum.

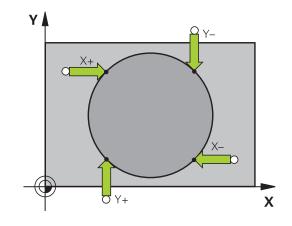
Select the probing function for the intersection of holes/cylindrical studs:

PROBI	NG
	c

- Select the touch probe function: Press the PROBING CC soft key
- Hole is to be probed automatically: Define by soft key
- Circular stud is to be probed automatically: Define by soft key

Preposition the touch probe approximately in the center of the hole or near the first touch point of the circular stud. After you have pressed the NC Start key, the TNC automatically probes the points on the circle.

Move the touch probe to the next hole, repeat the probing operation and have the TNC repeat the probing procedure until all the holes have been probed to set the datum.



15

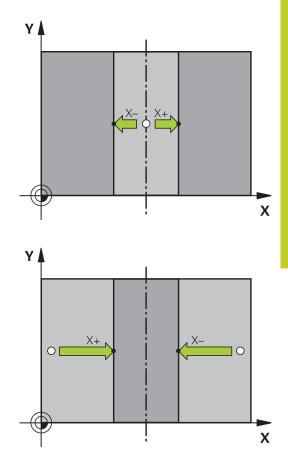
Setting the datum in the intersection of multiple holes:

н.		
н.	( <b></b> )	
н.	$\mathbf{\mathbf{\nabla}}$	

- Preposition the touch probe approximately in the center of the hole
- Hole is to be probed automatically: Define by soft key
- To probe the workpiece, press the machine START button. The touch probe probes the circle automatically.
- Repeat the probing procedure for the remaining elements
- Terminate the probing procedure and switch to the evaluation menu: Press the EVALUATE soft key
- Datum: In the menu window, enter both coordinates of the circle center, confirm with the SET DATUM soft key, or write the values to a table (See "Writing measured values from the touch probe cycles in a datum table", page 520, or See "Writing measured values from the touch probe cycles in the preset table", page 521)
- Terminate the probing function: Press the END soft key

#### Setting a center line as datum

- PROBING
- Select the probe function: Press the PROBING soft key
- Position the touch probe at a position near the first touch point
- Select the probing direction by soft key
- Start the probing procedure: Press the NC Start button
- Position the touch probe at a position near the second touch point
- Start the probing procedure: Press the NC Start button
- Datum: Enter the coordinate of the datum in the menu window, confirm with the SET DATUM soft key, or write the value to a table (See "Writing measured values from the touch probe cycles in a datum table", page 520, or See "Writing measured values from the touch probe cycles in the preset table", page 521.
- Terminate the probing function: Press the END key



15.9 Datum Setting with 3-D Touch Probe

#### Measuring workpieces with a 3-D touch probe

You can also use the touch probe in the Manual Operation and El. Handwheel operating modes to make simple measurements on the workpiece. Numerous programmable probe cycles are available for complex measuring tasks (see User's Manual for Cycles, Chapter 16, Checking workpieces automatically). With a 3-D touch probe you can determine:

- Position coordinates, and from them,
- Dimensions and angles on the workpiece

#### Finding the coordinates of a position on an aligned workpiece

- PROBING POS
- Select the probing function: Press the PROBING POS soft key
- Move the touch probe to a position near the touch point
- Select the probe direction and axis of the coordinate. Use the corresponding soft keys for selection
- Start the probing procedure: Press the machine START button

The TNC shows the coordinates of the touch point as reference point.

#### Finding the coordinates of a corner in the working plane

Find the coordinates of the corner point: See "Corner as datum ", page 531. The TNC displays the coordinates of the probed corner as reference point.

#### Measuring workpiece dimensions



- Select the probing function: Press the PROBING POS soft key
- Position the touch probe at a position near the first touch point A
- Select the probing direction by soft key
- Start the probing procedure: Press the machine START button
- If you need the current datum later, write down the value that appears in the Datum display
- Datum: Enter "0"
- Cancel the dialog: Press the END key
- Select the probing function again: Press the PROBING POS soft key
- Position the touch probe at a position near the second touch point B
- Select the probe direction with the soft keys: Same axis but from the opposite direction
- Start the probing procedure: Press the machine START button

The value displayed as datum is the distance between the two points on the coordinate axis.

## To return to the datum that was active before the length measurement:

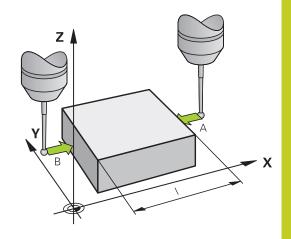
- Select the probing function: Press the PROBING POS soft key
- Probe the first touch point again
- Set the datum to the value that you wrote down previously
- Cancel the dialog: Press the END key

#### **Measuring angles**

You can use the 3-D touch probe to measure angles in the working plane. You can measure

- the angle between the angle reference axis and a workpiece edge, or
- the angle between two sides

The measured angle is displayed as a value of maximum 90°.



### 15.9 Datum Setting with 3-D Touch Probe

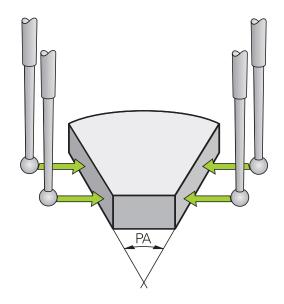
## Finding the angle between the angle reference axis and a workpiece edge

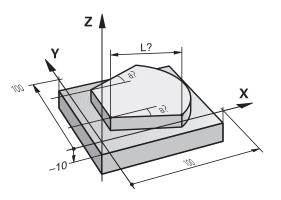


- Select the probe function by pressing the PROBING ROT soft key
- Rotation angle: If you will need the current basic rotation later, write down the value that appears under Rotation angle
- Make a basic rotation with workpiece edge to be compared See "Compensating workpiece misalignment with 3-D touch probe ", page 527
- Press the PROBING ROT soft key to display the angle between the angle reference axis and the workpiece edge as the rotation angle
- Cancel the basic rotation, or restore the previous basic rotation
- Set the rotation angle to the value that you previously wrote down

#### Measuring the angle between two workpiece edges

- Select the probe function by pressing the PROBING ROT soft key
- Rotation angle: If you need the current basic rotation later, write down the displayed rotation angle
- Make a basic rotation with first workpiece edge See "Compensating workpiece misalignment with 3-D touch probe ", page 527
- Probe the second edge as for a basic rotation, but do not set the rotation angle to zero!
- Press the PROBING ROT soft key to display the angle PA between the workpiece edges as the rotation angle
- Cancel the basic rotation, or restore the previous basic rotation by setting the rotation angle to the value that you wrote down previously





## Using touch probe functions with mechanical probes or measuring dials

If you do not have an electronic 3-D touch probe on your machine, you can also use all the previously described manual touch probe functions (exception: calibration function) with mechanical probes or by simply touching the workpiece with the tool.

In place of the electronic signal generated automatically by a 3-D touch probe during probing, you can manually initiate the trigger signal for capturing the **probing position** by pressing a key. Proceed as follows:



- Select any touch probe function by soft key
- Move the mechanical probe to the first position to be captured by the TNC



- Confirm the position: Press the actual-positioncapture soft key for the TNC to save the current position
- Move the mechanical probe to the next position to be captured by the TNC
- Confirm the position: Press the actual-positioncapture soft key for the TNC to save the current position
- If required, move to additional positions and capture as described previously
- Datum: In the menu window, enter the coordinates of the new datum, confirm with the SET DATUM soft key, or write the values to a table (See "Writing measured values from the touch probe cycles in a datum table", page 520, or See "Writing measured values from the touch probe cycles in the preset table", page 521)
- Terminate the probing function: Press the END key

15.10 Tilting the working plane (software option 1)

# 15.10 Tilting the working plane (software option 1)

#### **Application**, function

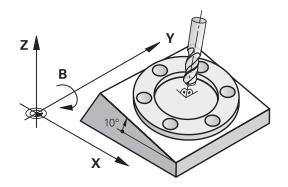
The functions for tilting the working plane are interfaced to the TNC and the machine tool by the machine tool builder. With some swivel heads and tilting tables, the machine tool builder determines whether the entered angles are interpreted as coordinates of the rotary axes or as angular components of a tilted plane. Refer to your machine manual.

The TNC supports the tilting functions on machine tools with swivel heads and/or tilting tables. Typical applications are, for example, oblique holes or contours in an oblique plane. The working plane is always tilted around the active datum. The program is written as usual in a main plane, such as the X/Y plane, but is executed in a plane that is tilted relative to the main plane.

There are three functions available for tilting the working plane:

- Manual tilting with the 3-D ROT soft key in the Manual Operation mode and Electronic Handwheel mode, See "To activate manual tilting:", page 543
- Tilting under program control, Cycle **19 WORKING PLANE** in the part program (see User's Manual for Cycles, Cycle 19 WORKING PLANE)
- Tilting under program control, PLANE function in the part program See "The PLANE Function: Tilting the Working Plane (Software Option 1)", page 411

The TNC functions for "tilting the working plane" are coordinate transformations. The working plane is always perpendicular to the direction of the tool axis.



When tilting the working plane, the TNC differentiates between two machine types:

#### Machine with tilting table

- You must tilt the workpiece into the desired position for machining by positioning the tilting table, for example with an L block.
- The position of the transformed tool axis **does not change** in relation to the machine-based coordinate system. Thus if you rotate the table—and therefore the workpiece—by 90° for example, the coordinate system does not rotate. If you press the Z+ axis direction button in the Manual Operation mode, the tool moves in Z+ direction.
- In calculating the transformed coordinate system, the TNC considers only the mechanically influenced offsets of the particular tilting table (the so-called "translational" components).

#### Machine with swivel head

- You must bring the tool into the desired position for machining by positioning the swivel head, for example with an L block.
- The position of the transformed tool axis changes in relation to the machine-based coordinate system. Thus if you rotate the swivel head of your machine-and therefore the tool —in the B axis by 90° for example, the coordinate system rotates also. If you press the Z+ axis direction button in the Manual Operation mode, the tool moves in X+ direction of the machine-based coordinate system.
- In calculating the transformed coordinate system, the TNC considers both the mechanically influenced offsets of the particular swivel head (the so-called "translational" components) and offsets caused by tilting of the tool (3-D tool length compensation).



TNC 640 | User's Manual

The TNC only supports tilting the working plane with spindle axis Z.

15

## 15 Manual operation and setup

15.10 Tilting the working plane (software option 1)

#### Traversing reference points in tilted axes

The TNC automatically activates the tilted working plane if this function was enabled when the control was switched off. Then the TNC moves the axes in the tilted coordinate system when an axis-direction key is pressed. Position the tool in such a way that a collision is excluded during the subsequent crossing of the reference points. To cross the reference points you have to deactivate the "Tilt Working Plane" function, See "To activate manual tilting:", page 543.



#### Danger of collision!

Be sure that the function for tilting the working plane is active in the Manual Operation mode and that the angle values entered in the menu match the actual angles of the tilted axis.

Deactivate the "Tilt Working Plane" function before you cross the reference points. Take care that there is no collision. Retract the tool from the current position first, if necessary.

## Position display in a tilted system

The positions displayed in the status window (ACTL. and NOML.) are referenced to the tilted coordinate system.

## Limitations on working with the tilting function

- The probing function for basic rotation is not available if you have activated the working plane function in the Manual Operation mode.
- The actual-position-capture function is not allowed if the tilted working plane function is active.
- PLC positioning (determined by the machine tool builder) is not possible.

## To activate manual tilting:



ACTIVE

- To select manual tilting, press the 3D ROT soft key.
- Use the arrow keys to move the highlight to the Manual Operation menu item
- To activate manual tilting, press the Active soft key
- Use the arrow keys to position the highlight on the desired rotary axis
- Enter the tilt angle



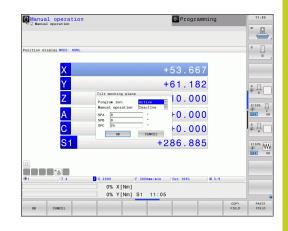
► To conclude entry, press the END key

To reset the tilting function, set the desired operating modes in the menu **Tilt working plane** to inactive.

If the tilted working plane function is active and the TNC moves the machine axes in accordance with the tilted axes, the status display

## shows the 🔊 symbol.

If you activate the "Tilt working plane" function for the Program Run operating mode, the tilt angle entered in the menu becomes active in the first block of the part program. If you use Cycle **19 WORKING PLANE** or the **PLANE** function in the part program, the angle values defined there are in effect. Angle values entered in the menu will be overwritten.



## 15 Manual operation and setup

15.10 Tilting the working plane (software option 1)

# Setting the current tool-axis direction as the active machining direction



This function must be enabled by your machine manufacturer. Refer to your machine manual.

In the Manual Operation and El. Handwheel modes of operation you can use this function to move the tool via the external direction keys or with the handwheel in the direction that the tool axis is currently pointed. Use this function if

- You want to retract the tool in the direction of the tool axis during program interrupt of a 5-axis machining program.
- You want to machine with an inclined tool using the handwheel or the external direction keys in the Manual Operation mode.



- To select manual tilting, press the 3D ROT soft key.
- Use the arrow keys to move the highlight to the Manual Operation menu item
- To activate the current tool-axis direction as the active machining direction, press the Tool Axis soft key



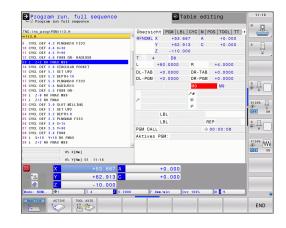
► To conclude entry, press the END key

To reset the tilting function, set the **Manual Operation** menu item in the "Tilt working plane" menu to inactive.

The we symbol appears in the status display when the **Move in tool-axis direction** function is active.



This function is even available when you interrupt program run and want to move the axes manually.



15

## Setting the datum in a tilted coordinate system

After you have positioned the rotary axes, set the datum in the same manner as for a non-tilted system. The behavior of the TNC during datum setting depends on the setting in machine parameter **CfgPresetSettings/chkTiltingAxes**:

- **chkTiltingAxes: On** With an active tilted working plane, the TNC checks during datum setting in the X, Y and Z axes whether the current coordinates of the rotary axes agree with the tilt angles that you defined (3-D ROT menu). If the tilted working plane function is not active, the TNC checks whether the rotary axes are at 0° (actual positions). If the positions do not agree, the TNC will display an error message.
- chkTiltingAxes: Off The TNC does not check whether the current coordinates of the rotary axes (actual positions) agree with the tilt angles that you defined.

#### Danger of collision!

Always set a reference point in all three reference axes.

16

Positioning with Manual Data Input

## **16** Positioning with Manual Data Input

16.1 Programming and executing simple machining operations

# **16.1 Programming and executing simple** machining operations

The Positioning with Manual Data Input mode of operation is particularly convenient for simple machining operations or to pre-position the tool. It enables you to write a short program in HEIDENHAIN conversational programming or in ISO format, and execute it immediately. You can also call TNC cycles. The program is stored in the file \$MDI. In the Positioning with MDI mode of operation, the additional status displays can also be activated.

## Positioning with manual data input (MDI)



#### Limitation

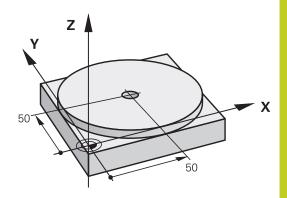
The following functions are not available in the MDI mode:

- FK free contour programming
- Program section repeats
- Subprogramming
- Path compensation
- The programming graphics
- Program call PGM CALL
- The program-run graphics
- Select the Positioning with MDI mode of operation. Program the file \$MDI as you wish
- To start program run, press the machine START button.

#### Example 1

A hole with a depth of 20 mm is to be drilled into a single workpiece. After clamping and aligning the workpiece and setting the datum, you can program and execute the drilling operation in a few lines.

First you pre-position the tool with straight-line blocks to the hole center coordinates at a setup clearance of 5 mm above the workpiece surface. Then drill the hole with Cycle **200 DRILLING**.



O BEGIN PGM \$MDI M	M	
1 TOOL CALL 1 Z S20	000	Call the tool: tool axis Z,
		spindle speed 2000 rpm
2 L Z+200 R0 FMAX		Retract the tool (F MAX = rapid traverse)
3 L X+50 Y+50 R0 FA	лах мз	Move the tool at F MAX to a position above the hole, spindle on
4 CYCL DEF 200 DRII	LING	Define the DRILLING cycle
Q200=5	;SET-UP CLEARANCE	Set-up clearance of the tool above the hole
Q201=-15	;DEPTH	Hole depth (algebraic sign=working direction)
Q206=250	;FEED RATE FOR PLNGNG	Feed rate for drilling
Q202=5	;PLUNGING DEPTH	Depth of each infeed before retraction
Q210=0	;DWELL TIME AT TOP	Dwell time after every retraction in seconds
Q203=-10	;SURFACE COORDINATE	Coordinate of the workpiece surface
Q204=20	;2ND SET-UP CLEARANCE	Set-up clearance of the tool above the hole
Q211=0.2	;DWELL TIME AT BOTTOM	Dwell time in seconds at the hole bottom
5 CYCL CALL		Call the DRILLING cycle
6 L Z+200 R0 FMAX M2		Retract the tool
7 END PGM \$MDI MM		End of program

Straight-line function: See "Straight line L", page 207, DRILLING cycle: See User's Manual, Cycles, Cycle 200 DRILLING.

## **16** Positioning with Manual Data Input

## 16.1 Programming and executing simple machining operations

## Example 2: Correcting workpiece misalignment on machines with rotary tables

- For running a basic rotation with the 3-D touch probe, see "Touch Probe Cycles in the Manual Operation and El. Handwheel modes of operation," section "Compensating workpiece misalignment," in the Cycle Programming User's Manual.
- Write down the rotation angle and cancel the basic rotation
  - Select operating mode: Positioning with MDI
  - Select the axis of the rotary table, enter the rotation angle you wrote down previously and set the feed rate. For example. L C+2.561 F50
  - Conclude entry

Ð

LP

IV

 Press the machine START button: The rotation of the table corrects the misalignment

## Protecting and erasing programs in \$MDI

The \$MDI file is generally intended for short programs that are only needed temporarily. Nevertheless, you can store a program, if necessary, by proceeding as described below:

Ŷ

PGM MGT

ŧ

- Select the Programming and Editing mode of operation
- To call the file manager, press the PGM MGT key (program management).
- Move the highlight to the \$MDI file



Select "Copy file": Press the COPY soft key

#### DESTINATION FILE =

Enter the name under which you want to save the current contents of the \$MDI file, e.g. HOLE.



Copy the file

END

Close the file manager: Press the END soft key

For more information: See "Copying a single file", page 112.



17.1 Graphics

## 17.1 Graphics

## Application

In the program run modes of operation as well as in the Test Run mode, the TNC graphically simulates the machining of the workpiece. Using soft keys, select whether you desire:

- Plan view
- Projection in three planes
- 3-D view
- 3-D line graphics

The TNC graphic depicts the workpiece as if it were being machined with a cylindrical end mill. If a tool table is active, you can also simulate the machining operation with a spherical cutter. For this purpose, enter R2 = R in the tool table.

The TNC will not show a graphic if

- the current program has no valid workpiece blank definition
- no program is selected



The TNC graphic does not show a radius oversize **DR** that has been programmed in the **TOOL CALL** block.

A graphic simulation is only possible under certain conditions for program sections or programs in which rotary axis movements are defined. The graphic may not be displayed correctly by the TNC.

The simulation of programs with 5-axis machining or tilted machining might run at reduced speed. Press the RESOLUTION soft key in order to reduce the resolution of the graphics, thereby increasing the simulation speed. Pressing the RESOLUTION soft key cycles the graphics resolution through **High**, **Medium** and **Low**.

## Speed of the Setting test runs



The most recently set speed remains active, even if the power is interrupted, until you change it.

After you have started a program, the TNC displays the following soft keys with which you can set the simulation speed:

Functions	Soft key
Perform the test run at the same speed at which the program will be run (programmed feed rates are taken into account)	1:1
Increase the test speed incrementally	
Decrease the test speed incrementally	
Test run at the maximum possible speed (default setting)	MAX

You can also set the simulation speed before you start a program:

$\succ$	
	5

- Shift the soft-key row
- Select the functions for setting the simulation speed
- Select the desired function by soft key, e.g. incrementally increasing the test speed

17.1 Graphics

## **Overview: Display modes**

The TNC displays the following soft keys in the Program Run and Test Run modes of operation:

View	Soft key
Plan view	
Projection in three planes	
3-D view	
High resolution 3-D graphics	
3-D line graphics	

#### Limitations during program run

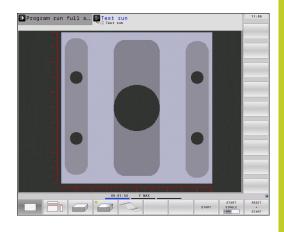
A graphical representation of a running program is not possible if the microprocessor of the TNC is already occupied with complicated machining tasks or if large areas are being machined. Example: Multipass milling over the entire blank form with a large tool. The TNC interrupts the graphics and displays the text **ERROR** in the graphics window. The machining process is continued, however. In the test run graphics, the TNC does not depict

multi-axis operations during machining. The error message **Axis cannot be shown** appears in the graphics window in such cases.

## **Plan view**

This is the fastest of the graphic display modes.

- Press the soft key for plan view
  - Regarding depth display, remember: The deeper the surface, the darker the shade



## **Projection in three planes**

Similar to a workpiece drawing, the part is displayed with a plan view and two sectional planes. A symbol to the lower left indicates whether the display is in first angle or third angle projection according to ISO 5456-2 (selected with MP7310).

Details can be isolated in this display mode for magnification (See "Magnifying details", page 560).

In addition, you can shift the sectional planes with the corresponding soft keys:

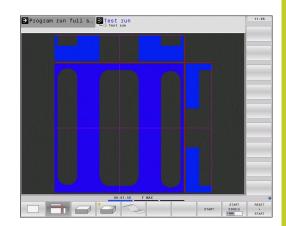


• Select the soft key for projection in three planes.

- Shift the soft-key row until the soft key for the functions for shifting the sectional plane appears
- Select the functions for shifting the sectional plane. The TNC offers the following soft keys:

Function	Soft keys
Shift the vertical sectional plane to the right or left	
Shift the vertical sectional plane forward or backward	
Shift the horizontal sectional plane upwards or downwards	

The positions of the sectional planes are visible during shifting. The default setting of the sectional plane is selected such that it lies in the working plane in the workpiece center and in the tool axis on the top surface.



## 17.1 Graphics

## 3-D view

The workpiece is displayed in three dimensions.

You can rotate the 3-D display about the vertical and horizontal axes via soft keys. If there is a mouse attached to your TNC, you can also perform this function by holding down the right mouse button and dragging the mouse.

The shape of the workpiece can be depicted by a frame overlay at the beginning of the graphic simulation.

In the Test Run mode of operation you can isolate details for magnification, See "Magnifying details", page 560.



Press the soft key for 3-D view.

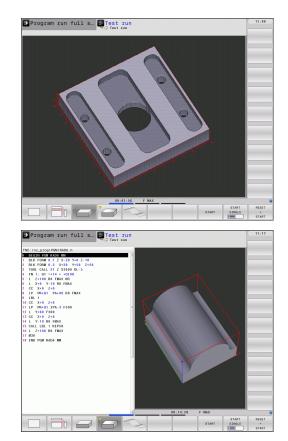
The high resolution 3-D view enables you to display the surface of the machined workpiece in greater detail. With a simulated light source, the TNC creates realistic light and shadow conditions.



Select high resolution 3-D view with the soft key.



The speed of the 3-D graphics depends on the tooth length (**LCUTS** column in the tool table). If **LCUTS** is defined as 0 (basic setting), the simulation calculates an infinitely long tooth length, which leads to a long processing time.



#### Rotating and magnifying/reducing the 3-D view



- Shift the soft-key row until the soft key for the rotating and magnification/reduction appears
- Select functions for rotating and magnifying/ reducing:

Function	Soft keys
Rotate in 5° steps about the vertical axis	
Tilt in 5° steps about the horizontal axis	
Magnify the graphic stepwise If the view is magnified, the TNC shows the letter <b>Z</b> in the footer of the graphic window	+
Reduce the graphic stepwise If the view is reduced, the TNC shows the letter <b>Z</b> in the footer of the graphic window	-
Reset image to programmed size	1:1

If there is a mouse attached to your TNC, you can also perform the functions described above with the mouse:

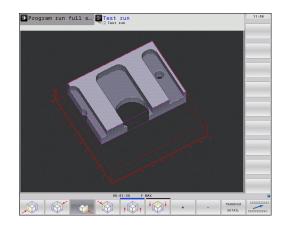
- In order to rotate the graphic shown in three dimensions: Hold the right mouse button down and move the mouse. After you release the right mouse button, the TNC orients the workpiece to the defined orientation
- In order to shift the graphic shown: Hold the center mouse button or the wheel button down and move the mouse. The TNC shifts the workpiece in the corresponding direction. After you release the center mouse button, the TNC shifts the workpiece to the defined position
- In order to zoom in on a certain area with the mouse: Draw a rectangular zoom area while holding the left mouse button down. After you release the left mouse button, the TNC zooms in on the defined area of the workpiece
- In order to quickly zoom in and out with the mouse: Rotate the wheel button forward or backward

17.1 Graphics

## **Magnifying details**

You can magnify details in all display modes in the Test Run mode and a Program Run mode.

The graphic simulation or the program run, respectively, must first have been stopped. A detail magnification is always effective in all display modes.



#### Changing the detail magnification

The soft keys are listed in the table

- Interrupt the graphic simulation, if necessary
- Shift the soft-key row in the Test Run mode, or in a Program Run mode, respectively, until the soft key for detail magnification appears



- Shift the soft-key row until the soft-key for the detail magnification functions appears
- ► Select the functions for detail magnification
- Press the corresponding soft key to select the workpiece surface (see table below)
- To reduce or magnify the blank form, press and hold the MINUS or PLUS soft key, respectively
- Restart the test run or program run by pressing the START soft key (RESET + START returns the workpiece to its original state)

Function	Soft keys
Select the left/right workpiece surface	
Select the front/back workpiece surface	
Select the top/bottom workpiece surface	
Shift the cutting surface for reducing or magnifying the blank form	- +
Select the isolated detail	TRANSFER DETAIL



After a new workpiece detail magnification is selected, the control "forgets" previously simulated machining operations. The TNC then displays machined areas as unmachined areas.

If the workpiece blank cannot be further enlarged or reduced, the TNC displays an error message in the graphics window. To clear the error message, reduce or enlarge the workpiece blank.

## **Repeating graphic simulation**

A part program can be graphically simulated as often as desired, either with the complete workpiece or with a detail of it.

Function	Soft key
Restore workpiece to the detail magnification in which it was last shown	RESET BLK FORM
Reset detail magnification so that the machined workpiece or workpiece blank is displayed as it was programmed with BLK FORM	WINDOW BLK Form

With the WINDOW BLK FORM soft key, you return the displayed workpiece blank to its originally programmed dimensions, even after isolating a detail without TRANSFER DETAIL.

## **Tool display**

You can display the tool during simulation in the plan view and in the projection in three planes. The TNC depicts the tool in the diameter defined in the tool table.

Function	Soft key
Do not display the tool during simulation	TOOLS DISPLAY HIDE
Display the tool during simulation	TOOLS DISPLAY HIDE

17.1 Graphics

#### Measurement of machining time

#### **Program Run modes of operation**

The timer counts and displays the time from program start to program end. The timer stops whenever machining is interrupted.



#### Test Run

The timer displays the time that the TNC calculates for the duration of tool movements that are executed at feed rate. Dwell times are included in the calculation by the TNC. The time calculated by the TNC can only conditionally be used for calculating the production time because the TNC does not account for the duration of machine-dependent interruptions, such as tool change.

#### Activating the stopwatch function

STORE

- Shift the soft-key row until the soft-key for the stopwatch functions appears
- Select the stopwatch functions
- Select the desired function by soft key, e.g. saving the displayed time

Stopwatch functions	Soft key
Store displayed time	STORE
Display the sum of stored time and displayed time	ADD
Clear displayed time	RESET 00:00:00 ()



During the test run, the TNC resets the machining time as soon as a new **BLK FORM** is evaluated.

## 3-D line graphics

## Application

Use the 3-D line graphics to have the TNC show the programmed traverse paths in three dimensions. A powerful zoom function is available for recognizing details quickly.

You should especially use the 3-D line graphics to inspect programs created externally for irregularities before machining, in order to avoid undesirable traces of the machining process on the workpiece. Such traces of machining can occur when points are output incorrectly by the postprocessor.

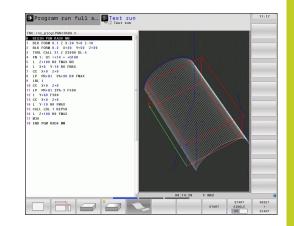
The TNC displays traverse movements with  $\ensuremath{\textbf{FMAX}}$  in blue in the 3-D line graphics.

You can use the 3-D line graphics in Split-Screen mode or in Full-Screen mode:

- To show program blocks to the left and 3-D line graphics to the right, press the SPLIT SCREEN key and PROGRAM + GRAPHICS soft key
- To show the 3-D line graphics on the entire screen, press the SPLIT SCREEN key and GRAPHICS soft key.

## Functions of the 3-D line graphics

Function	Soft key
Show and move the zoom frame up. Press and hold the soft key to move the frame	î
Show and move the zoom frame down. Press and hold the soft key to move the frame	ţ
Show and move the zoom frame to the left. Press and hold the soft key to move the frame	<b>~</b>
Show and move the zoom to the right. Press and hold the soft key to move the frame	->
Rotate workpiece clockwise	
Rotate workpiece counterclockwise	
Tilt workpiece backward	
Tilt workpiece forward	
Magnify the graphic stepwise If the view is magnified, the TNC shows the letter <b>Z</b> in the footer of the graphic window	+
Reduce the graphic stepwise If the view is reduced, the TNC shows the letter <b>Z</b> in the footer of the graphic window	- <del>.</del>



## 17.1 Graphics

Function	Soft key
Show workpiece at original size	1:1
Display BLK form with lines	BLK FORM DISPLAY HIDE

You can also use the mouse with the 3-D line graphics. The following functions are available:

- In order to rotate the wire model shown in three dimensions: Hold the right mouse button down and move the mouse. The TNC shows a directional arrow indicating in which direction the workpiece is turned
- In order to shift the wire model shown: Hold the center mouse button or the wheel button down and move the mouse. The TNC shifts the workpiece in the corresponding direction. After you release the center mouse button, the TNC shifts the workpiece to the defined position
- In order to zoom in on a certain area with the mouse: Draw a rectangular zoom area while holding the left mouse button down. After you release the left mouse button, the TNC zooms in on the defined area of the workpiece
- In order to quickly zoom in and out with the mouse: Rotate the wheel button forward or backward

#### Block number display ON/OFF



SHOW

BLOCK NR.

- Shift the soft-key row
- Show block numbers: Set the SHOW OMIT BLOCK NR. soft key to SHOW
- Hide block numbers: Set the SHOW OMIT BLOCK NR. soft key to OMIT

#### **Erasing the graphic**



Shift the soft-key row



▶ Erase graphic: Press CLEAR GRAPHICS soft key

#### Showing grid lines



- ► Shift the soft-key row: see figure
- Show grid lines: Press the "SHOW GRID LINES" soft key

with the mouse: Rotate the

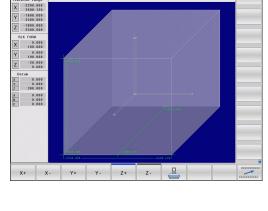
# 17.2 Showing the workpiece blank in the working space

## Application

This MOD function enables you to graphically check the position of the workpiece blank or reference point in the machine's working space and to activate work space monitoring in the Test Run mode of operation. This function is activated with the **BLANK IN WORKSPACE** soft key. You can activate or deactivate the function with the **SW limit monitoring** soft key (2nd soft-key row).

Another transparent cuboid represents the workpiece blank. Its dimensions are shown in the **BLK FORM** table. The TNC takes the dimensions from the workpiece blank definition of the selected program. The workpiece cuboid defines the coordinate system for input. Its datum lies within the traverse-range cuboid.

For a test run it normally does not matter where the workpiece blank is located within the working space. However, if you activate working-space monitoring, you must graphically shift the workpiece blank so that it lies within the working space. Use the soft keys shown in the table.



Program run full s... Test run

You can also activate the current datum for the Test Run operating mode (see the last line of the following table).

Function	Soft keys		
Shift workpiece blank in positive/negative X direction	X + X -		
Shift workpiece blank in positive/negative Y direction	Y + Y -		
Shift workpiece blank in positive/negative Z direction	Z+ Z-		
Show workpiece blank referenced to the set datum			
Switch monitoring function on or off	SW limit monitoring		

17

17.3 Functions for program display

## 17.3 Functions for program display

## **Overview**

In the Program Run modes of operation as well as in the Test Run mode, the TNC provides the following soft keys for displaying a part program in pages:

Functions	Soft key
Go back in the program by one screen	PAGE
Go forward in the program by one screen	
Go to the start of the program	BEGIN
Go to the end of the program	

## 17.4 Test Run

## Application

In the Test Run mode of operation you can simulate programs and program sections to reduce programming errors during program run. The TNC checks the programs for the following:

- Geometrical incompatibilities
- Missing data
- Impossible jumps
- Violation of the machine's working space

The following functions are also available:

- Blockwise test run
- Interruption of test at any block
- Optional block skip
- Functions for graphic simulation
- Measure machining time
- Additional status display



#### Danger of collision!

The TNC cannot graphically simulate all traverse motions actually performed by the machine. These include

- Traverse motions during tool change, if the machine manufacturer defined them in a toolchange macro or via the PLC
- Positioning movements that the machine manufacturer defined in an M-function macro
- Positioning movements that the machine manufacturer performs via the PLC

HEIDENHAIN therefore recommends proceeding with caution for every new program, even when the program test did not output any error message, and no visible damage to the workpiece occurred.

After a tool call, the TNC always starts a program test at the following position:

- In the machining plane at the position X=0, Y=0
- In the tool axis, 1 mm above the MAX point defined in the BLK FORM

If you call the same tool, the TNC resumes program simulation from the position last programmed before the tool call.

In order to ensure unambiguous behavior during program run, after a tool change you should always move to a position from which the TNC can position the tool for machining without causing a collision.

17.4 Test Run



Your machine tool builder can also define a toolchange macro for the Test Run operating mode. This macro will simulate the exact behavior of the machine. Refer to your machine manual.

#### Execute test run

If the central tool file is active, a tool table must be active (status S) to conduct a test run. Select a tool table via the file manager (PGM MGT) in the Test Run mode of operation

With the BLANK IN WORK SPACE function, you activate working space monitoring for the test run, See "Showing the workpiece blank in the working space ", page 565.

- ⋺
- Select the Test Run operating mode
- Call the file manager with the PGM MGT key and select the file you wish to test, or
- Go to the program beginning: Select line 0 with the GOTO key and confirm your entry with the ENT key

#### The TNC then displays the following soft keys:

Functions	Soft key	
Reset the blank form and test the entire program	RESET + START	
Test the entire program	START	
Test each program block individually	START SINGLE	
Halt test run (soft key only appears once you have started the test run)	STOP	

You can interrupt the test run and continue it again at any point —even within a fixed cycle. In order to continue the test, the following actions must not be performed:

- Selecting another block with the arrow keys or the GOTO key
- Making changes to the program
- Switching the operating mode
- Selecting a new program

17.5 Program run

## 17.5 Program run

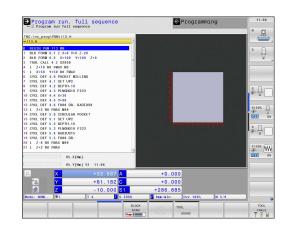
## Application

In the Program Run, Full Sequence mode of operation the TNC executes a part program continuously to its end or up to a program stop.

In the Program Run, Single Block mode of operation you must start each block separately by pressing the machine START button.

The following TNC functions are available in the program run modes of operation:

- Interrupt program run
- Starting the program run from a certain block
- Optional block skip
- Editing the tool table TOOL.T
- Checking and changing Q parameters
- Superimposing handwheel positioning
- Functions for graphic simulation
- Additional status display



## Running a part program

#### Preparation

- 1 Clamp the workpiece to the machine table.
- 2 Set the datum
- 3 Select the necessary tables and pallet files (status M).
- 4 Select the part program (status M).



You can adjust the feed rate and spindle speed with the override knobs.



It is possible to reduce the feed rate when starting the NC program using the FMAX soft key. The reduction applies to all rapid traverse and feed rate movements. The value you enter is no longer in effect after the machine has been turned off and on again. In order to re-establish the respectively defined maximum feed rate after switch-on, you need to re-enter the corresponding value.

The behavior of this function varies depending on the respective machine. Refer to your machine manual.

#### **Program Run, Full Sequence**

Start the part program with the machine START button

#### Program Run, Single Block

 Start each block of the part program individually with the machine START button

17.5 Program run

## Interrupt machining

There are several ways to interrupt a program run:

- Programmed interruptions
- Pressing the machine STOP button
- Switching to Program Run, Single Block

If the TNC registers an error during program run, it automatically interrupts the machining process.

#### **Programmed interruptions**

You can program interruptions directly in the part program. The TNC interrupts the program run at a block containing one of the following entries:

- STOP (with and without miscellaneous function)
- Miscellaneous function M0, M2 or M30
- Miscellaneous function M6 (determined by the machine tool builder)

#### Interruption through the machine STOP button

- Press the machine STOP button: The block that the TNC is currently executing is not completed. The NC stop signal in the status display blinks (see table)
- If you do not wish to continue the machining process, you can reset the TNC with the INTERNAL STOP soft key. The NC stop signal in the status display goes out. In this case, the program must be restarted from the program beginning

#### lcon

## Meaning



Program run is stopped

## Interruption of machining by switching to the Program Run, Single Block mode of operation.

You can interrupt a program that is being run in the Program Run, Full Sequence mode of operation by switching to the Program Run, Single Block mode. The TNC interrupts the machining process at the end of the current block.

## Moving the machine axes during an interruption

You can move the machine axes during an interruption in the same way as in the Manual Operation mode.



#### Danger of collision!

If you interrupt program run while the working plane is tilted, you can switch the coordinate system between tilted and non-tilted, as well as to the active tool axis direction, by pressing the 3-D ROT soft key.

The functions of the axis direction buttons, the electronic handwheel and the positioning logic for returning to the contour are then evaluated by the TNC. When retracting the tool make sure the correct coordinate system is active and the angular values of the tilt axes are entered in the 3-D ROT menu, if necessary.

#### Example: Retracting the spindle after tool breakage

- Interrupt machining
- Enable the external direction keys: Press the MANUAL TRAVERSE soft key
- Move the axes with the machine axis direction buttons.



On some machines you may have to press the machine START button after the MANUAL OPERATION soft key to enable the axis direction buttons. Refer to your machine manual.

## Resuming program run after an interruption



If you cancel a program with INTERNAL STOP, you have to start the program with the RESTORE POS. AT N function or with GOTO "0".

If a program run is interrupted during a fixed cycle, the program must be resumed from the beginning of the cycle. This means that some machining operations will be repeated.

If you interrupt a program run during execution of a subprogram or program section repeat, use the RESTORE POS AT N function to return to the position at which the program run was interrupted.

## 17.5 Program run

When a program run is interrupted, the TNC stores:

- The data of the last defined tool
- Active coordinate transformations (e.g. datum shift, rotation, mirroring)
- The coordinates of the circle center that was last defined



Note that the stored data remain active until they are reset (e.g. if you select a new program).

The stored data are used for returning the tool to the contour after manual machine axis positioning during an interruption (RESTORE POSITION soft key).

#### Resuming program run with the START button

You can resume program run by pressing the machine START button if the program was interrupted in one of the following ways:

- Machine STOP button pressed
- Programmed interruption

#### Resuming program run after an error

If the error message is not blinking:

- Remove the cause of the error
- Clear the error message from the screen: Press the CE key
- Restart the program, or resume program run where it was interrupted

#### If the error message is blinking

- Press and hold the END key for two seconds. This induces a TNC system restart
- Remove the cause of the error
- Restart

If you cannot correct the error, write down the error message and contact your service agency

## Any entry into program (mid-program startup)



The RESTORE POS AT N feature must be enabled and adapted by the machine tool builder. Refer to your machine manual.

With the RESTORE POS AT N feature (block scan) you can start a part program at any block you desire. The TNC scans the program blocks up to that point. Machining can be graphically simulated.

If you have interrupted a part program with an INTERNAL STOP, the TNC automatically offers the interrupted block N for mid-program startup.



Mid-program startup must not begin in a subprogram.

All necessary programs, tables and pallet files must be selected in a program run mode of operation (status M).

If the program contains a programmed interruption before the startup block, the block scan is interrupted. Press the machine START button to continue the block scan.

After a block scan, return the tool to the calculated position with RESTORE POSITION.

Tool length compensation does not take effect until after the tool call and a following positioning block. This also applies if you have only changed the tool length.

Program run, full sequence	🔊 Progr	amming	11:06
TNC:\nc_prog\PGW\113.H	Übersicht PGM LBL CYC	M POS TOOL TT	" _
→113.H	Aktives PGM:		
0 BEGIN PGN 113 NM	Text I		8 🗐
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	۴.		1
2 BLK FORM 0.2 X+100 Mid-program startup	Ď	00:00:08	H
3 TOOL CALL 4 Z S2000 4 L Z+10 R0 FMAX M3 Main program = 113.H		5:06	
5   X+50 Y+50 R0 FMAX Start-up at: N = 0			
	c prog\PGN\113.H	gramme	
7 CYCL DEF 4.1 SET UP2 Repetitions - 1			
8 CYCL DEF 4.2 DEPTH-10			
9 CYCL DEF 4.3 PLNGNG10			
10 CYCL DEF 4.4 X+30 0K	ENDE		
12 CYCL DEF 4.5 F888 DB- BADTUS8	PGM 5		
13 L Z+2 R0 FNAX M99	PGM 6:		\$100%
14 CYCL DEF 5.0 CIRCULAR POCKET			OFF 0
15 CYCL DEF 5.1 SET UP2	PGM 7:		SEE 0
16 CYCL DEF 5.2 DEPTH-10	PGM 8:		
17 CYCL DEF 5.3 PLNONG10 F333 18 CYCL DEF 5.4 RADIUS15	PGM 9:		84
18 CYCL DEF 5.4 RADIUS15 19 CYCL DEF 5.5 E888 DB.	PGM 10:		~ 1
20 L Z-8 R0 FMAX M99			
21 L Z+2 R0 FMAX			F100% W
	1		
0% X[Nm]			OFF 0
0% Y[Nm] S1 11:06			
🚨 X +53.667 A	+0.000		
😕 Y +61.182 C	+0.000		
👷 Z - 10.000 S1	+286.885		
Mode: NOML. 🗭 1 T 4 🗾 S 2000	Com/min Ovr 100	% N 5/9	
V ok END	ADVANCED		

## 17.5 Program run



The TNC skips all touch probe cycles in a midprogram startup. Result parameters that are written to from these cycles might therefore remain empty.

You may not use mid-program startup if the following occurs after a tool change in the machining program:

- The program is started in an FK sequence
- The stretch filter is active
- Pallet management is used
- The program is started in a threading cycle (Cycles 17, 18, 19, 206, 207 and 209) or the subsequent program block
- Touch-probe cycles 0, 1 and 3 are used before program start
- Go to the first block of the current program to start a block scan: Enter GOTO "0"

BLOCK
SCAN

- Select mid-program startup: Press the MID-PROGRAM STARTUP soft key
- Start-up at N: Enter the block number N at which the block scan should end
- Program: Enter the name of the program containing block N
- Repetitions: If block N is located in a program section repeat or in a subprogram that is to be run repeatedly, enter the number of repetitions to be calculated in the block scan
- Start mid-program startup: Press the machine START button
- Contour approach (see following section)

#### Entering a program with the GOTO key

If you use the GOTO block number key for going into a program, neither the TNC nor the PLC will execute any functions that ensure a safe start.

If you use the GOTO block number key for going into a subprogram,

- the TNC will skip the end of the subprogram (LBL 0)
- the TNC will reset function M126 (Shorter-path traverse of rotary axes)

In such cases you must always use the mid-program startup function.

### Returning to the contour

With the RESTORE POSITION function, the TNC returns to the workpiece contour in the following situations:

- Return to the contour after the machine axes were moved during a program interruption that was not performed with the INTERNAL STOP function
- Return to the contour after a block scan with RESTORE POS AT N, for example after an interruption with INTERNAL STOP
- Depending on the machine, if the position of an axis has changed after the control loop has been opened during a program interruption
- To select a return to contour, press the RESTORE POSITION soft key
- Restore machine status, if required
- To move the axes in the sequence that the TNC suggests on the screen, press the machine START button, or
- To move the axes in any sequence, press the soft keys RESTORE X, RESTORE Z, etc., and activate each axis with the machine START button
- ► To resume machining, press the machine START button

N = 10.0 ML         N = 30.0 KL	TNC:\nc_prog\PGM\113.H	Übersicht   PGM   LB		
9 OFC DOT 4 3 PLOADER 7332 2 -10 - 2 PLOADER 733 1 - CC DOT 4 3 PLOADER 733 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 4 - 5 - CLOADER 7 1 - CC DOT 5 - FLOADER 7 2 - CL C DOT 5 - FLOADER 7 2 - CL C DOT 5 - S - CLOADER 7 2 - CL C DOT 5 - CLOADER 7 2 - CL				
	10 CYCL DEF 4.4 X+30 11 CYCL DEF 4.5 Y+90	Y +62. Z -110.	913 C +	
14 0 PCL DOF 1.6 CENCULAR MONET         L         ±0.0000 H         ±4.0000 H           0 PCL DOF 1.6 TH UPEN         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D           15 OPCL DOF 1.5 TH UPEN         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D           10 PCL DOF 1.5 TH UPEN         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D           10 PCL DOF 1.5 TH UPEN         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D           10 PCL DOF 1.5 TH UPEN         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D           20 PCL DOF 3.6 UD T ML NUE         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D           20 PCL DOF 3.6 UD T ML NUE         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D         DL-PGM ±0.0000 D           20 PCL DOF 3.6 UD T ML NUE         DL L-PL NUE         DL L-PL NUE         DL L-PL NUE         DL L-PL NUE           20 PCL DOF 3.6 UD T ML NUE         DL L-PL NUE         DL L-PL NUE         DL L-PL NUE         D           20 PCL DUF 3.6 UD T ML NUE         DL L-PL NUE         DL L-PL NUE         D         D           20 PCL DUF 3.6 UD T ML NUE         D         D         D         D           20 PCL DUF 3.6 UD T ML NUE		T : 4 D8		
15 OFCL DEF 5. ST UP2 15 OFCL DEF 5. ST UP2 17 OFCL DEF 5. ST UP2 17 OFCL DEF 5. ST UP2 28 L 7.48 MORES 28 L 7.48 MORES 29 CH 00F 5.1 ST UP2 28 L 7.48 MORES 29 CH 00F 5.1 ST UP2 20 CH 00F 5.1 ST UP3 20 CH 00F 5.1 ST UP2 20 CH 00F		L +50.0000	R +4.	.0000
17 OPCLORE 5.3 FUENDARIE 1933 18 L - 24 B THOLENES 20 CPC L OF 1.4 INDUCTISS 21 L - 24 B THOLENES 23 CPC L OF 3.4 INDUCTISS 23 CPC L OF 3.4 INDUCTISS 24 C - 24 B THOLENES 25 CPC L OF 3.4 INDUCTISS 25 CPC L OF 3.4 INDUCTISS 26 CPC L OF 3.4 INDUCTISS 27 CPC L OF 3.4 INDUCTISS 26 CPC L OF 3.4 INDUCTISS 27 CPC L OF 3.4 INDUCTISS 26 CPC L OF 3.4 INDUCTISS 26 CPC L OF 3.4 INDUCTISS 27 CPC L OF 3.4 INDUCTISS 26 CPC L OF 3.4 INDUCTISS 26 CPC L OF 3.4 INDUCTISS 27 CPC L OF 3.4 INDUCTISS 28 CPC L OF 3.4 INDUCTISS 28 CPC L OF 3.4 INDUCTISS 29 CPC L OF 3.4 INDUCTISS 20 C	15 CYCL DEF 5.1 SET UP2	DL-TAB +0.0000	DR-TAB +0	0000
11 OFC. OFF 5.4 MAULTONS 10 OFC. OFF 5.4 MAULTONS 10 L 2 A 10 TMAX MPS 10 C C C OFF 3.2 OFT MLTINE 10 C C C C C C C C C C C C C C C C C C C		DL-PGM +0.0000	DR-PGM +0.	.0000
19 OCL OF 3.5 FIRST BL. 22 OCL OF 3.0 SIGN THILTING 23 OCL OF 3.1 SIGN THILTING 25 OCL OF 3.1 SIGN THILTING 35 OCL OF 3.1 SIGN THILTING 36 OCL OF 3.1 SIGN			Ma	19
20 L 2-2 NB FINOL 20 C VCL 607 3 A ST VIELTINE 20 C VCL 607 3 A ST VIEL 20 C VCL 607 4 A ST VIEL 20 C VCL				6. 2.
22 OPCL OF 23 - 50 OF UTLINE 25 OPCL OF 23 - 51 OF UTLINE 25 OPCL OF 23 - 51 OF UP2 25 OPCL OF 23 - 51 OPCL OF UP2 25 OPCL OF 23 OPCL OF 23 OPCL OF UP2 25 OPCL OF 24 OPCL OF UP2				
29 ONG 007 3-1 SET UP2 29 ONG 007 3-1 SET UP2 30 ONG 007 3-1 SET UP2 30 ONG 007 3-1 SET UP2 30 ONG 007 3-1 SET UP3 30 ON		-		S100%
24 OCC 047 3.5 OF PHILE 133 30 27 OCC 047 3.5 Vis9 27 OCC 047 3.5 Vis9 27 OCC 047 3.5 Vis9 28 L - 10 Vis0 FMX CPS 28 L - 10 Vis0 FMX CPS 29 L - 10 Vis0 FMX CPS 20 L			*	OFF
Se ORCL DEF 3-14 X*15 SE ORCL DEF 3-14 X*15		LBL		
201         CALL         © 0.00:00         POM CALL         © 0.00:00         PA           201         Lost Vita Brax         Attaves POM:         F		LBL	REP	8.4
Attives PGM: Provide PGM: PGM: PGM: PGM: PGM: PGM: PGM: PGM:		PGM CALL	• 00:00	0:08
39         L 2+2         R0< PADAC MIPS		Aktives PGM:		
et x(tma) et x(tma) et x(tma) 51 11116 2				F100%
Φ γ(ha) 55 11:16           Δ           +53.667 Å           +0.000           *           Y           +62.913 C           +0.000		<u>+</u>		
X         +53.667         A         +0.000           *         Y         +62.913         C         +0.000				( Sector
*62.913 C +0.000	0% Y[Nm] S1 11:16			
1 +62.913 C +0.000	🙆 X +53.667 A	+0.000		
		+0.000		
Mode: NOML. 🖗1 T 4 Z S 2000 F Dam/min Ovr 100% M 🚺 9	Node: NONE.   91   14 2 S 2000	F Das/san	JUE 100% IN E	79

# 17 Test run and program run

17.6 Automatic program start

# 17.6 Automatic program start

### Application



The TNC must be specially prepared by the machine tool builder for use of the automatic program start function. Refer to your machine manual.



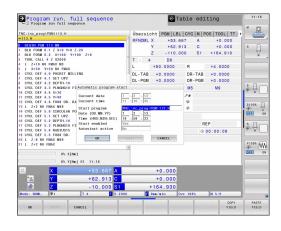
#### Caution: Danger for the operator!

The autostart function must not be used on machines that do not have an enclosed working space.

In a Program Run operating mode, you can use the AUTOSTART soft key (see figure at upper right) to define a specific time at which the program that is currently active in this operating mode is to be started:



- Show the window for entering the starting time (see figure at center right)
- Time (h:min:sec): Time of day at which the program is to be started
- Date (DD.MM.YYYY): Date at which the program is to be started
- ▶ To activate the start, press the OK soft key



# 17.7 Optional block skip

### Application

In a test run or program run, the control can skip over blocks that begin with a slash  $"/"\!:$ 



- To run or test the program without the blocks preceded by a slash, set the soft key to ON
- To run or test the program with the blocks
- preceded by a slash, set the soft key to OFF



This function does not work for **TOOL DEF** blocks. After a power interruption the TNC returns to the most recently selected setting.

### Inserting the "/" character

In the **Programming** mode you select the block in which the character is to be inserted



Select the INSERT soft key

### Erasing the "/" character

In the **Programming** mode you select the block in which the character is to be deleted



Select the REMOVE soft key

# 17 Test run and program run

17.8 Optional program-run interruption

# 17.8 Optional program-run interruption

### Application

The TNC optionally interrupts program run at blocks containing M1. If you use M1 in the Program Run mode, the TNC does not switch off the spindle or coolant.



- Do not interrupt program run or test run at blocks containing M1: Set soft key to OFF
- Interrupt program run or test run at blocks containing M1: Set soft key to ON



18.1 MOD function

# 18.1 MOD function

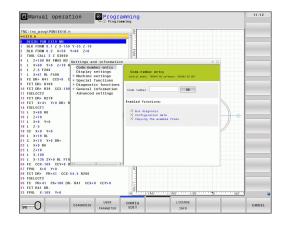
The MOD functions provide additional input possibilities and displays. In addition you can enter code numbers to enable access to protected areas.

### **Selecting MOD functions**

Open the pop-up window with the MOD functions:



To select the MOD functions, press the MOD key. The TNC opens a pop-up window displaying the available MOD functions.



### **Changing the settings**

As well as with the mouse, navigation with the keyboard is also possible in the MOD functions:

- Switch from the input area in the right window to the MOD function selections in the left window with the tab key
- Select MOD function
- Switch to the input field with the tab key or ENT key
- Enter value according to function and confirm with OK or make selection and confirm with Apply



If more than one possibility is available for a particular setting, you can superimpose a window listing all of the given possibilities by pressing the GOTO key. Select the setting with the ENT key. If you don't want to change the setting, close the window again with END.

### **Exiting MOD functions**

▶ Exit MOD functions: press the ABORT soft key or END key

### **Overview of MOD functions**

The following functions are available independent of the selected operating mode:

Code-number entry

Enter code number

Display settings

- Select position displays
- Defining the unit of measurement (mm/inches) for position display
- Setting programming language for MDI
- Display of time
- Show the info line

Machine settings

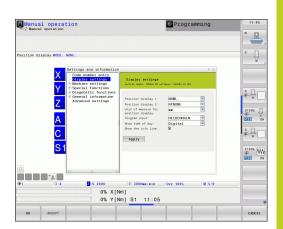
Selecting the machine kinematics

Diagnostic functions

- Profibus diagnosis
- Network information
- HeROS information

General information

- Software version
- FCL information
- License information
- Machine times



**18.2 Machine settings** 

## 18.2 Machine settings

#### **External access**

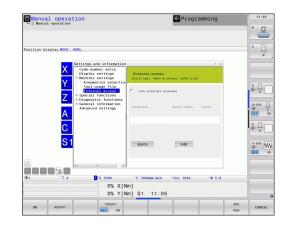


The machine tool builder can configure the external access options. Refer to your machine manual.

With the MOD function **External access** you can grant or restrict access to the TNC. If you have restricted the external access it is no longer possible to connect to the TNC and exchange data via a network or a serial connection, e.g. with the TNCremo data transfer software.

Restricting external access:

- ▶ In the MOD menu select the Machine settings group
- Select the External access menu
- Mark the selection field **Restrict external access** (with the space bar or mouse)
- Press the APPLY soft key

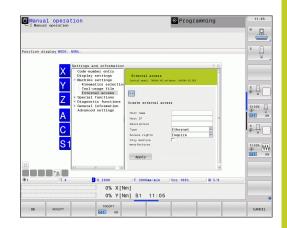


### Computer-specific access control

If your machine tool builder has set up computer-specific access control (machine parameter **CfgAccessCtrl**), you can permit access for up to 32 connections authorized by you. Select **Add new** to create a new connection. The TNC opens an input window for you to enter the connection data.

### Access settings

Host name of the external computer
Network address of the external computer
Additional information (text is shown in the overview list)
Network connection
Serial interface 1
Serial interface 2
The TNC opens a query dialog with external access
Do not permit network access
Permit network access without query
Connection possible only



## 18.2 Machine settings

If you assign the access right **Query** to a connection and access is implemented from this address, the TNC opens a pop-up window. You must permit or deny external access in the pop-up window:

External access	Permission
Yes	Permit once
Always	Permit continuously
Never	Deny continuously
No	Deny once



In the overview list an active connection is shown with a green symbol.

Connections without access rights are shown gray in the overview list.

Machine-dependent function: You can permit or restrict access for external diagnostics or commissioning software with the TNCOPT soft key.

### **Select kinematics**



The **Select Kinematics** function must be enabled and adapted by the machine manufacturer.

Refer to your machine manual.

You can use this function to test programs whose kinematics does not match the active machine kinematics. If your machine manufacturer saved different kinematic configurations in your machine, you can activate one of these kinematics configurations with the MOD function. When you select a kinematics model for the test run this does not affect machine kinematics.



#### Danger of collision!

When you switch the kinematics model for machine operation, the TNC implements all of subsequent movements with modified kinematics.

Ensure that you have selected the correct kinematics in the test run for checking your workpiece.

# 18.3 Position Display Types

# Application

In the Manual Operation mode and in the Program Run modes of operation, you can select the type of coordinates to be displayed.

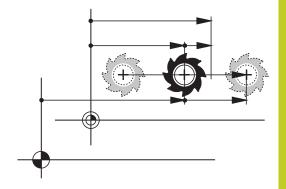
The figure at right shows the different tool positions:

- Starting position
- Target position of the tool
- Workpiece datum
- Machine datum

The TNC position displays can show the following coordinates:

Function	Display
Nominal position: the value presently commanded by the TNC	NOML.
Actual position; current tool position	ACTL.
Reference position; the actual position relative to the machine datum	REF ACTL
Reference position; the nominal position relative to the machine datum	REF NOML
Servo lag; difference between nominal and actual positions (following error)	LAG
Distance remaining to the programmed position; difference between actual and target positions	DIST
With the MOD function <b>Position display 1</b> , you caposition display in the status display.	an select the

With the MOD function **Position display 2**, you can select the position display in the status display.



18.4 Unit of Measurement

# 18.4 Unit of Measurement

### Application

This MOD function determines whether the coordinates are displayed in millimeters (metric system) or inches.

- To select the metric system (e.g. X = 15.789 mm), set the Change MM/INCH function to mm. The value is displayed to 3 decimal places.
- To select the inch system (e.g. X = 0.6216 inches), set the Change MM/INCH function to inches. The value is displayed to 4 decimal places

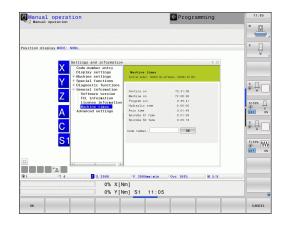
If you would like to activate the inch display, the TNC shows the feed rate in inch/min. In an inch program you must enter the feed rate larger by a factor of 10.

# 18.5 Displaying operating times

### Application

The MACHINE TIME soft key enables you to see various types of operating times:

Operating time	Meaning
Control on	Operating time of the control since being put into service
Machine on	Operating time of the machine tool since being put into service
Program run	Duration of controlled operation since being put into service
	chine tool builder can provide further g time displays. Refer to your machine



# 18.6 Software numbers

# Application

The following software numbers are displayed on the TNC screen after the "Software version" MOD function has been selected:

- Control model: Designation of the control (managed by HEIDENHAIN)
- NC software: Number of the NC software (managed by HEIDENHAIN)
- NCK: Number of the NC software (managed by HEIDENHAIN)
- PLC software: Number or name of the PLC software (managed by your machine tool builder)

In the "FCL information" MOD function, the TNC shows the following information:

 Development level (FCL=Feature Content Level): Development level of the software installed on the control, See "Feature Content Level (upgrade functions)", page 11

# 18.7 Entering the code number

### Application

The TNC requires a code number for the following functions:

Function	Code number
Selecting user parameters	123
Configuring an Ethernet card	NET123
Enabling special functions for Q parameter programming	555343

18.8 Setting up data interfaces

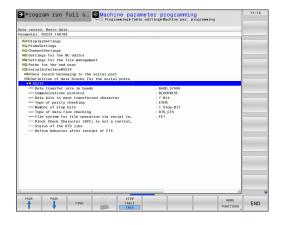
# 18.8 Setting up data interfaces

### Serial interfaces on the TNC 640

The TNC 640 automatically uses the LSV2 transmission protocol for serial data transfer. The LSV2 protocol is permanent and cannot be changed except for setting the baud rate (machine parameter **baudRateLsv2**). You can also specify another type of transmission (interface). The settings described below are therefore effective only for the respective newly defined interface.

### Application

To set up a data interface, select the file management (PGM MGT) and press the MOD key. Press the MOD key again and enter the code number 123. The TNC shows the user parameter **GfgSerialInterface**, in which you can enter the following settings:



### Setting the RS-232 interface

Open the RS232 folder. The TNC then displays the following settings:

### Setting the BAUD RATE (baudRate)

You can set the BAUD RATE (data transfer speed) from 110 to 115 200 baud.

18

### Setting the protocol (protocol)

The data transfer protocol controls the data flow of a serial transmission (comparable to MP5030 of the iTNC 530).

Here, the BLOCKWISE setting designates a form of data transfer where data is transmitted in blocks. This is not to be confused with the blockwise data reception and simultaneous blockwise processing by older TNC contouring controls. Blockwise reception of an NC program and simultaneous machining of the program is not possible!

Data transmission protocol	Selection
Standard data transmission (transmission line-by-line)	STANDARD
Packet-based data transfer	BLOCKWISE
Transmission without protocol (only character-by-character)	RAW_DATA

### Setting data bits (dataBits)

By setting the data bits you define whether a character is transmitted with 7 or 8 data bits.

### Check parity (parity)

The parity bit helps the receiver to detect transmission errors. The parity bit can be formed in three different ways:

- No parity (NONE): There is no error detection
- Even parity (EVEN): Here there is an error if the receiver finds that it has received an odd number of set bits
- Odd parity (ODD): Here there is an error if the receiver finds that it has received an even number of set bits

### Setting the stop bits (stopBits)

The start bit and one or two stop bits enable the receiver to synchronize to every transmitted character during serial data transmission.

### 18.8 Setting up data interfaces

### Setting handshaking (flowControl)

By handshaking, two devices control data transfer between them. A distinction is made between software handshaking and hardware handshaking.

- No data flow checking (NONE): Handshaking is not active
- Hardware handshaking (RTS\_CTS): Transmission stop is active through RTS
- Software handshaking (XON\_XOFF): Transmission stop is active through DC3 (XOFF)

### File system for file operations (fileSystem)

In **fileSystem** you define the file system for the serial interface. This machine parameter is not required if you don't need a special file system.

- EXT: Minimum file system for printers or non-HEIDENHAIN transmission software. Corresponds to the EXT1 and EXT2 modes of earlier TNC controls.
- FE1: Communication with the TNCserver PC software or an external floppy disk unit.

# Settings for data transfer with the TNCserver PC software

Enter the following settings in the user parameters (serialInterfaceRS232 / definition of data blocks for the serial ports / RS232):

Parameters	Selection
Data transfer rate in baud	Has to match the setting in TNCserver
Data transmission protocol	BLOCKWISE
Data bits in each transferred character	7 bits
Type of parity checking	EVEN
Number of stop bits	1 stop bit
Specify type of handshake:	RTS_CTS
File system for file operations	FE1

# Setting the operating mode of the external device (fileSystem)



The functions "Transfer all files," "Transfer selected file," and "Transfer directory" are not available in the FE2 and FEX modes.

External device	Operating mode	lcon
PC with HEIDENHAIN data transfer software TNCremoNT	LSV2	
HEIDENHAIN floppy disk units	FE1	
Non-HEIDENHAIN devices such as printers, scanners, punchers, PC without TNCremoNT	FEX	Ð

### 18.8 Setting up data interfaces

#### Data transfer software

For transfer of files to and from the TNC, we recommend using the HEIDENHAIN TNCremo data transfer software. With TNCremo, data transfer is possible with all HEIDENHAIN controls via the serial interface or the Ethernet interface.



You can download the current version of TNCremo free of charge from the HEIDENHAIN Filebase (www.heidenhain.de, Services and Documentation, Software, PC Software, TNCremoNT).

System requirements for TNCremo:

- PC with 486 processor or higher
- Windows 95, Windows 98, Windows NT 4.0, Windows 2000, Windows XP, Windows Vista operating systems
- 16 MB RAM
- 5 MB free memory space on your hard disk
- An available serial interface or connection to the TCP/IP network

#### Installation under Windows

- Start the SETUP.EXE installation program with the file manager (Explorer)
- ▶ Follow the setup program instructions

#### Starting TNCremoNT under Windows

 Click on <Start>, <Programs>, <HEIDENHAIN Applications>, <TNCremo>

When you start TNCremo for the first time, TNCremo automatically tries to set up a connection with the TNC.

#### Data transfer between the TNC and TNCremoNT



Before you transfer a program from the TNC to the PC, you must make absolutely sure that you have already saved the program currently selected on the TNC. The TNC saves changes automatically when you switch the mode of operation on the TNC, or when you select the file manager via the PGM MGT key.

Check whether the TNC is connected to the correct serial port on your PC or to the network.

Once you have started TNCremoNT, you will see a list of all files that are stored in the active directory in the upper section of the main window 1. Using <File>, <Change directory>, you can select any drive or another directory on your PC.

If you want to control data transfer from the PC, establish the connection with your PC in the following manner:

- Select <File>, <Setup connection>. TNCremoNT now receives the file and directory structure from the TNC and displays this at the bottom left of the main window 2
- To transfer a file from the TNC to the PC, select the file in the TNC window with a mouse click and drag and drop the highlighted file into the PC window 1
- To transfer a file from the PC to the TNC, select the file in the PC window with a mouse click and drag and drop the highlighted file into the TNC window 2

If you want to control data transfer from the TNC, establish the connection with your PC in the following manner:

- Select <Extras>, <TNCserver>. TNCremoNT is now in server mode. It can receive data from the TNC and send data to the TNC
- You can now call the file management functions on the TNC by pressing the key PGM MGTSee "Data transfer to/from an external data medium", page 125, in order to transfer the desired files

#### Exiting TNCremoNT

Select <File>, <Exit>



Refer also to the TNCremoNT context-sensitive help texts where all of the functions are explained in more detail. The help texts must be called with the F1 key.

Datei Ansicht Egtras (	🗷 🌆 📤	9		
s:\SCREE		\\BA\KLARTEXT\dumppgms[*.*]		Steuerung
Name	Größe	Attribute Datum	<b></b>	
				Dateistatus
□%TCHPRNT.A	79	04.03.97 11:34:06	_	Frei: 899 MByte
I.H	813	04.03.97 11:34:08		
🕒 1E.H 🔥 🚹	379	02.09.97 14:51:30		Insgesamt 8
🕒 1F.H	360	02.09.97 14:51:30		Maskiert: 18
1GB.H	412	02.09.97 14:51:30		p.
🗩 11.H	384	02.09.97 14:51:30	•	
	TNC:\NK\	SCRDUMP[*.*]		Verbindung
Name	Große	Attribute Datum		Protokoll:
				LSV-2
🗩 200.H	1596	06.04.99 15:39:42		Schnittsteller
🕑 201.H	1004	06.04.99 15:39:44		CDM2
P 202.H	1892	06.04.99 15:39:44		Contraction of the second second second
🗈 203.Н 🤈	2340	06.04.99 15:39:46		Baudrate (Auto Detec
🖻 210.H	3974	06.04.99 15:39:46		115200
	3604	06.04.99 15:39:40		
P)212.H	3352	06.04.99 15:39:40	1 million	
Do an	0750	00.04.00.15.00.40	•	

**18.9 Ethernet interface** 

### 18.9 Ethernet interface

### Introduction

The TNC is shipped with a standard Ethernet card to connect the control as a client in your network. The TNC transmits data via the Ethernet card with

- the smb protocol (Server Message Block) for Windows operating systems, or
- the TCP/IP protocol family (Transmission Control Protocol/ Internet Protocol) and with support from the NFS (Network File System)

### **Connection options**

You can connect the Ethernet card in your TNC to your network through the RJ45 connection (X26, 100BaseTX or 10BaseT), or directly to a PC. The connection is metallically isolated from the control electronics.

For a 100BaseTX or 10BaseT connection you need a Twisted Pair cable to connect the TNC to your network.



The maximum cable length between TNC and a node depends on the quality grade of the cable, the sheathing and the type of network (100BaseTX or 10BaseT).

No great effort is required to connect the TNC directly to a PC that has an Ethernet card. Simply connect the TNC (port X26) and the PC with an Ethernet crossover cable (trade names: crossed patch cable or STP cable).



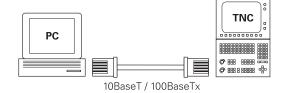


Make sure that the person configuring your TNC is a network specialist.

Please note that the TNC performs an automatic restart if you change the IP address of the TNC.

- Press the MOD key in the Programming and Editing operating mode and enter the code number NET123.
- In the file manager, select the NETWORK soft key. The TNC displays the main screen for network configuration





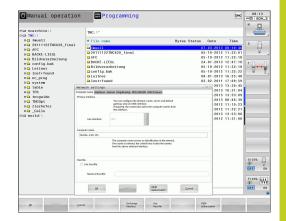
#### **General network settings**

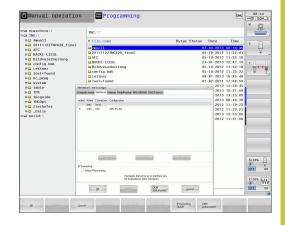
Press the DEFINE NET soft key to enter the general network settings. The **Computer name** tab is active:

Setting	Meaning
Primary interface	Name of the Ethernet interface to be integrated in your company network. Only active if a second, optional Ethernet interface is available on the control hardware
Computer name	Name displayed for the TNC in your company network
Host file	<b>Only required for special applications</b> : Name of a file in which the assignments of IP addresses to computer names is defined

Select the **Interfaces** tab to enter the interface settings:

Setting	Meaning
Interface list	List of the active Ethernet interfaces. Select one of the listed interfaces (via mouse or arrow keys)
	<ul> <li>Activate button: Activate the selected interface (an X appears in the Active column)</li> </ul>
	<ul> <li>Deactivate button: Deactivate the selected interface (- in the Active column)</li> </ul>
	<ul> <li>Configuration button: Open the configuration menu</li> </ul>
Allow IP forwarding	<b>This function must be kept deactivated</b> . Only activate this function if external access via the second, optional Ethernet interface of the TNC is necessary for diagnostic purposes. Only do so after instruction by our Service Department



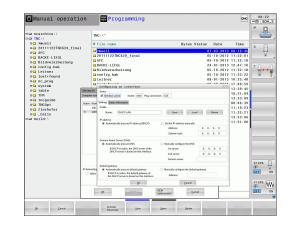


# **18.9 Ethernet interface**

Press the Configuration button to open the Configuration menu:

Setting	Meaning
Status	<ul> <li>Active interface: Connection status of the selected Ethernet interface</li> <li>Name: Name of the interface you are currently configuring</li> <li>Plug connection: Number of the plug connection of this interface on the logic unit of the control</li> </ul>
Profile	<ul> <li>Here you can create or select a profile in which all settings shown in this window are stored. HEIDENHAIN provides two standard profiles:</li> <li>DHCP-LAN: Settings for the standard TNC Ethernet interface, should work in a standard company network</li> <li>MachineNet: Settings for the second, optional Ethernet interface; for configuration of the machine network</li> </ul>
	Press the corresponding buttons to save, load and delete profiles
IP address	<ul> <li>Option Automatically procure IP address: The TNC is to procure the IP address from the DHCP server</li> <li>Option Manually set IP address: Manually define the IP address and subnet mask. Input: Four numerical values separated by points, in each field, e.g. 160.1.180.20 and 255.255.0.0</li> </ul>
Domain Name Server (DNS)	<ul> <li>Option Automatically procure DNS: The TNC is to automatically procure the IP address of the domain name server</li> <li>Option Manually configure DNS: Manually enter the IP addresses of the servers and the domain name</li> </ul>
Default gateway	<ul> <li>Option Automatically procure default GW: The TNC is to automatically procure the default gateway</li> <li>Option Manually configure default GW: Manually enter the IP addresses of the default gateway</li> </ul>

 Apply the changes with the OK button, or discard them with the Cancel button



	The	Internet 1	tab	currently	has	no function.
--	-----	------------	-----	-----------	-----	--------------

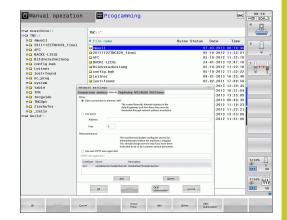
Setting	Meaning
Proxy	<ul> <li>Direct connection to Internet /NAT: The control forwards Internet inquiries to the default gateway and from there they must be forwarded through network address translation (e.g. if a direct connection to a modem is available)</li> </ul>
	<ul> <li>Use proxy: Define the Address and Port of the Internet router in your network, ask your network administrator for the correct address and port</li> </ul>
Telemaintenar	nce The machine manufacturer configures the
	server for telemaintenance here. Changes must always be made in agreement with your machine tool builder

Select the **Ping/Routing** tab to enter the ping and routing

Meaning

settings:

Setting



DO THE:	TNC: \`		
8 a #suel1 8 a 20111122TNC620 fin	∲ File name	Bytes Status Date	Time
B-D AFC	🗂 Jauell		013 08:10:46
BACKE - LIEGL	20111122TNC620_final		012 11:32:01
BG Bildverarbeitung	C AFC		012 11:32:18
e config.bak	BACKE - LIEGL		013 12:47:10 T
a Leitner	Bildverarbeitung		012 11:32:18
8 lost+found	Config.bak		012 11:32:22
ma nc prog	Leitner		013 16:25:48
B- system	lost+found		011 17:09:59
n Ca table	Network settings	0 H 23	013 13:39:45
B-CD TFR	Comparename interfaces internet PingRouting NPSUID;GID DHCP server		013 10:31:04 013 13:33:09
😁 🖬 tnoguide	Proj		013 13:33:09 013 08:46:39
= Ca TNCOpt	Address		012 11:19:23
8- Zierhofer			012 11:32:23
n 🖬 _Calls			013 13:53:06
0-⊖ world:\			012 11:31:00
	Sur		
	SAA	397	
	Bastro		
	Kernel IP routing table	(E)	
	Destination Gateway Germask Flags Metric Ref. Use Roce 0.0.0.0. 10.6.207254 0.0.0. UG 0. 0. 0.eM0		
	38.6.192.0 0.8.8.8 255.255.240.0 U 0 0 0 e#4	1	510
			6
		1	OF
			(arr
	Update		E10
			6
	OEM OEM	Garcel	IOF
	sutherization		

Ping	In the <b>Address:</b> field, enter the IP number for which you want to check the network connection. Input: Four numerical values separated by periods, e.g. <b>160.1.180.20</b> . As an alternative, you can enter the name of the computer whose connection you want to check
	<ul> <li>Press the Start button to begin the test. The TNC shows the status information in the Ping field</li> </ul>
	Press the <b>Stop</b> button to conclude the test
Routing	For network specialists: Status information of the operating system for the current routing
	Press the <b>Update</b> button to refresh the routing information
Select the NFS identifications:	<b>UID/GID</b> tab to enter the user and group
Setting	Meaning
Set UID/ GID for NFS shares	<ul> <li>User ID: Definition of which user identification the end user uses to access files in the network. Ask your network</li> </ul>

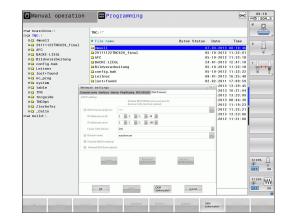
specialist for the proper value
Group ID: Definition of the group identification with which you access files in the network. Ask your network specialist for the proper value



# 18.9 Ethernet interface

**DHCP server**: Settings for automatic network configuration

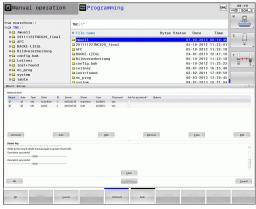
Setting	Meaning
DHCP server	<b>IP addresses from:</b> Define the IP address as of which the TNC is to derive the pool of dynamic IP addresses. The TNC transfers the values that appear dimmed from the static IP address of the defined Ethernet interface; these values cannot be edited.
	IP addresses to: Define the IP address up to which the TNC is to derive the pool of dynamic IP addresses
	• Lease Time (hours): Time within which the dynamic IP address is to remain reserved for a client. If a client logs on within this time, the TNC reassigns the same dynamic IP address.
	<b>Domain name</b> : Here you can define a name for the machine network if required. This is necessary if the same names are assigned in the machine network and in the external network, for example.
	Forward DNS externally: If IP Forwarding is active (Interfaces tab) and the option is active, you can specify that the name resolution for devices in the machine network can also be used by the external network.
	Forward DNS from outside: If IP Forwarding is active (Interfaces tab) and the option is active, you can specify that the TNC is to forward DNS inquiries from devices within the machine network to the name server of the external network if the DNS server of the MC cannot answer the inquiry.
	<ul> <li>Status button: Call an overview of the devices that are provided with a dynamic IP address in the machine network. You can also select settings for these devices.</li> </ul>
I	<ul> <li>Additional options button: Additional settings for the DNS/DHCP server.</li> </ul>
	Set standard values button: Set factory settings.

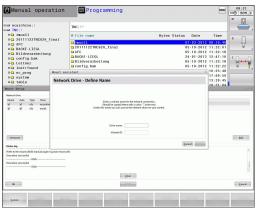


### Network settings specific to the device

 Press the DEFINE MOUNT soft key to enter the network settings for a specific device. You can define any number of network settings, but you can manage only seven at one time

Setting	Meaning
Network drive	List of all connected network drives. The TNC shows the respective status of the network connections in the columns: Mount: Network drive connected / not
	<ul> <li>connected</li> <li>Auto: Network drive is to be connected automatically /manually</li> <li>Type: Type of network connection. cifs</li> </ul>
	<ul><li>and nfs are possible</li><li>Drive: Designation of the drive on the TNC</li></ul>
	<ul> <li>ID: Internal ID that identifies if a mount point has been used for more than one connection</li> </ul>
	<ul> <li>Server: Name of the server</li> <li>Authorization name: Name of the directory on the server that the TNC is to access</li> </ul>
	<ul> <li>User: User name with which the user logs on to the network</li> </ul>
	<ul> <li>Password: Network drive password protected / not protected</li> </ul>
	<ul> <li>Request password?: Request / Do not request password during connection</li> <li>Optional Disclosure dubitions have a straight for the second straight for the</li></ul>
	<ul> <li>Options: Display additional connection options</li> </ul>
	To manage the network drives, use the screen buttons.
	To add network drives, use the <b>Add</b> button: The TNC then starts the connection wizard, which guides you by dialog through the required definitions.
Status log	Display of status information and error messages. Press the Clear button to delete the contents of the Status Log window.





18.10 Configure HR 550 FS wireless handwheel

# 18.10 Configure HR 550 FS wireless handwheel

### Application

Press the SET UP WIRELESS HANDWHEEL soft key to configure the HR 550 FS wireless handwheel. The following functions are available:

- Assigning the handwheel to a specific handwheel holder
- Setting the transmission channel
- Analyzing the frequency spectrum for determining the optimum transmission channel
- Select transmitter power
- Statistical information on the transmission quality

# Assigning the handwheel to a specific handwheel holder

- Make sure that the handwheel holder is connected to the control hardware.
- Place the wireless handwheel you want to assign to the handwheel holder in the handwheel holder
- Press the MOD key to select the MOD function
- Scroll through the soft-key row
  - Select the configuration menu for the wireless handwheel: Press the SET UP WIRELESS HANDWHEEL soft key
  - Click the Connect HR button: The TNC saves the serial number of the wireless handwheel located in the handwheel holder and shows it in the configuration window to the left of the Connect HR button
  - To save the configuration and exit the configuration menu, press the END button

Properties Frequency s	pectrum				
Configuration			Statistics		
handwheel serial no.	0037478964	Connect HW	Data packets	5228	
Channel setting	16	Select channel	Lost packets	0	0.00%
Channel in use	16		CRC error	0	0.00%
Transmitter power	Full power	Set power	Max. successive lost	0	
HW in charger	G				
Status					
HANDWHEEL ONL	INE Erro	r code			
	Stop HW	Start handwheel	Enc	1	

### Setting the transmission channel

If the wireless handwheel is started automatically, the TNC tries to select the transmission channel supplying the best transmission signal. If you want to set the transmission channel manually, proceed as follows:

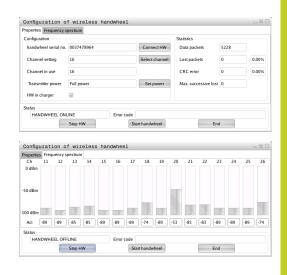
- Press the MOD key to select the MOD function
- Scroll through the soft-key row
  - Select the configuration menu for the wireless handwheel: Press the SET UP WIRELESS HANDWHEEL soft key
  - Click the Frequency spectrum tab
  - Click the Stop HR button: The TNC stops the connection to the wireless handwheel and determines the current frequency spectrum for all of the 16 available channels
  - Memorize the number of the channel with the least amount of radio traffic (smallest bar)
  - Click the Start handwheel button to reactivate the wireless handwheel
  - Click the Properties tab
  - Click the Select channel button: The TNC shows all available channel numbers. Click the channel number for which the TNC determined the least amount of radio traffic
  - ► To save the configuration and exit the configuration menu, press the **END** button

#### Selecting the transmitter power



Please keep in mind that the transmission range of the wireless handwheel decreases when the transmitter power is reduced.

- Press the MOD key to select the MOD function
- Scroll through the soft-key row
  - Select the configuration menu for the wireless handwheel: Press the SET UP WIRELESS HANDWHEEL soft key
  - Click the Set power button: The TNC shows the three available power settings. Click the desired setting
  - To save the configuration and exit the configuration menu, press the END button



Configuration			Statistics		
handwheel serial no.	0037478964	- Connect HW	Data packets	5228	
Channel setting	16	Select channel	Lost packets	0	0.00%
Channel in use	16		CRC error	0	0.00%
Transmitter power	Full power	Set power	Max. successive lost	0	
HW in charger	4				
Status					
HANDWHEEL ON	LINE En	ror code			

## 18.10 Configure HR 550 FS wireless handwheel

### **Statistical data**

Under **Statistics**, the TNC displays information about the transmission quality.

If the reception quality is poor so that a proper and safe stop of the axes cannot be ensured anymore, an emergency-stop reaction of the wireless handwheel is triggered.

The displayed value **Max. successive lost** indicates whether reception quality is poor. If the TNC repeatedly displays values greater than 2 during normal operation of the wireless handwheel within the desired range of use, then there is a risk of an undesired disconnection. This can be corrected by increasing the transmitter power or by changing to another channel with less radio traffic.

If this occurs, try to improve the transmission quality by selecting another channel (See "Setting the transmission channel", page 603) or by increasing the transmitter power (See "Selecting the transmitter power", page 603).

To display the statistical data, proceed as follows:

- Press the MOD key to select the MOD function
- Scroll through the soft-key row
  - To select the configuration menu for the wireless handwheel, press the SET UP WIRELESS HANDWHEEL soft key: The TNC displays the configuration menu with the statistical data

Properties Frequency s	pectrum				
Configuration			Statistics		
handwheel serial no.	0037478964	Connect HW	Data packets	5228	
Channel setting	16	Select channel	Lost packets	0	0.00%
Channel in use	16		CRC error	0	0.00%
Transmitter power	Full power	Set power	Max. successive lost	0	
HW in charger	6				
Status					
HANDWHEEL ONL	INE Error code				



Tables and overviews

# **19** Tables and overviews

19.1 Machine-specific user parameters

### **19.1** Machine-specific user parameters

### Application

The parameter values are entered in the **configuration editor**.



To enable you to set machine-specific functions, your machine tool builder can define which machine parameters are available as user parameters. Furthermore, your machine tool builder can integrate additional machine parameters, which are not described in the following, into the TNC. Refer to your machine manual.

The machine parameters are grouped as parameter objects in a tree structure in the configuration editor. Each parameter object has a name (e.g. **CfgDisplayLanguage**) that gives information about the parameters it contains. A parameter object, also called "entity", is marked with an "E" in the folder symbol in the tree structure. Some machine parameters have a key name to identify them unambiguously. The key name assigns the parameter to a group (e.g. X for X axis). The respective group folder bears the key name and is marked by a "K" in the folder symbol.



If you are in the configuration editor for the user parameters, you can change the display of the existing parameters. In the default setting, the parameters are displayed with short, explanatory texts. To display the actual system names of the parameters, press the key for the screen layout and then the SHOW SYSTEM NAME soft key. Follow the same procedure to return to the standard display.

Parameters not yet active and objects appear dimmed. These can be activated with the MORE FUNCTIONS and INSERT soft key.

The TNC saves a modification list of the last 20 changes to the configuration data. To restore modifications, select the corresponding line and press the MORE FUNCTIONS and DISCARD CHANGES soft keys.

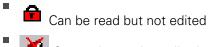
#### Calling the configuration editor and changing parameters

- Select the **Programming** mode of operation
- ► Press the **MOD** key
- Enter the code number **123**.
- Changing Parameters
- Press the END soft key to exit the configuration editor
- Press the SAVE soft key to save changes

The icon at the beginning of each line in the parameter tree shows additional information about this line. The icons have the following meanings:



- Branch exists but is closed
- Branch is open
- Empty object, cannot be opened
- Initialized machine parameter
- Uninitialized (optional) machine parameter



🔀 Cannot be read or edited

The type of the configuration object is identified by its folder symbol:

Key (group name)

∎ ⊞⊑⊐ <sub>List</sub>

Entity or parameter object

#### **Displaying help texts**

The **HELP** key enables you to call a help text for each parameter object or attribute.

If the help text does not fit on one page (1/2 is then displayed at the upper right, for example), press the **HELP PAGE** soft key to scroll to the second page.

To exit the help text, press the **HELP** key again.

Additional information, such as the unit of measure, the initial value, or a selection list, is also displayed. If the selected machine parameter matches a parameter in the TNC, the corresponding MP number is shown.

# **19** Tables and overviews

### 19.1 Machine-specific user parameters

#### **Parameter list**

#### Parameter settings

#### DisplaySettings

Settings for screen display

Sequence of displayed axes

[0] to [5]

#### Depends on available axes

Type of position display in position window

NOMINAL ACTUAL REF ACTL REF NOML LAG DIST

Type of position display in position window

NOMINAL ACTUAL REF ACTL REF NOML LAG DIST

Definition of decimal separation characters for position display

Display of feed rate in Manual Operation mode

at axis key: Only show feed rate when axis-direction key is pressed always minimum: Always show feed rate

Display of spindle position in the position display

during closed loop: Only show spindle position when spindle is in position control during closed loop and M5: Show spindle position when spindle is in position control and with M5

Show or hide soft key Preset table

True: Soft key Preset table is not shown False: Display soft key Preset table

19

#### **Parameter settings**

**DisplaySettings** 

Display step for single axes

List of all available axes

Display step for position display in mm or degrees

0.1
0.05
0.01
0.005
0.001
0.0005
0.0001
0.00005 (display step software option)
0.00001 (display step software option)

Display step for position display in inches

0.005 0.001 0.0005 0.0001 0.00005 (display step software option) 0.00001 (display step software option)

#### DisplaySettings

Definition of unit of measure valid for the display

metric: Use metric system inch: Use inch system

#### DisplaySettings

Format of NC programs and display of cycles

Program input in HEIDENHAIN conversational text or in DIN/ISO

HEIDENHAIN: Program input in BA MDI in conversational text dialog ISO: Program input in BA MDI in DIN/ISO

Display in cycles

TNC\_STD: Display cycles with comment texts TNC\_PARAM: Display cycles without comment texts

# 19 Tables and overviews

19.1 Machine-specific user parameters

#### **Parameter settings**

#### **DisplaySettings**

Behavior with control start-up

True: Display power interruption message False: Do not display power interruption message

#### DisplaySettings

Setting the NC and PLC dialog language

NC dialog language

ENGLISH **GERMAN CZECH** FRENCH ITALIAN **SPANISH** PORTUGUESE **SWEDISH** DANISH **FINNISH** DUTCH POLISH **HUNGARIAN RUSSIAN CHINESE** CHINESE\_TRAD **SLOVENIAN ESTONIAN KOREAN** LATVIAN **NORWEGIAN ROMANIAN SLOVAK** TURKISH **LITHUANIAN** 

PLC dialog language

See NC dialog language

PLC error message language

#### See NC dialog language

Help language

See NC dialog language

#### **Parameter settings**

DisplaySettings

Behavior with control start-up

Acknowledge "Power interruption" message

TRUE: Control start-up is only continued after message acknowledgement FALSE: "Power interruption" message not displayed

Display of cycles

TNC\_STD: Display cycles with comment texts TNC\_PARAM: Display cycles without comment texts

#### DisplaySettings

Settings for program-run graphics

Type of graphic display

High (compute-intensive): The position of linear and rotary axes is considered in the program-run graphics (3D) Low: Only the position of linear axes is considered in the program-run graphics (2.5D) Disabled: Program-run graphics deactivated

#### ProbeSettings

Configuration of probing behavior

Manual operation: Basic rotation considered

TRUE: Consider active basic rotation with probing FALSE: Always traverse paraxially during probing

Automatic mode: Multiple measuring with probing functions

1 to 3: Number of probes for each probing routine

Automatic mode: Confidence range for multiple measuring

0.002 to 0.999 [mm]: Range in which the measured value must lie with multiple measuring

#### Configuration of a round stylus

Coordinates of stylus center point

[0]: X coordinate of the stylus center point with reference to the machine datum[1]: Y coordinate of the stylus center point with reference to the machine datum[2]: Z coordinate of the stylus center point with reference to the machine datum

Setup clearance over the stylus for pre-positioning

0.001 to 99 999.9999 [mm]: Setup clearance in the tool axis direction

Clearance zone around the stylus for pre-positioning

0.001 to 99 999.9999 [mm]: Setup clearance in the plane vertically to the tool axis

## **19** Tables and overviews

19.1 Machine-specific user parameters

#### **Parameter settings**

CfgToolMeasurement

M function for spindle orientation

-1: Spindle orientation directly over NC0: Function inactive1 to 999: Number of M function for spindle orientation

Probing direction for tool radius measurement

X\_Positive, Y\_Positive, X\_Negative, Y\_Negative (depending on tool axis)

Distance of tool lower edge to stylus upper edge

0.001 to 99.9999 [mm]: Offset of stylus to tool

Rapid traverse in probing cycle

10 to 300 000 [mm/min]: Rapid traverse in probing cycle

Probing feed rate with tool measurement

1 to 3 000 [mm/min]: Probing feed rate with tool measurement

Calculation of probing feed rate

ConstantTolerance: Calculation of probing feed rate with constant tolerance VariableTolerance: Calculation of probing feed rate with variable tolerance ConstantFeed: Constant probing feed rate

Max. permissible rotation speed on the tool tip

1 to 129 [m/min]: Permissible rotation speed on mill circumference

Maximum permissible speed for tool measurement

#### 0 to 1 000 [1/min]: Maximum permissible speed

Maximum permissible measurement errors with tool measurement

0.001 to 0.999 [mm]: First maximum permissible measurement error

Maximum permissible measurement errors with tool measurement

0.001 to 0.999 [mm]: Second maximum permissible measurement error

Probing routine

MultiDirections: Probe from multiple directions SingleDirection: Probe from a single direction

#### **Parameter settings**

ChannelSettings

#### CH\_NC

Active kinematic

Kinematic to be activated

#### List of machine kinematics

Geometry tolerances

Permissible deviation of circle radius

0.0001 to 0.016 [mm]: Permissible deviation of circle radius at the circle end point compared to circle start point

#### Configuration of machining cycles

Overlap factor with pocket milling

0.001 to 1.414: Overlap factor for Cycle 4 POCKET MILLING and Cycle 5 CIRCULAR POCKET

Display "Spindle?" error message if no M3/M4 is active

on: Output error message off: Do not output error message

Display "Enter depth as negative" error message

on: Output error message off: Do not output error message

Approach behavior on the wall of a slot in cylinder surface

#### LineNormal: Approach with straight line CircleTangential: Approach with an arc

M function for spindle orientation

-1: Spindle orientation directly over NC0: Function inactive1 to 999: Number of M function for spindle orientation

Define behavior of NC program

Reset machining time at program start

True: Machining time is reset False: Machining time is not reset 19

19.1 Machine-specific user parameters

#### Parameter settings

Geometry filter for filtering out linear elements

Type of stretch filter

- Off: No filter active
- ShortCut: Leave out single points on polygon
- Average: The geometry filter smoothes corners

Maximum distance of filtered to unfiltered contour

0 to 10 [mm]: Filtered points are within this tolerance to the resulting line

Maximum length of the line resulting from filtering

0 to 1000 [mm]: Length over which geometry filtering is effective

Settings for the NC editor

Create backup data

TRUE: Create backup file after editing NC programs FALSE: Do not create backup file after editing NC programs

Behavior of cursor after deletion of lines

TRUE: Cursor on previous line after deletion (iTNC behavior) FALSE: Cursor on next line after deletion

Behavior of cursor with first or last line

TRUE: All-round cursors permitted at PGM start/end FALSE: All-round cursors not permitted at PGM start/end

Line break with multi-line sentences

ALL: Always display lines completely ACT: Only completely display lines of the active sentence NO: Only display lines completely when the sentence is edited

Activate help

TRUE: Always display help graphics during input FALSE: Only display help graphics when the CYCLE HELP soft key is set to ON. The CYCLE HELP OFF/ON soft key is displayed in Program operating mode after pressing the "Screen layout" button

Behavior of soft key row following a cycle input

TRUE: Leave cycle soft key row active after a cycle definition FALSE: Hide cycle soft key row after a cycle definition

Delete confirmation request with Block

TRUE: Display confirmation request when deleting an NC block FALSE: Do not display confirmation request when deleting an NC block

Line number up to which testing of the NC program is implemented

#### **Parameter settings**

100 to 9999: Program length to which geometry should be tested

DIN/ISO programming: Block number increment

0 to 250: Increment for generating DIN/ISO blocks in the program

Line number up to which identical syntax elements are searched for

500 to 9999: Search for cursored-in elements with up/down arrow buttons

Path specifications for end users

List with drives and/or directories

Drives and directories entered here are shown by the TNC in the file manager

FN 16 output path for execution

Path for FN 16 output if no path has been defined in the program

FN 16 output path for BA programming and test run

Path for FN 16 output if no path has been defined in the program

Settings for the file manager

Display of dependent files

MANUAL: Dependent files are displayed AUTOMATIC: Dependent files are not displayed

Universal Time (Greenwich Time)

Time difference to universal time [h]

-12 to 13: Time difference in hours relative to Greenwich Mean Time

serial Interface: See "Setting up data interfaces", page 590

∕∟

19.2 Connector pin layout and connection cables for data interfaces

# 19.2 Connector pin layout and connection cables for data interfaces

#### RS-232-C/V.24 interface for HEIDENHAIN devices

The interface complies with the requirements of EN 50 178 for **low voltage electrical separation**.

When using the 25-pin adapter block:

TNC		Conn. c	able 365725-»	(X	Adapter 310085-0		Conn. ca	able 274545-3	кх
Male	Assignment	Female	Color	Female	Male	Female	Male	Color	Female
1	Do not assign	1		1	1	1	1	White/ Brown	1
2	RXD	2	Yellow	3	3	3	3	Yellow	2
3	TXD	3	Green	2	2	2	2	Green	3
4	DTR	4	Brown	20	20	20	20	Brown	8 –
5	Signal GND	5	Red	7	7	7	7	Red	7
6	DSR	6	Blue	6	6	6	6 —		6
7	RTS	7	Gray	4	4	4	4	Gray	5
8	CTR	8	Pink	5	5	5	5	Pink	4
9	Do not assign	9					8	Violet	20
Hsg.	External shield	Hsg.	External shield	Hsg.	Hsg.	Hsg.	Hsg.	External shield	Hsg.

TNC	NC Conn. cable 355484-xx		-хх	Adapter block 363987-02		Conn. cable 366964-xx			
Male	Assignment	Female	Color	Male	Female	Male	Female	Color	Female
1	Do not assign	1	Red	1	1	1	1	Red	1
2	RXD	2	Yellow	2	2	2	2	Yellow	3
3	TXD	3	White	3	3	3	3	White	2
4	DTR	4	Brown	4	4	4	4	Brown	6
5	Signal GND	5	Black	5	5	5	5	Black	5
6	DSR	6	Violet	6	6	6	6	Violet	4
7	RTS	7	Gray	7	7	7	7	Gray	8
8	CTR	8	White/ Green	8	8	8	8	White/ Green	7
9	Do not assign	9	Green	9	9	9	9	Green	9
Hsg.	External shield	Hsg.	External shield	Hsg.	Hsg.	Hsg.	Hsg.	External shield	Hsg.

When using the 9-pin adapter block:

#### 19.2 Connector pin layout and connection cables for data interfaces

#### **Non-HEIDENHAIN devices**

The connector layout of a non-HEIDENHAIN device may substantially differ from that of a HEIDENHAIN device.

It depends on the unit and the type of data transfer. The table below shows the connector pin layout on the adapter block.

Adapter block 363987-02	C	Conn. cał	ole 366964-x	x
Female	Male	Female	Color	Female
1	1	1	Red	1
2	2	2	Yellow	3
3	3	3	White	2
4	4	4	Brown	6
5	5	5	Black	5
6	6	6	Violet	4
7	7	7	Gray	8
8	8	8	White/ Green	7
9	9	9	Green	9
Hsg.	Hsg.	Hsg.	Ext. shield	Hsg.

#### Ethernet interface RJ45 socket

Maximum cable length:

- Unshielded: 100 m
- Shielded: 400 m

Pin	Signal	Description
1	TX+	Transmit Data
2	TX–	Transmit Data
3	REC+	Receive Data
4	Vacant	
5	Vacant	
6	REC–	Receive Data
7	Vacant	
8	Vacant	

### **19.3** Technical Information

#### Explanation of symbols

<b>1</b> · · · · · · · · · · · · · · · · · · ·		
Standard		
Axis option		
Software option 1		
<b>2</b> Software option 2		
User functions		
Short description		Basic version: 3 axes plus closed-loop spindle
		Fourth NC axis plus auxiliary axis
		or
		8 additional axes or 7 additional axes plus 2nd spindle
		Digital current and shaft speed control
Program entry	In H	EIDENHAIN conversational and ISO
Position data		Nominal positions for lines and arcs in Cartesian coordinates or polar coordinates
		Incremental or absolute dimensions
		Display and entry in mm or inches
Tool compensation		Tool radius in the working plane and tool length
		Radius compensated contour look ahead for up to 99 blocks (M120)
	2	Three-dimensional tool-radius compensation for subsequent changing of tool data without having to recalculate the program
Tool tables	Mul	tiple tool tables with any number of tools
Constant contour speed		With respect to the path of the tool center
		With respect to the cutting edge
Parallel operation	Crea run	ating a program with graphical support while another program is being
3-D machining (software	2	Motion control with minimum jerk
option 2)	2	3-D tool compensation through surface normal vectors
	2	Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point. (TCPM = Tool Center Point Management)
	2	Keeping the tool normal to the contour
	2	Tool radius compensation perpendicular to traversing and tool direction
Rotary table machining (software option 1)	1	Programming of cylindrical contours as if in two axes
	1	Feed rate in distance per minute
Contour elements		Straight line
		Chamfer
		Circular path
		Circle center
		Circle radius

### **19.3 Technical Information**

**User functions** 

Corner rounding Via straight line: tangential or perpendicular
Via straight line: tangential or perpendicular
Via circular arc
FK free contour programming in HEIDENHAIN conversational format with graphic support for workpiece drawings not dimensioned for NC
Subprograms
Program-section repeat
Any desired program as subroutine
Cycles for drilling, and conventional and rigid tapping
Roughing of rectangular and circular pockets
Cycles for pecking, reaming, boring, and counterboring
Cycles for milling internal and external threads
Finishing of rectangular and circular pockets
Cycles for clearing level and inclined surfaces
Cycles for milling linear and circular slots
Cartesian and polar point patterns
Contour-parallel contour pocket
Contour train
OEM cycles (special cycles developed by the machine tool builder) can also be integrated
Cycles for turning operations
Datum shift, rotation, mirroring
Scaling factor (axis-specific)
Tilting the working plane (software option 1)
Mathematical functions: =, +, -, *, sin $\alpha$ , cos $\alpha$ , root
Logical operations (=, $\neq$ , <, >)
Calculating with parentheses
tan $\alpha$ , arc sin, arc cos, arc tan, a <sup>n</sup> , e <sup>n</sup> , ln, log, absolute value of a number, constant $\pi$ , negation, truncation of digits before or after the decimal point
Functions for calculation of circles
String parameters
Calculator
Complete list of all current error messages
Context-sensitive help function for error messages
Graphic support for the programming of cycles
Comment blocks in the NC program
Actual positions can be transferred directly into the NC program
Graphic simulation before program run, even while another program is being run
Plan view / projection in 3 planes / 3-D view / 3-D line graphic

		Magnification of details
Programming graphics	•	In the Programming mode, the contour of the NC blocks is drawn on screen while they are being entered (2-D pencil-trace graphics), even while another program is running
Program Run graphics		Graphic simulation of real-time machining in plan view / projection in 3
Display modes		planes / 3-D view
Machining time		Calculating the machining time in the Test Run mode of operation
		Display of the current machining time in the Program Run operating modes
Returning to the contour		Mid-program startup in any block in the program, returning the tool to the calculated nominal position to continue machining
		Program interruption, contour departure and return
Datum tables		Multiple datum tables, for storing workpiece-related datums
Touch probe cycles		Calibrate the touch probe
		Compensation of workpiece misalignment, manual or automatic
		Datum setting, manual or automatic
	-	Automatic workpiece measurement
		Cycles for automatic tool measurement
		Cycles for automatic tool measurement
		Cycles for automatic kinematics measurement

### **19.3 Technical Information**

#### Specifications

•		
Components		Operating panel
		TFT color flat-panel display with soft keys
Program memory		Minimum 21 GB
Input resolution and display		Up to 0.1 µm for linear axes
step		Up to 0.01 $\mu$ m for linear axes (with option 23)
		Up to 0.0001° for rotary axes
		Up to 0.000 01° for rotary axes (with option 23)
Input range		Maximum 999 999 999 mm or 999 999 999°
Interpolation		Linear in 4 axes
		Circular in 2 axes
		Helical: superimposition of circular and straight paths
		Helical: superimposition of circular and straight paths
Block processing time		0.5 ms
3-D straight line without radius compensation		
Axis feedback control		Position loop resolution: Signal period of the position encoder/1024
		Cycle time of position controller: 3 ms
		Cycle time of speed controller: 200 µs
Range of traverse		Maximum 100 m (3937 inches)
Spindle speed		Maximum 100 000 rpm (analog speed command signal)
Error compensation	-	Linear and nonlinear axis error, backlash, reversal peaks during circular movements, thermal expansion
		Stick-slip friction
Data interfaces		One each RS-232-C /V.24 max. 115 kilobaud
		Expanded interface with LSV-2 protocol for external operation of the TNC over the interface with HEIDENHAIN software TNCremo
		Ethernet interface 1000 Base T
		3 x USB 2.0
Ambient temperature		Operation: 0 °C to +45 °C
		Storage: –30 °C to +70 °C

Accessories

Electronic handwheels		One HR 550 FS portable wireless handwheel with display or
		One HR 520 portable handwheel with display, or
		One HR 420 portable handwheel with display or
		One HR 410 portable handwheel, or
		One HR 130 panel-mounted handwheel, or
		Up to three HR 150 panel-mounted handwheels via HRA 110 handwheel adapter
Touch probes		TS 220: triggering 3-D touch probe with cable connection, or
		TS 440: 3-D touch trigger probe with infrared transmission
		TS 444: Battery-free 3-D touch trigger probe with infrared transmission
		TS 640: 3-D touch trigger probe with infrared transmission
	•	TS 740: High-precision 3-D touch trigger probe with infrared transmission
		TT 140: 3-D touch trigger probe for tool measurement
	•	TT 449: 3-D touch trigger probe for tool measurement with infrared transmission
Hardware, options		
		1st additional axis for 4 axes plus spindle
		2nd additional axis for 5 axes plus spindle
	_	
Software option 1 (option nu		
	nber (	)8)
Rotary table machining	mber (	<b>D8)</b> Programming of cylindrical contours as if in two axes
Software option 1 (option nur Rotary table machining Coordinate transformation Interpolation	mber (	<b>Programming of cylindrical contours as if in two axes</b> Feed rate in distance per minute
Rotary table machining Coordinate transformation Interpolation	mber (	Programming of cylindrical contours as if in two axesFeed rate in distance per minuteWorking plane, tilting theCircle in 3 axes with tilted working plane (spacial arc)
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur	mber (	Programming of cylindrical contours as if in two axesFeed rate in distance per minuteWorking plane, tilting theCircle in 3 axes with tilted working plane (spacial arc)
Rotary table machining Coordinate transformation	mber (	Programming of cylindrical contours as if in two axes Feed rate in distance per minute Working plane, tilting the Circle in 3 axes with tilted working plane (spacial arc)
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur	mber (	Programming of cylindrical contours as if in two axes         Feed rate in distance per minute         Working plane, tilting the         Circle in 3 axes with tilted working plane (spacial arc)         D9)         Motion control with minimum jerk         3-D tool compensation through surface normal vectors
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur	mber (	<ul> <li>Programming of cylindrical contours as if in two axes</li> <li>Feed rate in distance per minute</li> <li>Working plane, tilting the</li> <li>Circle in 3 axes with tilted working plane (spacial arc)</li> <li>Motion control with minimum jerk</li> <li>3-D tool compensation through surface normal vectors</li> <li>Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point.</li> </ul>
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur	mber (	Programming of cylindrical contours as if in two axes         Feed rate in distance per minute         Working plane, tilting the         Circle in 3 axes with tilted working plane (spacial arc) <b>D9</b> Motion control with minimum jerk         3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point.         (TCPM = Tool Center Point Management)         Keeping the tool normal to the contour
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur 3-D machining	mber (	Programming of cylindrical contours as if in two axes         Feed rate in distance per minute         Working plane, tilting the         Circle in 3 axes with tilted working plane (spacial arc)         D9)         Motion control with minimum jerk         3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point.         (TCPM = Tool Center Point Management)         Keeping the tool normal to the contour
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur	mber (	Programming of cylindrical contours as if in two axes         Feed rate in distance per minute         Working plane, tilting the         Circle in 3 axes with tilted working plane (spacial arc)         D9)         Motion control with minimum jerk         3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point.         (TCPM = Tool Center Point Management)         Keeping the tool normal to the contour         Tool radius compensation perpendicular to traversing and tool direction         Linear in 5 axes (subject to export permit)
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur 3-D machining	mber (	Programming of cylindrical contours as if in two axes         Feed rate in distance per minute         Working plane, tilting the         Circle in 3 axes with tilted working plane (spacial arc)         D9)         Motion control with minimum jerk         3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point.         (TCPM = Tool Center Point Management)         Keeping the tool normal to the contour         Tool radius compensation perpendicular to traversing and tool direction         Linear in 5 axes (subject to export permit)
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur 3-D machining	mber (	Programming of cylindrical contours as if in two axes         Feed rate in distance per minute         Working plane, tilting the         Circle in 3 axes with tilted working plane (spacial arc)         D9)         Motion control with minimum jerk         3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point.         (TCPM = Tool Center Point Management)         Keeping the tool normal to the contour         Tool radius compensation perpendicular to traversing and tool direction         Linear in 5 axes (subject to export permit)
Rotary table machining Coordinate transformation Interpolation Software option 2 (option nur 3-D machining Interpolation HEIDENHAIN DNC (option nur	mber (	Programming of cylindrical contours as if in two axes         Feed rate in distance per minute         Working plane, tilting the         Circle in 3 axes with tilted working plane (spacial arc)         D9)         Motion control with minimum jerk         3-D tool compensation through surface normal vectors         Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point.         (TCPM = Tool Center Point Management)         Keeping the tool normal to the contour         Tool radius compensation perpendicular to traversing and tool direction         Linear in 5 axes (subject to export permit)

### **19.3 Technical Information**

collision monitoring in all		The machine manufacturer defines objects to be monitored
nachine operating modes		Three warning levels in manual operation
	-	Program interrupt during automatic operation
	-	Includes monitoring of 5-axis movements
oftware option for additional	conv	ersational languages (option number 41)
dditional conversational		Slovenian
anguages	-	Norwegian
		Slovak
		Latvian
	-	Korean
	-	Estonian
	-	Turkish
	-	Romanian
	-	Lithuanian
OXF Converter software option	ı (opt	ion number 42)
xtracting contour		Supported DXF format: AC1009 (AutoCAD R12)
orograms and machining positions from DXF data.	-	For contours and point patterns
extracting contour sections	-	Simple and convenient specification of reference points
rom plain-language rograms.	•	Select graphical features of contour sections from conversational programs
	_	re option (option number 45)
Adaptive Feed Control (AFC) se	oftwa	
	oftwa	Recording the actual spindle power by means of a teach-in cut
Function for adaptive feed- ate control for optimizing		
unction for adaptive feed- ate control for optimizing he machining conditions		Recording the actual spindle power by means of a teach-in cut
Function for adaptive feed- rate control for optimizing the machining conditions during series production	:	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run
Function for adaptive feed- ate control for optimizing the machining conditions during series production KinematicsOpt software option	:	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run tion number 48)
Function for adaptive feed- rate control for optimizing the machining conditions during series production KinematicsOpt software option Fouch-probe cycles for automatic testing and	= = n (opt	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run tion number 48) Backup/restore active kinematics
Function for adaptive feed- rate control for optimizing the machining conditions during series production KinematicsOpt software option Fouch-probe cycles for automatic testing and optimization of the machine	n (opt	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run tion number 48)
Function for adaptive feed- ate control for optimizing he machining conditions luring series production KinematicsOpt software option Fouch-probe cycles for automatic testing and optimization of the machine kinematics	n (op	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run <b>tion number 48)</b> Backup/restore active kinematics Test active kinematics Optimize active kinematics
Function for adaptive feed- ate control for optimizing he machining conditions luring series production KinematicsOpt software option ouch-probe cycles for utomatic testing and optimization of the machine inematics	n (op	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run tion number 48) Backup/restore active kinematics Test active kinematics Optimize active kinematics
Function for adaptive feed- ate control for optimizing he machining conditions during series production KinematicsOpt software option fouch-probe cycles for automatic testing and optimization of the machine kinematics Mill-Turning software option (of functions for milling/turning	n (opt	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run tion number 48) Backup/restore active kinematics Test active kinematics Optimize active kinematics number 50) Switching between Milling/Turning mode of operation
Function for adaptive feed- rate control for optimizing the machining conditions during series production KinematicsOpt software option Fouch-probe cycles for automatic testing and optimization of the machine kinematics Will-Turning software option (of Functions for milling/turning	n (opt	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run tion number 48) Backup/restore active kinematics Test active kinematics Optimize active kinematics number 50) Switching between Milling/Turning mode of operation Constant cutting speed
Adaptive Feed Control (AFC) so Function for adaptive feed- rate control for optimizing the machining conditions during series production KinematicsOpt software option Touch-probe cycles for automatic testing and optimization of the machine kinematics Mill-Turning software option (of Functions for milling/turning mode	n (op Deption	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run <b>tion number 48)</b> Backup/restore active kinematics Test active kinematics Optimize active kinematics <b>number 50)</b> Switching between Milling/Turning mode of operation Constant cutting speed Tool-tip radius compensation
Function for adaptive feed- rate control for optimizing the machining conditions during series production KinematicsOpt software option Fouch-probe cycles for automatic testing and optimization of the machine kinematics Will-Turning software option (of Functions for milling/turning	n (opt	Recording the actual spindle power by means of a teach-in cut Defining the limits of automatic feed rate control Fully automatic feed control during program run <b>tion number 48)</b> Backup/restore active kinematics Test active kinematics Optimize active kinematics <b>number 50)</b> Switching between Milling/Turning mode of operation Constant cutting speed Tool-tip radius compensation Turning cycles

19

Remote Desktop Manager soft	ware	option (option number 133)
Remote operation of		Windows on a separate computer unit
external computer units (e.g. Windows PC) via the TNC user interface		Incorporated in the TNC interface
Cross Talk Compensation (CTC	) soft	ware option (option number 141)
Compensation of axis couplings	•	Determination of dynamically caused position deviation through axis acceleration
		Compensation of the TCP
Position Adaptive Control (PAC	:) sof	tware option (option number 142)
Changing control parameters	•	Changing of the control parameters depending on the position of the axes in the working space
	•	Changing of the control parameters depending on the speed or acceleration of an axis
Load Adaptive Control (LAC) se	oftwa	re option (option number 143)
Dynamic changing of control		Automatic determination of workpiece weight and frictional forces
parameters	•	Continuous adaptation of the parameters of the adaptive precontrolling to the actual weight of the workpiece during machining
Active Chatter Control (ACC) se	oftwa	are option (option number 145)

Fully automatic function for chatter control during machining

### **19.3 Technical Information**

Positions, coordinates, circle radii, chamfer lengths	-99 999.9999 to +99 999.9999 (5, 4: places before the decimal point, places after the decimal point) [mm]
Tool numbers	0 to 32 767.9 (5, 1)
Tool names	16 characters, enclosed by quotation marks with <b>TOOL CALL</b> . Permitted special characters: #, \$, %, &, -
Delta values for tool compensation	–99.9999 to +99.9999 (2, 4) [mm]
Spindle speeds	0 to 99 999.999 (5, 3) [rpm]
Feed rates	0 to 99 999.999 (5.3) [mm/min] or [mm/tooth] or [mm/rev]
Dwell time in Cycle 9	0 to 3600.000 (4, 3) [s]
Thread pitch in various cycles	–99.9999 to +99.9999 (2, 4) [mm]
Angle of spindle orientation	0 to 360.0000 (3, 4) [°]
Angle for polar coordinates, rotation, tilting the working plane	-360.0000 to 360.0000 (3, 4) [°]
Polar coordinate angle for helical interpolation (CP)	-5 400.0000 to 5 400.0000 (4, 4) [°]
Datum numbers in Cycle 7	0 to 2999 (4, 0)
Scaling factor in Cycles 11 and 26	0.000001 to 99.999999 (2, 6)
Miscellaneous functions M	0 to 999 (4, 0)
Q parameter numbers	0 to 1999 (4, 0)
Q parameter values	–99 999.9999 to +99 999.9999 (9, 6)
Surface-normal vectors N and T with 3-D compensation	-9.999999999 to +9.999999999 (1, 8)
Labels (LBL) for program jumps	0 to 999 (5, 0)
Labels (LBL) for program jumps	Any text string in quotes ("")
Number of program section repeats REP	1 to 65 534 (5, 0)
Error number with Q parameter function FN14	0 to 1199 (4, 0)

Overview tables 19.4
----------------------

### **19.4** Overview tables

### Fixed cycles

Cycle number	Cycle designation	DEF active	CALL e active
7	Datum shift		
8	Mirror image		
9	Dwell time		
10	Rotation		
11	Scaling factor		
12	Program call		
13	Spindle orientation		
14	Contour definition		
19	Tilting the working plane		
20	Contour data SL II		
21	Pilot drilling SL II		
22	Rough out SL II		
23	Floor finishing SL II		
24	Side finishing SL II		
25	Contour train		
26	Axis-specific scaling		
27	Cylinder surface		
28	Cylindrical surface slot		
29	Cylinder surface ridge		
32	Tolerance		
200	Drilling		
201	Reaming		
202	Boring		
203	Universal drilling		
204	Back boring		
205	Universal pecking		
206	Tapping with a floating tap holder, new		
207	Rigid tapping, new		
208	Bore milling		
209	Tapping with chip breaking		
220	Polar pattern		
221	Cartesian pattern		
230	Multipass milling		
231	Ruled surface		
232	Face milling		
240	Centering		-

#### **19.4 Overview tables**

Cycle number	Cycle designation	DEF active	CALL active
241	Single-lip deep-hole drilling		
247	Datum setting		
251	Rectangular pocket (complete machining)		
252	Circular pocket (complete machining)		
253	Slot milling		
254	Circular slot		
256	Rectangular stud (complete machining)		
257	Circular stud (complete machining)		
262	Thread milling		
263	Thread milling/countersinking		
264	Thread drilling/milling		
265	Helical thread drilling/milling		
267	Outside thread milling		

#### **Miscellaneous functions**

Μ	Effect Effectiv	e at block	Start	End	Page
M0	Program STOP/Spindle STOP/Coolant OFF				349
M1	Optional program run STOP/Spindle STOP/Coolant OFF				580
M2	Program run STOP/Spindle STOP/Coolant OFF/CLEAR status (depending on machine parameter)/Return jump to block 1	s display		-	349
M3	Spindle ON clockwise				349
M4 M5	Spindle ON counterclockwise Spindle STOP				
M6	Tool change/STOP program run (depending on machine para Spindle STOP	meter)/		-	349
<b>M8</b>	Coolant on				349
M9	Coolant off				
M13	Spindle ON clockwise /coolant ON				349
M14	Spindle ON counterclockwise/coolant on				
M30	Same function as M2				349
M89	Vacant miscellaneous function <b>or</b> cycle call, modally effective (depending on MPs)		•		Cycles Manual
M91	Within the positioning block: Coordinates are referenced to datum	machine	-		350
M92	Within the positioning block: Coordinates are referenced to defined by machine tool builder, such as tool change position				350
M94	Reduce the rotary axis display to a value below 360°				436
M97	Machine small contour steps				353
M98	Machine open contours completely				354
M99	Blockwise cycle call			-	Cycles Manual

М	Effect Effective at bloc	k Start	End	Page
M101	Automatic tool change with replacement tool if maximum tool life ha expired	S	•	175
M102	Reset M101			
	Suppress error message for replacement tools with oversize			175
M108	Reset M107			
M109	Constant contouring speed at cutting edge (feed rate increase and reduction)	-		357
	Constant contouring speed at cutting edge (only feed rate reduction)			
	Reset M109/M110			
	Feed rate in mm/min on rotary axes			434
	Reset M116			
M118	Superimpose handwheel positioning during program run			360
M120	Pre-calculate the radius-compensated contour (LOOK AHEAD)			358
M126	Shorter-path traverse of rotary axes:			435
M127	Reset M126			
M128	Maintaining the position of the tool tip when positioning with tilted a (TCPM)	xes 🔳		437
M129	Reset M128			
M130	Within the positioning block: Points are referenced to the untilted coordinate system			352
M138	Selection of tilted axes			440
M140	Retraction from the contour in the tool-axis direction			362
M143	Delete basic rotation			364
M144	Compensating the machine's kinematic configuration for ACTUAL/ NOMINAL positions at end of block			441
M145	Reset M144		-	
M141	Suppress touch probe monitoring			363
	Automatically retract tool from the contour at an NC stop Reset M148			365

**19.5** Functions of the TNC 640 and the iTNC 530 compared

# 19.5 Functions of the TNC 640 and the iTNC 530 compared

#### **Comparison: Specifications**

Function	TNC 640	iTNC 530
Axes	18 maximum	18 maximum
Input resolution and display step:		
Linear axes	<ul> <li>0.1μm, 0.01 μm</li> <li>with option 23</li> </ul>	■ 0.1 µm
<ul> <li>Rotary axes</li> </ul>	<ul> <li>0.001°, 0.00001°</li> <li>with option 23</li> </ul>	<ul> <li>0.0001°</li> </ul>
Control loops for high-frequency spindles and torque/linear motors	With option 49	With option 49
Display	19-inch TFT color flat-panel display	15.1-inch TFT color flat-panel display, optional: 19-inch TFT
Memory media for NC, PLC programs and system files	Hard disk	Hard disk
Program memory for NC programs	> 21 GB	> 21 GB
Block processing time	0.5 ms	0.5 ms
HeROS operating system	yes	yes
Windows XP operating system	no	Option
Interpolation:		
Straight line	5 axes	5 axes
Circle	<ul> <li>3 axes</li> </ul>	<ul> <li>3 axes</li> </ul>
Helix	yes	yes
Spline	■ no	Yes with option 9
Hardware	modular in electrical cabinet	Modular in electrical cabinet

#### **Comparison: Data interfaces**

Function	TNC 640	iTNC 530
Gigabit Ethernet 1000BaseT	Х	Х
RS-232-C/V.24 serial interface	Х	Х
RS-422/V.11 serial interface	-	Х
USB interface	X (USB 2.0)	X (USB 2.0)

#### **Comparison: Accessories**

Function	TNC 640	iTNC 530
Electronic handwheels		
HR 410	• X	■ X
HR 420	■ X	X
HR 520/530/550	■ X	X
HR 130	<b>•</b> X	X
HR 150 via HRA 110	■ X	X
Touch probes		
TS 220	• X	X
TS 440	■ X	X
TS 444	■ X	X
TS 449 / TT 449	■ X	• X
TS 640	■ X	• X
TS 740	■ X	• X
TT 130 / TT 140	<b>X</b>	X
Industrial PC IPC 61xx	_	Х

#### **Comparison: PC software**

Function	TNC 640	iTNC 530
Programming station software	Available	Available
<b>TNCremoNT</b> for data transfer with <b>TNCbackup</b> for data backup	Available	Available
<b>TNCremoPlus</b> data transfer software with "live" screen	Available	Available
<b>RemoTools SDK 1.2</b> : Function library for developing your own applications for communicating with HEIDENHAIN controls	Limited functionality available	Available
<b>virtualTNC</b> : Control component for virtual machines	Not available	Available
<b>ConfigDesign</b> : Software for configuring the control	Available	Not available
<b>TeleService</b> : Software for remote diagnostics and maintenance	Available	Available

#### **19.5** Functions of the TNC 640 and the iTNC 530 compared

#### **Comparison: Machine-specific functions**

Function	TNC 640	iTNC 530
Switching the traverse range	Function not available	Function available
Central drive (1 motor for multiple machine axes)	Function available	Function available
C-axis operation (spindle motor drives rotary axis)	Function available	Function available
Automatic exchange of milling head	Function not available	Function available
Support of angle heads	Function not available	Function available
Balluf tool identification	Function available (with Python)	Function available
Management of multiple tool magazines	Function available	Function available
Expanded tool management via Python	Function available	Function available

#### **Comparison: User functions**

Function	TNC 640	iTNC 530
Program entry		
HEIDENHAIN conversational	• X	X
DIN/ISO	■ X	X
With smarT.NC		■ X
With ASCII editor	<ul> <li>X, directly editable</li> </ul>	<ul> <li>X, editable after conversion</li> </ul>
Position entry		
<ul> <li>Nominal positions for lines and arcs in Cartesian coordinates</li> </ul>	■ X	• X
<ul> <li>Nominal positions for lines and arcs in polar coordinates</li> </ul>	■ X	■ X
<ul> <li>Incremental or absolute dimensions</li> </ul>	■ X	X
Display and entry in mm or inches	■ X	• X
<ul> <li>Set the last tool position as pole (empty CC block)</li> </ul>	<ul> <li>X (error message if pole transfer is ambiguous)</li> </ul>	■ X
<ul> <li>Surface normal vectors (LN)</li> </ul>	■ X	■ X
Spline blocks (SPL)	-	<ul> <li>X, with option 09</li> </ul>

Function	TNC 640	iTNC 530
Tool compensation		
In the working plane, and tool length	• X	X
<ul> <li>Radius compensated contour look ahead for up to 99 blocks</li> </ul>	• X	■ X
Three-dimensional tool radius compensation	<ul> <li>X, with option 09</li> </ul>	<ul> <li>X, with option 09</li> </ul>
Tool table		
<ul> <li>Central storage of tool data</li> </ul>	• X	■ X
<ul> <li>Multiple tool tables with any number of tools</li> </ul>	■ X	X
<ul> <li>Flexible management of tool types</li> </ul>	■ X	<b>—</b>
<ul> <li>Filtered display of selectable tools</li> </ul>	• X	<b>I</b> -
<ul> <li>Sorting function</li> </ul>	■ X	<b>—</b>
Column names	Sometimes with _	Sometimes with -
<ul> <li>Copy function: Overwriting relevant tool data</li> </ul>	■ X	X
Form view	<ul> <li>Switchover with split- screen layout key</li> </ul>	<ul> <li>Switchover by soft key</li> </ul>
<ul> <li>Exchange of tool table between TNC 640 and iTNC 530</li> </ul>	• X	<ul> <li>Not possible</li> </ul>
Touch-probe table for managing different 3-D touch probes	Х	_
Creating tool-usage file, checking the availability	Х	Х
<b>Cutting-data tables</b> : Automatic calculation of spindle speed and feed rate from saved technology tables	_	Х
Define any tables	<ul> <li>Freely definable tables (.TAB files)</li> </ul>	<ul> <li>Freely definable tables (.TAB files)</li> </ul>
	<ul> <li>Reading and writing with FN functions</li> </ul>	<ul> <li>Reading and writing with FN functions</li> </ul>
	<ul> <li>Definable via config. data</li> </ul>	
	<ul> <li>Table names must start with a letter</li> </ul>	
	<ul> <li>Reading and writing with SQL functions</li> </ul>	

Function	TNC 640	iTNC 530
<b>Constant contouring speed</b> : Relative to the path of the tool center or relative to the tool's cutting edge	Х	Х
<b>Parallel operation</b> : Creating programs while another program is being run	Х	Х
Programming of counter axes	Х	Х
Tilting the working plane (Cycle 19, PLANE function)	X, option #08	X, option #08
Machining with rotary tables		
<ul> <li>Programming of cylindrical contours as if in two axes</li> </ul>		
<ul> <li>Cylinder Surface (Cycle 27)</li> </ul>	<ul> <li>X, option #08</li> </ul>	<ul> <li>X, option #08</li> </ul>
<ul> <li>Cylinder Surface Slot (Cycle 28)</li> </ul>	<ul> <li>X, option #08</li> </ul>	<ul> <li>X, option #08</li> </ul>
<ul> <li>Cylinder Surface Ridge (Cycle 29)</li> </ul>	<ul> <li>X, option #08</li> </ul>	<ul> <li>X, option #08</li> </ul>
<ul> <li>Cylinder Surface External Contour (Cycle 39)</li> </ul>		<ul><li>X, option #08</li></ul>
Feed rate in mm/min or rev/min	<ul> <li>X, option #08</li> </ul>	<ul> <li>X, option #08</li> </ul>
Traverse in tool-axis direction		
<ul> <li>Manual operation (3-D ROT menu)</li> </ul>	• X	<ul> <li>X, FCL2 function</li> </ul>
<ul> <li>During program interruption</li> </ul>	X	• X
With handwheel superimpositioning	X	<ul> <li>X, option #44</li> </ul>
<b>Approaching and departing the contour</b> : Via a straight line or arc	Х	Х
Entry of feed rates:		
<b>F</b> (mm/min), rapid traverse <b>FMAX</b>	• X	■ X
<ul> <li>FU (feed per revolution mm/rev)</li> </ul>	■ X	• X
<b>FZ</b> (tooth feed rate)	• X	• X
FT (time in seconds for path)		• X
FMAXT (only for active rapid traverse pot: time in seconds for path)	. –	• X
FK free contour programming		
<ul> <li>Programming for workpiece drawings not dimensioned for NC programming</li> </ul>	■ X	• X
<ul> <li>Conversion of FK program to conversational dialog</li> </ul>	<b>I</b> -	• X
Program jumps:		
<ul> <li>Maximum number of label numbers</li> </ul>	<b>9999</b>	<b>1000</b>
<ul> <li>Subprograms</li> </ul>	• X	• X
Nesting depth for subprograms	<b>2</b> 0	<b>6</b>
<ul> <li>Program section repeats</li> </ul>	• X	■ X
Any desired program as subroutine	• X	• X

Function	TNC 640	iTNC 530
Q parameter programming:		
<ul> <li>Standard mathematical functions</li> </ul>	■ X	• X
Formula entry	■ X	• X
String processing	X	• X
Local Q parameters QL	■ X	• X
Nonvolatile Q parameters QR	■ X	• X
<ul> <li>Changing parameters during program interruption</li> </ul>	■ X	• X
FN15:PRINT	<b>—</b>	• X
FN25:PRESET		• X
FN26:TABOPEN	■ X	• X
FN27:TABWRITE	X	• X
FN28:TABREAD	■ X	• X
FN29: PLC LIST	■ X	
FN31: RANGE SELECT	<b>—</b>	• X
FN32: PLC PRESET	<b>—</b>	• X
FN37:EXPORT	• X	
FN38: SEND	<b>—</b>	• X
Saving file externally with FN16	<b>—</b>	• X
<ul> <li>FN16 formatting: Left-aligned, right-aligned, string lengths</li> </ul>	• -	■ X
Writing to LOG file with FN16	• X	
<ul> <li>Displaying parameter contents in the additional status display</li> </ul>	■ X	• -
<ul> <li>Displaying parameter contents during programming (Q-INFO)</li> </ul>	■ X	■ X
SQL functions for writing and reading tables	• X	• -

Function	TNC 640	iTNC 530
Graphic support		
2-D programming graphics	• X	• X
REDRAW function	-	<b>•</b> ×
<ul> <li>Show grid lines as the background</li> <li>3-D line graphics</li> <li>Test graphics (plan view, projection in 3 planes, 3-D</li> </ul>	• X • X • X	■ - ■ X ■ X
view)		
<ul> <li>High-resolution view</li> </ul>	• X	• X
Tool display	X	■ X
Set the simulation speed	• X	<b>•</b> ×
<ul> <li>Coordinates of line intersection for projection in 3 planes</li> </ul>		• X
<ul> <li>Expanded zoom functions (mouse operation)</li> </ul>	• X	■ X
<ul> <li>Displaying frame for workpiece blank</li> </ul>	• X	■ X
<ul> <li>Displaying the depth value in plan view during mouse-over</li> </ul>	• -	• X
<ul> <li>Targeted stop of test run (STOP AT N)</li> </ul>	<b>—</b>	■ X
<ul> <li>Consideration of tool change macro</li> </ul>	-	• X
<ul> <li>Program run graphics (plan view, projection in 3 planes, 3-D view)</li> </ul>	• X	■ X
<ul> <li>High-resolution view</li> </ul>	• X	• X

Function	TNC 640	iTNC 530
Datum tables: for storing workpiece-related datums	Х	Х
Preset table: for saving reference points (presets)	Х	Х
Pallet management		
<ul> <li>Support of pallet files</li> </ul>	• X	• X
Tool-oriented machining		■ X
Pallet preset table: for managing pallet datums	<b>—</b>	• X
Returning to the contour		
With mid-program startup	X	■ X
<ul> <li>After program interruption</li> </ul>	X	X
Autostart function	Х	Х
<b>Actual position capture</b> : Actual positions can be transferred to the NC program	Х	X
Enhanced file management		
<ul> <li>Creating multiple directories and subdirectories</li> </ul>	• X	• X
<ul> <li>Sorting function</li> </ul>	• X	■ X
<ul> <li>Mouse operation</li> </ul>	• X	• X
<ul> <li>Selection of target directory by soft key</li> </ul>	■ X	■ X
Programming aids:		
<ul> <li>Help graphics for cycle programming</li> </ul>	<ul> <li>X, can be switched off via config datum</li> </ul>	■ X
<ul> <li>Animated help graphics when PLANE/PATTERN DEF function is selected</li> </ul>	• -	X
Help graphics for PLANE/PATTERN DEF	• X	■ X
<ul> <li>Context-sensitive help function for error messages</li> </ul>	• X	X
TNCguide: Browser-based help system	• X	X
<ul> <li>Context-sensitive call of help system</li> </ul>	• X	• X
Calculator	<ul> <li>X (scientific)</li> </ul>	<ul> <li>X (standard)</li> </ul>
<ul> <li>Comment blocks in NC program</li> </ul>	• X	■ X
<ul> <li>Structure blocks in NC program</li> </ul>	• X	■ X
Structure view in test run	<b>—</b>	X
Dynamic Collision Monitoring (DCM):		
<ul> <li>Collision monitoring in Automatic operation</li> </ul>	<ul> <li>X, option #40</li> </ul>	<ul> <li>X, option #40</li> </ul>
<ul> <li>Collision monitoring in Manual operation</li> </ul>	<ul> <li>X, option #40</li> </ul>	<ul><li>X, option #40</li></ul>
<ul> <li>Graphic depiction of the defined collision objects</li> </ul>	<ul> <li>X, option #40</li> </ul>	<ul> <li>X, option #40</li> </ul>
<ul> <li>Collision checking in the Test Run mode</li> </ul>		<ul> <li>X, option #40</li> </ul>
<ul> <li>Fixture monitoring</li> </ul>		<ul><li>X, option #40</li></ul>
Tool carrier management	<b>—</b>	<ul> <li>X, option #40</li> </ul>

19

Function	TNC 640	iTNC 530
CAM support:		
Loading of contours from DXF data	<ul> <li>X, option #42</li> </ul>	<ul><li>X, option #42</li></ul>
Loading of machining positions from DXF data	<ul> <li>X, option #42</li> </ul>	<ul> <li>X, option #42</li> </ul>
<ul> <li>Offline filter for CAM files</li> </ul>		<b>X</b>
Stretch filter	■ X	
MOD functions:		
<ul> <li>User parameters</li> </ul>	<ul> <li>Config data</li> </ul>	<ul> <li>Numerical structure</li> </ul>
<ul> <li>OEM help files with service functions</li> </ul>		• X
Data medium inspection		<b>•</b> X
Load service packs	<b>—</b>	• X
<ul> <li>Setting the system time</li> </ul>	X	<b>•</b> X
<ul> <li>Select the axes for actual position capture</li> </ul>	<b>—</b>	• X
<ul> <li>Definition of traverse range limits</li> </ul>	<b>—</b>	• X
<ul> <li>Restricting external access</li> </ul>	• X	• X
Switching the kinematics	• X	• X
Calling fixed cycles:		
With M99 or M89	■ X	<b>•</b> X
With CYCL CALL	• X	<b>•</b> X
With CYCL CALL PAT	• X	<b>•</b> X
With CYC CALL POS	X	• X
Special functions:		
<ul> <li>Creating backward programs</li> </ul>		<b>•</b> X
Datum shift with TRANS DATUM	X	• X
<ul> <li>Adaptive Feed Control AFC</li> </ul>	<ul> <li>X, option #45</li> </ul>	<ul><li>X, option #45</li></ul>
<ul> <li>Global definition of cycle parameters: GLOBAL DEF</li> </ul>	X	<b>•</b> X
Pattern definition with PATTERN DEF	X	<b>•</b> X
<ul> <li>Definition and execution of point tables</li> </ul>	X	<b>•</b> X
Simple contour formula CONTOUR DEF	■ X	<b>•</b> X
Functions for large molds and dies:		
<ul> <li>Global program settings (GS)</li> </ul>		<ul> <li>X, option #44</li> </ul>
Expanded M128: FUNCTION TCPM	• X	<b>•</b> X
Status displays:		
<ul> <li>Positions, spindle speed, feed rate</li> </ul>	X	■ X
<ul> <li>Larger depiction of position display, Manual Operation</li> </ul>	X	• X
<ul> <li>Additional status display, form view</li> </ul>	X	• X
<ul> <li>Display of handwheel traverse when machining with handwheel superimposition</li> </ul>	■ X	■ X
<ul> <li>Display of distance-to-go in a tilted system</li> </ul>		• X
<ul> <li>Dynamic display of Q-parameter contents, definable number ranges</li> </ul>	■ X	• -
<ul> <li>OEM-specific additional status display via Python</li> </ul>	• X	<b>•</b> X
Graphic display of residual run time		<b>•</b> X
Individual color settings of user interface	_	Х

#### **Comparison: Cycles**

Cycle	<b>TNC 640</b>	iTNC 530
1, pecking	Х	Х
2, tapping	Х	Х
3, slot milling	Х	Х
4, pocket milling	Х	Х
5, circular pocket	Х	Х
6, rough out (SL I, recommended: SL II, Cycle 22)	_	Х
7, datum shift	Х	Х
8, mirror image	Х	Х
9, dwell time	Х	Х
10, rotation	Х	Х
11, scaling	Х	Х
12, program call	Х	Х
13, oriented spindle stop	Х	Х
14, contour definition	Х	Х
15, pilot drilling (SL I, recommended: SL II, Cycle 21)	_	Х
16, contour milling (SL I, recommended: SL II, Cycle 24)	_	Х
17, tapping (controlled spindle)	Х	Х
18, thread cutting	Х	Х
19, working plane	X, option #08	X, option #08
20, contour data	Х	Х
21, pilot drilling	Х	Х
22, rough-out:	Х	Х
Parameter Q401, feed rate factor		<b>•</b> X
Parameter Q404, fine roughing strategy		• X
23, floor finishing	Х	Х
24, side finishing	Х	Х
25, contour train	Х	Х
26, axis-specific scaling factor	Х	Х
27, contour surface	X, option #08	X, option #08
28, cylinder surface	X, option #08	X, option #08
29, cylinder surface ridge	X, option #08	X, option #08
30, run 3-D data	_	Х
32, tolerance with HSC mode and TA	Х	Х
39, cylinder surface external contour	_	X, option #08
200, drilling	Х	Х
201, reaming	Х	Х
202, boring	Х	Х
203, universal drilling	Х	Х
204, back boring	Х	Х

Cycle	<b>TNC 640</b>	iTNC 530
205, universal pecking	Х	Х
206, tapping with floating tap holder	Х	Х
207, rigid tapping, new	Х	Х
208, bore milling	Х	Х
209, tapping with chip breaking	Х	Х
210, slot with reciprocating plunge	Х	Х
211, circular slot	Х	Х
212, rectangular pocket finishing	Х	Х
213, rectangular stud finishing	Х	Х
214, circular pocket finishing	Х	Х
215, circular stud finishing	Х	Х
220, circular pattern	Х	Х
221, linear pattern	Х	Х
225, engraving	Х	Х
230, multipass milling	Х	Х
231, ruled surface	Х	Х
232, face milling	Х	Х
240, centering	Х	Х
241, single-lip deep-hole drilling	Х	Х
247, datum setting	Х	Х
251, rectangular pocket (complete)	Х	Х
252, circular pocket (complete)	Х	Х
253, slot (complete)	Х	Х
254, circular slot (complete)	Х	Х
256, rectangular stud (complete)	Х	Х
257, circular stud (complete)	Х	Х
262, thread milling	Х	Х
263, thread milling/countersinking	Х	Х
264, thread drilling/milling	Х	Х
265, helical thread drilling/milling	Х	Х
267, outside thread milling	Х	Х
270, contour train data for defining the behavior of Cycle 25	_	Х
275, trochoidal milling	_	Х
276, 3-D contour train	_	Х
290, interpolation turning	_	X, option #96
800, Adapt rotary coordinate system	Х	_
801, Reset rotary coordinate system	Х	_
810, Turn contour, longitudinal	Х	_
811, Turn shoulder, longitudinal	Х	_
812, Turn shoulder, longitudinal extended	Х	

Cycle	TNC 640	iTNC 530
813, Turn, longitudinal plunge	Х	_
814, Turn, longitudinal plunge extended	Х	_
815, Turn contour-parallel	Х	_
820, Turn contour, transverse	Х	_
821, Turn shoulder face	Х	_
822, Turn shoulder face extended	Х	_
823, Turn, transverse plunge	Х	_
824, Turn, transverse plunge extended	Х	_
830, Thread, contour-parallel	Х	_
831, Thread, longitudinal	Х	_
832, Thread, extended	Х	_
840, Recessing contour, radial	Х	_
841, Recessing simple, radial	Х	_
842, Recessing, radial extended	Х	_
850, Recessing contour, axial	Х	_
851, Recessing simple axial	Х	_
852, Recessing axial extended	Х	_
860, Recessing contour, radial	Х	_
861, Recessing, radial	Х	_
862, Recessing, radial extended	Х	_
870, Recessing contour, axial	Х	_
871, Recessing, axial	Х	_
872, Recessing, axial extended	Х	_

#### Comparison: Miscellaneous functions

Μ	Effect	TNC 640	iTNC 530
M00	Program STOP/Spindle STOP/Coolant OFF	Х	Х
M01	Optional program STOP	Х	Х
M02	Program run STOP/Spindle STOP/Coolant OFF/CLEAR status display (depending on machine parameter)/Return jump to block 1	Х	X
<b>M03</b> M04 M05	Spindle ON clockwise Spindle ON counterclockwise Spindle STOP	Х	Х
M06	Tool change/Stop program run (machine-dependent function)/ Spindle STOP	Х	Х
<b>M08</b> M09	Coolant on Coolant off	Х	Х
<b>M13</b> M14	Spindle ON clockwise /coolant ON Spindle ON counterclockwise/coolant on	Х	Х
M30	Same function as M02	Х	Х

Μ	Effect	TNC 640	iTNC 530
M89	Vacant miscellaneous function <b>or</b> cycle call, modally effective (machine-dependent function)	Х	Х
M90	Constant contouring speed at corners (not required at TNC 640)	_	Х
M91	Within the positioning block: Coordinates are referenced to machine datum	Х	Х
M92	Within the positioning block: Coordinates are referenced to position defined by machine tool builder, such as tool change position	Х	Х
M94	Reduce the rotary axis display to a value below 360°	Х	Х
M97	Machine small contour steps	Х	Х
M98	Machine open contours completely	Х	Х
M99	Blockwise cycle call	Х	Х
<b>M101</b> M102	Automatic tool change with replacement tool if maximum tool life has expired Reset M101	Х	Х
M103	Reduce feed rate during plunging to factor F (percentage)	Х	Х
M104	Reactivate most recently set datum	_	Х
<b>M105</b> M106	Machining with second k <sub>v</sub> factor Machining with first k <sub>v</sub> factor	-	Х
<b>M107</b> M108	Suppress error message for replacement tools with oversize Reset M107	Х	Х
<b>M109</b> M110 M111	Constant contouring speed at cutting edge (feed rate increase and reduction) Constant contouring speed at cutting edge (only feed rate reduction) Reset M109/M110	Х	Х
<b>M112</b> M113	Enter contour transition between two contour elements Reset M112	– (recommended: Cycle 32)	X
<b>M114</b> M115	Automatic compensation of machine geometry when working with tilted axes Reset M114	– (recommended: M128, TCPM)	X, option #08
<b>M116</b> M117	Feed rate on rotary tables in mm/min Reset M116	X, option #08	X, option #08
M118	Superimpose handwheel positioning during program run	Х	Х
M120	Pre-calculate the radius-compensated contour (LOOK AHEAD)	Х	Х
M124	Contour filter	– (possible via user parameters)	Х
<b>M126</b> M127	Shorter-path traverse of rotary axes: Reset M126	Х	Х
<b>M128</b> M129	Maintaining the position of the tool tip when positioning with tilted axes (TCPM) Reset M128	X, option #09	X, option #09
M130	Within the positioning block: Points are referenced to the untilted coordinate system	Х	Х

М	Effect	<b>TNC 640</b>	iTNC 530
M134	Exact stop at nontangential contour transitions when positioning with rotary axes	_	Х
M135	Reset M134		
<b>M136</b> M137	Feed rate F in millimeters per spindle revolution Reset M136	Х	Х
M138	Selection of tilted axes	Х	Х
M140	Retraction from the contour in the tool-axis direction	Х	Х
M141	Suppress touch probe monitoring	Х	Х
M142	Delete modal program information	_	Х
M143	Delete basic rotation	Х	Х
M144	Compensating the machine's kinematic configuration for ACTUAL/NOMINAL positions at end of block	X, option #09	X, option #09
M145	Reset M144		
<b>M148</b> M149	Automatically retract tool from the contour at an NC stop Reset M148	Х	Х
M150	Suppress limit switch message	– (possible via FN 17)	Х
M197	Rounding the corners	Х	_
M200 -M204	Laser cutting functions	-	Х

## **Comparison: Touch probe cycles in the Manual Operation and El. Handwheel modes**

Cycle	TNC 640	iTNC 530
Touch-probe table for managing 3-D touch probes	Х	_
Calibrating the effective length	Х	Х
Calibrating the effective radius	Х	Х
Measuring a basic rotation using a line	Х	Х
Set the datum in any axis	Х	Х
Setting a corner as datum	Х	Х
Setting a circle center as datum	Х	Х
Setting a center line as datum	Х	Х
Measuring a basic rotation using two holes/cylindrical studs	Х	Х
Setting the datum using four holes/cylindrical studs	Х	Х
Setting the circle center using three holes/cylindrical studs	Х	Х
Support of mechanical touch probes by manually capturing the current position	By soft key	By hard key
Writing measured values in preset table	Х	Х
Writing measured values in datum tables	Х	Х

19

# Comparison: Touch probe cycles for automatic workpiece inspection

Cycle	<b>TNC 640</b>	iTNC 530
0, reference plane	Х	Х
1, polar datum	Х	Х
2, calibrating TS	_	Х
3, measuring	Х	Х
4, measuring in 3-D	_	Х
9, calibrating TS length	_	Х
30, calibrating TT	Х	Х
31, measuring tool length	Х	Х
32, measuring tool radius	Х	Х
33, measuring tool length and radius	Х	Х
400, basic rotation	Х	Х
401, basic rotation from two holes	Х	Х
402, basic rotation from two studs	Х	Х
403, compensating a basic rotation via a rotary axis	Х	Х
404, setting a basic rotation	Х	Х
405, compensating workpiece misalignment by rotating the C axis	Х	Х
408, slot center datum	Х	Х
409, ridge center datum	Х	Х
410, datum from inside of rectangle	Х	Х
411, datum from outside of rectangle	Х	Х
412, datum from inside of circle	Х	Х
413, datum from outside of circle	Х	Х
414, datum at outside corner	Х	Х
415, datum at inside corner	Х	Х
416, datum at circle center	Х	Х
417, datum in touch probe axis	Х	Х
418, datum at center of 4 holes	Х	Х
419, datum in one axis	Х	Х
420, measuring an angle	Х	Х
421, measuring a hole	Х	Х
422, measuring a circle from outside	Х	Х
423, measuring a rectangle from inside	Х	Х
424, measuring a rectangle from outside	Х	Х
425, measuring inside width	Х	Х
426, measuring a ridge from outside	Х	Х
427, boring	Х	Х
430, measuring a bolt hole circle	Х	Х
431, measuring a plane	Х	Х

Cycle	<b>TNC 640</b>	iTNC 530
440, measuring an axis shift	_	Х
441, Rapid probing (on TNC 640 partly possible with touch probe table)	-	Х
450, saving the kinematics	X, option 48	X, option 48
451, measuring the kinematics	X, option 48	X, option 48
452, preset compensation	X, option 48	X, option 48
460, calibrating a TS on a sphere	Х	Х
461, calibrate TS length	Х	Х
462, calibration in a ring	Х	Х
463, calibration on stud	Х	Х
480, calibrating a TT	Х	Х
481, measuring/inspecting the tool length	Х	Х
482, measuring/inspecting the tool radius	Х	Х
483, measuring/inspecting the tool length and radius	Х	Х
484, calibrating the infrared TT	Х	Х

#### **Comparison: Differences in programming**

Function	TNC 640	iTNC 530
Switching the operating mode while a block is being edited	Not permitted	Permitted
File handling:		
Save file function	<ul> <li>Available</li> </ul>	<ul> <li>Available</li> </ul>
Save file as function	<ul> <li>Available</li> </ul>	<ul> <li>Available</li> </ul>
Discard changes	Available	<ul> <li>Available</li> </ul>
File management:		
<ul> <li>Mouse operation</li> </ul>	<ul> <li>Available</li> </ul>	<ul> <li>Available</li> </ul>
<ul> <li>Sorting function</li> </ul>	<ul> <li>Available</li> </ul>	<ul> <li>Available</li> </ul>
<ul> <li>Entry of name</li> </ul>	<ul> <li>Opens the Select file pop-up window</li> </ul>	<ul> <li>Synchronizes the cursor</li> </ul>
<ul> <li>Support of shortcuts</li> </ul>	<ul> <li>Not available</li> </ul>	<ul> <li>Available</li> </ul>
<ul> <li>Favorites management</li> </ul>	<ul> <li>Not available</li> </ul>	<ul> <li>Available</li> </ul>
<ul> <li>Configuration of column structure</li> </ul>	<ul> <li>Not available</li> </ul>	<ul> <li>Available</li> </ul>
Soft-key arrangement	<ul> <li>Slightly different</li> </ul>	<ul> <li>Slightly different</li> </ul>
Skip block function	Available	Available
Selecting a tool from the table	Selection via split-screen menu	Selection in a pop-up window
Programming special functions with the SPEC FCT key	Pressing the key opens a soft-key row as a submenu. To exit the submenu, press the SPEC FCT key again; then the TNC shows the last active soft-key row	Pressing the key adds the soft-key row as the last row. To exit the menu, press the SPEC FCT key again; then the TNC shows the last active soft-key row

19

Function	TNC 640	iTNC 530
Programming approach and departure motions with the APPR DEP key	Pressing the key opens a soft-key row as a submenu. To exit the submenu, press the APPR DEP key again; then the TNC shows the last active soft-key row	Pressing the key adds the soft-key row as the last row. To exit the menu, press the APPR DEP key again; then the TNC shows the last active soft-key row
Pressing the END hard key while the CYCLE DEF and TOUCH PROBE menus are active	Terminates the editing process and calls the file manager	Exits the respective menu
Calling the file manager while the <b>CYCLE DEF</b> and <b>TOUCH PROBE</b> menus are active	Terminates the editing process and calls the file manager. The respective soft-key row remains selected when the file manager is exited	Error message <b>Key non-</b> functional
Calling the file manager while CYCL CALL, SPEC FCT, PGM CALL and APPR/DEP menus are active	Terminates the editing process and calls the file manager. The respective soft-key row remains selected when the file manager is exited	Terminates the editing process and calls the file manager. The basic soft-key row is selected when the file manager is exited

Function	TNC 640	iTNC 530
Datum table:		
<ul> <li>Sorting function by values within an axis</li> </ul>	<ul> <li>Available</li> </ul>	<ul> <li>Not available</li> </ul>
Resetting the table	<ul> <li>Available</li> </ul>	<ul> <li>Not available</li> </ul>
<ul> <li>Hiding axes that are not present</li> </ul>	<ul> <li>Available</li> </ul>	<ul> <li>Available</li> </ul>
Switching the list/form view	<ul> <li>Switchover via split-screen key</li> </ul>	<ul> <li>Switchover by toggle soft key</li> </ul>
<ul> <li>Inserting individual line</li> </ul>	<ul> <li>Allowed everywhere, renumbering possible after request. Empty line is inserted, must be filled with zeros manually</li> </ul>	<ul> <li>Only allowed at end of table. Line with value 0 in all columns is inserted</li> </ul>
<ul> <li>Transfer of actual position values in individual axis to the datum table per keystroke</li> </ul>	Not available	<ul> <li>Available</li> </ul>
<ul> <li>Transfer of actual position values in all active axes to the datum table per keystroke</li> </ul>	<ul> <li>Not available</li> </ul>	<ul> <li>Available</li> </ul>
<ul> <li>Using a key to capture the last positions measured by TS</li> <li>FK free contour programming:</li> </ul>	<ul> <li>Not available</li> </ul>	<ul> <li>Available</li> </ul>
<ul> <li>Programming of parallel axes</li> </ul>	<ul> <li>With X/Y coordinates, independent of machine type; switchover with FUNCTION PARAXMODE</li> </ul>	<ul> <li>Machine-dependent with the existing parallel axes</li> </ul>
<ul> <li>Automatic correction of relative references</li> </ul>	<ul> <li>Relative references in contour subprograms are not corrected automatically</li> </ul>	<ul> <li>All relative references are corrected automatically</li> </ul>
Handling of error messages:		
<ul> <li>Help with error messages</li> </ul>	<ul> <li>Call via ERR key</li> </ul>	<ul> <li>Call via HELP key</li> </ul>
<ul> <li>Switching the operating mode while help menu is active</li> </ul>	<ul> <li>Help menu is closed when the operating mode is switched</li> </ul>	<ul> <li>Operating mode switchover is not allowed (key is non- functional)</li> </ul>
<ul> <li>Selecting the background operating mode while help menu is active</li> </ul>	<ul> <li>Help menu is closed when F12 is used for switching</li> </ul>	<ul> <li>Help menu remains open when F12 is used for switching</li> </ul>
<ul> <li>Identical error messages</li> </ul>	<ul> <li>Are collected in a list</li> </ul>	<ul> <li>Are displayed only once</li> </ul>
<ul> <li>Acknowledgment of error messages</li> </ul>	<ul> <li>Every error message (even if it is displayed more than once) must be acknowledged, the Delete all function is available</li> </ul>	<ul> <li>Error message to be acknowledged only once</li> </ul>
<ul> <li>Access to protocol functions</li> </ul>	<ul> <li>Log and powerful filter functions (errors, keystrokes) are available</li> </ul>	<ul> <li>Complete log without filter functions available</li> </ul>
<ul> <li>Saving service files</li> </ul>	<ul> <li>Available. No service file is created when the system crashes</li> </ul>	<ul> <li>Available. A service file is automatically created when the system crashes</li> </ul>

Function	TNC 640	iTNC 530
Find function:		
<ul> <li>List of words recently searched for</li> </ul>	<ul> <li>Not available</li> </ul>	<ul> <li>Available</li> </ul>
Show elements of active block	<ul> <li>Not available</li> </ul>	<ul> <li>Available</li> </ul>
<ul> <li>Show list of all available NC blocks</li> </ul>	Not available	<ul> <li>Available</li> </ul>
Starting the find function with the up/down arrow keys when highlight is on a block	Works with max. 9999 blocks, can be set via config datum	No limitation regarding program length
Programming graphics:		
<ul> <li>True-to-scale display of grid</li> </ul>	Available	<ul> <li>Not available</li> </ul>
<ul> <li>Editing contour subprograms in SLII cycles with AUTO DRAW ON</li> </ul>	If error messages occur, the cursor is on the CYCL CALL block in the main program	<ul> <li>If error messages occur, the cursor is on the error- causing block in the contour subprogram</li> </ul>
Moving the zoom window	<ul> <li>Repeat function not available</li> </ul>	<ul> <li>Repeat function available</li> </ul>
Programming minor axes:		
Syntax FUNCTION PARAXCOMP: Define the behavior of the display and the paths of traverse	<ul> <li>Available</li> </ul>	<ul> <li>Not available</li> </ul>
Syntax FUNCTION PARAXMODE: Define the assignment of the parallel axes to be traversed	<ul> <li>Available</li> </ul>	<ul> <li>Not available</li> </ul>
Programming OEM cycles		
<ul> <li>Access to table data</li> </ul>	<ul> <li>Via SQL commands and via FN17/FN18 or TABREAD-TABWRITE functions</li> </ul>	<ul> <li>Via FN17/FN18 or TABREAD-TABWRITE functions</li> </ul>
<ul> <li>Access to machine parameters</li> </ul>	With the CFGREAD function	Via FN18 functions
<ul> <li>Creating interactive cycles with CYCLE QUERY, e.g. touch-probe cycles in Manual Operation mode</li> </ul>	<ul> <li>Available</li> </ul>	<ul> <li>Not available</li> </ul>

### Comparison: Differences in Test Run, functionality

Function	TNC 640	iTNC 530
Test Run up to block N	Function not available	Function available
Calculation of machining time	Each time the simulation is repeated by pressing the START soft key, the machining time is totaled	Each time the simulation is repeated by pressing the START soft key, time calculation starts at 0

#### **Comparison: Differences in Test Run, operation**

Function	TNC 640	iTNC 530
Arrangement of soft-key rows and soft keys within the rows	Arrangement of soft-key rows and active screen layout.	soft-keys varies depending on the
Zoom function	Each sectional plane can be selected by individual soft keys	Sectional plane can be selected via three toggle soft keys
Machine-specific miscellaneous functions M	Lead to error messages if they are not integrated in the PLC	Are ignored during Test Run
Displaying/editing the tool table	Function available via soft key	Function not available

#### **Comparison: Differences in Manual Operation, functionality**

Function	TNC 640	iTNC 530
Manual probing cycles in the tilted working plane (3DROT: Active)	Manual probing cycles in the tilted working plane can only be used if 3D-ROT for <b>Manual</b> and <b>Automatic</b> operating modes is set to "Active".	Manual probing cycles in the tilted working plane can only be used if 3D-ROT for <b>Manual</b> operating mode is set to "Active".
Jog increment function	The jog increment can be defined separately for linear and rotary axes	The jog increment applies for both linear and rotary axes

### 19.5 Functions of the TNC 640 and the iTNC 530 compared

Function	TNC 640	iTNC 530
Preset table	Basic transformation (translation and rotation) of machine table system to workpiece system via the columns X, Y and Z, as well as spatial angles SPA, SPB and SPC. In addition, the columns X_OFFS to W_OFFS can be used to define the axis offset of each individual axis. The function of the axis offsets can be configured.	Basic transformation (translation ) of machine table system to workpiece system via the columns X, Y and Z, as well as a <b>ROT</b> basic rotation in the working plane (rotation). In addition, the columns A to W can be used to define datums in the rotary and parallel axes.
Behavior during presetting	Presetting in a rotary axis has the same effect as an axis offset. The offset is also effective for kinematics calculations and for tilting the working plane. The machine parameter <b>CfgAxisPropKinn-</b> <b>&gt;presetToAlignAxis</b> is used to define whether the axis offset is to be taken into account internally after zero setting. Independently of this, an axis offset has always the following effects:	Rotary axis offsets defined by machine parameters do not influence the axis positions that were defined in the Tilt working plane function. MP7500 bit 3 defines whether the current rotary axis position referenced to the machine datum is taken into account, or whether a position of 0° is assumed for the first rotary axis (usually the C axis).
	<ul> <li>An axis offset always influences the nominal position display of the affected axis (the axis offset is subtracted from the current axis value).</li> <li>If a rotary axis coordinate is programmed in an L block, then the axis offset is added to the programmed coordinate.</li> </ul>	
Handling of preset table:		
<ul> <li>Editing the preset table in the Programming mode of operation</li> </ul>	<ul> <li>Possible</li> </ul>	<ul> <li>Not possible</li> </ul>
<ul> <li>Preset tables that depend on the range of traverse</li> </ul>	<ul> <li>Not available</li> </ul>	<ul> <li>Available</li> </ul>
Definition of feed-rate limitation	Feed-rate limitation can be	Only one feed-rate limitation can

defined separately for linear and

rotary axes

be defined for linear and rotary

axes

# **Comparison: Differences in Manual Operation**, operation

Function	TNC 640	iTNC 530
Capturing the position values from mechanical probes	Actual-position capture by soft key	Actual-position capture by hard key
Exiting the touch probe functions menu	Only via the END soft key	Via the END soft key or the END hard key
Exit the preset table	Only through the BACK/END soft keys	Through the END hard key at any time
Multiple editing of tool table TOOL.T, or pocket table tool_p.tch	Soft-key row that was last active before exiting is active	Permanently defined soft-key row (soft-key row 1) is displayed

### Comparison: Differences in Program Run, operation

Function	TNC 640	iTNC 530
Arrangement of soft-key rows and soft keys within the rows	Arrangement of soft-key rows and s active screen layout.	oft-keys varies depending on the
Operating-mode switchover after program run was interrupted by switching to the Single Block mode of operation, and canceled by <b>INTERNAL STOP</b>	When you return to the Program Run mode of operation: Error message <b>Selected block not</b> <b>addressed</b> . Use mid-program startup to select the point of interruption	Switching the operating mode is allowed, modal information is saved, program run can be continued by pressing NC start
GOTO is used to go to FK sequences after program run was interrupted there before switching the operating mode	Error message <b>FK programming:</b> Undefined starting position	GOTO allowed
Mid-program startup:		
<ul> <li>Behavior after restoring the machine status</li> </ul>	<ul> <li>The menu for returning must be selected with the RESTORE POSITION soft key</li> </ul>	<ul> <li>Menu for returning is selected automatically</li> </ul>
<ul> <li>Completing positioning for mid- program startup</li> </ul>	<ul> <li>After position has been reached, positioning mode must be exited with the RESTORE POSITION soft key</li> </ul>	The positioning mode is automatically exited after the position has been reached
<ul> <li>Switching the screen layout for mid-program startup</li> </ul>	<ul> <li>Only possible, if startup position has already been approached</li> </ul>	<ul> <li>Possible in all operating states</li> </ul>
Error messages	Error messages are still active after the error has been corrected and must be acknowledged separately	Error messages are sometimes acknowledged automatically after the error has been corrected

T

# Comparison: Differences in Program Run, traverse movements

#### Caution: Check the traverse movements!

NC programs that were created on earlier TNC controls may lead to different traverse movements or error messages on a TNC 640!

Be sure to take the necessary care and caution when running-in programs!

Please find a list of known differences below. The list does not pretend to be complete!

Function	TNC 640	iTNC 530
Handwheel-superimposed traverse with M118	Effective in the active coordinate system (which may also be rotated or tilted), or in the machine-based coordinate system, depending on the setting in the 3-D ROT menu for manual operation	Effective in the machine-based coordinate system
Approach/Departure with <b>APPR/DEP</b> , <b>R0</b> is active, contour element plane is not equal to working plane	If possible, the blocks are executed in the defined <b>contour</b> <b>element plane</b> , error message for <b>APPRLN</b> , <b>DEPLN</b> , <b>APPRCT</b> , <b>DEPCT</b>	If possible, the blocks are executed in the defined <b>working</b> <b>plane</b> ; error message for <b>APPRLN, APPRLT, APPRCT</b> , <b>APPRLCT</b>
Scaling approach/departure movements ( <b>APPR/DEP/RND</b> )	Axis-specific scaling factor is allowed, radius is not scaled	Error message
Approach/departure with APPR/DEP	Error message if <b>R0</b> is programmed for <b>APPR/DEP LN</b> or <b>APPR/DEP CT</b>	Tool radius 0 and compensation direction <b>RR</b> are assumed
Approach/departure with <b>APPR/DEP</b> if contour elements with length 0 are defined	Contour elements with length 0 are ignored. The approach/ departure movements are calculated for the first or last valid contour element	An error message is issued if a contour element with length 0 is programmed after the <b>APPR</b> block (relative to the first contour point programmed in the APPR block)
		For a contour element with length 0 before a <b>DEP</b> block, the TNC does not issue an error message, but uses the last valid contour element to calculate the departure movement

### **Functions of the TNC 640 and the iTNC 530 compared 19.5**

Function	TNC 640	iTNC 530
Effect of Q parameters	<b>Q60</b> to <b>Q99</b> (or <b>QS60</b> to <b>QS99</b> ) are always local	<b>Q60</b> to <b>Q99</b> (or <b>QS60</b> to <b>QS99</b> ) are local or global, depending on MP7251 in converted cycle programs (.cyc). Nested calls may cause problems
Automatic cancelation of tool radius compensation	<ul> <li>Block with R0</li> <li>DEP block</li> <li>END PGM</li> </ul>	<ul> <li>Block with R0</li> <li>DEP block</li> <li>PGM CALL</li> <li>Programming of Cycle 10 ROTATION</li> <li>Program selection</li> </ul>
NC blocks with M91	No consideration of tool radius compensation	Consideration of tool radius compensation
Tool shape compensation	Tool shape compensation is not supported, because this type of programming is considered to be axis-value programming, and the basic assumption is that axes do not form a Cartesian coordinate system	Tool shape compensation is supported
Mid-program startup in a point table	The tool is positioned above the next position to be machined	The tool is positioned above the last position that has been completely machined
Empty <b>CC</b> block (pole of last tool position is used) in NC program	Last positioning block in the working plane must contain both coordinates of the working plane	Last positioning block in the working plane does not necessarily need to contain both coordinates of the working plane. Can cause problems with <b>RND</b> or <b>CHF</b> blocks
Axis-specific scaling of <b>RND</b> block	<b>RND</b> block is scaled, the result is an ellipse	Error message is issued
Reaction if a contour element with length 0 is defined before or after a <b>RND</b> or <b>CHF</b> block	Error message is issued	Error message is issued if a contour element with length 0 is located before the <b>RND</b> or <b>CHF</b> block
		Contour element with length 0 is ignored if the contour element with length 0 is located after the <b>RND</b> or <b>CHF</b> block

## **19.5 Functions of the TNC 640 and the iTNC 530 compared**

Function	TNC 640	iTNC 530
Circle programming with polar coordinates	The incremental rotation angle IPA and the direction of rotation DR must have the same sign. Otherwise, an error message will be issued	The algebraic sign of the direction of rotation is used if the sign defined for <b>DR</b> differs from the one defined for <b>IPA</b>
Tool radius compensation on circular arc or helix with angular length = 0	The transition between the adjacent elements of the arc/helix is generated. Also, the tool axis motion is executed right before this transition. If the element is the first or last element to be corrected, the next or previous element is dealt with in the same way as the first or last element to be corrected	The equidistant line of the arc/ helix is used for generating the tool path
Compensation of tool length in the position display	The values <b>L</b> and <b>DL</b> from the tool table and the value <b>DL</b> from the <b>TOOL CALL</b> are taken into account in the position display	The values <b>L</b> and <b>DL</b> from the tool table are taken into account in the position display
Traverse movement in spacial arc	Error message is issued	No restrictions
SLII Cycles 20 to 24:		
<ul> <li>Number of definable contour elements</li> </ul>	<ul> <li>Max. 16384 blocks in up to 12 subcontours</li> </ul>	<ul> <li>Max. 8192 contour elements in up to 12 subcontours, no restrictions for subcontour</li> </ul>
<ul> <li>Define the working plane</li> </ul>	<ul> <li>Tool axis in TOOL CALL block defines the working plane</li> </ul>	<ul> <li>The axes of the first positioning block in the first subcontour define the working plane</li> </ul>
<ul> <li>Position at end of SL cycle</li> </ul>	End position = clearance height above the last position that is defined before the cycle call	<ul> <li>With MP7420, you can define whether the end position is above the last programmed position, or whether the tool moves only to clearance height</li> </ul>

### Functions of the TNC 640 and the iTNC 530 compared 19.5

Function	TNC 640	iTNC 530
SLII Cycles 20 to 24:		
<ul> <li>Handling of islands which are not contained in pockets</li> <li>Set operations for SL cycles with complex contour formulas</li> <li>Radius compensation is active during CYCL CALL</li> <li>Paraxial positioning blocks in contour subprogram</li> <li>Miscellaneous functions M in contour subprogram</li> <li>M110 (feed-rate reduction for inside corner)</li> </ul>	<ul> <li>Cannot be defined with complex contour formula</li> <li>Real set operation possible</li> <li>Error message is issued</li> </ul>	<ul> <li>Restricted definition in complex contour formula is possible</li> <li>Only restricted performance of real set operation possible</li> <li>Radius compensation is canceled, program is executed</li> <li>Program is executed</li> <li>M functions are ignored</li> <li>Function also works within SL cycles</li> </ul>
SLII Contour Train Cycle 25: APPR/DEP blocks in contour definition	Not allowed, machining of closed contours is more coherent	APPR/DEP blocks are allowed as contour elements
General cylinder surface machining:		
<ul> <li>Contour definition</li> <li>Offset definition on cylinder surface</li> <li>Offset definition for basic rotation</li> <li>Circle programming with C/CC</li> </ul>	<ul> <li>With X/Y coordinates, independent of machine type</li> <li>With datum shift in X/Y, independent of machine type</li> <li>Function available</li> <li>Function available</li> </ul>	<ul> <li>Machine-dependent, with existing rotary axes</li> <li>Machine-dependent datum shift in rotary axes</li> <li>Function not available</li> <li>Function not available</li> </ul>
APPR/DEP blocks in contour definition	<ul> <li>Function not available</li> </ul>	<ul> <li>Function available</li> </ul>
Cylinder surface machining with Cycle 28:		
<ul> <li>Complete roughing-out of slot</li> <li>Definable tolerance</li> <li>Cylinder surface machining with Cycle 29</li> </ul>	<ul> <li>Function available</li> <li>Function available</li> <li>Direct plunging to contour of ridge</li> </ul>	<ul> <li>Function not available</li> <li>Function available</li> <li>Circular approach to contour of ridge</li> </ul>
Cycles 25x for pockets, studs and slots:		
<ul> <li>Plunging movements</li> </ul>	In limit ranges (geometrical conditions of tool/contour) error messages are triggered if plunging movements lead to unreasonable/critical behavior	In limit ranges (geometrical conditions of tool/contour), vertical plunging is used if required

### **19.5 Functions of the TNC 640 and the iTNC 530 compared**

Function	TNC 640	iTNC 530
PLANE function:		
TABLE ROT/COORD ROT not defined	<ul> <li>Configured setting is used</li> </ul>	COORD ROT is used
<ul> <li>Machine is configured for axis angle</li> </ul>	<ul> <li>All PLANE functions can be used</li> </ul>	Only PLANE AXIAL is executed
<ul> <li>Programming an incremental spatial angle according to PLANE AXIAL</li> </ul>	<ul> <li>Error message is issued</li> </ul>	<ul> <li>Incremental spatial angle is interpreted as an absolute value</li> </ul>
<ul> <li>Programming an incremental axis angle according to PLANE</li> <li>SPATIAL if the machine is configured for spatial angle</li> </ul>	<ul> <li>Error message is issued</li> </ul>	<ul> <li>Incremental axis angle is interpreted as an absolute value</li> </ul>
Special functions for cycle programming:		
■ FN17	<ul> <li>Function available, details are different</li> </ul>	<ul> <li>Function available, details are different</li> </ul>
■ FN18	<ul> <li>Function available, details are different</li> </ul>	<ul> <li>Function available, details are different</li> </ul>
Compensation of tool length in the position display	The <b>DL</b> value from the <b>TOOL</b> <b>CALL</b> and the tool length entries <b>L</b> and <b>DL</b> from the tool table are taken into account in the position display	The tool length entries <b>L</b> and <b>DL</b> from the tool table are taken into account in the position display

#### **Comparison: Differences in MDI operation**

Function	TNC 640	iTNC 530
Execution of connected sequences	Function partially available	Function available
Saving modally effective functions	Function partially available	Function available

#### **Comparison: Differences in programming station**

Function	TNC 640	iTNC 530
Demo version	Programs with more than 100 NC blocks cannot be selected, an error message is issued	Programs can be selected, max. 100 NC blocks are displayed, further blocks are truncated in the display
Demo version	If nesting with PGM CALL results in more than 100 NC blocks, there is no test graphic display; an error message is not issued	Nested programs can be simulated.
Copying NC programs	Copying to and from the directory <b>TNC:</b> \ is possible with Windows Explorer	TNCremo or file manager of programming station must be used for copying
Shifting the horizontal soft-key row	Clicking the soft-key bar shifts the soft-key row to the right, or to the left	Clicking any soft-key bar activates the respective soft-key row

### Index

3	
3D compensation	447
Delta values	449
Face Milling	450
Normalized vector	448
Peripheral Milling	451
Tool orientation	449
3-D compensation	
Tool shapes	449
3-D line graphics	563
3-D touch probes	
Calibration	522
3-D view	558

#### Α

ACC	389
Accessing tables	311
Accessories	. 86
Actual position capture	. 99
Adaptive feed control	377
Adding comments 132,	134
Additional axes	, 91
Adjusting spindle speed	501
AFC	377
Angle functions	284
Approach contour	198
ASCII Files	398
Automatic program start	578
Automatic tool measurement	163

В

Basic rotation	528
Measuring in Manual Operation	
mode	528
Block	101
Delete	101

#### С

•	
Calculating with parentheses	321
Calculation of circles	285
Calculator	136
CAM programming	447
Chamfer	208
Chatter Control	389
Checking the axis positions	504
Circle 212, 214,	220
Circle center	210
Circular path 211,	220
Code numbers	589
Collision monitoring	371
Comparison	630
Compensating workpiece	
misalignment	
By measuring two points on a	
straight surface	527

Connecting/removing USB devices.

#### 128

Connector pin layout for data
interfaces
Context-sensitive help 147
Control panel 72
Conversational dialog
Coordinate transformation 395
Copying program sections 102, 102
Corner rounding 209

#### )

Data Backup	107
Data interface	590
Connector pin layouts	616
Set up	590
Data output on the screen	298
Data transfer software	594
Data transfer speed	
590, 591, 591, 591, 591, 592,	592
Datum management	508
Datum setting	507
Without a 3-D touch probe	507
Datum shift	
Resetting	397
Using the datum table	
Datum table	520
Transferring test results	
DCM	371
Defining local Q parameters	280
Defining nonvolatile Q parameter	
280	
Defining the workpiece blank	96
Depart contour	198
Dialog	
Directory 108,	-
Copy	115
Create	112
Delete	116
Displaying HTML files	121
Displaying Internet files	121
Display screen	
Downloading help files	152
Dynamic Collision Monitoring	-
-	

Enter spindle speed	173
Error messages 141,	141
Help with	141
Ethernet interface	596
Configuring	596
Connecting and disconnecting	
network drives	127
Connection options	596
Introduction	596
External access	584
External data transfer	
iTNC 530	125

#### FCL..... 589 FCL function..... 11 Feature Content Level...... 11 Feed rate..... 500 Adjust..... 501 On rotary axes, M116..... 434 Feed rate control, automatic..... 377 Feed rate factor for plunging movements M103...... 355 Feed rate in millimeters per spindle revolution M136...... 356 File Create..... 112 File manager..... 105, 108 Call..... 110 Copying files..... 112 Copying tables..... 114 Delete file..... 116 Directories..... 108 Сору..... 115 Create..... 112 External data transfer..... 125 File Create..... 112 File type..... 105 File type External file types..... 107 Function overview...... 109 Overwriting files..... 113 Protect file..... 119 Rename file..... 118, 118 Selecting files..... 111 Tagging files..... 117 File status..... 110 Filter for hole positions with DXF data update..... 259 FK programming..... 225, 225 Circular paths..... 231 Fundamentals..... 225 FK-Programming Graphics..... 227 FK programming Initiating dialog..... 229 Input options..... 232 Auxiliary points...... 235 Circle data..... 233 Closed contours...... 234 Direction and length of contour elements...... 232 End points..... 232 Relative data..... 236 Straight lines..... 230 FN14: ERROR: Displaying error messages..... 291, 291 FN16: F-PRINT: Output of formatted

texts
PLC
FN20: WAIT FOR: NC and PLC
synchronization
circle from 3 points
FN24: CIRCLE DATA: Calculate a
circle from 4 points
FN26: TABOPEN: Open a freely
definable table 405
FN27: TABWRITE: Write to a freely
definable table 406, 406
FN28: TABREAD: Read from a
freely definable table 407, 407
FN29: PLC: Transfer values to the
PLC 310
FN37: EXPORT 310
Form view 404
FS, Functional safety 502
Full circle 211
Functional safety FS 502
Fundamentals

### G

Graphics	554
Display modes	556
Magnifying details	560
With programming	138
Magnification of details	140
Graphic simulation	561
Tool display	561

#### Н

Handwheel	490
Hard disk	105
Helical interpolation	221
Helix	221
Help system	147
Help with error messages	141

#### ١. .

Inclined-tool machining in a tilted	
plane 432	
Inclined turning 479	
Initiated tools 167	
Inserting and modifying blocks. 101	
Interrupt machining 572	
iTNC 530 70	

#### Μ

M91, M92	350
Machine settings	584
Manual Datum Setting	530

Manual datum setting	
Circle center as datum	533
Corner as datum	531
In any axis	530
Setting a center line as datum §	535
Measurement of machining	
time	562
Measuring workpieces	536
M functions	
For program run inspection	349
For spindle and coolant	349
See miscellaneous functions	348
Mid-program startup	575
After power failure	575
Miscellaneous functions	348
enter	348
For coordinate data	350
For path behavior	353
For rotary axes	434
Modes of Operation	73
MOD function	582
Exit	582
Overview	583
Select	582
Monitoring	
Collision	371
Move machine axes	
Jog positioning	489
Moving the axes	
With machine axis direction	
buttons	489
Moving the machine axes	489
with the handwheel	490
Multiple Axis Machining	442

#### Ν

NC and PLC synchronization	308
NC error messages	141
Nesting	269
Network connection	127
Network settings	596

### 0

Open BMP file	124
Open contour corners M98	354
Open GIF file	124
Opening Excel files	121
Opening graphic files	124
Opening TXT files	123
Open INI file	123
Open JPG file	124
Open PNG file	124
Open TXT file	123
Operating times	588
Option number	589
Output of formatted Q	
parameters	295

#### Ρ

Pallet table	454
Application	454
Run	456
Select and exit	456
Transfer coordinates 454,	
Parallel axes	390
Parameter programming:See Q	
parameter programming 278,	325
Paraxcomp	390
Paraxmode	390
Part families	281
Path	108
Path contours	206
Cartesian coordinates	206
Circle with tangential	
connection	214
Circular path around circle	
center CC.	211
Circular path with defined	
radius	212
Overview	206
Straight line	207
Polar coordinates	218
Circular path around pole	
CC	220
Circular path with tangenti	al
connection	220
Overview	218
Straight line	219
Path functions	192
Fundamentals	192
Circles and circular arcs	195
Pre-position	196
PDF Viewer	120
PLANE Function	411
PLANE function	
Automatic positioning	427
Axis angle definition	425
Euler angle definition	418
Inclined-tool machining	
Incremental definition	424
Point definition	422
Positioning behavior	427
Projection angle definition	
Reset	414
Selection of possible solutions 430	;
Spatial angle definition	415
Vector definition	420
Plan view	420 557
PLC and NC synchronization	308
Pocket table	170
Polar coordinates	
Fundamentals	
Programming	
Positioning	
With Manual Data Input	

TNC 640 | User's Manual HEIDENHAIN Conversational Programming | 5/2013

With tilted working plane.... 352, 441 Preset table. 508, 521

Preset table 508, 521
Transferring test results 521
Principal axes 91, 91
Processing DXF data
Basic settings 246
Filter for hole positions 259
Selecting a contour
Selecting hole positions
Entering a diameter
Mouse-over 257
Single selection 256
Selecting machining positions 255
Setting layers 248
Setting the datum 249
Processing DXF Files 244
Program
Editing 100
Opening a new program
Organization
Structuring 135
Program call
Any desired program as
subprogram
Program defaults
Program management:See file
manager 105
Programming graphics 227
Programming tool movements 97
Program run 570
Execute 571
Interrupt 572
Mid-program startup 575
Optional block skip 579
Overview 570
Resuming after interruption 573
Program-section repeat 265
Projection in three planes 557

#### Q

Q parameter
Export
Transfer values to PLC
Transfer values to the PLC 310
Q parameter programming 278,
325
Additional functions
Angle functions 284
Calculation of circles 285
If-then decisions 286
Mathematical functions
Programming notes
279, 326, 327, 328, 330, 332
Q parameters 278, 325
Checking 288
Local parameters QL 278
Nonvolatile parameters QR 278

Preassigned	336

R	
Radius compensation	188
Entering	189
Outside corners, inside	
corners	190
Rapid traverse	156
Reading out machine parameter	ſS
333	
Recessing and undercutting	473
Reference system 91	, 91
Replacing texts	104
Retraction from the contour	362
Returning to the contour	577
Rotary axis	434
Reduce display M94	436
Shortest-path traverse: M126.	435
Rounding corners M197	366

#### S

Screen layout 71
Search function 103
Selecting a contour from DXF 251
Selecting positions from DXF 255
Selecting the datum
Selecting the unit of measure 96
Select kinematics 586
Setting the BAUD RATE
590, 591, 591, 591, 591, 592, 592
Software number 589
SPEC FCT 368
Special functions
Spindle load monitoring 388
SQL commands 311
Status display 75, 75
Additional76
General75
Straight line 207, 219
Straight line

т	
ТСРМ	442
Reset	446
Teach In 99,	, 207
Teach-in cut	382
Test Run	566
Test run	
Execute	569
Test Run	
Overview	566

test run	
Setting speed	555
Text File	398
Text file	
Delete functions	399
Finding text sections	401
Opening and exiting	398
Text variables	325
Tilted axes	437
Tilting the Working Plane 411,	540
Tilting the working plane	
Manual	540
TNCguide	147
TNCremo	594
TNCremoNT	594
Tool breakage monitoring	387
Tool change	175
Tool compensation	187
Length	187
Radius	188
Three-dimensional	447
Tool data	158
Call	173
Delta values	159
Entering into the program	159
Enter into the table	160
Tool data	
Initiating	167
Tool length	158
Tool management	180
Tool measurement	163
	158
Tool name	
Tool number	158
Tool radius	158
Tool table	160
edit, exit	164
Editing functions 167, 182,	183
Input options	160
Tool usage file	178
Tool usage test	178
Touch probe cycles	
. ,	
Manual Operation mode	514
See Touch Probe Cycles User'	S
Manual	
Touch probe monitoring	363
TRANS DATUM	395
Traversing reference marks	486
Trigonometry	284
Turning mode selection	461
-	460
Turning Operations	
Feed rate	465
Turning operations	
Program spindle speed	
Tool data	464
	464 467
Turning Operations	
Turning Operations Tool tip radius compensation	467
	467 472

#### U

Unbalance Functions User parameters	481
Machine-specific Using touch probe functions wi	th
mechanical probes or measurin dials	-
V	
Version numbers Virtual tool axis	
W	
Window Manager Wireless handwheel Assign handwheel holder Configure Selecting transmitter power Setting channel Statistical data Working space monitoring 565, Workpiece positions Writing probing values in a datu table Writing probing values in a press table.	493 602 603 603 604 569 93 m 520 set
Z	
Zero point shift Coordinate input ZIP archive	

# HEIDENHAIN

#### **DR. JOHANNES HEIDENHAIN GmbH**

Dr.-Johannes-Heidenhain-Straße 5 83301 Traunreut, Germany 2 +49 8669 31-0 FAX +49 8669 5061 E-mail: info@heidenhain.de

Technical support		
Measuring systems	2	+49 8669 31-3104
E-mail: service.ms-	supp	ort@heidenhain.de
TNC support	3	+49 8669 31-3101
E-mail: service.nc-s	suppo	ort@heidenhain.de
NC programming	6	+49 8669 31-3103
E-mail: service.nc-p	ogm@	@heidenhain.de
PLC programming	6	+49 8669 31-3102
E-mail: service.plc@heidenhain.de		
Lathe controls	6	+49 8669 31-3105
E-mail: service.lath	e-sup	port@heidenhain.de

www.heidenhain.de

#### Touch probes from HEIDENHAIN help you reduce non-productive time and

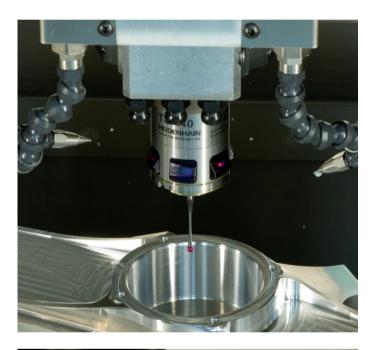
help you reduce non-productive time and improve the dimensional accuracy of the finished workpieces.

#### Workpiece touch probes

ΤS	220
TS	440,TS 444
TS	640,TS 740

Signal transmission by cable Infrared transmission Infrared transmission

- Workpiece alignment
- Setting datums
- Workpiece measurement





TT 140	Signal transmission by cable
TT 449	Infrared transmission
TL	Contact-free laser systems

- Tool measurement
- Wear monitoring
- Tool breakage detection



###