

HEIDENHAIN



TNC 320

User's Manual ISO programming

NC Software 771851-05 771855-05

English (en) 10/2017

Controls and displays

Keys

Keys on visual display unit

Кеу	Function
0	Selecting the screen layout
0	Toggle the display between machine operating mode, program- ming mode, and a third desktop
	Soft keys for selecting functions on screen
	Shifting between soft-key rows

Machine operating modes

Кеу	Function
M	Manual operation
	Electronic handwheel
	Positioning with manual data input
	Program run, single block
Ξ	Program run, full sequence

Programming modes

Кеу	Function
>	Programming
-	Test run

Entering and editing coordinate axes and numbers

Кеу		Function
X	V	Select coordinate axes or enter them in a program
0	9	Numbers
•	-/+	Decimal separator / Reverse algebraic sign
Р	Ι	Polar coordinate entry / Incremental values
٥		Q parameter programming / Q parameter status
-‡-		Capture actual position
NO ENT		Skip dialog questions, delete words
ENT		Confirm entry and resume dialog
END		Conclude block and exit entry
CE		Clear entries or error message
DEL		Abort dialog, delete program section

Tool functions

Кеу	Function
TOOL DEF	Define tool data in the program
TOOL CALL	Call tool data

Managing programs and files, control functions

Кеу	Function
PGM MGT	Select or delete programs and files, external data transfer
PGM CALL	Define program call, select datum and point tables
MOD	Select MOD functions
HELP	Display help text for NC error messages, call TNCguide
ERR	Display all current error messages
CALC	Show calculator
SPEC FCT	Show special functions

Cycles, subprograms and program section repeats

Кеу		Function
TOUCH PROBE		Define touch probe cycles
CYCL DEF	CYCL CALL	Define and call cycles
LBL SET	LBL CALL	Enter and call labels for subpro- gramming and program section repeats
STOP		Enter program stop in a program

Programming path movements

Кеу	Function
APPR DEP	Approach/depart contour
FK	FK free contour programming
L	Straight line
CC +	Circle center/pole for polar coordi- nates
C	Circular arc with center
CR	Circle with radius
CT 	Circular arc with tangential connec- tion
CHF o o	Chamfer/rounding arc

Potentiometer for feed rate and spindle speed

Feed rate	Spindle speed
50 (00) 150 0 WW F %	50 (5 S %) 5 S %)

Navigation keys

Кеу		Function
+	+	Position the cursor
GOTO		Go directly to blocks, cycles and parameter functions
HOME		Navigate to the program start or table start
END		Navigate to the program end or end of a table line
PG UP		Navigate up one page
PG DN		Navigate down one page
		Select the next tab in forms
Ēt	Ē	Up/down one dialog box or button

Fundamentals

About this manual

Safety precautions

Comply with all safety precautions indicated in this document and in your machine tool builder's documentation!

Precautionary statements warn of hazards in handling software and devices and provide information on their prevention. They are classified by hazard severity and divided into the following groups:

Danger indicates hazards for persons. If you do not follow the avoidance instructions, the hazard will **result in death or severe injury.**

WARNING

Warning indicates hazards for persons. If you do not follow the avoidance instructions, the hazard **could result in death or serious injury.**

Caution indicates hazards for persons. If you do not follow the avoidance instructions, the hazard **could result in minor or moderate injury.**

NOTICE

Notice indicates danger to material or data. If you do not follow the avoidance instructions, the hazard **could result in things other than personal injury, like property damage**.

Sequence of information in precautionary statements

All precautionary statements comprise the following four sections:

- Signal word indicating the hazard severity
- Type and source of hazard
- Consequences of ignoring the hazard, e.g.: "There is danger of collision during subsequent machining operations"
- Escape Hazard prevention measures

Informational notes

Observe the informational notes provided in these instructions to ensure reliable and efficient operation of the software. In these instructions, you will find the following informational notes:



The information symbol indicates a **tip**. A tip provides important additional or supplementary information.



This symbol prompts you to follow the safety precautions of your machine tool builder. This symbol also indicates machine-dependent functions. Possible hazards for the operator and the machine are described in the machine manual.



The book symbol represents a **cross reference** to external documentation, e.g. the documentation of your machine tool builder or other supplier.

Would you like any changes, or have you found any errors?

We are continuously striving to improve our documentation for you. Please help us by sending your requests to the following e-mail address:

tnc-userdoc@heidenhain.de

Control model, software and features

This manual describes functions and features provided by controls as of the following NC software numbers.

Control model	NC software number
TNC 320	771851-05
TNC 320 Programming Station	771855-05

The machine manufacturer adapts the usable features of the control to his machine by the setting machine parameters. Some of the functions described in this manual may therefore not be among the features provided by the control on your machine tool.

Control functions that may not be available on your machine include:

Tool measurement with the TT

In order to find out about the actual features of your machine, please contact the machine manufacturer.

Many machine manufacturers, as well as HEIDENHAIN, offer programming courses for the HEIDENHAIN controls. Participation in one of these courses is recommended to familiarize yourself thoroughly with the control's functions.



Cycle Programming User's Manual:

All of the cycle functions (touch probe cycles and fixed cycles) are described in the Cycle Programming User's Manual. If you need this user's manual, please contact HEIDENHAIN if required. ID: 1096959-xx

Software options

The TNC 320 features various software options that can be enabled by your machine tool builder. Each option is to be enabled separately and contains the following respective functions:

Additional Axis (option 0 and opt	ion 1)
Additional axis	Additional control loops 1 and 2
Advanced Function Set 1 (option	8)
Expanded functions Group 1	Machining with rotary tables
	 Cylindrical contours as if in two axes
	 Feed rate in distance per minute
	Coordinate conversions:
	Tilting the working plane
HEIDENHAIN DNC (option 18)	
	Communication with external PC applications over COM component
CAD Import (option 42)	
CAD import	Support for DXF, STEP and IGES
	 Adoption of contours and point patterns
	 Simple and convenient specification of presets
	 Selecting graphical features of contour sections from conversational programs
Extended Tool Management (opti	on 93)
Extended tool management	Python-based
Remote Desktop Manager (optior	ו 133)
Remote operation of external	Windows on a separate computer unit
computer units	Incorporated in the control's interface

Feature Content Level (upgrade functions)

Along with software options, significant further improvements of the control software are managed via the **F**eature **C**ontent **L**evel upgrade functions. If you install a software update on your control you do not automatically have the functions available as covered by the FCL.



All upgrade functions are available to you without surcharge when you receive a new machine.

Upgrade functions are identified in the manual as **FCL n**. The **n** signifies the serial number of the development status.

You can purchase a code number in order to permanently enable the FCL functions. For more information, contact your machine tool builder or HEIDENHAIN.

Intended place of operation

The control complies with the limits for a Class A device in accordance with the specifications in EN 55022, and is intended for use primarily in industrially-zoned areas.

Legal information

This product uses open source software. Further information is available on the control under:

- Programming operating mode
- MOD function
- LICENSE INFO soft key

New functions

New functions 34055x-06

- The active tool-axis direction can now be activated as a virtual tool axis in the Manual Operation mode and during handwheel superimpositioning, see "Superimposing handwheel positioning during program run: M118 ", page 439
- Writing and reading data in freely definable tables, see "Freely definable tables", page 463
- New touch probe Cycle 484 for calibrating the wireless touch probe TT 449, see Cycle Programming User's Manual
- The new HR 520 and HR 550 FS handwheels are supported, see "Traverse with electronic handwheels", page 519
- New operating Cycle 225 Engraving, see Cycle Programming User's Manual
- New manual probing cycle Center line as preset, see "Setting a center line as preset", page 569
- New function for rounding corners, see "Rounding corners: M197", page 446
- External access to the control can now be blocked with an MOD function, see "External access", page 628

Changed functions 34055x-06

- The maximum number of characters for the NAME and DOC fields in the tool table has been increased from 16 to 32, see "Entering tool data into the table", page 208
- Operation and positioning behavior of the manual probing cycles has been improved, see "Using a 3-D touch probe ", page 540
- Predefined values can now be entered into a cycle parameter with the PREDEF function in cycles, see Cycle Programming User's Manual
- With the KinematicsOpt cycles a new optimization algorithm is now used, see the Cycle Programming User's Manual
- With Cycle 257, CIRCULAR STUD, a parameter is now available with which you can determine the approach position on the stud, see User's Manual for Cycle Programming
- With Cycle 256 RECTANGULAR STUD, a parameter is now available with which you can determine the approach position on the stud, see Cycle Programming User's Manual
- With the manual **Basic Rotation** touch probe cycle, workpiece misalignment can now be compensated for via a table rotation, see "Compensation of workpiece misalignment by rotating the table", page 557

New functions 77185x-01

- New special operating mode RETRACT, see "Retraction after a power interruption", page 610
- New graphic simulation, see "Graphics ", page 586
- New Tool usage file MOD function in the machine settings group, see "Tool usage file", page 631
- New Set system time MOD function in the systems settings group, see "Set the system time", page 632
- New Graphic settings MOD group, see "Graphic settings", page 626
- With the new cutting data calculator you can calculate the spindle speed and the feed rate, see "Cutting data calculator", page 184
- With the jump commands new if/then decisions have been introduced, see "Programming if-then decisions", page 349
- The character set of machining Cycle 225 Engraving has been expanded to include more characters and the diameter sign, see Cycle Programming User's Manual
- New machining Cycle 275 Trochoidal Milling, see Cycle Programming User's Manual
- New Cycle 233 Face Milling, see Cycle Programming User's Manual
- In the drilling cycles 200, 203 and 205 the parameter Q395 DEPTH REFERENCE has been introduced in order to evaluate the T ANGLE, see Cycle Programming User's Manual
- Probing Cycle 4 MEASURING IN 3-D has been introduced, see Cycle Programming User's Manual

Modified functions 77185x-01

- Up to 4 M functions are now allowed in an NC block, see "Fundamentals", page 426
- New soft keys for transferring values have been introduced in the pocket calculator, see "Operation", page 181
- The distance-to-go display can now also be displayed in the input system, see "Select the position display", page 633
- Several input parameters have been added to Cycle 241 SINGLE-LIP DEEP HOLE DRILLING, see Cycle Programming User's Manual
- Parameter Q305 NUMBER IN TABLE has been added to Cycle 404, see Cycle Programming User's Manual
- In the thread milling cycles 26x an approaching feed rate has been introduced, see Cycle Programming User's Manual
- In Cycle 205 Universal Pecking you can now use parameter Q208 to define a feed rate for retraction, see Cycle Programming User's Manual

New functions 77185x-02

- Programs with .HU and .HC extensions can be selected and processed in all operating modes
- The functions SELECT PROGRAM and CALL SELECTED PROGRAM have been introduced, see "Calling any program as a subprogram", page 325
- New FEED DWELL function for programming repeating dwell times, see "Dwell time FUNCTION FEED", page 471
- The control automatically writes upper case letters at the start of a block, see "Programming path functions", page 262
- The D18 functions have been expanded, see "D18 Reading system data", page 363
- USB data carriers can be locked with the SELinux security software, see "SELinux security software", page 98
- The machine parameter **posAfterContPocket** (no. 201007) that influences positioning after an SL cycle has been introduced, see "Machine-specific user parameters", page 658
- Protective zones can be defined in the MOD menu, see "Entering traverse limits", page 630
- Write protection is possible for individual lines in the preset management, see "Saving presets in the table", page 531
- New manual probing function for aligning a plane, see "Measuring 3-D basic rotation", page 559
- New function for aligning the machining plane without rotary axes, see "Tilting the working plane without rotary axes", page 506
- CAD files can be opened without option number 42, see "Data Transfer from CAD Files", page 295
- New software option 93 Extended Tool Management, see "Calling tool management", page 234

Modified functions 77185x-02

- The input range of the DOC column in the pocket table has been expanded to 32 characters, see "Pocket table for tool changer", page 219
- Commands D15, D31 and D32 from predecessor controls no longer generate ERROR blocks during import. When simulating or running an NC program with these commands, the control interrupts the NC program with an error message that helps you to find an alternative implementation
- Miscellaneous functions M104, M105, M112, M114, M124, M134, M142, M150, M200 - M204 from predecessor controls no longer generate ERROR blocks during import. When simulating or running an NC program with these miscellaneous functions, the control interrupts the NC program with an error message that helps you to find an alternative implementation, see "Comparison: Miscellaneous functions", page 693
- The maximum file size of files output with D16 F-Print has been increased from 4 KB to 20 KB
- The Preset.PR preset management is write-protected in Programming operating mode, see "Saving presets in the table", page 531
- The input range of the Q parameter list for defining the QPARA tab on the status display consists of 132 input positions, see "Displaying Q parameters (QPARA tab)", page 89
- Manual calibration of the touch probe with fewer pre-positioning movements, see "Calibrating 3-D touch probes ", page 549
- The position display takes into account the DL oversizes programmed in the T block, selectable as an oversize of the workpiece or tool, see "Delta values for lengths and radii", page 207
- In single block mode the control executes each point individually with point pattern cycles and G79 PAT, see "Program run", page 603
- Rebooting the control is no longer possible with the END key but with the RESTART soft key, see "Switch-off", page 516
- The control displays the contouring feed rate in manual mode, see "Spindle speed S, feed rate F and miscellaneous function M", page 529
- Deactivate tilting in manual mode is only possible via the 3D-ROT menu, see "Activating manual tilting:", page 576
- Machine parameter maxLineGeoSearch (no. 105408) has been increased to max. 50000, see "Machine-specific user parameters", page 658
- The name of software option number 8 has changed, see "Software options", page 9

New and modified cycle functions 77185x-02

- Cycle G270 CONTOUR TRAIN DATA has been added
- Cycle G139 CYL. SURFACE CONTOUR has been added (option 1)
- The character set of machining cycle G225 ENGRAVING has been expanded with the CE character, ß, the @ character and system time
- Cycles G252-G254 have been expanded with the optional parameter Q439
- Cycle G122 ROUGH-OUT has been expanded by the optional parameters Q401, Q404
- Cycle G484 CALIBRATE IR TT has been expanded by the optional parameter Q536

Further information: Cycle Programming User's Manual

New functions 77185x-04

- New function FUNCTION DWELL for programming a dwell time, see "Dwell time FUNCTION DWELL", page 473
- New function FUNCTION S-PULSE for programming pulsing shaft speeds, see "Pulsing spindle speed FUNCTION S-PULSE", page 469
- The column KINEMATIC has been added to the tool table, see "Entering tool data into the table", page 208
- The column **OVRTIME** has been added to the tool table, see "Entering tool data into the table", page 208
- When importing tool data the CSV file may contain additional table columns not recognized by the control. During import a message is displayed indicating the unrecognized columns and informing that these values will not be adopted, see "Importing and exporting tool data", page 241
- Manual probe functions create a line in the preset management if the specified line does not exist yet, see "Writing measured values from the touch-probe cycles to the preset table", page 548
- Manual probe functions can write in a password-protected line, see "Recording measured values from the touch probe cycles", page 546
- During a manual touch probe cycle, control can be transferred to the handwheel, see "Traverse movements with a handwheel with display", page 542
- Several handwheels can be connected to a control, see "Traverse with electronic handwheels", page 519
- In Electronic handwheel mode of operation, the handwheel axis for an HR 130 can be selected with the orange axis keys
- If the control is set to the INCH unit of measure, the control also includes movements traversed by the handwheel in INCHES, see "Traverse with electronic handwheels", page 519
- The control differentiates between interrupted or stopped NC programs. In the interrupted status, the control offers more intervention options, see "Interrupting, stopping or aborting machining", page 605
- The software option number 42 DXF Converter now also produces CR circles, see "Basic settings", page 299
- With active structuring the structure block can be edited in the structure window, see "Definition and applications", page 179
- Animated help can be selected with the tilt working plane function, see "Overview", page 481
- The D18 functions have been expanded, see "D18 Reading system data", page 363
- The D16 functions have been expanded, see "D16 Formatted output of texts and Q parameter values", page 357
- The file saved with SAVE AS is now also found in the file management under LAST FILES, see "Editing an NC program", page 136
- If you save files with SAVE AS, you can select the target directory with the SWITCH soft key, see "Editing an NC program", page 136

- It is possible to search quickly for a file in file management by entering the first letter, see "Selecting drives, directories and files", page 148
- File management displays vertical scrollbars and supports scrolling with the mouse, see "Calling the file manager", page 147
- New machine parameter for recreating M7 and M8, see "Machine-specific user parameters", page 658
- The function STRLEN checks whether a string parameter has been defined, see "Finding the length of a string parameter", page 408
- The function SYSSTR enables the NC software version to be read out, see "Reading system data", page 405
- The function D38 can now be programmed without a code number
- Undefined Q parameters can now be transferred with the function **D00**
- For jumps with **D09**, QS parameters and texts are permitted as conditions, see "Programming if-then decisions", page 349
- Cylindrical workpiece blanks can now also be defined with a diameter instead of a radius, see "Defining the blank: G30/G31", page 129
- The transitional elements G24 and G25 can now also be executed between 3-D contours, i.e. with straight line blocks with three programmed coordinates or a helix
- The control now supports spatial arcs, i.e. circles in 3 axes vertical to the working plane, see "Circular path around circle center ", page 267
- Active kinematics is displayed in the 3D-ROT menu, see "Activating manual tilting:", page 576
- In operating modes Program run, single block and Program run, full sequence the screen layout PROGRAM + SECTS can be specified, see "Structuring programs", page 179
- In operating modes Program Run Full Sequence, Program Run Single Block and Positioning w/ Manual Data Input, the font size can be set to the same size as the Programming operating mode, see "Machine-specific user parameters", page 658
- The functions in the Positioning w/ Manual Data Input mode were expanded and adapted for improved operation, see "Positioning with Manual Data Input", page 579
- Active kinematics is displayed in the operating mode **RETRACT**, see "Retraction after a power interruption", page 610
- In the RETRACT operating mode, feed-rate limitation can be deactivated with the CANCEL THE FEED RATE LIMITATION soft key, see "Retraction after a power interruption", page 610
- In the Test Run operating mode a tool usage file can also be created without simulation, see "Tool usage test", page 226
- In the Test Run operating mode you can hide the rapid traverse movements with the FMAX PATHS soft key, see "3-D view in the Test Run operating mode", page 590
- In the Test Run operating mode you can reset the solid-model view with the RESET THE VOLUME MODEL soft key, see "3-D view in the Test Run operating mode", page 590

- In the Test Run operating mode you can reset the tool paths with the RESET TOOL PATHS soft key, see "3-D view in the Test Run operating mode", page 590
- In the Test Run operating mode the MEASURING soft key displays the coordinates if you position the mouse on the graphics, see "3-D view in the Test Run operating mode", page 590
- In the Test Run operating mode the STOP AT soft key simulates up to a predefined block, see "Test Run up to a certain block ", page 602
- Active basic transformation is shown in the status display on the POS tab, see "Positions and coordinates (POS tab)", page 88
- The status display now also shows the path of the active main program, see "Overview", page 86, see "General program information (PGM tab)", page 87
- In the status display the CYC tab now also shows T-Max and TA-Max
- Mid-program startup can now be continued, see "Entering the program at any point: Mid-program startup", page 613
- With functions NC/PLC Backup and NC/PLC Restore you can save and restore single directories or the complete TNC drive, see "Backup and restore", page 101

Modified functions 77185x-04

- When editing the tool table or tool management, only the current table line is blocked, see "Editing the tool table", page 213
- When importing tool tables, nonexistent tool types are imported as type undefined, see "Importing tool tables", page 216
- Tool names can now also include the special characters % and ,, see "Tool number, tool name", page 206
- When importing tool tables the numerical values are adopted from the R-OFFS column, see "Importing tool tables", page 216
- In the LIFTOFF column of the tool table the default is now N, see "Entering tool data into the table", page 208
- The L and R columns of the tool table are empty when a new tool is created, see "Editing the tool table", page 213
- In the tool table, the SELECT soft key is now available for the RT and KINEMATIC columns, see "Entering tool data into the table", page 208
- You cannot delete the tool data of tools still stored in the pocket table, see "Editing the tool table", page 213
- The touch probe function Corner as preset has been expanded, see "Corner as preset", page 564
- In all manual probing functions, quicker selection of the start angle of holes and studs is possible with soft keys (paraxial probing directions), see "Functions in touch probe cycles", page 543
- When probing, after acceptance of the actual value of the 1st point, for the 2nd point the soft key for the axis direction is shown
- In all manual probing functions, the direction of the reference axis is suggested as a default
- The arrangement of soft keys in the manual probing cycle PROBING P has been adapted, see "Corner as preset", page 564
- In manual probing cycles the hard keys END and Adopt Actual Position may be used
- The display of the machining feed rate has been changed in manual mode, see "Spindle speed S, feed rate F and miscellaneous function M", page 529
- The FMAX soft key in Program Run not only limits the machining feed rate during execution of the program but also the axis feed rate for manual axis movements, see "Feed rate limit F MAX", page 530
- Soft key allocations were adapted for incremental positioning
- The values entered for the traverse limits are checked for validity, see "Entering traverse limits", page 630
- When the preset management is opened, the cursor is on the line of the active preset
- The input range in columns SPA, SPB and SPC in the preset management was expanded to 999.9999, see "Managing presets", page 531
- New help graphics with PLANE RESET, see "Specifying the positioning behavior of the PLANE function", page 498

- Tilting is permitted in combination with mirroring, see "The PLANE function: Tilting the working plane (option 8)", page 479
- The behavior of COORD ROT and TABLE ROT in the 3D-ROT menu has been modified, see "Specifying the positioning behavior of the PLANE function", page 498
- Even when the 3D-ROT dialog is active in Manual operation mode, PLANE RESET still functions with active basic transformation, see "Activating manual tilting:", page 576
- When calculating the axis angle in the axes chosen with M138, the control sets the value to 0, see "Selecting tilting axes: M138", page 510
- The feed rate potentiometer only reduces the programmed feed rate and no longer the feed rate calculated by the control, see "Feed rate F", page 204
- The functions APPR LT, APPR LCT, DEP LT and DEP LCT position all three axes at on the auxiliary point at the same time, see "Approaching on a straight line with tangential connection: APPR LT", page 257, see "Approaching on a circular path with tangential connection from a straight line to the contour: APPR LCT", page 259
- The functions APPR CT and DEP CT allow approach to and departure from a helix. This movement is carried out as a helix with an even pitch, see "Overview: Types of paths for contour approach and departure", page 254
- Block editing no longer causes block marking to be canceled. If a block is edited with active block marking and another block is then selected via the syntax search, the marking is expanded to the newly selected block, see "Marking, copying, cutting and inserting program sections", page 139
- The current structure block can be more clearly recognized in the structure window, see "Definition and applications", page 179
- DHCP Lease Time is now also valid following power interruption. When HEROS is shut down, the DHCP server is no longer informed that the IP address is free again, see "Configuring the control", page 643
- In the status display the fields for the LBL names have been expanded to 32 characters
- The TT status display now also shows values if the user changes to the TT tab later
- Status displays can now also be switched over with the Next tab key, see "Additional status displays", page 86
- If a subprogram called with % ends with M2 or M30 the control outputs a warning
- M124 no longer triggers an error message but only a warning. This enables NC programs with programmed M124 to run through without interruption
- In the file management, the programs or directories at the cursor position are also displayed in a separate field beneath the current path display
- Upper and lower cases for a file name can be modified in the file management

- If a larger file is transferred to a USB device in the file management, the control displays a warning until file transfer is completed, see "USB devices on the control", page 171
- In the file management, the control also shows the momentary type filter with the path
- In the file management the SHOW ALL soft key is now displayed in all operating modes
- In the file management the function Select the target directory was modified for copying files or directories. The soft keys OK and CANCEL are available on the first two positions
- The colors of the programming graphics were changed, see "Programming graphics", page 186
- In the Test Run and Programming operating modes the tool data is reset when a program is reselected or restarted with the RESET + START soft key
- In the Test Run operating mode the control displays the datum of the machine table as the reference point when using BLANK IN WORK SPACE, see "Showing the workpiece blank in the working space ", page 596
- After modification of the active preset, resuming the program is only possible after GOTO or mid-program startup, see "Moving the machine axes during an interruption", page 608
- With mid-program startup an FK sequence can be entered, see "Entering the program at any point: Mid-program startup", page 613
- Mid-program startup operation and dialog guidance has been improved, also for pallet tables, see "Entering the program at any point: Mid-program startup", page 613

New and modified cycle functions 77185x-04

- New cycle 258 POLYGON STUD
- Cycles 421, 422 and 427 were expanded by the parameters Q498 and Q531
- In Cycle 247 PRESETTING, the preset number from the preset table can be selected with the corresponding parameter
- With Cycles 200 and 203 the behavior of the dwell time at top has been adapted
- Cycle 205 performs deburring on the coordinate surface
- With SL cycles, M110 is now taken into account with circles compensated inwards if it is active during machining
- With Cycle 251 Rectangular pocket, M110 is now taken into account with circles compensated inwards if it is active during machining
- Cycle 225 has been expanded with parameters Q516, Q367 and Q574. This enables a preset for the specific text position to be defined or the text length and character height to be scaled
- In Cycles 481 to 483, parameter Q340 was expanded with the input option "2". This makes it possible to check the tool without changing the tool table
- Cycle 251 has been expanded by parameter Q439. The finishing strategy was also revised
- The finishing strategy was revised with cycle 252
- Cycle 275 has been expanded with parameters Q369 and Q439

Further information: Cycle Programming User's Manual

New functions 77185x-05

- CONTOUR DEF can now also be programmed in ISO format see "Functions for contour and point machining menu", page 449
- The PLANE functions can now also be programmed in ISO format with FMAX and FAUTO, see "Specifying the positioning behavior of the PLANE function", page 498
- If a pallet table is selected in a Program Run operating mode, the **Tooling list** and **T usage order** are calculated for the entire pallet table, see "Tool management (option number 93)", page 233
- New FUNCTION COUNT function for controlling a counter, see "Defining a counter", page 457
- New FUNCTION LIFTOFF function for retracting the tool from the contour upon an NC stop, see "Lift off tool at NC stop: FUNCTION LIFTOFF", page 474
- You can also open the tool-carrier files in the file management, see "Tool carrier management", page 451
- With the ADAPT NC PGM / TABLE function, you can also import and modify freely definable tables, see "Importing tool tables", page 216
- The machine tool builder can define update rules that make it possible, for example, to automatically remove umlauts from tables and NC programs when importing a table, see "Importing tool tables", page 216
- A quick search for the tool name is possible in the tool table, see "Entering tool data into the table", page 208
- It is possible to comment out NC blocks, see "Commenting out an existing NC block", page 176
- The machine tool builder can disable the setting of presets in individual axes, see "Saving presets in the table", page 531, see "Presetting with a 3-D touch probe ", page 562
- Line 0 of the preset table can also be edited manually, see "Saving presets in the table", page 531
- The CAD viewer exports points with FMAX to an H file, see "Selecting the file type", page 310
- When multiple instances of the CAD viewer are open, they are shown somewhat smaller on the third desktop.
- The CAD viewer now enables you to extract data from STEP, IGES and STEP files, see "Data Transfer from CAD Files", page 295
- The nodes in all tree structures can be expanded and collapsed by double-clicking them.
- New icon in the status display for mirrored machining, see "General status display", page 84
- Graphic settings in the Test Run operating mode are permanently stored, see "3-D view in the Test Run operating mode", page 590
- In the Test Run operating mode, you can now choose between various traverse ranges, see "Application", page 596
- The tool data of touch probes can also be displayed and entered in the tool management (option 93), see "Editing tool management", page 235

- With the TCH PROBE MONITOR OFF soft key you can suppress touch-probe monitoring for 30 seconds, see "Suppress touch probe monitoring", page 543
- During manual probing ROT and P, workpiece misalignment can be compensated by aligning a rotary table, see "Compensation of workpiece misalignment by rotating the table", page 557, see "Corner as preset", page 564
- If the function for orienting the touch probe to the programmed probe direction is active, the number of spindle revolutions is limited when the guard door is open. In some cases, the direction of spindle rotation will change so that positioning will not always follow the shortest path.
- It is now also possible to transfer undefined parameters with the **D00** function
- With D16, it is possible to enter references to Q parameters or QS parameters as the source and target, see "D16 – Formatted output of texts and Q parameter values", page 357
- The D18 functions have been expanded, see "D18 Reading system data", page 363
- New machine parameter iconPrioList (no. 100813) for defining the order of icons in the status display, see "Machine-specific user parameters", page 658
- The machine parameter clearPathAtBlk (no. 124203) enables you to specify whether the tool paths will be cleared with a new BLK FORM in the Test Run operating mode, see "Machinespecific user parameters", page 658
- New optional machine parameter CfgDisplayCoordSys (no. 127500) for selecting the coordinate system in which a datum shift is to be shown in the status display, see "Machine-specific user parameters", page 658

Modified functions 77185x-05

- If you use locked tools, the control displays a warning in the **Programming** and **Test Run** operating modes, see "Programming graphics", page 186, see "Test run", page 599
- The control offers a positioning logic for returning to the contour, see "Returning to the contour", page 618
- The positioning logic for returning to the contour with a replacement tool has changed, see "Tool change", page 224
- Axes that are not active in the current kinematic model can also be referenced in a tilted working plane, see "Crossing the reference point in a tilted working plane", page 515
- Holes and threads are shown in light blue in the programming graphics, see "Programming graphics", page 186
- The tool is shown in red in the graphics while it is in contact with the workpiece, and blue during air cuts, see "Tool display", page 594
- The positions of the sectional planes are no longer reset when a program or a new blank form is selected, see "Projection in three planes", page 592
- Spindle speeds can be entered with decimal places also in the Manual operation mode. The control displays the decimal places when the spindle speed is < 1000, see "Entering values", page 529
- The sort order and the column widths in the tool selection window are retained when the control is switched off, see "Calling the tool data", page 222
- If a subprogram called with %:PGM ends with M2 or M30, the control issues a warning. The control automatically clears the warning as soon as you select another NC program, see "Programming notes", page 324
- The control displays an error message in the header until it is cleared or replaced by a higher-priority error, see "Display of errors", page 190
- The time needed to paste a large amount of data into an NC program was considerably reduced.
- To connect a USB stick you no longer have to press a soft key, see "Connecting and removing USB storage devices", page 157
- The speed of setting the jog increment, spindle speed and feed rate was adjusted for electronic handwheels.
- The icons of basic rotation, 3-D basic rotation and tilted working plane were modified to make them easier to distinguish, see "General status display", page 84
- The control automatically recognizes whether a table is to be imported or the table format is to be adapted, see "Importing tool tables", page 216
- When you place the cursor in an input field of the tool management, the entire input field is highlighted.
- When you double-click a selection field of the table editor with the mouse or press the ENT key, a pop-up window opens.
- When configuration subfiles are modified, the control no longer aborts the test run, but only displays a warning.

- You can neither set nor modify a preset without having referenced the axes, see "Traverse reference points", page 514
- The control issues a warning if the handwheel potentiometers are still active when the handwheel is deactivated, see "Traverse with electronic handwheels", page 519
- When using the HR 550 or HR 550FS handwheels, a warning is issued if the battery voltage is too low, see "Traverse with electronic handwheels", page 519
- The machine tool builder can define whether the R-OFFS offset will be taken into account for a tool with CUT 0, see "Tool table: Tool data required for automatic tool measurement", page 212
- The machine tool builder can change the simulated tool change position, see "Test run", page 599
- In the machine parameter decimalCharakter (no. 100805) you can define whether a period or a comma will be used as the decimal separator, see "Machine-specific user parameters", page 658

New and modified cycle functions 77185x-05

- New Cycle 441 FAST PROBING. With this cycle you can set various touch probe parameters (e.g. positioning feed rate) that are globally effective for all subsequently used touch probe cycles.
- Cycles 256 RECTANGULAR STUD and 257 CIRCULAR STUD were extended by the parameters Q215, Q385, Q369 and Q386.
- The feed rate behavior in Cycles 205 and 241 was changed.
- Changes of details in Cycle 233: Monitors the tooth length (LCUTS) during finishing, increases the area by Q357 in the milling direction when roughing with milling strategies 0 to 3 (provided that no limit has been set in the milling direction)
- CONTOUR DEF can be programmed in ISO format.
- The technologically outdated Cycles 1, 2, 3, 4, 5, 17, 212, 213, 214, 215, 210, 211, 230, and 231 grouped under OLD CYCLES can no longer be inserted using the editor. These cycles can still be executed and edited, however.
- The tool touch probe cycles, such as Cycles 480, 481 and 482, can be hidden
- Cycle 225 Engraving can engrave the current counter reading by using a new syntax.
- New SERIAL column in the touch probe table
- Enhancement of the contour train: Cycle 25 with Residual Material Machining, Cycle 276 Three-D Contour Train

Further information: Cycle Programming User's Manual

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First Steps with the TNC 320

1.1 Overview

This chapter is intended to help users quickly learn to handle the most important procedures on the control. For more information on a respective topic, see the section referred to in the text.

The following topics are included in this chapter:

- Machine switch-on
- Programming the first part
- Graphically testing the first part
- Setting up tools
- Workpiece setup
- Running the first program

1.2 Machine switch-on

Acknowledging the power interruption and moving to the reference points

A DANGER

Caution: Danger for the operator!

Machines and machine components always present mechanical hazards. Electric, magnetic or electromagnetic fields are particularly hazardous for persons with cardiac pacemakers or implants. The hazard starts when the machine is powered up!

- Read and follow the machine manual
- Read and follow the safety precautions and safety symbols
- Use the safety devices

 \odot

Refer to your machine manual. Switching on the machine and traversing the reference points can vary depending on the machine tool.

manua	l operation			HOT	Program	ming	
Position di	splay MODE: NOM					OOL TT TRANS QPARA	
X	+0.000	[11]	RENOM	X +0.000 Y +0.000	B C	+0.000	E a
Y	+0.000			7 +0.000	· · · ·	+0.000	1 4
			TIL	-	ROUGH		N N
Z	+110.000		L	+90.0000	R	+12.0000	
В	+0.000		DL-TAR	+0.0000	DR-TAB	+0.0000	
			DL-PGR	+0.0000	DR-PGM	+0.0000	8
C	+0.000	l.,			M50	MS	
					\$* \$		
				LBL			5100% F
æ1	T 12 Z	r		LBL		REP	5100%
S 1800	F 0mm/min		PGM CA	LL		(i) 00:00:00	OFF
Ovr 100%	M 5/9		Active	PGM: TNC:\nc_pr	ig_Stem	pel_stamp.h	
			S-OVR F-OVR	LIMIT 1			
м	s	F	TOUCH PROBE	PRESET MANAGEMENT		3D ROT	TOOL TABLE

 Switch on the power supply for control and machine The control starts the operating system. This process may take several minutes.

The control will then display the "Power interrupted" message in the screen header.

CE

Ē.

Press the CE key

The control compiles the PLC program.

- Switch on the machine control voltage The control checks operation of the emergency stop circuit and goes into Reference Run mode.
- Cross the reference point manually in the prescribed sequence: For each axis press the START key. If you have absolute linear and angle encoders on your machine there is no need for a reference run

The control is now ready for operation in the **Manual operation** mode.

- Approaching reference points
 Further information: "Switch-on", page 512
- Operating modes
 Further information: "Programming", page 82

1.3 Programming the first part

Selecting the correct operating mode

You can write programs only in **Programming** mode:

- \$
- Press the operating mode key

The control switches to the **Programming** mode of operation.

Further information on this topic

Operating modes
 Further information: "Programming", page 82

The most important control keys

Кеу	Functions for conversational guidance
ENT	Confirm entry and activate the next dialog prompt
NO ENT	Ignore the dialog question
END	End the dialog immediately
DEL	Abort dialog, discard entries
	Soft keys on the screen with which you select functions appropriate to the active operating state
Further information on this topic	

- Writing and editing programs
 Further information: "Editing an NC program", page 136
- Overview of keys
 Further information: "Controls and displays", page 2

Opening a new program/file management



Press the PGM MGT key

The control opens the file manager.

The file management of the control is arranged much like the file management on a PC with Windows Explorer. The file management enables you to manage data in the control's internal memory.

- Use the arrow keys to select the folder in which you want to open the new file
- Enter any desired file name with the extension .i

Press the ENT key The control asks you for the unit of measure for the new program.

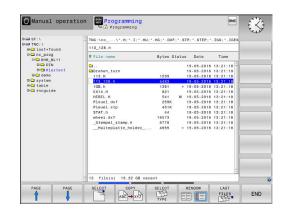
MM

ENT

 Select the unit of measure: Press the MM or INCH soft key

The control automatically generates the first and last blocks of the program. Afterwards you can no longer change these blocks.

- File management
 Further information: "Working with the file manager", page 145
- Creating a new program
 Further information: "Creating and writing programs", page 128



Defining a workpiece blank

After you have created a new program you can define a workpiece blank. For example, define a cuboid by entering the MIN and MAX points, each with reference to the selected preset.

After you have selected the desired blank form via soft key, the control automatically initiates the workpiece blank definition and asks for the required data:

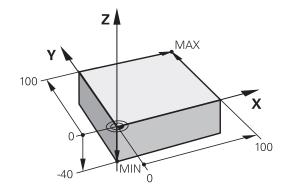
- Spindle axis Z Plane XY: Enter the active spindle axis. G17 is saved as default setting. Accept with the ENT key
- Workpiece blank def.: Minimum X: Enter the smallest X coordinate of the workpiece blank with respect to the preset, e.g. 0, confirm with the ENT key
- Workpiece blank def.: Minimum Y: Enter the smallest Y coordinate of the workpiece blank with respect to the preset, e.g. 0, confirm with the ENT key
- Workpiece blank def.: Minimum Z: Enter the smallest Z coordinate of the workpiece blank with respect to the preset, e.g. -40, confirm with the ENT key
- Workpiece blank def.: Maximum X: Enter the largest X coordinate of the workpiece blank with respect to the preset, e.g. 100, confirm with the ENT key
- Workpiece blank def.: Maximum Y: Enter the largest Y coordinate of the workpiece blank with respect to the preset, e.g. 100, confirm with the ENT key
- Workpiece blank def.: Maximum Z: Enter the largest Z coordinate of the workpiece blank with respect to the preset, e.g. 0, confirm with the ENT key The control ends the dialog.

Example

%NEW G71 *
N10 G30 G17 X+0 Y+0 Z-40*
N20 G31 X+100 Y+100 Z+0*
N99999999 %NEW G71 *

Further information on this topic

 Define workpiece blank
 Further information: "Creating a new NC program", page 132



Program layout

NC programs should be arranged consistently in a similar manner. This makes it easier to find your place, accelerates programming and reduces errors.

Recommended program layout for simple, conventional contour machining

Example

%BSPCONT G71 *
N10 G30 G71 X Y Z*
N20 G31 X Y Z*
N30 T5 G17 S5000*
N40 G00 G40 G90 Z+250*
N50 X Y*
N60 G01 Z+10 F3000 M13*
N70 X Y RL F500*
N160 G40 X Y F3000 M9*
N170 G00 Z+250 M2*
N9999999 BSPCONT G71 *

- 1 Call tool, define tool axis
- 2 Retract the tool
- 3 Pre-position the tool in the working plane near the contour starting point
- 4 In the tool axis, position the tool above the workpiece, or preposition immediately to workpiece depth. If required, switch on the spindle/coolant
- 5 Contour approach
- 6 Contour machining
- 7 Contour departure
- 8 Retract the tool, end program

Further information on this topic

 Contour programming
 Further information: "Programming tool movements for workpiece machining", page 248

Recommended program layout for simple cycle programs Example

%BSBCYC G71 *
N10 G30 G71 X Y Z*
N20 G31 X Y Z*
N30 T5 G17 S5000*
N40 G00 G40 G90 Z+250*
N50 G200*
N60 X Y*
N70 G79 M13*
N80 G00 Z+250 M2*
N9999999 BSBCYC G71 *

- 1 Call tool, define tool axis
- 2 Retract the tool
- 3 Define the fixed cycle
- 4 Move to the machining position
- 5 Call the cycle, switch on the spindle/coolant
- 6 Retract the tool, end program

Further information on this topic

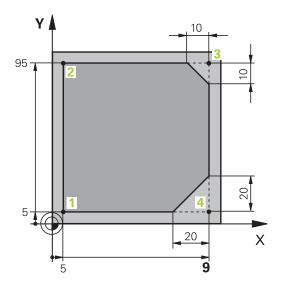
Cycle programming
 Further information: Cycle Programming User's Manual

Programming a simple contour

TOOL CALL

The contour shown to the right is to be milled once to a depth of 5 mm. You have already defined the workpiece blank. After you have initiated a dialog through a function key, enter all the data requested by the control in the screen header.

Call the tool: Enter the tool data. Confirm the entry in each case with the ENT key, and do not forget the G17 tool axis Press the L key to open a program block for a linear movement Press the left arrow key to switch to the input range for G codes Press the G00 soft key if you want to enter a G00 rapid traverse motion Press the **G90** soft key for absolute values G90 Retract tool: Press the orange axis key Z and enter the value for the position to be approached, e.g. 250. Press the ENT key Activate no radius compensation: Press the G40 G40 soft key Confirm Miscellaneous function M? with the END key The control stores the entered positioning block. Press the L key to open a program block for a linear movement Press the left arrow key to switch to the input range for G codes Press the GOO soft key if you want to enter a G00 rapid traverse motion Preposition the tool in the working plane: Press the orange X axis key and enter the value for the position to be approached, e.g. -20 Press the orange axis key Y and enter the value for the position to be approached, e.g. -20. Confirm your entry with the ENT key. Activate no radius compensation: Press the G40 G40 soft key Confirm Miscellaneous function M? with the ► **END** key The control stores the entered positioning block. Press the L key to open a program block for a linear movement Press the left arrow key to switch to the input range for G codes Press the G00 soft key if you want to enter a G00 rapid traverse motion



	•	Move tool to working depth: Press the orange axis key Z and enter the value for the position to be approached, e.g5. Press the ENT key
G 4 Ø		
	•	Miscellaneous function M? Switch on the spindle and coolant, e.g. M13 , and confirm with the END key
		The control stores the entered positioning block.
L	•	Press the ${\rm \textbf{L}}$ key to open an NC block for a linear movement
	•	Enter the coordinates of the contour starting point 1 in X and Y, e.g. 5/5, and confirm with the ENT key
G 4 1		Activate radius compensation to the left of the path: Press the G41 soft key
	•	Feed rate F=? Enter the machining feed rate, e.g. 700 mm/min, save your entry with the END key
G	•	Enter 26 to approach the contour: Define Rounding-off radius? for the circular arc, save entries with the END key
L		Machine the contour and move to contour point 2 : You only need to enter the information that changes. In other words, enter only the Y coordinate 95 and save your entry with the END key
L		Move to contour point 3 : Enter the X coordinate 95 and save your entry with the END key
CHF o	•	Define chamfer G24 at contour point 3 : Enter 10 mm for Chamfer side length? , save with the END key
L		Move to contour point 4 : Enter the Y coordinate 5 and save your entry with the END key
CHF o	•	Define chamfer G24 at contour point 4 : Enter 20 mm for Chamfer side length? , save with the END key
L	•	Move to contour point 1 : Enter the X coordinate 5 and save your entry with the END key
G		Enter 27 to depart from the contour: Define the Rounding-off radius? of the departing arc
L	•	Depart contour: Enter coordinates outside of the workpiece in X and Y, e.g20/-20, confirm with the ENT key
		Activate no radius compensation: Press the G40 soft key

- Press the L key to open an NC block for a linear movement
- Press the G00 soft key if you want to enter a rapid traverse motion
- Retract tool: Press the orange axis key Z to retract in the tool axis, and enter the value for the position to be approached, e.g. 250. Press the ENT key
- Activate no radius compensation: Press the G40 soft key
- Miscellaneous function M? Enter M2 to end the program, then confirm with the END key The control stores the entered positioning block.

Further information on this topic

L_

- Complete example with NC blocks
 Further information: "Example: Linear movements and chamfers with Cartesian coordinates", page 271
- Creating a new program
 Further information: "Creating and writing programs", page 128
- Approaching/departing contours
 Further information: "Approaching and departing a contour", page 251
- Programming contours
 Further information: "Overview of path functions", page 262
- Tool radius compensation
 Further information: "Tool radius compensation ", page 230
- Miscellaneous functions M
 Further information: "Miscellaneous functions for program run inspection, spindle and coolant ", page 428

Creating a cycle program

The holes (depth of 20 mm) shown in the figure at right are to be drilled with a standard drilling cycle. You have already defined the workpiece blank.

TOOL CALL

- Call the tool: Enter the tool data. Confirm the entry in each case with the ENT key, do not forget the tool axis
- Press the L key to open an NC block for a linear movement
- Press the left arrow key to switch to the input range for G codes
- G00
- Press the G00 soft key if you want to enter a rapid traverse motion
- Press the G90 soft key for absolute values
- Retract tool: Press the orange axis key Z and enter the value for the position to be approached, e.g. 250. Press the ENT key
- Activate no radius compensation: Press the G40 soft key
- Miscellaneous function M? Switch on the spindle and coolant, e.g. M13. Confirm with the END key

The control stores the entered positioning block.

► Call the cycle menu: Press the CYCL DEF key

DRILLING/ THREAD

200

G

G

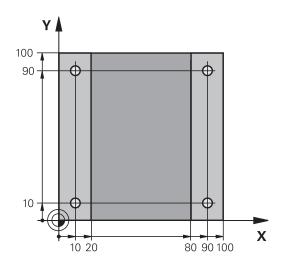
G

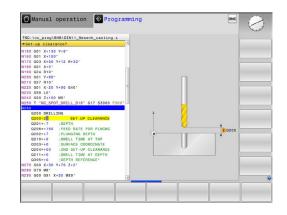
CYCL DEF

- Display the drilling cycles
- Select standard drilling cycle 200
 The control starts the dialog for cycle definition.
- Enter all parameters requested by the control step by step and conclude each entry with the ENT key

In the screen to the right, the control also displays a graphic showing the respective cycle parameter

- Enter 0 to approach the first drilling position: Enter the coordinates of the drilling position, call the cycle with M99
- Enter 0 to move to further drilling positions: Enter the coordinates of the specific drilling positions, and call the cycle with M99
- Enter 0 to retract the tool: Press the orange axis key Z and enter the value for the position to be approached, e.g. 250. Press the ENT key
- Miscellaneous function M? Enter M2 to end the program, then confirm with the END key The control stores the entered positioning block.





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Example

%C200 G71 *		
N10 G30 G17 X+0 Y+0 Z-40*		Workpiece blank definition
N20 G31 X+100 Y+100 Z+0*		
N30 T5 G17 S4500*		Tool call
N40 G00 G90 Z+250 G40*		Retract the tool
N50 G200 DRILLING		Define the cycle
Q200=2	;SET-UP CLEARANCE	
Q201=-20	;DEPTH	
Q206=250	;FEED RATE FOR PLNGNG	
Q202=5	;PLUNGING DEPTH	
Q210=0	;DWELL TIME AT TOP	
Q203=-10	;SURFACE COORDINATE	
Q204=20	;2ND SET-UP CLEARANCE	
Q211=0.2	;DWELL TIME AT DEPTH	
Q395=0	;DEPTH REFERENCE	
N60 G00 X+10 Y+10 M13 M99*		Spindle and coolant on, call the cycle
N70 G00 X+10 Y+90 M99*		Call the cycle
N80 G00 X+90 Y+10 M99*		Call the cycle
N90 G00 X+90 Y+90 M99*		Call the cycle
N100 G00 Z+250 M2*		Retract the tool, end program
N99999999 %C200 G71 *		

- Creating a new program
 Further information: "Creating and writing programs", page 128
- Cycle programming
 Further information: Cycle Programming User's Manual

1.4 Graphically testing the first part

Selecting the correct operating mode

You can test programs in the **Test Run** operating mode:

- $\overline{}$
- Press the operating mode key
 - The control switches to the **Test Run** mode of operation.

Further information on this topic

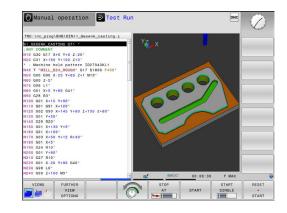
- Operating modes of the control
 Further information: "Modes of operation", page 81
- Testing programs
 Further information: "Test run", page 599

Selecting the tool table for the test run

If you have not yet activated a tool table in **Test Run** mode, then you must carry out this step.

PGM MGT	►	Press the PGM MGT key
		The control opens the file manager.
SELECT		Press the SELECT TYPE soft key
		The control shows a soft-key menu for selection of the file type to be displayed.
DEFAULT		Press the DEFAULT soft key
		The control shows all saved files in the right-hand window.
+		Move the cursor to the left onto the directories
t		Move the cursor to the TNC:\table directory
-		Move the cursor to the right onto the files
ŧ		Move the cursor onto the file TOOL.T (active tool table), confirm with the ENT key: TOOL.T contains the status S and is therefore active for Test Run
END		Press the END key: Exit the file manager

- Tool management
 Further information: "Entering tool data into the table", page 208
- Testing programs
 Further information: "Test run", page 599



Choosing the program you want to test



Press the PGM MGT key

- The control opens the file manager.
- LAST FILES
- Press the LAST FILES soft key

The control opens a pop-up window with the most recently selected files.

Use the arrow keys to select the program that you want to test. Load with the ENT key

Further information on this topic

 Program number
 Further information: "Working with the file manager", page 145

Selecting the screen layout and the view



Press the key for selecting the screen layout The control displays all available alternatives in the soft-key row.



Press the PROGRAM + GRAPHICS soft key In the left half of the screen the control shows the program; in the right half it shows the workpiece blank.

The control features the following views:

Soft keys	Function
VIEWS	Volume view
VIEWS	Volume view and tool paths
VIEWS	Tool paths

- Graphic functions
 Further information: "Graphics ", page 586
- Performing a test run
 Further information: "Test run", page 599

Starting the test run

RESET	Press the RESET + START soft key
START	The control resets the previously active tool data
	The control simulates the active program up to a programmed break or to the program end
	While the simulation is running, you can use the soft keys to change views
STOP	Press the STOP soft key
3106	The control interrupts the test run
START	Press the START soft key
STHRT	The control resumes the test run after a break

- Performing a test run Further information: "Test run", page 599
- Graphic functions Further information: "Graphics ", page 586
- Adjusting the simulation speed Further information: "Speed of the setting test runs", page 587

1.5 Setting up tools

Selecting the correct operating mode

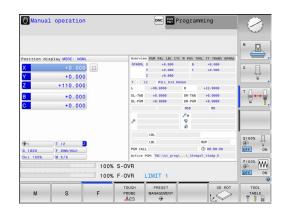
Tools are set up in the Manual operation mode:

- M
- Press the operating mode key

The control switches to the **Manual operation** mode.

Further information on this topic

Operating modes of the control
 Further information: "Modes of operation", page 81



Preparing and measuring tools

- Clamp the required tools in their tool holders
- When measuring with an external tool presetter: Measure the tools, note down the length and radius, or transfer them directly to the machine through a transfer program
- When measuring on the machine: store the tools in the tool changer

Further information: "The pocket table TOOL_P.TCH", page 73

The tool table TOOL.T



Refer to your machine manual.

The procedure for calling the tool management may differ from that described below.

In the TOOL.T tool table (permanently stored under **TNC:\table**\), you can save tool data such as length and radius, as well as further tool-specific information that the control needs in order to execute a wide variety of functions.

To enter tool data in the tool table TOOL.T, proceed as follows:

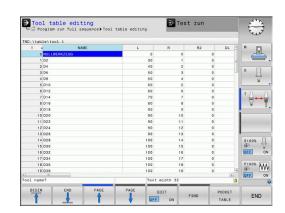


Display the tool table

The control shows the tool table.

- Edit the tool table: Set the EDIT soft key to ON
- With the upward or downward arrow keys you can select the tool number that you want to edit
- With the rightward or leftward arrow keys you can select the tool data that you want to edit
- To exit the tool table, press the **END** key

- Operating modes of the control
 Further information: "Modes of operation", page 81
- Working with the tool table
 Further information: "Entering tool data into the table", page 208
- Using the tool management (option 93)
 Further information: "Calling tool management", page 234



The pocket table TOOL_P.TCH



Refer to your machine manual.

The function of the pocket table depends on the machine.

In the pocket table TOOL_P.TCH (permanently saved under **TNC:\table**) you specify which tools your tool magazine contains. To enter data in the pocket table TOOL_P.TCH, proceed as follows:



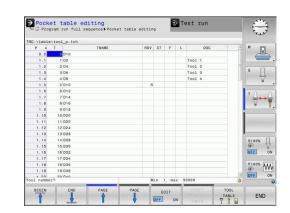
- Display the tool table
 - The control shows the tool table.



- Display the pocket table
 The control shows the pocket table.
- Edit the pocket table: Set the EDIT soft key to ON
- With the upward or downward arrow keys you can select the pocket number that you want to edit
- With the rightward or leftward arrow keys you can select the data that you want to edit
- ► To leave the pocket table, press the **END** key

Further information on this topic

- Operating modes of the control
 Further information: "Modes of operation", page 81
- Working with the pocket table
 Further information: "Pocket table for tool changer", page 219



1.6 Workpiece setup

Selecting the correct operating mode

Workpieces are set up in the $\ensuremath{\text{Manual operation}}$ or $\ensuremath{\text{Electronic}}$ handwheel mode



Press the operating mode key

The control switches to the **Manual operation** mode.

Further information on this topic

The operating mode Manual operation
 Further information: "Moving the machine axes", page 517

Clamping the workpiece

Mount the workpiece with a fixture on the machine table. If you have a 3-D touch probe on your machine, then you do not need to clamp the workpiece parallel to the axes.

If you do not have a 3-D touch probe available, you have to align the workpiece so that it is fixed with its edges parallel to the machine axes.

Further information on this topic

- Presetting with a 3-D touch probe
 Further information: "Presetting with a 3-D touch probe ", page 562
- Presetting without 3-D touch probe
 Further information: "Presetting without a 3-D touch probe", page 538

Presetting with a 3-D touch probe

Insert a 3-D touch probe: In the Positioning w/ Manual Data Input mode, run a T block containing the tool axis and then return to the Manual operation mode



Press the TOUCH PROBE soft key

The control displays the available functions in the soft-key row.



- Set the preset at a workpiece corner, for example
- Use the axis direction keys to position the touch probe near the first touch point on the first workpiece edge
- Select the probing direction via soft key
- Press the NC start key

The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point.

- Use the axis direction keys to pre-position the touch probe near the second touch point on the first workpiece edge
- Press the NC start key

The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point.

- Use the axis direction keys to pre-position the touch probe near the first touch point on the second workpiece edge
- Select the probing direction via soft key
- Press the NC start key

The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point.

- Use the axis direction keys to pre-position the touch probe near the second touch point on the second workpiece edge
- Press the NC start key

The touch probe moves in the defined direction until it contacts the workpiece and then automatically returns to its starting point. The control then displays the coordinates of the measured corner point.



- To set to 0: Press the SET PRESET soft key
- Press the END soft key to close the menu

Further information on this topic

Presetting

Further information: "Presetting with a 3-D touch probe ", page 562

1.7 Running the first program

Selecting the correct operating mode

You can run programs either in the **Program run, single block** or the **Program run, full sequence** mode:

Ð

-

- Press the operating mode key The control switches to the operating mode
 Program run, single block, and executes the NC program block by block.
- You have to confirm each block with the NC start key
- Press the operating mode key The control switches to the operating mode **Program run, full sequence**, and executes the program after NC start up to a program interruption or to the end of the program

Further information on this topic

- Operating modes of the control
 Further information: "Modes of operation", page 81
- Executing a program Further information: "Program run", page 603

Choosing the program you want to run



Press the PGM MGT key

The control opens the file manager.

- LAST FILES
- Press the LAST FILES soft key
 - The control opens a pop-up window with the most recently selected files.
- Use the arrow keys if required to select the program you want to run. Load with the ENT key

Further information on this topic

- File management
 - **Further information:** "Working with the file manager", page 145

Starting the program

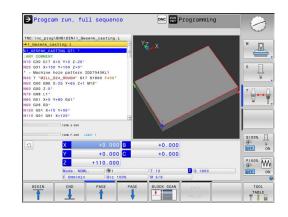


Press the NC start key

The control runs the active program.

Further information on this topic

Executing a program Further information: "Program run", page 603





Introduction

2.1 The TNC 320

HEIDENHAIN TNC controls are workshop-oriented contouring controls that enable you to program conventional milling and drilling operations right at the machine in easy-to-use Klartext conversational language. They are designed for milling, drilling and boring machines, as well as machining centers, with up to 6 axes. You can also change the angular position of the spindle under program control.

Keyboard and screen layout are clearly arranged in such a way that the functions are fast and easy to use.



HEIDENHAIN Klartext and DIN/ISO

HEIDENHAIN Klartext, the dialog-guided programming language for workshops, is an especially easy method of writing programs. Programming graphics illustrate the individual machining steps for programming the contour. If no NC-dimensioned drawing is available, then the FK free contour programming will help. Workpiece machining can be graphically simulated either during a test run or during a program run.

It is also possible to program in ISO format or DNC mode.

You can also enter and test one program while the control is running another.

Compatibility

Machining programs created on HEIDENHAIN contouring controls (starting from the TNC 150 B) may not always run on the TNC 320. If the NC blocks contain invalid elements, the control will mark these as ERROR blocks or with error messages when the file is opened.



Please also note the detailed description of the differences between the iTNC 530 and the TNC 320. **Further information:** "Functions of the TNC 320 and the iTNC 530 compared", page 684.

2.2 Visual display unit and operating panel

Display screen

The control is available either as a compact version or with a separate display unit and operating panel. Both variants of the control come with a 15-inch TFT color flat-panel display.

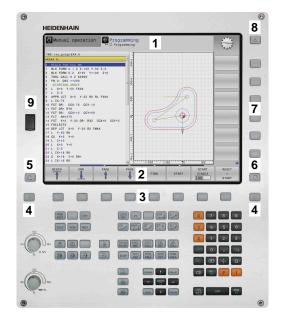
1 Header

When the control is on, the screen displays the selected operating modes in the header: The machine operating mode at left and the programming mode at right. The currently active mode is displayed in the larger field of the header, where the dialog prompts and messages also appear (exception: if the control only displays graphics).

2 Soft keys

In the footer the control indicates additional functions in a soft-key row. You can select these functions by pressing the keys immediately below them. The thin bars immediately above the soft-key row indicate the number of soft-key rows that can be called with the keys to the right and left that are used to switch the soft keys. The bar representing the active soft-key row is blue

- **3** Soft-key selection keys
- **4** Keys for switching the soft keys
- 5 Setting the screen layout
- **6** Key for switchover between machine operating modes, programming modes, and a third desktop
- 7 Soft-key selection keys for machine tool builders
- 8 Keys for switching the soft keys for machine tool builders
- 9 USB connection



Setting screen layout

The screen layout is user-selectable. In the **Programming** mode, for example, you can have the control show program blocks in the left window while the right window displays programming graphics. You could also display the program structure in the right window instead, or display only program blocks in one large window. The available screen windows depend on the selected operating mode.

Set up screen layout:

Ο

 Press the screen layout key: The soft-key row shows the available layout options
 Further information: "Modes of operation", page 81



Select the desired screen layout with a soft key

Control panel

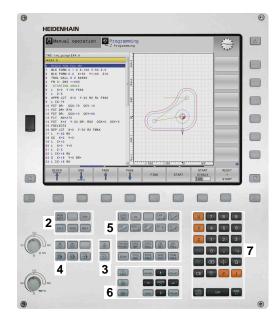
The TNC 320 is delivered with an integrated operating panel. As an alternative, the TNC 320 is also available with a separate display unit and an operating panel with an alphabetic keyboard.

- 1 Alphabetic keyboard for entering texts and file names, as well as for ISO programming
- **2** File management
 - Calculator
 - MOD function
 - HELP function
 - Show error messages
- 3 Programming modes
- 4 Machine operating modes
- **5** Initiating programming dialogs
- 6 Navigation keys and GOTO jump command
- 7 Numerical input and axis selection
- 10 Machine operating panel More information Machine manual

The functions of the individual keys are described on the inside front cover.

Refer to your machine manual. Some machine tool builders do not use the standard HEIDENHAIN operating panel.

External keys, e.g.**NC START** or **NC STOP**, are described in your machine manual.



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2.3 Modes of operation

Manual Operation and El. Handwheel

The **Manual operation** mode is required for setting up the machine tool. In this mode of operation, you can position the machine axes manually or by increments, set the presets and tilt the working plane.

The **Electronic handwheel** mode of operation allows you to move the machine axes manually with the HR electronic handwheel.

Soft keys for the screen layout	(select as described above)
---------------------------------	-----------------------------

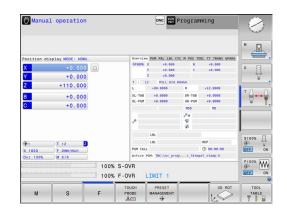
Soft key	Window
POSITION	Positions
POSITION + STATUS	Left: positions, right: status display
POSITION + KINEMATICS	Left: positions, right: collision object

Positioning with Manual Data Input

This mode of operation is used for programming simple traversing movements, such as for face milling or pre-positioning.

Soft keys for selecting the sc	reen layout
--------------------------------	-------------

Soft key	Window
PGM	Program
PROGRAM + STATUS	Left: program, right: status display
POSITION + KINEMATICS	Left: program, right: collision object



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SMDI G71 .					Y	+87.093	c	+	0.000	
10 T7 G17 S1					z	-115.000				
	Y+150 Z+100	540 M3*	-	T : 1		MILL_D24_R				S E
1999999999 %\$M	DI G71 .			L		.0000	R		.0000	8
			1	DL-TAB		.0000	DR - TAE		.0000	7
				DL-PGM	+0	.0000	DR - PGP		.0000	
							MS		M9	τЛ
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	1000 5-000				LBL			REP		
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	100% F-OVR LI	117 1		Active	PGN: T	NC:\nc_prog	\\$mdi.i			S100% [
0	X	-4.764	в		÷	0.000				OFF
	Y	+87.093	С		2	0.000				
	Z	-5.000								F100% W
	Mode: NOML				T 12		ZS	1800		OFF
	F Omm/min	0vr 10	0%		M 5					(Sec.)
STATUS	STATUS	TOOL	ST	TUS	ST	TUS OF			-	
				DRD.						

Programming

In this mode of operation you create NC programs. The FK free programming feature, the various cycles and the Q parameter functions help you with programming and add necessary information. If desired, you can have the programming graphics show the programmed paths of traverse.

Soft keys for selecting the screen layout

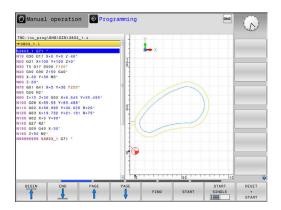
Soft key	Window
PGM	Program
PROGRAM + SECTS	Left: program, right: program structure
PROGRAM + GRAPHICS	Left: program blocks, right: programming graph- ics

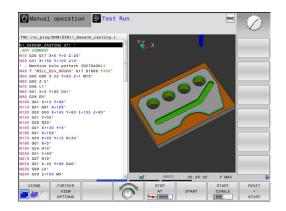
Test Run

In the **Test Run** mode of operation, the control checks NC programs and program sections for errors, such as geometrical incompatibilities, missing or incorrect data within the program or violations of the working space. This simulation is supported graphically in different display modes.

Soft keys for selecting the screen layout

Soft key	Window
PGM	Program
PROGRAM + STATUS	Left: program, right: status display
PROGRAM + GRAPHICS	Left: program, right: graphics
GRAPHICS	Graphic





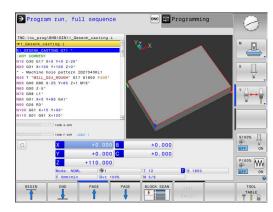
Program Run, Full Sequence and Program Run, Single Block

In the **Program Run Full Sequence** mode, the control executes a program continuously to its end or to a manual or programmed stop. You can resume program run after an interruption.

In the **Program Run Single Block** mode, you execute each block separately by pressing the **NC start** key. With point pattern cycles and **CYCL CALL PAT** the controls stops after each point.

Soft keys for selecting the screen layout

Soft key	Window
PGM	Program
PROGRAM + SECTS	Left: program, right: structure
PROGRAM + STATUS	Left: program, right: status display
PROGRAM + GRAPHICS	Left: program, right: graphics
GRAPHICS	Graphic



2.4 Status displays

General status display

The general status display in the lower part of the screen informs you of the current state of the machine.

It is displayed automatically in the following operating modes:

Program run, single block

i

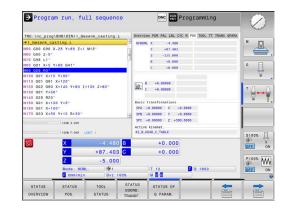
- Program run, full sequence
- Positioning w/ Manual Data Input

If the **GRAPHICS** screen layout is selected the status display is not shown.

In the **Manual operation** and **Electronic handwheel** modes the status display appears in the large window.

Information in the status display

lcon	Meaning
ACTL.	Position display: Actual, nominal or distance-to-go coordinates mode
XYZ	Machine axes; the control displays auxiliary axes in lower-case letters. The sequence and quantity of displayed axes is determined by the machine tool builder. Refer to your machine manual for more information
•	Number of the active preset from the preset table. If the preset was set manually, the control displays the text MAN behind the symbol
FSM	The displayed feed rate in inches corresponds to one tenth of the effective value. Spindle speed S, feed rate F and active M functions
•	Axis is clamped
\oslash	Axis can be moved with the handwheel
	Axes are moving under a basic rotation
	Axes are moving under a 3-D basic rotation
	Axes are moving in a tilted working plane
4	Axes are mirrored and moved



Meaning

is active

lcon

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 ${\bf c}$

	terminated
	In this condition the control has no modally effec- tive program information (i.e. the contextual refer- ence), so that all handling is possible, e.g. cursor movements or modification of Q parameters.
ET)	Program started, execution runs
	For safety reasons, the control permits no handling in this condition
D	Program stopped, e.g. in operating mode Program run, full sequence after pressing the NC stop key
	For safety reasons, the control permits no handling in this condition
	Program interrupted, e.g. in operating mode Positioning w/ Manual Data Input following the error-free execution of an NC block In this condition the control permits various
	handling, e.g. cursor movements or the modifi- cation of Q parameters. With this handling the control may lose the modally effective program information (i.e. the contextual reference). Loss of this contextual reference may cause undesired tool positions!
	Further information: "Programming and execut- ing simple machining operations", page 580 and "Program-controlled interruptions", page 606
×	Program aborted or terminated
s %	Pulsing spindle speed function is active
6	The order of icons can be changed with the optional machine parameter iconPrioList (no. 100813). The

control-in-operation symbol is always visible and cannot

The function for traversing in the tool-axis direction

No program selected, program reselected,

program aborted via internal stop or program

be configured.

Additional status displays

The additional status displays contain detailed information on the program run. This can be called in all operating modes except for the **Programming** mode.

To switch on the additional status display

O

Call the soft key row for screen layout

PROGRAM

STATUS

Select the layout option for the additional status display

In the right half of the screen, the control shows the **Overview** status form.

To select an additional status display



- Toggle through the soft key rows until the **STATUS** soft keys appear
- STATUS POS.
- Either select the additional status display directly with the soft key, e.g. positions and coordinates; or
- ► use the switch-over soft keys to select the desired view

Select the status displays described below as follows:

- directly with the corresponding soft key
- via the switchover soft keys
- or by using the **next tab** key

Ö

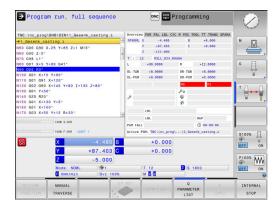
Please note that some of the status information described below is not available unless the associated software option is enabled on your control.

Overview

The **Overview** status form is displayed by the control following switch-on if you selected the screen layout PROGRAM + STATUS (or **POSITION + STATUS**). The overview form contains a summary of the most important status information, which you can also find on the various detail forms.

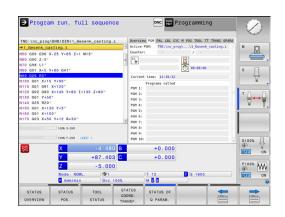
Soft key	Meaning
STATUS OVERVIEW	Position display
	Tool information
	Active M functions
	Active coordinate transformations
	Active subprogram
	Active program section repeat
	Program called with %
	Current machining time

Name and path of the active main program



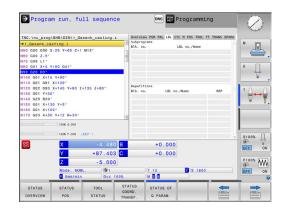
General program information (PGM tab)

Soft key	Meaning
No direct selection possible	Name and path of the active main program
	Actual/nominal value counter
	Circle center CC (pole)
	Dwell time counter
	Current machining time
	Current time
	Active programs



Program section repeats and subprograms (LBL tab)

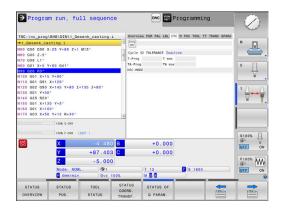
Soft key	Meaning
No direct selection possible	Active program section repeats with block number, label number, and number of programmed repeats/repeats yet to be run
	Active subprograms with block number in which the subprogram was called and the label number that was called



Information on standard cycles (CYC tab)

Soft key	Meaning
No direct selection possible	Active fixed cycle

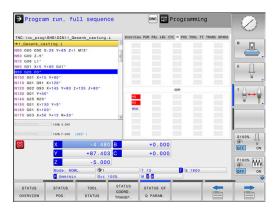
Active values of Cycle 32 Tolerance



Active miscellaneous functions M (M tab)

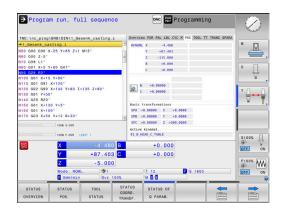
Soft key	Meaning
No direct selection possible	List of the active M functions with fixed meaning

List of the active M functions that are adapted by your machine manufacturer



Positions and coordinates (POS tab)

Soft key	Meaning
STATUS POS.	Type of position display, e.g. actual position
	Tilt angle of the working plane
	Angle of basic transformations
	Active kinematics



Information on tools (TOOL tab)

Soft key	Meaning				
TOOL	Display of active tool:				
STATUS	T: Tool number and tool name				
	RT: Number and name of a replacement tool				
	Tool axis				
	Tool length and tool radii				
	Oversizes (delta values) from the tool table (TAB) and the TOOL CALL (PGM)				
	Tool life, maximum tool life (TIME 1) and maximum tool life for TOOL CALL (TIME 2)				
	Display of programmed tool and replacement tool				

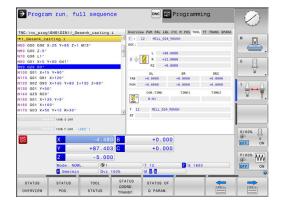
Display of programmed tool and replacement tool

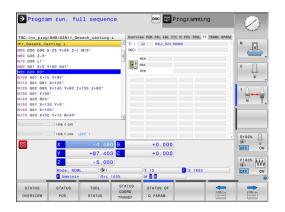
Tool measurement (TT tab)



The control displays this tab only if the function is active on your machine.

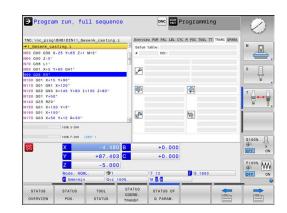
Soft key	Meaning
No direct selection possible	Active tool
	Measured values from tool measurement





Coordinate transformations (TRANS tab)

Soft key	Meaning
STATUS COORD. TRANSF.	Name of the active datum table
	Active datum number (#), comment from the active line of the active datum number (DOC) from Cycle G53
	Active datum shift (Cycle G54); the control displays an active datum shift in up to 8 axes
	Mirrored axes (Cycle G28)
	Active rotation angle (Cycle G73)
	Active scaling factor/factors (Cycle G72); the control displays an active scaling factor in up to 6 axes
	Scaling datum
A In	the optional machine parameter CfgDisplayCoordSys



6

In the optional machine parameter **CfgDisplayCoordSys** (no. 127501) you can specify the coordinate system in which the status display shows an active datum shift.

Further information: Cycle Programming User's Manual

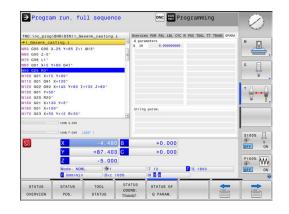
Displaying Q parameters (QPARA tab)

Soft key	Meaning				
STATUS OF Q PARAM.	Display the current values of the defined Q parameters				
	Display the character strings of the defined string parameters				

6

Press the **Q PARAMETER LIST** soft key. The control opens a pop-up window. For each parameter type (Q, QL, QR, QS) define the parameter numbers you wish to control. Separate single Q parameters with a comma, and connect sequential Q parameters with a hyphen, e.g. 1,3,200-208. The input range per parameter type is 132 characters.

The display in the **QPARA** tab always contains eight decimal places. The result of $Q1 = COS \ 89.999$ is shown by the control as 0.00001745, for example. Very large and very small values are displayed by the control in exponential notation. The result of $Q1 = COS \ 89.999 \ * 0.001$ is shown by the control as +1.74532925e-08, whereby e-08 corresponds to the factor of 10⁻⁸.



2.5 Window manager

Refer to your machine manual.

The machine tool builder determines the scope of function and behavior of the window manager.

The control features the Xfce window manager. Xfce is a standard application for UNIX-based operating systems, and is used to manage graphical user interfaces. The following functions are possible with the window manager:

- Display a task bar for switching between various applications (user interfaces)
- Manage an additional desktop, on which special applications from your machine manufacturer can run
- Control the focus between NC software applications and those of the machine manufacturer
- You can change the size and position of pop-up windows. It is also possible to close, minimize and restore pop-up windows

The control shows a star in the upper left of the screen if an application of the window manager or the window manager itself has caused an error. In this case, switch to the window manager and correct the problem. If required, refer to your machine manual.

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Overview of taskbar

In the task bar you can choose different workspaces by mouse click.

The control provides the following workspaces:

- Workspace 1: Active operating mode
- Workspace 2: Active programming mode
- Workspace 3: CAD-Viewer or applications of the machine tool builder (optionally available)
- Workspace 4: applications of the machine tool builder (optionally available)

In addition, you can also select other applications from the task bar which you have started in parallel to the control software, e.g. the **TNCguide**.



You can randomly move all open applications to the right of the green HEIDENHAIN symbol between the workspaces by pressing and holding the left mouse button.

Click the green HEIDENHAIN symbol to open a menu in which you can get information, make settings or start applications.

The following functions are available:

- About HEROS: Open information about the operating system of the control
- NC Control: Start and stop the control software (for diagnostic purposes only)
- Web Browser: Start the web browser
- Diagnostic: Diagnostic applications
 - **GSmartControl**: Available only to authorized specialists
 - **HE Logging**: Define settings for internal diagnostic files
 - **HE Menu**: Available only to authorized specialists
 - perf2: Check processor load and process load
 - Portscan: Test active connections
 Further information: "Portscan", page 93
 - Portscan OEM: Available only to authorized specialists
 - RemoteService: Start and stop remote maintenance
 Further information: "Remote Service", page 94
 - **Terminal**: Enter and execute console commands
- **Settings**: Operating system settings
 - Date/Time: Set date and time
 - Language/Keyboards: Select system dialog language and keyboard version—the control overwrites the setting of the system dialog language when starting with the language setting of the machine parameter CfgDisplayLanguage (no. 101300)
 - Network: Define network settings
 - Printer: Configure and manage printer
 Further information: "Printer", page 96
 - Screensaver: Define screensaver

							09:42
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⊡ nc_prog © — demo	€ File name		Bytes S	Status	Date	Time	
🕀 😂 PGM	EX16.H		997	+ 09	01-2014	12:28:55	
D-C PGM2	EX16 SL.H		1792			12:28:55	Participant and a second second
IB-C PGM3	EX18.H		833	+ 01	-01-201	12:28:55	
🕮 🖵 system	EX18 SL.H		1513	+ 05	.01-2014	12:28:55	
🗉 🗀 table	EX4.H		1036	01	-01-201-	12:28:55	
🕮 🖵 tncguide	HEBEL . H		541	+ 01	-01-2014	12:28:55	
	koord.h		2375	+ 14	-01-2014	10:02:46	
	NEUGL . I		684	+ 01	-01-2014	12:28:55	
	PAT.H		158	01	-01-2014	12:28:55	
	PL1.H		2700	+ 14	-01-2014	12:00:46	
	Ra-Pl.h		6920	05	-01-2014	12:28:55	
	RAD6 . h		400	E + 10	0-01-2014	05:52:31	
	Rastplatte	. h	4837	01	0-01-2014	12:28:55	
	Reset.H		380	+ 09	9-01-2014	12:28:55	
	Schulter.h		3599	01	-01-2014	12:28:55	
	STAT.H		479	01	-01-2014	12:28:55	
	STAT1.H		623	09	9-01-2014	12:28:55	
	TCH.h		1275	01	0-01-2014	12:28:55	
	turbine.H		2065			12:28:55	
	Über HeROS	Eldschimschoner	1127			12:28:55	
	NC Control	Date/Time	1195			12:28:55	
0	Webbrowser	🖓 Frewall	2671K	01	0-01-2014	12:28:57	
9	Remote Desktop Manager	G Language					
	Diagnostic >	Network	_				
PAGE PAG	Einstellungen	* SELinux	CT	WINC	OW	LAST	
	Tools >	Shares	Fi			FILES	END
SII 7	C 601 -	WindowManagerConfig	50	12 (TNCqui		NC Control Panel	09:42:26 0

- SELinux: Define safety software for Linux-based operating systems
- Shares: Connect and manage external network drives
- VNC: Define the setting for external software accessing the control for e.g. maintenance work (Virtual Network Computing)
 Further information: "VNC", page 99
- WindowManagerConfig: Available only to authorized specialists
- Firewall: Configure the firewall
 Further information: "Firewall", page 649
- HePacketManager: Available only to authorized specialists
- HePacketManager Custom: Available only to authorized specialists
- **Tools**: File applications
 - Document Viewer: Display and print files, e.g. PDF files
 - File Manager: Available only to authorized specialists
 - Geeqie: Open, manage, and print graphics
 - **Gnumeric**: Open, edit, and print tables
 - **Keypad**: Open virtual keyboard
 - Leafpad: Open and edit text files
 - NC/PLC Backup: Create backup file
 Further information: "Backup and restore", page 101
 - NC/PLC Restore: Restore backup file
 Further information: "Backup and restore", page 101
 - Ristretto: Open graphics
 - Screenshot: Create screenshots
 - TNCguide: Call up help system
 - Xarchiver: Extract or compress directories
 - Applications: Supplementary applications
 - Orage Calender: Open calendar
 - Real VNC viewer: Define the setting for external software accessing the control for e.g. maintenance work (Virtual Network Computing)
- The applications available under tools can be started directly by selecting the corresponding file type in the file management of the control
 Further information: "Additional tools for management of external file types", page 158

Portscan

The PortScan function enables the cyclic or manual searching for all open, incoming TCP and UDP list ports on the system. All ports found are compared with whitelists. If the control finds a non-listed port it shows a corresponding pop-up window.

The HeROS **Diagnostic** menu contains the **Portscan** and **Portscan OEM** applications for this purpose. **Portscan OEM** is only executable after entering the machine manufacturer password.

The **Portscan** function searches for all open, incoming TCP and UDP ports on the system and compares them to four whitelists stored in the system:

- System-internal whitelists /etc/sysconfig/portscanwhitelist.cfg and /mnt/sys/etc/sysconfig/portscanwhitelist.cfg
- Whitelist for ports with machine manufacturer-specific functions, e.g. for Python and DNC applications: /mnt/plc/etc/ sysconfig/portscan-whitelist.cfg
- Whitelist for ports with customer-specific functions: /mnt/tnc/ etc/sysconfig/portscan-whitelist.cfg

For each entry, the whitelist specifies the type of port (TCP/UDP), the port number, the providing program, and optional comments. If the automatic port scan function is active, only ports listed in the whitelists can be open. Non-listed ports trigger a notification window.

The result of the scan is saved to a log file (LOG:/portscan/scanlog and LOG:/portscan/scanlogevil), and if new ports are found that are not listed in one of the whitelists these are displayed.

Manually starting Portscan

Proceed as follows to manually start the Portscan:

- Taskbar at the bottom edge of the screen
 Further information: "Window manager", page 90
- Press the green HEIDENHAIN button to open the JH menu
- Select the Diagnostic menu item
- Select the Portscan menu item
 - The control opens the HeRos Portscan pop-up window.
- Press the Start key

Cyclically starting Portscan

Proceed as follows to automatically start the Portscan cyclically:

- Taskbar at the bottom edge of the screen
 Further information: "Window manager", page 90
- Press the green HEIDENHAIN button to open the JH menu
- Select the **Diagnostic** menu item
- Select the Portscan menu item The control opens the HeRos Portscan pop-up window.
- Press the Automatic update on key
- Set the time interval with the slider

Remote Service

Together with the Remote Service Setup Tool, the TeleService from HEIDENHAIN enables encrypted end-to-end connections to be established between a service computer and the machine tool. To enable the HEIDENHAIN control to communicate with the HEIDENHAIN server it must be connected to the internet.

Further information: "Configuring the control", page 643

In its basic state the firewall of the control blocks all incoming and outgoing connections. For this reason the firewall must be deactivated for the duration of the service session.

Setting up the control

To set up the control, proceed as follows:

- Taskbar at the bottom edge of the screen
 Further information: "Window manager", page 90
- Press the green HEIDENHAIN button to open the JH menu
- Select the Settings menu item
- Select the Firewall menu item
 The control displays the Firewall/SSH settings dialog
- Deactivate the firewall by removing the Active option in the Firewall tab.
- Press the Apply button to save the settings
- Press the **OK** button

The firewall is disabled.



Do not forget to activate the firewall again after the end of the service session.

Automatic installation of a session certificate

With an NC software installation a temporary certificate is automatically installed on the control. An installation, also in the form of an update, may only be carried out by a service technician from the machine tool builder.

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Service	Method	Log	Computer		Descriptio			
LSV2	Permit all				for HEIDENHAIN VCRemoNT	Teleservice		
SMB	Permit all			SMB (CIFS) Server				
SSH	Permit all	8		SSH server				
VNC	Permit all			VNC server				
Advance	ed 🦳 Set sta							

Manual installation of a session certificate

A new certificate must be installed if no valid session certificate is installed on the control. Clarify which certificate is needed with your service employee. He will then provide you with a valid certificate file if necessary.

To install the certificate on the control proceed as follows:

- Taskbar at the bottom edge of the screen
 Further information: "Window manager", page 90
- Press the green HEIDENHAIN button to open the JH menu
- Select the **Settings** menu item
- Select the Network menu item The control displays the Network settings dialog
- Select the Internet tab. The settings in the Remote maintenance field are configured by the machine tool builder.
- Press the Add key and select the file from the menu
- Press the **Open** key

The certificate is opened.

- Press the OK soft key
- It may be necessary to restart the control to load the settings

Launching the service session

Proceed as follows to start the service session:

- Open the task bar at the bottom edge of the screen
- Press the green HEIDENHAIN button to open the JH menu
- Select the **Diagnostic** menu item
- Select the **RemoteService** menu item
- Enter the Session key of the machine tool builder

HCP server Sandbax SMB release Intel forwards internet Inquiries Io the galoway and from there they must be de through network address translation.
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mitmax and from there they must be
hine tool builder configures servers for tenance before the machine is shipped. Id change servers conif you have been id to do so by customer service personnel.
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Printer

The **Printer** function in the HeROS menu enables you to add and manage printers.

Displaying the printer settings

Proceed as follows to access the printer settings:

- Open the task bar at the bottom edge of the screen Further information: "Window manager", page 90
- ▶ Press the green HEIDENHAIN button to open the JH menu
- Select the **Settings** menu item
- Select the **Printer** menu item

The control opens the Heros Printer Manager pop-up window.

The name of the printer is displayed in the input field.

Soft key	Meaning		
CREATE	Creates the printer named in the input field		
CHANGE	Modifies the properties of the selected printer		
COPY	Creates the printer named in the input field with the attributes of the selected print- er This can be useful if printing both portrait and landscape formats on the same print- er		
DELETE	Deletes the selected printer		
UP	Selects the desired printer		
DOWN			
STATUS	Displays status information of the selected printer		
PRINT TEST PAGE	Prints a test page on the selected printer		

For each printer, the following attributes can be set:

Setting	Meaning	
Name of the printer	The printer name can be changed here.	
Connection	Here, you can select the connection type	
	 USB: The USB connection can be assigned here. The name is displayed automatically. 	
	 Network: Enter the network name or the IP address of the target printer here. In addition, specify the port of the network printer here (default: 9100) 	
	Printer not connected	
Timeout	Defines the delay to printing after the last change has been made to the file to be printed in PRINTER:. This can be useful if the file to be printed is populated with data by using FN functions, e.g. during probing.	
Standard printer	Select to define the standard printer in case several printers are available. Is defined automatically when creating the first printer.	

Setting	Meaning	
Settings for printing of text	These settings are applicable when printing text documents: Paper size 	
	 Number of copies 	
	Job name	
	Font size	
	Header	
	 Print options (black and white, color, duplex) 	
Orientation	Portrait, landscape for all printable files	
Expert options	Available only to authorized specialists	

Print options:

- Copying of the file to be printed in PRINTER: The file to be printed is automatically forwarded to the standard printer and deleted from the directory after the print job has been executed
- Using the FN 16: F-PRINT function
 Further information: "Printing messages", page 362

List of printable files:

- Text files
- Graphic files
- PDF files

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The connected printer must be PostScript-enabled.

SELinux security software

SELinux is an extension for Linux-based operating systems. SELinux is an additional security software package based on Mandatory Access Control (MAC) and protects the system against the running of unauthorized processes or functions and therefore protects against viruses and other malware.

MAC means that every action must be explicitly permitted, otherwise it will not be executed by the control. The software is intended as protection in addition to the normal access restriction in Linux. Certain processes and actions can only be executed if the standard functions and access control of SELinux permit it.



The SELinux installation of the control has been prepared to permit running only programs installed with the HEIDENHAIN NC software. Other programs cannot be run with the standard installation.

The access control of SELinux under HEROS 5 is regulated as follows:

- The control executes only applications that are installed with the HEIDENHAIN NC software
- Files in connection with the security of the software (SELinux system files, HEROS 5 boot files, etc.) may only be changed by programs that are selected explicitly
- New files generated by other programs must never be executed
- USB data carriers cannot be deselected
- There are only two processes that are permitted to execute new files:
 - Starting a software update: A software update from HEIDENHAIN can replace or change system files
 - Starting the SELinux configuration: The configuration of SELinux is usually password-protected by your machine manufacturer; refer here to the relevant machine manual

HEIDENHAIN recommends activating SELinux because it provides additional protection against attacks from
outside.

VNC

(Ö)

Use the **VNC** function to configure the behavior of the various VNC clients. This includes, for example, operation via soft keys, mouse and the ASCII keyboard.

- The control provides the following options:
- List of permitted clients (IP address or name)
- Password for the connection
- Additional server options
- Additional settings for assigning the focus

Refer to your machine manual.

For multiple clients or operating units, the focus assignment procedure depends on the design and the operating situation of the machine.

This function must be adapted by your machine manufacturer.

Opening the VNC settings

Proceed as follows to open the VNC settings:

- Open the task bar at the bottom edge of the screen
 Further information: "Window manager", page 90
- ▶ Press the green HEIDENHAIN button to open the JH menu
- Select the Settings menu item
- Select the VNC menu item

The control opens the VNC Settings pop-up window.

The control provides the following options:

- Add: Add new VNC viewer/client
- Remove: Deletes the selected client Only possible with manually entered clients.
- Edit: Edit the configuration of the selected client
- Update: Updates the display. Required with connection attempts during which the dialog is open.

VNC settings

Dialog	Option	Meaning
VNC participant settings	Computer name:	IP address or computer name
	VNC:	Connection of the client to the VNC viewer
	VNC Focus	The client participates in the focus assignment
	Туре	 Manual Manually entered client
		 Denied This client is not permitted to connect
		 TeleService/IPC 61xx Client via TeleService connection
		 DHCP Other computer that obtains an IP address from this computer

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	Warnings and information about if the VNC protocol has not been authorized for all VNC clients due to firewall settings on the control.
	Further information: "Firewall", page 649.
Enabling TeleService/ IPC 61xx	Connection via TeleService/IPC 61xx is always permitted
Password verification	The client must enter a password for verification. If this option is active, the password must be entered when the connection is established.
Deny	Access generally denied to all other VNC clients.
Inquire	During connection attempts a corresponding dialog is opened.
Permitted	Access is generally granted to all other VNC clients.
Enabling VNC focus	Enable focus assignment for this system. Otherwise there is no central focus assignment. In the default setting, the focus is actively reassigned by the owner of the focus by clicking the focus symbol. This means that the owner of the focus must first release the focus by clicking the focus symbol before any other client can retrieve the focus.
Enabling concurrency VNC focus	In the default setting, the focus is actively reassigned by the owner of the focus by clicking the focus symbol. This means that the owner of the focus must first release the focus by clicking the focus symbol before any other client can retrieve the focus. If concurrency focus is selected, any client can retrieve the focus at any time without having to wait for the current owner of the focus to release it.
Timeout Concurrency VNC Focus	Time period within which the current owner of the focus can object to the focus being withdrawn or can prevent the reassign- ment of the focus. If a client requests the focus, a dialog in which the reassignment of focus can be refused appears on all clients' screens.
	Current status of VNC focus on the respective client: Focus is owned by other client. Mouse and keyboard are disabled.
	Current status of VNC focus on respective client: Focus is owned by current client. Entries can be made.
!! =?!!	Current status of VNC focus on the respective client: Request by the owner of the focus to give the focus to another client. Mouse and keyboard are disabled until the focus is assigned unambigu- ously.
	TeleService/ IPC 61xx Password verification Deny Inquire Permitted Enabling VNC focus Enabling concurrency VNC focus Timeout Concurrency VNC Focus Xeacual Xeacual Xeacual Xeacual

If **Enable concurrency VNC focus** is selected, a pop-up window appears. This dialog makes it possible to refuse that the focus be given to the requesting client. If this does not occur, the focus changes to the requesting client after the set time limit.

Backup and restore

With the **NC/PLC Backup** and **NC/PLC Restore** functions you can back up and restore individual folders or the complete **TNC** drive. You can save the backup files locally, on a network drive, or to USB storage devices.

The backup program generates a *****. **tncbck** file that can also be processed by the PC tool TNCbackup (part of TNCremo). The restore program can restore these files as well as those from existing TNCbackup programs. If a *****. tncbck file is selected in the file manager of the control, the program **NC/PLC Restore** is automatically launched.

Backup and restore is subdivided into several steps. Navigate between these steps with the **FORWARD** and **BACK** soft keys. Specific actions for steps are selectively displayed as soft keys.

Opening NC/PLC Backup or NC/PLC Restore

Proceed as follows to open the functions:

- Open the task bar at the bottom edge of the screen Further information: "Window manager", page 90
- Press the green HEIDENHAIN button to open the JH menu
- Select the **Tools** menu item
- Open the NC/PLC Backup or NC/PLC Restore menu item The control opens the pop-up window.

Backing up data

To backup data from the control, proceed as follows:

- Select NC/PLC Backup
- Select the type
 - Back up the **TNC** partition
 - Back up the directory tree: Select the directory for backup in the file management
 - Back up the machine configuration (for machine tool builders only)
 - Complete backup (for machine tool builders only)
 - Comment: Freely configurable comment for the backup
- Select the next step with the FORWARD soft key
- Stop the control if required with the STOP NC SOFTWARE soft key
- Define the exclusion rules
 - User preset rules
 - Write own rules to the table
- Select the next step with the FORWARD soft key The control generates a list of files for backing up.
- Check the list. Deselect files if necessary.
- Select the next step with the FORWARD soft key
- Enter the name of the backup file
- Select the storage path
- Select the next step with the FORWARD soft key The control generates the backup file.
- Confirm with the **OK** soft key

The control concludes the backup process and restarts the NC software.

Restoring data

NOTICE

Caution: Data may be lost!

When you restore data (Restore function), any existing data will be overwritten without a confirmation prompt. Existing data is not automatically backed up by the control before running the restore process. Power failures or other problems can interfere with the data restore process. As a consequence, data may be irreversibly damaged or deleted.

 Before starting the data restore process, make a backup of the existing data

To restore the data proceed as follows:

- Select NC/PLC Restore
- Select the archive to be restored
- Select the next step with the FORWARD soft key The control generates a list of files for restoring.
- Check the list. Deselect files if necessary.
- Select the next step with the FORWARD soft key
- Stop the control if required with the STOP NC SOFTWARE soft key
- Extract the archive The control restores the files.
- Confirm with the OK soft key The control restarts the NC software.

2.6 Remote Desktop Manager (option 133)

Introduction

The Remote Desktop Manager enables you to display external computer units on the control screen that are connected via Ethernet, and to operate them via the control. You can also start programs specifically under HEROS or display web pages of an external server.

HEIDENHAIN offers you the IPC 6641 as a Windows computer. With the IPC 6641 Windows computer you can start and operate Windows-based applications directly from the control.

The following connection options are available:

- Windows Terminal Server (RemoteFX): Displays the desktop of a remote Windows computer on the control
- VNC: Connection to an external computer. Displays the desktop of a remote Windows or Unix computer on the control
- Switch-off/restart of a computer: Configure automatic shutdown of a Windows computer
- World Wide Web: Available only to authorized specialists
- **SSH**: Available only to authorized specialists
- **XDMCP**: Available only to authorized specialists
- User-defined connection: Available only to authorized specialists

1	HEIDENHAIN assures a functioning connection between HEROS 5 and the IPC 6641.
	No guarantee is given for other combinations and connections.

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If you are using a TNC 320 with touch control, you can replace some keystrokes with hand-to-screen contact. **Further information:** "Operating the Touchscreen", page

Configuring connections – Windows Terminal Service (RemoteFX)

Configuring an external computer

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You do not need additional software for your external computer for connecting to the Windows Terminal Service.

Proceed as follows to configure the external computer, e.g. in the Windows 7 operating system:

- Press the Windows Start button and select Control Panel on the Start menu
- Select System and Security
- Select System
- Select Remote settings
- Under Remote Assistance, enable Allow Remote Assistance connections to this computer
- Under Remote Desktop, select Allow connections from computers running any version of Remote Desktop
- Press OK to confirm your settings

Configuring the control

Proceed as follows to configure the control:

- Press the **DIADUR** key to open the HeROS menu
- Select Remote Desktop Manager
 The control opens the Remote Desktop Manager.
- Press New connection
- Press Windows Terminal Service (RemoteFX) The control opens the Selection of server operating system pop-up window.
- Select the desired operating system
 - Win XP
 - Win 7
 - Win 8.X
 - Win 10
 - Another Windows
- Press OK

The control opens the Edit the connection pop-up window.

Edit the connection

Setting	Meaning	Input
Connection name	Name of the connection in the Remote Desktop Manager	Required
Restarting after end of	Behavior with terminated connection:	Required
connection	Always restart	
	Never restart	
	 Always after an error 	
	 Ask after an error 	
Automatic starting upon login	Connection automatically established during control power-up	Required
Add to favorites	Connection icon in the task bar:	Required
	Single click with the left mouse button	
	The control switches to the desktop of the connection.	
	Single click with the right mouse button	
	The control displays the connection menu.	
Move to the following workspace	Number of desktop for the connection, whereby desktops 0 and 1 are reserved for the NC software	Required
	Default setting: Third desktop	
Release USB mass memory	Enable access to connected USB mass memory	Required
Computer	Host name or IP address of the external computer	Required
	In the recommended configuration of the IPC 6641, the IP address 192.168.254.3 is used	
User name	Name of the user	Required
Password	User password	Required
Windows domain	Domain of the external computer	Optional
Full screen mode or user- defined window size	Size of the connection window	
Entries in the Advanced options area	Available only to authorized specialists	Optional

For integrating the IPC 6641, HEIDENHAIN recommends using a RemoteFX connection.

For RemoteFX, the screen of the external computer is not mirrored, as for VNC. Instead, a separate desktop is opened. The desktop that is active on the external computer when the connection is established is then locked and the user is logged off. This prevents that two users access the control simultaneously.

Configuring the connection – VNC

Configuring an external computer



You do not need an additional VNC server for your external computer for connecting to VNC.

Install and configure the VNC server, e.g. the TightVNC server, before configuring the control.

Configuring the control

Proceed as follows to configure the control:

Press the **DIADUR** key to open the HeROS menu

- Select Remote Desktop Manager The control opens the Remote Desktop Manager.
- Press New connection
- Press VNC

The control opens the **Edit the connection** pop-up window.

Edit the connection

Setting	Meaning	Input	
Connection name:	Name of the connection in the Remote Desktop Manager	Required	
Restarting after end of	Behavior with terminated connection:	Required	
connection:	Always restart		
	Never restart		
	 Always after an error 		
	Ask after an error		
Automatic starting upon login	Connection automatically established during control power-up	Required	
Add to favorites	Connection icon in the task bar:	Required	
	Single click with the left mouse button		
	The control switches to the desktop of the connection.		
	Single click with the right mouse button		
	The control displays the connection menu.		
Move to the following workspace	Number of desktop for the connection, whereby desktops 0 and 1 are reserved for the NC software	Required	
	Default setting: Third desktop		
Release USB mass memory	Permit access to connected USB mass memory		
Calculator	Host name or IP address of the external computer. In the recom- mended configuration of the IPC 6641, the IP address 192.168.254.3 is used		
Password	Password for connecting to the VNC server	Required	

Setting	Meaning	Input	
Full-screen mode or User- defined window size:	Size of the connection window	Required	
Permit further connections (share)	Enable access to the VNC server also by other VNC connections	Required	
View only	The external computer cannot be operated in display mode	Required	
Entries in the Advanced options area	Available only to authorized specialists	Optional	

With VNC, the screen of the external computer is mirrored directly. The active desktop on the external computer is not locked automatically.

With a VNC connection, it is also possible to completely shut down the external computer via the Windows menu. As the computer cannot be rebooted over a connection, it must actually be switched off and on again.

Shutting down or rebooting an external computer

	NOTICE			
	Caution: Data may be lost!			
	If the external computer is not shut down properly, data may be irreversibly damaged or deleted.			
	 Configure automatic shutdown of the Windows computer 			
Proceed as follows to configure the control:				
Press the DIADUR key to open the HeROS menu				
	Select Remote Desktop Manager			
	The control opens the Remote Desktop Manager.			
	Press New connection			

- Press New connection
- Press Switch-off/restart of a computer The control opens the Edit the connection pop-up window.
- Edit the connection

Setting	Meaning	Input
Connection name:	Name of the connection in the Remote Desktop Manager	Required
Restarting after end of connection:	Not necessary with this connection	-
Automatic starting upon login	Not necessary with this connection	_
Add to favorites	Connection icon in the task bar:	Required
	 Single click with the left mouse button 	
	The control switches to the desktop of the connection.	
	Single click with the right mouse button	
	The control displays the connection menu.	
Move to the following workspace	Not active with this connection	-

Setting	Meaning	Input
Release USB mass memory	Not advisable with this connection	_
Calculator	Host name or IP address of the external computer. In the recom- mended configuration of the IPC 6641, the IP address 192.168.254.3 is used	Required
User name	User name with which the connection should be logged on	Required
Password	Password for connecting to the VNC server	Required
Windows domain:	Domain of the target computer, if required	Optional
Max. waiting time (seconds):	When the control shuts down, it commands the Windows comput- er to shut down. Before the control displays the message You may switch off now , it waits for <timeout></timeout> seconds. If the Windows computer is switched off before the <timeout></timeout> seconds have expired, the control stops waiting.	Required
Force	If Force is not selected, Windows waits up to 20 seconds. This delays the shutdown process or the Windows computer is switched off before Windows has shut down.	Required
Restart	Reboot the Windows computer.	Required
Run during restart	during restart Reboot the Windows computer when the control reboots. Effective only if the control is rebooted using the shutdown icon at the bottom right in the taskbar or if a reboot is initiated as a result of a change in the system settings (e.g. network settings).	
Run during switch-off	The Windows computer is switched off when the control is shut down (no reboot). This is the standard scenario. The END key will then no longer trigger a reboot, either.	Required
Entries in the Advanced options area	Available only to authorized specialists	Optional

Starting and stopping the connection

Once a connection has been configured, it is shown as an icon in the Remote Desktop Manager window. Click the connection icon with the right mouse key to open a menu in which the display can be started and stopped.

Use the right DIADUR key on the keyboard to change to the third desktop and back to the control interface. You can also use the task bar to get to this desktop.

If the desktop of the external connection or the external computer is active, all inputs from the mouse and the keyboard are transmitted there.

When the HEROS 5 operating system is shut down, all connections are canceled automatically. Please note, however, that only the connection is canceled, whereas the external computer or the external system is not shut down automatically.

Further information: "Shutting down or rebooting an external computer", page 108

2.7 Accessories: HEIDENHAIN 3-D touch probes and electronic handwheels

3-D touch probes

Applications for HEIDENHAIN 3-D touch probes:

- Automatically align workpieces
- Quickly and precisely set presets
- Measure the workpiece during program run
- Measure and inspect tools

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All of the cycle functions (touch probe cycles and fixed cycles) are described in the Cycle Programming User's Manual. If you need this user's manual, please contact HEIDENHAIN if required. ID: 1096959-xx

Touch trigger probes TS 260, TS 444, TS 460, TS 642 and TS 740

The TS 248 and TS 260 touch probes are particularly cost-effective and transmit the trigger signals via a cable.

The wireless TS 740 and TS 642 touch probes as well as the smaller TS 460 and TS 444 touch probes are suitable for use on machines with tool changers. All of the above touch probes feature infrared signal transmission. TS 460 also supports wireless transmission and offers optional collision protection. Thanks to an integrated air turbine generator, the TS 444 touch probe is battery-free.

HEIDENHAIN touch trigger probes feature either a wear-resistant optical switch or several high-precision pressure sensors (TS 740) that detect the deflection of the stylus. On deflection, a trigger signal is generated, which causes the control to store the current position of the touch probe as the actual value.

Tool touch probes TT 160 and TT 460

The TT 160 and TT 460 touch probes are designed for the efficient and precise measurement and inspection of tool dimensions.

The control offers cycles that enable you to determine the tool length and radius while the spindle is rotating or stationary. The tool touch probe features a particularly rugged design and a high degree of protection, which make it insensitive to coolants and swarf.

A wear-resistant optical switch generates the trigger signal. With the TT 160, signal transmission is by cable. The TT 460 supports infrared and radio transmission.



HR electronic handwheels

Electronic handwheels facilitate moving the axis slides precisely by hand. A wide range of traverses per handwheel revolution is available. Apart from the HR 130 and HR 150 integral handwheels, HEIDENHAIN also offers the HR 510, HR 520 and HR 550FS portable handwheels.

Further information: "Traverse with electronic handwheels", page 519





Fundamentals, File Management

3.1 Fundamentals

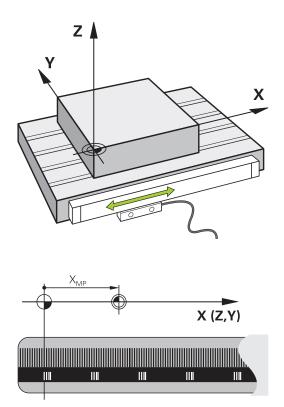
Position encoders and reference marks

The machine axes are equipped with position encoders that register the positions of the machine table or tool. Linear axes are usually equipped with linear encoders, rotary tables and tilting axes with angle encoders.

When a machine axis moves, the corresponding position encoder generates an electrical signal. The control evaluates this signal and calculates the precise actual position of the machine axis.

If there is a power interruption, the calculated position will no longer correspond to the actual position of the machine slide. To recover this assignment, incremental position encoders are provided with reference marks. The scales of the position encoders contain one or more reference marks that transmit a signal to the control when they are crossed over. This enables the control to re-establish the assignment of the displayed position to the current machine position. For linear encoders with distance-coded reference marks, the machine axes need to move by no more than 20 mm, for angle encoders by no more than 20°.

With absolute encoders, an absolute position value is transmitted to the control immediately upon switch-on. In this way the assignment of the actual position to the machine slide position is re-established directly after switch-on.



Reference systems

For the control to traverse an axis according to a defined path it requires a **reference system**.

A paraxially mounted linear encoder on a machine tool serves as a simple reference system for linear axes. The linear encoder represents a **number ray**, a unidimensional coordinate system.

To approach a point on the **plane**, the control requires two axes and therefore a reference system with two dimensions.

To approach a point in the **space**, the control requires three axes and therefore a reference system with three dimensions. If these three axes are configured perpendicular to each other this creates a so-called **three-dimensional Cartesian coordinate system**.



According to the right-hand rule the fingertips point in the positive directions of the three main axes.

For a point to be uniquely determined in space, a **coordinate origin** is needed in addition to the configuration of the three dimensions. The common intersection serves as the coordinate origin in a 3-D coordinate system. This intersection has the coordinates **X+0**, **Y+0** and **Z+0**.

The control must differentiate between various reference systems for it to always perform a tool change at the same position for example, or carry out a machining operation always related to the current workpiece position.

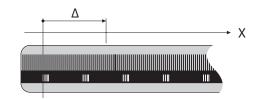
The control differentiates between the following reference systems:

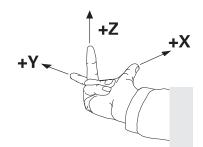
- Machine coordinate system M-CS:
 Machine Coordinate System
- Basic coordinate system B-CS:
 Basic Coordinate System
- Workpiece coordinate system W-CS:
 Workpiece Coordinate System
- Working plane coordinate system WPL-CS:
 Working Plane Coordinate System
- Input coordinate system I-CS: Input Coordinate System
- Tool coordinate system T-CS: Tool Coordinate System

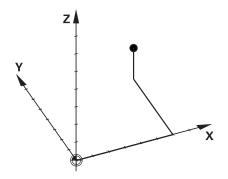
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All reference systems build up on each other. They are subject to the kinematic chain of the specific machine tool.

The machine coordinate system is the reference system.







Machine coordinate system M-CS

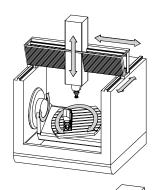
The machine coordinate system corresponds to the description of kinematics and therefore to the actual mechanical design of the machine tool.

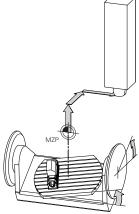
Because the mechanics of a machine tool never precisely correspond to a Cartesian coordinate system, the machine coordinate system consists of several one-dimensional coordinate systems. These one-dimensional coordinate systems correspond to the physical machine axes that are not obligatorily perpendicular to each other.

The position and orientation of the one-dimensional coordinate systems are defined with the aid of translations and rotations based on the spindle tip in the description of kinematics.

The position of the coordinate origin, the so-called machine datum, is defined by the machine manufacturer during machine configuration. The values in the machine configuration define the zero positions of the encoders and the corresponding machine axes. The machine datum does not necessarily have to be located in the theoretical intersection of the physical axes. It can therefore also be located outside of the traverse range.

Because the machine configuration values cannot be modified by the user, the machine coordinate system is used for determining constant positions, e.g. the tool change point.





Machine datum (MZP)

Son	кеу	

TRANSFORM

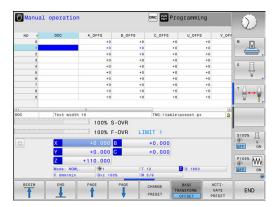
Application

The user can define shifts in the machine coordinate system according to the specific axis with use of the **OFFSET** values of the preset table.



The machine tool builder configures the **OFFSET** columns of the preset management in accordance with the machine.

Further information: "Managing presets", page 531



6

Another feature is **OEM-OFFSET**, which is available only to the machine tool builder. **OEM-OFFSET** can be used to define additive axis shifts for rotary and parallel axes.

All **OFFSET** values (from all the above **OFFSET** input possibilities) together difference between the **ACTL**. and the **RFACTL** position of an axis.

The control converts all movements in the machine coordinate system, independent of the reference system used for value input. Example of a 3-axis machine tool with a Y axis as oblique axis, not arranged perpendicularly to the ZX plane:

In the Positioning w/ Manual Data Input operating mode, run an NC block with L IY+10

The control determines the required axis nominal values from the defined values.

During positioning the control moves the Y and Z machine axes.

The **RFACTL** and **RFNOML** displays show movements of the Y axis and Z axis in the machine coordinate system.

The **ACTL.** and **NOML.** displays only show one movement of the Y axis in the input coordinate system.

In the Positioning w/ Manual Data Input operating mode, run an NC block with L IY-10 M91

The control determines the required axis nominal values from the defined values.

During positioning the control only moves the Y machine axis.

The **RFACTL** and **RFNOML** displays only show one movement of the Y axis in the machine coordinate system.

The **ACTL.** and **NOML.** displays show movements of the Y axis and Z axis in the input coordinate system.

The user can program positions related to the machine datum, e.g. by using the miscellaneous function **M91**.

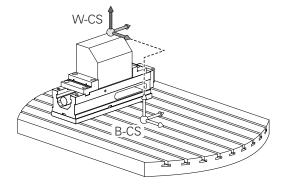
Basic coordinate system B-CS

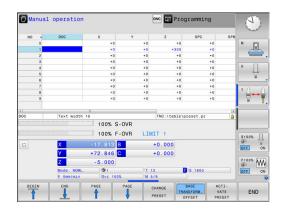
The basic coordinate system is a 3-D Cartesian coordinate system. Its coordinate origin is the end of the kinematics model.

The orientation of the basic coordinate system in most cases corresponds to that of the machine coordinate system. There may be exceptions to this if a machine manufacturer uses additional kinematic transformations.

The kinematic model and thus the position of the coordinate origin for the basic coordinate system is defined by the machine manufacturer in the machine configuration. The user cannot modify the machine configuration values.

The basic coordinate system serves to determine the position and orientation of the workpiece coordinate system.





Soft key Application
The user determines the position and orientation
of the workpiece coordinate system by using a 3D touch probe for example. The control saves the
values determined with respect to the basic coordinate system as **BASE TRANSFORM.** values in the
preset management.



The machine tool builder configures the **BASE TRANSFORM.** columns of the preset management in accordance with the machine.

Further information: "Managing presets", page 531

Workpiece coordinate system W-CS

The workpiece coordinate system is a 3-D Cartesian coordinate system. Its coordinate origin is the active preset.

The position and orientation of the workpiece coordinate system depend on the **BASE TRANSFORM.** values of the active line in the preset table.

Soft key	Application
BASE TRANSFORM. OFFSET	The user determines the position and orientation of the workpiece coordinate system by using a 3- D touch probe for example. The control saves the values determined with respect to the basic coordi- nate system as BASE TRANSFORM. values in the preset management.

Further information: "Managing presets", page 531

In the workpiece coordinate system the user defines the position and orientation of the working plane coordinate system with use of transformations.

Transformations in the workpiece coordinate system:

3D ROT functions

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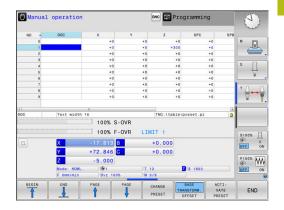
- PLANE functions
- Cycle 19 WORKING PLANE
- Cycle 7 DATUM SHIFT (shifting before tilting the working plane)
- Cycle 8 MIRROR IMAGE (mirroring before tilting the working plane)

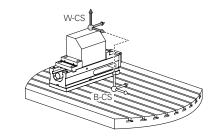
The result of transformations built up on each other depends on the programming sequence.

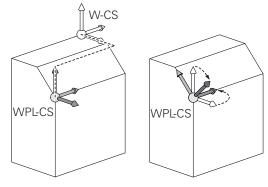
In every coordinate system, program only the specified (recommended) transformations. This applies to both setting and resetting the transformations. Any other use may lead to unexpected or undesired results. Please observe the following programming notes.

Programming notes:

- Transformations (mirroring and shifting) that are programmed before the PLANE functions (except for PLANE AXIAL) will change the position of the tilt datum (origin of the working plane coordinate system WPL-CS) and the orientation of the rotary axes
 - If you just program a shift, then only the position of the tilt datum will change
 - If you just program mirroring, then only the orientation of the rotary axes will change
- When used in conjunction with PLANE AXIAL and Cycle 19, the programmed transformations (mirroring, rotation and scaling) do not affect the position of the tilt datum or the orientation of the rotary axes







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Without active transformations in the workpiece coordinate system, the position and orientation of the working plane coordinate system and workpiece coordinate system are identical.

There are no transformations in the workpiece coordinate system on 3-axis machine tools or with pure 3-axis machining. The **BASE TRANSFORM.** values of the active line of the preset table have a direct effect on the working plane coordinate system with this assumption.

Other transformations are of course possible in the working plane coordinate system. **Further information:** "Working plane coordinate system WPL-CS", page 121

Working plane coordinate system WPL-CS

The working plane coordinate system is a 3-D Cartesian coordinate system.

The position and orientation of the working plane coordinate system depend on the active transformations in the workpiece coordinate system.

Without active transformations in the workpiece coordinate system, the position and orientation of the working plane coordinate system and workpiece coordinate system are identical.

There are no transformations in the workpiece coordinate system on 3-axis machine tools or with pure 3-axis machining. The **BASE TRANSFORM.** values of the active line of the preset table have a direct effect on the working plane coordinate system with this assumption.

In the working plane coordinate system the user defines the position and orientation of the input coordinate system with use of transformations.

Transformations in the working plane coordinate system:

- Cycle 7 DATUM SHIFT
- Cycle 8 MIRROR IMAGE
- Cycle 10 **ROTATION**
- Cycle 11 SCALING
- Cycle 26 AXIS-SPECIFIC SCALING
- PLANE RELATIVE

As a **PLANE** function, the **PLANE RELATIVE** is effective in the workpiece coordinate system and aligns the working plane coordinate system.

The values of additive tilting always relate to the current working plane coordinate system.

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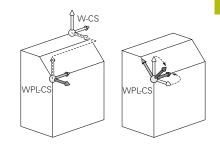
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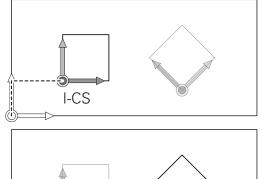
The result of transformations built up on each other depends on the programming sequence.

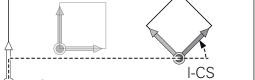
Without active transformations in the working plane coordinate system, the position and orientation of the input coordinate system and working plane coordinate system are identical.

There are also no transformations in the workpiece coordinate system on 3-axis machine tools or with pure 3-axis machining. The **BASE TRANSFORM.** values of the active line of the preset table have a direct effect on the input coordinate system with this assumption.









Input coordinate system I-CS

The input coordinate system is a 3-D Cartesian coordinate system. The position and orientation of the input coordinate system depend on the active transformations in the working plane coordinate system.

> Without active transformations in the working plane coordinate system, the position and orientation of the input coordinate system and working plane coordinate system are identical.

There are also no transformations in the workpiece coordinate system on 3-axis machine tools or with pure 3-axis machining. The **BASE TRANSFORM.** values of the active line of the preset table have a direct effect on the input coordinate system with this assumption.

With the aid of positioning blocks in the input coordinate system, the user defines the position of the tool and therefore the position of the tool coordinate system.



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The **NOML.**, **ACTL.**, **LAG** and **ACTDST** displays are also based on the input coordinate system.

Positioning blocks in input coordinate system:

- Paraxial positioning blocks
- Positioning blocks with Cartesian or polar coordinates

Example

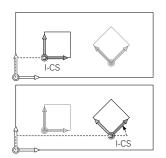
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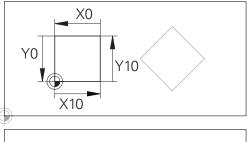
N70 X+48 R+*

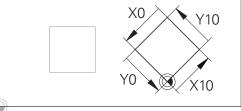
N70 G01 X+48 Y+102 Z-1.5 R0*

Orientation of the tool coordinate system can be performed in various reference systems. **Further information:** "Tool coordinate system T-CS", page 123









A contour referencing the input coordinate system origin can easily be transformed any way you need.

Tool coordinate system T-CS

The tool coordinate system is a 3-D Cartesian coordinate system. Its coordinate origin is the tool reference point. The values of the tool table, L and R with milling tools and ZL, XL and YL with turning tools, reference this point.

Further information: "Entering tool data into the table", page 208

In accordance with the values from the tool table, the coordinate origin of the tool coordinate system is shifted to the tool center point TCP. TCP stands for **T**ool **C**enter **P**oint.

If the NC program does not reference the tool tip, the tool center point must be shifted. The required shift is implemented in the NC program using the delta values during a tool call.



The position of the TCP as shown in the diagram is obligatory in conjunction with the 3-D tool compensation.



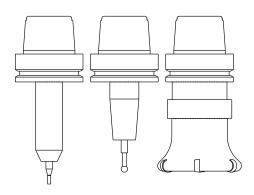
With the aid of positioning blocks in the input coordinate system, the user defines the position of the tool and therefore the position of the tool coordinate system.

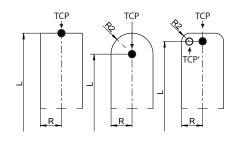
If miscellaneous function **M128** is active, the orientation of the tool coordinate system depends on the tool's current angle of inclination.

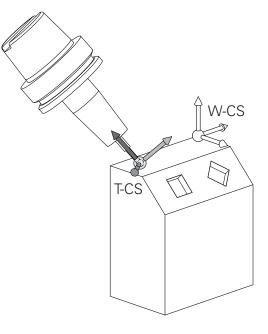
Tool angle of inclination in the machine coordinate system:

Example

N70 G01 X+10 Y+45 A+10 C+5 R0 M128*







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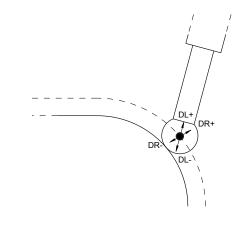
With the shown positioning blocks with vectors, 3-D tool compensation is possible with compensation values **DL**, **DR** and **DR2** from the **T** block.

The methods of function of the compensation values depend on the type of tool.

The control detects the various tool types with the columns **L**, **R** and **R2** of the tool table:

- $R2_{TAB} + DR2_{TAB} + DR2_{PROG} = 0$ → end mill
- $R2_{TAB} + DR2_{TAB} + DR2_{PROG} = R_{TAB} + DR_{TAB} + DR_{PROG}$ $\rightarrow radius cutter or ball cutter$
- $0 < R2_{TAB} + DR2_{TAB} + DR2_{PROG} < R_{TAB} + DR_{TAB} + DR_{PROG}$
 - \rightarrow toroid cutter or toroidal cutter

Without the **TCPM** function or miscellaneous function **M128**, orientation of the tool coordinate system and input coordinate system is identical.



Designation of the axes on milling machines

The X, Y and Z axes on your milling machine are also referred to as tool axis, principal axis (1st axis) and secondary axis (2nd axis). The assignment of the tool axis is decisive for the assignment of the principal and secondary axes.

Tool axis	Principal axis	Secondary axis
X	Y	Z
Y	Z	Х
Z	Х	Y

Polar coordinates

If the production drawing is dimensioned in Cartesian coordinates, you also write the NC program using Cartesian coordinates. For parts containing circular arcs or angles it is often simpler to give the dimensions in polar coordinates.

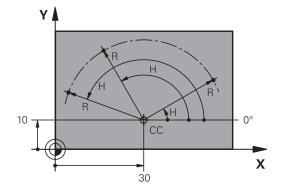
While the Cartesian coordinates X, Y and Z are three-dimensional and can describe points in space, polar coordinates are twodimensional and describe points in a plane. Polar coordinates have their datum at a circle center (CC), or pole. A position in a plane can be clearly defined by the:

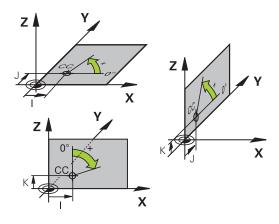
- Polar Radius, the distance from the circle center CC to the position, and the
- Polar Angle, the value of the angle between the angle reference axis and the line that connects the circle center CC with the position.

Setting the pole and the angle reference axis

The pole is set by entering two Cartesian coordinates in one of the three planes. These coordinates also set the reference axis for the polar angle H.

Coordinates of the pole (plane)	Reference axis of the angle
X/Y	+X
Y/Z	+Y
Z/X	+Z





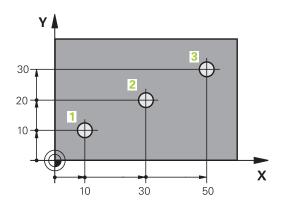
Absolute and incremental workpiece positions

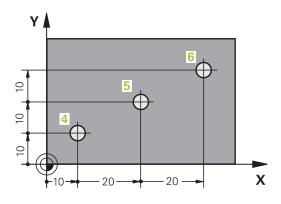
Absolute workpiece positions

Absolute coordinates are position coordinates that are referenced to the datum of the coordinate system (origin). Each position on the workpiece is unambiguously defined by its absolute coordinates.

Example 1: Holes dimensioned in absolute coordinates

Hole 1	Hole 2	Hole 3
X = 10 mm	X = 30 mm	X = 50 mm
Y = 10 mm	Y = 20 mm	Y = 30 mm





Incremental workpiece positions

Incremental coordinates are referenced to the last programmed nominal position of the tool, which serves as the relative (imaginary) datum. When you write an NC program in incremental coordinates, you thus program the tool to move by the distance between the previous and the subsequent nominal positions. This is why they are also referred to as chain dimensions.

To program a position in incremental coordinates, enter the G91 function before the axis.

Example 2: Holes dimensioned in incremental coordinates

Absolute coordinates of hole 4

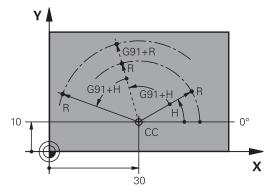
X = 10 mm			
Y = 10 mm			

Hole 5, with respect to 4	Hole 6, with respect to 5
G91 X = 20 mm	G91 X = 20 mm
G91 Y = 10 mm	G91 Y = 10 mm

Absolute and incremental polar coordinates

Absolute coordinates always refer to the pole and the angle reference axis.

Incremental polar coordinates always refer to the last programmed nominal position of the tool.



Selecting the preset

A production drawing identifies a certain form element of the workpiece, usually a corner, as the absolute preset (datum). When setting the preset, you first align the workpiece along the machine axes, and then move the tool in each axis to a defined position relative to the workpiece. Set the display of the control either to zero or to a known position value for each position. This establishes the reference system for the workpiece, which will be used for the control's display and your part program.

If the production drawing is dimensioned in relative presets, simply use the coordinate transformation cycles.

Further information: Cycle Programming User's Manual

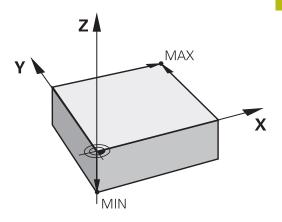
If the production drawing is not dimensioned for NC, set the preset at a position or corner on the workpiece from which the dimensions of the remaining workpiece positions can be measured.

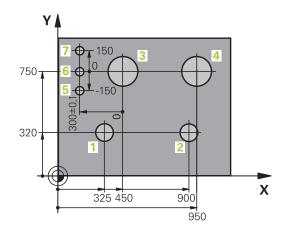
The fastest, easiest and most accurate way of presetting is by using a 3-D touch probe from HEIDENHAIN.

Further information: "Presetting with a 3-D touch probe ", page 562

Example

The workpiece drawing shows holes (1 to 4), whose dimensions are shown with respect to an absolute preset with the coordinates X=0 Y=0. The coordinates of holes 5 to 7 refer to the relative preset with the absolute coordinates X=450 Y=750. By using the **Datum shift** cycle you can shift the datum temporarily to the position X=450, Y=750 and program the holes (5 to 7) without further calculations.





3.2 Creating and writing programs

Structure of an NC program in ISO format

A machining program consists of a series of NC blocks. The illustration on the right shows the elements of a block.

The control numbers the blocks of a part program automatically depending on the **blockIncrement** machine parameter (105409). The **blockIncrement** machine parameter (105409) defines the block number increment.

The first block of a program is identified by %, the program name and the active unit of measure.

The subsequent blocks contain information on:

- The workpiece blank
- Tool calls
- Approaching a safe position
- Feed rates and spindle speeds, as well as
- Path contours, cycles and other functions

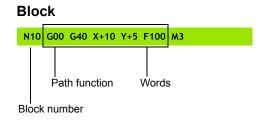
The last block of a program is identified by **N99999999**, the program name and the active unit of measure.

NOTICE

Danger of collision!

The control does not automatically check whether collisions can occur between the tool and the workpiece. There is danger of collision during the approach movement after a tool change!

If necessary, program an additional safe auxiliary position



Defining the blank: G30/G31

Immediately after initiating a new program, you define an unmachined workpiece blank. If you wish to define the blank at a later stage, press the **SPEC FCT** key, the **PROGRAM DEFAULTS** soft key, and then the **BLK FORM** soft key. The control needs this definition for graphic simulation.



You only need to define the workpiece blank if you wish to run a graphic test for the program!

The control can depict various types of blank forms:

Soft key	Function
	Define a rectangular blank
	Define a cylindrical blank
	Define a rotationally symmetric blank of any shape
Destangula	r blonk

Rectangular blank

The sides of the cuboid lie parallel to the X, Y and Z axes. This blank is defined by two of its corner points:

- MIN point G30: the smallest X, Y and Z coordinates of the blank form, entered as absolute values.
- MAX point G31: the largest X, Y and Z coordinates of the blank form, entered as absolute or incremental values

Example

%NEW G71 *	Program begin, name, unit of measure
N10 G30 G17 X+0 Y+0 Z-40*	Spindle axis, MIN point coordinates
N20 G31 X+100 Y+100 Z+0*	MAX point coordinates
N99999999 %NEW G71 *	Program end, name, unit of measure

Cylindrical blank

The cylindrical blank form is defined by the dimensions of the cylinder:

- X, Y or Z: Rotation axis
- D, R: Diameter or radius of the cylinder (with positive algebraic sign)
- L: Length of the cylinder (with positive algebraic sign)
- DIST: Shifting along the rotational axis
- DI, RI: Inside diameter or inside radius for a hollow cylinder



The parameters **DIST** and **RI** or **DI** are optional and need not be programmed.

Example

%NEW G71 *	Program begin, name, unit of measure
N10 BLK FORM CYLINDER Z R50 L105 DIST+5 RI10*	Spindle axis, radius, length, distance, inside radius
N99999999 %NEW G71 *	Program end, name, unit of measure

Rotationally symmetric blank of any shape

You define the contour of the rotationally symmetric blank in a subprogram. Use X, Y or Z as the rotation axis.

In the workpiece blank definition you refer to the contour description:

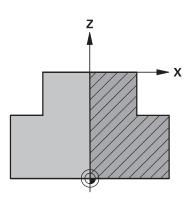
- DIM_D, DIM-R: Diameter or radius of the rotationally symmetrical blank form
- LBL: Subprogram with the contour description

The contour description may contain negative values in the rotation axis but only positive values in the reference axis. The contour must be closed, i.e. the contour beginning corresponds to the contour end.

If you define a rotationally symmetric blank with incremental coordinates, the dimensions are then independent of the diameter programming.



The subprogram can be designated with a number, an alphanumeric name, or a QS parameter.



Example

%NEW G71 *	Program begin, name, unit of measure
N10 BLK FORM ROTATION Z DIM_R LBL1*	Spindle axis, manner of interpretation, subprogram number
N20 M30*	End of main program
N30 G98 L1*	Beginning of subprogram
N40 G01 X+0 Z+1*	Starting point of contour
N50 G01 X+50*	Programming in the positive direction of the principal axis
N60 G01 Z-20*	
N70 G01 X+70*	
N80 G01 Z-100*	
N90 G01 X+0*	
N100 G01 Z+1*	Contour end
N110 G98 L0 *	End of subprogram
N99999999 %NEW G71 *	Program end, name, unit of measure

Creating a new NC program

You always enter an NC program in **Programming** mode. An example of program initiation:



Operating mode: Press the Programming key

PGM MGT Press the PGM MGT key The control opens the file manager.

Select the directory in which you wish to store the new NC program:

FILE NAME = NEW.I



MM

Enter the new program name

- Press the ENT key
- Select the unit of measure: Press the MM or INCH soft key

The control switches the screen layout and initiates the dialog for defining the **BLK FORM** (workpiece blank).

 Select a rectangular workpiece blank: Press the soft key for a rectangular blank form

Working plane in graphic: XY



Enter the spindle axis, e.g. **G17**

Workpiece blank def.: Minimum



Enter in sequence the X, Y and Z coordinates of the MIN point and confirm each of your entries with the ENT key

Workpiece blank def.: Maximum



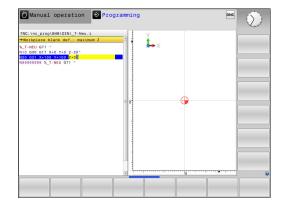
Enter in sequence the X, Y and Z coordinates of the MAX point and confirm each of your entries with the ENT key

Example

%NEW G71 *	Program begin, name, unit of measure
N10 G30 G17 X+0 Y+0 Z-40*	Spindle axis, MIN point coordinates
N20 G31 X+100 Y+100 Z+0*	MAX point coordinates
N99999999 %NEW G71 *	Program end, name, unit of measure

The control automatically generates the first and last blocks of the NC program.

0	If you do not wish to define a blank form, cancel the
	dialog at Working plane in graphic: XY using the DEL key.

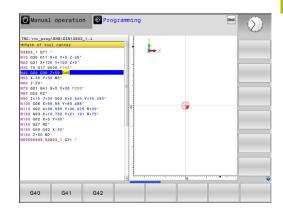


Programming tool movements in DIN/ISO

Press the **SPEC FCT** key to program a block. Press the **PROGRAM FUNCTIONS** soft key, and then the **DIN/ISO** soft key. You can also use the gray path function keys to get the corresponding G code.



If you enter DIN/ISO functions via a connected USB keyboard, make sure that capitalization is active.



Example of a positioning block



G

• Enter 1 and press the ENT key to

COORDINATES ?



▶ 10 (enter the target coordinate for the X axis)



20 (enter the target coordinate for the Y axis)



Go to the next question with ENT.

MILLINGDEFINITIONPOINTPATH



Enter 40 and confirm with ENT to traverse without tool radius compensation, or



Move the tool to the left or to the right of the programmed contour: Press the G41 or G42 soft key

Feed rate F=?

▶ 100 (enter a feed rate of 100 mm/min for this path contour)

▶ Go to the next question with **ENT**.

MISCELLANEOUS FUNCTION M ?

- **3** (enter the miscellaneous function **M3 Spindle on**)
 - ▶ With the **END** key, the control ends this dialog.

Example

END

N30 G01 G40 X+10 Y+5 F100 M3*

Actual position capture

The control enables you to transfer the current tool position into the program, for example during

- Positioning-block programming
- Cycle programming

To transfer the correct position values, proceed as follows:

- Place the input box at the position in the block where you want to insert a position value
- +-

 Select the actual-position-capture function In the soft-key row the control displays the axes whose positions can be transferred.

AXIS Z

A

Select the axis
 The control writes the current position of the selected axis into the active input box.

In the working plane the control always captures the coordinates of the tool center, even though tool radius compensation is active.

The control takes the active tool length compensation into account and always captures the coordinate of the tool tip in the tool axis.

The control keeps the soft-key row for axis selection active until the **actual position capture** key is pressed again. This behavior remains in effect even if you save the current block or open a new block with a path function key. If you have to choose an input alternative via soft key (e.g. for radius compensation), then the control closes the soft-key row for axis selection.

The **actual-position-capture** function is not allowed if the **Tilt working plane** function is active.

Editing an NC program



The active NC program cannot be edited while it is being run.

While you are creating or editing an NC program, you can select any desired line in the NC program or individual words in a block with the arrow keys or the soft keys:

Soft key/key	Function
PAGE	Go to previous page
	Go to next page
BEGIN	Go to beginning of program
	Go to end of program
	Change the position of the current block on the screen. Press this soft key to display addition- al NC blocks that are programmed before the current block
	No function if the NC program is fully visible on the screen
	Change the position of the current block on the screen. Press this soft key to display addition- al NC blocks that are programmed after the current block
	No function if the NC program is fully visible on the screen
Ŧ	Move from one block to the next
-	Select individual words in a block
	To select a certain block, press the GOTO key, enter the desired block number, and confirm with the ENT key. Or: Press the GOTO key, enter the block number step and jump up or down the number of entered lines by pressing the N LINES soft key

Soft key/key Function	
CE	Set the selected word to zero
	Erase an incorrect number
	 Delete the (clearable) error message
INO ENT	Delete the selected word
DEL	Delete the selected block
	Erase cycles and program sections
INSERT LAST NC BLOCK	Insert the block that you last edited or deleted

Inserting blocks at any desired location

 Select the block after which you want to insert a new block and initiate the dialog

Saving changes

The control normally saves changes automatically if you switch the operating mode or if you select the file manager. If you deliberately want to save changes to the program, proceed as follows:

Select the soft-key row with the saving functions

STORE	

Press the STORE soft key The control saves all changes made since the last time you saved the program.

Saving a program to a new file

You can save the contents of the currently active program under a different program name. Proceed as follows:

Select the soft-key row with the saving functions



Press the SAVE AS soft key

- The control opens a window in which you can enter the directory and the new file name.
- Select the target directory if required with the SWITCH soft key
- Enter the file name
- Confirm with the OK soft key or the ENT key, or press the CANCEL soft key to abort



The file saved with **SAVE AS** can also be found in the file management by pressing the **LAST FILES** soft key.

Undoing changes

You can undo all changes made since the last time you saved the program. Proceed as follows:

Select the soft-key row with the saving functions



Press the CANCEL CHANGE soft key

- The control opens a window in which you can confirm or cancel this action.
- Confirm with the YES soft key or cancel with the ENT key, or press the NO soft key to abort

Editing and inserting words

- Select a word in a block and overwrite it with the new one. The dialog is available while the word is highlighted
- To accept the change, press the **END** key

If you want to insert a word, press the horizontal arrow key repeatedly until the desired dialog appears. You can then enter the desired value.

Looking for the same words in different blocks

- ->
- Select a word in a block: Press the arrow key repeatedly until the desired word is highlighted
- ł
- Select a block with the arrow keys
 - Arrow down: search forwards
 - Arrow up: search backwards

The word that is highlighted in the new block is the same as the one you selected previously.



If you start a search in a very long NC program, the control shows a progress indicator. You can cancel the search at any time, if necessary.

Marking, copying, cutting and inserting program sections

The control provides the following functions for copying program sections within an NC program or into another NC program:

Soft key	Function
SELECT BLOCK	Switch the marking function on
CANCEL SELECTION	Switch the marking function off
CUT OUT BLOCK	Cut the marked block
INSERT BLOCK	Insert the block that is stored in the buffer memory
COPY BLOCK	Copy the marked block

To copy a program section, proceed as follows:

- Select the soft key row containing the marking functions
- Select the first block of the section you wish to copy
- Mark the first block: Press the SELECT BLOCK soft key. The control highlights the block in color and displays the CANCEL SELECTION soft key.
- Move the highlight to the last block of the program section you wish to copy or cut.

The control shows the marked blocks in a different color. You can end the marking function at any time by pressing the **CANCEL SELECTION** soft key.

Copy the selected program section: Press the COPY BLOCK soft key. Cut the selected program section: Press the CUT OUT BLOCK soft key.

The control stores the selected block.



If you want to transfer a program section to another NC program, you now need to select the desired NC program in the file manager.

- Using the arrow keys, select the block after which you wish to insert the copied (cut) program section
- Insert the saved program section: Press the INSERT BLOCK soft key
- To end the marking function, press the CANCEL SELECTION soft key

The control's search function

The search function of the control enables you to search for any text within a program and replace it by a new text, if required.

Finding any text

FIND

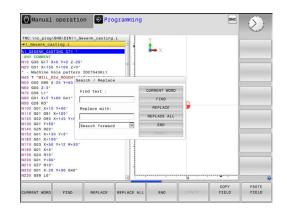
FIND

FIND

END

3 1	
	Select the search function
	The control superimposes the search window and displays the available search functions in the soft-key row.
	Enter the text to be searched for, e.g.: TOOL
	Select forwards search or backwards search
	Start the search process
	The control moves to the next block containing the text you are searching for.
	Repeat the search process
	The control moves to the next block containing the text you are searching for.

Terminate the search function: Press the END soft key



Finding/Replacing any text

NOTICE

Caution: Data may be lost!

The **REPLACE** and **REPLACE ALL** functions overwrite all found syntax elements without a confirmation prompt. The original file is not automatically backed up by the control before the replacement process. As a consequence, NC programs may be irreversibly damaged.

- Back up the NC programs, if required, before you start the replacement
- Be careful when using **REPLACE** and **REPLACE ALL**



The **FIND** and **REPLACE** functions cannot be used in the active NC program while the program is being run. The functions are also not available if write protection is active.

- Select the block containing the word you wish to find
 - FIND

FIND

REPLACE

END

Select the search function The control superimposes the search window and displays the available search functions in the soft-key row.

- Press the CURRENT WORD soft key The control loads the first word of the current block. If required, press the soft key again to load the desired word.
- Start the search process
 The control moves to the next occurrence of the text you are searching for.
- To replace the text and then move to the next occurrence of the text, press the **REPLACE** soft key. To replace all text occurrences, press the **REPLACE ALL** soft key. To skip the text and move to its next occurrence press the **FIND** soft key
- Terminate the search function: Press the END soft key

3.3 File management: Basics

Files

Files in the control	Туре
Programs in HEIDENHAIN format	.Н
in DIN/ISO format	.I
Compatible programs	
HEIDENHAIN unit programs	.HU
HEIDENHAIN contour programs	.HC
Tables for	
Tools	.Т
Tool changers	.TCH
Datums	.D
Points	.PNT
Presets	.PR
Touch probes	.TP
Backup files	.BAK
Dependent data (e.g. structure items)	.DEP
Freely definable tables	.TAB
Text as	
ASCII files	.Α
Log files	.TXT
Help files	.CHM
CAD files as	
ASCII files	.DXF
	.IGES
	.STEP

When you write a part program on the control, you must first enter a program name. The control saves the program to the internal memory as a file with the same name. The control can also save texts and tables as files.

The control provides a special file management window in which you can easily find and manage your files. Here you can call, copy, rename and erase files.

With the control you can manage and save files up to a total size of **2 GB**.



Depending on the setting, the control generates backup files with the extension *.bak after editing and saving of NC programs. This reduces the available memory space.

File names

When you store programs, tables and texts as files, the control adds an extension to the file name, separated by a point. This extension indicates the file type.

File name	File type
PROG20	.l

File names, drive names and directory names on the control must comply with the following standard: The Open Group Base Specifications Issue 6 IEEE Std 1003.1, 2004 Edition (POSIX Standard).

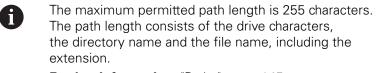
The following characters are permitted:

A B C D E F G H I J K L M N O P Q R S T U V W X Y Z a b c d e f g h i j k l m n o p q r s t u v w x y z 0 1 2 3 4 5 6 7 8 9 _ -

The following characters have special meanings:

Character	Meaning	
	The last period (dot) in a file name is the extension separator	
\ and /	Directory separators	
:	Separates the drive name from the directory	

Do not use any other characters. This helps to prevent file transfer problems, etc. Table names must start with a letter.



Further information: "Paths", page 145

Displaying externally generated files on the control

The control features several additional tools which you can use to display the files shown in the table below. Some of the files can also be edited.

File types	Туре	
PDF files Excel tables	pdf xls	
Internet files	csv html	
Text files	txt ini	
Graphics files	bmp gif jpg png	

Further information: "Additional tools for management of external file types", page 158

Data backup

HEIDENHAIN recommends backing up new programs and files created on the control to a PC at regular intervals.

The **TNCremo** data transmission freeware from HEIDENHAIN is a simple and convenient method for backing up data stored on the control.

You can also backup files directly from the control. **Further information:** "Backup and restore", page 101

You additionally need a data medium on which all machinespecific data, such as the PLC program, machine parameters, etc., are stored. Ask your machine manufacturer for assistance, if necessary.



Take the time occasionally to delete any unneeded files so that the control always has enough hard-disk space for system files (such as the tool table).

3.4 Working with the file manager

Directories

To ensure that you can easily find your programs and files, we recommend that you organize your internal memory into directories. You can divide a directory into further directories, which are called subdirectories. With the -/+ key or **ENT** you can show or hide the subdirectories.

Paths

A path indicates the drive and all directories and subdirectories under which a file is saved. The individual names are separated by a backslash λ .



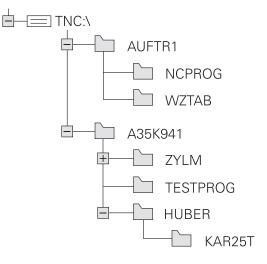
The maximum permitted path length is 255 characters. The path length consists of the drive characters, the directory name and the file name, including the extension.

Example

The directory AUFTR1 was created on the **TNC** drive. Then, in the AUFTR1 directory, the directory NCPROG was created and the part program PROG1.H was copied into it. The part program now has the following path:

TNC:\AUFTR1\NCPROG\PROG1.I

The chart at right illustrates an example of a directory display with different paths.



Overview: Functions of the file manager

Soft key	Page				
	Copy a single file	150			
SELECT	Display a specific file type	148			
NEW FILE	Create new file	150			
LAST FILES	Display the last 10 files that were selected	153			
DELETE	Delete a file	153			
TAG	Tag a file	155			
RENAME ABC = XYZ	Rename file	156			
	Protect a file against editing and erasure	157			
	Cancel file protection	157			
ADAPT NC PGM / TABLE	Import tool table of an iTNC 530	216			
	Customize table view	468			
NET	Manage network drives	170			
SELECT EDITOR	Select the editor	157			
SORT	Sort files by properties	156			
COPY DIR	Copy a directory	153			
ALL	Delete directory with all its subdirectories				
	Refresh directory				
RENAME	Rename a directory				
	Create a new directory				

Calling the file manager

PGM MGT Press the PGM MGT key

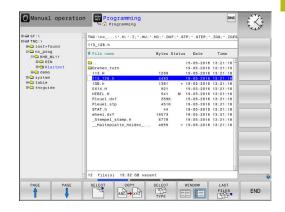
The control displays the file management window (see figure for default setting. If the control displays a different screen layout, press the **WINDOW** soft key).

The narrow window on the left shows the available drives and directories. Drives designate devices with which data are stored or transferred. A drive is the internal memory of the control. Other drives are the interfaces (RS232, Ethernet) to which you can connect a PC for example. A directory is always identified by a folder symbol to the left and the directory name to the right. Subdirectories are shown to the right of and below their parent directories. If there are subdirectories, you can show or hide them using the **-/+** key.

If the directory tree is longer than the screen, navigate using the scroll bar or a connected mouse.

The wide window on the right shows you all files that are stored in the selected directory. Each file is shown with additional information, illustrated in the table below.

Display	Meaning
File nam	e File name and file type
Bytes	File size in bytes
Status	File properties:
E	Program is selected in the Programming mode of operation
S	Program is selected in the Test Run mode of operation
M	Program is selected in a Program Run mode of operation
+	Program has non-displayed dependent files with the extension DEP, e.g. with use of the tool usage test
A	File is protected against erasing and editing
A	File is protected against erasing and editing, because it is being run
Date	Date that the file was last edited
Time	Time that the file was last edited
6	To display the dependent files, set the machine parameter dependentFiles (no. 122101) to MANUAL .

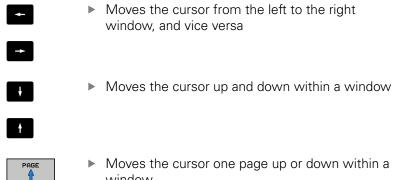


Selecting drives, directories and files



▶ To call the file manager, press the **PGM MGT** key.

Navigate with a connected mouse or use the arrow keys or the soft keys to move the cursor to the desired position on the screen:



Moves the cursor one page up or down within a window

▶ To select a drive, press the SELECT soft key, or

Step 1: Select drive

Move the highlight to the desired drive in the left window



PAGE



Press the ENT key

Step 2: Select a directory

Move the highlight to the desired directory in the left-hand window—the right-hand window automatically shows all files stored in the highlighted directory

Step 3: Select a file



Press the SELECT TYPE soft key



SHOW ALL

- Press the soft key for the desired file type, or
- Press the SHOW ALL soft key to display all files, or
- DISPLAY
- Use wildcards, e.g. 4*.h: Show all files of type .h starting with a 4
- Move the highlight to the desired file in the right window
- SELECT

ENT

Press the SELECT soft key, or

Press the ENT key The control opens the selected file in the operating mode from which you called the file manager.

6

If you enter the first letter of the file you are looking for in file management, the cursor automatically jumps to the first program with the same letter.

Creating a new directory

Move the highlight in the left window to the directory in which you want to create a subdirectory



- Press the NEW DIRECTORY soft key
- Enter a directory name
 Press the ENT key



Press the **OK** soft key to confirm or

Press the **CANCEL** soft key to abort

Creating new file

- Select the directory in the left window in which you wish to create the new file
- Position the cursor in the right window



- ▶ Press the **NEW FILE** soft key
- Enter the file name with extension
- Press the ENT key

Copying a single file

- Move the cursor to the file you wish to copy
 - Press the COPY soft key to select the copying function

The control opens a pop-up window.

Copying files into the current directory



- Enter the name of the destination file.
- Press the ENT key or the OK soft key

The control copies the file to the active directory. The original file is retained.

Copying files into another directory



Press the Target Directory soft key to select the target directory from a pop-up window



Press the ENT key or the OK soft key The control copies the file under the same name to the selected directory. The original file is retained.

0

When you start the copying process with the **ENT** key or the **OK** soft key, the control displays a pop-up window with a progress indicator.

Copying files into another directory

- Select a screen layout with two equally sized windows
- In the right window
- Press the SHOW TREE soft key
- Move the cursor to the directory into which you wish to copy the files, and display the files in this directory with the ENT key
- In the left window
- Press the SHOW TREE soft key
- Select the directory with the files to copy and press the SHOW FILES soft key to display them



вс→хүг

- Press the Tag soft key: Call the file tagging functions
- Press the Tag soft key: Position the cursor on the file you wish to copy and tag. You can tag several files in this way, if desired
- Press the Copy soft key: Copy the tagged files into the target directory

Further information: "Tagging files", page 155

If you have tagged files in both the left and right windows, the control copies from the directory in which the cursor is located.

Overwriting files

If you copy files to a directory in which other files are stored under the same name, the control will ask whether the files in the target directory should be overwritten:

- Overwrite all files (Existing files field selected): Press the OK soft key, or
- ▶ To leave the files as they are, press the CANCEL soft key

If you want to overwrite a protected file, select the **Protected files** field or cancel the process.

Copying a table

Importing lines to a table

If you are copying a table into an existing table, you can overwrite individual lines with the **REPLACE FIELDS** soft key. Prerequisites:

- The target table must exist
- The file to be copied must only contain the lines you want to replace
- Both tables must have the same file extension

NOTICE

Caution: Data may be lost!

If you use the **REPLACE FIELDS** function, all lines of the target file that are contained in the copied table will be overwritten without a confirmation prompt. The original file is not automatically backed up by the control before the replacement process. As a consequence, tables may be irreversibly damaged.

- Back up the tables, if required, before you start the replacement
- Be careful when using **REPLACE FIELDS**

Example

With a tool presetter you have measured the length and radius of ten new tools. The tool presetter then generates the TOOL_Import.T tool table with 10 lines (for the 10 tools).

- Copy this table from the external data medium to any directory
- Copy the externally created table to the existing TOOL.T table using the control's file management.
 The control asks you whether you want to overwrite the existing TOOL.T tool table.
- If you press the REPLACE FIELDS soft key, the control will completely overwrite the current TOOL.T tool table. After this copying process the new TOOL.T table consists of 10 lines.
- Or press the REPLACE FIELDS soft key for the control to overwrite the 10 lines in the TOOL.T file. The data of the other lines is not changed.

Extracting lines from a table

You can select one or more lines in a table and save them in a separate table.

- Open the table from which you want to copy lines
- Use the arrow keys to select the first line to be copied
- Press the MORE FUNCTIONS soft key
- Press the TAG soft key
- Select additional lines, if required
- Press the SAVE AS soft key
- Enter a name for the table in which the selected lines are to be saved

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Copying a directory

- Move the highlight in the right window onto the directory you want to copy
- Press the COPY soft key The control opens the window for selecting the target directory.
- Select the target directory and confirm with the ENT key or the OK soft key

The control copies the selected directory and all its subdirectories to the selected target directory.

Choosing one of the last files selected

To call the file manager, press the PGM MGT key.



PGM MGT

> To display the last ten files selected: press the LAST FILES soft key

Press the arrow keys to move the cursor to the file you wish to select:



Moves the cursor up and down within a window

► To select the file, press the **OK** soft key, or



i

Press the ENT key

The **COPY FIELD** soft key allows you to copy the path of a marked file. You can reuse the copied path later, e.g. when calling a program with the **PGM CALL** key.

Deleting a file

NOTICE

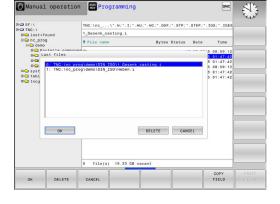
Caution: Data may be lost!

The **DELETE** function permanently deletes the file. The file is not automatically backed up by the control, e.g. to a recycle bin, before being deleted. Files are irreversibly deleted by this function.

- Regularly back up important data to external drives
- Move the cursor to the file you want to delete
 - To select the erasing function, press the DELETE soft key

The control asks whether you want to delete the file.

- To confirm the deletion, press the OK soft key; or
- ▶ To cancel deletion, press the CANCEL soft key



Deleting a directory

NOTICE

Caution: Data may be lost!

The **DELETE ALL** function permanently deletes all files of the directory. The files are not automatically backed up by the control, e.g. to a recycle bin, before being deleted. Files are irreversibly deleted by this function.

- Regularly back up important data to external drives
- Move the cursor to the directory you want to delete



To select the erasing function, press the DELETE soft key

The control asks you whether you really want to delete the directory and all its subdirectories and files.

- ► To confirm the deletion, press the **OK** soft key; or
- ► To cancel deletion, press the **CANCEL** soft key

Tagging files

Soft key	Tagging function
TAG FILE	Tag a single file
TAG ALL FILES	Tag all files in the directory
UNTAG FILE	Untag a single file
UNTAG ALL FILES	Untag all files
COPY TAG	Copy all tagged files

Some functions, such as copying or erasing files, can not only be used for individual files, but also for several files at once. To tag several files, proceed as follows:

- Move the cursor to the first file
- TAG
- ▶ To display the tagging functions, press the **TAG** soft key
- TAG FILE
- ► To tag the file, press the **TAG FILE** soft key



FILE

Move the cursor to other files

▶ To select the next file, press the **TAG FILE** soft key. Repeat this process for all files you want to tag.

To copy tagged files:



Leave the active soft-key row



Press the COPY soft key

To delete tagged files:



Leave the active soft-key row



Press the **DELETE** soft key

Renaming a file

Move the cursor to the file you wish to rename



- To select the function for renaming, press the RENAME soft key
- Enter the new file name; the file type cannot be changed
- ► To rename: Press the **OK** soft key or the **ENT** key

Sorting files

Select the folder in which you wish to sort the files



- Press the SORT soft key
- Select the soft key with the corresponding display criterion
 - SORT BY NAME
 - SORT BY SIZE
 - SORT BY DATE
 - SORT BY TYPE
 - SORT BY STATUS
 - UNSORTED

Additional functions

Protecting a file / Canceling file protection

Move the cursor to the file you want to protect

I	MORE
l	FUNCTIONS

 To select the additional functions, press the MORE FUNCTIONS soft key



Enable file protection: Press the **PROTECT** soft key. The file is tagged with the "protected" symbol



To cancel file protection, press the UNPROTECT soft key

Selecting the editor

 Move the cursor in the right-hand window onto the file you want to open



- To select the additional functions, press the MORE FUNCTIONS soft key
- SELECT
- To select the editor with which to open the selected file, press the SELECT EDITOR soft key
- Mark the desired editor
- Press the **OK** soft key to open the file

Connecting and removing USB storage devices

The control automatically detects connected USB devices with a supported file system.

▶ To remove a USB device, proceed as follows:



Move the cursor to the left-hand window
 Press the MORE FUNCTIONS soft key



Remove the USB device

Further information: "USB devices on the control", page 171

Additional tools for management of external file types

The additional tools enable you to display or edit various externally created file types on the control.

File types	Description
PDF files (pdf)	page 159
Excel spreadsheets (xls, csv)	page 160
Internet files (htm, html)	page 161
ZIP archives (zip)	page 163
Text files (ASCII files, e.g. txt, ini)	page 164
Video files (ogg, oga, ogv, ogx)	page 165
Graphics files (bmp, jpg, gif, png)	page 165

Files with the extensions pdf, xls, zip, bmp, gif, jpg and png must be transmitted in binary format from the PC to the control. Adjust the setting in the TNCremo data transfer software, if required (menu item >**Extras > Configuration > Mode**).

6

Displaying PDF files

To open PDF files directly on the control, proceed as follows:



- ► To call the file manager, press the **PGM MGT** key.
- Select the directory in which the PDF file is saved
- Move the cursor to the PDF file
- Press the ENT key The control opens the PDF file in its own application using the PDF viewer additional tool.

6

A

ENT

With the key combination ALT+TAB you can always return to the control's user interface while leaving the PDF file open. Alternatively, you can also click the corresponding symbol in the task bar to switch back to the user interface of the control.

If you position the mouse pointer over a button, a brief tool tip explaining the function of this button will be displayed. More information on how to use the **PDF viewer** is provided under **Help**.

Proceed as follows to exit the **PDF viewer**:

- ▶ Use the mouse to select the File menu item
- Select Close

The control returns to the file management.

If you are not using a mouse, proceed as follows to close the **PDF** viewer:

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- Press the key for switching the soft keys The **PDF viewer** opens the **File** pull-down menu.
- Move the cursor to the **Close** menu item.
 - Press the ENT key The control returns to the file management.



Displaying and editing Excel files

Proceed as follows to open and edit Excel files with the extension **xls**, **xlsx** or **csv** directly on the control:



- To call the file manager, press the PGM MGT key.
- Select the directory in which the Excel file is saved
- Move the cursor to the Excel file
- Press the ENT key The control opens the Excel file in its own application using the Gnumeric additional tool.



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With the key combination ALT+TAB you can always return to the control's user interface while leaving the Excel file open. Alternatively, you can also click the corresponding symbol in the task bar to switch back to the user interface of the control.

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If you position the mouse pointer over a button, a brief tool tip explaining the function of this button will be displayed. More information on how to use the **Gnumeric** function is provided under **Help**.

Proceed as follows to exit Gnumeric:

- Use the mouse to select the File menu item
- Select Close

The control returns to the file management.

If you are not using a mouse, proceed as follows to close the additional **Gnumeric** tool:



Press the key for switching the soft keys The **Gnumeric** additional tool opens the **File** pulldown menu.



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- Move the cursor to the Close menu item
- Press the ENT key The control returns to the file management.

Displaying Internet files



Configure and use the sandbox on your control. For safety and security reasons, always open the browser in the sandbox.

Proceed as follows to open Internet files with the extension **htm** or **html** directly on the control:



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- ► To call the file manager, press the **PGM MGT** key.
- Select the directory in which the Internet file is saved
- ▶ Move the cursor to the Internet file
- Press the ENT key The control opens the Internet file in its own application using the Web Browser additional tool.



With the key combination ALT+TAB you can always return to the control's user interface while leaving the PDF file open. Alternatively, you can also click the corresponding symbol in the task bar to switch back to the user interface of the control.

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If you position the mouse pointer over a button, a brief tool tip explaining the function of this button will be displayed. More information on how to use **Web Browser** is available in **Help**.



Proceed as follows to exit the Web Browser:

- ▶ Use the mouse to select the **File** menu item
- Select Quit

The control returns to the file management.

If you are not using a mouse, proceed as follows to close the **Web Browser**:

\triangleright	 Press the key for switching the soft keys: The Web Browser opens the File pull-down menu
ţ	Move the cursor to the Quit menu item
ENT	 Press the ENT key The control returns to the file management.
6	Do not change the Web Browser version. Otherwise, the security settings of SELinux will block the execution of Web Browser.

Working with ZIP archives

Proceed as follows to open ZIP archives with the extension \boldsymbol{zip} directly on the control:



- To call the file manager, press the PGM MGT key.
- Select the directory in which the archive file is saved
- Move the cursor to the archive file
- Press the ENT key The control opens the archive file in its own application using the Xarchiver additional tool.

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With the key combination ALT+TAB you can always return to the control's user interface while leaving the archive file open. Alternatively, you can also click the corresponding symbol in the task bar to switch back to the user interface of the control.

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If you position the mouse pointer over a button, a brief tool tip explaining the function of this button will be displayed. More information on how to use the **Xarchiver** function is provided under **Help**.

Proceed as follows to exit Xarchiver:

- ▶ Use the mouse to select the **ARCHIVE** menu item
- Select Exit

The control returns to the file management.

If you are not using a mouse, proceed as follows to close the **Xarchiver**:

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- Press the key for switching the soft keys
 Xarchiver opens the ARCHIVE pull-down menu.
- Move the cursor to the Exit menu item

Press the ENT key

The control returns to the file management.

		FKPROG	ZIP -	Xar	chive	r 0.5.2				• • •
Archive Agtion Help										
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	FK-SL-KOMBL	н -ам-а	2.0	fat	2268	744	defX	16-May-01	13:50	
	themus.c	-64-30-	2.0	fat	2643	1012	defX	6-Apr-99	16:31	
	ficth	-64-30-	2.0	fat	605869	94167	defX	5-Mar-99	10:55	
		-69-3	2.0	fat	\$\$9265	83261	defX	S-Mar-99	10:41	
	PKS.H	-64-30-	2.0	fat	655	309	defx	16-May-01	13.50	
	FK4.H	-64-3	2.0	fat	948	394	defX	16-May-01	13.50	
	FIGH	-ma-	2.0	fat	449	241	defX	16-May-01	13:50	
	PK1H	-64-3	2.0	fat	348	189	defX	18-Sep-03	13:39	
	farresa.h	-ew-a-	2.0	fat	266	169	defX	16-May-01	13.50	
	country h	ew-a-	2.0	fat	509	252	defX	16-May-01	13:50	
	bsplk1.h	-m-a	2.0	fat	383	239	defX	16 May 01	13:50	
	bri.h	-04-2	2.0	fat	538	261	defX	27-Ape-01	10:36	
	apprict.h	-64-3	2.0	fat	601	325	defx	13-Jun-97	13.96	
	appr2.h	-64-3	2.0	fat	600	327	detx	30-Jul-99	08:49	
	ANKER.H	-64-3	2.0	fat	580	310	defX	16-May-01	13:50	
	ANKER2.H	-00-3	2.0	64	1253	601	defX.	16-May-01	13:50	

Displaying and editing text files

Use the internal text editor to open and edit text files (ASCII files, e.g. with the extension txt). Proceed as follows:



- To call the file manager, press the **PGM MGT** key.
- Select the drive and the directory in which the text file is saved
- Move the cursor to the text file
- Press the ENT key The control opens the text file with the internal text editor.

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Alternatively, you can also open the ASCII files using the **Leafpad** additional tool. The shortcuts you are familiar with from Windows, which you can use to edit texts quickly (CTRL+C, CTRL+V,...), are available within **Leafpad**.

With the key combination ALT+TAB you can always return to the control's user interface while leaving the text file open. Alternatively, you can also click the corresponding symbol in the task bar to switch back to the user interface of the control.

Proceed as follows to open Leafpad:

- Use the mouse to select the Menu HEIDENHAIN icon from the task bar
- Select the Tools and Leafpad menu items in the pull-down menu

Proceed as follows to exit **Leafpad**:

- Use the mouse to select the File menu item
- Select Exit

The control returns to the file management.

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For head axes the rotary axis must be measured twice, each time with a stylus of a different length. After exchanging the stylus between the two measurements, the touch probe must be recalibrated. The new calibration cycle 640 automatically calibrates the touch probe using the XXX calibration sphere from MEIDENNIN already in place.

upport for the messarement of Mirth-coupled spindle heads has also been improved. In stillinging of the spindle head can now be performed via as NC survey that the machine tool builder stillinging of the spindle head can be been builder and the spindle s

Displaying video files



This feature must be enabled and adapted by the machine tool builder.

Proceed as follows to open video files with the extension **ogg**, **oga**, **ogv** or **ogx** directly on the control:



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- To call the file manager, press the PGM MGT key.
- Select the directory in which the video file is saved
- Move the cursor to the video file
- Press the ENT key The control opens the video file in its own application.

Displaying graphic files

Proceed as follows to open graphics files with the extension **bmp**, **gif**, **jpg** or **png** directly on the control:



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- ► To call the file manager, press the **PGM MGT** key.
- Select the directory in which the graphics file is saved
- Move the cursor to the graphics file
- Press the ENT key The control opens the graphics file in its own application using the ristretto additional tool.

With the key combination ALT+TAB you can always return to the control's user interface while leaving the graphics file open. Alternatively, you can also click the corresponding symbol in the task bar to switch back to the user interface of the control.



More information on how to use the **ristretto** function is provided under **Help**.

Proceed as follows to exit ristretto:

- Use the mouse to select the File menu item
- Select Exit

The control returns to the file management.

If you are not using a mouse, proceed as follows to close the additional **ristretto** tool:



- Press the key for switching the soft keys ristretto opens the File pull-down menu.
- Move the cursor to the Exit menu item

ENT

Press the ENT key The control returns to the file management.



Additional tools for ITCs

The following additional tools allow you to apply various settings for the touch screens on connected ITCs.

ITCs are industrial PCs without their own memory media, and therefore they do not have their own operating system. This feature is what makes ITCs different from IPCs.

ITCs are frequently used with large machinery, e.g. as a clone of the actual control system.



Refer to your machine manual.

The machine manufacturer defines and configures the display and function of the connected ITCs and IPCs.

Additional tool	Application				
ITC Calibration	4-point calibration				
ITC Gestures	Configuration of gesture control				
ITC touchscreen configuration	Selection of touch sensitivity				



The additional tools for the ITCs are only provided by the control in the taskbar with connected ITCs.

ITC Calibration

Using the additional tool **ITC Calibration,** you align the position for the mouse cursor displayed with the actual movement position of your finger.

Calibration using the additional **ITC Calibration** tool is recommended in the following cases:

- After replacing the touchscreen
- When changing the touch screen position (parallel axis error due to amended viewing angle)

Calibration involves the following steps:

Start the tool in control using the task bar

The ITC opens the calibration screen with four touch points in the corners of the screen $% \left({{{\rm{TC}}}} \right)$

 Touch the four touch points shown one after the other The ITC closes the calibration screen once calibration has been successfully completed

ITC Gestures

Using the additional **ITC Gestures** tool, the machine manufacturer configures the gesture control on the touch screen.



Refer to your machine manual.

This function may only be used with the permission of your machine manufacturer.

ITC touchscreen configuration

Using the additional **ITC Touchscreen Configuration** tool, you can select the touch sensitivity of the touch screen.

The ITC gives you the following options:

- Normal Sensitivity (Cfg 0)
- High Sensitivity (Cfg 1)
- Low Sensitivity (Cfg 2)

Use the **Normal Sensitivity (Cfg 0)** setting as standard. If you find it difficult to operate the equipment while wearing gloves in this setting, select the **High Sensitivity (Cfg 1)** setting.



If the ITC touch screen is not splash-proof, select the **Low Sensitivity (Cfg 2)** setting. This stops the ITC interpreting drops of water as touches.

Configuration involves the following steps:

- Start the tool in control using the task bar The ITC opens a pop-up window with three options
- Select Touch Sensitivity
- Press the OK button
 The ITC closes the pop-up window

Data transfer to or from an external data carrier



Before you can transfer data to an external data medium, you must set up the data interface. **Further information:** "Setting up data interfaces", page 637

PGM MGT

► To call the file manager, press the **PGM MGT** key.



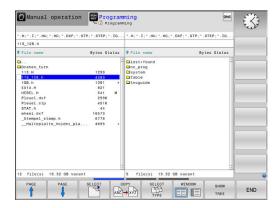
 Select the screen layout for data transfer: press the WINDOW soft key.

Use the arrow keys to move the cursor to the file you wish to transfer:



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Moves the cursor up and down within a window





 Moves the cursor from the right to the left window, and vice versa If you wish to copy from the control to the external data medium, move the cursor in the left window to the file to be transferred. If you wish to copy from the external data medium to the control, move the cursor in the right window to the file to be transferred.



- Select another drive or directory: Press the SHOW TREE soft key
- Use the arrow keys to select the desired directory
- Select the desired file: Press the SHOW FILES soft key



- Use the arrow keys to select the file
- ► Transfer a single file: Press the **COPY** soft key
- Confirm with the OK soft key or with the ENT key A status window appears on the control, informing about the copying progress, or



- Stop transfer: Press the **WINDOW** soft key
 - The control displays the standard file manager window again.

The control in a network



Protect your data and your control by running your machines in a secure network.

6

Use the Ethernet card to connect the control to the network.

Further information: "Ethernet interface ", page 643 The control logs any error messages that occur during network operation.

If the control is connected to a network, the left directory window displays additional drives. All the functions described above (selecting a drive, copying files, etc.) also apply to network drives, provided that you have been granted the corresponding rights.

Connecting and disconnecting a network drive

PGM
MGT

To call the file manager, press the PGM MGT key

NET

 Select network settings: Press the NET soft key (soft-key row 2)

- To manage the network drives: Press the DEFINE NETWORK CONNECTN. soft key. In a window the control shows the network drives available for access.
- With the soft keys described below you can define the connection for each drive.

Soft key	Function					
Connect	Establish the network connection. If the connection is active, the control marks the Mount column.					
Separate	End network connection					
Auto	Automatically establish network connection whenever the control is switched on. The control marks the Auto column if the connec- tion is established automatically					
Add	Set up new network connection					
Remove	Delete existing network connection					
Сору	Copy network connection					
Edit	Edit network connection					
Clear	Delete the status window					

	maau	r opi	STATIC			ogramm	TUA				09:24
D-D TNC: \ D-D lost+found			TP	TNC:\nc_prog\PGM*.H:*.I:*.DXF							
Hount Setup			4	A							
Network of	10.00										
Mount		Type	Drive	D	Server	Share	User	Password	Ask for password?	Options	
		cits	5:	1	zeichnun	Screens	a13608	145			
Mou	14		Aun	0		Add		Remov		Copy	Edit
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USB devices on the control



Use the USB port only for file transfer and backup. Before editing or running an NC program, save it to the hard disk of the control. This helps to avoid duplicate data maintenance and prevents potential problems resulting from data transfer during program run.

Backing up data from or loading onto the control is especially easy with USB devices. The control supports the following USB block devices:

- Floppy disk drives with FAT/VFAT file system
- Memory sticks with the FAT/VFAT file system
- Hard disks with the FAT/VFAT file system
- CD-ROM drives with the Joliet (ISO 9660) file system

The control automatically detects these types of USB devices when connected. The control does not support USB devices with other file systems (such as NTFS). The control displays the **USB: TNC does not support device** error message when such a device is connected.

If an error message is displayed when connecting a USB data medium, check the setting in the SELinux security software.

Further information: "SELinux security software", page 98

If the control displays the **USB: TNC does not support device** error message when using a USB hub, ignore and acknowledge the message with the **CE** key.

If the control repeatedly fails to correctly detect a USB device with the FAT/VFAT file system, connect another device to check the port. If this resolves the problem, use the properly working device.

Working with USB devices

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Refer to your machine manual.

Your machine tool builder can assign permanent names for USB devices.

The USB devices appear as separate drives in the directory tree, so you can use the file management functions described in the earlier chapters.

If a larger file is transferred to a USB device in the file management, the control displays a dialog **Write access on USB device** until file transfer is completed. The dialog is closed with the **HIDE** soft key and file transfer is continued in the background. The control displays a warning until file transfer is completed.

Removing USB devices

► To remove a USB device, proceed as follows:



- Move the cursor to the left-hand window
- Press the MORE FUNCTIONS soft key

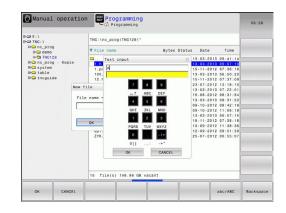


Remove the USB device

Programming Aids

4.1 Screen keypad

If you are using the compact version of the control (without alphabetic keyboard), you can enter letters and special characters with the screen keypad or with a PC keyboard connected to the USB port.



Entering text with the screen keyboard

- Press the GOTO key if you want to enter letters, e.g. a program name or directory name, using the screen keypad.
 The control opens a window in which the numeric entry field of the control is displayed with the corresponding letters assigned.
- You can move the cursor to the desired character by repeatedly pressing the respective key
- Wait until the control transfers the selected character to the entry field before you enter the next character
- ▶ Use the **OK** soft key to load the text into the open dialog field

Use the **abc/ABC** soft key to select upper or lower case. If your machine manufacturer has defined additional special characters, you can call them with the **SPECIAL CHARACTERS** soft key and insert them. Use the **BACKSPACE** soft key to delete individual characters.

4.2 Adding comments

Application

You can add comments to an NC program to explain program steps or make general notes.

The control shows long comments in different ways, depending on the machine parameter **lineBreak** (no. 105404). It either wraps the comment lines or displays the >> symbol to indicate additional content. The last character in a comment block must not have any tilde(~).

You can add comments in different ways.

Entering comments during programming

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To use this function you will need a keyboard connected via USB.

- Enter the data for an NC block
- Press the semicolon key; on the alphabetic keyboard The control displays the dialog prompt Comment?
- Enter the comment
- Press the END key to conclude the NC block

Inserting comments after program entry

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To use this function you will need a keyboard connected via USB.

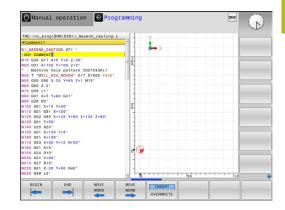
- Select the NC block to which you want to add the comment
- Select the last word in the NC block with the right arrow key:
- Press the semicolon key; on the alphabetic keyboard The control displays the dialog prompt Comment?
- Enter the comment
- Press the END key to conclude the NC block

Entering a comment in a separate block



To use this function you will need a keyboard connected via USB.

- Select the NC block after which you want to insert the comment
- Initiate the programming dialog with the semicolon key; on the alphabetic keyboard
- Enter your comment and conclude the NC block by pressing the END key



Commenting out an existing NC block

Proceed as follows to change an existing NC block to a comment:

Select the NC block to be commented out



► Press the INSERT COMMENT soft key

The control inserts a semicolon ; at the beginning of the block.

Press the END key

Changing a comment for an NC block

Proceed as follows to change a commented-out NC block to an active NC block:

Select the comment block you want to change



Press the **REMOVE COMMENT** soft key Alternative:

- Press the > key on the alphabetic keyboard The control removes the semicolon; at the beginning of the block.
- Press the END key

Functions for editing of the comment

Soft key	Function
BEGIN	Jump to beginning of comment
	Jump to end of comment
MOVE WORD	Jump to the beginning of a word. Use a space to separate words
MOVE WORD	Jump to the end of a word. Use a space to separate words
INSERT OVERWRITE	Switch between paste and overwrite mode

4.3 Freely editing an NC program

Certain syntax elements, such as LN blocks, cannot be entered directly in the NC editor by using the available keys and soft keys. To prevent the use of an external text editor, the control offers the following possibilities:

- Free syntax input using the control's integrated text editor
- Free syntax input using the ? key in the NC editor

Free syntax input using the control's integrated text editor

Proceed as follows to add syntax to an existing NC program:

- ▶ Press the **PGM MGT** key
 - The control opens the file manager.Press the MORE FUNCTIONS soft key



SELECT

ок

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- Press the SELECT EDITOR soft key
 - The control opens a selection window.
- Select the **TEXT EDITOR** option
- ► Confirm your selection with **OK**
- Add the desired syntax

The control does not check the syntax in the text editor. Check your entries in the NC editor when you are finished.

Free syntax input using the ? key in the NC editor



To use this function you will need a keyboard connected via USB.

Proceed as follows to add syntax to an existing, open NC program:

Enter ?

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The control opens a new NC block.



- Add the desired syntax
- Confirm your entry with END



After confirmation, the control checks the syntax. Errors will result in **ERROR** blocks.

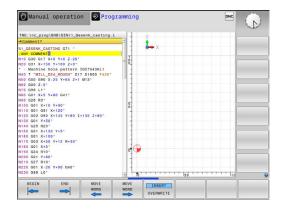
4.4 Display of NC programs

Syntax highlighting

The control displays syntax elements with various colors according to their meaning. Programs are made more legible and clear with color-highlighting.

Color highlighting of syntax elements

Use	Color
Standard color	Black
Display of comments	Green
Display of numerical values	Blue
Display of the block number	Violet
Display of FMAX	Orange
Display of the feed rate	Brown



Scrollbar

Screen content can be shifted with the mouse using the scroll bar at the right edge of the program window. In addition, the size and position of the scrollbar indicates program length and cursor position.

4.5 Structuring programs

Definition and applications

The control offers you the possibility to comment part programs in structuring blocks. Structuring blocks are texts with up to 252 characters and are used as comments or headlines for the subsequent program lines.

With the aid of appropriate structuring blocks, you can organize long and complex programs in a clear and comprehensible manner.

This function is particularly convenient if you want to change the program later. Structuring blocks can be inserted into the part program at any point.

Structure blocks can also be displayed in a separate window, and be edited or added to, as desired. Use the appropriate screen layout for this.

The control manages the inserted structure items in a separate file (extension: .SEC.DEP). This speeds navigation in the program structure window.

The **PROGRAM + SECTS** screen layout can be selected in the following operating modes:

- Program run, single block
- Program run, full sequence
- Programming

Displaying the program structure window / Changing the active window

PROGRAM
+
SECTS

- Display structure window: For this screen layout press the PROGRAM + STRUCTURE soft key
- Change the active window: Press the CHANGE WINDOW soft key



Inserting a structure block in the program window

Select the block after which the structuring block is to be inserted

SPEC FCT	Press the SPEC FCT key
PROGRAM- MING AIDS	Press the PROGRAMMING AIDS soft key
INSERT	Press the INSERT SECTION soft key
SECTION	 Enter the structuring text
	If necessary, change the structure depth with the soft key
0	You can also insert structure blocks with the key combination Shift + 8 .

Selecting blocks in the program structure window

If you are scrolling through the program structure window block by block, the control at the same time automatically moves the corresponding NC blocks in the program window. This way you can quickly skip large program sections.

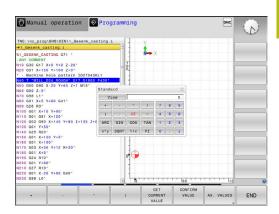
4.6 Calculator

Operation

The control features an integrated calculator with the basic mathematical functions.

- Use the CALC key to show and hide the calculator
- Select the arithmetical functions: The calculator is operated with short commands via soft key or through the alphabetic keyboard

Calculate function	Shortcut (soft key)	
Addition	+	
Subtraction	_	
Multiplication	*	
Division	/	
Calculating with parentheses	()	
Arc cosine	ARC	
Sine	SIN	
Cosine	COS	
Tangent	TAN	
Powers of values	Х^Ү	
Square root	SQRT	
Inversion	1/x	
pi (3.14159265359)	PI	
Add value to buffer memory	M+	
Save the value to buffer memory	MS	
Recall from buffer memory	MR	
Delete buffer memory contents	MC	
Natural logarithm	LN	
Logarithm	LOG	
Exponential function	e^x	
Check the algebraic sign	SGN	
Form the absolute value	ABS	



Calculate function	Shortcut (soft key)
Truncate decimal places	INT
Truncate places before the decimal point	FRAC
Modulus operator	MOD
Select view	View
Delete value	CE
Unit of measure	MM or INCH
Show angle values in radians (standard: angle in degrees)	RAD
Select the display mode of the numeri-	DEC (decimal) or HEX

cal value (hexadecimal)

Transferring the calculated value into the program

- Use the arrow keys to select the word into which the calculated value is to be transferred
- Superimpose the on-line calculator by pressing the CALC key and perform the desired calculation
- Press the CONFIRM VALUE soft key

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The control transfers the value into the active input field and closes the calculator.

You can also transfer values from an NC program into the calculator. When you press the **GET CURRENT VALUE** soft key or the **GOTO** key, the control transfers the value from the active input field to the calculator.

The calculator remains in effect even after a change in operating modes. Press the **END** soft key to close the calculator.

Functions in the pocket calculator

Soft key	Function
AX. VALUES	Load the nominal or reference value of the respective axis position into the calculator
GET CURRENT VALUE	Load the numerical value from the active input field into the calculator
CONFIRM VALUE	Load the numerical value from the calculator field into the active input field
COPY FIELD	Copy the numerical value from the calculator
PASTE FIELD	Insert the copied numerical value into the calcu- lator
CUTTING DATA CALCULATOR	Open the cutting data calculator
Vou	can also shift the calculator with the arrow kove on

0

You can also shift the calculator with the arrow keys on your keyboard. If you have connected a mouse you can also position the calculator with this.

4.7 Cutting data calculator

Application

With the cutting data calculator you can calculate the spindle speed and the feed rate for a machining process. Then you can load the calculated values into an opened feed rate or spindle speed dialog box in the NC program.

To open the cutting data calculator, press the

CUTTING DATA CALCULATOR soft key. The control shows the soft key if you

- open the on-line calculator (press the CALC soft key)
- open the dialog field for spindle speed input in the T block
- open the dialog field for feed rate input in positioning blocks or cycles
- enter a feed rate in manual mode (press the F soft key)

enter a spindle speed in manual mode (press the S soft key) The cutting data calculator is displayed with different input fields depending on whether you calculate a spindle speed or a feed rate:

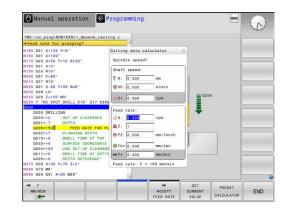
Window for spindle speed calculation:

Code letter	Meaning
R:	Tool radius (mm)
VC:	Cutting speed (m/min)
S=	Result for spindle speed (rev/min)

Window for feed rate calculation:

Code letter	Meaning
S:	Spindle speed (rpm)
Z:	Number of teeth on the tool (n)
FZ:	Feed per tooth (mm/tooth)
FU:	Feed rate per revolution (mm/1)
F=	Result for feed rate (mm/min)

You can transfer the feed rate from the **T** block into subsequent traversing blocks and cycles by pressing the **F AUTO** soft key. If you have to change the feed rate later, you only need to adjust the feed rate value in the **T** block.



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Functions in the cutting data calculator:

Soft key	Function
U S RPM	Load the spindle speed from the cutting data calculator form into an open dialog field.
MM/MIN	Load the feed rate from the cutting data calcula- tor form into an open dialog field.
∜ VC M∕MIN	Load the cutting speed from the cutting data calculator form into an open dialog field.
<pre> FZ MM∠TOOTH S </pre>	Load the feed per tooth from the cutting data calculator form into an open dialog field.
S FU MM/REV	Load the feed per revolution from the cutting data calculator form into an open dialog field.
ACCEPT TOOL RADIUS	Load the tool radius into the cutting data calcu- lator form
じ CONFIRM RPM	Load the spindle speed from the open dialog field into the cutting data calculator form
RCCEPT FEED RATE	Load the feed rate from the open dialog field into the cutting data calculator form
STATE ACCEPT FEED RATE	Load the feed per revolution from the open dialog field into the cutting data calculator form
ACCEPT FEED RATE	Load the feed per tooth from the open dialog field into the cutting data calculator form
GET CURRENT VALUE	Load the value from an open dialog field into the cutting data calculator form
POCKET CALCULATOR	Switch to the pocket calculator
ţ	Move the cutting data calculator in the direction of the arrow
INCH	Use inch values in the cutting data calculator
END	Close the cutting data calculator

4.8 **Programming graphics**

Activating and deactivating programming graphics

While you are writing an NC program, you can have the control generate a 2-D pencil-trace graphic of the programmed contour.

- Press the Screen layout key
- Press the PROGRAM + GRAPHICS soft key

The control shows the NC program to the left and graphics to the right.



Set the AUTO DRAW soft key to ON

While you are entering the program lines, the control generates each programmed movement in the graphics window in the right screen half.

If you do not wish to have the control generate graphics during programming, set the **AUTO DRAW** soft key to **OFF**.

If **AUTO DRAW** is set to **ON**, the control ignores the following program content when creating 2-D pencil-trace graphics:

- Program section repetitions
- Jump commands
- M functions, such as M2 or M30
- Cycle calls
- Warnings due to locked tools

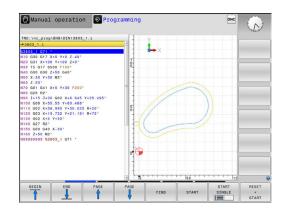
Therefore, only use automatic drawing during contour programming.

The control resets the tool data if you reopen a program or press the **RESET + START** soft key.

The control uses various colors in the programming graphics:

- **blue:** uniquely specified contour element
- violet: not yet uniquely specified contour element, can still be modified by e.g. an RND
- light blue: holes and threads
- ocher: tool midpoint path
- red: rapid traverse

Further information: "FK programming graphics", page 283



Generating a graphic for an existing program

Use the arrow keys to select the block up to which you want the graphic to be generated, or press GOTO and enter the desired block number



Reset previously active tool data and generate graphics: Press the RESET + START soft key

Additional functions:

Soft key	Function
RESET + START	Reset previously active tool data. Generate programming graphics
START SINGLE	Generate programming graphic blockwise
START	Generate a complete graphic or complete it after RESET + START
STOP	Stop the programming graphics. This soft key only appears while the control is generating the programming graphics
VIEWS	Selecting views Plan view Front view Page view
TOOL PATH: SHOW HIDE	Display or hide tool paths
FMAX PATHS DISPLAY HIDE	Display or hide tool paths in rapid traverse

Block number display ON/OFF



Shift the soft-key row



To show block numbers: Set the BLOCK NO. SHOW OMIT soft key to SHOW

To hide block numbers: Set the BLOCK NO. SHOW OMIT soft key to OMIT

Erasing the graphic



Shift the soft-key row



Erase the graphics: Press the CLEAR GRAPHICS soft key

Showing grid lines

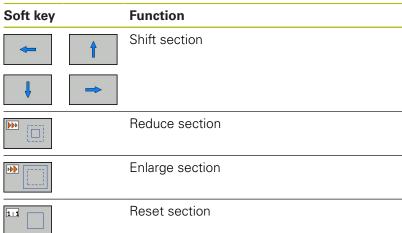


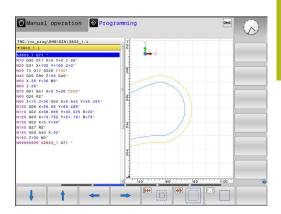
- Shift the soft-key row
- OFF ON
- Show grid lines: Press the Show grid lines soft key

Magnification or reduction of details

- You can select the graphics display
- Shift the soft-key row

The following functions are available:





With the **RESET BLK FORM** soft key, you can restore the original section.

You can also use the mouse to change the graphic display. The following functions are available:

- To shift the model shown, hold the center mouse button or mouse wheel down and move the mouse. If you simultaneously press the shift key, you can only shift the model horizontally or vertically.
- To zoom in on a certain area, mark a zoom area by holding the left mouse button down. After you release the left mouse button, the control zooms in on the defined area.
- To rapidly magnify or reduce any area, rotate the mouse wheel backwards or forwards.

4.9 Error messages

Display of errors

The control displays error messages in the following cases, for example:

Incorrect data input

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- Logical errors in the NC program
- Contour elements that are impossible to machine
- Incorrect use of touch probes

When an error occurs, the control displays it in red type in the header.

The control uses different colors for different error classes:

- red for errors
- yellow for warnings
- green for notes
- blue for information

Long and multi-line error messages are displayed in abbreviated form. Complete information on all pending errors is shown in the error window.

The control displays an error message in the header until it is cleared or replaced by a higher-priority error (higher error class). Information that appears only briefly is always displayed.

An error message that contains an NC block number was caused by an error in the indicated NC block or in the preceding NC block.

If a rare **processor check error** should occur, the control automatically opens the error window. You cannot correct such an error. Shut down the system and restart the control.

Opening the error window



Press the ERR key

The control opens the error window and displays all accumulated error messages.

Closing the error window



ERR

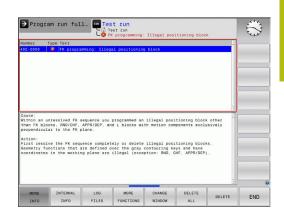
Press the END soft key; or

Press the ERR key The control closes the error window.

Detailed error messages

The control displays possible causes of the error and suggestions for solving the problem:

- Open the error window
- MORE INFO
- Information on the error cause and corrective action: Position the cursor on the error message and press the MORE INFO soft key The control opens a window with information on
 - the error cause and corrective action.
- ▶ Leave Info: Press the **MORE INFO** soft key again



INTERNAL INFO soft key

The **INTERNAL INFO** soft key supplies information on the error message. This information is only required if servicing is needed.

Open the error window



- Detailed information about the error message: Position the cursor on the error message and press the INTERNAL INFO soft key The control opens a window with internal information about the error.
- To exit Details, press the INTERNAL INFO soft key again

FILTER soft key

The **FILTER** soft key enables you to filter identical warnings listed immediately in succession.

Open the error window



Press the MORE FUNCTIONS soft key

- FILTER OFF ON
- Press the FILTER soft key The control filters the identical warnings



Leave Filter: Press the GO BACK soft key

Clearing errors

Clearing errors outside of the error window



 Clear the errors/messages in the header: Press the CE key



In certain situations you cannot use the **CE** key for clearing the errors because the key is used for other functions.

Clearing errors

• Open the error window



 Clear individual errors: Position the cursor on the error message and press the **DELETE** soft key.

DELETE	
ALL	

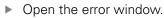
 Clear all error messages: Press the DELETE ALL soft key.

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If the cause of the error has not been corrected, the error message cannot be cleared. In this case, the error message remains in the window.

Error log

The control stores errors occurred and important events (e.g. system start) in an error log. The capacity of the error log is limited. If the log is full, the control uses a second file. If this is also full, the first error log is deleted and newly written etc. If required, switch from **CURRENT FILE** to **PREVIOUS FILE** to view the history.





- Press the LOG FILES soft key
- Open the error log file: Press the ERROR LOG soft key
- Set the previous error log if required: Press the PREVIOUS FILE soft key
- Set the current error log if required: Press the CURRENT FILE soft key

The oldest entry is at the beginning of the log file, and the most recent entry is at the end.

Keystroke log

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The control stores each key pressed and important events (e.g. system start) in a keystroke log. The capacity of the keystroke log is limited. If the keystroke log is full, the control switches to a second keystroke log. If this is also full, the first keystroke log is deleted and newly written etc. If required, switch from CURRENT FILE to **PREVIOUS FILE** to view the history of the inputs.

LOG FILES	Press the LOG FILES soft key
YSTROKE	 Open the keystroke log file: Press the
LOG	KEYSTROKE LOG soft key
REVIOUS	 Set the previous keystroke log if required: Press the PREVIOUS FILE soft key
URRENT	 Set the current keystroke log if required: Press
FILE	the CURRENT FILE soft key

The control saves each key pressed during operation in a keystroke log. The oldest entry is at the beginning, and the most recent entry is at the end of the file.

Overview of the keys and soft keys for viewing the log

Soft key/Keys	Function
BEGIN	Go to beginning of keystroke log
	Go to end of keystroke log
FIND	Find text
CURRENT	Current keystroke log
PREVIOUS FILE	Previous keystroke log
	Up/down one line
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Return to main menu

Informational texts

If an operating error occurred, e.g. pressing an impermissible key or entering a value outside of a validity range, the control displays an information text in the header to inform you of the operating error. The control deletes this information text with the next valid entry.

Saving service files

If necessary, you can save the current status of the control and make it available to a service technician for evaluation. A group of service files is saved (error and keystroke logs as well as other files that contain information about the current status of the machine and the machining).

If you repeat the **SAVE SERVICE FILES** function with the same file name, the previously saved group of service files is overwritten. Therefore, use another file name when executing the function another time.

Saving service files

Open the error window



FILES

OK

Press the LOG FILES soft key

- Press the SAVE SERVICE FILES soft key The control opens a pop-up window in which you can enter a file name or a complete path for the service file.
- Save the service files: Press the **OK** soft key

Calling the TNCguide help system

You can call the control's help system via soft key. Immediately the help system shows you the same error explanation that you receive by pressing the **HELP** soft key.



Refer to your machine manual. If your machine manufacturer also provides a help system, the control shows an additional **Machine manufacturer (OEM)** soft key with which you can call this separate help system. There you will find further, more detailed information on the error message concerned.



▶ Call the help for HEIDENHAIN error messages



 Call the help for HEIDENHAIN machine-specific error messages, if available

4.10 TNCguide context-sensitive help system

Application

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Before you can use the TNCguide, you need to download the help files from the HEIDENHAIN home page

Further information: "Downloading current help files", page 200

The **TNCguide** context-sensitive help system contains the user documentation in HTML format. The TNCguide is called with the **HELP** key, and the control often immediately displays the information specific to the condition from which the help was called (context-sensitive call). Even if you are editing an NC block and press the **HELP** key, you are usually brought to the exact place in the documentation that describes the corresponding function.



The control tries to start the TNCguide in the language that you have selected as the conversational language. If the required language version is not available, the control automatically opens the English version.

The following user documentation is available in TNCguide:

- Conversational Programming User's Manual (BHBKlartext.chm)
- ISO User's Manual (BHBIso.chm)
- Cycle Programming User's Manual (BHBtchprobe.chm)
- List of All Error Messages (errors.chm)

In addition, the **main.chm** "book" file is available, with the contents of all existing .chm files.



As an option, your machine tool builder can embed machine-specific documentation in the **TNCguide**. These documents then appear as a separate book in the **main.chm** file.

Contents Index Find	Switch-on
Controls of the TNC Fundamentals Contents	Switch-on and crossing over the reference points can vary depending on the machine tool. Refer to your machine manual.
First Steps with the TNC 320 Introduction	Switch on the power supply for TNC and machine. The TNC then displays the following dialog: SYSTEM STARTUP
Programming: Fundamenta	TNC is started
Programming: Programmin	POWER INTERRUPTED
Programming: Tools	CE - TNC message that the power was interruptedclear the message
Programming: Programmin	COMPLEE A PLC PROGRAM
Programming: Data transfe	The PLC program of the TNC is automatically comolied
Programming: Subprogram	RELAY EXT, DC VOLTAGE MISSING
Programming: Q Parameters	
Programming: Miscellaneo	Switch on external dc voltage. The TNC checks the functioning of the EMERGENCY STOP circuit
Programming: Special func	MANUAL OPERATION
Programming: Multiple Axis	TRAVERSE REFERENCE POINTS
 Manual operation and setup 	Coss the reference points manually in the displayed sequence: For each axis press the machine START button, or
 Switch-on, switch-off 	machine Street auton, or
Switch-on Switch-off	Cross the reference points in any sequence. Press and hold the machine axis direction button for each axis until the reference point has been traversed
Moving the machine axes	. (Y)
BACK	PAGE PAGE DIRECTORY WINDOW SWITCH

Working with TNCguide

Calling TNCguide

There are several ways to start the TNCguide:

- Press the HELP key.
- Click the help symbol at the lower right of the screen beforehand, then click the appropriate soft keys
- Open a help file (CHM file) via the file management. The control can open any .chm file, even if it is not saved in the control's internal memory



On the Windows programming station, the TNCguide is opened in the internally defined standard browser.

For many soft keys there is a context-sensitive call through which you can go directly to the description of the soft key's function. This functionality requires using a mouse. Proceed as follows:

- Select the soft-key row containing the desired soft key
- Click with the mouse on the help symbol that the control displays just above the soft-key row

The mouse pointer turns into a question mark.

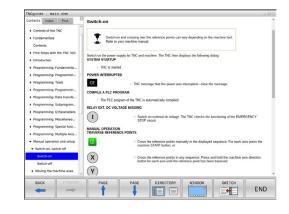
 Move the question mark to the soft key for which you want an explanation

The control opens the TNCguide. If there is no entry point for the selected soft key, then the control opens the book file **main.chm**. You can search for the desired explanation using full text search or by using the navigation.

Even if you are editing an NC block, context-sensitive help is available:

- Select any NC block
- Select the desired word
- ▶ Press the **HELP** key.

The control opens the Help system and shows the description of the active function. This does not apply for miscellaneous functions or cycles from your machine manufacturer.



Navigating in the TNCguide

It's easiest to use the mouse to navigate in TNCguide. A table of contents appears on the left side of the screen. By clicking the rightward pointing triangle you open subordinate sections, and by clicking the respective entry you open the individual pages. It is operated in the same manner as the Windows Explorer.

Linked text positions (cross references) are shown underlined and in blue. Clicking the link opens the associated page.

Of course you can also operate TNCguide through keys and soft keys. The following table contains an overview of the corresponding key functions.

Soft key	Function
t	 If the table of contents at left is active: Select the entry above it or below it
+	 If the text window at right is active: Move the page downward or upward if texts or graphics are not shown completely
→	If the table of contents at left is active: Open up the table of contents
	 If the text window at right is active: No function
+	If the table of contents at left is active: Close the table of contents
	 If the text window at right is active: No function
ENT	If the table of contents at left is active: Use the cursor key to show the selected page
	If the text window at right is active: If the cursor is on a link, jump to the linked page
	 If the table of contents at left is active: Switch the tab between the display of the table of contents, display of the subject index, and the full-text search function and switching to the screen half at right If the text window at right is active: Jump
	back to the window at leftIf the table of contents at left is active:
	Select the entry above it or below itIf the text window at right is active: Jump to next link
BACK	Select the page last shown
	Page forward if you have used the Select page last shown function
	Move up by one page
PAGE	Move down by one page

Soft key	Function
DIRECTORY	Display or hide table of contents
WINDOW	Switch between full-screen display and reduced display. With the reduced display you can see some of the rest of the control window
SUITCH	The focus is switched internally to the control application so that you can operate the control when the TNCguide is open. If the full screen is active, the control reduces the window size automatically before the change of focus



Exit TNCguide

Subject index

The most important subjects in the Manual are listed in the subject index (**Index** tab). You can select them directly by mouse or with the arrow keys.

The left side is active.



Select the Index tab

 Use the arrow keys or the mouse to select the desired keyword

Alternative:

Enter the first few characters

The control synchronizes the subject index and creates a list in which you can find the subject more easily.

 Use the ENT key to call the information on the selected keyword

ontents Index Find	Switch-on
Controls of the TNC Fundamentals Contents	Switch-on and crossing over the reference points can vary depending on the machine tool. Refer to your machine manual.
First Steps with the TNC 320 Introduction	Switch on the power supply for TNC and machine. The TNC then displays the following dialog: SYSTEM STARTUP
Programming: Fundamenta	TNC is started
Programming: Programmin	POWER INTERRUPTED
Programming: Tools	CE > TNC message that the power was interrupted—clear the message
Programming: Programmin	COMPLEE A PLC PROGRAM
Programming: Data transfe	The PLC program of the TNC is automatically comoiled
Programming: Subprogram	RELAY EXT. DC VOLTAGE MISSING
Programming: Q Parameters	
Programming: Miscellaneo	Switch on external dc voltage. The TNC checks the functioning of the EMERGENCY STOP circuit
Programming: Special func Programming: Multiple Axis	MANUAL OPERATION TRAVERSE REFERENCE POINTS
Manual operation and setup Switch-on, switch-off	Cosss the reference points manually in the displayed sequence: For each axis press the machine START button, or
Switch-on Switch-off	Cross the reference points in any sequence: Press and hold the machine axis direction button for each axis until the reference point has been traversed
 Moving the machine axes 	. (Y)
BACK	

Full-text search

In the **Find** tab you can search all of TNCguide for a specific word. The left side is active.



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- Select the Find tab
- Activate the Find: entry field
- Enter the search word
- Press the ENT key

The control lists all sources containing the word.

- Use the arrow keys to navigate to the desired source
- Press the ENT key to go to the selected source

The full-text search only works for single words. If you activate the **Search only in titles** function, the control searches only through headings and ignores the body text. To activate the function, use the mouse or select it and then press the space bar to confirm.

Downloading current help files

You'll find the help files for your control software on the HEIDENHAIN homepage: http://content.heidenhain.de/doku/tnc_guide/html/en/index.html

Navigate to the suitable help file as follows:

- TNC Controls
- ▶ Series, e.g. TNC 300
- Desired NC software number, e.g. TNC 320 (77185x-04)
- Select the desired language version from the TNCguide online help table
- Download the ZIP file
- Extract the ZIP file
- Move the extracted CHM files to the TNC:\tncguide\en directory or the respective language subdirectory on the control



When using TNCremo to transfer the .chm files to the control, select the binary mode for files with the **.chm** extension.

Language	TNC directory
German	TNC:\tncguide\de
English	TNC:\tncguide\en
Czech	TNC:\tncguide\cs
French	TNC:\tncguide\fr
Italian	TNC:\tncguide\it
Spanish	TNC:\tncguide\es
Portuguese	TNC:\tncguide\pt
Swedish	TNC:\tncguide\sv
Danish	TNC:\tncguide\da
Finnish	TNC:\tncguide\fi
Dutch	TNC:\tncguide\nl
Polish	TNC:\tncguide\pl
Hungarian	TNC:\tncguide\hu
Russian	TNC:\tncguide\ru
Chinese (simplified)	TNC:\tncguide\zh
Chinese (traditional)	TNC:\tncguide\zh-tw
Slovenian	TNC:\tncguide\sl
Norwegian	TNC:\tncguide\no
Slovak	TNC:\tncguide\sk
Korean	TNC:\tncguide\kr
Turkish	TNC:\tncguide\tr
Romanian	TNC:\tncguide\ro

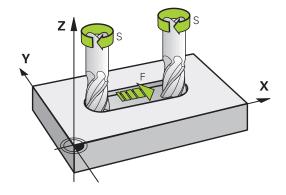


Tools

5.1 Entering tool-related data

Feed rate F

The feed rate \mathbf{F} is the speed at which the tool center point moves. The maximum feed rates can be different for the individual axes and are set in machine parameters.



Input

You can enter the feed rate in the ${\bf T}$ block and in every positioning block.

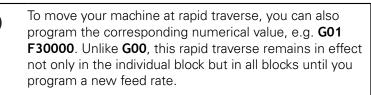
Further information: "Programming tool movements in DIN/ISO", page 133

You enter the feed rate **F** in mm/min in millimeter programs, and in 1/10 inch/min in inch-programs, for resolution reasons.

Rapid traverse

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If you wish to program rapid traverse, enter G00.



Duration of effect

A feed rate entered as a numerical value remains in effect until a block with a different feed rate is reached. **G00** is only effective in the block in which it is programmed. After the block with **G00** is executed, the feed rate will return to the last feed rate entered as a numerical value.

Changing during program run

You can adjust the feed rate during the program run with the feed rate potentiometer $\ensuremath{\mathsf{F}}$

The feed rate potentiometer lowers the programmed feed rate, not the feed rate calculated by the control.

Spindle speed S

The spindle speed S is entered in revolutions per minute (rpm) in a T block (tool call). Instead, you can also define the cutting speed Vc in meters per minute (m/min).

Programmed change

In the NC program, you can change the spindle speed in a **T** block by entering the spindle speed only:



► To program the spindle speed, press the **S** key on the alphabetic keyboard.

Enter the new spindle speed



If the number of the already inserted tool is entered in the ${\bf T}$ block without specifying the tool axis, then only the spindle speed will change.

If the tool axis is also entered in the **T** block, the control will insert a replacement tool if a replacement tool was defined.

Changing during program run

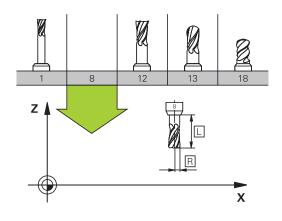
You can adjust the spindle speed during program run with the spindle speed potentiometer S.

5.2 Tool data

Requirements for tool compensation

You usually program the coordinates of path contours as they are dimensioned in the workpiece drawing. To allow the control to calculate the tool center path (i.e. the tool compensation) you must also enter the length and radius of each tool you are using.

Tool data can be entered either directly in the part program with **G99** or separately in a tool table. In a tool table, you can also enter additional data for the specific tool. The control will consider all the data entered for the tool when executing the part program.



Tool number, tool name

Each tool is identified by a number between 0 and 32767. If you are working with tool tables, you can also enter a tool name for each tool. Tool names can have up to 32 characters.

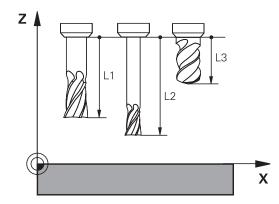
Permitted special characters: #\$ % & , - _ . 0 1 2 3 4 5 6 7 8 9 @ A B C D E F G H I J K L M N O P Q R S T U V W X Y Z The control automatically replaces lowercase letters with corresponding uppercase letters during saving. Impermissible characters: <blank space> !" '() * + :;

< = > ? [/] ^ ` { | } ~

The tool number 0 is automatically defined as the zero tool with the length L=0 and the radius R=0. In tool tables, tool T0 should also be defined with L=0 and R=0.

Tool length L

You should always enter the tool length L as an absolute value based on the tool reference point. The entire tool length is essential for the control in order to perform numerous functions involving multi-axis machining.



Tool radius R

You can enter the tool radius R directly.

Delta values for lengths and radii

Delta values are offsets in the length and radius of a tool.

A positive delta value describes a tool oversize (**DL**, **DR**>0). If you are programming the machining data with an allowance, enter the oversize value in the **T**.

A negative delta value describes a tool undersize (**DL**, **DR**<0). An undersize is entered in the tool table for wear.

Delta values are usually entered as numerical values. In a ${\bf T}$ block, you can also assign the values to Q parameters.

Input range: You can enter a delta value with up to \pm 99.999 mm.

Delta values from the tool table influence the graphical representation of the clearing simulation. Delta values from the **T** block do not change the

represented size of the **tool** during the simulation. However, the programmed delta values move the **tool** by the defined value in the simulation.



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Delta values from the **T** block influence the position display depending on the optional machine parameter **progToolCallDL** (no. 124501).

Entering tool data into the NC program

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Refer to your machine manual.

The machine tool builder determines the scope of functions of the **G99** function.

The number, length and radius of a specific tool is defined in the **G99** block of the part program:

Select the tool definition: Press the TOOL DEF key

- Tool number: Each tool is uniquely identified by its tool number
- Tool length: Compensation value for the tool length
- Tool radius: Compensation value for the tool radius

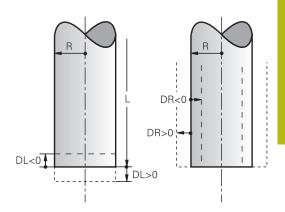


TOOL DEF

> In the programming dialog, you can transfer the value for tool length and tool radius directly into the input line by pressing the desired axis soft key.

Example

N40 G99 T5 L+10 R+5*



Entering tool data into the table

You can define and store up to 32 767 tools and their tool data in a tool table. Also see the editing functions later in this chapter.

You must use tool tables if:

- you wish to use indexed tools such as stepped drills with more than one length compensation value
 Further information: "Indexed tool", page 209
- your machine tool has an automatic tool changer
- you want to work with the machining cycle G122,
 Further information: Cycle Programming User's Manual
- you want to work with machining cycles 251 to 254,
 Further information: Cycle Programming User's Manual

NOTICE

Caution: Data may be lost!

Deleting line 0 from the tool table will destroy the structure of the table. As a result, locked tools might no longer be recognized as locked and, consequently, the search for a replacement tool will not work, either. The problem cannot be solved by reinserting a line 0. The original tool table will be permanently damaged!

- Restore the tool table
 - Add a new line 0 to the defective tool table
 - Copy the defective tool table (e.g. toolcopy.t)
 - Delete the defective tool table (current tool.t)
 - Copy the copied tool table (toolcopy.t) as tool.t
 - Delete the copied tool table (toolcopy.t)
- Contact HEIDENHAIN Service (NC helpline)
 - All table names must start with a letter. Please keep this in mind when creating and managing additional tables. You can select the table view with the **Screen Layout**

key. You can choose between a list view and a form view.

Other settings, such as **HIDE/ SORT/ COLUMNS**, can be made after the file is open.

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Indexed tool

Step drills, T-slot milling cutters, side milling cutters and, in generally, all tools that require the input of multiple length and radius data cannot be fully defined in a single line of the tool table. Each line of the table permits the definition of one length and one radius.

In order to assign multiple compensation data to a tool (multiple tool table lines), add an indexed tool number (such as T 5.1) to an existing tool definition (T 5). Each additional line of the table thus comprises the original tool number, a period and an index (in ascending order from 1 to 9). The original tool table line contains the maximum tool length; the tool lengths in the subsequent table lines are given in descending order of their distance to the tool holder point.

Proceed as follows to create an indexed tool number (table line):

- INSERT LINE
- Open the tool table
- Press the Insert Line soft key The control opens the Insert Line pop-up window
- In the Number of new lines = input field, enter the number of lines to add
- Enter the original tool number into the Tool number input field
- ► Confirm with **OK**

The control adds the additional lines to the tool table

5

Quick search for the tool name:

If the $\ensuremath{\textbf{EDIT}}$ soft key is set to $\ensuremath{\textbf{OFF}}$, you can search for a tool name. Proceed as follows:

- Enter the first few characters of the tool name, e.g. MI The control shows a dialog box with the entered text and jumps to the first match.
- Enter additional characters to narrow down the search result, e.g. MILL
- If the control cannot find any more matches for the entered search string, you can press the last entered character (e.g. L) to jump between matches, as with the arrow keys.

The quick search can also be used for tool selection in the **TOOL CALL** block.

Abbr. Inputs Dialog т Number by which the tool is called in the program (e.g. 5, indexed: 5.2) NAME Name by which the tool is called in the program (max. Tool name? 32 characters, all capitals, no spaces) L Tool length? Tool length L R Tool radius R Tool radius? **R2** Tool radius R2 for toroid cutters (only for 3-D radius Tool radius 2? compensation or graphical representation of a machining operation with spherical or toroid cutters) DL Tool length oversize? Delta value for tool length L DR Delta value for tool radius R Tool radius oversize? DR2 Delta value for tool radius R2 Tool radius oversize 2? TL Set tool lock (TL for Tool Locked Tool locked? Yes=ENT/ No=NOENT RT Number of a replacement tool - if available - as replace-**Replacement tool?** ment tool (RT: for Replacement Tool) An empty field or input **0** means no replacement tool has been defined. TIME1 Maximum tool life in minutes. This function can vary Maximum tool age? depending on the individual machine tool. Your machine manual provides more information TIME2 Maximum tool life in minutes during a tool call: If the Max. tool age for TOOL CALL? current tool age reaches or exceeds this value, the control inserts the replacement tool during the next T block (if the tool axis is specified) CUR_TIME Current age of the tool in minutes: The control automati-Current tool age? cally counts the current tool life (CUR_TIME: For CURrent TIME) A starting value can be entered for used tools

Tool table: Standard tool data

Abbr.	Inputs	Dialog
ТҮРЕ	Tool type: Press the ENT key to edit the field. The GOTO key opens a window for selecting the tool type (in the tool management, press the SELECT soft key to open a pop-up window). You can assign tool types to specify the display filter settings such that only the selected type is visible in the table	Tool type?
DOC	Comment on tool (max. 32 characters)	Tool description
PLC	Information on this tool that is to be sent to the PLC	PLC status?
LCUTS	Tooth length of the tool for Cycles 22, 233, 256, 257	Tooth length in the tool axis?
ANGLE	Maximum plunge angle of the tool for reciprocating plunge-cut in Cycles 22 and 208	Maximum plunge angle?
NMAX	Limit the spindle speed for this tool. The programmed value is monitored (error message) as well as an increase in the shaft speed via the potentiometer. Function inactive: Enter	Maximum speed [rpm]
	Input range: 0 to +999 999 if function not active: enter -	
LIFTOFF	Definition of whether the control should retract the tool in the direction of the positive tool axis at an NC stop in order to avoid leaving dwell marks on the contour. If Y is defined, the control retracts the tool from the contour, provided M148 has been activated.	Retract allowed? Yes=ENT/ No=NOENT
	Further information: "Automatically retracting the tool from the contour at an NC stop: M148", page 445	
TP_NO	Reference to the number of the touch probe in the touch- probe table	Number of the touch probe
T-ANGLE	Point angle of the tool. Is used by the Centering cycle (Cycle 240) in order to calculate the centering depth from the diameter entry	Point angle
РІТСН	Thread pitch of the tool. Used by tapping cycles (Cycle 206, Cycle 207 and Cycle 209). A positive algebraic sign means a right-hand thread.	Tool thread pitch?
LAST_USE	Date and time that the tool was last inserted via T block	Date/time of last tool call
PTYP	Tool type for evaluation in the pocket table	Tool type for pocket table?
	Function is defined by the machine manufacturer. Refer to your machine manual.	
KINEMATIC	Press the SELECT soft key to display the tool carrier kinematics (in the tool management, press the SELECT soft key) and press the OK soft key to confirm the file name and path. Further information: "Allocating parameterized tool carri- ers", page 455	Tool-carrier kinematics
OVRTIME	Time for exceeding the tool life in minutes	Tool life expired
	Further information: "Overtime for tool life", page 226	
	Function is defined by the machine manufacturer. Refer to your machine manual.	

Tool table: Tool data required for automatic tool measurement

Refer to your machine manual. \bigcirc The machine tool builder defines whether the R-OFFS

offset will be taken into account for a tool with CUT 0.

Abbr.	Inputs	Dialog
CUT	Number of teeth (99 teeth maximum)	Number of teeth?
LTOL	Permissible deviation from tool length L for wear detec- tion. If the entered value is exceeded, the control locks the tool (status L). Input range: 0 to 0.9999 mm	Wear tolerance: length?
RTOL	Permissible deviation from tool radius R for wear detec- tion. If the entered value is exceeded, the control locks the tool (status L). Input range: 0 to 0.9999 mm	Wear tolerance: radius?
R2TOL	Permissible deviation from tool radius R2 for wear detec- tion. If the entered value is exceeded, the control locks the tool (status L). Input range: 0 to 0.9999 mm	Wear tolerance: Radius 2?
DIRECT	Cutting direction of the tool for measuring the tool during rotation	Cutting direction? M4=ENT/ M3=NOENT
R-OFFS	Tool length measurement: Tool offset between stylus center and tool center. Default setting: No value entered (offset = tool radius)	Tool offset: radius?
L-OFFS	Tool radius measurement: tool offset in addition to offsetToolAxis between upper surface of stylus and lower surface of tool. Default: 0	Tool offset: length?
LBREAK	Permissible deviation from tool length L for breakage detection. If the entered value is exceeded, the control locks the tool (status L). Input range: 0 to 3.2767 mm	Breakage tolerance: length?
RBREAK	Permissible deviation from tool radius R for breakage detection. If the entered value is exceeded, the control locks the tool (status L). Input range: 0 to 0.9999 mm	Breakage tolerance: radius?
	For a description of the cycles governing automatic tool measurement,	
	Further information: Cycle Programming User's Manual	

Editing the tool table

The tool table that is active during execution of the part program is designated TOOL.T and must be saved in the **TNC:\table** directory. Other tool tables that are to be archived or used for test runs are given different file names with the extension .T. By default, for the **Test Run** and **Programming** modes the control also uses the TOOL.T tool table. In the **Test Run** mode, press the **TOOL TABLE** soft key to edit it.

To open the tool table TOOL.T:

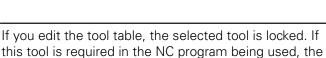
Select any machine operating mode



OFF ON

A

 Select the tool table: Press the TOOL TABLE soft key



Set the EDIT soft key to ON

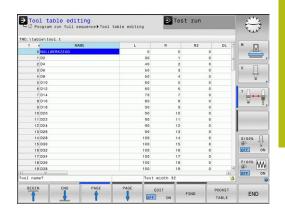
control shows the message: **Tool table locked**.

If a new tool is created, the length and radius columns remain empty until entered manually. An attempt to insert such a newly created tool will be aborted by the control and an error message will appear. This means you cannot insert a tool for which no geometry data are available yet.

Proceed as follows to use the keyboard or a connected mouse for navigation and editing:

- Arrow keys: move from one cell to the next
- ENT key: jump to the next cell; with selection fields: open the selection dialog
- Mouse click on a cell: move to the cell
- Double click on a cell: place the cursor in the cell; with selection fields: open the selection dialog

Soft key	Editing functions of the tool table
BEGIN	Select the table start
END	Select the table end
	Select the previous page in the table
	Select the next page in the table
FIND	Find the text or number
BEGIN LINE	Go to beginning of line



Soft key	Editing functions of the tool table
	Go to end of line
COPY FIELD	Copy active field
PASTE	Insert copied field
APPEND N LINES	Add the entered number of lines (tools) at the end of the table
INSERT LINE	Insert a line with definable tool number
DELETE	Delete the current line (tool)
SORT	Sort the tools according to the content of a column
SELECT	Select possible entries from a pop-up window
RESET COLUMN	Reset the value
EDIT CURRENT FIELD	Place the cursor in the current cell

Displaying only specific tool types (filter setting)

- Press the TABLE FILTER soft key
- Select the desired tool type by soft key
 The control displays only tools of the selected type.
- Cancel the filter: Press the SHOW ALL soft key

Refer to your machine manual.
 The machine tool builder adapts the features of the filter function to the requirements of your machine.

Soft key	Filter functions of the tool table
TABLE FILTER	Select the filter function
SHOW ALL	Cancel the filter settings and show all tools
DEFAULT FILTER	Use the default filter
DRILL	Show all drills in the tool table
	Show all cutters in the tool table
THREADTOOL	Show all taps/thread cutters in the tool table
TCH. PROBE	Show all touch probes in the tool table

Hiding or sorting the tool table columns

You can adapt the layout of the tool table to your needs. Columns that are not to be displayed can be simply hidden:

- Press the HIDE/ SORT/ COLUMNS soft key
- Select the appropriate column name with the arrow key
- Press the HIDE COLUMN soft key to remove this column from the table view

You can also modify the sequence of columns in the table:

You can also modify the sequence of columns in the table with the Move before: dialog. The entry highlighted in Displayed columns: is moved in front of this column

Use a connected mouse or the control's keyboard to navigate in the form. Navigation using the control's keyboard:



PGM MGT

- Press the navigation keys to go to the input fields.
- Use the arrow keys to navigate within an input field.
- ► To open pop-down menus, press the **GOTO** key.

The function **freeze number of columns** enables you to determine how many columns (0-3) the control will freeze to the left border of the screen. These columns will remain visible when you navigate to the right within the table.

Opening any other tool table

Select the **Programming** operating mode

- To call the file manager, press the PGM MGT key
- Select a file or enter a new file name. Confirm your entry with the ENT key or the SELECT soft key

When you have opened the tool table, you can edit the tool data by moving the cursor to the desired position in the table with the arrow keys or the soft keys. You can overwrite the stored values, or enter new values at any position.

Further information: "Editing the tool table", page 213

Exiting any other tool table

 Call the file manager and select a file of a different type, such as an NC program

Importing tool tables



Refer to your machine manual.

The machine tool builder can adapt the **ADAPT NC PGM / TABLE** function.

The machine tool builder can define update rules that make it possible, for example, to automatically remove umlauts from tables and NC programs. If you export a tool table from an iTNC 530 and import it into a TNC 320, you have to adapt its format and content before you can use the tool table. On the TNC 320, you can adapt the tool table conveniently with the **ADAPT NC PGM / TABLE** function. The control converts the contents of the imported tool table to a format valid for the TNC 320 and saves the changes to the selected file.

Follow this procedure:

 Save the tool table of the iTNC 530 to the TNC:\table directory



Select the **Programming** operating mode



Press the PGM MGT key

import

t t

MORE FUNCTIONS

NC PGM TABLE

- Press the MORE FUNCTIONS soft key
- Press the ADAPT NC PGM / TABLE soft key The control asks you whether you want to overwrite the selected tool table.

Move the cursor to the tool table you want to

- Press the CANCEL soft key
- Alternative: Press the **OK** soft key to overwrite
- Open the converted table and check its contents
 New columns in the tool table are highlighted green
- Press the **REMOVE UPDATE INFORMATION** soft key The green columns are displayed in white again

The following characters are permitted in the Name i column of the tool table: # \$ % & , - . 0 1 2 3 4 5 6 7 8 9 @ A B C D E F G H I J K L M N O P Q R S T U V W X Y Z During the import, a comma is converted to a period. The control overwrites the active tool table when importing an external table with the same name. To prevent data loss, back up the original tool table before you start the import! The procedure for copying tool tables using the file manager is described in the section on file management. Further information: "Copying a table", page 152 When iTNC 530 tool tables are imported, all defined tool types are transferred as well. Tool types not present are imported as type **Undefined**. Check the tool table after the import.

Overwriting tool data from an external PC

Application

The HEIDENHAIN data transfer software TNCremo provides an especially convenient way to use an external PC to overwrite tool data.

Further information: "Software for data transfer", page 641

This application case occurs if you wish to determine tool data on an external tool presetter and then transfer this to the control.

Requirements

In addition to option 18 HEIDENHAIN DNC, TNCremo (from version 3.1) is required with TNCremoPlus functions.

Procedure

i

- Copy the TOOL.T tool table to the control, for example to TST.T
- Start the data transfer software TNCremo on the PC
- Connect to the control
- Transfer the copied tool table TST.T to the PC
- Use any text editor to reduce TST.T to the lines and columns to be changed (see figure). Make sure that the header is not changed and the data is always flush in the column. The tool number (column T) need not be consecutive
- In TNCremo, select the menu item <Extras> and <TNCcmd>: This starts TNCcmd.
- To transfer the TST.T file to the control, enter the following command and confirm with the return key (see figure): put tst.t tool.t /m

During transfer, only the tool data defined in the subfile (e.g. TST.T) is overwritten. All other tool data of the table TOOL.T remains unchanged.

The procedure for copying tool tables using the file manager is described in the file management.

Further information: "Copying a table", page 152

BEGIN	TST	.T MM		
Т	NAME		L	R
1			+12.5	+9
3			+23.15	+3.5
[END]				
TNCcmdPlu		mmand Line Clien 9(340594) (192.1	t for HEIDENHAIN Contr 68.56.101)	rols - Version: 5.92
TNCcmdPlu Connectin	s - WIN32 Co g with TNC64	0(340594) (192.1		rols - Version: 5.92
TNCcmdPlu Connectin Connectio	s - WIN32 Co g with TNC64 n establishe	0(340594) (192.1	68.56.101)	rols - Version: 5.92

Pocket table for tool changer

 \bigcirc

Refer to your machine manual.

The machine tool builder adapts the features of the pocket table to the requirements of your machine.

For automatic tool changing you need the a pocket table. You manage the assignment of your tool changer in the pocket table. The pocket table is in the **TNC:\table** directory. The machine manufacturer can amend the name, path and content of the pocket table. If you wish, you can select different views using the soft keys in the **TABLE FILTER** menu.

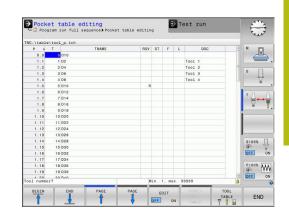
Editing a pocket table in a Program Run operating mode



- Select the tool table: Press the TOOL TABLE soft key
- POCKET TABLE EDIT

OFF ON

- Press the POCKET TABLE soft key
- Set the EDIT soft key to ON. On your machine this might not be necessary or even possible. Refer to your machine manual



Selecting a pocket table in Programming mode

Proceed as follows to select the pocket table in the Programming mode of operation:



- ► To call the file manager, press the **PGM MGT** key.
- Press the SHOW ALL soft key
- Select a file or enter a new file name
- Confirm your entry with the ENT key or the SELECT soft key

Abbr.	Inputs	Dialog
P	Pocket number of the tool in the tool magazine	-
Т	Tool number	Tool number?
RSV	Pocket reservation for box magazines	Pocket reserv.: Yes = ENT / No = NOENT
ST	Special tool (ST); If your special tool blocks pockets in front of and behind its actual pocket, these additional pockets need to be locked in column L (status L).	Special tool?
F	The tool is always returned to the same pocket in the tool magazine	Fixed pocket? Yes = ENT / No = NO ENT
L Locked pocket (L: for Locked)		Pocket locked Yes = ENT / No = NO ENT
DOC	Display of the comment to the tool from TOOL.T	-
PLC	Information on this tool pocket that is to be sent to the PLC	PLC status?
P1 P5	Function is defined by the machine tool builder. The machine tool documentation provides further information	Value?
РТҮР	Tool type. Function is defined by the machine tool builder. The machine tool documentation provides further information	Tool type for pocket table?
LOCKED_ABOVE	Box magazine: Lock the pocket above	Lock the pocket above?
LOCKED_BELOW	_OCKED_BELOW Box magazine: Lock the pocket below	
LOCKED_LEFT	Box magazine: Lock the pocket at left	Lock the pocket at left?
LOCKED_RIGHT	Box magazine: Lock the pocket at right	Lock the pocket at right?

5

Soft key	Editing functions for pocket tables
	Select the table start
END	Select the table end
PAGE	Select the previous page in the table
PAGE	Select the next page in the table
RESET POCKET	Reset pocket table
TABLE	Depends on optional machine parameter enableReset (no.106102)
RESET COLUMN	Reset tool number T column
т	Depends on machine parameter showResetColumnT (no.)
BEGIN LINE	Go to beginning of line
END LINE	Go to end of line
SIMULATED TOOL CHANGE	Simulate a tool change
SELECT	Select a tool from the tool table: The control shows the contents of the tool table. Use the arrow keys to select a tool, press OK to transfer it to the pocket table
RESET COLUMN	Reset the value
EDIT CURRENT FIELD	Place the cursor in the current cell
SORT	Sort the view
0	Refer to your machine manual. The machine manufacturer defines the features, properties and designations of the various display filters.

Calling the tool data

Before you can call the tool, you have to define it in a **G99** block or in the tool table.

A T in the NC program is programmed with the following data:



Press the TOOL CALL key

► **Tool number**: Enter the number or name of the tool. With the **TOOL NAME** soft key you can enter a name. With the **QS** soft key you enter a string parameter. The control automatically places the tool name in quotation marks. You have to assign a tool name to a string parameter first. Names always refer to an entry in the active tool table TOOL .T.



- Alternative: Press the SELECT soft key The control opens a window where you can select a tool directly from the TOOL.T tool table.
- To call a tool with other compensation values, enter a decimal point followed by the index you defined in the tool table.
- Working spindle axis X/Y/Z: Enter the tool axis
- Spindle speed S: Enter the spindle speed S in revolutions per minute (rpm) Alternatively, you can define the cutting speed Vc in meters per minute (m/min). Press the VC soft key
- Feed rate F: Enter feed rate F in millimeters per minute (mm/min). The feed rate is effective until you program a new feed rate in a positioning block or in a T block
- Tool length oversize DL: Enter the delta value for the tool length
- Tool radius oversize DR: Enter the delta value for the tool radius
- Tool radius oversize DR2: Enter the delta value for the tool radius 2

If the number of the already inserted tool is entered in the T block without specifying the tool axis, then only the spindle speed will change.
 If the tool axis is also entered in the T block, the control will insert a replacement tool if a replacement tool was

defined.

Tool selection in the pop-up window

If you open a pop-up window for tool selection, the control marks all tools available in the tool magazine green.

You can search for a tool in the pop-up window:



ENT

- Press the GOTO key
- Alternative: Press the FIND soft key
- Enter the tool name or tool number
- Press the ENT key The control goes to the first tool that matches the entered search string.

The following functions can be used with a connected mouse:

- You can sort the data in ascending or descending order by clicking a column of the table head.
- You can arrange the columns in any sequence you want by clicking a column of the table head and then moving it with the mouse key pressed down

The pop-up windows displayed for a tool number search and a tool name search can be configured separately. The sort order and the column widths are retained when the control is switched off.

Tool call

Call tool number 5 in the tool axis Z with a spindle speed 2500 rpm and a feed rate of 350 mm/min. The tool length and tool radius 2 are to be programmed with an oversize of 0.2 and 0.05 mm, the tool radius with an undersize of 1 mm.

Example

N20 T 5.2 G17 S2500 DL+0.2 DR-1*

The character **D** preceding **L**, **R** and **R2** designates delta values.

Preselection of tools



Refer to your machine manual. The preselection of tools with **G51** can vary depending

on the individual machine tool.

If you are working with tool tables, use a **G51** block to preselect the next tool. Simply enter the tool number or a corresponding Q parameter, or type the tool name in quotation marks.

Tool change

Automatic tool change



Refer to your machine manual.

The tool change function can vary depending on the individual machine tool.

If your machine tool has automatic tool changing capability, the program run is not interrupted. When the control reaches a tool call with ${\bf T},$ it replaces the inserted tool by another from the tool magazine.

Automatic tool change if the tool life expires: M101



Refer to your machine manual.

The function of **M101** can vary depending on the individual machine tool.

When the specified tool life has expired, the control can automatically insert a replacement tool and continue machining with it. Activate the miscellaneous function **M101** for this. **M101** is reset with **M102**.

Enter the respective tool life after which machining is to be continued with a replacement tool in the **TIME2** column of the tool table. In the **CUR_TIME** column the control enters the current tool life. If the current tool life is higher than the value entered in the **TIME2** column, a replacement tool will be inserted at the next possible point in the program no later than one minute after expiration of the tool life. The change is made only after the NC block has been completed.

The control performs the automatic tool change at a suitable point in the program. The automatic tool change is not performed:

- During execution of machining cycles
- While radius compensation (G41/G42) is active
- Directly after an approach function **APPR**
- Directly before a departure function DEP
- Directly before and after G24 and G25
- During execution of macros
- During execution of a tool change
- Directly after a T block or G99
- During execution of SL cycles

NOTICE

Danger of collision!

During an automatic tool change with **M101**, the control always retracts the tool in the tool axis first. There is danger of collision when retracting tools for machining undercuts, such as side milling cutters or T-slot milling cutters!

Deactivate the tool change with M102

After the tool change the control positions the tool according to the following logic, unless otherwise specified by the machine tool builder:

- If the target position in the tool axis is below the current position, the tool axis is positioned last
- If the target position in the tool axis is above the current position, the tool axis is positioned first

Depending on the NC program, the machining time can increase as a result of the tool life verification and calculation of the automatic tool change. You can influence this with the optional entry element **BT** (block tolerance).

If you enter the **M101** function, the control continues the dialog by requesting **BT**. Here you define the number of NC blocks (1 - 100) by which the automatic tool change may be delayed. The resulting time period by which the tool change is delayed depends on the content of the NC blocks (e.g. feed rate, path). If you do not define **BT**, the control uses the value 1 or, if applicable, a default value defined by the machine manufacturer.

The higher the value of **BT**, the smaller will be the effect of an extended program duration through the **M101** function. Please note that this will delay the automatic tool change!

> Use the formula **BT** = 10: Average machining time of an NC block in seconds to calculate a suitable starting value for **BT**. Round up to the next integer. If the calculated result is greater than 100, use the maximum input value of 100.

> If you want to reset the current age of a tool (e.g. after changing the indexable inserts), enter the value 0 in the CUR_TIME column.

Overtime for tool life



This feature must be enabled and adapted by the machine tool builder.

The tool condition at the end of planned tool life depends on e.g. the tool type, machining method and workpiece material. In the **OVRTIME** column of the tool table, enter the time in minutes for which the tool is permitted to be used beyond the tool life.

The machine manufacturer specifies whether this column is enabled and how it is used during tool search.

Tool usage test

Requirements



Refer to your machine manual. The tool usage test function must be enabled by your machine tool builder.

To conduct a tool usage test, you must activate **Create tool usage files** in the MOD menu.

Further information: "Tool usage file", page 631

Generating a tool usage file

Depending on the setting in the MOD menu, you have the following options for generating the tool usage file:

- Completely simulate the NC program in the Test Run operating mode
- Completely run the NC program in the Program Run, Full Sequence/Single Block operating modes
- In the Test Run operating mode, press the GENERATE TOOL USAGE FILE soft key (also possible without simulation)

The tool usage file generated is in the same directory as the NC program. It contains the following information:

Column	Meaning			
TOKEN	 TOOL: Tool usage time per tool call. The entries are listed in chronological order. 			
	TTOTAL: Total usage time of a tool			
	STOTAL : Call of a subprogram. The			
	entries are listed in chronological order.			
	TIMETOTAL: The total machining time of the NC program is entered in the WTIME column. In the PATH column the control saves the path name of the corresponding NC program. The TIME column shows the sum of all TIME entries (feed time without rapid traverse movements). The control sets all other columns to 0			
	TOOLFILE: In the PATH column, the control saves the path name of the tool table with which you conducted the test run. This enables the control during the actual tool usage test to detect whether you performed the test run with TOOL.T			
TNR	Tool number (-1: Tool not inserted yet)			
IDX	Tool index			
NAME	Tool name from the tool table			
TIME	Tool usage time in seconds (feed time without rapid traverse movements)			
WTIME	Tool-usage time in seconds (total usage time between tool changes)			
RAD	Tool radius R + Oversize of tool radius DR from the tool table. (in mm)			
BLOCK	Block number in which the T block was programmed			
РАТН	 TOKEN = TOOL: Path name of the active main program or subprogram TOKEN = STOTAL: Path name of the 			
	subprogram			
Т	Tool number with tool index			
OVRMAX	Maximum feed rate override that occurred during machining. The control enters the value 100 (%) during the test run			
OVRMIN	Minimum feed rate override that occurred during machining. The control enters the			
	value -1 during the test run			

The control saves the tool usage times in a separate file with the extension **pgmname.I.T.DEP**. This file is not visible unless the machine parameter **dependentFiles** (no. 122101) is set to **MANUAL**

There are two ways to run a tool usage test for a pallet file:

- If the cursor in the pallet file is on a pallet entry, the control runs the tool usage test for the entire pallet.
- If the cursor in the pallet file is on a program entry, the control runs the tool usage test only for the selected program.

Using a tool usage test

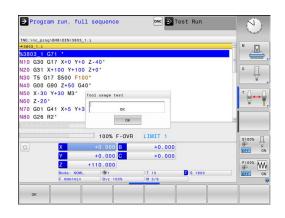
Before starting a program in the **Program Run, Full Sequence/ Single Block** operating modes, you can check whether the tools being used in the selected program are available and have sufficient remaining service life. The control then compares the actual service-life values in the tool table with the nominal values from the tool usage file.



Press the TOOL USAGE soft key

- Press the TOOL USAGE TEST soft key The control opens the Tool usage test pop-up window indicating the result of the usage test.
- Press the **OK** soft key
 The control closes the pop-up window.
- Alternative: Press the ENT key

You can query the tool usage test with the D18 ID975 NR1 function.



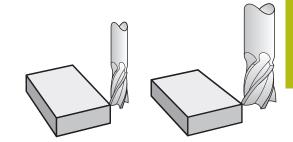
5.3 Tool compensation

Introduction

The control adjusts the tool path by the compensation value for the tool length in the spindle axis. In the machining plane, it compensates the tool radius.

If you are writing the part program directly on the control, the tool radius compensation is effective only in the working plane.

The control accounts for the compensation value in up to five axes including the rotary axes.



Tool length compensation

Length compensation becomes effective automatically as soon as a tool is called. To cancel length compensation, call a tool with the length L=0 (e.g. ${\bm T}~{\bm 0}).$

NOTICE

Danger of collision!

The control uses the defined tool lengths for tool length compensation. Incorrect tool lengths will result in an incorrect tool length compensation. The control does not perform a length compensation and a collision check for tools with a length of **0** and after **T 0**. Danger of collision during subsequent tool positioning movements!

- Always define the actual tool length of a tool (not just the difference)
- ▶ Use **T 0** only to empty the spindle

For tool length compensation, the control takes the delta values from both the ${\bf T}$ block and the tool table into account:

Compensation value = $L + DL_{CALL T block} + DL_{TAB}$ with

L: Tool length L from G99 block or tool table

DL_{CALL T block}: Oversize for length DL in the T block

DL_{TAB}: Oversize for length **DL** in the tool table

Tool radius compensation

The block for programming a tool movement contains:

- G41 or G42 for radius compensation
- **G40**, if there is no radius compensation

The radius compensation is effective as soon as a tool is called and traversed with a straight-line block in the working plane with G41 or G42.



The control automatically cancels radius compensation in the following cases:

- Straight-line block with **G40**
- **DEP** function for departing from the contour
- Selection a new program via **PGM MGT**

For radius compensation, the control takes the delta values from both the ${\bf T}$ block and the tool table into account:

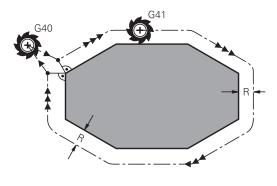
Compensation value = $\mathbf{R} + \mathbf{D}\mathbf{R}_{CALLT \ block} + \mathbf{D}\mathbf{R}_{TAB}$ with

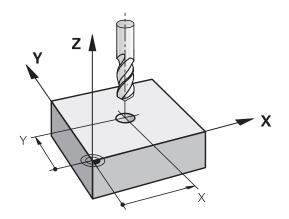
R:Tool radius R from G99 block or tool tableDR_CALLT block:Oversize for radius DR in the T blockDR TAB:Oversize for radius DR in the tool table

Contouring without radius compensation: G40

The tool center moves in the working plane along the programmed path, or to the programmed coordinates.

Applications: Drilling and boring, pre-positioning





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Contouring with radius compensation: G42 and G41

G42: The tool moves to the right of the programmed contour

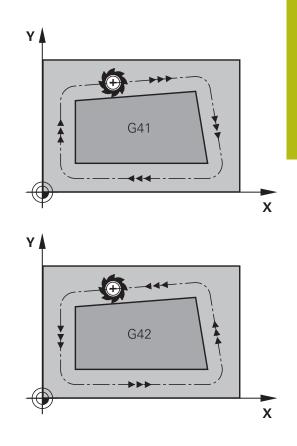
G41: The tool moves to the left of the programmed contour

The tool center moves along the contour at a distance equal to the radius. **Right** or **left** are to be understood as based on the direction of tool movement along the workpiece contour.

Between two NC blocks with different radius compensations **G42** and **G41** you must program at least one traversing block in the working plane without radius compensation (that is, with **G40**).

The control does not put radius compensation into effect until the end of the block in which it is first programmed.

When radius compensation is activated with **RR/RLG42/ G41** or canceled with **G40** the control always positions the tool perpendicular to the programmed starting or end position. Position the tool at a sufficient distance from the first or last contour point to prevent the possibility of damaging the contour.



Entering radius compensation

Radius compensation is entered in a **G01** block. Enter the coordinates of the target point and confirm your entry with the **ENT** key.

,	
G 4 1	 Select tool movement to the left of the programmed contour: Press the G41 soft key, or
G 4 2	 Select tool movement to the right of the contour: Press the G42 soft key, or
G 4 Ø	 Select tool movement without radius compensation or cancel radius compensation: Select function G40

Terminate the block: Press the END key

Radius compensation: Machining corners

• Outside corners:

If you program radius compensation, the control moves the tool around outside corners on a transitional arc. If necessary, the control reduces the feed rate at outside corners to reduce machine stress, for example at very great changes of direction

Inside corners:

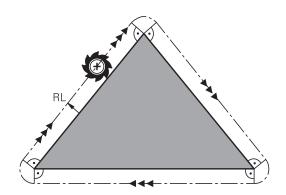
The control calculates the intersection of the tool center paths at inside corners under radius compensation. From this point it then starts the next contour element. This prevents damage to the workpiece at the inside corners. The permissible tool radius, therefore, is limited by the geometry of the programmed contour.

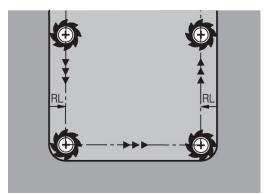
NOTICE

Danger of collision!

The control needs safe positions for contour approach and departure. These positions must enable the control to perform compensating movements when radius compensation is activated and deactivated. Incorrect positions can lead to contour damage. Danger of collision during machining!

- Program safe approach and departure positions at a sufficient distance from the contour
- Consider the tool radius
- Consider the approach strategy





5.4 Tool management (option number 93)

Basics

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Refer to your machine manual.

Tool management is a machine-dependent function, which may be partly or completely deactivated. The machine tool builder defines the exact range of functions.

In tool management, your machine manufacturer can provide a wide range of functions for tool handling. Examples:

- Display and editing of all tool data from the tool table and the touch probe table
- Easily readable and adaptable representation of the tool data in fillable forms
- Any description of the individual tool data in the new table view
- Mixed representation of data from the tool table and the pocket table
- Fast sorting of all tool data by mouse
- Use of graphic aids, e.g. color coding of tool or magazine status
- Program-specific or pallet-specific list of all available tools
- Program-specific or pallet-specific usage sequence of all tools
- Copying and pasting of all tool data pertaining to a tool
- Graphic depiction of tool type in the table view and in the detail view for a better overview of the available tool types

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If you edit a tool in tool management, the selected tool is locked. If this tool is required in the NC program being used, the control shows the message: **Tool table** locked.

00	ls P	ockets Tooling list T	usage or	der					
т	T	NAME	PT'	т	POCI	MAGAZINE	Tool life	REMAIN	M
0	2	NULLWERKZEUG	0				Not monitored	0	
1	12	MILL_D2_ROUGH	0		1	Main magazin	Not monitored	0	
2	12	MILL_D4_ROUGH	0			Main magazin	Not monitored	0	S
3	- 12	MILL_D6_ROUGH	0		3	Main magazin	Not monitored	0	4
4	10	MILL_D8_ROUGH	0		- 4	Main magazin	Not monitored	0	
5	- 12	MILL_D10_ROUGH	0		5	Main magazin	Not monitored	0	
6	12	MILL_D12_ROUGH	0			Main magazin	Not monitored	0	тД
7	17	MILL_D14_ROUGH	0		7	Main magazin	Not monitored	0	
8	10	MILL_D16_ROUGH	0		8	Main magazin	Not monitored	0	· ·
9	12	MILL_D18_ROUGH	0		9	Main magazin	Not monitored	0	1
10	12	MILL_D20_ROUGH	0		10	Main magazin	Not monitored	0	
11	12	MILL_D22_ROUGH	0		11	Main magazin	Not monitored	0	
12	10	MILL_D24_ROUGH	0			Spindle	Not monitored	0	I
13		MILL_D26_ROUGH	0		13	Main magazin	Not monitored	0	S100%
14	12	MILL_D28_ROUGH	0		14	Main magazine	Not monitored	0	0
15		MILL_D30_ROUGH	0		15	Main magazin	Not monitored	0	OFF
16	10	MILL_D32_ROUGH	0		16	Main magazin	Not monitored	0	
17	17	MILL_D34_ROUGH	0		17	Main magazin	Not monitored	0	F100%
18	10	MILL_D36_ROUGH	0		18	Main magazine	Not monitored	0	<u> </u>
19	10	MTLL D38 BOUGH	0		19	Main manazin	Not monitored	n ~	OFF

Calling tool management



Refer to your machine manual.

The procedure for calling the tool management may differ from that described below.

- Select the tool table: Press the TOOL TABLE soft key
- Scroll through the soft-key row



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TOOL TABLE

> Press the TOOL MANAGEMENT soft key The control switches to the new table view.

Tool management view

In the new view, the control presents all tool information in the following four tabs:

- **Tools**: Tool specific information
- **pockets**: Pocket-specific information
- Tooling list: List of all tools in the NC program that is selected in the Program Run mode (only if you have already created a tool usage file)

Further information: "Tool usage test", page 226

 T usage order: List of the sequence of all tools that are inserted in the program selected in the Program Run mode (only if you have already created a tool usage file)
 Further information: "Tool usage test", page 226



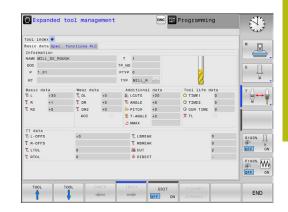
If a pallet table is selected in the Program Run operating mode, the **Tooling list** and **T usage order** are calculated for the entire pallet table.

	Pockets Tooling list	T usage or	ler					
TT	NAME	PT'	т	POCI	MAGAZINE	Tool life	REMAIN	M 🔽
0	NULLWERKZEUG	0				Not monitored	0	
1	MILL_D2_ROUGH	0		1	Main magazin	Not monitored	0	
2	MILL_D4_ROUGH	0			Main magazin	Not monitored	0	S E
3	MILL_D6_ROUGH	0			Main magazin	Not monitored	0	4
4 1	MILL_D8_ROUGH	0			Main magazin	Not monitored	0	M
5	MILL_D10_ROUGH	0			Main magazin	Not monitored	0	
6 1	MILL_D12_ROUGH	0			Main magazin	Not monitored	0	т
7 1	MILL_D14_ROUGH	0		7	Main magazin	Not monitored	0	Q
8	MILL_D16_ROUGH	0		8	Main magazin	Not monitored	0	
9	MILL_D18_ROUGH	0			Main magazin	Not monitored	0	1
10	MILL_D20_ROUGH	0			Main magazin	Not monitored	0	
11 8	MILL_D22_ROUGH	0		11	Main magazin	Not monitored	0	
12	MILL_D24_ROUGH	0			Spindle	Not monitored	0	I
13	MILL_D26_ROUGH	0		13	Main magazin	Not monitored	0	S100%
14	MILL_D28_ROUGH	0		14	Main magazin	Not monitored	0	0 9
15	MILL_D30_ROUGH	0		15	Main magazin	Not monitored	0	OFF
16	MILL_D32_ROUGH	0			Main magazin	Not monitored	0	
17 1	MILL_D34_ROUGH	0		17	Main magazin	Not monitored	0	F100% A
18	MILL_D36_ROUGH	0		18	Main magazin	Not monitored	0	
19	MTLL D38 ROUGH	0		19	Main manazin	Not monitored	0 *	OFF

Editing tool management

The tool management can be operated by mouse or with the keys and soft keys:

Soft key	Editing functions for tool management
	Select the table start
	Select the table end
	Select the previous page in the table
PAGE	Select the next page in the table
FORM FOR TOOL	Call the form view of the marked tool. Alternative function: Press the ENT key
	Changing tab: Tools, Pockets, Assembly list, T usage sequence
FIND	Search function: Here you can select the column to be searched and then the search term either from a list or by entering it
TOOL IMPORT	Import tools
EXPORT TOOL	Export tools
DELETE MARKED TOOLS	Delete marked tools
APPEND N LINES	Add several lines at end of table
UPDATE THE VIEW	Update table view
PROG. TOOL DISPLAY HIDE	Show the programmed tools column (if the Pockets tab is active)
COLUMN SORT MOVE	 Define the settings: SORT COLUMN active: Click the column header to sort the content of the column SHIFT COLUMN active: The column can be moved by drag and drop
RESET SETTINGS	Reset the manually changed settings (move columns) to the original condition



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You can edit the tool data only in the form view. To activate the form view, press the **FORM FOR TOOL** soft key or the **ENT** key for the currently highlighted tool. If you use the tool management without a mouse, then you can activate and deactivate functions with the -/+ key.

In the tool management, use the $\ensuremath{\textbf{GOTO}}$ key to search for the tool number or pocket number.

In addition, you can perform the following functions by mouse:

- Sorting function: You can sort the data in ascending or descending order (depending on the active setting of the soft key) by clicking a column of the table head.
- Arrange columns. You can arrange the columns in any sequence you want by clicking a column of the table head and then moving it with the mouse key pressed down. The control does not save the current column sequence when you exit the tool management (depending on the active setting of the soft key).
- Show miscellaneous information in the form view: The control displays tool tips when you leave the mouse pointer on an active entry field for more than a second and when you have set the EDIT ON/OFF soft key to ON

Editing with active form view

If the form view is active, the following functions are available to you:

Soft key	Editing functions, form view
TOOL	Select the tool data of the previous tool
TOOL	Select the tool data of the next tool
INDEX	Select previous tool index (only active if indexing is enabled)
INDEX	Select the next tool index (only active if indexing is enabled)
SELECT	Open a pop-up window for selection (only available for selection fields)
DISCARD CHANGES	Discard all changes made since the form was called
INSERT INDEX	Add tool index
DELETE	Delete tool index
COPY DATA RECORD	Copy the tool data of the selected tool
INSERT DATA REC.	Insert the copied tool data in the selected tool

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Deleting marked tool data

Using this function you can simply delete tool data that you no longer need.

Follow the steps outlined below for deleting:

- In the tool management you use the arrow keys or mouse to mark the tool data that you wish to delete
- Press the DELETE MARKED TOOLS soft key The control shows a pop-up window listing the tool data to be deleted.
- Press the START soft key to start the deletion procedure The control shows a pop-up window with the deletion status.
- Terminate the delete process by pressing the END key or soft key

NOTICE

Caution: Data may be lost!

The **DELETE MARKED TOOLS** function permanently deletes the tool data. The data is not automatically backed up by the control, e.g. to a recycle bin, before being deleted. The data is irreversibly deleted by this function.

Regularly back up important data to external drives



The tool data of tools still stored in the pocket table cannot be deleted. The tools must be removed from the magazine first.

Available tool types

The tool management displays the various tool types with an icon. The following tool types are available:

lcon	Tool type	Tool type number
T	Undefined,****	99
H	Milling cutter, MILL	0
8	Drill,DRILL	1
.	Tap, TAP	2
	Center drill,CENT	4
2	Turning Tool, TURN	29
ļ	Touch probe,TCHP	21
	Ream,REAM	3
Ŷ	Countersink, CSINK	5
8	Piloted counterbore(TSINK),TSINK	6
de.	Boring tool,BOR	7
+	Back boring tool,BCKBOR	8
Y	Thread mill,GF	15
8	Thread mill w/ countersink,GSF	16
	Thread mill w/ single thread,EP	17
6	Thread mill w/ indxbl insert,WSP	18
8	Thread milling drill,BGF	19
.	Circular thread mill,ZBGF	20

lcon	Tool type	Tool type number
7	Roughing cutter (MILL_R),MILL_R	9
8	Finishing cutter (MILL_F),MILL_F	10
8	Rough/finish cutter,MILL_RF	11
8	Floor finisher(MILL_FD),MILL_FD	12
8	Side finisher (MILL_FS),MILL_FS	13
	Face milling cutter,MILL_FACE	14

Importing and exporting tool data

Importing tool data



Refer to your machine manual.

The machine tool builder can define update rules that make it possible, for example, to automatically remove umlauts from tables and NC programs.

Using this function you can simply import tool data that you have measured externally on a presetting device, for example. The file to be imported must have the CSV format (comma separated value). The **CSV** file format describes the structure of a text file for exchanging simply structured data. Accordingly, the import file must have the following structure:

- **Row 1**: In the first line you define the column names in which the data defined in the subsequent lines is to be placed. The column names are separated with a comma.
- **Other lines**: All the other lines contain the data that you wish to import into the tool table. The order of the data must match the order of the column names in Line 1. The data is separated by commas, decimal numbers are to be defined with a decimal point.

Follow the steps outlined below for importing:

- Copy the tool table to be imported to the TNC:\system\tooltab directory on the hard disk of the control
- Start expanded tool management
- Press the TOOL IMPORT soft key in the tool management The control shows a pop-up window with the CSV files that are saved in the TNC:\system\tooltab directory
- Use the arrow keys or mouse to select the file to be imported and confirm with the ENT key
 The control shows a pop-up window with the content of the CSV file
- ► Start the import procedure with the **EXECUTE** soft key.

0	-	The CSV file to be imported must be stored in the TNC:\system\tooltab directory.
	•	If you import the tool data of existing tools (whose numbers are in the pocket table) the control issues an error message. You can then decide whether to skip this data record or insert a new tool. The control inserts a new tool into the first empty line of the tool table.
	-	If the imported CSV file contains unknown table columns, the control displays a message during import. An additional note informs you that the data will not be transferred.
	-	Make sure that the column designations have been specified correctly. Further information: "Entering tool data into the table", page 208
	-	You can import any tool data, the associated data record does not have to contain all the columns (or data) of the tool table.
	-	The column names can be in any order, the data must be defined in the corresponding order.

Example

T,L,R,DL,DR	Line 1 with column names
4,125.995,7.995,0,0	Line 2 with tool data
9,25.06,12.01,0,0	Line 3 with tool data
28,196.981,35,0,0	Line 4 with tool data

Exporting tool data

Using this function you can simply export tool data to read it into the tool database of your CAM system, for example. The control stores the exported file in the CSV format (comma separated value). The **CSV** file format describes the structure of a text file for exchanging simply structured data. The export file has the following structure:

- Line 1: In the first line the control stores the column names of all the relevant tool data to be defined. The column names are separated from each other by commas.
- **Further lines**: All the other lines contain the data of the tools that you have exported. The order of the data matches the order of the column names in Line 1. The data is separated by commas, the control outputs decimal numbers with a decimal point.

Follow the steps outlined below for exporting:

- In the tool management you use the arrow keys or mouse to mark the tool data that you wish to export
- Press the EXPORT TOOL soft key The control shows a pop-up window

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- Enter a name for the CSV file and confirm it with the ENT key
- Start the export procedure with the EXECUTE soft key The control shows a pop-up window with the status of the export process
- Terminate the export process by pressing the END key or soft key

By default the control stores the exported CSV file in the **TNC:\system\tooltab** directory.

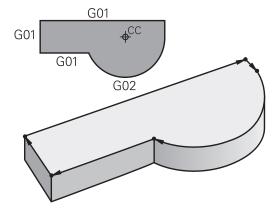


Programming Contours

6.1 Tool movements

Path functions

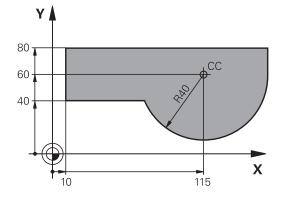
A workpiece contour is usually composed of several contour elements such as straight lines and circular arcs. With the path functions, you can program the tool movements for **straight lines** and **circular arcs**.



FK free contour programming

If a production drawing is not dimensioned for NC and the dimensions given are not sufficient for creating a part program, you can program the workpiece contour with the FK free contour programming. The control calculates the missing data.

With FK programming, you also program tool movements for **straight lines** and **circular arcs**.



Miscellaneous functions M

With the control's miscellaneous functions you can affect

- the program run, e.g., a program interruption
- the machine functions, such as switching spindle rotation and coolant supply on and off
- the path behavior of the tool

Subprograms and program section repeats

If a machining sequence occurs several times in a program, you can save time and reduce the chance of programming errors by entering the sequence once and then defining it as a subprogram or program section repeat. If you wish to execute a specific program section only under certain conditions, you also define this machining sequence as a subprogram. In addition, you can have a part program call a separate program for execution.

Further information: "Subprograms and Program Section Repeats", page 317

Programming with Q parameters

Instead of programming numerical values in a machining program, you enter markers called Q parameters. You assign the values to the Q parameters separately with the Q parameter functions. You can use the Q parameters for programming mathematical functions that control program execution or describe a contour.

In addition, programming with Q parameters enables you to measure with the 3-D touch probe during the program run.

Further information: "Programming Q Parameters", page 337

6.2 Fundamentals of path functions

Programming tool movements for workpiece machining

You create a part program by programming the path functions for the individual contour elements in sequence. You do this by entering the coordinates of the end points of the contour elements given in the production drawing. The control calculates the actual path of the tool from these coordinates, and from the tool data and radius compensation.

The control moves all machine axes programmed in the NC block of a path function simultaneously.

Movement parallel to the machine axes

If the NC block contains one coordinate, the control moves the tool parallel to the programmed machine axis.

Depending on the individual machine tool, the part program is executed by movement of either the tool or the machine table on which the workpiece is clamped. Path contours are programmed as if the tool were moving.

Example

N50	Block number
G00	Path function straight line at rapid traverse
X+100	Coordinate of the end point

The tool retains the Y and Z coordinates and moves to the position X=100.

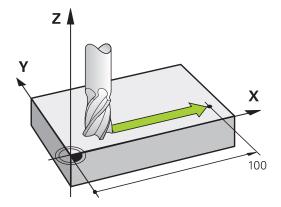
Movement in the main planes

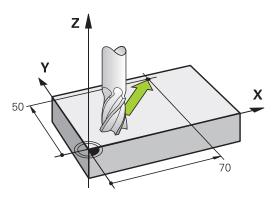
If the NC block contains two coordinates, the control moves the tool in the programmed plane.

Example

N50 G00 X+70 Y+50*

The tool retains the Z coordinate and moves on the XY plane to the position X=70, Y=50.





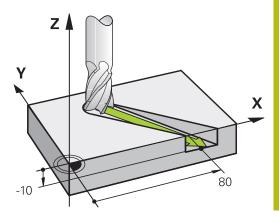
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Three-dimensional movement

If the NC block contains three coordinates, the control moves the tool spatially to the programmed position.

Example

N50 G01 X+80 Y+0 Z-10*



Circles and circular arcs

The control moves two machine axes simultaneously on a circular path relative to the workpiece. You can define a circular movement by entering the circle center with I and J.

When you program a circle, the control assigns it to one of the main planes. This plane is defined automatically when you set the spindle axis during a T:

Spindle axis	Main plane
(G17)	XY, also UV, XV, UY
(G18)	ZX , also WU, ZU, WX
(G19)	YZ, also VW, YW, VZ

You can program circles that do not lie parallel to a main plane by using the function for **Tilt working plane** or with Q parameters.

Further information: "The PLANE function: Tilting the working plane (option 8)", page 479

Further information: "Principle and overview of functions", page 338

Direction of rotation DR for circular movements

When a circular path has no tangential transition to another contour element, enter the direction of rotation as follows:

Clockwise direction of rotation: $\ensuremath{\textbf{G02/G12}}$

Counterclockwise direction of rotation: G03/G13

Radius compensation

The radius compensation must be in the block in which you move to the first contour element. You cannot activate radius compensation in a circle block. It must be activated beforehand in a straight-line block.

Further information: "Path contours Cartesian coordinates", page 262

Pre-positioning

NOTICE

Danger of collision!

The control does not automatically check whether collisions can occur between the tool and the workpiece. Incorrect prepositioning can also lead to contour damage. There is danger of collision during the approach movement!

- Program a suitable pre-position
- Check the sequence and contour with the aid of the graphic simulation

6.3 Approaching and departing a contour

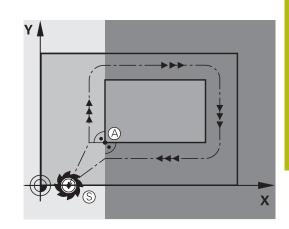
Starting point and end point

The tool approaches the first contour point from the starting point. The starting point must be:

- Programmed without radius compensation
- Approachable without danger of collision
- Close to the first contour point

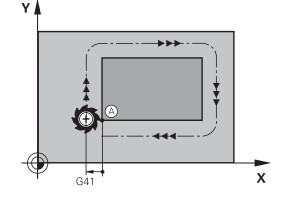
Example in the figure on the right:

If you set the starting point in the dark gray area, the contour will be damaged when the first contour element is approached.



First contour point

You need to program a radius compensation for the tool movement to the first contour point.

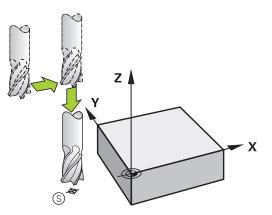


Approaching the starting point in the spindle axis

When the starting point is approached, the tool must be moved to the working depth in the spindle axis. If danger of collision exists, approach the starting point in the spindle axis separately.

Example

N40 G00 Z-10*	
N30 G01 X+20 Y+30 G41 F350*	



End point

The end point should be selected so that it is:

- Approachable without danger of collision
- Near to the last contour point
- In order to make sure the contour will not be damaged, the optimal ending point should lie on the extended tool path for machining the last contour element

Example in the figure on the right:

If you set the end point in the dark gray area, the contour will be damaged when the end point is approached.

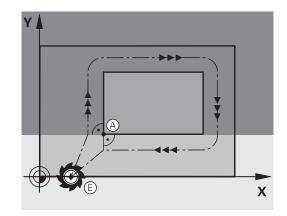
Departing the end point in the spindle axis:

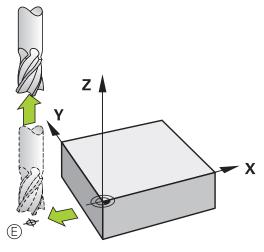
Program the departure from the end point in the spindle axis separately.

Example

N50 G01 G40 X+60 Y+70 F700*

N60 G00 Z+250*





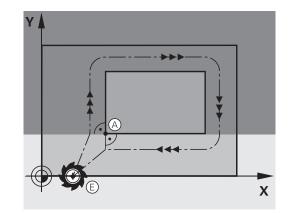
Common starting and end points

Do not program any radius compensation if the starting point and end point are the same.

In order to make sure the contour will not be damaged, the optimal starting point should lie between the extended tool paths for machining the first and last contour elements.

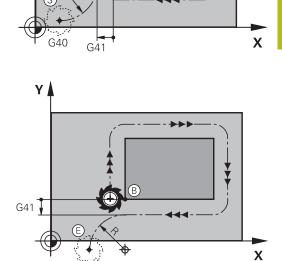
Example in the figure on the right:

If you set the end point in the dark gray area, the contour will be damaged when the contour is approached/departed.



Tangential approach and departure

With **G26** (figure at center right), you can program a tangential approach to the workpiece, and with **G27** (figure at lower right) a tangential departure. In this way you can avoid dwell marks.



G40

Y

Starting point and end point

The starting point and the end point lie outside the workpiece, close to the first and last contour points. They are to be programmed without radius compensation.

Approach

► **G26** is entered after the block in which the first contour element is programmed: This will be the first block with radius compensation **G41/G42**

Departure

 G27 after the block in which the last contour element is programmed: This will be the last block with radius compensation G41/G42

6

The radius for **G26** and **G27** must be selected so that the control can execute the circular path between the starting point and the first contour point, as well as the last contour point and the end point.

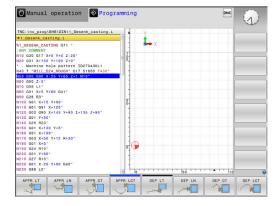
Example

N50 G00 G40 G90 X-30 Y+50*	Starting point
N60 G01 G41 X+0 Y+50 F350*	First contour point
N70 G26 R5*	Tangential approach with radius R = 5 mm
Program contour blocks	
	Last contour point
N210 G27 R5*	Tangential departure with radius R = 5 mm
N220 G00 G40 X-30 Y+50*	End point

Overview: Types of paths for contour approach and departure

The functions for contour approach **APPR** and departure **DEP** are activated with the **APPR/DEP** key. You can then select the following path forms with the corresponding soft keys:

Approach	Departure	Function
APPR LT	DEP LT	Straight line with tangential connec- tion
APPR LN	DEP LN	Straight line perpendicular to a contour point
APPR CT	DEP CT	Circular arc with tangential connec- tion
APPR LCT	DEP LCT	Circular arc with tangential connec- tion to the contour. Approach and departure to an auxiliary point outside the contour on a tangentially connect-



Approaching and departing a helix

The tool approaches and departs a helix on its extension by moving in a circular arc that connects tangentially to the contour. You program helical approach and departure with the **APPR CT** and **DEP CT** functions.

ing line

Important positions for approach and departure

Starting point P_S

You program this position in the block before the APPR block. P_{S} lies outside the contour and is approached without radius compensation (G40).

Auxiliary point P_H

Some of the paths for approach and departure go through an auxiliary point P_H that the control calculates from your input in the APPR or DEP block. The control moves from the current position to the auxiliary point P_H at the feed rate last programmed. If you have programmed **G00** (positioning at rapid traverse) in the last positioning block before the approach function, the control also approaches the auxiliary point P_H at rapid traverse

- First contour point P_A and last contour point P_E
 You program the first contour point P_A in the APPR block.
 The last contour point P_E can be programmed with any path function. If the APPR block also includes the Z coordinate, the control moves the tool simultaneously to the first contour point P_A.
- End point P_N

The position $P_{\rm N}$ lies outside of the contour and results from your input in the DEP block. If the DEP block also includes the Z coordinate, the control moves the tool simultaneously to the end point $P_{\rm N}.$

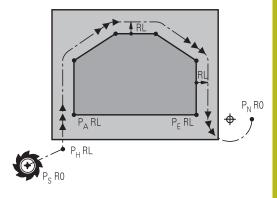
Abbreviation	Meaning
APPR	Approach
DEP	Departure
L	Line
С	Circle
т	Tangential (smooth connection)
N	Normal (perpendicular)

NOTICE

Danger of collision!

The control does not automatically check whether collisions can occur between the tool and the workpiece. Incorrect prepositioning and incorrect auxiliary points P_H can also lead to contour damage. There is danger of collision during the approach movement!

- Program a suitable pre-position
- Check the auxiliary point P_H, the sequence and the contour with the aid of the graphic simulation



R0=G40; RL=G41; RR=G42

With the **APPR LT**, **APPR LN** and **APPR CT** functions, the control moves the tool to the auxiliary point P_H at the last programmed feed rate (which can also be **FMAX**). With the **APPR LCT** function, the control moves to the auxiliary point P_H at the feed rate programmed with the APPR block. If no feed rate is programmed yet before the approach block, the control generates an error message.

Polar coordinates

You can also program the contour points for the following approach/ departure functions over polar coordinates:

- APPR LT becomes APPR PLT
- APPR LN becomes APPR PLN
- APPR CT becomes APPR PCT
- APPR LCT becomes APPR PLCT
- DEP LCT becomes DEP PLCT

Select an approach or departure function with the soft key, then press the orange ${\bf P}$ key.

Radius compensation

The tool radius compensation is programmed together with the first contour point P_A in the APPR block. The DEP blocks automatically discard the tool radius compensation.

()	If you program APPR LN or APPR CT with G40 , the control stops the machining/simulation with an error
	message. This method of function differs from the iTNC 530

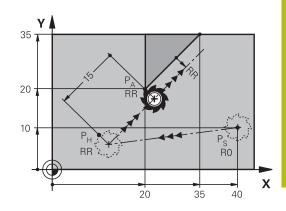
control!

HEIDENHAIN | TNC 320 | ISO Programming User's Manual | 10/2017

Approaching on a straight line with tangential connection: APPR LT

The tool moves on a straight line from the starting point P_S to an auxiliary point P_H . It then moves to the first contour point P_A on a straight line that connects tangentially to the contour. The auxiliary point P_H is separated from the first contour point P_A by the distance **LEN**.

- \blacktriangleright Use any path function to approach the starting point P_S
- Initiate the dialog with the APPR DEP key and APPR LT soft key
 - Coordinates of the first contour point P_A
 - LEN: Distance from the auxiliary point P_H to the first contour point P_A
 - Radius compensation G41/G42 for machining



R0=G40; RL=G41; RR=G42

Example

APPR LT

N70 G00 X+40 Y+10 G40 M3*	Approach P _S without radius compensation
N80 APPR LT X+20 Y+20 Z-10 LEN15 G42 F100*	P_A with radius comp. G42, distance P_H to P_A : LEN=15
N90 G01 X+35 Y+35*	End point of the first contour element
N100 G01*	Next contour element

Approaching on a straight line perpendicular to the first contour point: APPR LN

- Use any path function to approach the starting point P_S.
- Initiate the dialog with the APPR DEP key and APPR LN soft key:
- APPR LN
- Coordinates of the first contour point P_A
- Length: Distance to the auxiliary point P_H.
 Always enter LEN as a positive value
- Radius compensation G41/G42 for machining

Example

N70 G00 X+40 Y+10 G40 M3*	Approach PS without radius compensation
N80 APPR LN X+10 Y+20 Z-10 LEN15 G24 F100*	PA with radius comp. G42
N90 G01 X+20 Y+35*	End point of the first contour element
N100 G01*	Next contour element

Approaching on a circular path with tangential connection: APPR CT

The tool moves on a straight line from the starting point P_S to an auxiliary point P_H . It then moves from PH to the first contour point PA following a circular arc that is tangential to the first contour element.

The arc from P_H to P_A is determined through the radius R and the center angle **CCA**. The direction of rotation of the circular arc is automatically derived from the tool path for the first contour element.

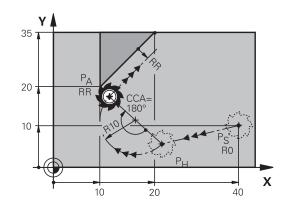
- ▶ Use any path function to approach the starting point P_S.
- Initiate the dialog with the APPR DEP key and APPR CT soft key



- Coordinates of the first contour point P_A
- Radius R of the circular arc
 - If the tool should approach the workpiece in the direction defined by the radius compensation: Enter R as a positive value
 - If the tool should approach the workpiece opposite to the radius compensation: Enter R as a negative value.
- Center angle **CCA** of the arc
 - CCA can be entered only as a positive value.
 - Maximum input value 360°
- Radius compensation G41/G42 for machining

Example

N70 G00 X+40 Y+10 G40 M3*	Approach PS without radius compensation
N80 APPR CT X+10 Y+20 Z-10 CCA180 R+10 G42 F100*	PA with radius comp. G42, radius R=10
N90 G01 X+20 Y+35*	End point of the first contour element
N100 G01*	Next contour element



R0=G40; RL=G41; RR=G42

Approaching on a circular path with tangential connection from a straight line to the contour: APPR LCT

The tool moves on a straight line from the starting point P_S to an auxiliary point P_H . It then moves to the first contour point P_A on a circular arc. The feed rate programmed in the APPR block is effective for the entire path that the control traversed in the approach block (path P_S to P_A).

If you have programmed the coordinates of all three principal axes X, Y and Z in the approach block, the control moves the tool from the position defined before the APPR block to the auxiliary point P_H on all three axes simultaneously. Then the connect goes from P_H to P_A only on the working plane.

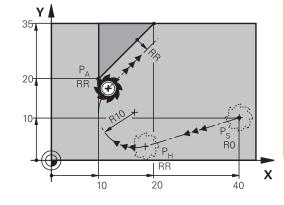
The arc is connected tangentially both to the line $P_S - P_H$ as well as to the first contour element. Once these lines are known, the radius then suffices to completely define the tool path.

- ▶ Use any path function to approach the starting point P_S.
- Initiate the dialog with the APPR DEP key and APPR LCT soft key:
 - Coordinates of the first contour point P_A
 - Radius R of the circular arc. Enter R as a positive value
 - Radius compensation G41/G42 for machining

Example

APPR LCT

N70 G00 X+40 Y+10 G40 M3*	Approach PS without radius compensation
N80 APPR LCT X+10 Y+20 Z-10 R10 G42 F100*	PA with radius comp. G42, radius R=10
N90 G01 X+20 Y+35*	End point of the first contour element
N100 G01*	Next contour element



R0=G40; RL=G41; RR=G42

Departing in a straight line with tangential connection: DEP LT

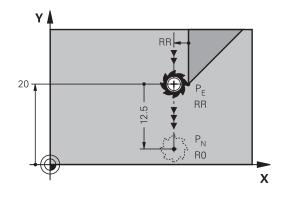
The tool moves on a straight line from the last contour point P_E to the end point P_N . The line lies on the extension of the last contour element. P_N is separated from P_E by the distance **LEN**.

 Program the last contour element with the end point P_E and radius compensation

▶ Initiate the dialog with the APPR DEP key and DEP LT soft key



 LEN: Enter the distance from the last contour element P_E to the end point P_N.



R0=G40; RL=G41; RR=G42

Example

N20 G01 Y+20 G42 F100*	Last contour element: PE with radius compensation
N30 DEP LT LEN12.5 F100*	Depart contour by LEN=12.5 mm
N40 G00 Z+100 M2*	Retract in Z, return to block 1, end program

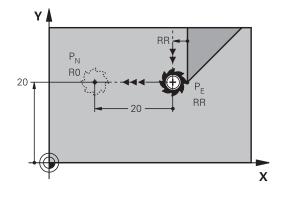
Departing in a straight line perpendicular to the last contour point: DEP LN

The tool moves on a straight line from the last contour point P_E to the end point P_N. The line departs on a perpendicular path from the last contour point P_E. P_N is separated from P_E by the distance **LEN** plus the tool radius.

- Program the last contour element with the end point P_E and radius compensation
- ▶ Initiate the dialog with the APPR DEP key and DEP LN soft key



 LEN: Enter the distance from the last contour element to P_N. Important: Enter a positive value in LEN



R0=G40; RL=G41; RR=G42

Example

N20 G01 Y+20 G42 F100*	Last contour element: PE with radius compensation
N30 DEP LN LEN+20 F100*	Depart perpendicular to contour by LEN=20 mm
N40 G00 Z+100 M2*	Retract in Z, return to block 1, end program

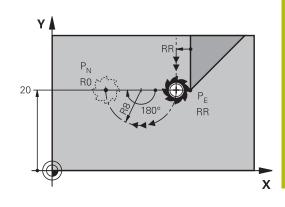
Departing on a circular path with tangential connection: DEP CT

The tool moves on a circular arc from the last contour point P_E to the end point $\mathsf{P}_\mathsf{N}.$ The circular arc connects tangentially to the last contour element.

- Program the last contour element with the end point P_E and radius compensation
- Initiate the dialog with the APPR DEP key and DEP CT soft key



- Center angle CCA of the arc
 Radius R of the circular arc
 - If the tool should depart the workpiece in the direction opposite to the radius compensation: Enter R as a positive value.
 - If the tool should depart the workpiece in the direction **opposite** to the radius compensation: Enter R as a negative value.



R0=G40; RL=G41; RR=G42

Example

N20 G01 Y+20 G42 F100*	Last contour element: PE with radius compensation
N30 DEP CT CCA 180 R+8 F100*	Center angle=180°, arc radius=8 mm
N40 G00 Z+100 M2*	Retract in Z, return to block 1, end program

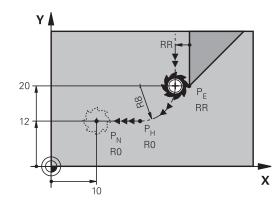
Departing on a circular arc tangentially connecting the contour and a straight line: DEP LCT

The tool moves on a circular arc from the last contour point P_S to an auxiliary point P_H. It then moves on a straight line to the end point P_N. The arc is tangentially connected both to the last contour element and to the line from P_H to P_N. Once these lines are known, the radius R suffices to unambiguously define the tool path.

- Program the last contour element with the end point P_E and radius compensation
- Initiate the dialog with the APPR/DEP key and DEP LCT soft key



- Enter the coordinates of the end point P_N
- Radius R of the circular arc. Enter R as a positive value



R0=G40; RL=G41; RR=G42

Example

N20 G01 Y+20 G42 F100*	Last contour element: PE with radius compensation
N30 DEP LCT X+10 Y+12 R+8 F100*	Coordinates PN, arc radius=8 mm
N40 G00 Z+100 M2*	Retract in Z, return to block 1, end program

6.4 Path contours — Cartesian coordinates

Overview of path functions

Path function key	Function	Tool movement	Required input	Page
L	Straight line L	Straight line	Coordinates of the end point of the straight line	263
	G00 and G01			
CHF o	Chamfer: CHF	Chamfer between two	Chamfer side length	264
	G24	straight lines		
	Circle center CC	None	Coordinates of the circle center or pole	266
	l and J			
C	Circular arc C	Circular arc around a	Coordinates of the arc	267
	G02 and G03	circle center CC to an arc end point	end point, direction of rotation	
CR	Circular arc CR	Circular arc with a certain	Coordinates of the arc	268
	G05	radius	end point, arc radius, direction of rotation	
	Circular arc CT	Circular arc with tangen-	Coordinates of the arc	270
	G06	tial connection to the preceding and subse- quent contour elements	end point	
	Corner rounding RND	Circular arc with tangen-	Rounding radius R	265
	G25	tial connection to the preceding and subse- quent contour elements		
FK	FK free contour programming	Straight line or circular path with any connection to the preceding contour element	"Path contours – FK free contour programming ", page 281	284

Programming path functions

You can program path functions conveniently by using the gray path function keys. In further dialogs, you are prompted by the control to make the required entries.

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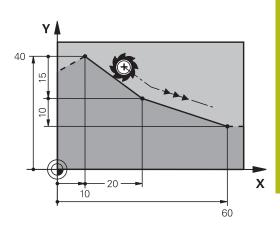
If you enter DIN/ISO functions via a connected USB keyboard, make sure that capitalization is active. At the start of the block the control automatically writes in capitals.

Straight line in rapid traverse G00 or straight line with feed rate F G01

The control moves the tool in a straight line from its current position to the straight-line end point. The starting point is the end point of the preceding block.



- Press the L key to open a program block for a linear movement with feed rate
- Coordinates of the end point of the straight line, if necessary
- Radius compensation G40/G41/G42
- Feed rate F
- Miscellaneous function M



Movement at rapid traverse

A straight line block for a rapid traverse motion (G00 block) can also be initiated with the ${\bf L}$ key:

- Press the L key to open a program block for a linear movement
- Press the left arrow key to switch to the input range for G codes
- Press the G00 soft key if you want to enter a rapid traverse motion

Example

N70 G01 G41 X+10 Y+40 F200 M3*
N80 G91 X+20 Y-15*
N90 G90 X+60 G91 Y-10*

Actual position capture

You can also generate a straight-line block (**G01** block) by using the **actual position capture** key:

- In the Manual Operation mode, move the tool to the position you want to capture
- Switch the screen display to programming.
- Select the NC block after which you want to insert the straight line block



Press the actual position capture key

The control generates a straight-line block with the actual position coordinates.

Inserting a chamfer between two straight lines

The chamfer enables you to cut off corners at the intersection of two straight lines.

- The line blocks before and after the **G24** block must be in the same working plane as the chamfer.
- The radius compensation before and after the G24 block must be the same
- The chamfer must be machinable with the current tool
- CHF of

Chamfer side length: Length of the chamfer, and if necessary:

Feed rate F (effective only in G24 block)

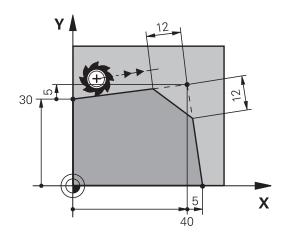
Example

A

N70 G01 G41 X+0 Y+30 F300 M3* N80 X+40 G91 Y+5* N90 G24 R12 F250* N100 G91 X+5 G90 Y+0*

> You cannot start a contour with a **G24** block. A chamfer is possible only in the working plane. The corner point is cut off by the chamfer and is not part of the contour.

A feed rate programmed in the **G24** block is effective only in that CHF block. After the **G24** block, the previous feed rate becomes effective again.



Rounded corners G25

The G25 function rounds off contour corners.

The tool moves on an arc that is tangentially connected to both the preceding and subsequent contour elements.

The rounding arc must be machinable with the called tool.

	RND 💡
l	~

- Rounding radius: Enter the radius, and if necessary:
- Feed F (effective only in the G25 block)

Example

A

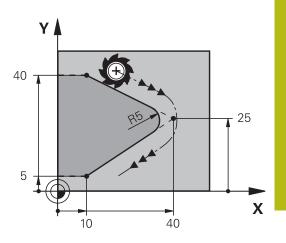
N50 G01	X+10 Y+40 G41 F300 M3*
N60 G01	X+40 Y+25*
N70 G25	R5 F100*
N80 G01	X+10 Y+5*

In the preceding and subsequent contour elements, both coordinates must lie in the plane of the rounding arc. If you machine the contour without tool-radius compensation, you must program both coordinates in the plane.

The corner point is cut off by the rounding arc and is not part of the contour.

A feed rate programmed in the **G25** block is effective only in that **G25** block. After the **G25** block, the previous feed rate becomes effective again.

You can also use an **G25** block for a tangential contour approach.



Circle center I, J

You can define a circle center for circles that you have programmed with the **G02**, **G03** or **G05** function. This is done in the following ways:

- Entering the Cartesian coordinates of the circle center in the working plane, or
- Using the circle center defined in an earlier block, or
- Capturing the coordinates with the Actual-position capture key
- SPEC FCT
- To program the circle center, press the SPEC FCT key
- Press the PROGRAM FUNCTIONS soft key
- Press the DIN/ISO soft key
- Press the I or J soft key
- Enter coordinates for the circle center or, if you want to use the last programmed position, G29 coordinates

Example

N50 I+25 J+25*

or

N10 G00 G40 X+25 Y+25*

N20 G29*

The program lines 10 and 20 do not refer to the illustration.

Validity

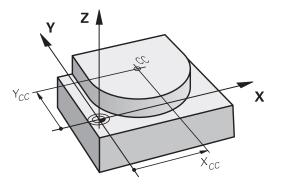
The circle center definition remains in effect until a new circle center is programmed.

Entering the circle center incrementally

If you enter the circle center with incremental coordinates, you have programmed it relative to the last programmed position of the tool.



The only effect of **I** and **J** is to define a position as circle center: The tool does not move to this position. The circle center is also the pole for polar coordinates.

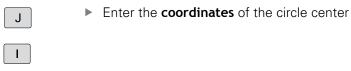


Circular path around circle center

Before programming a circular arc, you must first enter the circle center ${\bf I},\,{\bf J}.$ The last programmed tool position will be the starting point of the arc.

Direction of rotation

- In clockwise direction: G02
- In counterclockwise direction: G03
- Without programmed direction: **G05**. The control traverses the circular arc with the last programmed direction of rotation.
- Move the tool to the circle starting point



- Enter the coordinates of the arc end point, and if necessary:
- Feed F
- Miscellaneous function M

The control normally makes circular movements in the active working plane. However, you can also program circular arcs that do not lie in the active working plane. By simultaneously rotating these circular movements you can create spatial arcs (arcs in three axes), e.g. **G2 Z... X...** (with tool axis Z).

Example

C____

N50 I+25 J+25*

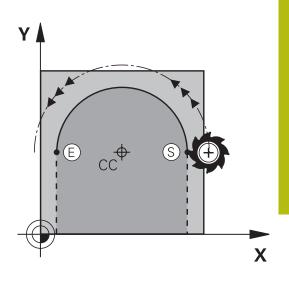
N60 G01	G42	X+45	Y+25	F200	M3*
---------	-----	------	------	------	-----

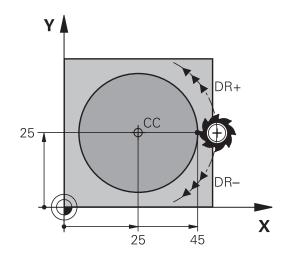
N70 G03 X+45 Y+25*

Full circle

For the end point, enter the same point that you used for the starting point.

The starting and end points of the arc must lie on the circle.
 The maximum value for input tolerance is 0.016 mm. Set the input tolerance in the machine parameter circleDeviation (no. 200901).
 Smallest possible circle that the control can traverse: 0.016 mm.





Circle G02/G03/G05 with defined radius

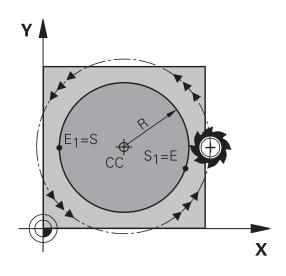
The tool moves on a circular path with the radius R.

Direction of rotation

- In clockwise direction: G02
- In counterclockwise direction: G03
- Without programmed direction: **G05**. The control traverses the circular arc with the last programmed direction of rotation.



- Coordinates of the arc end point
- Radius R (the algebraic sign determines the size of the arc)
- Miscellaneous function M
- ► Feed F



Full circle

For a full circle, program two blocks in succession:

The end point of the first semicircle is the starting point of the second. The end point of the second semicircle is the starting point of the first.

Central angle CCA and arc radius R

The starting and end points on the contour can be connected with four arcs of the same radius:

Smaller arc: CCA<180°

Enter the radius with a positive sign R>0

Larger arc: CCA>180°

i

Enter the radius with a negative sign R<0

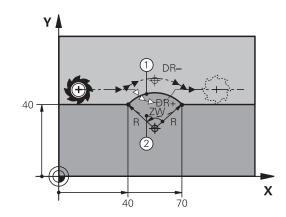
The direction of rotation determines whether the arc is curving outward (convex) or curving inward (concave):

Convex: Direction of rotation **G02** (with radius compensation **G41**) Concave: Direction of rotation **G03** (with radius compensation **G41**)

> The distance from the starting and end points of the arc diameter cannot be greater than the diameter of the arc. The maximum radius is 99.9999 m.

You can also enter rotary axes A, B and C.

The control normally makes circular movements in the active working plane. However, you can also program circular arcs that do not lie in the active working plane. By simultaneously rotating these circular movements you can create spatial arcs (arcs in three axes).



Example

N100 G01 G41 X+40 Y+40 F200 M3* N110 G02 X+70 Y+40 R+20* (arc 1)

or

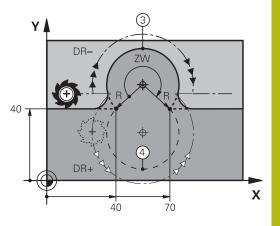
N110 G03 X+70 Y+40 R+20* (arc 2)

or

N110 G02 X+70 Y+40 R-20* (arc 3)

or

N110 G03 X+70 Y+40 R-20* (arc 4)



Circle G06 with tangential connection

The tool moves on an arc that starts tangentially to the previously programmed contour element.

A transition between two contour elements is called tangential when there is no kink or corner at the intersection between the two contours—the transition is smooth.

The contour element to which the tangential arc connects must be programmed immediately before the **G06** block. This requires at least two positioning blocks.



Coordinates of the arc end point, and if necessary:

- Feed F
- Miscellaneous function M

Example

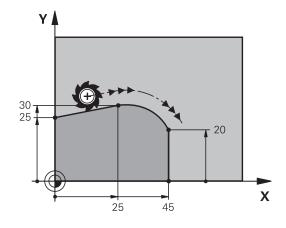
A

N70 G01 G41 X+0 Y+25 F300 M3*

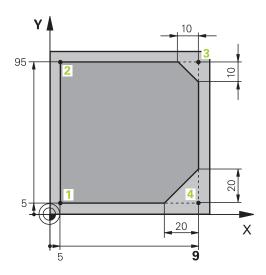
N80 X+25 Y+30* N90 G06 X+45 Y+20*

N100 G01 Y+0*

A tangential arc is a two-dimensional operation: the coordinates in the **G06** block and in the contour element preceding it must be in the same plane of the arc!

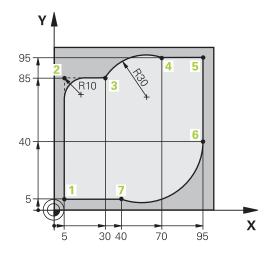


Example: Linear movements and chamfers with Cartesian coordinates



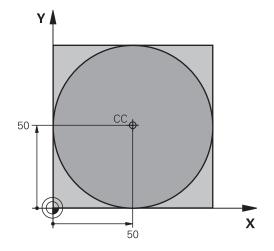
%LINEAR G71 *	
N10 G30 G17 X+0 Y+0 Z-20*	Define the workpiece blank for graphic workpiece simulation
N20 G31 G90 X+100 Y+100 Z+0*	
N30 T1 G17 S4000*	Call the tool in the spindle axis and with the spindle speed S
N40 G00 G40 G90 Z+250*	Retract the tool in the spindle axis at rapid traverse
N50 X-10 Y-10*	Pre-position the tool
N60 G01 Z-5 F1000 M3*	Move to working depth at feed rate F = 1000 mm/min
N70 G01 G41 X+5 Y+5 F300*	Approach the contour at point 1, activate radius compensation G41
N80 G26 R5 F150*	Tangential approach
N90 Y+95*	Move to point 2
N100 X+95*	Point 3: first straight line for corner 3
N110 G24 R10*	Program a chamfer with length 10 mm
N120 Y+5*	Point 4: 2nd straight line for corner 3, 1st straight line for corner 4
N130 G24 R20*	Program a chamfer with length 20 mm
N140 X+5*	Move to last contour point 1, second straight line for corner 4
N150 G27 R5 F500*	Tangential exit
N160 G40 X-20 Y-20 F1000*	Retract the tool in the working plane, cancel radius compensation
N170 G00 Z+250 M2*	Retract the tool, end program
N99999999 %LINEAR G71 *	

Example: Circular movements with Cartesian coordinates



%CIRCULAR G71 *	
N10 G30 G17 X+0 Y+0 Z-20*	Define the workpiece blank for graphic workpiece simulation
N20 G31 G90 X+100 Y+100 Z+0*	
N30 T1 G17 S4000*	Call the tool in the spindle axis and with the spindle speed S
N40 G00 G40 G90 Z+250*	Retract the tool in the spindle axis at rapid traverse
N50 X-10 Y-10*	Pre-position the tool
N60 G01 Z-5 F1000 M3*	Move to working depth at feed rate F = 1000 mm/min
N70 G01 G41 X+5 Y+5 F300*	Approach the contour at point 1, activate radius compensation G41
N80 G26 R5 F150*	Tangential approach
N90 Y+85*	Point 2: First straight line for corner 2
N100 G25 R10*	Insert radius with R = 10 mm, feed rate: 150 mm/min
N110 X+30*	Move to point 3: Starting point of the arc
N120 G02 X+70 Y+95 R+30*	Move to point 4: End point of the arc with G02, radius 30 mm
N130 G01 X+95*	Move to point 5
N140 Y+40*	Move to point 6
N150 G06 X+40 Y+5*	Move to point 7: End point of the arc, circular arc with tangential connection to point 6, the control automatically calculates the radius
N160 G01 X+5*	Move to last contour point 1
N170 G27 R5 F500*	Depart the contour on a circular arc with tangential connection
N180 G40 X-20 Y-20 F1000*	Retract the tool in the working plane, cancel radius compensation
N190 G00 Z+250 M2*	Retract the tool in the tool axis, end of program
N99999999 %CIRCULAR G71 *	

Example: Full circle with Cartesian coordinates



%C-CC G71 *	
N10 G30 G17 X+0 Y+0 Z-20*	Definition of workpiece blank
N20 G31 G90 X+100 Y+100 Z+0*	
N30 T1 G17 S3150*	Tool call
N40 G00 G40 G90 Z+250*	Retract the tool
N50 I+50 J+50*	Define the circle center
N60 X-40 Y+50*	Pre-position the tool
N70 G01 Z-5 F1000 M3*	Move to working depth
N80 G41 X+0 Y+50 F300*	Approach starting point, radius compensation G41
N90 G26 R5 F150*	Tangential approach
N100 G02 X+0*	Move to the circle end point (= circle starting point)
N110 G27 R5 F500*	Tangential exit
N120 G01 G40 X-40 Y-50 F1000*	Retract the tool in the working plane, cancel radius compensation
N130 G00 Z+250 M2*	Retract the tool in the tool axis, end of program
N99999999 %C-CC G71 *	

6.5 Path contours – Polar coordinates

Overview

With polar coordinates you can define a position in terms of its angle **H** and its distance **R** relative to a previously defined pole **I**, **J**. Polar coordinates are useful with:

- Positions on circular arcs
- Workpiece drawing dimensions in degrees, e.g. bolt hole circles

Overview of path functions with polar coordinates

Path function key	Tool movement	Required input	Page
L + P	Straight line	Polar radius, polar angle of the straight-line end point	275
с_ + Р	Circular path around circle center/pole to arc end point	Polar angle of the arc end point,	276
	Circular path corresponding to active direction of rotation	Polar angle of the circle end point	276
ст_р + Р	Circular arc with tangential connection to the preceding contour element	Polar radius, polar angle of the arc end point	276
°~ + P	Combination of a circular and a linear movement	Polar radius, polar angle of the arc end point, coordinate of the end point in the tool axis	277

Datum for polar coordinates: pole I, J

You can set the pole (I, J) at any point in the machining program, before indicating points in polar coordinates. Set the pole in the same way as you would program the circle center.

- ► To program a pole, press the **SPEC FCT** key.
- Press the PROGRAM FUNCTIONS soft key
- Press the DIN/ISO soft key
- Press the I or J soft key
- Coordinates: Enter Cartesian coordinates for the pole or, if you want to use the last programmed position, enter G29. Before programming polar coordinates, define the pole. You can only define the pole in Cartesian coordinates. The pole remains in effect until you define a new pole.

Example

SPEC FCT

N120 I+45 J+45*

Straight line in rapid traverse G10 or straight line with feed rate F G11

The tool moves in a straight line from its current position to the straight-line end point. The starting point is the end point of the preceding block.



Ρ

Polar coordinate radius R: Enter the distance from the pole CC to the straight-line end point.

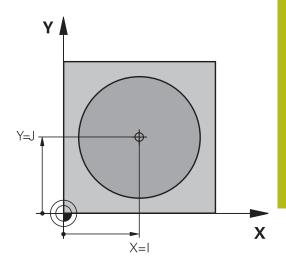
Polar coordinate angle H: Angular position of the straight-line end point between –360° and +360°

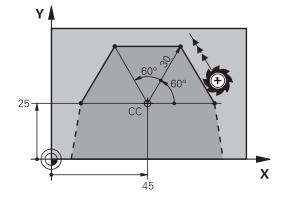
The sign of ${\bf H}$ depends on the angle reference axis:

- If the angle from the angle reference axis to R is counterclockwise: H>0
- If the angle from the angle reference axis to **R** is clockwise: **H**<0

Example

N120 I+45	J+45*
N130 G11	G42 R+30 H+0 F300 M3*
N140 H+60	*
N150 G91	H+60*
N160 G90	H+180*





275

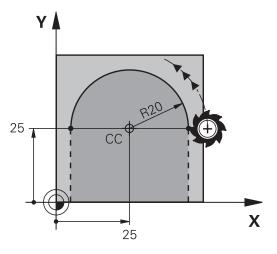
Circular path G12/G13/G15 around pole I, J

The polar coordinate radius **R** is also the radius of the arc. **R** is defined by the distance from the starting point to the pole **I**, **J**. The last programmed tool position will be the starting point of the arc.

Direction of rotation

- In clockwise direction: G12
- In counterclockwise direction: G13
- Without programmed direction: G15. The control traverses the circular arc with the last programmed direction of rotation.

Polar-coordinates angle H: Angular position of the arc end point between -99999.9999° and +99999.9999°



Example

C

Ρ

N180 I+25 J+25*
N190 G11 G42 R+20 H+0 F250 M3*
N200 G13 H+180*

Circle G16 with tangential connection

The tool moves on a circular path, starting tangentially from a preceding contour element.



Р

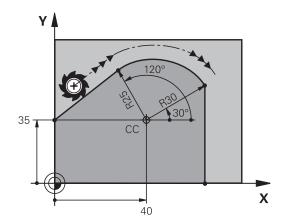
- Polar coordinate radius R: Distance between the arc end point and the pole I, J
- Polar coordinate angle H: Angular position of the arc end point.

6

The pole is **not** the center of the contour arc!

Example

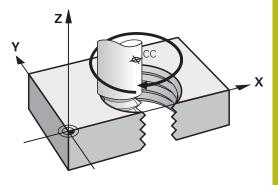
N120 I+40 J+35*
N130 G01 G42 X+0 Y+35 F250 M3*
N140 G11 R+25 H+120*
N150 G16 R+30 H+30*
N160 G01 Y+0*



Helix

A helix is a combination of a circular movement in a main plane and a linear movement perpendicular to this plane. You program the circular path in a main plane.

A helix is programmed only in polar coordinates.



Application

- Large-diameter internal and external threads
- Lubrication grooves

Calculating the helix

To program a helix, you must enter the total angle through which the tool is to move on the helix in incremental dimensions, and the total height of the helix.

Thread revolutions n:	Thread revolutions + overrun at start and end of thread
Total height h:	Thread pitch P times thread revolu- tions n
Incremental total angle G91 H:	Thread revolutions x 360° + angle for beginning of thread + angle for thread overrun
Starting coordinate Z:	Pitch P times (thread revolutions + thread overrun at start of thread)

Shape of the helix

The table below illustrates in which way the shape of the helix is determined by the work direction, direction of rotation and radius compensation.

Internal thread	Work direction	Direction of rotation	Radius compensation
Right-hand	Z+	G13	G41
Left-hand	Z+	G12	G42
Right-hand	Z–	G12	G42
Left-hand	Z–	G13	G41
External thread			
Right-hand	Z+	G13	G42
Left-hand	Z+	G12	G41
Right-hand	Z–	G12	G41
Left-hand	Z–	G13	G42

Programming a helix

Always enter the same algebraic sign for the direction of rotation and the incremental total angle **G91 h**. The tool may otherwise move in a wrong path and damage the contour.

For the total angle **G91 h** you can enter a value of -99 999.9999° to +99 999.9999°.

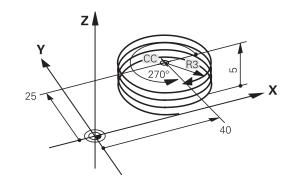
C P

i

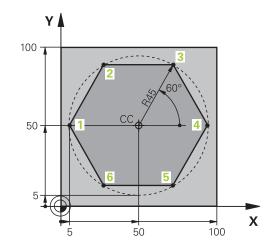
- Polar coordinates angle: Enter the total angle of tool traverse along the helix in incremental dimensions. After entering the angle, specify the tool axis with an axis selection key.
- **Coordinate**: Enter the coordinate for the height of the helix in incremental dimensions
- Enter the radius compensation according to the table

Example: Thread M6 x 1 mm with 5 revolutions

N120 I+40 J+25*
N130 G01 Z+0 F100 M3*
N140 G11 G41 R+3 H+270*
N150 G12 G91 H-1800 Z+5*

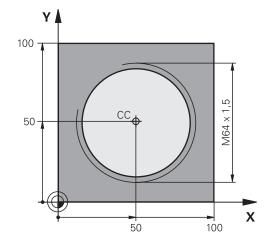


Example: Linear movement with polar coordinates



%LINEARPO G71 *	
N10 G30 G17 X+0 Y+0 Z-20*	Definition of workpiece blank
N20 G31 G90 X+100 Y+100 z+0*	
N30 T1 G17 S4000*	Tool call
N40 G00 G40 G90 Z+250*	Define the preset for polar coordinates
N50 I+50 J+50*	Retract the tool
N60 G10 R+60 H+180*	Pre-position the tool
N70 G01 Z-5 F1000 M3*	Move to working depth
N80 G11 G41 R+45 H+180 F250*	Approach the contour at point 1
N90 G26 R5*	Approach the contour at point 1
N100 H+120*	Move to point 2
N110 H+60*	Move to point 3
N120 H+0*	Move to point 4
N130 H-60*	Move to point 5
N140 H-120*	Move to point 6
N150 H+180*	Move to point 1
N160 G27 R5 F500*	Tangential exit
N170 G40 R+60 H+180 F1000*	Retract the tool in the working plane, cancel radius compensation
N180 G00 Z+250 M2*	Retract in the spindle axis, end of program
N99999999 %LINEARPO G71 *	

Example: Helix



%HELIX G71 *	
N10 G30 G17 X+0 Y+0 Z-20*	Definition of workpiece blank
N20 G31 G90 X+100 Y+100 Z+0*	
N30 T1 G17 S1400*	Tool call
N40 G00 G40 G90 Z+250*	Retract the tool
N50 X+50 Y+50*	Pre-position the tool
N60 G29*	Transfer the last programmed position as the pole
N70 G01 Z-12,75 F1000 M3*	Move to working depth
N80 G11 G41 R+32 H+180 F250*	Approach first contour point
N90 G26 R2*	Connection
N100 G13 G91 H+3240 Z+13,5 F200*	Helical traverse
N110 G27 R2 F500*	Tangential exit
N120 G01 G40 G90 X+50 Y+50 F1000*	Retract the tool, end program
N130 G00 Z+250 M2*	
N99999999 %HELIX G71 *	

6.6 Path contours – FK free contour programming

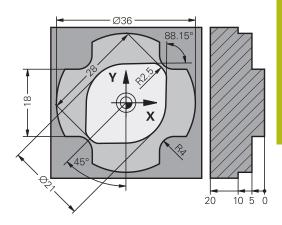
Fundamentals

Workpiece drawings that are not dimensioned for NC often contain unconventional coordinate data that cannot be entered with the gray dialog keys.

You can enter such dimensional data directly by using the free contour programming function FK, e.g.

- If there are known coordinates on or in the proximity of the contour element
- If coordinate data refers to another contour element
- If directional data and data regarding the course of the contour are known

The control derives the contour from the known coordinate data and supports the programming dialog with the interactive FK programming graphics. The figure at upper right shows a workpiece drawing for which FK programming is the most convenient programming method.



i)

Programming notes

The FK free contour programming feature can only be used for programming contour elements that lie in the working plane.

The working plane for FK programming is defined according to the following hierarchy:

- 1. Using the plane defined in an **FPOL** block
- 2. Using the working plane defined in the TOOL CALLT block (e.g. G17 = X/Y plane)
- 3. The standard X/Y plane is active if none of these applies

The display of the FK soft keys depends on the spindle axis in the workpiece blank definition. If for example you enter spindle axis **G17** in the workpiece blank definition, the control only shows FK soft keys for the X/Y plane.

You must enter all available data for every contour element. Even the data that does not change must be entered in every block—otherwise it will not be recognized.

Q parameters are permissible in all FK elements, except in elements with relative references (e.g. **RX** or **RAN**), or in elements that are referenced to other NC blocks.

If both FK blocks and conventional blocks are entered in a program, the FK contour must be fully defined before you can return to conventional programming.

The control needs a fixed point that it can use as the basis for all calculations. Use the gray path function keys to program a position that contains both coordinates of the working plane immediately before programming the FK contour. Do not enter any Q parameters in this block.

If the first block of an FK contour is an **FCT** or **FLT** block, you must program at least two NC blocks with the gray path function keys to fully define the direction of contour approach.

Do not program an FK contour immediately after an **L** command.

FK programming graphics

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If you wish to use graphic support during FK programming, select the **PROGRAM + GRAPHICS** screen layout.

Further information: "Programming", page 82

Incomplete coordinate data often is not sufficient to fully define a workpiece contour. In this case, the control indicates the possible solutions in the FK graphic. You can then select the contour that matches the drawing.

The control uses various colors in the FK graphics:

blue: uniquely specified contour element

The last FK element is only shown in blue after the departure movement.

- violet: not yet uniquely specified contour element
- ocher: tool midpoint path

►

- **red:** rapid traverse
- **green:** more than one solution is possible

If the data permit several possible solutions and the contour element is displayed in green, select the correct contour element as follows:



- Press the SHOW SOLUTION soft key repeatedly until the correct contour element is displayed.
 Use the zoom function if you cannot distinguish possible solutions in the standard setting
- SELECT SOLUTION

If the displayed contour element matches the drawing, select the contour element with **SELECT SOLUTION**

If you do not yet wish to select a green contour element, press the **START SINGLE** soft key to continue the FK dialog.



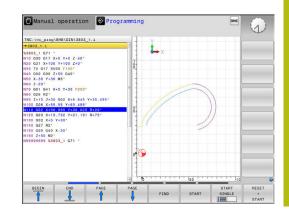
Select the green contour elements as soon as possible with the **SELECT SOLUTION** soft key. This way you can reduce the ambiguity of subsequent elements.

Showing block numbers in the graphic window

To show a block number in the graphic window:



 Set the SHOW OMIT BLOCK NR. soft key to SHOW (soft-key row 3)



Initiating the FK dialog

If you press the gray FK path function key, the control displays the soft keys you can use to initiate the FK dialog. Press the **FK** key a second time to deselect the soft keys.

If you initiate the FK dialog with one of these soft keys, the control shows additional soft-key rows that you can use for entering known coordinates, directional data and data regarding the course of the contour.

Soft key	FK element
FLT	Straight line with tangential connection
FL	Straight line without tangential connection
FCT	Circular arc with tangential connection
FC	Circular arc without tangential connection
FPOL	Pole for FK programming

Pole for FK programming



- ► To display the soft keys for free contour programming, press the **FK** key
- FPOL
- To initiate the dialog for defining the pole, press the **FPOL** soft key

The control displays the axis soft keys of the active working plane.

Enter the pole coordinates using these soft keys



The pole for FK programming remains active until you define a new one using FPOL.

Free straight line programming

Straight line without tangential connection

FK

- ► To display the soft keys for free contour programming, press the **FK** key
- FL
- To initiate the dialog for free programming of straight lines, press the FL soft key

The control displays additional soft keys.

 Enter all known data in the block by using these soft keys

The FK graphic displays the programmed contour element in violet until sufficient data is entered. If the entered data describes several solutions, the graphic will display the contour element in green.

Further information: "FK programming graphics", page 283

Straight line with tangential connection

If the straight line connects tangentially to another contour element, initiate the dialog with the soft key:



- To display the soft keys for free contour programming, press the FK key
- FLT
- ► To initiate the dialog, press the **FLT** soft key
- Enter all known data in the block by using the soft keys

Free circular path programming

Circular arc without tangential connection

FK

- To display the soft keys for free contour programming, press the FK key
- FC
- To initiate the dialog for free programming of circular arcs, press the FC soft key

The control displays soft keys with which you can enter direct data on the circular arc or data on the circle center.

 Enter all known data in the block by using these soft keys

The FK graphic displays the programmed contour element in violet until sufficient data is entered. If the entered data describes several solutions, the graphic will display the contour element in green.

Further information: "FK programming graphics", page 283

Circular arc with tangential connection

If the circular arc connects tangentially to another contour element, initiate the dialog with the **FCT** soft key:

	FK	
_		_

FCI

- ► To display the soft keys for free contour programming, press the **FK** key
- ► To initiate the dialog, press the **FCT** soft key
- Enter all known data in the block by using the soft keys

Input possibilities

End point coordinates

Soft keys	
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Cartesian coordinates X and Y

Polar coordinates referenced to FPOL

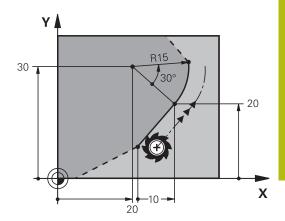
Known data

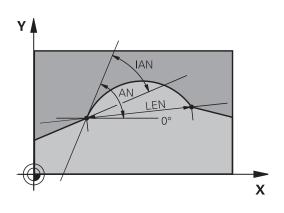


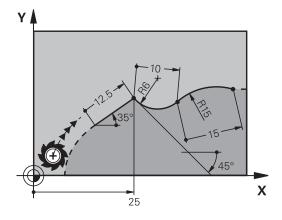
N70 FPOL X+20 Y+30* N80 FL IX+10 Y+20 G42 F100* N90 FCT PR+15 IPA+30 DR+ R15*

Direction and length of contour elements

Soft keys	Known data
LEN	Length of a straight line
AN	Gradient angle of a straight line
LEN	Chord length LEN of an arc
AN	Gradient angle AN of an entry tangent
CCA	Center angle of an arc







NOTICE

Danger of collision!

Incremental gradient angles **IAN** are referenced by the control to the direction of the previous traversing block. NC programs from previous control models (including iTNC 530) are not compatible. There is danger of collision during the execution of imported NC programs!

- Check the sequence and contour with the aid of the graphic simulation
- Adapt imported NC programs if required

Example

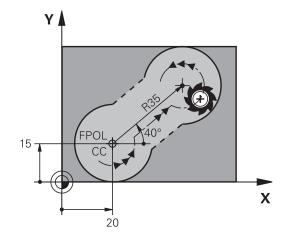
N20 FLT X+25 LEN 12.5 AN+35 G41 F200* N30 FC DR+ R6 LEN 10 AN-45* N40 FCT DR- R15 LEN 15*

Circle center CC, radius and direction of rotation in the FC/FCT block

The control calculates a circle center for free-programmed arcs from the data you enter. This makes it possible to program full circles in an FK program block.

If you wish to define the circle center in polar coordinates you must use FPOL, not **CC**, to define the pole. FPOL is entered in Cartesian coordinates and remains in effect until the control encounters a block in which another **FPOL** is defined.

A programmed or automatically calculated circle center or pole is effective only in connected conventional or FK sections. If an FK section splits up two conventionally programmed sections, the information about a circle center or pole will be lost. The two conventionally programmed sections must each have their own (if necessary, identical) CC blocks. Conversely, this information will also be lost if there is a conventional section between two FK sections.



Soft keys	Known data
	Circle center in Cartesian coordinates
PR +	Center point in polar coordinates
DR- DR+	Rotational direction of the arc
₹ R	Radius of an arc

Example

i

N10 FC CCX+20 CCY+15 DR+ R15*		
N20 FPOL X+20 Y+15*		
N30 FL AN+40*		
N40 FC DR+ R15 CCPR+35 CCPA+40*		

Closed contours

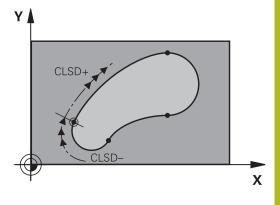
You can identify the beginning and end of a closed contour with the **CLSD** soft key. This reduces the number of possible solutions for the last contour element.

Enter **CLSD** as an addition to another contour data entry in the first and last blocks of an FK section.



Beginning of CLSD+ contour: End of contour: CLSD–

N10 G01 X+5 Y+35 G41 F500 M3*
N20 FC DR- R15 CLSD+ CCX+20 CCY+35*
N30 FCT DR- R+15 CLSD-*



6

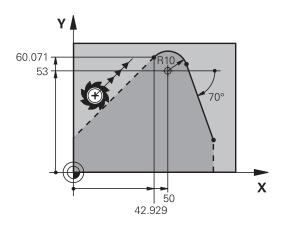
Auxiliary points

For both free-programmed straight lines and free-programmed circular arcs, you can enter the coordinates of auxiliary points that are located on the contour or in its proximity.

Auxiliary points on a contour

The auxiliary points are located on the straight line, the extension of the straight line, or on the circular arc.

5		Known data
PZX	X coordinate of an auxiliary point P1 or P2 of a straight line	
P2Y		Y coordinate of an auxiliary point P1 or P2 of a straight line
P2X	P3X	X coordinate of an auxiliary point P1, P2 or P3 of a circular path
P2Y	PSY	Y coordinate of an auxiliary point P1, P2 or P3 of a circular path
	PZX PZV	P2X P2Y P2Y P3X P3X P2X



Auxiliary points near a contour

Soft keys	5	Known data
PDX	PDV	X and Y coordinates of the auxil- iary point near a straight line
		Distance of auxiliary point to straight line
PDX	PDY	X and Y coordinates of an auxiliary point near a circular arc
		Distance of auxiliary point to circu- lar arc

N10 FC DR- R10 P1X+42.929 P1Y+60.071*	
N20 FLT AN-70 PDX+50 PDY+53 D10*	

Relative data

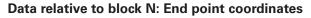
i

Relative data are values based on another contour element. The soft keys and program words for relative entries begin with the letter \mathbf{R} . The figure on the right shows the dimensional data that should be programmed as relative data.

The coordinates and angles for relative data are always programmed in incremental dimensions. You must also enter the block number of the contour element on which the data are based.

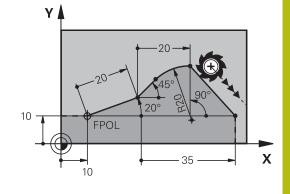
The block number of the contour element on which the relative data are based can only be located up to 64 positioning blocks before the block in which you program the reference.

If you delete a block on which relative data are based, the control will display an error message. Change the program first before you delete the block.



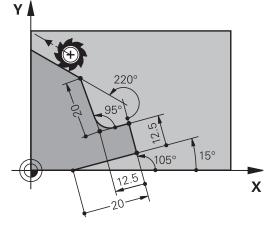
Soft keys	Known data
RX N	Cartesian coordinates relative to block N
RPR N	Polar coordinates relative to block N

N10 FPOL X+10 Y+10*	
N20 FL PR+20 PA+20*	
N30 FL AN+45*	
N40 FCT IX+20 DR- R20 CCA+90 RX 20*	
N50 FL IPR+35 PA+0 RPR 20*	



Data relative to block N: Direction and distance of the contour element

Soft key	Known data
RAN N	Angle between a straight line and another element or between the entry tangent of the arc and another element
PAR N	Straight line parallel to another contour element
DP	Distance from a straight line to a parallel contour element



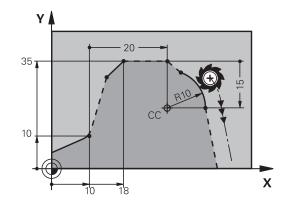
Example

N10 FL LEN 20 AN+15*
N20 FL AN+105 LEN 12.5*
N30 FL PAR 10 DP 12.5*
N40 FSELECT 2*
N50 FL LEN 20 IAN+95*
N60 FL IAN+220 RAN 20*

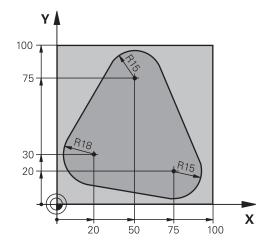
Data relative to block N: Circle center CC

Soft key		Known data
	RCCY N	Cartesian coordinates of the circle center relative to block N
RCCPR N	RCCPA N	Polar coordinates of the circle center relative to block N

N10 FL X+10 Y+10 G41*
N20 FL*
N30 FL X+18 Y+35*
N40 FL*
N50 FL*
N60 FC DR- R10 CCA+0 ICCX+20 ICCY-15 RCCX10 RCCY30*



Example: FK programming 1



%FK1 G71*	
N10 G30 G17 X+0 Y+0 Z-20*	Definition of workpiece blank
N20 G31 X+100 Y+100 Z+0*	
N30 T 1 G17 S500*	Tool call
N40 G00 G90 Z+250 G40 M3*	Retract the tool
N50 G00 X-20 Y+30 G40*	Pre-positioning the tool
N60 G01 Z-10 G40 F1000*	Move to working depth
N70 APPR CT X+2 Y+30 CCA90 R+5 G41 F250*	Approach the contour on a circular arc with tangential connection
N80 FC DR- R18 CLSD+ CCX+20 CCY+30*	FK contour section:
N90 FLT*	Program all known data for each contour element
N100 FCT DR- R15 CCX+50 CCY+75*	
N110 FLT*	
N120 FCT DR- R15 CCX+75 CCY+20*	
N130 FLT*	
N140 FCT DR- R18 CLSD- CCX+20 CCY+30*	
N150 DEP CT CCA90 R+5 F2000*	Depart the contour on a circular arc with tangential connection
N160 G00 X-30 Y+0*	
N170 G00 Z+250 M2*	Retract the tool, end program
N99999999 %FK1 G71 *	

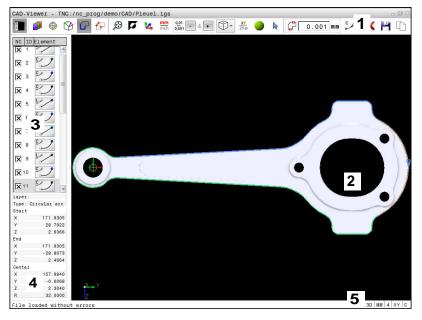
Data Transfer from CAD Files

7.1 Screen layout of the CAD viewer

Fundamentals of the CAD viewer

Screen display

When you open the **CAD-Viewer**, the following screen layout is displayed:



- 1 Menu bar
- 2 Graphics window
- 3 List View window
- 4 Window element information
- 5 Status bar

File formats

The **CAD-Viewer** enables you to open standardized CAD data formats directly on the control.

The control displays the following file formats:

File	Туре	Format
Step	.STP and .STEP	AP 203
		AP 214
IGES	.IGS and .IGES	Version 5.3
DXF	.DXF	R10 to 2015

7.2 CAD import (option 42)

Application

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If the control is set to ISO, the extracted contours or machining positions are nevertheless output as Klartext programs in .H conversational format.

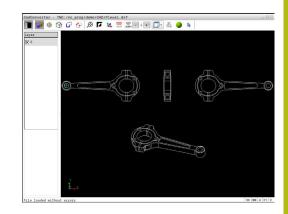
You can open CAD files directly on the control in order to extract contours or machining positions and save them as Klartext programs or as point files. Klartext programs acquired in this manner can also be run on older HEIDENHAIN controls, since these contour programs contain only **L** and **CC/C** blocks.

If you process files in **Programming** mode, the control generates contour programs with the file extension **.H** and point files with the extension **.PNT** by default. You can select the file type in the save dialog. To insert a selected contour or a selected machining position directly in an NC program, use the control's clipboard.



Operating notes:

- Before loading the file into the control, ensure that the name of the file contains only permitted characters. Further information: "File names", page 143
- The control does not support binary DXF format. Save the DXF file in ASCII format in the CAD or drawing program.



Using the CAD viewer

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To use the **CAD-Viewer**, you have to use a mouse or touchpad. All operating modes and functions as well as contours and machining positions can only be selected with the mouse or touch pad.

The **CAD-Viewer** runs as a separate application on the third desktop of the control. This enables you to use the screen switchover key to switch between the machine operating modes, the programming modes and the **CAD-Viewer**. This is particularly useful if you want to add contours or machining positions to a Klartext program by copy and paste using the clipboard.

Opening the CAD file



PGM MGT

- Press the Programming key
- ► To call the file manager, press the **PGM MGT** key



CAD

- In order to see the soft key menu for selecting the file types to be displayed, press the SELECT TYPE soft key
- To show all CAD files, press the SHOW CAD or SHOW ALL soft key
- Select the directory in which the CAD file is saved



Select the desired CAD file



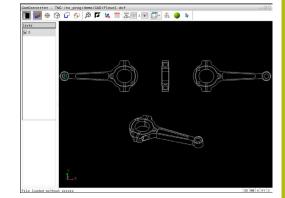
Press the ENT key

The control starts the **CAD-Viewer** and shows the file contents on the screen. The control displays the layers in the List View window and the drawing in the Graphics window.

Basic settings

The basic settings specified below are selected using the icons in the toolbar.

lcon	Setting
	Show or hide the Window List view to expand the Graphics window
1	Display of the various layers
٢	Set a preset
Ŷ	Set the datum
G	Select the contour
┎ ╋	Select hole positions
	Set the zoom to the largest possible view of the complete graphics
	Change the background color (black or white)
4	Switch between 2-D and 3-D mode. The active mode is color-highlighted
mm inch	Set the unit of measure, mm or inch , for the file. The control then outputs the contour program and the machining positions in this unit of measure. The active unit of measure is highlighted in red
0,01 0,001	Set resolution: The resolution specifies how many decimal places the control will use when generating the contour program. Default setting: 4 decimal places with mm and 5 decimal places with inch
	Switch between various view of the model e.g. Top
	Selection and deselection: The active + symbol is the same as the pressed Shift key, and the active - symbol is the same as the pressed CTRL key. The active cursor symbol is the same as the mouse



lcon	Setting
5	The most recent step is undone.
¢	Contour assumption mode: The tolerance specifies how far apart neighbor- ing contour elements may be from each other. You can use the tolerance to compensate for inaccuracies that occurred when the drawing was made. The default setting is 0.001 mm
C CR	Arc mode: Arc mode defines whether circular arcs are output in C format or CR format (e.g. for cylin- der surface interpolation) in the NC program.
W	Point assumption mode: Specify whether the control should display the tool path as a dashed line during selection of machining positions
∛ →†	Path optimization mode: The control optimizes the tool traverse movement to give the shortest traverse movements between the machining positions. Optimization is reset with repeated actuations
\bigcirc	Hole position mode: The control opens a pop-up window in which you can filter the holes by size
•	erating notes: Set the correct unit of measure, since the CAD file does not contain any such information. When generating NC programs for previous control models, you must limit the resolution to three decimal places. In addition, you must remove the comments that the CAD-Viewer inserts into the contour program. The control displays the active basic settings in the status bar of the screen.

Setting layers

CAD files usually contain several layers. The designer uses these layers to create groups of various types of elements, e.g. the actual workpiece contour, dimensions, auxiliary and design lines, shadings, and texts.

Hiding unneeded layers makes the graphics easier to read and facilitates the extraction of the required information.

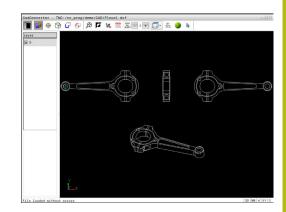


Operating notes:

- The CAD file to be processed must contain at least one layer. Elements not assigned to a layer are automatically moved by the control to the anonymous layer.
- You can even select a contour if the designer has saved the lines on different layers.



- Select the mode for the layer settings
 In the List View window the control shows all layers contained in the active CAD file
- Hide a layer: Select the layer with the left mouse button, and click its check box to hide it
- Alternatively, use the space key
- Show a layer: Select the layer with the left mouse button, and click its check box to show it
- Alternatively, use the space key



Setting a preset

The datum of the drawing in the CAD file is not always located in a manner that lets you use it directly as a workpiece preset. Therefore, the control has a function with which you can shift the workpiece preset to a suitable location by clicking an element. You can also define the orientation of the coordinate system.

You can define a preset at the following locations:

- At the beginning, end or center of a straight line
- At the beginning, center or end of a circular arc
- At the transition between quadrants or at the center of a complete circle
- At the intersection between:
 - A straight line and a straight line, even if the intersection is actually on the extension of one of the lines
 - Straight line circular arc
 - Straight line full circle
 - Circle circle (regardless of whether a circular arc or a full circle)



Operating notes:

- You can change the preset even after you have selected the contour. The control does not calculate the actual contour data until you save the selected contour in a contour program.
- The preset and optional orientation are inserted in the NC program as a comment starting with **origin**.

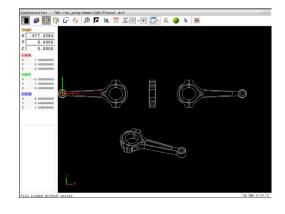
Selecting a preset on a single element

- Select the mode for specifying the preset
- Click the desired element with the mouse The control indicates possible locations for presets on the selected element with stars.
- Click the star you want to select as preset
- Use the zoom function if the selected element is too small

The control sets the preset symbol at the selected location.

You can adjust the orientation of the coordinate system, if required.

Further information: "Adjusting the orientation of the coordinate system", page 303



Selecting a preset on the intersection of two elements



- Select the mode for specifying the preset
- Click the first element (straight line, circle or circular arc) with the left mouse button The element is color-highlighted.
- Click the second element (straight line, circle or circular arc) with the left mouse button The control sets the preset symbol on the intersection.

You can adjust the orientation of the coordinate system, if required.

Further information: "Adjusting the orientation of the coordinate system", page 303



Operating notes:

- If there are several possible intersections, the control selects the intersection nearest the mouse-click on the second element.
- If two elements do not intersect directly, the control automatically calculates the intersection of their extensions.
- If the control cannot calculate an intersection, it deselects the previously selected element.

If a preset is set, the color of the \oplus "Setting a preset" icon changes.

You can delete a preset by pressing the \Re icon.

Adjusting the orientation of the coordinate system

The position of the coordinate system is defined by the orientation of the axes.



The preset has already been set

Left-click an element that is in the positive X direction

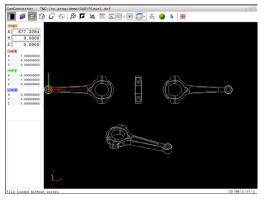
The control aligns the X axis and displays it in red in the list view.

Left-click an element that is approximately in the positive Y direction

The control aligns the Y and Z axes and displays them in green and blue in the list view.

Element Information

In the Element Information window, the control shows how far the preset you have chosen is located from the drawing datum, and how this reference system is oriented with respect to the drawing.



Defining the datum

The workpiece preset is not always located in a manner that lets you machine the entire part. Therefore, the control has a function with which you can define a new datum and a tilting operation. You can also define the orientation of the coordinate system.

The datum with the orientation of the coordinate system can be defined at the same positions as a preset.

Further information: "Setting a preset", page 302

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The datum and its optional orientation can be inserted as comments in the NC program by using the **TRANS DATUM AXIS** function for the datum and the **PLANE VECTOR** function for the orientation.

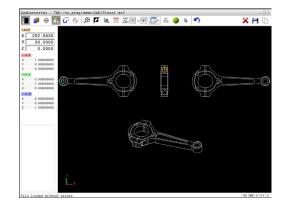
Selecting the datum on a single element

- Select the mode for specifying the datum
- Click the desired element with the mouse The control indicates possible locations for the datum on the selected element with stars.
- Click the star you want to select as datum
- Use the zoom function if the selected element is too small

The control sets the preset symbol at the selected location.

You can adjust the orientation of the coordinate system, if required.

Further information: "Adjusting the orientation of the coordinate system", page 305



Selecting a datum on the intersection of two elements





- Click the first element (straight line, circle or circular arc) with the left mouse button The element is color-highlighted.
- Click the second element (straight line, circle or circular arc) with the left mouse button
 The control sets the preset symbol on the intersection.

You can adjust the orientation of the coordinate system, if required.

Further information: "Adjusting the orientation of the coordinate system", page 305



Operating notes:

- If there are several possible intersections, the control selects the intersection nearest the mouse-click on the second element.
- If two elements do not intersect directly, the control automatically calculates the intersection of their extensions.
- If the control cannot calculate an intersection, it deselects the previously selected element.

When a datum has been set, the color of the datum setting icon $\$ changes.

You can delete a datum by pressing the X icon.

Adjusting the orientation of the coordinate system

The position of the coordinate system is defined by the orientation of the axes.



- The datum has already been set
- Left-click an element that is in the positive X direction

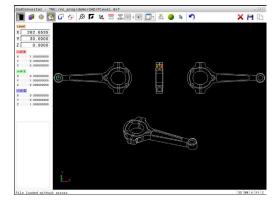
The control aligns the X axis and displays it in red in the list view.

 Left-click an element that is approximately in the positive Y direction

The control aligns the Y and Z axes and displays them in green and blue in the list view.

Element information

In the Element Information window, the control shows how far the datum you have chosen is located from the workpiece preset.



Selecting and saving a contour



Operating notes:

- Demo mode is active if option 42 is not enabled.
 You can select a maximum of 10 elements in demo mode.
- Specify the direction of rotation during contour selection so that it matches the desired machining direction.
- Select the first contour element such that approach without collision is possible.
- If the contour elements are very close to one another, use the zoom function.

The following elements are selectable as contours:

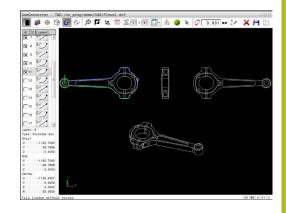
- Line segment
- Circle
- Circular arc
- Polyline

On curved elements, such as splines or ellipses, you can select the end points and center points. They can also be selected as part of contours and converted to polylines during export.

Element information

In the Element Information window the control displays a range of information about the last contour element you selected in the List View window or in the Graphics window.

- Layer: Indicates the layer you are currently on
- **Type**: Indicates the current element type, e.g. line
- **Coordinates**: Shows the starting point and end point of an element, and circle center and radius where appropriate



- Select the contour selection mode
 The Graphics window is active for the contour selection.
- To select a contour element, click the element with the mouse

The control displays the machining sequence as a dashed line.

- Position the mouse on the other side of the center point of an element to modify the machining sequence
- Select the element with the left mouse button

The selected contour element turns blue. If further contour elements in the selected machining sequence are selectable, the control highlights these elements in green. At junctions, the control chooses the element with the least deviation in direction.

 Click the last green element to add all elements to the contour program

The control shows all selected contour elements in the List View window. Elements that are still green are displayed without a check mark in the **NC** column. The control does not save these elements to the contour program.

- You can also add selected elements to the contour program by clicking them in the List View window
- If necessary you can also deselect elements that you already selected by clicking the element in the Graphics window again, but this time while pressing the CTRL key
- Alternative: Click the icon to deselect all selected elements
- Save the selected contour elements to the clipboard of the control so that you can then insert the contour in a Klartext program
- Alternative: Save the selected contour elements as a Klartext program

The control displays a pop-up window in which you can select the target directory, a file name, and the file type.

- Confirm the entry The control saves the contour program to the selected directory.
- If you want to select more contours, press the Cancel Selected Elements soft key and select the next contour as described above



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Operating notes:

- The control also transfers two workpiece-blank definitions (BLK FORM) to the contour program. The first definition contains the dimensions of the entire CAD file. The second one, which is the active one, contains only the selected contour elements, so that an optimized size of the workpiece blank results.
- The control only saves elements that have been selected (blue elements), which means that they have been given a check mark in the List View window.

Dividing, extending and shortening contour elements

Proceed as follows to modify contour elements:



- The Graphics window is active for the contour selection
- To select the starting point, select an element or the intersection between two elements (using the + icon)
- Select the next contour element by clicking it with the mouse

The control displays the machining sequence as a dashed line.

When the element is selected the control displays it in blue.

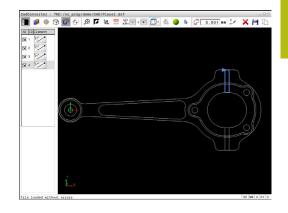
If the elements cannot be connected the control displays the selected element in gray.

If further contour elements in the selected machining sequence are selectable, the control highlights these elements in green. At junctions, the control chooses the element with the least deviation in direction.

- Click the last green element to add all elements to the contour program.
- A

Operating notes:

- You select the machining sequence of the contour with the first contour element.
- If the contour element to be extended or shortened is a straight line, then the control extends or shortens the contour element along the same line. If the contour element to be extended or shortened is a circular arc, then the control extends or shortens the contour element along the same arc.



Selecting and saving machining positions



Operating notes:

- Demo mode is active if option 42 is not enabled. You can select a maximum of 10 elements in demo mode.
- If the contour elements are very close to one another, use the zoom function.
- If required, configure the basic settings so that the control shows the tool paths. Further information: "Basic settings", page 299

Three possibilities are available in the pattern generator for defining machining positions:

- Single selection: You select the desired machining position through individual mouse clicks.
 Further information: "Single selection", page 311
- Rapid selection of hole positions with the mouse area: By dragging the mouse to define an area, you can select all the hole positions within this area.
 Further information: "Rapid selection of hole positions with the mouse area", page 312
- Rapid selection of hole positions via an icon: Click the icon and the control then displays all existing hole diameters.
 Further information: "Rapid selection of hole positions via icon", page 313

Selecting the file type

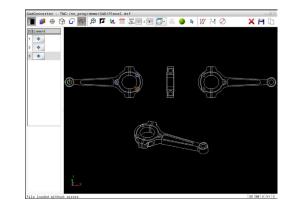
The following file types are available:

- Point table (.PNT)
- Klartext conversational language program (.H)

If you save the machining positions to a Klartext program, the control creates a separate linear block with cycle call for every machining position (L X... Y... Z... F MAX M99). You can also transfer this program to older TNC controls and run it there.



The point tables (.PNT) of the TNC 640 and iTNC 530 are not compatible. Transferring and processing on the other control type in each case may lead to problems and unforeseen performance.



Single selection



 Select the mode for choosing a machining position

The Graphics window is active for position selection.

 To select a machining position, click the element with the mouse

The control displays the element in orange.

If the shift key is pressed at the same time, the control indicates possible machining positions on the element with stars.

 If you click a circle, the control adopts the circle center as machining position

If the shift key is pressed at the same time, the control indicates possible machining positions with stars.

The control loads the selected position into the List View window (displays a point symbol).

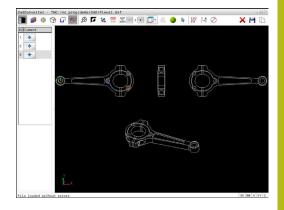
- If necessary you can also deselect elements that you already selected by clicking the element in the Graphics window again, but this time while pressing the CTRL key
- Alternative: Select the element in the List View window and press the **DEL** key
- Alternative: Click the icon to deselect all selected elements
- Save the selected machining positions to the clipboard of the control so that you can then insert them as a positioning block with cycle call in a Klartext program
- Alternative: Save the selected machining positions as a point file
 The control displays a pop-up window in which

you can select the target directory, a file name, and the file type.



 Confirm the entry The control saves the contour program to the selected directory.

 If you want to select more machining positions, press the Cancel Selected Elements icon and select as described above







Rapid selection of hole positions with the mouse area

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 Select the mode for choosing a machining position

The Graphics window is active for position selection.

 To select machining positions, press the shift key and define an area with the left mouse button
 All complete circles that are fully enclosed within the area are adopted as hole positions by the control.

The control opens a pop-up window in which you can filter the holes by size.

 Configure the filter settings and press the OK button to confirm
 Further information: "Filter settings",

page 314

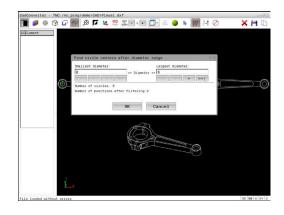
The control loads the selected positions into the List View window (displays a point symbol).

- If necessary you can also deselect elements that you already selected by clicking the element in the Graphics window again, but this time while pressing the CTRL key
- Alternative: Select the element in the List View window and press the **DEL** key
- Alternative: Deselect all elements by dragging an area open again, but this time while pressing the CTRL key
- Save the selected machining positions to the clipboard of the control so that you can then insert them as a positioning block with cycle call in a Klartext program
- Alternative: Save the selected machining positions as a point file

The control displays a pop-up window in which you can select the target directory, a file name, and the file type.



- Confirm the entry The control saves the contour program to the selected directory.
- If you want to select more machining positions, press the Cancel Selected Elements icon and select as described above



Rapid selection of hole positions via icon

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 Select the mode for choosing machining positions

The Graphics window is active for position selection.

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Select the icon The control opens a pop-up window in which you can filter the holes by size.

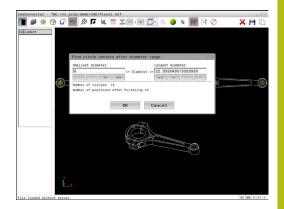
 Configure the filter settings if required and press the OK button to confirm
 Further information: "Filter settings", page 314

The control loads the selected positions into the List View window (displays a point symbol).

- If necessary you can also deselect elements that you already selected by clicking the element in the Graphics window again, but this time while pressing the CTRL key
- Alternative: Select the element in the List View window and press the **DEL** key
- Alternative: Click the icon to deselect all selected elements
- Save the selected machining positions to the clipboard of the control so that you can then insert them as a positioning block with cycle call in a Klartext program
- Alternative: Save the selected machining positions as a point file

The control displays a pop-up window in which you can select the target directory, a file name, and the file type.

- Confirm the entry The control saves the contour program to the selected directory.
- If you want to select more machining positions, press the Cancel Selected Elements icon and select as described above









Filter settings

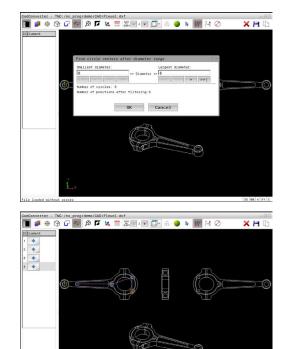
After you have used the quick selection function to mark hole positions, a pop-up window appears in which the smallest diameter found is to the left and the largest diameter to the right. With the buttons just below the diameter display you can adjust the diameter so that you can load the hole diameters that you want.

The following buttons are available:

lcon	Filter setting of smallest diameter
1<<	Display the smallest diameter found (default setting)
<	Display the next smaller diameter found
>	Display the next larger diameter found
>>	Display the largest diameter found. The control sets the filter for the smallest diameter to the value set for the largest diameter
lcon	Filter setting of largest diameter
<<	Display the smallest diameter found. The control sets the filter for the largest diameter to the value set for the smallest diameter
<	Display the next smaller diameter found
>	Display the next larger diameter found
>>1	Display the largest diameter found (default setting)

You can have the tool paths displayed by clicking the $\ensuremath{\textbf{SHOW TOOL}}$ $\ensuremath{\textbf{PATH}}$ icon.

Further information: "Basic settings", page 299



Element information

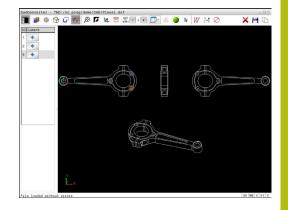
In the Element Information window, the control displays the coordinates of the machining position that you last selected in the List View window or Graphics window by clicking on the mouse.

You can also use the mouse to change the graphic display. The following functions are available:

- To rotate the model shown in three dimensions, hold down the right mouse button and move the mouse
- To shift the model shown, hold the center mouse button or mouse wheel down and move the mouse
- To zoom in on a certain area, mark a zoom area by holding the left mouse button down

After you release the left mouse button, the control zooms in on the defined area.

- To rapidly magnify or reduce any area, rotate the mouse wheel backwards or forwards
- To return to the standard display, press the shift key and simultaneously double-click with the right mouse button. The rotation angle is maintained if you only double-click with the right mouse button





Subprograms and Program Section Repeats

8.1 Labeling subprograms and program section repeats

Subprograms and program section repeats enable you to program a machining sequence once and then run it as often as necessary.

Label

The beginnings of subprograms and program section repeats are marked in a part program by labels (G98 L).

A LABEL is identified by a number between 1 and 65535 or by a name you define. Each LABEL number or LABEL name can be set only once in the program with the **LABEL SET** key or by entering **G98**. The number of label names you can enter is only limited by the internal memory.



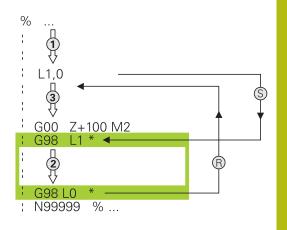
Do not use a label number or label name more than once!

Label 0 (**G98 L0**) is used exclusively to mark the end of a subprogram and can therefore be used as often as desired.

8.2 Subprograms

Operating sequence

- 1 The control executes the part program up to the **Ln,0** command for calling a subprogram
- 2 The subprogram is then executed until the subprogram end **G98 L0**
- 3 The control then resumes the part program from the block after the subprogram call **Ln,0**



Programming notes

- A main program can contain any number of subprograms
- You can call subprograms in any sequence and as often as desired
- A subprogram cannot call itself
- Write subprograms after the block with M2 or M30
- If subprograms are located before the block with M2 or M30 in the part program, they will be executed at least once even if they are not called

Programming the subprogram

- ► To mark the beginning: Press the LBL SET key
- Enter the subprogram number. If you want to use a label name, press the LBL NAME soft key to switch to text entry.
- Enter the text
- Mark the end: Press the LBL SET key and enter the label number 0

Calling a subprogram

LBL CALL

LBL SET

- Call a subprogram: Press the LBL CALL key
- Enter the subprogram number of the subprogram you wish to call. If you want to use a label name, press the LBL NAME soft key to switch to text entry.

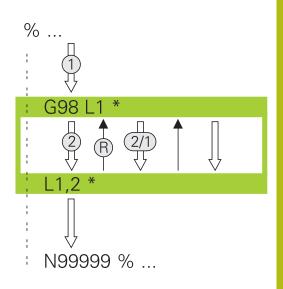
6

L 0 is not permitted (Label 0 is only used to mark the end of a subprogram).

8.3 Program-section repeats

Label G98

The beginning of a program section repeat is marked by the label **G98 L**. The end of a program section repeat is identified by **Ln,m**.



Operating sequence

- 1 The control executes the part program up to the end of the program section (**Ln**,**m**)
- 2 Then the program section between the called LABEL and the label call **Ln,m** is repeated the number of times entered after **m**
- 3 The control then continues with the part program

Programming notes

- You can repeat a program section up to 65 534 times in succession
- The total number of times the program section is executed is always one more than the programmed number of repeats, because the first repeat starts after the first machining process.

Programming a program section repeat

LBL SET

LBL

- To mark the beginning, press the LBL SET key and enter a LABEL NUMBER for the program section you wish to repeat. If you want to use a label name, press the LBL NAME soft key to switch to text entry.
- Enter the program section

Calling a program section repeat

- Call a program section: Press the **LBL CALL** key
- Enter the program section number of the program section to be repeated. If you want to use a LABEL name, press the LBL NAME soft key to switch to text entry
- Enter the number of repeats REP and confirm with the ENT key.

8.4 Any desired NC program as subprogram

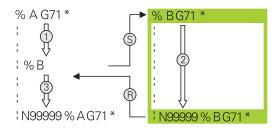
Overview of the soft keys

When you press the **PGM CALL** key, the control displays the following soft keys:

Soft key	Function
CALL PROGRAM	Call an NC program with %
SELECT DATUM TABLE	Select a datum table with %:TAB:
SELECT POINT TABLE	Select a point table with %:PAT:
SELECT CONTOUR	Select a contour program with %:CNT:
SELECT PROGRAM	Select an NC program with %:PGM:
CALL SELECTED PROGRAM	Call the last selected file with %<>%
SELECT CYCLE	Select any NC program with G: : as a fixed cycle Further information : Cycle Programming User's Manual

Operating sequence

- 1 The control executes the NC program up to the block in which another NC program is called with **%**.
- 2 Then the control executes the called NC program up to the end of program
- 3 The control then resumes executing the calling NC program with the block after the program call



Programming notes

- The control does not require any labels to call any part program
- The called NC program must not contain any % call into the calling NC program (an endless loop ensues)
- The called NC program must not contain the miscellaneous functions M2 or M30. If you have defined subprograms with labels in the called NC program, you can then replace M2 or M30 with the D09 P01 +0 P02 +0 P03 99 jump function

If the called NC program contains the miscellaneous functions **M2** or **M30**, then the control displays a warning. The control automatically clears the warning as soon as you select another NC program.

Calling any program as a subprogram

NOTICE

Danger of collision!

The control does not automatically check whether collisions can occur between the tool and the workpiece. If coordinate transformations are not specifically reset in called NC programs, then these transformation are likewise effective for the calling NC program. Danger of collision during machining!

- Reset coordinate transformations used in the same NC program
- Check the machining sequence using a graphic simulation if required

6

Programming notes:

- If the program you want to call is located in the same directory as the program you are calling it from, then you only need to enter the program name.
- If the program called is not located in the same directory as the calling program, you must enter the complete path, for example TNC:\ZW35\HERE \PGM1.H

Alternatively, you can program relative paths:

- Starting from the folder of the calling program one folder level up ... VPGM1.H
- Starting from the folder of the calling program one folder level down DOWN\PGM1.H
- Starting from the folder of the calling program one folder level up and in one other folder ...\THERE
 \PGM3.H
- If you want to call a DIN/ISO program, enter the file type .I after the program name.
- You can also call a program with Cycle **G39**.
- You can call any program by also using the function Select the cycle (G::).
- As a rule, Q parameters are effective globally with a program call with %. So please note that changes to Q parameters in the called program also influence the calling program.

Calling a program with Calling a program

The % function calls any program as a subprogram. The control runs the called program from the position where it was called in the program.



 To select the functions for program call, press the PGM CALL key

CALL PROGRAM

- Press the CALL PROGRAM soft key The control starts the dialog for defining the program to be called.
- Enter the path name with the keyboard

or



Press the SELECT FILE soft key The control shows a selection window that allows you to select the program to be called.

▶ Press the ENT key

Calling a program with SELECT PROGRAM and CALL SELECTED PROGRAM

Use the function **%:PGM** to select any program as a subprogram and call it at another position in the program. The control runs the called program from the position where it was called in the program with **%<>%**.

The **%:PGM:** function is also permitted with string parameters, so that you can dynamically control program calls.

To select the program, proceed as follows:



 To select the functions for program call, press the PGM CALL key



Press the SELECT PROGRAM soft key The control starts the dialog for defining the program to be called.



- Press the SELECT FILE soft key The control shows a selection window that allows you to select the program to be called.
- Press the ENT key

To call the selected program, proceed as follows:

- PGM CALL
- To select the functions for program call, press the PGM CALL key



Press the CALL SELECTED PROGRAM soft key With %<>%, the control calls the last program selected.

If an NC program that was called using %<>% is missing, then the control interrupts the execution or simulation with an error message. In order to avoid undesired interruptions during program run, all paths to the program beginning can be checked using the D18 function (ID10 NR110 and NR111) Further information: "D18 – Reading system data", page 363

8.5 Nesting

Types of nesting

- Subprogram calls in subprograms
- Program-section repeats within a program-section repeat
- Subprogram calls in program section repeats
- Program-section repeats in subprograms

Nesting depth

The nesting depth is the number of successive levels in which program sections or subprograms can call further program sections or subprograms.

- Maximum nesting depth for subprograms: 19
- Maximum nesting depth for main program calls: 19, where a G79 acts like a main program call
- You can nest program section repeats as often as desired

Subprogram within a subprogram

Example

%UPGMS G71 *	
N17 L "UP1",0*	Subprogram at label G98 L1 is called
N35 G00 G40 Z+100 M2*	Last program block of the
	main program with M2
N36 G98 L "UP1"	Beginning of subprogram SP1
N39 L2,0*	Subprogram at label G98 L2 is called
N45 G98 L0*	End of subprogram 1
N46 G98 L2*	Beginning of subprogram 2
N62 G98 L0*	End of subprogram 2
N99999999 %UPGMS G71 *	

Program execution

- 1 Main program UPGMS is executed up to block 17.
- 2 Subprogram SP1 is called, and executed up to block 39.
- 3 Subprogram 2 is called, and executed up to block 62. End of subprogram 2 and return jump to the subprogram from which it was called.
- 4 Subprogram 1 is called, and executed from block 40 up to block 45. End of subprogram 1 and return jump to the main program UPGMS.
- 5 Main program UPGMS is executed from block 18 up to block 35. Return jump to block 1 and end of program.

Repeating program section repeats

Example

%REPS G71 *	
N15 G98 L1*	Beginning of program section repeat 1
N20 G98 L2*	Beginning of program section repeat 2
N27 L2,2*	Program section call with two repeats
N35 L1,1*	Program section between this block and G98 L1
	(block N15) is repeated once
N99999999 %REPS G71 *	

Program execution

- 1 Main program REPS is executed up to block 27.
- 2 Program section between block 27 and block 20 is repeated twice.
- 3 Main program REPS is executed from block 28 to block 35.
- 4 Program section between block 35 and block 15 is repeated once (including the program section repeat between 20 and block 27).
- 5 Main program REPS is executed from block 36 to block 50. Return jump to block 1 and end of program.

Repeating a subprogram

Example

%UPGREP G71 *	
N10 G98 L1*	Beginning of program section repeat 1
N11 L2,0*	Subprogram call
N12 L1,2*	Program section call with two repeats
N19 G00 G40 Z+100 M2*	Last block of the main program with M2
N20 G98 L2*	Beginning of subprogram
N28 G98 L0*	End of subprogram
N99999999 %UPGREP G71 *	

Program execution

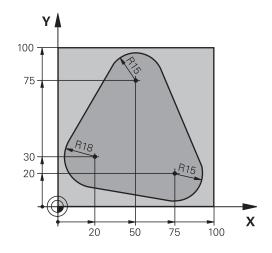
- 1 Main program UPGREP is executed up to block 11.
- 2 Subprogram 2 is called and executed.
- 3 Program section between block 12 and block 10 is repeated twice. This means that subprogram 2 is repeated twice.
- 4 Main program UPGREP is executed from block 13 up to block19. Return jump to block 1 and end of program.

8.6 Programming examples

Example: Milling a contour in several infeeds

Program run:

- Pre-position the tool to the workpiece surface
- Enter the infeed depth in incremental values
- Contour milling
- Repeat infeed and contour-milling

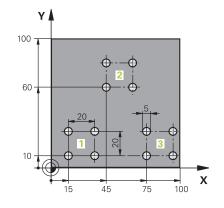


%PGMREP G71 *	
N10 G30 G17 X+0 Y+0 Z-40*	
N20 G31 G90 X+100 Y+100 Z+0*	
N30 T1 G17 S3500*	Tool call
N40 G00 G40 G90 Z+250*	Retract the tool
N50 I+50 J+50*	Set pole
N60 G10 R+60 H+180*	Pre-position in the working plane
N70 G01 Z+0 F1000 M3*	Pre-position to the workpiece surface
N80 G98 L1*	Set label for program section repeat
N90 G91 Z-4*	Infeed depth in incremental values (in space)
N100 G11 G41 G90 R+45 H+180 F250*	First contour point
N110 G26 R5*	Contour approach
N120 H+120*	
N130 H+60*	
N140 H+0*	
N150 H-60*	
N160 H-120*	
N170 H+180*	
N180 G27 R5 F500*	Contour departure
N190 G40 R+60 H+180 F1000*	Retract tool
N200 L1,4*	Return jump to label 1; section is repeated a total of 4 times
N200 G00 Z+250 M2*	Retract the tool, end program
N99999999 %PGMWDH G71 *	

Example: Groups of holes

Program run:

- Approach the groups of holes in the main program
- Call the group of holes (subprogram 1) in the main program
- Program the group of holes only once in subprogram
 1

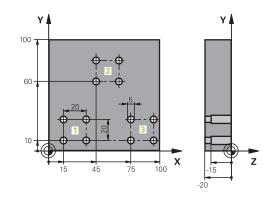


%SP1 G71 *		
N10 G30 G17 X+0 Y+	0 Z-40*	
N20 G31 G90 X+100 Y	Y+100 Z+0*	
N30 T1 G17 S3500*		Tool call
N40 G00 G40 G90 Z+	250*	Retract the tool
N50 G200 DRILLING		Define the DRILLING cycle
Q200=2	;SET-UP CLEARANCE	
Q201=-30	;DEPTH	
Q206=300	;FEED RATE FOR PLNGNG	
Q202=5	;PLUNGING DEPTH	
Q210=0	;DWELL TIME AT TOP	
Q203=+0	;SURFACE COORDINATE	
Q204=2	;2ND SET-UP CLEARANCE	
Q211=0	;DWELL TIME AT DEPTH	
Q395=0	;DEPTH REFERENCE	
N60 X+15 Y+10 M3*		Move to starting point for group 1
N70 L1,0*		Call the subprogram for the group
N80 X+45 Y+60*		Move to starting point for group 2
N90 L1,0*		Call the subprogram for the group
N100 X+75 Y+10*		Move to starting point for group 3
N110 L1,0*		Call the subprogram for the group
N120 G00 Z+250 M2*		End of main program
N130 G98 L1*		Beginning of subprogram 1: Group of holes
N140 G79*		Call cycle for 1st hole
N150 G91 X+20 M99*		Move to 2nd hole, call cycle
N160 Y+20 M99*		Move to 3rd hole, call cycle
N170 X-20 G90 M99*		Move to 4th hole, call cycle
N180 G98 L0*		End of subprogram 1
N99999999 %UP1 G7	1 *	

Example: Group of holes with several tools

Program run:

- Program the fixed cycles in the main program
- Call the complete hole pattern (subprogram 1) in the main program
- Approach the groups of holes (subprogram 2) in subprogram 1
- Program the group of holes only once in subprogram 2



%SP2 G71 *		
N10 G30 G17 X+0 Y	+0 Z-40*	
N20 G31 G90 X+100) Y+100 Z+0*	
N30 T1 G17 S5000*		Centering drill tool call
N40 G00 G40 G90 Z	+250*	Retract the tool
N50 G200 DRILLING	i	Define the CENTERING cycle
Q200=2	;SET-UP CLEARANCE	
Q201=-3	;DEPTH	
Q206=250	;FEED RATE FOR PLNGNG	
Q202=3	;PLUNGING DEPTH	
Q210=0	;DWELL TIME AT TOP	
Q203=+0	;SURFACE COORDINATE	
Q204=10	;2ND SET-UP CLEARANCE	
Q211=0.2	;DWELL TIME AT DEPTH	
Q395=0	;DEPTH REFERENCE	
N60 L1,0*		Call subprogram 1 for the entire hole pattern
N70 G00 Z+250 M6*		Tool change
N80 T2 G17 S4000*		Drill tool call
N90 D0 Q201 P01 -	25*	New depth for drilling
N100 D0 Q202 P01	+5*	New plunging depth for drilling
N110 L1,0*		Call subprogram 1 for the entire hole pattern
N120 G00 Z+250 M6	5*	Tool change
N130 T3 G17 S500*		Reamer tool call
N140 G201 REAMIN	G	Cycle definition: REAMING
Q200=2	;SET-UP CLEARANCE	
Q201=-15	;DEPTH	
Q206=250	;FEED RATE FOR PLNGNG	
Q211=0.5	;DWELL TIME AT DEPTH	
Q208=400	;RETRACTION FEED RATE	
Q203=+0	;SURFACE COORDINATE	
Q204=10	;2ND SET-UP CLEARANCE	
N150 L1,0*		Call subprogram 1 for the entire hole pattern

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N160 G00 Z+250 M2*	End of main program
N170 G98 L1*	Beginning of subprogram 1: Entire hole pattern
N180 G00 G40 G90 X+15 Y+10 M3*	Move to starting point for group 1
N190 L2,0*	Call subprogram 2 for the group
N200 X+45 Y+60*	Move to starting point for group 2
N210 L2,0*	Call subprogram 2 for the group
N220 X+75 Y+10*	Move to starting point for group 3
N230 L2,0*	Call subprogram 2 for the group
N240 G98 L0*	End of subprogram 1
N250 G98 L2*	Beginning of subprogram 2: Group of holes
N260 G79*	Call cycle for 1st hole
N270 G91 X+20 M99*	Move to 2nd hole, call cycle
N280 Y+20 M99*	Move to 3rd hole, call cycle
N290 X-20 G90 M99*	Move to 4th hole, call cycle
N300 G98 L0*	End of subprogram 2
N310 %UP2 G71 *	



Programming Q Parameters

9.1 Principle and overview of functions

With Q parameters you can program entire families of parts in a single NC program by programming variable Q parameters instead of fixed numerical values.

Use Q parameters for e.g.:

- Coordinate values
- Feed rates
- Spindle speeds
- Cycle data

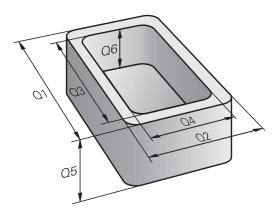
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With Q parameters you can also:

- Program contours that are defined through mathematical functions
- Make execution of machining steps depend on certain logical conditions

Q parameters are always identified with letters and numbers. The letters determine the type of Q parameter and the numbers the Q parameter range.

For more information, see the table below:



Q parameter type	Q parameter range	Meaning
Q parameters:		Parameters affect all NC programs in the control's memory
	0 – 99	Parameters for the user , if there are no overlaps with the HEIDENHAIN-SL cycles
	100 – 199	Parameters for special functions on the control that can be read by NC programs of the user or by cycles
	200 – 1199	Parameters primarily used for HEIDENHAIN cycles
	1200 – 1399	Parameters that are primarily used with manufacturer cycles when values are given back to the user program
	1400 – 1599	Parameters primarily used as input parameters for manufacturer cycles
	1600 – 1999	Parameters for users
QL parameters:		Parameters only effective locally within an NC program
	0 – 499	Parameters for users
QR parameters:		Parameters permanently (remanence) affect all NC programs in the control's memory, even after a power interruption
	0 to 99	Parameters for users
	100 to 199	Parameters for HEIDENHAIN functions (e.g., cycles)
	200 to 499	Parameters for the machine tool builder (e.g., cycles)

- -

QS parameters (the **S** stands for string) are also available on the control and enable you to process texts.

Q parameter type	Q parameter range	Meaning
QS parameters:		Parameters affect all NC programs in the control's memory
	0 – 99	Parameters for the user , where no overlaps with the HEIDENHAIN SL cycles are present
	100 – 199	Parameters for special functions on the control that can be read by NC programs of the user or by cycles
	200 – 1199	Parameters primarily used for HEIDENHAIN cycles
	1200 – 1399	Parameters that are primarily used with manufacturer cycles when values are given back to the user program
	1400 – 1599	Parameters primarily used as input parameters for manufacturer cycles
	1600 – 1999	Parameters for users

NOTICE

Danger of collision!

Q parameters are used in the HEIDENHAIN cycles, in machine tool builder cycles, and in supplier functions. You can also program Q parameters within the NC program. If, when using Q parameters, the recommended Q parameter ranges are not used exclusively, then this can lead to overlapping (reciprocal effects) and thus cause undesired behavior. Danger of collision during machining!

- Only use Q parameter ranges recommended by HEIDENHAIN.
- Comply with the documentation from HEIDENHAIN, the machine tool builder, and suppliers.
- Check the machining sequence using a graphic simulation

Programming notes

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You can mix $\ensuremath{\Omega}$ parameters and numerical values within an NC program.

Q parameters can be assigned numerical values between -999 999 999 and +999 999 999. The input range is limited to 16 digits, of which 9 may be before the decimal point. Internally the control calculates numbers up to a value of 10¹⁰.

You can assign a maximum of 255 characters to **QS** parameters.

The control automatically assigns some Q and QS parameters the same data, e.g., the Q parameter **Q108** is automatically assigned the current tool radius.

Further information: " Preassigned Q parameters", page 413

The control saves numerical values internally in a binary number format (standard IEEE 754). Due to the standardized format used, the control does not represent some decimal numbers with a binary number that is 100% exact (round-off error). If you use calculated Q parameter contents for jump commands or positioning moves, then you must take this fact into consideration.

You can reset Q parameters to the status **Undefined**. If a position is programmed with a Q parameter that is undefined, the control ignores this movement.

Calling Q parameter functions

When you are writing a part program, press the **Q** key (in the numeric keypad for numerical input and axis selection, below the +/- key). The control then displays the following soft keys:

Soft key	Function group	Page
BASIC ARITHM.	Basic arithmetic (assign, add, subtract, multiply, divide, square root)	343
TRIGO- NOMETRY	Trigonometric functions	346
JUMP	lf/then conditions, jumps	348
DIVERSE FUNCTION	Other functions	352
FORMULA	Entering formulas directly	396
CONTOUR FORMULA	Function for machining complex contours	See Cycle Program- ming User's Manual
If you define or assign a Q parameter, then the control shows the Q , QL and QR soft keys. You can use these soft keys to select the desired parameter type. Then you define the parameter number. If you have a USB keyboard connected, you can press the Q key to open the dialog for entering a formula.		

9.2 Part families—Q parameters in place of numerical values

Application

The Q parameter function **d0: ASSIGN** assigns numerical values to Q parameters. This enables you to use variables in the program instead of fixed numerical values.

Example

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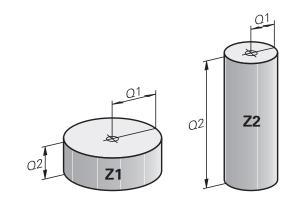
N150 D00 Q10 P01 +25*	Assign
	Q10 is assigned the value 25
N250 G00 X +Q10*	Corresponds to G00 X +25

You need write only one program for a whole family of parts, entering the characteristic dimensions as \mbox{Q} parameters.

To program a particular part, you then assign the appropriate values to the individual $\ensuremath{\Omega}$ parameters.

Example: Cylinder with Q parameters

Cylinder radius:	R = Q1
Cylinder height:	H = Q2
Cylinder Z1:	Q1 = +30 Q2 = +10
Cylinder Z2:	Q1 = +10 Q2 = +50



9.3 Describing contours with mathematical functions

Application

The Q parameters listed below enable you to program basic mathematical functions in a machining program:

- Select a Q parameter function: Press the Q key (in the numerical keypad on the right). The Q parameter functions are displayed in a soft key row
- To select the basic mathematical functions, press the BASIC ARITHM... soft key.

The control then displays the following soft keys:

Overview

Soft key	Function
D0 X = Y	D00 : ASSIGN e. g., D00 Q5 P01 +60 * Directly assign value Reset Q parameter value
D1 X + Y	D01 : ADDITION e. g., D01 Q1 P01 -Q2 P02 -5 * Calculate and assign the sum of two values
D2 X - Y	D02 : SUBTRACTION e. g. D02 Q1 P01 +10 P02 +5 * Form and assign difference between two values
D3 X * Y	D03 : MULTIPLICATION e. g. D03 Q2 P01 +3 P02 +3 * Form and assign the product of two values
D4 X / Y	D04 : DIVISION e.g., D04 Q4 P01 +8 P02 +Q2 * Calculate and assign the quotient of two values Not permitted: Division by 0
DS SORT	D05 : SQUARE ROOT e.g., D05 Q50 P01 4 * Calculate and assign the square root of a value Not permitted: Square root of a negative value

You can enter the following to the right of the = sign:

- Two numbers
- Two Q parameters
- A number and a Q parameter

The Q parameters and numerical values in the equations can be entered with positive or negative signs.

Programming fundamental operations

Example 1 Example N16 D00 Q5 P01 +10* N17 D03 Q12 P01 +Q5 P02 +7* Select the Q parameter function: Press the Q key Q ▶ To select the mathematical functions, press the BASIC BASIC ARITHM. soft key. ARITHM. Select the ASSIGN Q parameter function: Press FNe X = Y the **D0 X=Y** soft key PARAMETER NUMBER FOR RESULT? Enter 5 (the number of the Q parameter) and confirm with the ENT key FIRST VALUE / PARAMETER? Enter 10: Assign the numerical value 10 to Q5 ENT and confirm with the ENT key Example 2 Q



Select the Q parameter function: Press the Q key



- To select the mathematical functions, press the BASIC ARITHM. soft key.
- **FN3** Х * Ч
- ▶ To select the MULTIPLICATION Q parameter function, press the D3 X * Y soft key

PARAMETER NUMBER FOR RESULT?



Enter 12 (the number of the Q parameter) and confirm with the ENT key

FIRST VALUE / PARAMETER?

Enter Q5 as the first value and confirm with the ENT key.

SECOND VALUE / PARAMETER?



ENT

Enter 7 as the second value and confirm with the ENT key.

Example 3 – Reset Q parameters Example

16 D00: Q	5 SET UNDEFINED*	
17 D00: Q	17 D00: Q1 = Q5*	
Q	Select the Q parameter function: Press the Q key	
BASIC Arithm.	 To select the mathematical functions, press the BASIC ARITHM. soft key. 	
FNØ X = Y	Select the ASSIGN Q parameter function: Press the D0 X=Y soft key	
PARAMETER NUMBER FOR RESULT?		
ENT	Enter 5 (the number of the Q parameter) and confirm with the ENT key	

1. VALUE OR PARAMETER?

SET UNDEFINED

6

Press SET UNDEFINED

The **D00** function also supports transfer of the value **Undefined**. If you wish to transfer the undefined Q parameter without **D00**, the control shows the error message **Invalid value**.

9.4 Angle functions

Definitions

Sine:

 $\sin \alpha = a / c$ $\cos \alpha = b / c$

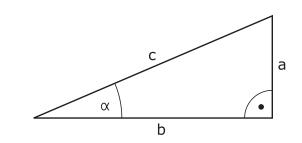
 $\tan \alpha = a / b = \sin \alpha / \cos \alpha$

where

Cosine:

Tangent:

- c is the side opposite the right angle
- \blacksquare a is the side opposite the angle α
- b is the third side.
- The control can find the angle from the tangent:
- α = arctan (a / b) = arctan (sin α / cos α)



Example:

 $\begin{array}{l} a=25 \text{ mm} \\ b=50 \text{ mm} \\ \alpha=\arctan\left(a\/\ b\right)=\arctan 0.5=26.57^\circ \\ \text{Furthermore:} \\ a^2+b^2=c^2 \ (\text{where } a^2=a\ x\ a) \\ c=\sqrt{\left(a^2+b^2\right)} \end{array}$

Programming trigonometric functions

Press the **TRIGONOMETRY** soft key to call the trigonometric functions. The control then displays the soft keys listed in the table below:

Soft key	Function
D6 SIN(X)	D06 : SINUS e. g., D06 Q20 P01 -Q5 * Calculate and assign the sine of an angle in degrees (°)
FN7 COS(X)	D07 : COSINE e. g., D07 Q21 P01 -Q5 * Calculate and assign the cosine of an angle in degrees (°)
D8 X LEN Y	D08 : ROOT SUM OF SQUARES e. g., D08 Q10 P01 +5 P02 +4 * Calculate and assign lengths from two values
D13 X ANG Y	D13 : ANGLE e.g., D13 Q20 P01 +10 P02 -Q1 * Calculate and assign an angle with the arc tangent from the opposite and adjacent sides or with the sine and cosine of the angle (0 < angle < 360°)

9.5 Calculation of circles

Application

The control can use the functions for calculating circles to calculate the circle center and the circle radius from three or four given points on the circle. The calculation is more accurate if four points are used.

Application: These functions can be used, for example, if you wish to determine the location and size of a hole or a pitch circle using the programmable probing function.

Soft key	Function
D23 3 POINTS OF CIRCLE	FN 23: Determining the CIRCLE DATA from three points e. g., D23 Q20 P01 Q30

The coordinate pairs of three points on a circle must be saved in Q30 and the following five parameters—in this case, up to Q35.

The control then saves the circle center in the reference axis (X if spindle axis is Z) in parameter Q20, the circle center in the minor axis (Y if spindle axis is Z) in parameter Q21, and the circle radius in parameter Q22.

Soft key	Function
D24 4 POINTS OF CIRCLE	FN 24: Determining the CIRCLE DATA from four points e. g., D24 Q20 P01 Q30

The coordinate pairs of four points on a circle must be saved in Q30 and the following seven parameters—in this case, up to Q37.

The control then saves the circle center in the reference axis (X if spindle axis is Z) in parameter Q20, the circle center in the minor axis (Y if spindle axis is Z) in parameter Q21, and the circle radius in parameter Q22.



Note that **D23** and **D24** automatically overwrite the resulting parameter and the two following parameters.

9.6 If-then decisions with Q parameters

Application

The control can make logical if-then decisions by comparing a Q parameter with another Q parameter or with a numerical value. If the condition is fulfilled, the control continues the program at the label that is programmed after the condition.

Further information: "Labeling subprograms and program section repeats", page 318

If it is not fulfilled, then the control executes the next block.

To call another program as a subprogram, enter a **%** program call after the block with the label.

Unconditional jumps

An unconditional jump is programmed by entering a conditional jump whose condition is always true. Example:

D09 P01 +10 P02 +10 P03 1 *

Programming if-then decisions

Possibilities for jump inputs

The following inputs are possible for the condition $\ensuremath{\mathsf{IF}}$:

- Numbers
- Texts
- Q, QL, QR
- **QS** (string parameter)

You have three possibilities for entering the jump address GOTO:

- LBL NAME
- LBL NUMBER
- QS

Press the **JUMP** soft key to call the if-then conditions. The control then displays the following soft keys:

Soft key	Function
D9 IF X EQ Y GOTO	D09 : IF EQUAL, JUMP e. g. D09 P01 +Q1 P02 +Q3 P03 "UPCAN25" * If both values or parameters are equal, jump to specified label
D9 IF X EQ Y GOTO IS UNDEFINED	D09: IF UNDEFINED, JUMP e.g., D09 P01 +Q1 IS UNDEFINED P03 "UPCAN25" * If the specified parameter is undefined, then a jump is made to the specified label
D9 IF X EQ Y GOTO	D09: IF DEFINED, JUMP e. g., D09 P01 +Q1 IS DEFINED P03 "UPCAN25" *
IS DEFINED	If the specified parameter is defined, then a jump is made to the specified label
D10 IF X NE Y GOTO	D10 : IF UNEQUAL, JUMP e. g. D10 P01 +10 P02 -Q5 P03 10 * If both values or parameters are unequal, jump to specified label
D11 IF X GT Y GOTO	D11 : IF GREATER, JUMP g. g. D11 P01 +Q1 P02 +10 P03 QS5 * If the first value or parameter is greater than the second value or parameter, jump to specified label
D12 IF X LT Y GOTO	D12 : IF LESS, JUMP e. g. D12 P01 +Q5 P02 +0 P03 "ANYNAME" * If the first value or parameter is smaller than the second value or parameter, jump to specified label

9.7 Checking and changing Q parameters

Procedure

You can check Q parameters in all operating modes, and also edit them.

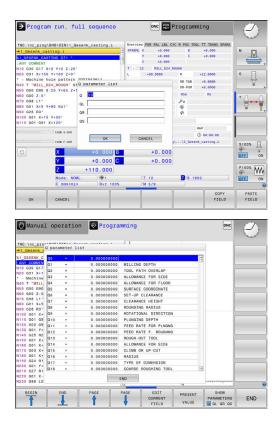
If you are in a program run, interrupt it if required (e.g., by pressing the NC STOPP key and the INTERNAL STOP soft key), or stop the test run



A

- To call the Q parameter functions, press the Q INFO soft key or the Q key The control lists all of the parameters and their
 - corresponding current values.
 Use the arrow keys or the GOTO key to select the desired parameter.
 - If you would like to change the value, press the EDIT CURRENT FIELD soft key. Enter a new file name and confirm with ENT
 - To leave the value unchanged, press the PRESENT VALUE soft key or end the dialog with the END key

All of the parameters with displayed comments are used by the control within cycles or as transfer parameters. If you want to check or edit local, global or string parameters, press the **SHOW PARAMETERS Q QL QR QS** soft key. The control then displays the specific parameter type. The functions previously described also apply.



You can have Q parameters also displayed in the additional status display in all operating modes (except **Programming** mode).

 If you are in a program run, interrupt it if required (e.g. by pressing the NC-STOPP key and the INTERNAL STOP soft key), or stop the test run



Call the soft key row for screen layout

- PROGRAM + STATUS
- Select the layout option for the additional status display

In the right half of the screen, the control shows the **Overview** status form.



Press the STATUS OF Q PARAM. soft key



- Press the Q PARAMETER LIST soft key.
 - The control opens a pop-up window.
- For each parameter type (Q, QL, QR, QS), define the parameter numbers you wish to control. Separate single Q parameters with a comma, and connect sequential Q parameters with a hyphen, e.g. 1,3,200-208. The input range per parameter type is 132 characters

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The display in the **QPARA** tab always contains eight decimal places. The result of Q1 = COS 89.999 is shown by the control as 0.00001745, for example. Very large or very small values are displayed by the control in exponential notation. The result of Q1 = COS 89.999 * 0.001 is shown by the control as +1.74532925e-08, whereby e-08 corresponds to the factor of 10^{-8} .

9.8 Additional functions

Overview

Press the **DIVERSE FUNCTION** soft key to call the additional functions. The control then displays the following soft keys:

Soft key	Function	Page
D14 ERROR=	D14 Display error messages	353
D16 F-PRINT	D16 Formatted output of texts or Q parameter values	357
D18 SYS-DATUM READ	D18 Read system data	363
D19 PLC=	D19 Transfer values to the PLC	392
D20 WAIT FOR	D20 NC and PLC synchronization	393
D26 OPEN THE TABLE	D26 Open a freely definable table	466
D27 WRITE TO TABLE	D27 Write to a freely definable table	467
D28 READ TABLE	D28 Read from a freely definable table	468
D29 PLC LIST=	D29 Transfer up to eight values to the PLC	394
D37 EXPORT	D37 Export local Q parameters or QS parameters into a calling program	395
D38 TRANSMIT	D38 Send information from the NC program	395

D14: Displaying error messages

With the **D14** error function, you can output error messages under program control. The messages are predefined by the machine tool builder or by HEIDENHAIN. If, during a program run or test run, the control encounters a block with **D14**, then the control will interrupt the program run or test run and display an error message. The program must then be restarted.

Error numbers area	Standard dialog
0 999	Machine-dependent dialog
1000 1199	Internal error messages

Example

The control is intended to display a message if the spindle is not switched on.

N180 D14 P01 1000*

Error message predefined by HEIDENHAIN

Error number	Text
1000	Spindle?
1001	Tool axis is missing
1002	Tool radius too small
1003	Tool radius too large
1004	Range exceeded
1005	Start position incorrect
1006	ROTATION not permitted
1007	SCALING FACTOR not permitted
1008	MIRROR IMAGE not permitted
1009	Datum shift not permitted
1010	Feed rate is missing
1011	Input value incorrect
1012	Incorrect sign
1013	Entered angle not permitted
1014	Touch point inaccessible
1015	Too many points
1016	Contradictory input
1017	CYCL incomplete
1018	Plane wrongly defined
1019	Wrong axis programmed
1020	Wrong rpm
1021	Radius comp. undefined

Error number	Text
1022	Rounding-off undefined
1023	Rounding radius too large
1024	Program start undefined
1025	Excessive nesting
1026	Angle reference missing
1027	No fixed cycle defined
1028	Slot width too small
1029	Pocket too small
1030	Q202 not defined
1031	Q205 not defined
1032	Q218 must be greater than Q219
1033	CYCL 210 not permitted
1034	CYCL 211 not permitted
1035	Q220 too large
1036	Q222 must be greater than Q223
1037	Q244 must be greater than 0
1038	Q245 must not equal Q246
1039	Angle range must be under 360°
1040	Q223 must be greater than Q222
1041	Q214: 0 not permitted
1042	Traverse direction not defined
1043	No datum table active
1044	Position error: center in axis 1
1045	Position error: center in axis 2
1046	Hole diameter too small
1047	Hole diameter too large
1048	Stud diameter too small
1049	Stud diameter too large
1050	Pocket too small: rework axis 1
1051	Pocket too small: rework axis 2
1052	Pocket too large: scrap axis 1
1053	Pocket too large: scrap axis 2
1054	Stud too small: scrap axis 1
1055	Stud too small: scrap axis 2
1056	Stud too large: rework axis 1
1057	Stud too large: rework axis 2

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Error number	Text
1058	TCHPROBE 425: length exceeds max
1059	TCHPROBE 425: length below min
1060	TCHPROBE 426: length exceeds max
1061	TCHPROBE 426: length below min
1062	TCHPROBE 430: diameter too large
1063	TCHPROBE 430: diameter too small
1064	No measuring axis defined
1065	Tool breakage tolerance exceeded
1066	Enter Q247 unequal to 0
1067	Enter Q247 greater than 5
1068	Datum table?
1069	Enter Q351 unequal to 0
1070	Thread depth too large
1071	Missing calibration data
1072	Tolerance exceeded
1073	Block scan active
1074	ORIENTATION not permitted
1075	3-D ROT not permitted
1076	Activate 3-D ROT
1077	Enter depth as negative
1078	Q303 in meas. cycle undefined!
1079	Tool axis not allowed
1080	Calculated values incorrect
1081	Contradictory meas. points
1082	Incorrect clearance height
1083	Contradictory plunge type
1084	This fixed cycle not allowed
1085	Line is write-protected
1086	Oversize greater than depth
1087	No point angle defined
1088	Contradictory data
1089	Slot position 0 not allowed
1090	Enter an infeed not equal to 0
1091	Switchover of Q399 not allowed
1092	Tool not defined
1093	Tool number not permitted

Error number	Text
1094	Tool name not permitted
1095	Software option not active
1096	Kinematics cannot be restored
1097	Function not permitted
1098	Contradictory workpc. blank dim.
1099	Measuring position not allowed
1100	Kinematic access not possible
1101	Meas. pos. not in traverse range
1102	Preset compensation not possible
1103	Tool radius too large
1104	Plunging type is not possible
1105	Plunge angle incorrectly defined
1106	Angular length is undefined
1107	Slot width is too large
1108	Scaling factors not equal
1109	Tool data inconsistent

D16 – Formatted output of texts and Q parameter values



With **D16**, you can output any messages from your NC program on the screen. The control displays such messages in a pop-up window.

Further information: "Displaying messages on the control's screen", page 361

With the function **D16**, you can save Q parameter values and output formatted texts (e.g. in order to save measurement reports). If you output the values, then the control saves the data in the file that you define in the **D16** block. The maximum size of the output file is 20 kB.

To be able to use the function **D16**, first program a text file that specifies the output format.

Available functions

Use the following formatting functions for creating a text file:

Special charac- ters	Function
""	Define output format for texts and variables between the quotation marks
%9.3F	Format for Q parameter:
	Define %: format
	 9.3: Total of 9 characters (incl. decimal point), of which 3 are decimal places
	 F: Floating (decimal number), format for Q, QL, QR
%+7.3F	Format for Q parameter:
	Define %: format
	+: number right-aligned
	 7.3: Total of 7 characters (incl. decimal point), of which 3 are decimal places
	 F: Floating (decimal number), format for Q, QL, QR
%S	Format for text variable QS
%D or %I	Format for integer
,	Separation character between output format and parameter
;	End of block character
\n	Line break
+	Q parameter value, right-aligned
_	Q parameter value, left-aligned

The following functions allow you to include the following additional information in the protocol log file:

Keyword	Function
CALL_PATH	Indicates the path for the NC program where you will find the FN16 function. Example: "Measuring program: %S",CAL- L_PATH;
M_CLOSE	Closes the file to which you are writing with FN16. Example: M_CLOSE;
M_APPEND	Upon renewed output, appends the log to the existing log. Example: M_APPEND;
M_AP- PEND_MAX	Upon renewed output, appends the log to the existing log until the maximum specified file size in kilobytes is exceeded. Example: M_APPEND_MAX20;
M_TRUNCATE	Overwrites the log upon renewed output. Example: M_TRUNCATE;
L_ENGLISH	Outputs text only for English conversational language
L_GERMAN	Outputs text only for German conversational language
L_CZECH	Outputs text only for Czech conversational language
L_FRENCH	Outputs text only for French conversational language
L_ITALIAN	Outputs text only for Italian conversational language
L_SPANISH	Outputs text only for Spanish conversational language
L_PORTUGUE	Outputs text only for Portuguese conversa- tional language
L_SWEDISH	Outputs text only for Swedish conversation- al language
L_DANISH	Outputs text only for Danish conversational language
L_FINNISH	Outputs text only for Finnish conversational language
L_DUTCH	Outputs text only for Dutch conversational language
L_POLISH	Outputs text only for Polish conversational language
L_HUNGARIA	Outputs text only for Hungarian conversa- tional language
L_CHINESE	Outputs text only for Chinese conversational language
L_CHINESE_TRAD	Outputs text only for Chinese (traditional) conversational language

Keyword	Function
L_SLOVENIAN	Outputs text only for Slovenian conversa- tional language
L_NORWEGIAN	Outputs text only for Norwegian conversa- tional language
L_ROMANIAN	Outputs text only for Romanian conversa- tional language
L_SLOVAK	Outputs text only for Slovakian conversation- al language
L_TURKISH	Outputs text only for Turkish conversational language
L_ALL	Display text independently of the conversa- tional language
HOUR	Number of hours from the real-time clock
MIN	Number of minutes from the real-time clock
SEC	Number of seconds from the real-time clock
DAY	Day from the real-time clock
MONTH	Month as a number from the real-time clock
STR_MONTH	Month as a string abbreviation from the real- time clock
YEAR2	Two-digit year from the real-time clock
YEAR4	Four-digit year from the real-time clock

Creating a text file

To output the formatted texts and Q-parameter values, create a text file with the control's text editor. In this file you then define the output format and Q parameters you want to output. Create this file with the extension .A.

Example of a text file to define the output format:

"MEASURING LOG OF IMPELLER CENTER OF GRAVITY";

"DATE: %02d.%02d.%04d",DAY,MONTH,YEAR4;

```
"TIME: %02d:%02d:%02d",HOUR,MIN,SEC;
```

"NO. OF MEASURED VALUES: = 1";

"X1 = %9.3F", Q31;

"Y1 = %9.3F", Q32;

"Z1 = %9.3F", Q33;

In the NC program, program D16 to activate the output:

Enter the path of the source and the path of the output file in the D16.

Specify the output file containing the output texts within the function **D16**. The control generates the output file at the end of program (**G71**), at program abortion (**NC-STOPP** key) or via **M_CLOSE** command.



If you only specify the file name as the path name of the log file, then the control saves the log file in the directory of the NC program with the **D16** function.

Program relative paths as an alternative to complete paths:

- Starting from the folder of the calling file one folder level down D16 P01 MASKE\MASKE1.A/ PROT \PROT1.TXT
- Starting from the folder of calling file one folder level up and in another folder D16 P01 ..\MASKE \MASKE1.A/ ..\PROT1.TXT

Example

N90 D16 P01 TNC:\MASK\MASK1.A/ TNC:\PROT1.TXT

The control then creates the file PROT1.TXT: MEASURING LOG OF IMPELLER CENTER OF GRAVITY DATE: July 15, 2015 TIME: 8:56:34 AM NO. OF MEASURED VALUES : = 1 X1 = 149.360 Y1 = 25.509 Z4 = 27.000

Z1 = 37.000

i

Operating and programming notes:

- If you output the same file multiple times in the program, then, within the target file, the control adds the current output after the previously output contents.
- In the **D16** block, program the format file and the log file with their respective file type extensions.
- The file name extension of the log file determines the file format of the output (e.g., TXT, .A, .XLS, .HTML).
- In machine parameters (no. 102202) and (no. 102203) you can define a default path for outputting log files.
- If you use **D16** the file must not be UTF8-encoded.
- You receive a great deal of relevant and interesting information for a log file by means of the function D18 (e.g., the number of the last touch probe cycle used).

Further information: "D18 – Reading system data", page 363

Displaying messages on the control's screen

You can also use the function **D16** to display any messages from the NC program in a pop-up window on the control's screen. This makes it easy to display explanatory texts, including long texts, at any point in the program in a way that the user has to react to them. You can also display Q-parameter contents if the protocol description file contains such instructions.

For the message to appear on the control's screen, you need only enter **screen:** as the name of the protocol file.

Example

N90 D16 P01 TNC:\MASK\MASK1.A/screen:

If the message has more lines than fit in the pop-up window, you can use the arrow keys to page in the window.

To close the pop-up window, press the **CE** key. To have the program close the window, program the following NC block:

Example

i

N90 D16 P01 TNC:\MASK\MASK1.A/SCLR:

If you output the same file multiple times in the program, then, within the target file, the control adds the current output after the previously output contents.

Exporting messages

The **D16** function also enables you to save the log files externally. Enter the complete target path in the **D16** function:

Example

N90 D16 P01 TNC:\MSK\MSK1.A / PC325:\LOG\PRO1.TXT

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If you output the same file multiple times in the program, then, within the target file, the control adds the current output after the previously output contents.

Entering the source or the target with parameters

You can enter the source file and the output file as Q parameters or as QS parameters. For this purpose you previously define the desired parameter in the NC program.

Further information: "Assign string parameters", page 401

In order for the control to recognize that you are working with Q parameters, enter them in the **D16** function with the following syntax:

Input	Function
:'QS1'	Set the QS parameter with preceding colon and between single quotation marks
:'QL3'.txt	Specify additional file name extension for the target file if required

Printing messages

You can also use the function **D16** to print any messages on a connected printer.

Further information: "Printer", page 96

In order for the messages to be sent to the printer, you must enter **Printer:** as the name of the log file and then enter the corresponding file name.

The control saves the file in the **PRINTER:** path until the file is printed.

Example

N90 D16 P01 TNC:\MASKE\MASKE1.A/PRINTER:\DRUCK1

D18 – Reading system data

With the **D18** function you can read system data and store them in Q parameters. The selection of the system datum occurs via a group number (ID no.), a system data number, and, if necessary, an index.



The read values of the function **D18** are always output by the control in **metric** units regardless of the NC program's unit of measure.

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The following is a complete list of the **D18** function. Please be aware that not all functions are available depending on the model of your control.

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Program i	nformation			
	10	3	-	Number of the active machining cycle
		6	-	Number of the most recently executed touch probe cycle -1 = None
		7	-	Type of calling NC program: -1 = None 0 = Visible NC program 1 = Cycle/macro, main program is visible 2 = Cycle/macro, there is no visible main program
		103	Q parameter number	Relevant within NC cycles; for inquiry as to whether the Q parameter given under IDX was explicitly stated in the associated CYCLE DEF.
		110	QS parameter number	Is there a file with the name QS(IDX)? 0 = No, 1 = Yes This function eliminates relative file paths.
		111	QS parameter number	Is there a directory with the name QS(IDX)? 0 = no, 1 = Yes Only absolute directory paths are possible.

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Branch ad	dresses of the sy	stem		
	13	1	-	Label jumped to during M2/M30 instead of ending the current program. Value = 0: M2/M30 have the normal effect
		2	-	Label jumped to in the event of FN14: ERROR with the NC CANCEL reaction instead of aborting the program with an error message. The error number programmed in the FN14 command can be read under ID992 NR14. Value = 0: FN14 has the normal effect.
		3	-	Label jumped to in the event of an inter- nal server error (SQL, PLC, CFG) or with erroneous file operations (FUNCTION FILECOPY, FUNCTION FILEMOVE, or FUNCTION FILEDELETE) instead of aborting the program with an error message. Value = 0: Error has the normal effect.
Machine s	status			
	20	1	-	Active tool number
		2	-	Prepared tool number
		3	-	Active tool axis 0 = X 6 = U 1 = Y 7 = V 2 = Z 8 = W
		4	-	Programmed spindle speed
		5	-	Active spindle condition -1 = spindle condition not defined 0 = M3 active 1 = M4 active 2 = M5 active after M3 3 = M5 active after M4
		7	-	Active gear range
		8	-	Active coolant status 0 = off, 1 = on
		9	-	Active feed rate
		10	-	Index of prepared tool
		11	-	Index of active tool
		14	-	Number of active spindle
		20	-	Programmed cutting speed in turning opera- tion
		21	-	Spindle mode in turning mode: 0 = constant speed 1 = constant cutting speed
		22	-	Coolant status M7: 0 = inactive, 1 = active

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		23	-	Coolant status M8: 0 = inactive, 1 = active
Channel d	lata			
	25	1	-	Channel number
Cycle para	ameters			
	30	1	-	Set-up clearance
		2	-	Hole depth / milling depth
		3	-	Plunging depth
		4	-	Feed rate for plunging
		5	-	First side length of pocket
		6	_	Second side length of pocket
		7	-	First side length of slot
		8	-	Second side length of slot
		9	-	Radius of circular pocket
		10	-	Feed rate for milling
		11	-	Rotational direction of the milling path
		12	-	Dwell time
		13	-	Thread pitch for Cycles 17 and 18
		14	_	Finishing allowance
		15	_	Roughing angle
		21	-	Probing angle
		22	-	Probing path
		23	-	Probing feed rate
		49	_	HSC mode (Cycle 32 Tolerance)
		50	-	Tolerance for rotary axes (Cycle 32 Tolerance
		52	Q parameter number	Type of transfer parameter for user cycles: -1: Cycle parameter not programmed in CYCL DEF 0: Cycle parameter numerically programmed in CYCL DEF (Q parameter) 1: Cycle parameter programmed as string in CYCL DEF (Q parameter)
		60	-	Clearance height (touch probe cycles 30 to 33)
		61	-	Inspection (touch probe cycles 30 to 33)
		62	-	Cutting edge measurement (touch probe cycles 30 to 33)
		63	-	Q parameter number for the result (touch probe cycles 30 to 33)
		64	-	Q parameter type for the result (touch probe cycles 30 to 33) 1 = Q, 2 = QL, 3 = QR

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		70	-	Multiplier for feed rate (cycles 17 and 18)
Vlodal sta	itus			
	35	1	-	Dimensions: 0 = absolute (G90) 1 = incremental (G91)
Data for S	QL tables			
	40	1	-	Result code for the last SQL command. If the last result code was 1 (=error), the error code is transferred as the return code.
Data from	the tool table			
	50	1	Tool no.	Tool length L
		2	Tool no.	Tool radius R
		3	Tool no.	Tool radius R2
		4	Tool no.	Oversize for tool length DL
		5	Tool no.	Tool radius oversize DR
		6	Tool no.	Tool radius oversize DR2
		7	Tool no.	Tool locked TL 0 = not locked, 1 = locked
		8	Tool no.	Number of the replacement tool RT
		9	Tool no.	Maximum tool age TIME1
		10	Tool no.	Maximum tool age TIME2
		11	Tool no.	Current tool age CUR.TIME
		12	Tool no.	PLC status
		13	Tool no.	Maximum tooth length LCUTS
		14	Tool no.	Maximum plunge angle ANGLE
		15	Tool no.	TT: Number of tool teeth CUT
		16	Tool no.	TT: Wear tolerance for length, LTOL
		17	Tool no.	TT: Wear tolerance for radius, RTOL
		18	Tool no.	TT: Direction of rotation DIRECT 0 = positive, -1 = negative
		19	Tool no.	TT: Offset in plane R-OFFS R = 99999.9999
		20	Tool no.	TT: Offset in length LOFFS
		21	Tool no.	TT: Breakage tolerance for length, LBREAK
		22	Tool no.	TT: Breakage tolerance for radius, RBREAK
		28	Tool no.	Maximum speed NMAX
		32	Tool no.	Point angle TANGLE
		34	Tool no.	LIFTOFF allowed $(0 = No, 1 = Yes)$
		35	Tool no.	Wear tolerance for radius R2TOL

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		36	Tool no.	Tool type TYPE (miller = 0, grinder = 1, touch probe = 21)
		37	Tool no.	Corresponding line in the touch-probe table
		38	Tool no.	Timestamp of last use
		40	Tool no.	Pitch for thread cycles
Data from	the pocket table			
	51	1	Pocket number	Tool number
		2	Pocket number	0 = no special tool 1 = special tool
		3	Pocket number	0 = no fixed pocket 1 = fixed pocket
		4	Pocket number	0 = pocket not locked 1 = pocket locked
		5	Pocket number	PLC status
Determine	e the tool pocket			
	52	1	Tool no.	Pocket number
		2	Tool no.	Tool magazine number
Fool data	for T and S strob	es		
	57	1	T code	Tool number IDX0 = T0 strobe (store tool), IDX1 = T1 strobe (load tool), IDX2 = T2 strobe (prepare tool)
		2	T code	Tool index IDX0 = T0 strobe (store tool), IDX1 = T1 strobe (load tool), IDX2 = T2 strobe (prepare tool)
		5	-	Spindle speed IDX0 = T0 strobe (store tool), IDX1 = T1 strobe (load tool), IDX2 = T2 strobe (prepare tool)
Values pro	ogrammed in TOC	DL CALL		
	60	1	-	Tool number T
		2	-	Active tool axis 0 = X 1 = Y 2 = Z 6 = U 7 = V 8 = W
		3	-	Spindle speed S
		4	_	Oversize for tool length DL
		5	_	Tool radius oversize DR
		6	-	Automatic TOOL CALL 0 = Yes, 1 = No
		7	-	Tool radius oversize DR2

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		8	-	Tool index
		9	-	Active feed rate
		10	-	Cutting speed [mm/min]
Values pro	ogrammed in TOC	DL DEF		
	61	0	Tool no.	Read the number of the tool change sequence: 0 = Tool already in spindle, 1 = Change between external tools, 2 = Change from internal to external tool, 3 = Change from special tool to external tool, 4 = Load external tool, 5 = Change from external to internal tool, 6 = Change from special tool to internal tool, 7 = Change from special tool to internal tool, 8 = Load internal tool, 9 = Change from external tool to special tool, 10 = Change from special tool to internal tool, 11 = Change from special tool to internal tool, 12 = Load special tool, 13 = Unload external tool, 14 = Unload internal tool, 15 = Unload special tool
		1	-	Tool number T
		2	-	Length
		3	-	Radius
		4	-	Index
		5	-	Tool data programmed in TOOL DEF 1 = Yes, 0 = No

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Values for	LAC and VSC			
	71	0	2	Total inertia determined by the LAC weighing run in [kgm²] (with A/B/C rotary axes) or total mass in [kg] (with X/Y/Z linear axes)
		1	0	Cycle 957 Retraction from thread
Freely ava	ilable memory ar	ea for OEM cycles		
	72	0-39	0 to 30	Freely available memory area for OEM cycles. The values are only reset by the control during a control reboot (= 0). With "Cancel," the values are not reset to the value that they had at the time of execu- tion. Up to and including 597110-11: only NR 0-9 and IDX 0-9 Starting with 597110-12: NR 0-39 and IDX 0-30
Freely ava	ilable memory ar	ea for user cycles		
	73	0-39	0 to 30	Freely available memory area for user cycles The values are only reset by the control during a control reboot (= 0). With "Cancel," the values are not reset to the value that they had at the time of execu- tion. Up to and including 597110-11: only NR 0-9 and IDX 0-9 Starting with 597110-12: NR 0-39 and IDX 0-30
Minimum	spindle speed			
	90	1	Spindle ID	Minimum spindle speed of the lowest gear range. If no gear ranges are configured, the spindle speed is taken from the parameter set with index 0. Index 99 = active spindle
Tool comp	pensation			
	200	1	1 = without oversize 2 = with oversize 3 = with oversize and oversize from TOOL CALL	Active radius
		2	1 = without oversize 2 = with oversize 3 = with oversize and oversize from TOOL CALL	Active length

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		3	1 = without oversize 2 = with oversize 3 = with oversize and oversize from TOOL CALL	Rounding radius R2
		6	Tool no.	Tool length Index 0= active tool
Coordinat	e transformations			
	210	1	-	Basic rotation (manual)
		2	-	Programmed rotation
		3	-	Active mirror axis. Bits 0 to 2 and 6 to 8: Axes X, Y, Z and U, V, W
		4	Axis	Active scaling factor Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
		5	Rotary axis	3D-ROT Index: 1 - 3 (A, B, C)
		6	-	Tilt working plane in Program Run operating modes 0 = Not active -1 = Active
		7	-	Tilt working plane in Manual operating modes 0 = Not active -1 = Active
		8	QL parameter no.	Angle of misalignment between spindle and tilted coordinate system. Projects the angle specified in the QL parameter from the input coordinate system to the tool coordinate system. If IDX is omitted, the angle 0 is used for projection.

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Active coo	ordinate system			
	211	-	-	1 = input system (default) 2 = REF system 3 = tool change system
Special tra	ansformations in t	turning mode		
	215	1	-	Angle for the precession of the input system in the XY plane in turning mode To reset the transformation the value 0 must be entered for the angle. This transformation is used in connection with Cycle 800 (parameter Q497)
		3	1-3	Reading out of the spatial angle written with NR2 Index: 1 - 3 (redA, redB, redC)
Current da	atum shift			
	220	2	Axis	Current datum shift in [mm] Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
		3	Axis	Read the difference between reference point and preset. Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
		4	Axis	Read values for OEM offset. Index: 1 - 9 (X_OFFS, Y_OFFS, Z_OFFS,)
Traverse ra	ange			
	230	2	Axis	Negative software limit switches Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
		3	Axis	Positive software limit switches Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
		5	-	Software limit switch on or off: 0 = on, 1 = off For modulo axes, either both the upper and lower limits or no limit at all must be set.
		12	Axis	Persistently overwrite the value for the negative software limit switch in CfgPosition- Limits. Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
		13	Axis	Persistently overwrite the value for the positive software limit switch in CfgPosition- Limits. Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
Read the r	nominal position	in the REF system		
	240	1	Axis	Current nominal position in the REF system
Read the r				fsets (handwheel, etc.)
	241	1	Axis	Current nominal position in the REF system
Read the o		n the active coordi		
	270	1	Axis	Current nominal position in the input system
	current position in			· · · ·

Read information to M128 280 1 - M128 active: -1 = Yes, 0 = No Machine kinematics 290 5 - 0: Temperature compensation not active 1: Temperature compensation active 290 5 - 0: Temperature compensation active 10 - Index of the machine kinematics from Channels/Channels/Ethnels programmed in FUNCTION MODE MILL or FUNCTION MODE TURN -1 = Not programmed. Read data of the machine kinematics 295 1 QS parameter no. Read the axis names of the active 3-axis kinematics. The axis names are written according to QS(IDX+2). 295 1 QS parameter no. Read the axis names of the active 3-axis kinematics. The axis names are written according to QS(IDX), QS(IDX+1), and QS(IDX+2). 2 0 Is FACING HEAD POS function active? 2 0 Is FACING HEAD POS function active? 2 0 Is FACING HEAD POS function active? 1 ×ss. 0 = No (A trotary axis can be excluded from the kinematics calculating using M138.) Index: 4.5 (14, R, B, C) 10 Axis ID Determine programmable axes. Determin the axis ID associated with the specified index (index from CfgAxis/axisList). Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W) 11 Axis ID Determine programmable axes. Dete	Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
280 1 - M128 active: -1 = Yes, 0 = No Machine kinematics 5 - 0: Temperature compensation not active 1: Temperature compensation active 290 5 - 0: Temperature compensation active 1: Temperature compensation active 10 - Index of the machine kinematics from Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels		271	1	Axis	Current nominal position in the input system
Machine kinematics -1 = Yes, 0 = No 290 5 - 0: Temperature compensation not active 1: Temperature compensation active 10 - Index of the machine kinematics from Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Channels/Chanels/Chanels/Channels/Chanels/Channels/Chanels/Channels/	Read infor	mation to M128			
290 5 - 0: Temperature compensation not active 1: Temperature compensation active 2: Temperature compensation activ		280	1	-	
1: Temperature compensation active 10 - Index of the machine kinematics from Channels/ChannelSettings/CfgKin- List/kinComposite/Models programmed in FUNCTION MODE TURN –1 = Not programmed. Read data of the machine kinematics 295 1 QS parameter no. Read the axis names of the active 3-axis kinematics. The axis names are written according to QS(IDX), QS(IDX+1), and QS(IDX), QS(IDX+1), and QS(IDX+2). 0 = Operation successful 2 0 Is FACING HEAD POS function active? 1 = Yes, 0 = No 4 Rotary axis Read whether the defined rotary axis par pates in the kinematic calculation 1 = Yes, 0 = No 4 Rotary axis Determine programmable axes. Determin the axis ID associated with the specified index (index from CfgAxis/axis.list). Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W) 11 Axis ID Determine programmable axes. Determin the index of the axis ID associated with the specified index (index from CfgAxis/axis.list). Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W) Modify the geometrical behavior 310 20 Axis Diameter programmable axes. Determin the index of the axis ID (index from CfgAxis/axis.list). Index: Axis ID (index from CfgAxis/axis.list). 320 1 0 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (lock-ahead ca lation). 32 - Read the processing time of the current	Machine k	inematics			
Channels/ChannelSettings/CfgKin- List/kinCompositeModels programmed in FUNCTION MODE WILL or FUNCTION MODE TURN –1 = Not programmed. Read data of the machine kinematics 295 1 QS parameter no. Read the axis names of the active 3-axis kinematics. The axis names are written according to QS(IDX, QS(IDX), 1), and QS(IDX, 2). 2 0 Is FACING HEAD POS function active? 1 = Yes, 0 = No 4 Rotary axis Read whether the defined rotary axis par pates in the kinematic calculation. 1 = Yes, 0 = No 4 Rotary axis Determine programmable axes. Determin the axis ID associated with the specified index: 4, 5, 6 (A, B, C) 10 Axis Determine programmable axes. Determin the axis ID associated with the specified index: 1 - 9 (X, Y, Z, A, B, C, U, V, W) 11 Axis ID Determine programmable axes. Determin the index of the axis (X = 1, Y = 2,) for specified axis ID Index: Axis ID (index from CfgAxis/axisList). Index: Axis ID (index from CfgAxis/axisList). Modify the geometrical behavior 310 20 Axis Diameter programming: -1 = on, 0 = off Gurrent system time 320 1 0 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (lock-ahead ca lation). 320 1 0 System time in seconds that has ela		290	5	-	
295 1 QS parameter no. Read the axis names of the active 3-axis kinematics. The axis names are written according to QS(IDX), QS(IDX+1), and QS(IDX+2). 0 Operation successful 2 0 Is FACING HEAD POS function active? 1 = Yes, 0 = No 4 Rotary axis Read whether the defined rotary axis par pates in the kinematic calculation. 1 = Yes, 0 = No 10 Axis Determine programmable axes. Determine the axis ID associated with the specified index: 4, 56 (A, B, C) 10 Axis Determine programmable axes. Determine the axis ID associated with the specified index index index if N (X, Y, Z, A, B, C, U, V, W) 11 Axis ID Determine programmable axes. Determine the dax of the axis (X = 1, Y = 2,) for specified axis ID index: Axis ID (index from CfgAxis/axisList). Index: Axis ID (index from CfgAxis/axisList). 310 20 Axis Diameter programming: -1 = on, 0 = off Current system time 320 1 0 System time in seconds that has elapsed since 010.11970, 00:00:00 (look-ahead ca lation). 32 - Read the processing time of the current I			10	-	Channels/ChannelSettings/CfgKin- List/kinCompositeModels programmed in FUNCTION MODE MILL or FUNCTION MODE TURN
no. kinematics. The axis names are written according to QS(IDX, QS(IDX+1), and QS(IDX+2), 0 = Operation successful 2 0 Is FACING HEAD POS function active? 1 = Yes, 0 = No 4 Rotary axis Read whether the defined rotary axis par pates in the kinematic calculation. 1 = Yes, 0 = No 4 Rotary axis Read whether the defined rotary axis par pates in the kinematic calculation. 1 = Yes, 0 = No 10 Axis Determine programmable axes. Determine the axis ID associated with the specified index (index from CfgAxis/axisList). Index: 1 - 9 (X, Y, Z, A, B, C, U, VW) 11 Axis ID Determine programmable axes. Determine the index of the axis ID associated with the specified axis ID index: Axis ID (index from CfgAxis/axisList). Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W) 11 Axis ID Determine programmable axes. Determine the index of the axis ID associated with the specified axis ID associated with the specified axis ID associated with the specified axis ID associated with the index of the axis ID associated with the specified axis ID associated with the index of the axis ID associated with the index of the axis ID associated with the index of the axis ID associated with the specified axis ID associated with the index of the axis ID associated with the index of the axis ID associated with the index of the axis ID associated	Read data	of the machine k	kinematics		
Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time 1 = Yes, 0 = No Image: Second System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calation). Image: Second System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calation). Image: Second System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calation). Image: Second System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calation). Image: Second System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calation). Image: Second System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calation). Imag		295	1	•	kinematics. The axis names are written according to QS(IDX), QS(IDX+1), and QS(IDX+2).
Pates in the kinematic calculation. 1 = Yes, 0 = No (A rotary axis can be excluded from the kinematics calculating using M138.) Index: 4, 5, 6 (A, B, C) 10 Axis Determine programmable axes. Determin the axis ID associated with the specified index (index from CfgAxis/axisList). Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W) 11 Axis ID Determine programmable axes. Determine the axis ID associated with the specified index (index from CfgAxis/axisList). Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W) 11 Axis ID Determine programmable axes. Determine the index of the axis (X = 1, Y = 2,) for specified axis ID index from CfgAxis/axisList Modify the geometrical behavior Index: Axis ID (index from CfgAxis/axisList) 310 20 Axis Biameter programming: -1 = on, 0 = off Index: Axis ID (index from CfgAxis/axisList) 320 1 0 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (real time). 1 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calation). Index: A since 01.01.1970, 00:00:00 (look-ahead calation). 3 - Read the processing time of the current I			2	0	
the axis ID associated with the specified index (index from CfgAxis/axisList). Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W) 11 Axis ID Determine programmable axes. Determine the index of the axis (X = 1, Y = 2,) for specified axis ID Index: Axis ID (index from CfgAxis/axisList) Modify the geometrical behavior Index: Axis ID (index from CfgAxis/axisList) 310 20 Axis Diameter programming: -1 = on, 0 = off Current system time 320 1 0 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (real time). 1 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead ca lation). 3 - Read the processing time of the current for the current for the second the			4	Rotary axis	1 = Yes, 0 = No (A rotary axis can be excluded from the kinematics calculating using M138.)
the index of the axis (X = 1, Y = 2,) for specified axis ID Index: Axis ID (index from CfgAxis/axisLis Modify the geometrical behavior Index: Axis ID (index from CfgAxis/axisLis 310 20 Axis Diameter programming: -1 = on, 0 = off Current system time 0 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (real time). 1 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calation). 3 - Read the processing time of the current Notes in the second structure of the current Notes in the			10	Axis	-
310 20 Axis Diameter programming: -1 = on, 0 = off Current system time 320 1 0 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (real time). 1 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead ca lation). 3 - Read the processing time of the current N			11	Axis ID	Determine programmable axes. Determine the index of the axis (X = 1, Y = 2,) for the specified axis ID Index: Axis ID (index from CfgAxis/axisList)
Current system time O System time in seconds that has elapsed since 01.01.1970, 00:00:00 (real time). 320 1 0 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (real time). 1 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead ca lation). 3 -	Modify the	e geometrical bel	havior		
320 1 0 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (real time). 1 System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead ca lation). 3 - Read the processing time of the current N		310	20	Axis	Diameter programming: $-1 = 0n, 0 = 0$ ff
since 01.01.1970, 00:00:00 (real time).1System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead ca lation).3-Read the processing time of the current N	Current sy	stem time			
3 - Read the processing time of the current N		320	1	0	System time in seconds that has elapsed since 01.01.1970, 00:00:00 (real time).
				1	System time in seconds that has elapsed since 01.01.1970, 00:00:00 (look-ahead calculation).
program.			3	-	Read the processing time of the current NC program.

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Formattin	g of system time			
	321	0	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: DD.MM.YYYY hh:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: DD.MM.YYYY hh:mm:ss
		1	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YYYY h:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YYYY h:mm:ss
		2	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YYYY h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YYYY h:mm
		3	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YY h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YY h:mm
		4	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: YYYY-MM-DD hh:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: YYYY-MM-DD hh:mm:ss
		5	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: YYYY-MM-DD hh:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: YYYY-MM-DD hh:mm

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		6	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: YYYY-MM-DD h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: YYYY-MM-DD h:mm
		7	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: YY-MM-DD h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: YY-MM-DD h:mm
		8	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: DD.MM.YYYY
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: DD.MM.YYYY
		9	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YYYY
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YYYY
		10	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: D.MM.YY
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: D.MM.YY
		11	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: YYYY-MM-DD
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: YYYY-MM-DD

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		12	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: YY-MM-DD
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: YY-MM-DD
		13	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: hh:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: hh:mm:ss
		14	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: h:mm:ss
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: h:mm:ss
		15	0	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (real time) Format: h:mm
			1	Formatting of: System time in seconds that have elapsed since 00:00:00 UTC on January 1, 1970 (look-ahead calculation) Format: h:mm

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Global Pro	ogram Settings (C	GPS): Global activa	tion status	
	330	0	-	0 = No GPS setting is active 1 = Any GPS setting is active
Global Pro	ogram Settings (C	GPS): Individual act	tivation status	6
	331	0	-	0 = No GPS setting is active 1 = Any GPS setting is active
		1	-	GPS: Basic rotation 0 = Off, 1 = On
		3	Axis	GPS: Mirroring 0 = Off, 1 = On Index: 1 - 6 (X, Y, Z, A, B, C)
		4	-	GPS: Shift in the modified workpiece system 0 = Off, 1 = On
		5	-	GPS: Rotation in input system 0 = Off, 1 = On
		6	-	GPS: Feed rate factor 0 = Off, 1 = On
		8	-	GPS: Handwheel superimpositioning 0 = Off, 1 = On
		10	-	GPS: Virtual tool axis VT 0 = Off, 1 = On
		15	-	 GPS: Selection of the handwheel coordinate system 0 = Machine coordinate system M-CS 1 = Workpiece coordinate system W-CS 2 = Modified workpiece coordinate system mW-CS 3 = Working plane coordinate system WPL-CS
		16	-	GPS: Shift in the workpiece system 0 = Off, 1 = On
		17	-	GPS: Axis offset 0 = Off, 1 = On

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Global Pro	ogram Settings (C	GPS)		
	332	1	-	GPS: Angle of a basic rotation
		3	Axis	GPS: Mirroring 0 = Not mirrored, 1 = Mirrored Index: 1 - 6 (X, Y, Z, A, B, C)
		4	Axis	GPS: Shift in the modified workpiece coordi- nate system mW-CS Index: 1 - 6 (X, Y, Z, A, B, C)
		5	-	GPS: Angle of rotation in input coordinate system I-CS
		6	-	GPS: Feed rate factor
		8	Axis	GPS: Handwheel superimpositioning Maximum value Index: 1 - 10 (X, Y, Z, A, B, C, U, V, W, VT)
		9	Axis	GPS: Value for handwheel superimpositioning Index: 1 - 10 (X, Y, Z, A, B, C, U, V, W, VT)
		16	Axis	GPS: Shift in the workpiece coordinate system W-CS Index: 1 - 3 (X, Y, Z)
		17	Axis	GPS: Axis offset Index: 4 - 6 (A, B, C)
FS touch	trigger probe			
	350	50	1	Touch probe type: 0: TS120, 1: TS220, 2: TS440, 3: TS630, 4: TS632, 5: TS640, 6: TS444, 7: TS740
			2	Line in the touch-probe table
		51	-	Effective length
		52	1	Effective radius of the stylus tip
			2	Rounding radius
		53	1	Center offset (reference axis)
			2	Center offset (minor axis)
		54	-	Spindle-orientation angle in degrees (center offset)
		55	1	Rapid traverse
			2	Measuring feed rate
			3	Feed rate for pre-positioning: FMAX_PROBE or FMAX_MACHINE
		56	1	Maximum measuring range
			2	Set-up clearance
		57	1	Spindle orientation possible 0=No, 1=Yes
			2	Angle of spindle orientation in degrees

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
TT tool to	uch probe for too	l measurement		
	350	70	1	TT: Touch probe type
			2	TT: Line in the tool touch probe table
		71	1/2/3	TT: Touch probe center (REF system)
		72	-	TT: Touch probe radius
		75	1	TT: Rapid traverse
			2	TT: Measuring feed rate with stationary spindle
			3	TT: Measuring feed rate with rotating spindle
		76	1	TT: Maximum probing path
			2	TT: Safety clearance for linear measurement
			3	TT: Safety clearance for radius measurement
			4	TT: Distance from the lower edge of the cutter to the upper edge of the stylus
		77	-	TT: Spindle speed
		78	-	TT: Probing direction
		79	-	TT: Activate radio transmission
		80	-	TT: Stop probing movement upon stylus
				deflection
reset fro	m touch probe cy	cle (probing result	s)	deflection
Preset fro	m touch probe cy 360	r cle (probing result 1	s) Coordinate	deflection Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (input coordi- nate system). Compensations: length, radius, and center offset
Preset fro				Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (input coordi- nate system). Compensations: length, radius, and center offset Last preset of a manual touch probe cycle, or
Preset fro		1	Coordinate	Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (input coordi- nate system). Compensations: length, radius, and center offset Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (machine coordi nate system, only axes from the active 3-D kinematics are allowed as index).
Preset fro		2	Coordinate Axis	Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (input coordi- nate system). Compensations: length, radius, and center offset Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (machine coordi- nate system, only axes from the active 3-D kinematics are allowed as index). Compensation: only center offset Result of measurement in the input system of touch probe Cycles 0 and 1. The measure- ment result is read out in the form of coordi-
Preset fro		1 2 3	Coordinate Axis Coordinate	 Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (input coordinate system). Compensations: length, radius, and center offset Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (machine coordinate system, only axes from the active 3-D kinematics are allowed as index). Compensation: only center offset Result of measurement in the input system of touch probe Cycles 0 and 1. The measurement result is read out in the form of coordinates. Compensation: only center offset Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (workpiece coordinate system) The measurement result is read in the form of coordinates.
Preset fro		1 2 3 4	Coordinate Axis Coordinate Coordinate	 Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (input coordinate system). Compensations: length, radius, and center offset Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (machine coordinate system, only axes from the active 3-D kinematics are allowed as index). Compensation: only center offset Result of measurement in the input system of touch probe Cycles 0 and 1. The measurement result is read out in the form of coordinates. Compensation: only center offset Last preset of a manual touch probe cycle, or last touch point from Cycle 0 (workpiece coordinate system) The measurement result is read in the form of coordinates. Compensation: only center offset

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Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		11	-	Error status of probing: 0: Probing was successful –1: Touch point not reached –2: Touch probe already deflected at the start of the probing process
Read valu	es from or write v	alues to the activ	e datum table	
	500	Row number	Column	Read values
Read valu	es from or write v	alues to the prese	et table (basic	transformation)
	507	Row number	1-6	Read values
Read axis	offsets from or w	rite axis offsets to	o the preset ta	ble
	508	Row number	1-9	Read values
Data for p	allet machining			
	510	1	-	Active line
		2	-	Pallet number from the PAL/PGM field
		3	-	Active row of the pallet table.
		4	-	Last line of the NC program for the current pallet.
		5	Axis	Tool-oriented editing: Clearance height is programmed: 0 = No, 1 = Yes Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
		6	Axis	Tool-oriented editing: Clearance height The value is invalid if ID510 NR5 returns the value 0 with the corresponding IDX. Index: 1 - 9 (X, Y, Z, A, B, C, U, V, W)
		10	-	Row number up to which the pallet table is to be searched during block scan.
		20	-	Type of pallet editing? 0 = Workpiece-oriented 1 = Tool oriented
		21	-	Automatic continuation after NC error: 0 = Locked 1 = Active 10 = Abort continuation 11 = Continuation with the rows in the pallet table that would have been executed next if not for the NC error 12 = Continuation with the row in the pallet table in which the NC error arose 13 = Continuation with the next pallet

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Read data	from the point t	able		
	520	Row number	1-3 X/Y/Z	Read value from active point table.
			10	Read value from active point table.
			11	Read value from active point table.
Read or w	rite the active pro	eset		
	530	1	-	Number of the active preset in the active preset table.
Active pa	llet preset			
	540	1	-	Number of the active pallet preset. Returns the number of the active preset. If no pallet preset is active, the function returns the value –1.
		2	-	Number of the active pallet preset. As with NR1.
Values for	the basic transfo	ormation of the pal	let preset	
	547	row number	Axis	Read values of the basic transformation from the pallet preset table. Index: 1 - 6 (X, Y, Z, SPA, SPB, SPC)
Axis offse	ts from the pallet	preset table		
	548	Row number	Offset	Read values of the axis offsets from the pallet preset table. Index: 1 - 9 (X_OFFS, Y_OFFS, Z_OFFS,)
OEM offse	et			
	558	Row number	Offset	Read values for OEM offset. Index: 1 - 9 (X_OFFS, Y_OFFS, Z_OFFS,)
Read and	write the machin	e status		
	590	2	1-30	Freely available; not deleted during program selection.
		3	1-30	Freely available; not deleted during a power failure (persistent storage).
Read/writ	te look-ahead par	ameter of a single	axis (at machi	ne level)
	610	1	-	Minimum feed rate (MP_minPathFeed) in mm/min
		2	-	Minimum feed rate at corners (MP_min- CornerFeed) in mm/min
		3	-	Feed-rate limit for high speeds (MP_maxG1Feed) in mm/min
		4	-	Max. jerk at low speeds (MP_maxPathJerk) in m/s ³
		5	-	Max. jerk at high speeds (MP_maxPath- JerkHi) in m/s ³
		6	-	Tolerance at low speeds (MP_pathTolerance in mm

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		7	-	Tolerance at high speeds (MP_pathToler- anceHi) in mm
		8	-	Max. derivative of jerk (MP_maxPathYank) in m/s ⁴
		9	-	Tolerance factor for curve machining (MP_curveTolFactor)
		10	-	Factor for max. permissible jerk at curvature changes (MP_curveJerkFactor)
		11	-	Maximum jerk with probing movements (MP_pathMeasJerk)
		12	-	Angle tolerance for machining feed rate (MP_angleTolerance)
		13	-	Angle tolerance for rapid traverse (MP_angle ToleranceHi)
		14	-	Max. corner angle for polygons (MP_max- PolyAngle)
		18	-	Radial acceleration with machining feed rate (MP_maxTransAcc)
		19	-	Radial acceleration with rapid traverse (MP_maxTransAccHi)
		20	Index of physi- cal axis	Max. feed rate (MP_maxFeed) in mm/min
		21	Index of physi- cal axis	Max. acceleration ($\ensuremath{\text{MP}}\xspace_\ensuremath{\text{maxAcceleration}}\xspace)$ in $\ensuremath{\text{m/s}}\xspace^2$
		22	Index of physi- cal axis	Maximum transition jerk of the axis in rapid traverse (MP_axTransJerkHi) in m/s ²
		23	Index of physi- cal axis	Maximum transition jerk of the axis during machining free rate (MP_axTransJerk) in m/s ³
		24	Index of physi- cal axis	Acceleration feedforward control (MP_com- pAcc)
		25	Index of physi- cal axis	Axis-specific jerk at low speeds (MP_axPath Jerk) in m/s ³
		26	Index of physi- cal axis	Axis-specific jerk at high speeds (MP_ax- PathJerkHi) in m/s ³
		27	Index of physi- cal axis	More precise tolerance examination in corners (MP_reduceCornerFeed) 0 = deactivated, 1 = activated
		28	Index of physi- cal axis	DCM: Maximum tolerance for linear axes in mm (MP_maxLinearTolerance)
		29	Index of physi- cal axis	DCM: Maximum angle tolerance in [°] (MP_maxAngleTolerance)
		30	Index of physi- cal axis	Tolerance monitoring for successive threads (MP_threadTolerance)

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		31	Index of physi- cal axis	Form (MP_shape) of the axisCutterLoc filter 0: Off 1: Average 2: Triangle 3: HSC 4: Advanced HSC
		32	Index of physi- cal axis	Frequency MP_frequency) of the axisCutter Loc filter in Hz
		33	Index of physi- cal axis	Form (MP_shape) of the axisPosition filter 0: Off 1: Average 2: Triangle 3: HSC 4: Advanced HSC
		34	Index of physi- cal axis	Frequency (MP_frequency) of the axisPosi- tion filter in Hz
		35	Index of physi- cal axis	Order of the filter for Manual operating mode (MP_manualFilterOrder)
		36	Index of physi- cal axis	HSC mode (MP_hscMode) of the axisCut- terLoc filter
		37	Index of physi- cal axis	HSC mode (MP_hscMode) of the axisPosi- tion filter
		38	Index of physi- cal axis	Axis-specific jerk for probing movements (MP_axMeasJerk)
		39	Index of physi- cal axis	Weighting of the filter error for calculating filter deviation (MP_axFilterErrWeight)
		40	Index of physi- cal axis	Maximum filter length of position filter (MP_maxHscOrder)
		41	Index of physi- cal axis	Maximum filter length of CLP filter (MP_maxHscOrder)
		42	-	Maximum feed rate of the axis at machining feed rate (MP_maxWorkFeed)
		43	-	Maximum path acceleration at machining feed rate (MP_maxPathAcc)
		44	-	Maximum path acceleration at rapid traverse (MP_maxPathAccHi)
		51	Index of physi- cal axis	Compensation of following error in the jerk phase (MP_IpcJerkFact)
		52	Index of physi- cal axis	kv factor of the position controller in 1/s (MP_kvFactor)

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Measure t	he maximum uti	lization of an axis		
	621	0	Index of physi- cal axis	Conclude measurement of the dynamic load and save the result in the specified Q parameter.
Read SIK o	contents			
	630	0	Option no.	You can explicitly determine whether the SIK option given under IDX has been set or not. 1 = option is enabled 0 = option is not enabled
		1	-	You can determine whether a Feature Content Level (for upgrade functions) is set, and which one. -1 = No FCL is set <no.> = FCL that is set</no.>
		2	-	Read serial number of the SIK -1 = No valid SIK in the system
		10	-	Define the type of control: 0 = iTNC 530 1 = NCK-based control (TNC 640, TNC 620, TNC 320, TNC 128, PNC 610,)
Norkpiece	e counter			
	920	1	-	Planned workpieces. In Test Run operating mode the counter generally generates the value 0.
		2	-	Already machined workpieces. In Test Run operating mode the counter generally generates the value 0.
		12	-	Workpieces still to be machined. In Test Run operating mode the counter generally generates the value 0.
Read and	write data of cur	rent tool		
	950	1	-	Tool length L
		2	-	Tool radius R
		3	-	Tool radius R2
		4	-	Oversize for tool length DL
		5	-	Tool radius oversize DR
		6	-	Tool radius oversize DR2
		7	-	Tool locked TL 0 = not locked, 1 = locked
		8	-	Number of the replacement tool RT
		9	-	Maximum tool age TIME1
		10	-	Maximum tool age TIME2 at TOOL CALL
		11	-	Current tool age CUR.TIME
		12	-	PLC status

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		13	-	Tooth length in the tool axis LCUTS
		14	-	Maximum plunge angle ANGLE
		15	-	TT: Number of tool teeth CUT
		16	-	TT: Wear tolerance for length LTOL
		17	-	TT: Wear tolerance for radius RTOL
		18	-	TT: Direction of rotation DIRECT 0 = positive, -1 = negative
		19	-	TT: Offset in plane R-OFFS R = 99999.9999
		20	-	TT: Offset in length L-OFFS
		21	-	TT: Break tolerance for length LBREAK
		22	-	TT: Break tolerance for radius RBREAK
		28	-	Maximum spindle speed [rpm] NMAX
		32	-	Point angle TANGLE
		34	-	LIFTOFF allowed $(0 = No, 1 = Yes)$
		35	-	Wear tolerance for radius R2TOL
		36	-	Tool type TYPE (miller = 0, grinder = 1, touch probe = 21)
		37	-	Corresponding line in the touch-probe table
		38	-	Timestamp of last use
		39	-	ACC
		40	-	Pitch for thread cycles
		44	-	Exceeding the tool life
reely ava	ilable memory ar	ea for tool manage	ement	
	956	0-9	-	Freely available data area for tool manage- ment. The data is not reset when the program is aborted.
ransform	ation data for ge	neral tools		
	960	1	-	Position within the tool system explicitly defined:
		2	-	Position defined by directions:
		3	-	Shift in X
		4	-	Shift in Y
		5		Shift in Z
		6	-	X component of the Z direction
		7	-	Y component of the Z direction
		8	-	Z component of the Z direction
		9	-	X component of the X direction
		10	_	Y component of the X direction

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		11	-	Z component of the X direction
		12	-	Type of angle definition:
		13	-	Angle 1
		14	-	Angle 2
		15	-	Angle 3

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Tool usage	and tooling			
	975	1	-	Tool usage test for the current program: Result –2: Test not possible, function disabled in the configuration Result –1: Test not possible, tool usage file missing Result 0: Test OK, all tools available Result 1: Test not OK
		2	Line	Check availability of the tools required in the pallet from line IDX in the current pallet table. -3 = No pallet is defined in row IDX, or function was called outside of pallet editing -2/-1/0/1 see NR1
Lift off the	tool at NC stop			
	980	3	-	 (This function is obsolete—HEIDENHAIN recommends not to use it any longer. ID980 NR3 = 1 is equivalent to ID980 NR1 = -1, ID980 NR3 = 0 has the same effect as ID980 NR1 = 0. Other values are not permissible.) Enable lift-off to the value defined in CfgLiftOff: 0 = Lock lift-off function 1 = Enable lift-off function
Touch prob	e cycles and coo	rdinate transform	ations	
	990	1	-	Approach behavior: 0 = Standard behavior 1 = Approach probing position without compensation Effective radius, set-up clear- ance is zero
		2	16	Automatic / Manual machine operating modes
		4	-	0 = Stylus not deflected 1 = Stylus deflected
		6	-	TT tool touch probe active? 1 = Yes 0 = No
		8	-	Momentary spindle angle in [°]
		10	ΩS parameter no.	Determine the tool number from the tool name. The return value depends on the rules configured for the search of the replacement tool. If there are multiple tools with the same name, the first tool from the tool table will be selected. If the tool selected by these rules is locked, a replacement tool will be returned. -1: No tool with the specified name found in

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		16	0	0 = Transfer control over the channel spindle to the PLC, 1 = Assume control over the channel spindle
			1	0 = Pass tool spindle control to the PLC, 1 = Take control of the tool spindle
		19	-	Suppress touch prove movement in cycles: 0 = Movement will be suppressed (CfgMa- chineSimul/simMode parameter not equal to FullOperation or Test Run operating mode is active) 1 = Movement will be performed (CfgMa- chineSimul/simMode parameter = FullOpera- tion, can be programmed for testing purpos- es)
Status of	execution			
	992	10	-	Block scan active 1 = yes, 0 = no
		11	-	 Block scan—information on block scan: 0 = Program started without block scan 1 = Iniprog system cycle is run before block scan 2 = Block scan is running 3 = Functions are being implemented -1 = Iniprog cycle was canceled before block scan -2 = Cancelation during block scan -3 = Cancelation of the block scan after the search phase, before or during the update of functions -99 = Implicit cancelation
		12	-	 Type of canceling for interrogation within the OEM_CANCEL macro: 0 = No cancellation 1 = Cancellation due to error or emergency stop 2 = Explicit cancellation with internal stop after stop in the middle of the block 3 = Explicit cancellation with internal stop after stop at the end of a block
		14	-	Number of the last FN14 error
		16	-	Real execution active? 1 = execution, 0 = simulation
		17	-	2-D graphics during programming active? 1 = yes 0 = no
		18	-	Generate graphics during programming (soft key AUTO DRAW) active? 1 = yes 0 = no

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
		20	-	Information on combined milling/turning mode of operation: 0 = Milling (after FUNCTION MODE MILL) 1 = Turning (after FUNCTION MODE TURN) 10 = Execute the operations for the turning- to-milling transition 11 = Execute the operations for the milling-to turning transition
		30	-	Interpolation of multiple axes permitted? 0 = No (e.g. for straight cut control) 1 = yes
		31	-	R+/R– possible/permitted in MDI mode? 0 = No 1 = Yes
		32	0	Cycle call possible/permitted? 0 = No 1 = Yes
			Cycle number	Single cycle enabled: 0 = No 1 = Yes
		40	-	Copy tables in Test Run operating mode? Value 1 will be set when a program is selected and when the RESET+START soft key is pressed. The iniprog.h system cycle will then copy the tables and reset the system datum. 0 = no 1 = yes
		101	-	M101 active (visible condition)? 0 = no 1 = yes
		136	-	M136 active? 0 = no 1 = yes

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Activate n	nachine paramete	er subfile		
	1020	13	QS parameter no.	Has a machine parameter subfile with path from QS number (IDX) been loaded? 1 = Yes 0 = No
Configura	tion settings for a	cycles		
	1030	1	-	Display spindle does not rotate error message? (CfgGeoCycle/displaySpindleErr) 0 = no, 1 = yes
			-	Check the algebraic sign for depth error message! display? (CfgGeoCycle/displayDepthErr) 0 = no, 1 = yes
Write or re	ead PLC data syn	chronously in real	time	
	2000	10	Marker no.	PLC markers General note for NR10 to NR80: The functions are executed synchronously in real time, i.e. the function is not executed until the corresponding point is reached in the program. HEIDENHAIN recommends using the WRITE TO PLC or READ FROM PLC commands instead of ID2000 and synchronizing the execution in real time by using FN20: WAIT FOR SYNC .
		20	Input no.	PLC input
		30	Output no.	PLC output
		40	Counter no.	PLC counter
		50	Timer no.	PLC timer
		60	Byte no.	PLC byte
		70	Word no.	PLC word
		80	Double-word no.	PLC double word

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Do not wri	ite or read PLC d	ata synchronously	in real time	
	2001	10-80	see ID 2000	Same as ID2000 NR10 to NR80, but not synchronous in real time. Function is execut- ed in the look-ahead calculation. HEIDENHAIN recommends using the WRITE TO PLC and READ FROM PLC commands instead of ID2001.
Bit test				
	2300	Number	Bit number	This function checks whether a bit has been set in a number. The number to be checked is transferred as NR, the bit to be searched for as IDX, with IDX0 designating the least significant bit. To call this function for great numbers, make sure to transfer NR as a Q parameter. 0 = Bit not set 1 = Bit set
Read prog	ram information	(system string)		
	10010	1	-	Path of the pallet subprogram, without subprogram calls using CALL PGM
		3	-	Path of the cycle selected with SEL CYCLE or CYCLE DEF 12 PGM CALL , or path of the currently active cycle
		10	-	Path of the NC program selected with SEL PGM "" .
Read chan	nel data (system	n string)		
	10025	1	-	Name of machining channel (key)
Read data	for SQL tables (system string)		
	10040	1	-	Symbolic name of the preset table.
		2	-	Symbolic name of the datum table.
		3	-	Symbolic name of the pallet preset table.
		10	-	Symbolic name of the tool table.
		11	-	Symbolic name of the pocket table.
Read mack	hine kinematics			
	10290	10	-	Symbolic name of the machine kinemat- ics from Channels/ChannelSettings/CfgKin- List/kinCompositeModels programmed in FUNCTION MODE MILL or FUNCTION MODE TURN.
Read data	of touch probes	(TS, TT) (system st	tring)	
	10350	50	-	TS probe type from TYPE column of the touch probe table (tchprobe.tp)
		70	-	Type of TT tool touch probe from CfgTT/type
		73	-	Key name of the active tool touch probe TT from CfgProbes/activeTT .

Group name	Gruppen- nummerID	Systemdaten- nummer	Index	Description
Read and	write data of tou	ch probes (TS, TT)	(system strin	ng)
	10350	74	-	Serial number of the active tool touch probe TT from CfgProbes/activeTT .
Read the	data for pallet pro	ocessing (system s	tring)	
	10510	1	-	Pallet name.
		2	-	Path of the selected pallet table.
Read vers	ion ID of the NC s	software (system s	tring)	
	10630	10	-	This string corresponds to the format of the version ID displayed, i.e. 340590 07 or 817601 04 SP1 .
Read data	of the current to	ol (system string)		
	10950	1	-	Current tool name.
Example: axis to Q2	-	of the active scalin	ig factor for t	he Z
N55 D18 C	25 ID210 NR4 IDX3	*		

D19 – Transfer values to the PLC

NOTICE

Danger of collision!

Changes to the PLC can result in undesired behavior and serious errors (e.g., inoperability of the control). For this reason, access to the PLC is protected by password. The FN function provides HEIDENHAIN as well as your machine tool builder and suppliers the ability to communicate with the PLC from an NC program. It is not recommended that the machine operator or NC programmer use this. There is risk of collision during the execution of the function and during the subsequent processing!

- Only use the function in consultation with HEIDENHAIN, the machine tool builder, or the supplier.
- Comply with the documentation from HEIDENHAIN, the machine tool builder, and suppliers.

The **D19** function transfers up to two numerical values or Q parameters to the PLC.

D20 – NC and PLC synchronization

NOTICE

Danger of collision!

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- Comply with the documentation from HEIDENHAIN, the machine tool builder, and suppliers.

With the **D20** function you can synchronize the NC and PLC during a program run. The NC stops machining until the condition that you have programmed in the **D20** block is fulfilled.

SYNC is used whenever you read, for example, system data via **D18** that require synchronization with real time. The control stops the look-ahead calculation and executes the following NC block only when the NC program has actually reached that block.

Example: Pause internal look-ahead calculation, read current position in the X axis

N32 D20 SYNC

N33 D18 Q1 ID270 NR1 IDX1*

D29 – Transfer values to the PLC

NOTICE

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- Only use the function in consultation with HEIDENHAIN, the machine tool builder, or the supplier.
- Comply with the documentation from HEIDENHAIN, the machine tool builder, and suppliers.

The **D29** function transfers up to eight numerical values or Q parameters to the PLC.

D37 - EXPORT

NOTICE

Danger of collision!

Changes to the PLC can result in undesired behavior and serious errors (e.g., inoperability of the control). For this reason, access to the PLC is protected by password. The FN function provides HEIDENHAIN as well as your machine tool builder and suppliers the ability to communicate with the PLC from an NC program. It is not recommended that the machine operator or NC programmer use this. There is risk of collision during the execution of the function and during the subsequent processing!

- Only use the function in consultation with HEIDENHAIN, the machine tool builder, or the supplier.
- Comply with the documentation from HEIDENHAIN, the machine tool builder, and suppliers.

You need the **D37** function if you want to create your own cycles and integrate them in the control.

D38 – Send information from NC program

The function **D38** enables you to write texts and Q parameter values to the log from the NC program and send to a DNC application.

Data transmission is through a standard TCP/IP computer network.



For more detailed information, consult the Remo Tools SDK manual.

Example

Document values from Q1 and Q23 in the log.

D38* /"Q parameter Q1: %f Q23: %f" P02 +Q1 P02 +Q23*

9.9 Entering formulas directly

Entering formulas

Using soft keys, you can enter mathematical formulas containing multiple calculation operations directly into the NC program.



Select Q-parameter functions

FORMULA

Press the FORMULA soft key

Select Q, QL, or QR

The control displays the following soft keys in several soft-key rows:

Soft key	Linking function
+	Addition e.g., Q10 = Q1 + Q5
-	Subtraction e.g., Q25 = Q7 - Q108
*	Multiplication e.g., Q12 = 5 * Q5
/	Division e.g., Q25 = Q1 / Q2
(Opening parenthesis e.g., Q12 = Q1 * (Q2 + Q3)
,	Closing parenthesis e.g., Q12 = Q1 * (Q2 + Q3)
sa	Square the value e.g., Q15 = SQ 5
SORT	Calculate square root e.g., Q22 = SQRT 25
SIN	Sine of an angle e.g., Q44 = SIN 45
COS	Cosine of an angle e.g., Q45 = COS 45
TAN	Tangent of an angle e.g., Q46 = TAN 45
ASIN	Arc sine Inverse function of the sine; determine the angle from the ratio of the opposite side to the hypotenuse e.g., Q10 = ASIN 0.75
ACOS	Arc cosine Inverse function of the cosine; determine the angle from the ratio of the adjacent side to the hypotenuse e.g., Q11 = ACOS Q40

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Soft key	Linking function
ATAN	Arc tangent Inverse function of the tangent; determine the angle from the ratio of the opposite side to the adjacent side e.g., Q12 = ATAN Q50
^	Powers of values e.g., Q15 = 3^3
PI	Constant PI (3,14159) e.g., Q15 = PI
LN	Calculate the natural logarithm of a number Base 2,7183 e.g., Q15 = LN Q11
LOG	Logarithm of a number, Base 10 e.g., Q33 = LOG Q22
EXP	Exponential function, 2.7183 to the power of n e.g., Q1 = EXP Q12
NEG	Negate values (multiply by -1) e.g., Q2 = NEG Q1
INT	Remove digits after the decimal point Calculate an integer e.g., Q3 = INT Q42
ABS	Absolute value of a number e.g., Q4 = ABS Q22
FRAC	Remove digits before the decimal point Calculate a fraction e.g., Q5 = FRAC Q23
SGN	Check algebraic sign of a number e.g., Q12 = SGN Q50 When return value Q12 = 0, then Q50 = 0 When return value Q12 = 1, then Q50 > 0 When return value Q12 = -1, then Q50 < 0
×	Calculate modulo value (division remainder) e.g., Q12 = 400 % 360 result: Q12 = 40

Rules for formulas

Mathematical formulas are programmed according to the following rules:

Higher-level operations are performed first Example

12 Q1 = 5 * 3 + 2 * 10 = 35

- 1 Calculation 5 * 3 = 15
- 2 Calculation 2 * 10 = 20
- 3 Calculation 15 + 20 = 35

or

Example

13 Q2 = SQ 10 - 3^3 = 73

- 1 Calculation step 10 squared = 100
- 2 Calculation step 3 to the third power = 27
- 3 Calculation 100 27 = 73

Distributive law

Law of distribution with parentheses calculation a * (b + c) = a * b + a * c

Example of entry

Calculate an angle with the arc tangent from the opposite side (Q12) and adjacent side (Q13); then store in Q25.



Select the formula entry function: Press the **Q** key and the **FORMULA** soft key, or use the shortcut



Press the Q key on the ASCII keyboard

Enter 25 (parameter number) and press the

Advance through the soft key menu and press

Shift the soft-key row and select the arc

the OPENING PARENTHESIS soft key

PARAMETER NUMBER FOR RESULT?

ENT key

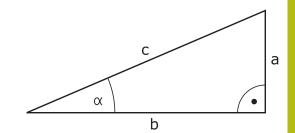
tangentfunction



- Enter **12** (Q parameter number)
- Select division
 - Enter 13 (Q parameter number)
 - Close parentheses and conclude formula entry

Example

N10 Q25 = ATAN (Q12/Q13)



9.10 String parameters

String processing functions

You can use the **QS** parameters to create variable character strings. You can output such character strings for example through the **D16** function to create variable logs.

You can assign a linear sequence of characters (letters, numbers, special characters and spaces) up to a length of 255 characters to a string parameter. You can also check and process the assigned or imported values using the functions described below. As in Q parameter programming, you can use a total of 2000 QS parameters.

Further information: "Principle and overview of functions", page 338

The **STRING FORMULA** and **FORMULA** Q parameter functions contain various functions for processing the string parameters.

Soft key	Functions of the STRING FORMULA	Page
STRING	Assigning string parameters	401
CFGREAD	Read out machine parameter	410
	Chain-linking string parameters	401
TOCHAR	Converting a numerical value to a string parameter	403
SUBSTR	Copy a substring from a string parameter	404
SYSSTR	Read system data	405
Soft key	Formula string functions	Page
TONUMB	Converting a string parameter to a numerical value	406
TONUMB	5 5 I	406 407
	numerical value	
INSTR	numerical value Checking a string parameter Finding the length of a string parame-	407

Assign string parameters

Before using string variables, you must first assign the variables. Use the **DECLARE STRING** command to do so.

- SPEC FCT
- Press the SPEC FCT key



- Press the PROGRAM FUNCTIONS soft key
- STRING Press
 - Press the STRING FUNCTIONS soft key



Press the DECLARE STRING soft key

Example

N30 DECLARE character string QS10 = "Workpiece"

Chain-linking string parameters

With the concatenation operator (string parameter || string parameter) you can make a chain of two or more string parameters.

- SPEC FCT PROGRAM FUNCTIONS STRING FUNCTIONS STRING FORMULA
- Press the PROGRAM FUNCTIONS soft key

Press the SPEC FCT key

- Press the STRING FUNCTIONS soft key
- Press the STRING FORMULA soft key
 - Enter the number of the string parameter in which the control is to save the concatenated
 - string. Confirm with the **ENT** key.
 - Enter the number of the string parameter in which the **first** substring is saved. Confirm with the **ENT** key

The control shows the concatenation symbol $\left| \; \right|$ an.

- Press the ENT key
- Enter the number of the string parameter in which the second substring is saved. Confirm with the ENT key
- Repeat the process until you have selected all the required substrings. Conclude with the END key

Example: QS10 is to include the complete text of QS12, QS13 and QS14 $\,$

N37 QS10 = QS12 || QS13 || QS14

Parameter contents:

- QS12: Workpiece
- QS13: Status:
- QS14: Scrap
- QS10: Workpiece Status: Scrap

Converting a numerical value to a string parameter

With the **TOCHAR** function, the control converts a numerical value into a string parameter. This enables you to chain numerical values with string variables.



- Show the soft-key row with special functions
- PROGRAM FUNCTIONS STRING
- Open the function menu
- Press the String functions soft key



TOCHAR

FUNCTIONS

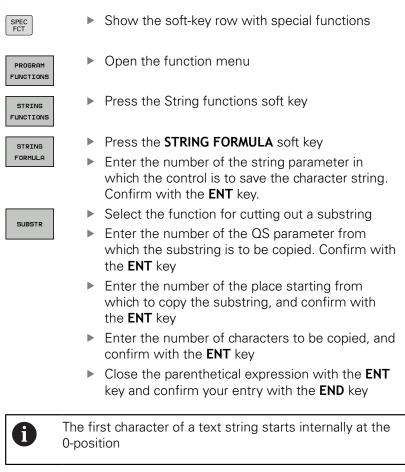
- Press the STRING FORMULA soft key
- Select the function for converting a numerical value to a string parameter
- Enter the number or the desired Q parameter to be converted by the control, and confirm with the ENT key
- If desired, enter the number of digits after the decimal point that the control should convert, and confirm with the ENT key
- Close the parenthetical expression with the ENT key and confirm your entry with the END key

Example: Convert parameter Q50 to string parameter QS11, use 3 decimal places

N37 QS11 = TOCHAR (DAT+Q50 DECIMALS3)

Copying a substring from a string parameter

The **SUBSTR** function copies a definable range from a string parameter.



Example: A four-character substring (LEN4) is read from the string parameter QS10 beginning with the third character (BEG2)

N37 QS13 = SUBSTR (SRC_QS10 BEG2 LEN4)

Reading system data

With the function **SYSSTR** you can read system data and store them in string parameters. You select the system data through a group number (ID) and a number.

Entering IDX and DAT is not required.

Group name, ID no.	Number	Meaning
Program information, 10010	1	Path of the current main program or pallet program
	3	Path of the cycle selected with CYCL DEF G39 PGM CALL
	10	Path of the program selected with %:PGM
Channel data, 10025	1	Channel name
Values programmed in the tool call, 10060	1	Tool name
Current system time, 10321	1 - 16	1: DD.MM.YYYY hh:mm:ss
		2 and 16: DD.MM.YYYY hh:mm
		3: DD.MM.YY hh:mm
		4: YYYY-MM-DD hh:mm:ss
		5 and 6: YYYY-MM-DD hh:mm
		7: YY-MM-DD hh:mm
		8 and 9: DD.MM.YYYY
		10: DD.MM.YY
		11: YYYY-MM-DD
		12: YY-MM-DD
		13 and 14: hh:mm:ss
		15: hh:mm
Touch-probe data, 10350	50	Probe type of the active touch probe TS
	70	Probe type of the active touch probe TT
	73	Key name of the active touch probe TT from MP activeTT
	2	Path of the selected pallet table
NC software version, 10630	10	Version identifier of the NC software version
Tool data, 10950	1	Tool name
	2	DOC entry of the tool
	4	Tool-carrier kinematics

Converting a string parameter to a numerical value

The **TONUMB** function converts a string parameter to a numerical value. The value to be converted should be only numerical.

The QS parameter to be converted must contain only one numerical value. Otherwise, the Control will output an error message		
0	 Select Q-parameter functions 	
FORMULA	Press the FORMULA soft key	
FORHULA	Enter the number of the string parameter in which the control is to save the numerical value. Confirm with the ENT key.	
\bigcirc	 Shift the soft-key row 	
TONUMB	 Select the function for converting a string parameter to a numerical value 	
	 Enter the number of the QS parameter to be converted by the control, and confirm with the ENT key 	
	 Close the parenthetical expression with the ENT key and confirm your entry with the END key 	
Example: Convert string parameter QS11 to a numerical		

Example: Convert string parameter QS11 to a numerica parameter Q82

N37 Q82 = TONUMB (SRC_QS11)

Testing a string parameter

The **INSTR** function checks whether a string parameter is contained in another string parameter.



- Select Q-parameter functions
 Press the FORMULA soft key
- Enter the number of the Q parameter for the result and confirm with the ENT key The control saves the place at which the text to be searched for begins. It is saved in the parameter.
- Shift the soft-key row
- INSTR

A

 \triangleleft

- Select the function for checking a string parameter
- Enter the number of the QS parameter in which the text to be searched for is saved. Confirm with the ENT key
- Enter the number of the QS parameter to be searched for by the control, and confirm with the ENT key
- Enter the number of the place at which the control is to start search the substring, and confirm with the ENT key.
- Close the parenthetical expression with the ENT key and confirm your entry with the END key

The first character of a text string starts internally at the 0-position

If the control cannot find the required substring, it will save the total length of the string to be searched (counting starts at 1) in the result parameter.

If the substring to be searched for appears multiple times, then the control returns the first place at which it finds the substring.

Example: Search through QS10 for the text saved in parameter QS13. Begin the search at the third place.

N37 Q50 = INSTR (SRC_QS10 SEA_QS13 BEG2)

Finding the length of a string parameter

The STRLEN function returns the length of the text saved in a selectable string parameter.

Q	 Select Q parameter function
FORMULA	 Press the FORMULA soft key Enter the number of the Q parameter in which the control is to save the ascertained string length. Confirm with the ENT key. Shift the soft-key row
	 Select the function for finding the text length of a string parameter
	Enter the number of the QS parameter from which the control is to ascertain the length, and confirm with the ENT key
	 Close the parenthetical expression with the ENT key and confirm your entry with the END key
Example	e: Find the length of QS15
N37 Q52	2 = STRLEN (SRC_QS15)
6	If the selected string parameter is not defined the control returns the result -1 .

control returns the result -1.

Comparing alphabetic priority

The **STRCOMP** function compares string parameters for alphabetic priority.

٥	 Select Q parameter function 	
FORMULA	 Press the FORMULA soft key Enter the number of the Q parameter in which the control is to save the result of comparison, and confirm with the ENT key. 	
\bigcirc	 Shift the soft-key row 	
STRCOMP	 Select the function for comparing string parameters 	
	 Enter the number of the first QS parameter that the control is to compare, and confirm with the ENT key 	
	 Enter the number of the second QS parameter that the control is to compare, and confirm with the ENT key 	
	Close the parenthetical expression with the ENT key and confirm your entry with the END key	
A	The control returns the following results:	
	• 0 : The compared QS parameters are identical	
	 -1: The first QS parameter precedes the second QS parameter alphabetically 	
	+1: The first QS parameter follows the second QS parameter alphabetically	

Example: QS12 and QS14 are compared for alphabetic priority N37 Q52 = STRCOMP (SRC_QS12 SEA_QS14)

Reading out machine parameters

With the **CFGREAD** function, you can read out machine parameters of the control as numerical values or as strings. The read-out values are always output in metric units of measure.

In order to read out a machine parameter, you must use the control's configuration editor to determine the parameter name, parameter object, and, if they have been assigned, the group name and index:

lcon	Туре	Meaning	Example
₽Æ	Кеу	Group name of the machine parameter (if available)	CH_NC
₽ <mark>€</mark>	Entity	Parameter object (name begins with Cfg)	CfgGeoCycle
	Attribute	Name of the machine parameter	displaySpindle
⊕ <mark>©</mark> ⊒	Index	List index of a machine parameter (if available)	[0]
•	If you are in the configuration editor for the user parameters, you can change the display of the existing parameters. In the default setting, the parameters are displayed with short, explanatory texts. Further information: "Changing the display of the parameters", page 658		

Each time you want to interrogate a machine parameter with the **CFGREAD** function, you must first define a QS parameter with attribute, entity and key.

The following parameters are read in the CFGREAD function's dialog:

- **KEY_QS**: Group name (key) of the machine parameter
- **TAG_QS**: Object name (entity) of the machine parameter
- **ATR_QS**: Name (attribute) of the machine parameter
- **IDX**: Index of the machine parameter

Reading a string of a machine parameter

In order to store the content of a machine parameter as a string in a QS parameter:



Press the Q key.

STRING FORMULA

- Press the STRING FORMULA soft key
- Enter the number of the string parameter in which the control is to save the machine parameter
- Press the ENT key
- Select the CFGREAD function
- Enter the numbers of the string parameters for key, entity, and attribute
- ▶ Press the **ENT** key
- Enter the number for the index, or skip the dialog with NNO ENT, whichever applies
- Close the parenthesized expression with the ENT key
- Press the END key to conclude entry

Example: Read as a string the axis designation of the fourth axis

Parameter settings in the configuration editor

DisplaySettings CfgDisplayData axisDisplayOrder [0] to [5]

Example

14 QS11 = ""	Assign string parameter for key
15 QS12 = "CfgDisplaydata"	Assign string parameter for entity
16 QS13 = "axisDisplay"	Assign string parameter for parameter name
17 QS1 = CFGREAD(KEY_QS11 TAG_QS12 ATR_QS13 IDX3)	Read out machine parameter

Reading a numerical value of a machine parameter

Store the value of a machine parameter as a numerical value in a Q parameter:

	Q	

FORMULA

Select Q parameter function

- Press the FORMULA soft key
 Enter the number of the Q parameter in which the control is to save the machine parameter
- Press the ENT key
- ► Select the **CFGREAD** function
- Enter the numbers of the string parameters for key, entity, and attribute
- ▶ Press the ENT key
- Enter the number for the index, or skip the dialog with NNO ENT, whichever applies
- Close the parenthesized expression with the ENT key
- ▶ Press the **END** key to conclude entry

Example: Read overlap factor as Q parameter

Parameter settings in the configuration editor

ChannelSettings

CH_NC

CfgGeoCycle

pocketOverlap

Example

N10 QS11 = "CH_NC"	Assign string parameter for key	
N20 QS12 = "CfgGeoCycle"	Assign string parameter for entity	
N30 Q\$13 = "pocketOverlap"	Assign string parameter for parameter name	
N40 Q50 = CFGREAD(KEY_QS11 TAG_QS12 ATR_QS13)	Read out machine parameter	

9.11 Preassigned Q parameters

The Q parameters Q100 to Q199 are assigned values by the control. The following types of information are assigned to the Q parameters:

- Values from the PLC
- Tool and spindle data
- Data on operating status
- Results of measurements from touch probe cycles etc.

The control saves the preassigned Q parameters Q108, Q114 and Q115 - Q117 in the unit of measure used by the active program.

NOTICE

Danger of collision!

Q parameters are used in the HEIDENHAIN cycles, in machine tool builder cycles, and in supplier functions. You can also program Q parameters within the NC program. If, when using Q parameters, the recommended Q parameter ranges are not used exclusively, then this can lead to overlapping (reciprocal effects) and thus cause undesired behavior. Danger of collision during machining!

- Only use Q parameter ranges recommended by HEIDENHAIN.
- Comply with the documentation from HEIDENHAIN, the machine tool builder, and suppliers.
- Check the machining sequence using a graphic simulation

You must not use preassigned Q parameters (QS parameters) between **Q100** and **Q199** (**QS100** and **QS199**) as calculation parameters in the NC programs.

Values from the PLC: Q100 to Q107

The control assigns values from the PLC to parameters Q100 to Q107 in an NC program.

Active tool radius: Q108

The active value of the tool radius is assigned to Q108. Q108 is calculated from:

- Tool radius R (tool table or G99 block)
- Delta value DR from the tool table
- Delta value DR from the **T** block



i

The control remembers the current tool radius even if the power is interrupted.

Tool axis: Q109

The value of Q109 depends on the current tool axis:

Tool axis	Parameter value
No tool axis defined	Q109 = -1
X axis	Q109 = 0
Y axis	Q109 = 1
Z axis	Q109 = 2
U axis	Q109 = 6
V axis	Q109 = 7
Waxis	Q109 = 8

Spindle status: Q110

The value of the parameter Q110 depends on the M function last programmed for the spindle.

M function	Parameter value
No spindle status defined	Q110 = -1
M3: Spindle ON, clockwise	Q110 = 0
M4: Spindle ON, counterclockwise	Q110 = 1
M5 after M3	Q110 = 2
M5 after M4	Q110 = 3

Coolant on/off: Q111

M function	Parameter value
M8: Coolant ON	Q111 = 1
M9: Coolant OFF	Q111 = 0

Overlap factor: Q112

The control assigns Q112 to the overlap factor for pocket milling.

Unit of measurement for dimensions in the program: Q113

During nesting the %, the value of the parameter Q113 depends on the dimensional data of the program from which the other programs are called.

Dimensional data of the main program	Parameter value
Metric system (mm)	Q113 = 0
Imperial system (inch)	Q113 = 1

Tool length: Q114

The current value for the tool length is assigned to Q114.



The Control remembers the current tool length even if the power is interrupted.

Coordinates after probing during program run

The parameters Q115 to Q119 contain the coordinates of the spindle position at the moment of contact during programmed measurement with the 3-D touch probe. The coordinates refer to the preset that is active in the **Manual operation** mode.

The length of the stylus and the radius of the ball tip are not compensated in these coordinates.

Coordinate axis	Parameter value
X axis	Q115
Y axis	Q116
Z axis	Q117
4th axis Machine-dependent	Q118
5th axis Machino dopondont	Q119

Machine-dependent

Deviation between actual value and nominal value during automatic tool measurement with, for example, the TT 160

Deviation of actual from nominal value	Parameter value
Tool length	Q115
Tool radius	Q116

Tilting the working plane with spatial (workpiece) angles instead of spindle head angles: Coordinates for rotary axes calculated by the control.

Coordinates	Parameter value
A axis	Q120
B axis	Q121
C axis	Q122

Measurement results from touch probe cycles

Further information: Cycle Programming User's Manual

Center in reference axisQ151Center in minor axisQ152DiameterQ153Pocket lengthQ154Pocket widthQ155Length of the axis selected in the cycleQ156Position of the centerlineQ157Angle in the A axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket widthQ165Measured lengthQ166Pocket widthQ165Measured lengthQ167Potet minor axisQ170Rotation about the A axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Measured actual values	Parameter value
Center in minor axisQ152DiameterQ153Pocket lengthQ154Pocket widthQ155Length of the axis selected in the cycleQ156Position of the centerlineQ157Angle in the A axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ170Rotation about the A axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Angle of a straight line	Q150
DiameterQ153Pocket lengthQ154Pocket widthQ155Length of the axis selected in the cycleQ156Position of the centerlineQ157Angle in the A axisQ158Angle in the B axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ170Rotation about the A axisQ170Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Center in reference axis	Q151
Pocket lengthQ154Pocket widthQ155Length of the axis selected in the cycleQ156Position of the centerlineQ157Angle in the A axisQ158Angle in the B axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ171Rotation about the C axisQ172Workpiece statusQ180ReworkQ181	Center in minor axis	Q152
Pocket widthQ155Length of the axis selected in the cycleQ156Position of the centerlineQ157Angle in the A axisQ158Angle in the B axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Diameter	Q153
Length of the axis selected in the cycleQ156Position of the centerlineQ157Angle in the A axisQ158Angle in the B axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ172Workpiece statusQ180ReworkQ181	Pocket length	Q154
Position of the centerlineQ157Angle in the A axisQ158Angle in the B axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ172Workpiece statusQ180ReworkQ181	Pocket width	Q155
Angle in the A axisQ158Angle in the B axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ172Workpiece statusQ180ReworkQ181	Length of the axis selected in the cycle	Q156
Angle in the B axisQ159Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Position of the centerline	Q157
Coordinate of the axis selected in the cycleQ160Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ172Workpiece statusQ180ReworkQ181	Angle in the A axis	Q158
Measured deviationParameter valueCenter in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ172Workpiece statusQ180GoodQ181	Angle in the B axis	Q159
Center in reference axisQ161Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Coordinate of the axis selected in the cycle	Q160
Center in minor axisQ162DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Measured deviation	Parameter value
DiameterQ163Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Center in reference axis	Q161
Pocket lengthQ164Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Center in minor axis	Q162
Pocket widthQ165Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Diameter	Q163
Measured lengthQ166Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Pocket length	Q164
Position of the centerlineQ167Determined space angleParameter valueRotation about the A axisQ170Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Pocket width	Q165
Determined space angleParameter valueRotation about the A axisQ170Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Measured length	Q166
Rotation about the A axisQ170Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Position of the centerline	Q167
Rotation about the B axisQ171Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Determined space angle	Parameter value
Rotation about the C axisQ172Workpiece statusParameter valueGoodQ180ReworkQ181	Rotation about the A axis	Q170
Workpiece statusParameter valueGoodQ180ReworkQ181	Rotation about the B axis	Q171
Good Q180 Rework Q181	Rotation about the C axis	Q172
Rework Q181	Workpiece status	Parameter value
	Good	Q180
Scrap Q182	Rework	Q181
	Scrap	Q182

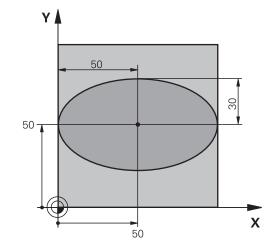
Tool measurement with the BLUM laser	Parameter value
Reserved	Q190
Reserved	Q191
Reserved	Q192
Reserved	Q193
Reserved for internal use	Parameter value
Marker for cycles	Q195
Marker for cycles	Q196
Marker for cycles (machining patterns)	Q197
Number of the last active measuring cycle	Q198
Status of tool measurement with TT	Parameter value
Tool within tolerance	Q199 = 0.0
Tool is worn (LTOL/RTOL is exceeded)	Q199 = 1.0
Tool is broken (LBREAK/RBREAK is exceed- ed)	Q199 = 2.0

9.12 Programming examples

Example: Ellipse

Program run

- The contour of the ellipse is approximated by many short lines (defined in Q7). The more calculation steps you define for the lines, the smoother the curve becomes.
- The milling direction is determined with the starting angle and end angle in the plane: Machining direction is clockwise: Starting angle > end angle Machining direction is counterclockwise: Starting angle < end angle
- The tool radius is not taken into account



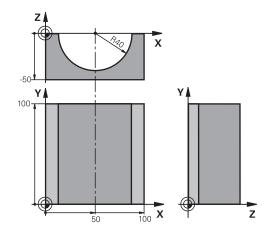
%ELLIPSE G71 *	
N10 D00 Q1 P01 +50*	Center in X axis
N20 D00 Q2 P01 +50*	Center in Y axis
N30 D00 Q3 P01 +50*	Semiaxis in X
N40 D00 Q4 P01 +30*	Semiaxis in Y
N50 D00 Q5 P01 +0*	Starting angle in the plane
N60 D00 Q6 P01 +360*	End angle in the plane
N70 D00 Q7 P01 +40*	Number of calculation steps
N80 D00 Q8 P01 +30*	Rotational position of the ellipse
N90 D00 Q9 P01 +5*	Milling depth
N100 D00 Q10 P01 +100*	Feed rate for plunging
N110 D00 Q11 P01 +350*	Feed rate for milling
N120 D00 Q12 P01 +2*	Set-up clearance for pre-positioning
N130 G30 G17 X+0 Y+0 Z-20*	Workpiece blank definition
N140 G31 G90 X+100 Y+100 Z+0*	
N150 T1 G17 S4000*	Tool call
N160 G00 G40 G90 Z+250*	Retract the tool
N170 L10.0*	Call machining operation
N180 G00 Z+250 M2*	Retract the tool, end program
N190 G98 L10*	Subprogram 10: Machining operation
N200 G54 X+Q1 Y+Q2*	Shift datum to center of ellipse
N210 G73 G90 H+Q8*	Account for rotational position in the plane
N220 Q35 = (Q6 - Q5) / Q7	Calculate angle increment
N230 D00 Q36 P01 +Q5*	Copy starting angle
N240 D00 Q37 P01 +0*	Set counter
N250 Q21 = Q3 * COS Q36	Calculate X coordinate for starting point

N260 Q22 = Q4 * SIN Q36	Calculate Y coordinate for starting point
N270 Q00 G40 X+Q21 Y+Q22 M3*	Move to starting point in the plane
N280 Z+Q12*	Pre-position in spindle axis to set-up clearance
N290 G01 Z-Q9 FQ10*	Move to working depth
N300 G98 L1*	
N310 Q36 = Q36 + Q35	Update the angle
N320 Q37 = Q37 + 1	Update the counter
N330 Q21 = Q3 * COS Q36	Calculate the current X coordinate
N340 Q22 = Q4 * SIN Q36	Calculate the current Y coordinate
N350 G01 X+Q21 Y+Q22 FQ11*	Move to next point
N360 D12 P01 +Q37 P02 +Q7 P03 1*	Unfinished? If not finished, return to LBL 1
N370 G73 G90 H+0*	Reset the rotation
N380 G54 X+0 Y+0*	Reset the datum shift
N390 G00 G40 Z+Q12*	Move to set-up clearance
N400 G98 L0*	End of subprogram
N99999999 %ELLIPSE G71 *	

Example: Concave cylinder machined with spherical cutter

Program run

- This program functions only with a spherical cutter. The tool length refers to the sphere center.
- The contour of the cylinder is approximated by many short line segments (defined in Q13). The more line segments you define, the smoother the curve becomes.
- The cylinder is milled in longitudinal cuts (here: parallel to the Y axis).
- The milling direction is determined with the starting angle and end angle in space:
 Machining direction clockwise:
 Starting angle > end angle
 Machining direction counterclockwise:
 Starting angle < end angle
- The tool radius is compensated automatically



%CYLIN G71 *

%CTLIN G/1 "	
N10 D00 Q1 P01 +50*	Center in X axis
N20 D00 Q2 P01 +0*	Center in Y axis
N30 D00 Q3 P01 +0*	Center in Z axis
N40 D00 Q4 P01 +90*	Starting angle in space (Z/X plane)
N50 D00 Q5 P01 +270*	End angle in space (Z/X plane)
N60 D00 Q6 P01 +40*	Cylinder radius
N70 D00 Q7 P01 +100*	Length of the cylinder
N80 D00 Q8 P01 +0*	Rotational position in the X/Y plane
N90 D00 Q10 P01 +5*	Allowance for cylinder radius
N100 D00 Q11 P01 +250*	Feed rate for plunging
N110 D00 Q12 P01 +400*	Feed rate for milling
N120 D00 Q13 P01 +90*	Number of cuts
N130 G30 G17 X+0 Y+0 Z-50*	Workpiece blank definition
N140 G31 G90 X+100 Y+100 Z+0*	
N150 T1 G17 S4000*	Tool call
N160 G00 G40 G90 Z+250*	Retract the tool
N170 L10.0*	Call machining operation
N180 D00 Q10 P01 +0*	Reset allowance
N190 L10.0*	Call machining operation
N200 G00 G40 Z+250 M2*	Retract the tool, end program
N210 G98 L10*	Subprogram 10: Machining operation
N220 Q16 = Q6 - Q10 - Q108	Account for allowance and tool, based on the cylinder radius
N230 D00 Q20 P01 +1*	Set counter
N240 D00 q24 p01 +Q4*	Copy starting angle in space (Z/X plane)
N250 Q25 = (Q5 - Q4) / Q13	Calculate angle increment
N260 G54 X+Q1 Y+Q2 Z+Q3*	Shift datum to center of cylinder (X axis)

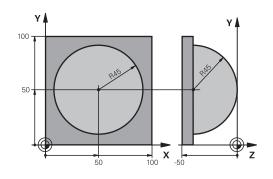
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N270 G73 G90 H+Q8*	Account for rotational position in the plane
N280 G00 G40 X+0 Y+0*	Pre-position in the plane to the cylinder center
N290 G01 Z+5 F1000 M3*	Pre-position in the spindle axis
N300 G98 L1*	
N310 I+0 K+0*	Set pole in the Z/X plane
N320 G11 R+Q16 H+Q24 FQ11*	Move to starting position on cylinder, plunge-cutting obliquely into the material
N330 G01 G40 Y+Q7 FQ12*	Longitudinal cut in Y+ direction
N340 D01 Q20 P01 +Q20 P02 +1*	Update the counter
N350 D01 Q24 P01 +Q24 P02 +Q25*	Update solid angle
N360 D11 P01 +Q20 P02 +Q13 P03 99*	Finished? If finished, jump to end
N370 G11 R+Q16 H+Q24 FQ11*	Move on an approximated arc for the next longitudinal cut
N380 G01 G40 Y+0 FQ12*	Longitudinal cut in Y- direction
N390 D01 Q20 P01 +Q20 P02 +1*	Update the counter
N400 D01 Q24 P01 +Q24 P02 +Q25*	Update solid angle
N410 D12 P01 +Q20 P02 +Q13 P03 1*	Unfinished? If not finished, return to LBL 1
N420 G98 L99*	
N430 G73 G90 H+0*	Reset the rotation
N440 G54 X+0 Y+0 Z+0*	Reset the datum shift
N450 G98 L0*	End of subprogram
N99999999 %CYLIN G71 *	

Example: Convex sphere machined with end mill

Program run

- This program requires an end mill.
- The contour of the sphere is approximated by many short lines (in the Z/X plane, defined in Q14). The smaller you define the angle increment, the smoother the curve becomes.
- You can determine the number of contour cuts through the angle increment in the plane (defined in Q18).
- The tool moves upward in three-dimensional cuts.
- The tool radius is compensated automatically



N10 D00 Q1 P01 +50*Center in X axisN20 D00 Q2 P01 +50*Center in Y axisN30 D00 Q4 P01 +90*Starting angle in space (Z/X plane)N40 D00 Q5 P01 +0*End angle in space (Z/X plane)N50 D00 Q14 P01 +5*Angle increment in spaceN60 D00 Q6 P01 +45*Sphere radiusN70 D00 Q8 P01 +0*Starting angle of rotational position in the X/Y planeN80 D00 Q9 p01 +360*End angle of rotational position in the X/Y planeN80 D00 Q10 P01 +5*Allowance in sphere radius for roughingN10 D00 Q11 P01 +5*Allowance in sphere radius for roughingN10 D00 Q12 P01 +350*Feed rate for millingN10 D00 Q12 P01 +350*Feed rate for millingN10 D00 Q12 P01 +350*Feed rate for millingN10 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN150 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN120 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN20 D00 Q18 P01 +0*Call machining operationN130 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN20 D00 Q18 P01 +5*Call machining operationN210 G00 G40 Z+250 M2*Retract the toolN170 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q1 P02 +Q6*Calculate Z coordinate for pre-positioning <th>%SPHERE G71 *</th> <th></th>	%SPHERE G71 *	
N30 D00 Q4 P01 +90*Starting angle in space (Z/X plane)N40 D00 Q5 P01 +0*End angle in space (Z/X plane)N50 D00 Q14 P01 +5*Angle increment in spaceN60 D00 Q6 P01 +45*Sphere radiusN70 D00 Q8 P01 +0*Starting angle of rotational position in the X/Y planeN80 D00 Q9 p01 +360*End angle of rotational position in the X/Y planeN90 D00 Q18 P01 +10*Angle increment in the X/Y plane for roughingN10 D00 Q10 P01 +5*Allowance in sphere radius for roughingN110 D00 Q11 P01 +2*Set-up clearance for pre-positioning in the spindle axisN120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN150 D00 Q18 P01 +0*Retract the toolN170 L10.0*Call machining operationN180 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 G03 G40 Z+250 M2*Retract the toolN170 L10.0*Call machining operationN200 G04 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q1+P02 +Q6*Corpy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q10*Corpy rotational position in the planeN270 D10 Q42 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N10 D00 Q1 P01 +50*	Center in X axis
N40 D00 Q5 P01 +0*End angle in space (Z/X plane)N50 D00 Q14 P01 +5*Angle increment in spaceN60 D00 Q6 P01 +45*Sphere radiusN70 D00 Q8 P01 +0*Starting angle of rotational position in the X/Y planeN80 D00 Q9 p01 +360*End angle of rotational position in the X/Y planeN90 D00 Q18 P01 +10*Angle increment in the X/Y plane for roughingN100 D00 Q10 P01 +5*Allowance in sphere radius for roughingN10 D00 Q11 P01 +5*Allowance in sphere radius for roughingN110 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 C00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 Q10 P01 +0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN180 D00 Q18 P01 +0*Reset allowanceN190 D00 Q18 P01 +0*Call machining operationN200 G98 L10*Subprogram 10: Machining operationN200 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q4*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 +Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z	N20 D00 Q2 P01 +50*	Center in Y axis
N50 D00 Q14 P01 +5*Angle increment in spaceN60 D00 Q6 P01 +45*Sphere radiusN70 D00 Q8 P01 +0*Starting angle of rotational position in the X/Y planeN80 D00 Q9 p01 +360*End angle of rotational position in the X/Y planeN90 D00 Q18 P01 +10*Angle increment in the X/Y plane for roughingN100 D00 Q10 P01 +5*Allowance in sphere radius for roughingN110 D00 Q11 P01 +2*Set-up clearance for pre-positioning in the spindle axisN120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 D00 Q10 P01 +0*Reset allowanceN170 L10.0*Call machining operationN180 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 G40 Z+250 M2*Retract the toolN170 L10.0*Call machining operationN180 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q10*Account for allowance in the sphere radiusN260 G54 X+Q1 +Q2 Z-Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane <th>N30 D00 Q4 P01 +90*</th> <th>Starting angle in space (Z/X plane)</th>	N30 D00 Q4 P01 +90*	Starting angle in space (Z/X plane)
N60 D00 Q6 P01 +45*Sphere radiusN70 D00 Q8 P01 +0*Starting angle of rotational position in the X/Y planeN80 D00 Q9 p01 +360*End angle of rotational position in the X/Y planeN90 D00 Q18 P01 +10*Angle increment in the X/Y plane for roughingN100 D00 Q10 P01 +5*Allowance in sphere radius for roughingN110 D00 Q11 P01 +2*Set-up clearance for pre-positioning in the spindle axisN120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 D00 Q10 P01 +0*Rest allowanceN180 D00 Q10 P01 +0*Rest allowanceN180 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN120 L10.0*Call machining operationN180 D00 Q18 P01 +5*Retract the toolN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 G40 Z+250 M2*Retract the tool, end programN210 G00 G40 Z+250 M2*Retract the tool, end programN210 G00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N220 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphere <t< th=""><th>N40 D00 Q5 P01 +0*</th><th>End angle in space (Z/X plane)</th></t<>	N40 D00 Q5 P01 +0*	End angle in space (Z/X plane)
N70 D00 Q8 P01 +0*Starting angle of rotational position in the X/Y planeN80 D00 Q9 p01 +360*End angle of rotational position in the X/Y planeN90 D00 Q18 P01 +10*Angle increment in the X/Y plane for roughingN100 D00 Q10 P01 +5*Allowance in sphere radius for roughingN110 D00 Q11 P01 +2*Set-up clearance for pre-positioning in the spindle axisN120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN180 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q6*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N50 D00 Q14 P01 +5*	Angle increment in space
N80 D00 Q9 p01 +360*End angle of rotational position in the X/Y planeN90 D00 Q18 P01 +10*Angle increment in the X/Y plane for roughingN100 D00 Q10 P01 +5*Allowance in sphere radius for roughingN110 D00 Q11 P01 +2*Set-up clearance for pre-positioning in the spindle axisN120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN210 G00 G40 Z+250 M2*Calculate Z coordinate for pre-positioningN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N60 D00 Q6 P01 +45*	Sphere radius
N90 D00 Q18 P01 +10*Angle increment in the X/Y plane for roughingN100 D00 Q10 P01 +5*Allowance in sphere radius for roughingN110 D00 Q11 P01 +2*Set-up clearance for pre-positioning in the spindle axisN120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN200 G40 Z+250 M2*Retract the tool, end programN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N70 D00 Q8 P01 +0*	Starting angle of rotational position in the X/Y plane
N100 D00 Q10 P01 +5*Allowance in sphere radius for roughingN110 D00 Q11 P01 +2*Set-up clearance for pre-positioning in the spindle axisN120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Copy rotational position in the planeN270 D01 Q16 P01 +Q8*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N80 D00 Q9 p01 +360*	End angle of rotational position in the X/Y plane
N110 D00 Q11 P01 +2*Set-up clearance for pre-positioning in the spindle axisN120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q6*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N90 D00 Q18 P01 +10*	Angle increment in the X/Y plane for roughing
N120 D00 Q12 P01 +350*Feed rate for millingN130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*N150 T1 G17 S4000*N150 T1 G17 S4000*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q28 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N100 D00 Q10 P01 +5*	Allowance in sphere radius for roughing
N130 G30 G17 X+0 Y+0 Z-50*Workpiece blank definitionN140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N110 D00 Q11 P01 +2*	Set-up clearance for pre-positioning in the spindle axis
N140 G31 G90 X+100 Y+100 Z+0*Tool callN150 T1 G17 S4000*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N120 D00 Q12 P01 +350*	Feed rate for milling
N150 T1 G17 S4000*Tool callN160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N130 G30 G17 X+0 Y+0 Z-50*	Workpiece blank definition
N160 G00 G40 G90 Z+250*Retract the toolN170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN250 D01 Q26 P01 +Q6 P02 +Q108*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N140 G31 G90 X+100 Y+100 Z+0*	
N170 L10.0*Call machining operationN180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN250 D01 Q26 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N150 T1 G17 S4000*	Tool call
N180 D00 Q10 P01 +0*Reset allowanceN190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N160 G00 G40 G90 Z+250*	Retract the tool
N190 D00 Q18 P01 +5*Angle increment in the X/Y plane for finishingN200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N170 L10.0*	Call machining operation
N200 L10.0*Call machining operationN210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N180 D00 Q10 P01 +0*	Reset allowance
N210 G00 G40 Z+250 M2*Retract the tool, end programN220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N190 D00 Q18 P01 +5*	Angle increment in the X/Y plane for finishing
N220 G98 L10*Subprogram 10: Machining operationN230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N200 L10.0*	Call machining operation
N230 D01 Q23 P01 +Q11 P02 +Q6*Calculate Z coordinate for pre-positioningN240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N210 G00 G40 Z+250 M2*	Retract the tool, end program
N240 D00 Q24 P01 +Q4*Copy starting angle in space (Z/X plane)N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N220 G98 L10*	Subprogram 10: Machining operation
N250 D01 Q26 P01 +Q6 P02 +Q108*Compensate sphere radius for pre-positioningN260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N230 D01 Q23 P01 +Q11 P02 +Q6*	Calculate Z coordinate for pre-positioning
N260 D00 Q28 P01 +Q8*Copy rotational position in the planeN270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N240 D00 Q24 P01 +Q4*	Copy starting angle in space (Z/X plane)
N270 D01 Q16 P01 +Q6 P02 -Q10*Account for allowance in the sphere radiusN280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N250 D01 Q26 P01 +Q6 P02 +Q108*	Compensate sphere radius for pre-positioning
N280 G54 X+Q1 Y+Q2 Z-Q16*Shift datum to center of sphereN290 G73 G90 H+Q8*Account for starting angle of rotational position in the plane	N260 D00 Q28 P01 +Q8*	Copy rotational position in the plane
N290 G73 G90 H+Q8* Account for starting angle of rotational position in the plane	N270 D01 Q16 P01 +Q6 P02 -Q10*	Account for allowance in the sphere radius
	N280 G54 X+Q1 Y+Q2 Z-Q16*	Shift datum to center of sphere
N300 G98 L1* Pre-position in the spindle axis	N290 G73 G90 H+Q8*	Account for starting angle of rotational position in the plane
	N300 G98 L1*	Pre-position in the spindle axis

N310 I+0 J+0*	Set pole in the X/Y plane for pre-positioning	
N320 G11 G40 R+Q26 H+Q8 FQ12*	Pre-position in the plane	
N330 I+Q108 K+0*	Set pole in the Z/X plane, offset by the tool radius	
N340 G01 Y+0 Z+0 FQ12*	Move to working depth	
N350 G98 L2*		
N360 G11 G40 R+Q6 H+Q24 FQ12*	Move upward on an approximated arc	
N370 D02 Q24 P01 +Q24 P02 +Q14*	Update solid angle	
N380 D11 P01 +Q24 P02 +Q5 P03 2*	Inquire whether an arc is finished. If not finished, return to LBL 2	
N390 G11 R+Q6 H+Q5 FQ12*	Move to the end angle in space	
N400 G01 G40 Z+Q23 F1000*	Retract in the spindle axis	
N410 G00 G40 X+Q26*	Pre-position for next arc	
N420 D01 Q28 P01 +Q28 P02 +Q18*	Update rotational position in the plane	
N430 D00 Q24 P01 +Q4*	Reset solid angle	
N440 G73 G90 H+Q28*	Activate new rotational position	
N450 D12 P01 +Q28 P02 +Q9 P03 1*	Unfinished? If not finished, return to LBL 1	
N460 D09 P01 +Q28 P02 +Q9 P03 1*		
N470 G73 G90 H+0*	Reset the rotation	
N480 G54 X+0 Y+0 Z+0*	Reset the datum shift	
N490 G98 L0*	End of subprogram	
N99999999 %SPHERE G71 *		



Miscellaneous Functions

10.1 Entering miscellaneous functions M and STOP

Fundamentals

With the control's miscellaneous functions—also called M functions—you can affect:

- the program run, e.g. a program interruption
- the machine functions, such as switching spindle rotation and coolant supply on and off
- the path behavior of the tool

You can enter up to four M (miscellaneous) functions at the end of a positioning block or in a separate block. The control displays the following dialog question: **Miscellaneous function M**?

You usually enter only the number of the miscellaneous function in the programming dialog. Some miscellaneous functions can be programmed with additional parameters. In this case, the dialog is continued for the parameter input.

In the **Manual operation** and **Electronic handwheel** operating modes, the M functions are entered with the ${\bf M}$ soft key.

Effectiveness of miscellaneous functions

Please note that some M functions become effective at the start of a positioning block, and others at the end, regardless of their position in the NC block.

M functions come into effect in the block in which they are called.

Some miscellaneous functions are effective only in the block in which they are programmed. Unless the miscellaneous function is only effective blockwise, you must either cancel it in a subsequent block with a separate M function, or it is automatically canceled by the control at the end of the program.

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If multiple functions were programmed in a single NC block, the execution sequence is as follows:

- M functions taking effect at the start of the block are executed before those taking effect at the end of the block
- If all M functions are effective at the start or end of the block, execution takes place in the sequence as programmed

Entering a miscellaneous function in a STOP block

If you program a **STOP** block, the program run or test run is interrupted at the block, e.g. for a tool inspection. You can also enter an M (miscellaneous) function in a **STOP** block:

- STOP
- To program an interruption of program run, press the STOP key
- ▶ Enter a miscellaneous function M

Example

N87 G38 M6*

10.2 Miscellaneous functions for program run inspection, spindle and coolant

Overview

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Refer to your machine manual. The machine manufacturer can influence the behavior of the miscellaneous functions described below.

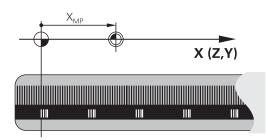
М	Effect	Effective at block	Start	End
M0	Program STOP Spindle STOP		-	
M1	Optional program STOP Spindle STOP if necessary Coolant OFF if necessary (function defined by the machine tool builder)			
M2	STOP program run Spindle STOP Coolant off Return jump to block 1 Clear status display Functional scope depends on machine parameter resetAt (no. 100901)			•
M3	Spindle ON clockwise			
M4	Spindle ON counterclockwise			
M5	Spindle STOP			
M6	Tool change Spindle STOP Program STOP			•
M 8	Coolant ON			
M9	Coolant OFF			
M13	Spindle ON clock Coolant ON	wise	•	
M14	Spindle ON coun Coolant ON	terclockwise	•	
M30	Same as M2			

10.3 Miscellaneous functions for coordinate entries

Programming machine-referenced coordinates: M91/ M92

Scale datum

On the scale, a reference mark indicates the position of the scale datum.



Machine datum

The machine datum is required for the following tasks:

- Define the axis traverse limits (software limit switches)
- Approach machine-referenced positions (e.g. tool change positions)
- Set a workpiece preset

The distance in each axis from the scale datum to the machine datum is defined by the machine manufacturer in a machine parameter.

Standard behavior

The control references the coordinates to the workpiece datum.

Further information: "Presetting without a 3-D touch probe", page 538

Behavior with M91 – Machine datum

If you want the coordinates in a positioning block to be referenced to the machine datum, end the block with M91.



If you program incremental coordinates in an M91 block, enter them with respect to the last programmed M91 position. If no M91 position is programmed in the active NC block, then enter the coordinates with respect to the current tool position.

The coordinate values on the control screen reference the machine datum. Switch the display of coordinates in the status display to REF.

Further information: "Status displays", page 84

Behavior with M92 – Additional machine reference point

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Refer to your machine manual.

In addition to the machine datum, the machine tool builder can also define an additional machine-based position as a machine reference point.

For each axis, the machine tool builder defines the distance between the machine reference point and the machine datum.

If you want the coordinates in positioning blocks to be based on the additional machine reference point, end these block with M92.



Radius compensation remains the same in blocks that are programmed with **M91** or **M92**. The tool length will **not** be taken into account.

Effect

M91 and M92 are effective only in the blocks in which M91 and M92 have been programmed.

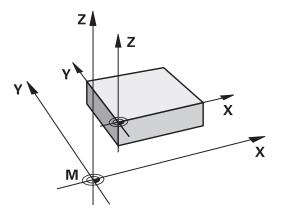
M91 and M92 take effect at the start of block.

Workpiece preset

If you want the coordinates to always be referenced to the machine datum, you can disable the setting of presets for one or more axes.

If presetting is inhibited for all axes, the control no longer displays the **SET PRESET** soft key in the **Manual operation** mode.

The figure shows coordinate systems with the machine and workpiece datum.



M91/M92 in the Test Run mode

In order to be able to graphically simulate M91/M92 movements, you need to activate working space monitoring and display the workpiece blank referenced to the defined preset.

Further information: "Showing the workpiece blank in the working space ", page 596

Moving to positions in a non-tilted coordinate system with a tilted working plane: M130

Standard behavior with a tilted working plane

The control references the coordinates in the positioning blocks to the tilted working plane coordinate system.

Behavior with M130

Despite an active tilted working plane, the control references the coordinates in straight line blocks to the non-tilted workpiece coordinate system.

The control then positions the tilted tool at the programmed coordinates of the non-tilted workpiece coordinate system.

NOTICE

Danger of collision!

The **M130** function is only active blockwise. The control executes the subsequent machining operations in the tilted working plane coordinate system again. Danger of collision during machining!

- Check the sequence and positions using a graphic simulation
- 6

Programming notes:

- The M130 function is only allowed if the Tilt the working plane function is active.
- If the M130 function is combined with a cycle call, the control will interrupt the execution with an error message.

Effect

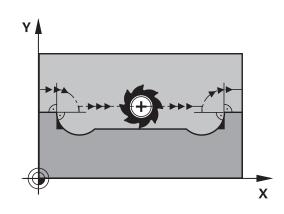
M130 functions blockwise in straight-line blocks without tool radius compensation.

10.4 Miscellaneous functions for path behavior

Machining small contour steps: M97

Standard behavior

The control inserts a transition arc at outside corners. For very small contour steps, the tool would damage the contour. In such cases, the control interrupts the program run and generates the **Tool radius too large** error message.



Behavior with M97

The control determines a path intersection for the contour elements—such as inner corners—and moves the tool above this point.

Program M97 in the same block as the outside corner.

HEIDENHAIN recommends to use the much more powerful **M120 LA** function instead of **M97** here. **Further information:** "Calculating the radiuscompensated path in advance (LOOK AHEAD): M120 ", page 437

Effect

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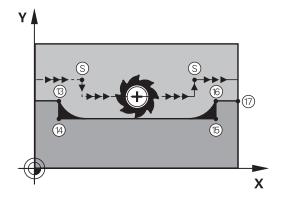
The **M97** function is only effective in the NC block where it is programmed.



The control does not completely finish the corner when it is machined with **M97**. You may wish to rework the contour with a smaller tool.

Example

N50 G99 G01 R+20*	Large tool radius
N130 X Y F M97*	Move to contour point 13
N140 G91 Y-0.5 F*	Machine small contour step 13 to 14
N150 X+100*	Move to contour point 15
N160 Y+0.5 F M97*	Machine small contour step 15 to 16
N170 G90 X Y *	Move to contour point 17



Machining open contour corners: M98

Standard behavior

Behavior with M98

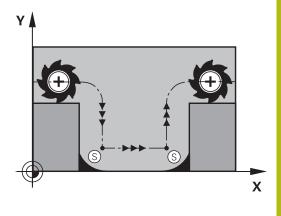
completely machined:

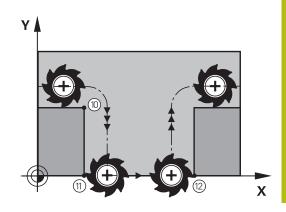
The control calculates the intersections of the cutter paths at inside corners and moves the tool in the new direction at those points.

If the contour is open at the corners, however, this will result in incomplete machining.

With the M98 miscellaneous function, the control temporarily

suspends radius compensation to ensure that both corners are





Effect

M98 is effective only in the blocks where it is programmed.M98 becomes effective at the end of the block.

Example: Move to the contour points 10, 11 and 12 in succession

N100 G01 G41 X Y F*
N110 X G91 Y M98*
N120 X+*

Feed rate factor for plunging movements: M103

Standard behavior

The control moves the tool at the last programmed feed rate, regardless of the direction of traverse.

Behavior with M103

The control reduces the feed rate when the tool moves in the negative direction of the tool axis. The feed rate for plunging FZMAX is calculated from the last programmed feed rate FPROG and a factor F%:

FZMAX = FPROG x F%

Programming M103

If you program **M103** in a positioning block, the control continues the dialog by prompting you for the F factor.

Effect

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M103 becomes effective at the start of the block. To cancel **M103**, program **M103** once again without a factor.

The **M103** is also effective with an active tilted working plane coordinate system. The feed rate reduction is then effective in the negative direction when moving the **tilted** tool axis.

Example

The feed rate for plunging is to be 20% of the feed rate in the plane.

	Actual contouring feed rate (mm/min):
N170 G01 G41 X+20 Y+20 F500 M103 F20*	500
N180 Y+50*	500
N190 G91 Z-2.5*	100
N200 Y+5 Z-5*	141
N210 X+50*	500
N220 G90 Z+5*	500

Feed rate in millimeters per spindle revolution: M136

Standard behavior

The control moves the tool at the programmed F feed rate in mm/ min

Behavior with M136



In NC programs based on inch units, **M136** is not allowed in combination with the alternative **FU** feed rate. The spindle is not permitted to be controlled when M136 is active.

With **M136**, the control does not move the tool in mm/min, but rather at the programmed F feed rate in millimeters per spindle revolution. If you change the spindle speed by using the spindle override, the control changes the feed rate accordingly.

Effect

M136 becomes effective at the start of the block.

You can cancel **M136** by programming **M137**.

Feed rate for circular arcs: M109/M110/M111

Standard behavior

The control applies the programmed feed rate to the path of the tool center.

Behavior at circular arcs with M109

For inside and outside machining of circular arcs, the control keeps the feed rate at the cutting edge constant.

NOTICE

Caution: Danger to the tool and workpiece!

If the **M109** function is active, the control might dramatically increase the feed rate when machining very small outside corners. During the execution, there is a risk of tool breakage or workpiece damage.

► Do not use **M109** for machining very small outside corners

Behavior at circular arcs with M110

With circular arcs, the control only keeps the feed rate constant for inside machining operations. The feed rate will not be adjusted for outside machining of circular arcs.



If you program **M109** or **M110** with a number > 200 before calling a machining cycle, the adjusted feed rate will also be effective for circular arcs within these machining cycles. The initial state is restored after finishing or canceling a machining cycle.

Effect

M109 and **M110** become effective at the start of the block. **M109** and **M110** can be canceled with **M111**.

Calculating the radius-compensated path in advance (LOOK AHEAD): M120

Standard behavior

If the tool radius is larger than the contour step that needs to be machined with radius compensation, the control interrupts program run and generates an error message. **M97** inhibits the error message, but this results in dwell marks and will also move the corner.

Further information: "Machining small contour steps: M97", page 432

The control might damage the contour in case of undercuts.

Behavior with M120

The control checks radius-compensated contours for undercuts and tool path intersections, and calculates the tool path in advance from the current block. Areas of the contour that would be damaged by the tool will not be machined (shown darker in the figure). You can also use **M120** to calculate the tool radius compensation for digitized data or data created on an external programming system. This means that deviations from the theoretical tool radius can be compensated.

The number of blocks (99 max.) calculated in advance, can be defined with **LA** (Look **A**head) following **M120**. Note that the larger the number of blocks you choose, the higher the block processing time will be.

Input

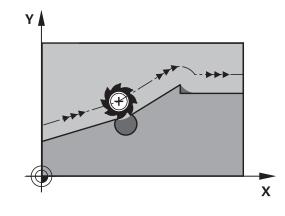
If you enter **M120** in a positioning block, the control continues the dialog for this block by prompting you for the number of **LA** blocks to be calculated in advance.

Effect

M120 must be included in an NC block that also contains an **G41** or **G42** radius compensation. **M120** is then effective from this block until

- radius compensation is canceled with G40
- M120 LA0 is programmed
- M120 is programmed without LA
- another program is called with %
- the working plane is tilted with Cycle G80 or with the PLANE function

M120 becomes effective at the start of the block.



Restrictions

- After an external or internal stop, you can only re-enter the contour with the function **RESTORE POS. AT N**. Before you start the block scan, you must cancel **M120**, otherwise the control will generate an error message.
- If you want to approach the contour on a tangential path, you must use the APPR LCT function. The block with APPR LCT must contain only the coordinates of the working plane.
- If you want to depart the contour on a tangential path, you must use the function **DEP LCT**. The block with **DEP LCT** must contain only the coordinates of the working plane.
- Before using the functions listed below, you have to cancel M120 and the radius compensation:
 - Cycle **G60** Tolerance
 - Cycle **G80** Working plane
 - PLANE function
 - M114
 - M128

Superimposing handwheel positioning during program run: M118

Standard behavior

In the Program Run operating modes, the control moves the tool as defined in the NC program.

Behavior with M118

M118 permits manual corrections by handwheel during the program run. For this purpose, you program **M118** and enter an axis-specific value (linear or rotary axis).

NOTICE

Danger of collision!

If you use the **M118** function to modify the position of a rotary axis with the handwheel and then execute the **M140** function, the control ignores the superimposed values with the retraction movement. This results in unwanted and unpredictable movements, especially when using machines with head rotation axes. There is a danger of collision during these compensating movements!

Do not combine M118 with M140 when using machines with head rotation axes.

Input

If you enter **M118** in a positioning block, the control continues the dialog for this block by prompting you for the axis-specific values. The coordinates are entered with the orange axis direction buttons or the ASCII keyboard.

Effect

To cancel handwheel positioning, program **M118** once again without coordinate input.

M118 becomes effective at the start of the block.

Example

You want to be able to use the handwheel during program run to move the tool in the working plane X/Y by ± 1 mm and in the rotary axis B by $\pm 5^{\circ}$ from the programmed value:

N250 G01 G41 X+0 Y+38.5 F125 M118 X1 Y1 B5*

M118 is always effective in the machine coordinate system.

Further information: "Handwheel superimp.:", page **M118** is also effective in the **Positioning w/ Manual Data Input** operating mode!

Virtual tool axis VT

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Refer to your machine manual.

Your machine tool builder must have prepared the control for this function.

With the virtual tool axis, you can also traverse with the handwheel in the direction of a sloping tool on a machine with swivel heads. To traverse in a virtual tool axis direction, select the **VT** axis on the display of your handwheel.

Further information: "Traverse with electronic handwheels", page 519

When using a HR 5xx handwheel, you can select the virtual axis directly with the orange VI axis key, if necessary.

In conjunction with the **M118** function, it is also possible to carry out handwheel superimpositioning in the currently active tool axis direction. For this purpose, program at least the spindle axis with its permitted range of traverse in the **M118** function (e.g. **M118 Z5**) and select the **VT** axis on the handwheel.

Retraction from the contour in the tool-axis direction: M140

Standard behavior

In the **Program Run Single Block** and **Program Run Full Sequence** operating modes, the control moves the tool as defined in the machining program.

Behavior with M140

With **M140 MB** (move back), you can retract the tool from the contour by a programmable distance in the direction of the tool axis.

Input

If you enter **M140** in a positioning block, the control continues the dialog and prompts you for the path the tool should use for retracting from the contour. Enter the desired path that the tool should follow when retracting from the contour, or press the **MB MAX** soft key to move to the limit of the traverse range.

In addition, you can program the feed rate at which the tool traverses the entered path. If you do not enter a feed rate, the control moves the tool along the entered path at rapid traverse.

Effect

M140 is effective only in the NC block in which it is programmed.M140 becomes effective at the start of the block.

Example

Block 250: Retract the tool 50 mm from the contour. Block 251: Move the tool to the limit of the traverse range.

N250 G01 X+0 Y+38.5 F125 M140 MB50*

N251 G01 X+0 Y+38.5 F125 M140 MB MAX*

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M140 is also effective if the **Tilt working plane** function is active. For machines with swivel heads the control then moves the tool in the tilted coordinate system.

With **M140 MB MAX** you can only retract in the positive direction.

Always define a tool call with tool axis before **M140**, otherwise the traverse direction is not defined.

NOTICE

Danger of collision!

If you use the **M118** function to modify the position of a rotary axis with the handwheel and then execute the **M140** function, the control ignores the superimposed values with the retraction movement. This results in unwanted and unpredictable movements, especially when using machines with head rotation axes. There is a danger of collision during these compensating movements!

Do not combine M118 with M140 when using machines with head rotation axes.

Suppressing touch probe monitoring: M141

Standard behavior

If the stylus is deflected, the control issues an error message as soon as you want to move a machine axis.

Behavior with M141

The control moves the machine axes even if the touch probe is deflected. This function is required if you wish to write your own measuring cycle in connection with measuring cycle 3 in order to retract the stylus by means of a positioning block after it has been deflected.

NOTICE

Danger of collision!

The function **M141** suppresses the corresponding error message if the stylus is deflected. The control does not perform an automatic collision check with the stylus. Because of this behavior, you must check whether the touch probe can retract safely. There is a risk of collision if you choose the wrong direction for retraction.

 Carefully test the NC program or program section in the Program run, single block operating mode



M141 functions only for movements with straight-line blocks.

Effect

M141 is effective only in the NC block in which **M141** is programmed.

M141 becomes effective at the start of the block.

Deleting basic rotation: M143

Standard behavior

The basic rotation remains in effect until it is reset or is overwritten with a new value.

Behavior with M143

The control erases a programmed basic rotation from the NC program.



The function **M143** is not permitted with mid-program startup.

Effect

M143 is effective only from the NC block in which it is programmed.

M143 becomes effective at the start of the block.



M143 deletes the entries in columns **SPA**, **SPB**, and **SPC** in the preset table; reactivating the corresponding preset table line does not activate the deleted basic rotation.

Automatically retracting the tool from the contour at an NC stop: M148

Standard behavior

In case of an NC stop, the control stops all traverse movements. The tool stops moving at the point of interruption.

Behavior with M148

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Refer to your machine manual.

This function must be configured and enabled by your machine tool builder.

In the **CfgLiftOff** (no. 201400) machine parameter, the machine tool builder defines the path the control is to traverse for a **LIFTOFF** command. You can also use the **CfgLiftOff** machine parameter to deactivate the function.

Set the **Y** parameter in the **LIFTOFF** column of the tool table for the active tool. The control then retracts the tool from the contour by 2 mm max. in the direction of the tool axis.

Further information: "Entering tool data into the table", page 208

LIFTOFF takes effect in the following situations:

- An NC stop triggered by you
- An NC stop triggered by the software, e.g. if an error occurred in the drive system
- When a power interruption occurs

Effect

M148 remains in effect until deactivated with M149.

M148 becomes effective at the start of the block, M149 at the end of the block.

Rounding corners: M197

Standard behavior

With active radius compensation, the control inserts a transition arc at outside corners. This may lead to rounding of that edge.

Behavior with M197

With the **M197** function, the contour at the corner is tangentially extended and a smaller transition arc is then inserted. When you program the **M197** function and then press the **ENT** key, the control opens the **DL** input field. In **DL**, you define the length the control by which the control extends the contour elements. With **M197**, the corner radius is reduced, the corner is rounded less and the traverse movement is still smooth.

Effect

The **M197** function acts blockwise and is only effective on outside corners.

Example

G01 X... Y... RL M197 DL0.876*

Special Functions

11.1 Overview of special functions

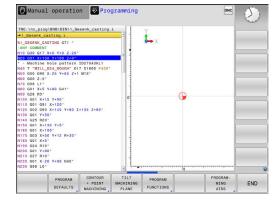
The control provides the following powerful special functions for a large number of applications:

Function	Description
Working with text files	page 459
Working with freely definable tables	page 463

Press the **SPEC FCT** key and the corresponding soft keys to access further special functions of the control. The following tables give you an overview of which functions are available.

Main menu for SPEC FCT special functions

SPEC FCT	 Press the SPEC FCT key to select functions 	t the special
Soft key	Function	Description
PROGRAM DEFAULTS	Define program defaults	page 449
CONTOUR + POINT MACHINING	Functions for contour and point machining	page 449
TILT MACHINING PLANE	Define the PLANE function	page 482
PROGRAM FUNCTIONS	Define different DIN/ISO functions	page 450
PROGRAM- MING AIDS	Programming aids	page 173



After pressing the **SPEC FCT** key, you can open the **smartSelect** selection window with the **GOTO** key. The control displays a structure overview with all available functions. You can rapidly navigate with the cursor or mouse and select functions in the tree diagram. The control displays online help for the selected function in the window on the right.

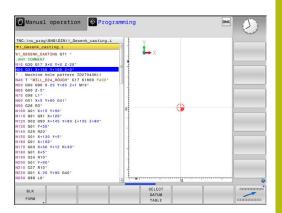
A

Program defaults menu



Press the Program Defaults soft key

Soft key	Function	Description
BLK FORM	Define workpiece blank	page 129
DATUM TABLE	Select datum table	See Cycle- Programming User's Manual
GLOBAL DEF	Define global cycle parameters	See Cycle- Programming User's Manual

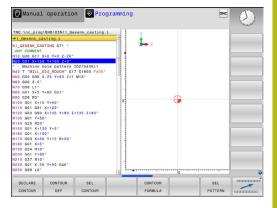


Functions for contour and point machining menu

CONTOUR	
+ POINT	
CONTOUR + POINT MACHINING	

 Press the soft key for functions for contour and point machining

Soft key	Function	Description
DECLARE	Assign contour description	See Cycle- Programming User's Manual
CONTOUR DEF	Define a simple contour formula	See Cycle- Programming User's Manual
SEL CONTOUR	Select a contour definition	See Cycle- Programming User's Manual
CONTOUR FORMULA	Define a complex contour formula	See Cycle- Programming User's Manual
SEL PATTERN	Select the point file with machin- ing positions	See Cycle- Programming User's Manual



Menu for defining different DIN/ISO functions

PROGRAM FUNCTIONS Press the PROGRAM FUNCTIONS soft key

Soft key	Function	Description
FUNCTION	Define the counter	page 457
STRING FUNCTIONS	Define string functions	page 400
FUNCTION SPINDLE	Define pulsing spindle speed	page 469
FUNCTION FEED	Define recurring dwell time	page 471
FUNCTION DWELL	Define dwell time in seconds or revolutions	page 473
DIN/IS0	Define DIN/ISO functions	page 456
INSERT COMMENT	Add comments	page 175

11.2 Tool carrier management

Fundamentals

You can create and manage tool carriers using the tool carrier management. The control factors the tool carriers into the calculations.

On machines with 3 axes, tool carriers for right-angled angled heads help processing on tool axes X and Y, as the control takes the dimensions of the angle heads into consideration.

Along with software option number 8, **Advanced Function Set** 1, you can tilt the working plane to the angle of the removable angled heads and thus keep working with the **Z** tool axis.

You must carry out the following steps so that the control can factors the tool carriers into the calculations:

- Save tool carrier templates
- Assign input parameters to tool carriers
- Allocate parameterized tool carriers

Save tool carrier templates

Many tool carriers only differ from others in terms of their dimensions, but their geometric shape is identical. So that you don't have to design all your tool carriers yourself, HEIDENHAIN supplies a range of ready-made tool carrier templates. Tool carrier templates are 3-D models with fixed geometries but changeable dimensions.

The tool carrier templates must be saved in **TNC:\system \Toolkinematics** and have the extension **.cft**.

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If the tool carrier templates are not available in your control, please download the data you require from:

http://www.klartext-portal.com/nc-solutions/en

6

If you need further tool carrier templates, please contact your machine manufacturer or third-party vendor.

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The tool carrier templates may consist of several subfiles. If the sub-files are incomplete, the control will display an error message.

Do not use incomplete tool carrier templates!

Assigning input parameters to tool carriers

Before the control can factor the tool carrier into the calculations, you must give the tool carrier template the actual dimensions. These parameters are entered in the additional **ToolHolderWizard** tool.

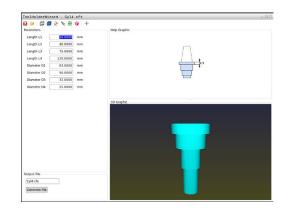
Save the parameterized tool carriers with the extension **.cfx** under **TNC:\system\Toolkinematics**.

The additional **ToolHolderWizard** tool is mainly operated with a mouse. Using the mouse, you can also set the desired screen layout by drawing a line between the areas **Parameter**, **Help graphics** and **3-D graphics** by holding down the left mouse button.

The following icons are available in the additional **ToolHolderWizard** tool:

lcon	Function
X	Close tool
<u>-</u>	Open file
Ø	Switch between wire frame model and solid object view
Ø	Switch between shaded and transparent view
t.t.	Display or hide transformation vectors
^А вс	Show or hide names of collision objects
₽	Display or hide test points
Ð	Show or hide measurement points
+++	Return to starting view of the 3-D model
6	If the tool carrier template does not contain any transformation vectors, names, test points and

If the tool carrier template does not contain any transformation vectors, names, test points and measurement points, the additional **ToolHolderWizard** tool does not execute any function when the corresponding icons are activated.



Parameterizing the tool carrier template in the Manual operation operating mode

Proceed as follows to parameterize tool carrier templates and save these parameters:



Press the Manual operation key



Press the TOOL TABLE soft key



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Press the EDIT soft key

Move the cursor to the KINEMATIC column



- Press the SELECT soft key
- Press the TOOL HOLDER WIZARD soft key The control opens the additional ToolHolderWizard tool in a pop-up window.
- Press the OPEN FILE icon
 The control opens a pop-up window.
- Select the desired tool carrier template using the preview screen
- Press the **OK** button
 The control opens the selected tool carrier template.

The cursor goes to the first parameterizable value.

- Adjust values
- Enter the name for the parameterized tool holder in the **Output file** area
- Press the GENERATE FILE button
- If required, reply to the message on the control
- Press the CLOSE icon
 The control closes the additional tool

Parameterizing the tool carrier template in the Programming operating mode

Proceed as follows to parameterize tool carrier templates and save these parameters:



Press the **Programming** key

PGM MGT

X

- Press the PGM MGT key
- Select the path TNC:\system\Toolkinematics
- Select the tool carrier template
 The control opens the additional
 ToolHolderWizard tool with the selected tool carrier template.
 The cursor goes to the first parameterizable value.
- Adjust values
- Enter the name for the parameterized tool holder in the **Output file** area
- Press the GENERATE FILE button
- ▶ If required, reply to the message on the control
- Press the CLOSE icon
 The control closes the additional tool

Allocating parameterized tool carriers

To allow the control to factor a parameterized tool carrier into calculations, you must allocate the tool carrier to a tool and **call the tool again**.



Parameterized tool carriers can consist of several subfiles. If the sub-files are incomplete, the control will display an error message.

Only use fully parameterized tool carriers!

Proceed as follows to allocate a parameterized tool carrier to a tool:

Press the TOOL TABLE soft key

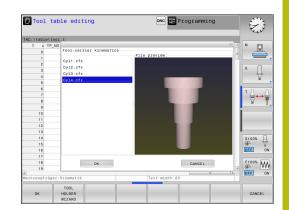


- Operating mode: Press the Manual operation key
- TOOL TABLE

EDIT OFF ON

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- Press the EDIT soft key
- Move the cursor to the KINEMATIC column of the required tool
- SELECT
- Press the SELECT soft key The control opens a pop-up window with parameterized tool carriers
- Select the desired tool carrier using the preview screen
- Press the OK soft key The control copies the name of the selected tool carrier to the KINEMATIC column
- Exit the tool table



11.3 Defining DIN/ISO functions

Overview



If a USB keyboard is connected, you can also directly type in the DIN/ISO functions on the keyboard.

The control provides soft keys with the following functions for creating DIN/ISO programs:

Soft kov	Function
Soft key	
DIN/IS0	Select ISO functions
F	Feed rate
G	Tool movements, cycles and program functions
I	X coordinate of the circle center/pole
J	Y coordinate of the circle center/pole
L	Label call for subprogram and program section repeat
М	Miscellaneous function
Ν	Block number
т	Tool call
Н	Polar coordinate angle
К	Z coordinate of the circle center/pole
R	Polar coordinate radius
S	Spindle speed

11.4 Defining a counter

Application



Refer to your machine manual.

Your machine manufacturer enables this function.

The FUNCTION COUNT function allows you to control a simple counter from within the NC program. For example, this function allows you to count the number of manufactured workpieces. The counter is only effective in the **Program Run Single Block** and **Program Run Full Sequence** operating modes.

The counter values are retained even after a restart of the control.

You can use Cycle 225 to engrave the current counter value into the workpiece.

NOTICE

Caution: Data may be lost!

Only one counter can be managed by the control. If you execute an NC program that resets the counter, any counter progress of another NC program will be deleted.

- > Please check prior to machining whether a counter is active.
- If necessary, note down the counter value and enter it again via the MOD menu after execution.



You can use Cycle 225 to engrave the current counter value into the workpiece.

Further information: Cycle Programming User's Manual

Define FUNCTION COUNT

The FUNCTION COUNT function provides the following possibilities:

Soft key	Meaning
FUNCTION COUNT INC	Increase count by 1
FUNCTION COUNT RESET	Reset counter
FUNCTION COUNT TARGET	Set the nominal count (target value) to the desired value
	Input value: 0–9999
FUNCTION COUNT SET	Set the counter to the desired value Input value: 0–9999
FUNCTION COUNT ADD	Increment the counter by the desired value Input value: 0–9999
FUNCTION COUNT REPEAT	Repeat the NC program starting from this label if more parts are to be machined.

Example

N50 FUNCTION COUNT RESET*	Reset the counter value
N60 FUNCTION COUNT TARGET10*	Enter the target number of parts to be machined
N70 G98 L11*	Enter the jump label
N80 G	Machining
N510 FUNCTION COUNT INC*	Increment the counter value
N520 FUNCTION COUNT REPEAT LBL 11*	Repeat the machining operations if more parts are to be machined.
N530 M30*	
N540 %COUNT G71*	

11.5 Creating text files

Application

You can use the control's text editor to write and edit texts. Typical applications:

- Recording test results
- Documenting working procedures
- Creating formula collections

Text files have the extension .A (for ASCII files). If you want to edit other types of files, you must first convert them into type .A files.

Opening and exiting a text file

- Operating mode: Press the **Programming** key
- ► To call the file manager, press the **PGM MGT** key.
- Display type .A files: Press the SELECT TYPE soft key and SHOW ALL soft key one after the other
- Select a file and open it with the SELECT soft key or ENT key, or create a new file by entering the new file name and confirming your entry with the ENT key

To leave the text editor, call the file manager and select a file of a different file type, for example a part program.

Soft key	Cursor movements
Son key	Cursor movements
MOVE WORD	Move cursor one word to the right
MOVE WORD	Move cursor one word to the left
	Go to next screen page
PAGE	Go to previous screen page
BEGIN	Cursor at beginning of file
	Cursor at end of file

Editing texts

Above the first line of the text editor, there is an information field showing the file name, location and line information:

 File:
 Name of the text file

Line: Line in which the cursor is presently located

Column: Column in which the cursor is presently located

The text is inserted or overwritten at the location of the cursor. You can move the cursor to any desired position in the text file by pressing the arrow keys.

You can insert a line break with the **RETURN** or **ENT** key.

Deleting and re-inserting characters, words and lines

With the text editor, you can erase words and even lines, and insert them at any desired location in the text.

- Move the cursor to the word or line that you wish to erase and insert at a different place in the text
- Press the DELETE WORD or DELETE LINE soft key: The text is deleted and stored temporarily.
- Move the cursor to the location where you wish insert the text, and press the INSERT LINE / WORD soft key.

Soft key	Function		
DELETE	Delete and temporarily store a line		
DELETE WORD	Delete and temporarily store a word		
DELETE CHAR	Delete and temporarily store a character		
INSERT LINE / WORD	Insert a line or word from temporary storage		

Editing text blocks

You can copy and erase text blocks of any size, and insert them at other locations. Before any of these actions, you must first select the desired text block:

- To select a text block: Move the cursor to the first character of the text you wish to select.
- SELECT BLOCK

▶ Press the **SELECT BLOCK** soft key.

Move the cursor to the last character of the text you wish to select. You can select whole lines by moving the cursor up or down directly with the arrow keys—the selected text is shown in a different color.

After selecting the desired text block, you can edit the text with the following soft keys:

Soft key	Function
CUT OUT BLOCK	Delete the selected block and store temporarily
COPY BLOCK	Store the selected block temporarily without erasing (copy)

If desired, you can now insert the temporarily stored block at a different location:

- Move the cursor to the location where you want to insert the temporarily stored text block
- INSERT BLOCK
- Press the INSERT BLOCK soft key—the text block is inserted.

You can insert the temporarily stored text block as often as desired

Transferring the selected block to a different file

Select the text block as described previously



Press the APPEND TO FILE soft key.

The control displays the **Destination file =** dialog message.

Enter the path and the name of the destination file.

The control appends the selected text block to the specified file. If no target file with the specified name is found, the control creates a new file with the selected text.

Inserting another file at the cursor position

Move the cursor to the location in the text where you wish to insert another file



▶ Press the **READ FILE** soft key.

- The control displays the **File name =** dialog message.
- Enter the path and name of the file you want to insert

Finding text sections

With the text editor, you can search for words or character strings in a text. The control provides the following two options.

Finding the current text

The search function is used for finding the next occurrence of the word in which the cursor is presently located:

- Move the cursor to the desired word.
- ► To select the search function, press the **FIND** soft key.
- Press the FIND CURRENT WORD soft key.
- ▶ To find a word: press the **FIND** soft key.
- Exit the search function: Press the **END** soft key

Finding any text

- To select the search function, press the FIND soft key. The control shows the Find text : dialog prompt
- Enter the text that you wish to find
- ► To find text: press the **FIND** soft key.
- Exit the search function: Press the END soft key

11.6 Freely definable tables

Fundamentals

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In freely definable tables you can save and read any information from the NC program. The Q parameter functions **D26** to **D28** are provided for this purpose.

You can change the format of freely definable tables, i.e. the columns and their properties, by using the structure editor. They enable you to make tables that are exactly tailored to your application.

You can also toggle between a table view (standard setting) and form view.

The names of tables and table columns must start with a letter and must not contain an arithmetic operator (e.g., +). Due to SQL commands, these characters can cause problems when inputting data or reading it out.

Creating a freely definable table

- ► To call the file manager, press the PGM MGT key
- Enter any desired file name with the .TAB extension and confirm it with the ENT key

The control displays a pop-up window with permanently stored table formats

Use the arrow key to select the desired table template, e.g. example.tab and confirm it with the ENT key
The control or control or control to the control formed formed formed.

The control opens a new table in the predefined format

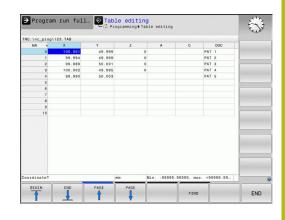
 To adapt the table to your requirements you have to edit the table format

Further information: "Editing the table format", page 464

Refer to your machine manual.

Machine tool builders may define their own table templates and save them in the control. When you create a new table, the control opens a pop-up window listing all available table templates.

You can also save your own table templates in the control. To do so, create a new table, change the table format and save the table in the **TNC:\system\proto** directory. Then your template will also be available in the list box for table templates when you create a new table.



Editing the table format

Press the EDIT FORMAT soft key (toggle the soft key row) The control opens the editor form displaying the table structure. The meanings of the structure commands (header entries) are shown in the following table.

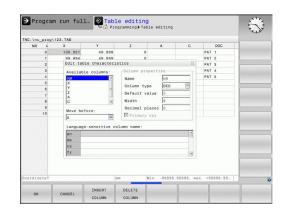
Structure command	Meaning				
Available columns:	List of all columns contained in the table				
Move before:	The entry highlighted in Available columns is moved in front of this column				
Name	Column name: Is displayed in the header				
Column type	Column name: Is displayed in the header TEXT: Text entry SIGN: + or - sign BIN: Binary number DEC: Decimal, positive, whole number (cardinal number) HEX: Hexadecimal number INT: Whole number LENGTH: Length (is converted in inch programs) FEED: Feed rate (mm/min or 0.1 inch/ min) IFEED: Feed rate (mm/min or inch/min) FLOAT: Floating-point number BOOL: Logical value INDEX: Index TSTAMP: Fixed format for date and time UPTEXT: Text entry in upper case				
Default value	Default value for the fields in this column				
Width	Width of the column (number of charac- ters)				
Primary key	First table column				
Language-sensitive	Language-sensitive dialogs				

Language-sensitive Language-sensitive dialogs column name

Use a connected mouse or the control's keyboard to navigate in the form. Navigation using the control's keyboard:

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Press the navigation keys to go to the entry fields. Use the arrow keys to navigate within an entry field. To open pop-down menus, press the GOTO key.





In a table that already contains lines you can not change the table properties **Name** and **Column type**. Once you have deleted all lines, you can change these properties. If required, create a backup copy of the table beforehand.

With the **CE** and **ENT** key combination, you can reset invalid values in fields with the **TSTAMP** column type.

Exiting the structure editor

Press the OK soft key

The control closes the editor form and applies the changes. All changes are discarded by pressing the **CANCEL** soft key.

Switching between table and form view

All tables with the $\ensuremath{\textbf{.TAB}}$ extension can be opened in either list view or form view.



 Press the key for setting the screen layout. Select the respective soft key for list view or form view (form view: with or without dialog texts)

In the left half of the form view, the control lists the line numbers with the contents of the first column.

In the right half you can change the data.

- Press the ENT key or the arrow key to move to the next entry field
- To select another line press the navigation key (folder symbol). This moves the cursor to the left window, and you can select the desired line with the arrow keys. Press the green navigation key to switch back to the input window.

NC:\nc_prog\	123.TAB		NR: 0				
NR 4 0 1 2 3 4 5 6 6 7 8 9	X 100.001 99.994 99.989 100.002 99.990	Y 49.5 50.(49.5 50.(NR Coordinate Coordinate Coordinate Coordinate Remark			0 10001 49.999 0 PAT 1	
10	9999.99999, m	ax. +	Coordinate [mm]			1/1	
TABLE. FILTER	HIDE/ SORT/ COLUMNS	EDIT		MORE FUNCTIONS	RESET	EDIT GURRENT FIELD	SORT

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D26 – Open a freely definable table

With the function **D26: TABOPEN** you open a freely definable table to be written to with **D27** or to be read from with **D28**.



Only one table can be opened in an NC program at any one time. A new block with **D26** automatically closes the last opened table.

The table to be opened must have the extension $\ensuremath{\textbf{.TAB}}$

Example: Open the table TAB1.TAB, which is saved in the directory TNC: \DIR1.

N56 D26 TNC:\DIR1\TAB1.TAB

D27 – Write to a freely definable table

With the **D27** function you write to the table that you previously opened with **D26**.

You can define multiple column names in a **D27** block. The column names must be written between quotation marks and separated by a comma. You define in Q parameters the value that the control is to write to the respective column.



The **D27** function by default writes values to the currently open table, even in the **Test Run** operating mode. The **D18 ID992 NR16** function allows you to retrieve the operating mode in which the program is running. If the **D27** function is to be run only in the **Program run, single block** and **Program run, full sequence** operating modes, you can skip the respective program section by using a jump statement. **Further information:** "If-then decisions with Q parameters", page 348

You can write only to numerical table fields.

If you wish to write to more than one column in a block, you must save the values under successive Q parameter numbers.

Example

You wish to write to the columns "Radius," "Depth" and "D" in line 5 of the presently opened table. The value to be written in the table must be saved in the Q parameters Q5, Q6 and Q7.

N53 Q5 = 3.75

N54 Q6 = -5

N55 Q7 = 7.5

N56 D27 P01 5/"RADIUS, DEPTH, D" = Q5

D28 – Read from a freely definable table

With the D28 function you read from the table previously opened with D26.

You can define, i.e. read, multiple column names in a **D28** block. The column names must be written between quotation marks and separated by a comma. In the **D28** block you can define the Q parameter number in which the control is to write the value that is first read.



You can read only numerical table fields.

If you wish to read from more than one column in a block, the control will save the values under successive Q parameter numbers.

Example

You wish to read the values of the columns "Radius," "Depth" and "D" from line 6 of the presently opened table. Save the first value in Q parameter Q10 (second value in Q11, third value in Q12).

N56 D28 Q10 = 6/"RADIUS, DEPTH, D"

Customizing the table format

NOTICE

Caution: Data may be lost!

The **ADAPT NC PGM / TABLE** function changes the format of all tables permanently. Existing data is not automatically backed up by the control before running the format change process, i.e. the files are changed permanently and might no longer be usable.

 Only use the function in consultation with the machine tool builder.

Soft key Function



Adapt format of tables present after changing the control software version



The names of tables and table columns must start with a letter and must not contain an arithmetic operator (e.g., +). Due to SQL commands, these characters can cause problems when inputting data or reading it out.

11.7 Pulsing spindle speed FUNCTION S-PULSE

Programming a pulsing spindle speed

Application

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Refer to your machine manual.

Read and note the functional description of the machine tool builder.

Follow the safety precautions.

Using the **S-PULSE FUNCTION** you can program a pulsing spindle speed, when operating at a constant spindle speed.

You can define the duration of a vibration (period length) using the P-TIME input value or a speed change in percent using the SCALE input value. The spindle speed changes in a sinusoidal form around the target value.

Procedure Example

N30 FUNCTION S-PULSE P-TIME10 SCALE5*

Proceed as follows for the definition:

SPEC FCT	Show the soft-key row with special functions
PROGRAM FUNCTIONS	Press the PROGRAM FUNCTIONS soft key
FUNCTION	Press the FUNCTION SPINDLE soft key
SPINDLE- PULSE	 Press the SPINDLE-PULSE soft key Define period length P-TIME Define speed change SCALE
6	The control never exceeds a programmed speed limit. The spindle speed is maintained until the sinusoidal

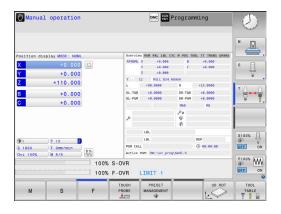
Symbols

In the status bar the symbol indicates the condition of the pulsing shaft speed:

curve of the S-PULSE FUNCTION falls below the

maximum speed once more.

lcon	Function
s %	Pulsing spindle speed active



Resetting the pulsing spindle speed

Example

N40 FUNCTION S-PULSE RESET*

Use the $\ensuremath{\textbf{FUNCTION}}$ $\ensuremath{\textbf{S-PULSE}}$ $\ensuremath{\textbf{RESET}}$ to reset the pulsing spindle speed.

Proceed as follows for the definition:



Show the soft-key row with special functions



Press the PROGRAM FUNCTIONS soft key



Press the FUNCTION SPINDLE soft key



▶ Press the **RESET SPINDLE-PULSE** soft key.

11.8 Dwell time FUNCTION FEED

Programming dwell time

Application



Refer to your machine manual. Read and note the functional description of the machine tool builder.

Follow the safety precautions.

The **FUNCTION FEED DWELL** function can be used to program a recurring dwell time in seconds, e.g. to force chip breaking . Program **FUNCTION FEED DWELL** immediately prior to the machining you wish to run with chip breaking.

The **FUNCTION FEED DWELL** function is not effective with rapid traverse movements and probing motion.

NOTICE

Caution: Danger to the tool and workpiece!

When the **FUNCTION FEED DWELL** function is active, the control will repeatedly interrupt the feed movement. While the feed movement is interrupted, the tool remains at its current position while the spindle continues to turn. Due to this behavior, workpieces need to be scrapped if threads are cut. In addition, there is a danger of tool breakage during execution!

Deactivate the FUNCTION FEED DWELL function before cutting threads

Procedure Example

N30 FUNCTION FEED DWELL D-TIME0.5 F-TIME5*

Proceed as follows for the definition:



Press the PROGRAM FUNCTIONS soft key

Show the soft-key row with special functions



FEED

Press the FUNCTION FEED soft key

- Press the FEED DWELL soft key
- Define the interval duration for dwelling D-TIME
- Define the interval duration for cutting F-TIME

Resetting dwell time



Reset to the dwell time immediately following the machining with chip breaking.

Example

N40 FUNCTION FEED DWELL RESET*

Use **FUNCTION FEED DWELL RESET** to reset the recurring dwell time.

Proceed as follows for the definition:



Show the soft-key row with special functions



Press the PROGRAM FUNCTIONS soft key



RESET

Press the FUNCTION FEED soft key

Press the RESET FEED DWELL soft key



You can also reset the dwell time by entering D-TIME 0. The control automatically resets the **FUNCTION FEED DWELL** function at the end of a program.

11.9 Dwell time FUNCTION DWELL

Programming dwell time

Application

The **FUNCTION DWELL** function enables you to program a dwell time in seconds or define the number of spindle revolutions for dwelling.

Procedure

Example

N30 FUNCTION DWELL TIME10*

Example

N40 FUNCTION DWELL REV5.8

Proceed as follows for the definition:



Show the soft-key row with special functions



Press the PROGRAM FUNCTIONS soft key



FUNCTION DWELL soft key



Press the DWELL TIME soft key

- DWELL REVOLUTIONS
- Define the duration in seconds
- Alternatively, press the DWELL REVOLUTIONS soft key
- Define the number of spindle revolutions

11.10 Lift off tool at NC stop: FUNCTION LIFTOFF

Programming tool lift-off with FUNCTION LIFTOFF

Requirement

Ö

Refer to your machine manual.

This function must be configured and enabled by your machine tool builder. In the **CfgLiftOff** (no. 201400) machine parameter, the machine tool builder defines the path the control is to traverse for a **LIFTOFF** command. You can also use the **CfgLiftOff** machine parameter to deactivate the function.

In the $\ensuremath{\text{LIFTOFF}}$ column of the tool table, set the $\ensuremath{\text{Y}}$ parameter for the active tool.

Further information: "Entering tool data into the table", page 208

Application

The **LIFTOFF** function is effective in the following situations:

- In case of an NC stop triggered by you
- In case of an NC stop triggered by the software, e. g. if an error has occurred in the drive system.
- In case of a power failure

The tool retracts from the contour by up to 2 mm. The control calculates the lift off direction based on the input in the **FUNCTION LIFTOFF** block.

You can program the **LIFTOFF** function in the following ways:

- FUNCTION LIFTOFF TCS X Y Z: Lift-off with a defined vector in the tool coordinate system
- FUNCTION LIFTOFF ANGLE TCS SPB: Lift-off with a defined angle in the tool coordinate system
- Lift-off in the tool axis direction with M148

Further information: "Automatically retracting the tool from the contour at an NC stop: M148", page 445

Programming tool lift-off with a defined vector Example

N40 FUNCTION LIFTOFF TCS X+0 Y+0.5 Z+0.5*

With **LIFTOFF TCS X Y Z**, you define the lift-off direction as a vector in the tool coordinate system. The control calculates the lift-off height in each axis based on the tool path defined by the machine tool builder.

Proceed as follows for the definition:

SPEC FCT	Show the soft-key row with special functions
PROGRAM FUNCTIONS	Press the PROGRAM FUNCTIONS soft key
FUNCTION LIFTOFF	Press the FUNCTION LIFTOFF soft key
LIFTOFF TCS	 Press the LIFTOFF TCS soft key Enter X, Y, and Z vector components

Programming tool lift-off with a defined angle Example

N40 FUNCTION LIFTOFF ANGLE TCS SPB+20*

With **LIFTOFF ANGLE TCS SPB**, you define the lift-off direction as a spatial angle in the tool coordinate system.

The SPB angle you enter describes the angle between Z and X. If you enter 0° , the tool lifts off in the tool Z axis direction.

Proceed as follows for the definition:



Show the soft-key row with special functions



Press the PROGRAM FUNCTIONS soft key

Press the FUNCTION LIFTOFF soft key

FUNCTION

- LIFTOFF P
- Press the LIFTOFF ANGLE TCS soft key
 - Enter the SPB angle

Resetting the lift-off function

Example

N40 FUNCTION LIFTOFF RESET*

Use the **FUNCTION LIFTOFF RESET** to reset the lift-off function. Proceed as follows for the definition:

SPEC FCT	Show the soft-key row with special functions
PROGRAM FUNCTIONS	Press the PROGRAM FUNCTIONS soft key
FUNCTION LIFTOFF	Press the FUNCTION LIFTOFF soft key
LIFTOFF RESET	Press the LIFTOFF RESET soft key
A	You can also reset the lift-off with M149.
	The control automatically resets the FUNCTION LIFTOFF function at the end of a program.

11



Multiple-Axis-Machining

12.1 Functions for multiple axis machining

This chapter summarizes the control functions for multiple axis machining:

Control function	Description	Page	
PLANE	Define machining in the tilted working plane	479	
M116 Feed rate of rotary axes		507	
M126 Shortest-path traverse of rotary axes		508	
M94 Reduce display value of rotary axes		509	
M138	Selection of tilted axes	510	

12.2 The PLANE function: Tilting the working plane (option 8)

Introduction

axis.

 \odot

Refer to your machine manual. The machine manufacturer must enable the functions for tilting the working plane! You can only use the **PLANE** function in its entirety on machines having at least two rotary axes (table axes, head axes or combined axes). An exception is the **PLANE AXIAL** function. **PLANE AXIAL** can also be used on a machine which has only one programmed rotary

The **PLANE** functions provide powerful options to define tilted working planes in various ways.

The parameter definition of the **PLANE** functions is subdivided into two parts:

- The geometric definition of the plane, which is different for each of the available PLANE functions.
- The positioning behavior of the PLANE function, which is independent of the plane definition and is identical for all PLANE functions

Further information: "Specifying the positioning behavior of the PLANE function", page 498

NOTICE

Danger of collision!

Cycle **28 MIRROR IMAGE** may have different effects in conjunction with the **Tilt working plane** function. The effect mainly depends on the programming sequence, the mirrored axes and the tilting function used. There is a danger of collision during the tilting operation and subsequent machining.

- Check the sequence and positions using a graphic simulation
- Carefully test the NC program or program section in the Program run, single block operating mode

Examples

- 1 Cycle **28 MIRROR IMAGE** programmed before the tilting function without rotary axes:
 - The tilt of the PLANE function used (except PLANE AXIAL) is mirrored
 - The mirroring is effective after the tilt with PLANE AXIAL or Cycle 19
- 2 Cycle **28 MIRROR IMAGE** programmed before the tilting function with a rotary axis:
 - The mirrored rotary axis has no effect on the tilt specified in the **PLANE** function used, because only the movement of the rotary axis is mirrored

A

- Operating and programming notes:
- The actual-position-capture function is not possible with an active tilted working plane.
- If you use the PLANE function when M120 is active, the control automatically rescinds the radius compensation, which also rescinds the M120 function.
- Always use PLANE RESET to cancel PLANE functions. Entering 0 in all PLANE parameters (e.g. all three spatial angles) exclusively resets the angles, but not the function.
- If you restrict the number of tilting axes with the M138 function, your machine may provide only limited tilting possibilities. The machine tool builder will decide whether the control takes the angles of deselected axes into account or sets them to 0.
- The control only supports tilting the working plane with spindle axis Z.

Overview

Most **PLANE** functions (except **PLANE AXIAL**) can be used to describe the desired working plane independently of the rotary axes available on your machine. The following possibilities are available:

Soft key	Function	Required parameters	Page
SPATIAL	SPATIAL	Three spatial angles: SPA, SPB, and SPC	484
PROJECTED	PROJECTED	Two projection angles: PROPR and PROMIN and a rotation angle ROT	486
EULER	EULER	Three Euler angles: precession (EULPR), nutation (EULNU) and rotation (EULROT),	488
VECTOR	VECTOR	Normal vector for defining the plane and base vector for defining the direction of the tilted X axis	490
POINTS	POINTS	Coordinates of any three points in the plane to be tilted	493
REL. SPA.	RELATIVE	Single, incrementally effective spatial angle	495
AXIAL	AXIAL	Up to three absolute or incremental axis angles A,B,C	496
RESET	RESET	Reset the PLANE function	483

Running an animation

To familiarize yourself with the various definition possibilities of each **PLANE** function, you can start animated sequences via soft key. To do so, first enter animation mode and then select the desired **PLANE** function. While the animation plays, the control highlights the soft key of the selected **PLANE** function with a blue color.

Soft key	Function
SELECT ANIMATION OFF ON	Switch on the animation mode
SPATIAL	Select the desired animation (highlighted in blue)

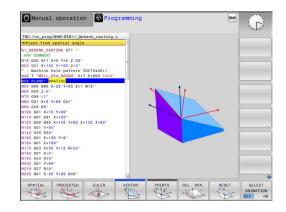
Defining the PLANE function



Show the soft-key row with special functions



- Press the TILT MACHINING PLANE soft key The control display the available PLANE functions in the soft-key row.
- Select the PLANE function



Selecting functions

Press the soft key linked to the desired function The control continues the dialog and prompts you for the required parameters.

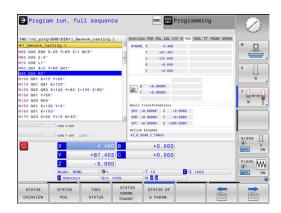
Selecting the function while animation is active

- Press the soft key linked to the desired function The control plays the animation.
- To apply the currently active function, press the soft key of that function again or press the ENT key

Position display

As soon as a **PLANE** function (except **PLANE AXIAL**) is active, the control shows the calculated spatial angle in the additional status display.

In the Distance-To-Go display (**ACTDST** and **REFDST**) the control shows, during tilting (**MOVE** or **TURN** mode) in the rotary axis, the distance to go to the calculated final position of the rotary axis.



Resetting PLANE function

Example

N10 PLANE RESET MOVE DIST50 F1000*		
SPEC FCT	Show the soft-key row with special functions	
TILT MACHINING PLANE	Press the TILT MACHINING PLANE soft key The control displays the available PLANE functions in the soft-key row	
RESET	 Select the reset function 	
	 Specify whether the control should automatically move the tilting axes to the home position (MOVE or TURN) or not (STAY) Further information: "Automatic positioning: MOVE/TURN/STAY (entry is mandatory)", page 499 Press the END key. 	
1	The PLANE RESET function resets the active tilt and the angles (PLANE function or Cycle G80) (angle = 0 and function inactive). It does not need to be defined more than once.	
	Deactivate tilting in the Manual operation operating mode in the 3D ROT menu.	
	Further information: "Activating manual tilting:", page 576	

Defining the working plane with the spatial angle: PLANE SPATIAL

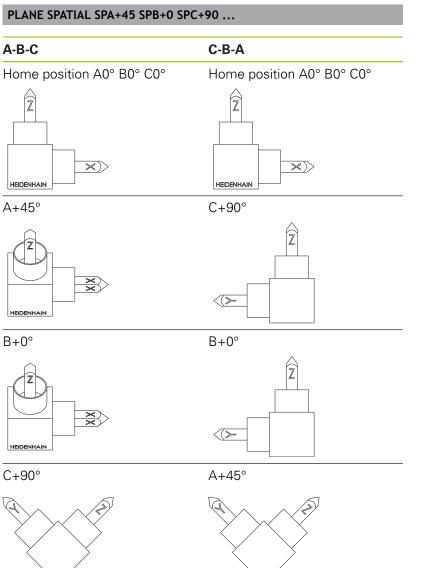
Application

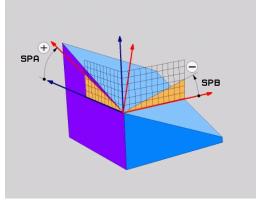
Spatial angles define a working plane through up to three rotations in the non-tilted workpiece coordinate system (**tilting sequence A-B-C**).

Most users assume three successive rotations in the reversed order (**tilting sequence C-B-A**).

The result is identical for both perspectives, as the following comparison shows.

Example





Tilting order A-B-C:

- 1 Tilt about the non-tilted X axis of the workpiece coordinate system
- 2 Tilt about the non-tilted Y axis of the workpiece coordinate system
- 3 Tilt about the non-tilted Z axis of the workpiece coordinate system

Tilting order C-B-A:

- 1 Tilt about the non-tilted Z axis of the workpiece coordinate system
- 2 Tilt about the tilted Y axis
- 3 Tilt about the tilted X axis

Programming notes:

- You must always define all three spatial angles SPA, SPB and SPC, even if one or more have the value 0.
- Depending on the machine, Cycle G80 requires you to enter spatial angles or axis angles. If the configuration (machine parameter setting) allows the input of spatial angles, the angle definition is the same in Cycle G80 and in the PLANE SPATIAL function.
- You can select the desired positioning behavior.
 Further information: "Specifying the positioning behavior of the PLANE function", page 498

Input parameters

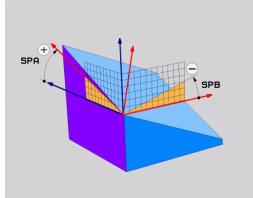
Example

i

N50 PLANE SPATIAL SPA+27 SPB+0 SPC+45*

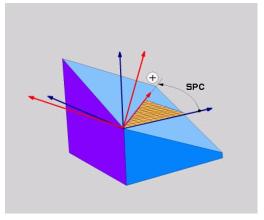


- Spatial angle A?: Rotational angle SPA about the (non-tilted) X axis. Input range from -359.9999 to +359.9999
- Spatial angle B?: Rotational angle SPB about the (non-tilted) Y axis. Input range from -359.9999 to +359.9999
- Spatial angle C?: Rotational angle SPC about the (non-tilted) Z axis. Input range from -359.9999 to +359.9999
- Continue with the positioning properties
 Further information: "Specifying the positioning behavior of the PLANE function", page 498



Abbreviations used

Abbreviation	Meaning
SPATIAL	In space
SPA	$\ensuremath{\textbf{Sp}}\xspace$ at the the the the the the the the the th
SPB	Sp atial B : Rotation about the (non-tilted) Y axis
SPC	Sp atial C : Rotation about the (non-tilted) Z axis



Defining the working plane with the projection angle: PLANE PROJECTED

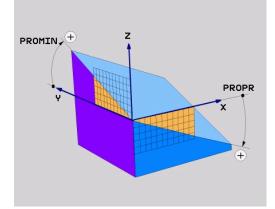
Application

Projection angles define a working plane by specifying two angles that you can communicate by projection of the 1st coordinate plane (Z/X on tool axis Z) and 2nd coordinate plane (Y/Z on tool axis Z) to the working levels to be defined.



Programming notes:

- The projection angles correspond to the angle projections on the planes of a rectangular coordinate system. The angles at the outer faces of the workpiece only are identical to the projection angles if the workpiece is rectangular. Thus, with workpieces that are not rectangular, the angle specifications from the engineering drawing often differ from the actual projection angles.
- You can select the desired positioning behavior.
 Further information: "Specifying the positioning behavior of the PLANE function", page 498

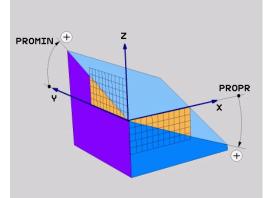


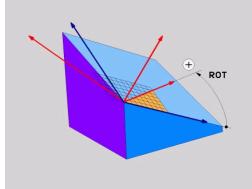
Input parameters



Projection angle on 1st Coordinate plane?: Projected angle of the tilted machining plane in the 1st coordinate plane of the untilted coordinate system (Z/X for tool axis Z). Input range: from -89.9999° to +89.9999°. The 0° axis is the principal axis of the active working plane (X for tool axis Z, positive direction)

- Proj. angle on 2nd Coordinate plane?: Projected angle in the 2nd coordinate plane of the untilted coordinate system (Y/Z for tool axis Z). Input range: from -89.9999° to +89.9999°. The 0° axis is the minor axis of the active machining plane (Y for tool axis Z)
- ROT angle of tilted plane?: Rotation of the tilted coordinate system around the tilted tool axis (corresponds to a rotation with Cycle 10 ROTATION). The rotation angle is used to simply specify the direction of the principal axis of the working plane (X for tool axis Z, Z for tool axis Y). Input range: -360° to +360°
- Continue with the positioning properties
 Further information: "Specifying the positioning behavior of the PLANE function", page 498





Example

N50 PLANE PROJECTED PROPR+24 PROMIN+24 ROT+30*

Abbreviations used:

PROJECTED	Projected
PROPR	Principal plane
PROMIN	Minor plane
ROT	Rotation

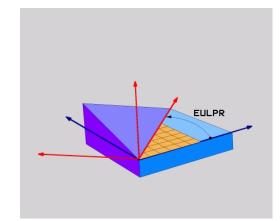
Defining the working plane with the Euler angle: PLANE EULER

Application

Euler angles define a machining plane through up to three **rotations about the respectively tilted coordinate system**. The Swiss mathematician Leonhard Euler defined these angles.

6

You can select the desired positioning behavior. **Further information:** "Specifying the positioning behavior of the PLANE function", page 498



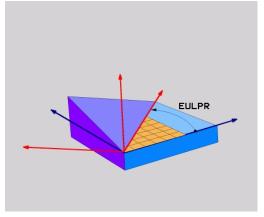
Input parameters

F	RO.	JEC	TED	
	4	+		
	5	T	5	

- Rot. angle Main coordinate plane?: Rotary angle EULPR around the Z axis. Please note:
 Input range: -180.0000° to 180.0000°
 - The 0° axis is the X axis
- Tilting angle tool axis?: Tilting angle EULNUT of the coordinate system around the X axis shifted by the precession angle. Please note:
 - Input range: 0° to 180.0000°
 - The 0° axis is the Z axis
- ROT angle of tilted plane?: Rotation EULROT of the tilted coordinate system around the tilted Z axis (corresponds to a rotation with Cycle 10 ROTATION). Use the rotation angle to simply define the direction of the X axis on the tilted working plane. Please note:
 - Input range: 0° to 360.0000°
 - The 0° axis is the X axis
- Continue with the positioning properties
 Further information: "Specifying the positioning behavior of the PLANE function", page 498

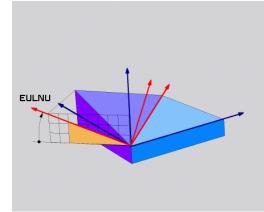
Example

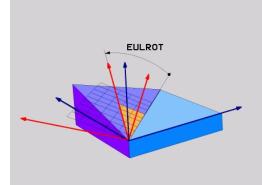
N50 PLANE EULER EULPR45 EULNU20 EULROT22*



Abbreviations used

Abbreviation	Meaning
EULER	Swiss mathematician who defined these angles
EULPR	Pr ecession angle: angle describing the rotation of the coordinate system around the Z axis
EULNU	Nu tation angle: angle describing the rotation of the coordinate system around the X axis shifted by the precession angle
EULROT	Rot ation angle: angle describing the rotation of the tilted machining plane around the tilted Z axis





Defining the working plane with two vectors: PLANE VECTOR

Application

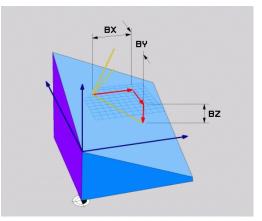
You can use the definition of a working plane via **two vectors** if your CAD system can calculate the base vector and normal vector of the tilted machining plane. A normalized input is not necessary. The control internally calculates the normal, so you can enter values between -9.999999 and +9.999999.

The base vector required for the definition of the machining plane is defined by the components **BX**, **BY** and **BZ**. The normal vector is defined by the components **NX**, **NY** and **NZ**.



Programming notes:

- The control calculates standardized vectors from the values you enter.
- The normal vector defines the slope and the orientation of the working plane. The base vector defines the orientation of the main axis X in the defined working plane. To ensure that the definition of the working plane is unambiguous, you must program the vectors perpendicular to each other. The machine tool builder defines how the control will behave for vectors that are not perpendicular.
- The programmed normal vector must not be too short, e.g. all directional components having a length of 0 or 0.0000001. In this case, the control would not be able to determine the slope. Machining is aborted and an error message is displayed. This behavior is independent of the configuration of the machine parameters.
- You can select the desired positioning behavior.
 Further information: "Specifying the positioning behavior of the PLANE function", page 498



Refer to your machine manual. The machine tool builder configures the behavior of the

control with vectors that are not perpendicular. Alternatively to generating the default error message, the control can correct (or replace) the base vector that is not perpendicular. This correction (or replacement) does not affect the normal vector.

Default correction behavior of the control if the base vector is not perpendicular:

The base vector is projected along the normal vector onto the working plane (defined by the normal vector).

Correction behavior of the control if the base vector is not perpendicular and too short, parallel or antiparallel to the normal vector:

- If the normal vector has no X component, the base vector corresponds to the original X axis
- If the normal vector has no Y component, the base vector corresponds to the original Y axis

Input parameters



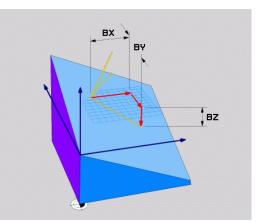
- X component of base vector?: X component BX of the base vector B; input range: from -9.9999999 to +9.9999999
- Y component of base vector?: Y component BY of the base vector B; input range: from -9.9999999 to +9.9999999
- Z component of base vector?: Z component BZ of the base vector B; input range: from -9.9999999 to +9.9999999
- X component of normal vector?: X component NX of the normal vector N; input range: from -9.9999999 to +9.9999999
- Y component of normal vector?: Y component NY of the normal vector N; input range: from -9.9999999 to +9.9999999
- Z component of normal vector?: Z component NZ of the normal vector N; input range: from -9.9999999 to +9.9999999
- Continue with the positioning properties
 Further information: "Specifying the positioning behavior of the PLANE function", page 498

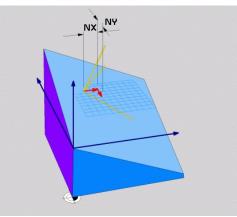
Example

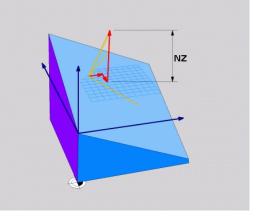
N50 PLANE VECTOR BX0.8 BY-0.4 BZ-0.42 NX0.2 NY0.2 NT0.92 ..*

Abbreviations used

Abbreviation	Meaning
VECTOR	Vector
BX, BY, BZ	Base vector : X, Y, and Z components
NX, NY, NZ	Normal vector : X, Y, and Z components







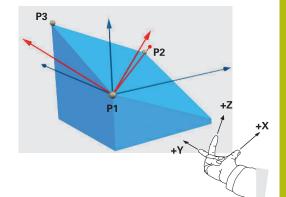
Defining the working plane via three points: PLANE POINTS

Application

F)

A working plane can be uniquely defined by entering **any three points P1 to P3 in this plane**. This possibility is realized in the **PLANE POINTS** function.

- Programming notes:
- The three points define the slope and orientation of the plane. The position of the active datum is not changed through **PLANE POINTS**.
- Point 1 and Point 2 determine the orientation of the tilted main axis X (for tool axis Z).
- Point 3 defines the slope of the tilted working plane. In the defined working plane, the Y axis is automatically oriented perpendicularly to the main axis X. The position of Point 3 thus also determines the orientation of the tool axis and consequently the orientation of the working plane. To have the positive tool axis pointing away from the workpiece, Point 3 must be located above the connection line between Point 1 and Point 2 (right-hand rule).
- You can select the desired positioning behavior.
 Further information: "Specifying the positioning behavior of the PLANE function", page 498



Input parameters



- X coordinate of 1stplane point?: X coordinate P1X of the 1st plane point
- Y coordinate of 1stplane point?: Y coordinate P1Y of the 1st plane point
- Z coordinate of 1stplane point: Z coordinate P1Z of the 1st plane point
- X coordinate of 2ndplane point?: X coordinate P2X of the 2nd plane point
- Y coordinate of 2ndplane point?: Y coordinate P2Y of the 2nd plane point
- Z coordinate of 2ndplane point?: Z coordinate P2Z of the 2nd plane point
- X coordinate of 3rdplane point?: X coordinate P3X of the 3rd plane point
- Y coordinate of 3rdplane point?: Y coordinate P3Y of the 3rd plane point
- Z coordinate of 3rdplane point?: Z coordinate P3Z of the 3rd plane point
- Continue with the positioning properties
 Further information: "Specifying the positioning behavior of the PLANE function", page 498

Example

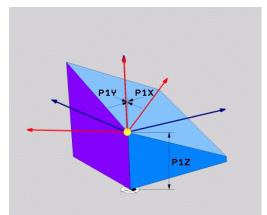
N50 PLANE POINTS P1X+0 P1Y+0 P1Z+20 P2X+30 P2Y+31 P2Z+20 P3X+0 P3Y+41 P3Z+32.5*

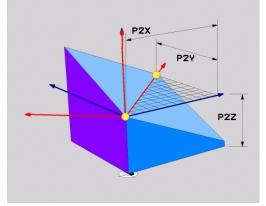
Abbreviations used

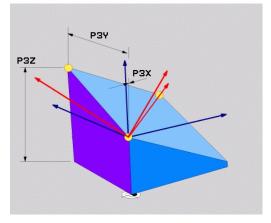
Abbreviation Meaning

Points

POINTS







Defining the working plane via a single incremental spatial angle: PLANE RELATIV

Application

A

Use a relative spatial angle when an already active tilted working plane is to be tilted by **another rotation**. Example: machining a 45° chamfer on a tilted plane.

Programming notes:

- The defined angle is always in effect in respect to the active working plane, regardless of the tilting function you used before.
- You can program any number of PLANE RELATIV functions in a row..
- If you want to return the working plane to the orientation that was active before the PLANE RELATIV function, define the same PLANE RELATIV function again but enter the value with the opposite algebraic sign.
- If you use PLANE RELATIV without previous tilting, PLANE RELATIV will be effective directly in the workpiece coordinate system. In this case, you can tilt the original working plane by entering a defined spatial angle in the PLANE RELATIV function.
- You can select the desired positioning behavior.
 Further information: "Specifying the positioning behavior of the PLANE function", page 498

Input parameters



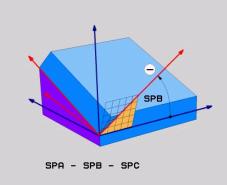
- Incremental angle?: Spatial angle by which the active machining plane is to be rotated. Use a soft key to select the axis to be rotated around. Input range: -359.9999° to +359.9999°
- Continue with the positioning properties
 Further information: "Specifying the positioning behavior of the PLANE function", page 498

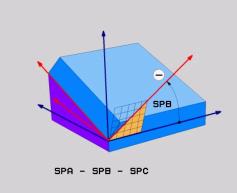
Example

N50 PLANE RELATIV SPB-45*

Abbreviations used

Abbreviation	Meaning
RELATIVE	Relative to



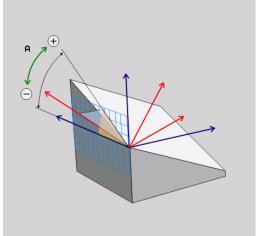


Tilting the working plane through axis angle: PLANE AXIAL

Application

The **PLANE AXIAL** function defines both the slope and the orientation of the working plane and the nominal coordinates of the rotary axes.

1	PLANE AXIAL can also be used on machines that have only one rotary axis. The input of nominal coordinates (axis angle input) is advantageous in that it provides an unambiguously defined tilting situation based on defined axis positions. Spatial angles entered without an additional definition are often mathematically ambiguous. Without the use of a CAM system, entering axis angles, in most cases, only makes sense if the rotary axes are positioned perpendicularly.
0	Refer to your machine manual. If your machine allows spatial angle definitions, you can continue your programming with PLANE RELATIV after PLANE AXIAL .
•	 Programming notes: The axis angles must correspond to the axes present on the machine. If you try to program axis angles for rotary axes that do not exist on the machine, the control will generate an error message. Use PLANE RESET to reset the PLANE AXIAL function. Entering 0 only resets the axis angle, but does not deactivate the tilting function. The axis angles of the PLANE AXIAL function are modally effective. If you program an incremental axis angle, the control will add this value to the currently effective axis angle. If you program two different rotary axes in two successive PLANE AXIAL functions, the new working plane is derived from the two defined axis angles. The SEQ, TABLE ROT and COORD ROT functions have no effect in conjunction with PLANE AXIAL.
	The PLANE AXIAL function does not take basic rotation into account.

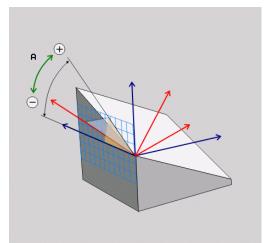


Input parameters Example

N50 PLANE AXIAL B-45*

Axis angle A?: Axis angle to which the A axis
is to be tilted. If entered incrementally, it is the
angle by which the A axis is to be tilted from its
current position. Input range: –99999.9999° to +99999.9999°

- Axis angle B?: Axis angle to which the B axis is to be tilted. If entered incrementally, it is the angle by which the B axis is to be tilted from its current position. Input range: -99999.9999° to +99999.9999°
- Axis angle C?: Axis angle to which the C axis is to be tilted. If entered incrementally, it is the angle by which the C axis is to be tilted from its current position. Input range: –99999.9999° to +99999.9999°
- Continue with the positioning properties
 Further information: "Specifying the positioning behavior of the PLANE function", page 498



Abbreviations used

Abbreviation	Meaning
AXIAL	In the axial direction

Specifying the positioning behavior of the PLANE function

Overview

Independently of which PLANE function you use to define the tilted machining plane, the following functions are always available for the positioning behavior:

- Automatic positioning
- Selection of alternate tilting possibilities (not with **PLANE AXIAL**)
- Selection of the type of transformation (not with PLANE AXIAL)

NOTICE

Danger of collision!

Cycle **28 MIRROR IMAGE** may have different effects in conjunction with the **Tilt working plane** function. The effect mainly depends on the programming sequence, the mirrored axes and the tilting function used. There is a danger of collision during the tilting operation and subsequent machining.

- Check the sequence and positions using a graphic simulation
- Carefully test the NC program or program section in the Program run, single block operating mode

Examples

- 1 Cycle **28 MIRROR IMAGE** programmed before the tilting function without rotary axes:
 - The tilt of the PLANE function used (except PLANE AXIAL) is mirrored
 - The mirroring is effective after the tilt with PLANE AXIAL or Cycle 19
- 2 Cycle **28 MIRROR IMAGE** programmed before the tilting function with a rotary axis:
 - The mirrored rotary axis has no effect on the tilt specified in the **PLANE** function used, because only the movement of the rotary axis is mirrored

Automatic positioning: MOVE/TURN/STAY (entry is mandatory)

After you have entered all parameters for the plane definition, you must specify how the rotary axes will be positioned to the calculated axis values:

MOVE	•	The PLANE function is to automatically position the rotary axes to the calculated position values. The position of the tool relative to the workpiece remains the same.
		The control carries out a compensation movement in the linear axes.
TURN	•	The PLANE function is to automatically position the rotary axes to the calculated position values, but only the rotary axes are positioned.
		The control does not carry out a compensation movement for the linear axes.
STAY		You will position the rotary axes later in a separate positioning block

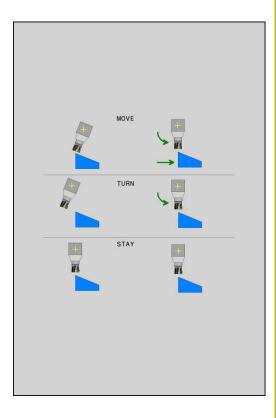
If you selected the **MOVE** option (the **PLANE** function is used to position the axes automatically), the following two parameters: **Dist. tool tip - center of rot.** and **Feed rate? F =** are still to be defined.

If you selected the **TURN** option (the **PLANE** function is used to position the axes automatically), the following parameter: **Feed** rate? F = is still to be defined.

As an alternative to defining a feed rate **F** directly by entering a numerical value, you can also position the axes with **FMAX** (rapid traverse) or **FAUTO** (feed rate from the **T** block).



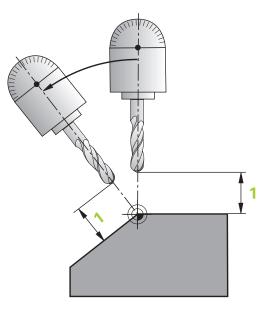
If you use **PLANE** together with **STAY,** you have to position the rotary axes in a separate block after the **PLANE** function.

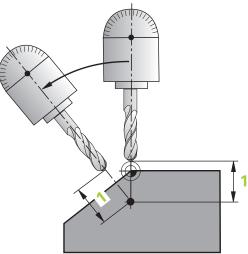


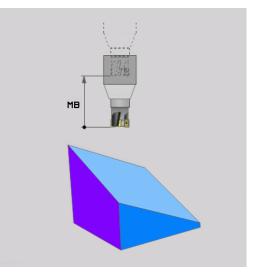
- Dist. tool tip center of rot. (incremental): The DIST parameter shifts the center of rotation of the movement relative to the current position of the tool tip.
 - If the tool is already at the given distance to the workpiece before positioning, then the tool is at the same relative position after positioning (see figure at center right, 1 = DIST)
 - If the tool is not at the given distance to the workpiece before positioning, then the tool is offset relatively from the original position after positioning (see figure at bottom right, 1 = DIST)

The control tilts the tool (or table) relative to the tool tip.

- Feed rate? F=: Contour speed at which the tool should be positioned
- Retraction length in the tool axis?: The retraction path MB is effective incrementally from the current tool position in the active tool axis direction that the control approaches before tilting. MB MAX positions the tool just before the software limit switch.







Positioning the rotary axes in a separate block

Proceed as follows if you want to position the rotary axes in a separate positioning block (option **STAY** selected):

NOTICE Danger of collision!

The control does not automatically check whether collisions can occur between the tool and the workpiece. Incorrect or no prepositioning before tilting the tool to position can lead to a risk of collision during the tilting movement!

- Program a safe position of the tool before the tilting movement.
- Carefully test the NC program or program section in the Program run, single block operating mode
- Select any PLANE function, and define automatic tilting to position with the STAY option. During program execution, the control calculates the position values of the rotary axes present on the machine, and stores them in the system parameters Q120 (A axis), Q121 (B axis) and Q122 (C axis)
- Define the positioning block with the angular values calculated by the control.

Example: Tilt a machine with a rotary table C and a tilting table A to a spatial angle of B+45

•••	
N10 G00 Z+250 G40*	Position at clearance height
N20 PLANE SPATIAL SPA+0 SPB+45 SPC+0 STAY*	Define and activate the PLANE function
N30 G01 A+Q120 C+Q122 F2000*	Position the rotary axis with the values calculated by the control.
	Define machining in the tilted working plane

Selection of alternate tilting possibilities: SEQ +/- (entry optional)

The orientation you define for the working plane is used by the control to calculate the appropriate position of the rotary axes on your machine. In general, there are always two possible solutions.

Use the **SEQ** switch to specify which possible solution the control should use:

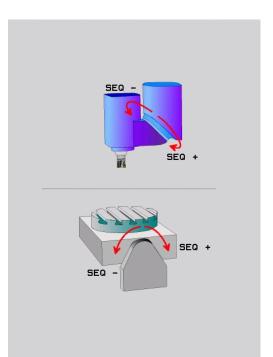
- SEQ+ positions the master axis so that it assumes a positive angle. The master axis is the first rotary axis going out from the tool or the last rotary axis going out from the table (depending on the machine configuration)
- **SEQ-** positions the master axis so that it assumes a negative angle.

If the solution you chose with **SEQ** is not within the machine's range of traverse, the control displays the **Entered angle not permitted** error message.

When the function is used, the switch is nonfunctional.

If you do not define $\ensuremath{\text{SEQ}}$, the control determines the solution as follows:

- 1 The control first checks whether both possible solutions are within the traverse range of the rotary axes.
- 2 If they are, then the control selects the shortest possible solution based on the current position of the rotary axes.
- 3 If only one solution is within the traverse range, the control selects this solution
- 4 If neither solution is within the traverse range, the control displays the **Entered angle not permitted** error message.



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Example for machine with rotary table C and tilting table A. Programmed function: PLANE SPATIAL SPA+0 SPB+45 SPC+0

0	050	
Starting position	SEQ	Resulting axis position
A+0, C+0	not prog.	A+45, C+90
A+0, C+0	+	A+45, C+90
A+0, C+0	-	A–45, C–90
A+0, C–105	not prog.	A–45, C–90
A+0, C–105	+	A+45, C+90
A+0, C–105	-	A–45, C–90
A+0, C+0	not prog.	A–45, C–90
A+0, C+0	+	Error message
A+0, C–135	+	A+45, C+90
	A+0, C+0 A+0, C+0 A+0, C-105 A+0, C-105 A+0, C-105 A+0, C+0 A+0, C+0	A+0, C+0 not prog. A+0, C+0 + A+0, C+0 - A+0, C-105 not prog. A+0, C-105 + A+0, C-105 - A+0, C-105 - A+0, C-105 + A+0, C-105 + A+0, C+0 not prog. A+0, C+0 +

Selecting the type of transformation (entry optional)

The transformation types **COORD ROT** and **TABLE ROT** influence the orientation of the working plane coordinate system through the axis position of a so-called free rotary axis.

Any rotary axis becomes a free rotary axis with the following constellation:

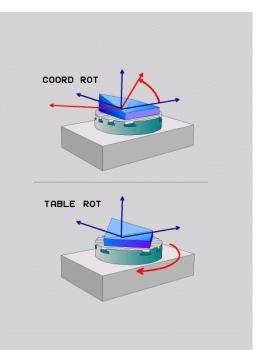
- the rotary axis has no effect on the tool angle of inclination because the rotation axis and tool axis are parallel in the tilting situation
- the rotary axis is the first rotary axis in the kinematic chain starting from the workpiece

The effect of the transformation types **COORD ROT** and **TABLE ROT** therefore depends on the programmed spatial angles and the machine kinematics.

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Programming notes:

- If no free rotary axis is created in a tilting situation, the COORD ROT and TABLE ROT transformation types have no effect
- With the PLANE AXIAL function the COORD ROT and TABLE ROT transformation types have no effect



Effect with a free rotary axis

Programming notes

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- For the positioning behavior with the COORD ROT and TABLE ROT transformation types, it does not matter if the free rotary axis is a table or head axis
- The resulting axis position of the free rotary axis depends on an active basic rotation among other factors
- The orientation of the working plane coordinate system also depends on a programmed rotation, for example with Cycle 10 ROTATION

Soft key	Effect
ROT	COORD ROT:
ĺ,	The control positions the free rotary axis to 0
	The control aligns the working plane coordinate system according to the programmed spatial angle
ROT	TABLE ROT with:
	SPA and SPB equal to 0
	SPC equal or unequal to 0
	The control aligns the free rotary axis according to the programmed spatial angle
	The control aligns the working plane coordinate system according to the basic coordinate system
	TABLE ROT with:
	At least SPA or SPB unequal to 0
	SPC equal or unequal to 0
	The control does not position the free rotary axis. The position before tilting the working plane is maintained
	Because the workpiece was not positioned, the control aligns the working plane coordinate system according to the programmed spatial angle
	f no transformation type was specified, the control uses the COORD ROT transformation type for the PLANE functions

Example

The example below shows the effect of the **TABLE ROT** transformation type in conjunction with a free rotary axis.

N60 G00 B+45 R0*

N70 PLANE SPATIAL SPA-90 SPB+20 SPC+0 TURN F5000 TABLE ROT* Pre-position rotary axis Tilt working plane

•••



The control positions the B axis to the axis angle B+45 With the programmed tilting situation with SPA-90, the B axis becomes the free rotary axis

The control does not position the free rotary axis. The position of the B axis before tilting the working plane is maintained

Because the workpiece was not positioned, the control aligns the working plane coordinate system according to the programmed spatial angle SPB+20

Tilting the working plane without rotary axes



Refer to your machine manual.

This feature must be enabled and adapted by the machine tool builder.

The machine tool builder must take the precise angle into account, e.g. the angle of a mounted angular head in the kinematics description.

You can also orient the programmed working plane perpendicularly to the tool without defining rotary axes, e.g. when adapting the working plane for a mounted angular head.

Use the **PLANE SPATIAL** function and the **STAY** positioning behavior to swivel the working plane to the angle specified by the machine tool builder.

Example of mounted angular head with permanent tool direction Y:

Example

N10 T 5 G17 S4500*

N20 PLANE SPATIAL SPA+0 SPB-90 SPC+0 STAY*

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The tilt angle must be precisely adapted to the tool angle, otherwise the control will generate an error message.

12.3 Miscellaneous functions for rotary axes

Feed rate in mm/min on rotary axes A, B, C: M116 (option 8)

Standard behavior

The control interprets the programmed feed rate of a rotary axis in degrees/min (in mm programs and also in inch programs). The feed rate therefore depends on the distance from the tool center to the center of the rotary axis.

The larger this distance becomes, the greater the contouring feed rate.

Feed rate in mm/min on rotary axes with M116

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Refer to your machine manual. The machine geometry must be specified by the machine tool builder in the description of kinematics.

Programming notes:

- The **M116** function can be used with table axes and head axes.
- The M116 function is also effective if the Tilt working plane function is active.
- It is not possible to combine the M128 or TCPM functions with M116. If you want to activate M116 for an axis while the M128 or TCPM function is active, you must deactivate the compensating movement for this axis indirectly using M138. This is done indirectly because with M138, you specify the axis for which the M128 or TCPM function is effective. Thus, M116 automatically affects the very axis that was not selected with M138.
 Further information: "Selecting tilting axes: M138", page 510
- Without the M128 or TCPM function, M116 can be effective for two rotary axes at the same time.

The control interprets the programmed feed rate of a rotary axis in mm/min (or 1/10 inch/min). In this case, the control calculates the feed rate for the block at the start of each block. The feed rate of a rotary axis will not change while the block is executed, even if the tool moves toward the center of the rotary axis.

Effect

M116 is effective in the working plane. Reset **M116** with **M117**. At the end of the program, **M116** is automatically canceled.

M116 becomes effective at the start of the block.

Shortest-path traverse of rotary axes: M126

Standard behavior



Refer to your machine manual.

The positioning behavior of rotary axes is machinedependent.

The default behavior of the control while positioning rotary axes whose display has been reduced to values less than 360° is dependent on the **shortestDistance** machine parameter (no. 300401). This machine parameter defines whether the control should consider the difference between nominal and actual positions, or whether it should always choose the shortest path to the programmed position (even without M126). Examples:

Actual position	Nominal position	Traverse
350°	10°	–340°
10°	340°	+330°

Behavior with M126

With **M126**, the control will move a rotary axis, whose display is reduced to values less than 360°, on the shortest path of traverse. Examples:

Actual position	Nominal position	Traverse	
350°	10°	+20°	
10°	340°	-30°	

Effect

M126 becomes effective at the start of the block.

To cancel **M126**, enter **M127**. At the end of program, **M126** is automatically canceled.

Reducing display of a rotary axis to a value less than 360°: M94

Standard behavior

The control moves the tool from the current angular value to the programmed angular value.

Example:

Current angular value:	538°
Programmed angular value:	180°
Actual distance of traverse:	-358°

Behavior with M94

At the start of block, the control first reduces the current angular value to a value less than 360° and then moves the tool to the programmed value. If multiple rotary axes are active, **M94** will reduce the display of all rotary axes. As an alternative, you can specify a rotary axis after **M94**. The control then reduces the display of this axis only.

If you entered a traverse limit or a software limit switch is active, M94 is ineffective for the corresponding axis.

Example: Reduce the display of all active rotary axes

N50 M94*

Example: Reduce the display of the C axis

N50 M94 C*

Example: Reduce the display of all active rotary axes and then move the tool in the C axis to the programmed value

M50 G00 C+180 M94*

Effect

 $\boldsymbol{\textbf{M94}}$ is effective only in the NC block where it is programmed.

M94 becomes effective at the start of the block.

Selecting tilting axes: M138

Standard behavior

The control performs **M128**, and **Tilt working plane** only for those axes that the machine tool builder has specified in the machine parameters.

Behavior with M138

The control performs the above functions only in those tilting axes that you have defined using **M138**.



Refer to your machine manual.

If you restrict the number of tilting axes with the **M138** function, your machine may provide only limited tilting possibilities. The machine tool builder will decide whether the control takes the angles of deselected axes into account or sets them to 0.

Effect

M138 becomes effective at the start of the block.

You can cancel **M138** by reprogramming it without specifying any axes.

Example

Perform the above-mentioned functions only in the tilting axis C.

N50 G00 Z+100 G40 M138 C*



Manual Operation and Setup

13.1 Switch-on, switch-off

Switch-on

ADANGER

Caution: Danger for the operator!

Machines and machine components always present mechanical hazards. Electric, magnetic or electromagnetic fields are particularly hazardous for persons with cardiac pacemakers or implants. The hazard starts when the machine is powered up!

- Read and follow the machine manual
- Read and follow the safety precautions and safety symbols
- Use the safety devices

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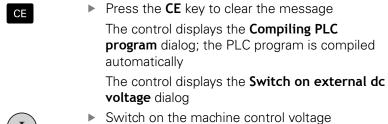
Refer to your machine manual.

Switching on the machine and traversing the reference points can vary depending on the machine tool.

Switch the machine and the control on as follows:

Switch on the power supply for the control and the machine The control displays the switch-on status in the subsequent dialogs.

If booting was successful, the control displays the $\ensuremath{\textbf{Power}}$ interrupted dialog



 Switch on the machine control voltage The control carries out a self-test.

If the control does not register an error, it displays the **Traverse** reference points dialog.

If the control registers an error, it issues an error message.

Check the axis positions



This section applies only to machine axes with EnDat encoders.

If the actual axis position after the machine is switched on does not match the position at switch-off, the control displays a pop-up window.

- Check the axis position of the affected axis
- If the current axis position matches that proposed in the display, confirm with YES

NOTICE

Danger of collision!

If they are not paid attention to, deviations between the actual axis positions and those expected by the control (saved at the time of switch-off) can lead to undesirable and unforeseeable movements of the axes. There is risk of collision during referencing and all subsequent movements.

- Check the axis positions
- Only confirm the pop-up window with YES if the axis positions match
- Despite confirmation, at first only move the axis carefully
- If there are discrepancies or you have any doubts, contact your machine tool builder

Traverse reference points

If the control performs the self-test successfully, it then displays the **Traverse reference points** dialog.

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Refer to your machine manual. Switching on the machine and traversing the reference points can vary depending on the machine tool. If your machine is equipped with absolute encoders, you can leave out crossing the reference points.
If you intend only to edit or graphically simulate NC programs, you can select the Programming or Test Run mode of operation immediately after switching on the control voltage, without needing to reference the axes.
You can neither set a preset nor modify a preset via the preset table without having referenced the axes. The control issues the Traverse reference points hint.
You can cross the reference points later. For this purpose, in Manual operation mode press the PASS OVER REFERENCE soft key.

Cross the reference points manually in the displayed sequence:

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	_		
	Ť	Ľ	
	+	-	

For each axis press the NC START button, or The control is now ready for operation in the Manual operation mode.

As an alternative you can cross the reference points in any sequence:

	X+
ſ	Y+

Press and hold the axis direction button for each axis until the reference point has been traversed The control is now ready for operation in the Manual operation mode.

Crossing the reference point in a tilted working plane

If the **Tilt working plane** function was active before the control was switched off, then the control automatically activates the function after restarting. This means that movements via the axis keys take place in the tilted working plane.

Before traversing the reference points you must deactivate the **Tilt the working plane** function, otherwise the control interrupts the process with an error message. You can also reference axes not activated in the current kinematic model without needing to deactivate **Tilt the working plane**, such as a tool magazine.

Further information: "Activating manual tilting:", page 576

NOTICE

Danger of collision!

The control does not automatically check whether collisions can occur between the tool and the workpiece. Incorrect prepositioning or insufficient spacing between components can lead to a risk of collision when referencing the axes.

- Pay attention to the information on the screen
- If necessary, move to a safe position before referencing the axes
- Watch out for possible collisions



If the machine does not have any absolute encoders, the position of the rotary axes must be confirmed. The position shown in the pop-up window is the last position before the control was switched off.

Switch-off



Refer to your machine manual.

Deactivation is a machine-dependent function.

To prevent data from being lost on switch-off, you need to shut down the operating system of the control as follows:



 Operating mode: Press the Manual operation key



DOWN

- Press the OFF soft key
- ► Confirm with the **SHUT DOWN** soft key
- When the control displays the message Now you can switch off in a pop-up window, you may switch off the power supply to the control

NOTICE

Caution: Data may be lost!

The control must be shut down so that running processes can be concluded and data can be saved. Immediate switch-off of the control by turning off the main switch can lead to data loss not matter what state the control was in.

- Always shut down the control
- Only turn off the main switch after being prompted on the screen

13.2 Moving the machine axes

Note



Refer to your machine manual. Movement of the axes via the axis direction keys can vary depending on the machine.

Moving the axis with the axis direction keys

(m)	Operating mode: Press the Manual operatio key	n
X+	Press the axis direction key and hold it down long as you wish the axis to move; or	as
X+	To move the axis continuously: Press and ho the axis direction button and press the NC St key	
	To stop: Press the NC Stop key	

You can move several axes at a time with these two methods. The control then shows the feed rate. You can change the feed rate at which the axes are moved with the \mathbf{F} soft key.

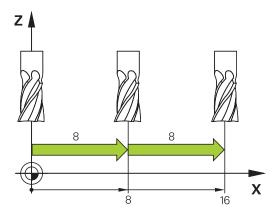
Further information: "Spindle speed S, feed rate F and miscellaneous function M", page 529

If a moving task is active on the machine, the control displays the **control in operation** symbol.

Incremental jog positioning

With incremental jog positioning you can move a machine axis by a preset distance.

$\textcircled{\begin{tabular}{ c c c c } \hline \hline & \hline & \hline & \hline & \hline & \hline & \hline & & \hline & \hline & & \hline \\ & \hline & \hline$	 Operating mode: Press the Manual operation or Electronic handwheel key
	Shift the soft-key row
INCRE- MENT OFF ON	 Select incremental jog positioning: Switch the INCREMENT soft key to ON
CONFIRM VALUE	Enter the infeed of the linear axes and confirm with the CONFIRM VALUE soft key
ENT	Alternatively, confirm with the ENT key
t	 Use the arrow keys to position the cursor on the rotary axis
CONFIRM VALUE	Enter the infeed of the rotary axes and confirm with the CONFIRM VALUE soft key
ENT	Alternatively, confirm with the ENT key
и ок	Confirm with the OK soft key
V OK	The increment is active.
INCRE- MENT OFF ON	Deactivate incremental jog positioning: Switch the INCREMENT soft key to OFF
6	If you are in the Jog increment menu, you can switch off incremental jog positioning with the SWITCH OFF soft key.
	The input range for the infeed is from 0.001 mm to 10 mm.



Traverse with electronic handwheels

Caution: Danger for the operator!

Unsecured connections, defective cables, and improper use are always sources of electrical dangers. The hazard starts when the machine is powered up!

- Devices should be connected or removed only by authorized service technicians
- Only switch on the machine via a connected handwheel or a secured connection

The control supports traversing with the following new electronic handwheels:

- HR 510: Simple handwheel without display, data transfer via cable
- HR 520: Handwheel with display, data transfer via cable
- HR 550FS: Handwheel with display, data transfer via radio

In addition to this, the control continues to support the cable handwheels HR 410 (without display) and HR 420 (with display).

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Refer to your machine manual.

Your machine tool builder can make additional functions of the HR 5xx handwheels available.



If you want to use the **Handwheel superimp.:** function in a virtual tool axis **VT**, then we recommend the handwheel HR 5xx.

Further information: "Virtual tool axis VT", page 440

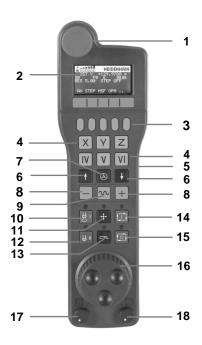
The portable HR 520 and HR 550FS handwheels feature a display on which the control shows information. In addition, you can use the handwheel soft keys for important setup functions, e.g. presetting or entering and running M functions.

As soon as you have activated the handwheel with the handwheel activation key, the operating panel is locked. The control shows this status in a pop-up window on the screen.



1 EMERGENCY STOP key

- 2 Handwheel display for status and for selecting functions
- 3 Soft keys
- **4** Axis keys; can be exchanged by the machine manufacturer depending on the axis configuration
- 5 Permissive key
- 6 Arrow keys for defining handwheel sensitivity
- 7 Handwheel activation key
- 8 Key for traverse direction of the selected axis
- **9** Rapid traverse superimposing for the axis direction key
- **10** Spindle switch-on (machine-dependent function, key can be exchanged by the machine manufacturer)
- **11 Generate NC block** key (machine-dependent function, key can be exchanged by the machine manufacturer)
- **12** Spindle switch-off (machine-dependent function, key can be exchanged by the machine manufacturer)
- **13 CTRL** key for special functions (machine-specific function, key can be exchanged by the machine manufacturer)
- **14 NC START** key (machine-dependent function, key can be exchanged by the machine manufacturer)
- **15 NC STOP** key (machine-dependent function, key can be exchanged by the machine manufacturer)
- 16 Handwheel
- 17 Spindle speed potentiometer
- **18** Feed rate potentiometer
- **19** Cable connection, not available with the HR 550FS wireless handwheel



Handwheel display

- 1 Only with wireless handwheel HR 550FS: Shows whether the handwheel is in the docking station or whether wireless operation is active
- 2 Only with wireless handwheel HR 550FS: Shows the signal strength, 6 bars = maximum signal strength
- **3** Only with wireless handwheel HR 550FS: Shows the charge status of the rechargeable battery, 6 bars = fully charged A bar moves from the left to the right during recharging
- 4 ACTL: Type of position display
- 5 Y+129.9788: Position of the selected axis
- 6 *: STIB (control in operation); program run has been started or axis is in motion
- 7 SO: Current spindle speed
- 8 F0: Feed rate at which the selected axis is moving
- 9 E: Error message

If an error message appears on the control, the handwheel display shows the message **ERROR** for three seconds. Then the letter **E** is shown in the display as long as the error is pending on the control.

- 10 3D: Tilted-working-plane function is active
- 11 2D: Basic rotation function is active
- **12 RES 5.0**: Active handwheel resolution. Path traversed by the selected axis with a handwheel revolution
- **13 STEP ON** or **OFF**: Incremental jog active or inactive. If the function is active, the control additionally displays the current traversing step
- **14** Soft-key row: Selection of various functions, described in the following sections



Special features of the wireless handwheel HR 550FS

ADANGER

Caution: Danger for the operator!

Wireless handwheels, due to their rechargeable batteries and the influence of other wireless devices, are more susceptible to interference than cable-bound connections are. Ignoring the requirements for and information about safe operation leads to endangerment of the user, for example during installation or maintenance work.

- Check the radio connection of the handwheel for possible overlapping with other wireless devices
- Switch off the wireless handwheel and the handwheel holder after an operating time of 120 hours at the latest so that the control can run a functional test when it is restarted
- If more than one wireless handwheel is being used in a workshop, then ensure an unambiguous assignment between the handwheels and the handwheel holders (such as with color-coded stickers)
- If more than one wireless handwheel is being used in a workshop, then ensure an unambiguous assignment between the handwheels and the respective machine (such as with a functional test)

The HR 550FS wireless handwheel features a rechargeable battery. The battery starts charging when you put the handwheel in the holder.

You can operate the HR 550FS with the battery for up to 8 hours before it must be recharged again. When the handwheel is completely discharged, it takes about 3 hours until it is fully recharged in the handwheel holder. If the HR 550 is not needed, always put it in the handwheel holder. This way you can ensure that the handwheel batteries are always ready for use thanks to the contact strip on the rear side of the wireless handwheel and the recharge control, and that there is a direct contact connection for the emergency stop circuit.

As soon as the handwheel is in its holder, it switches internally to cable operation. This means you can still use it even if the handwheel is fully discharged. The functions are the same as with wireless operation.



Clean the contacts **1** in the handwheel holder and of the handwheel regularly to ensure their proper functioning.

The transmission range is amply dimensioned. If you should nevertheless happen to come near the edge of the transmission area, which is possible with very large machines, the HR 550FS warns you in time with a plainly noticeable vibration alarm. If this happens you must reduce the distance to the handwheel holder in which the radio receiver is integrated.





NOTICE

Caution: Danger to the tool and workpiece!

The wireless handwheel triggers an emergency stop reaction if the radio transmission is interrupted, the battery is fully empty, or if there is a defect. Emergency stop reactions during machining can cause damage to the tool or workpiece.

- Place the handwheel in the handwheel holder when it is not in use
- Keep the distance between the handwheel and the handwheel holder small (pay attention to the vibration alarm)
- Test the handwheel before machining

If the control has triggered an emergency stop you must reactivate the handwheel. Proceed as follows:

- Press the MOD key to select the MOD function
- Select Machine settings
- SET UP WIRELESS HANDWHEEL
- Press the SET UP WIRELESS HANDWHEEL soft key
- Click the Start handwheel button to reactivate the wireless handwheel
- To save the configuration and exit the configuration menu, press END

The **MOD** operating mode includes a function for commissioning and configuring the handwheel.

Further information: "Configuring the HR 550FS wireless handwheel", page 652

Selecting the axis to be moved

You can activate the principal axes X, Y, Z and three other axes defined by the machine manufacturer directly through the axis keys. Your machine tool builder can also place the virtual axis VT directly on one of the free axis keys. If the virtual axis VT is not on one of the axis keys, proceed as follows:

Press the handwheel soft key F1 (AX)

The control shows all active axes on the handwheel display. The currently active axis flashes.

Select the desired axis with the handwheel soft keys F1 (->) or F2 (<-) and confirm with the F3 (OK) handwheel soft key</p>

Setting the handwheel sensitivity

The handwheel sensitivity determines which path an axis takes per revolution of the handwheel. The sensitivity levels are predefined and are selectable with the handwheel arrow keys (only when incremental jog is not active).

Selectable sensitivity levels: 0.001/0.002/0.005/0.01/0.02/0.05/0.1/0.2/0.5/1 [mm/revolution or degrees/revolution]

Selectable sensitivity levels:

0.00005/0.001/0.002/0.004/0.01/0.02/0.03 [in mm/revolution or degrees/revolution]

Moving the axes

		To activate the handwheel, press the handwheel button on the HR 5xx:
		Now you can operate the control only via the HR 5xx. The control displays a pop-up window with this information on the screen.
	•	Select the desired operating mode with the OPM soft key if necessary
		If required, press and hold the permissive button
X		Use the handwheel to select the axis to be moved. Select the additional axes with the soft keys as required
+		Move the active axis in the positive direction with the + key, or
-	•	Move the active axis in the negative direction with the - key
$\textcircled{\black}{\black}$		To deactivate the handwheel, press the handwheel key on the HR 5xx
		Now you can operate the control via the operating panel again.

Potentiometer settings

ADANGER

Caution: Danger for the operator!

Activating the handwheel does not automatically activate the potentiometers of the handwheel; rather the potentiometers on the operating panel of the control remain active. After an NC start on the handwheel, the control immediately begins with machining or with axis positioning, even though the potentiometers on the handwheel are set to 0 %. There is a risk of death to anybody inside the working space!

- Before using the handwheel, set the potentiometers of the operating panel to 0 %
- When using the handwheel, always also activate the potentiometers of the handwheel

The potentiometers of the machine operating panel continue to be active after you have activated the handwheel. If you want to use the potentiometers on the handwheel, proceed as follows:

Press the CTRL and handwheel keys on the HR 5xx at the same time

The control shows the soft-key menu for selecting the potentiometers in the handwheel's display.

Press the HW soft key to activate the handwheel potentiometers

If you have activated the potentiometers on the handwheel, you must reactivate the potentiometers of the machine operating panel before deselecting the handwheel. Proceed as follows:

Press the CTRL and handwheel keys on the HR 5xx at the same time

The control shows the soft-key menu for selecting the potentiometers in the handwheel's display.

Press the KBD soft key to activate the potentiometers of the machine operating panel

The control issues a warning if the handwheel potentiometers are still active after the handwheel has been deactivated.

Incremental jog positioning

With incremental jog positioning the control moves the currently active handwheel axis by a preset increment defined by you:

- Press the handwheel soft key F2 (STEP)
- Activate incremental jog positioning: Press handwheel soft key 3 (ON)
- Select the desired jog increment by pressing the F1 or F2 key. The smallest possible increment is 0.0001 mm (0.00001 inches). The largest possible increment is 10 mm (0.3937 inches).
- Confirm the selected jog increment with soft key 4 (OK)
- With the + or handwheel key, move the active handwheel axis in the corresponding direction



If you press and hold the **F1** or **F2** key, each time it reaches a decimal value 0 the control increases the counting increment by a factor of 10.

By also pressing the **CTRL** key, you can increase the counting increment by a factor of 100 when pressing **F1** or **F2**.

Inputting miscellaneous functions M

- Press the F3 (MSF) handwheel soft key
- Press the F1 (M) handwheel soft key
- Select the desired M function number by pressing the F1 or F2 key
- Execute the M miscellaneous function with the **NC Start** key

Entering the spindle speed S

- Press the F3 (MSF) handwheel soft key
- Press the F2 (S) handwheel soft key
- Select the desired speed by pressing the F1 or F2 key
- Activate the new speed S with the NC Start key



If you press and hold the **F1** or **F2** key, each time it reaches a decimal value 0 the control increases the counting increment by a factor of 10.

By also pressing the CTRL key, you can increase the counting increment by a factor of 100 when pressing F1 or F2.

Entering the feed rate F

- Press the F3 (MSF) handwheel soft key
- Press the F3 (F) handwheel soft key
- Select the desired feed rate by pressing the F1 or F2 key
- Confirm the new feed rate F with the F3 (OK) handwheel soft key

If you press and hold the **F1** or **F2** key, each time it reaches a decimal value 0 the control increases the counting increment by a factor of 10.

By also pressing the **CTRL** key, you can increase the counting increment by a factor of 100 when pressing **F1** or **F2**.

Presetting

0

Refer to your machine manual. The machine tool builder can disable presetting in individual axes.

- Press the F3 (MSF) handwheel soft key
- Press the F4 (PRS) handwheel soft key
- If required, select the axis in which the preset is to be set.
- Zero the axis with the handwheel soft key F3 (OK) or with F1 and F2 set the desired value and then confirm with F3 (OK). By also pressing the CTRL key, you can increase the counting increment to 10

Changing modes of operation

With the handwheel soft key **F4** (**OPM**) you can use the handwheel to switch the operating mode, provided that the current status of the control allows a mode change.

- Press the F4 (OPM) handwheel soft key
- Select the desired operating mode by handwheel soft key
 - MAN: Manual operation
 MDI: Positioning w/ Manual Data Input
 SGL: Program run, single block
 RUN: Program run, full sequence

Generating a complete traversing block



Refer to your machine manual.

Your machine tool builder can assign any function to the **Generate NC block** handwheel key.

- Select the Positioning w/ Manual Data Input operating mode
- If required, use the arrow keys on the control's keyboard to select the NC block after which the new traversing block is to be inserted
- Activate the handwheel
- Press the Generate NC block key on the handwheel The control inserts a complete traversing block containing all axis positions selected through the MOD function.

Features in the program run modes of operation

You can use the following functions in the Program Run modes of operation:

- The NC Start key (NC Start handwheel key)
- The NC Stop key (NC Stop handwheel key)
- After the NC Stop key has been pressed: Internal stop (handwheel soft keys MOP and then Stop)
- After the NC STOP key has been pressed: Traverse manual axes (handwheel soft keys MOP and then MAN)
- Returning to the contour after the axes were moved manually during a program interruption (MOP and then REPO handwheel soft keys). The handwheel soft keys, which function similarly to the screen soft keys, are used for operating.
 Further information: "Returning to the contour", page 618
- On/off switch for the Tilt working plane function (handwheel soft keys MOP and then 3D)

13.3 Spindle speed S, feed rate F and miscellaneous function M

Application

In the Manual operation and Electronic handwheel operating modes, you can enter the spindle speed S, feed rate F and the miscellaneous functions M with soft keys.

Further information: "Entering miscellaneous functions M and STOP", page 426

IO

Refer to your machine manual.

The machine tool builder defines which additional functions are available on the machine.

Entering values

Spindle speed S, miscellaneous function M

```
S
```

Select input for spindle speed: press the S soft key

SPINDLE SPEED S=



Enter 1000 (spindle speed) and apply this value with the NC Start key

The spindle speed with the entered speedS is started with a miscellaneous function M. Input a miscellaneous function M in the same way.

The control shows the current spindle speed in the status display. If the spindle speed is less than 1000, the control also shows a decimal place that has been entered.

Feed rate F

After entering a feed rate **F**, confirm your entry with the **ENT** key. The following is valid for feed rate F:

- If you enter F=0, then the feed rate that the machine tool builder has defined as minimum feed rate is effective
- If the feed rate entered exceeds the maximum value that has been defined by the machine tool builder, then the value defined by the machine tool builder is effective
- F is not lost during a power interruption
- The control displays the feed rate.
 - When **3D ROT** is active the machining feed rate is shown if several axes are moved
 - If 3D ROT is not active, the feed drive display remains empty if several axes are moved

Adjusting spindle speed and feed rate

With the potentiometers you can vary the spindle speed S and feed rate F from 0 % to 150 % of the set value.

The feed rate potentiometer only lowers the programmed feed rate, not the feed rate calculated by the control.



The override for spindle speed is only functional on machines with infinitely variable spindle drive.



Feed rate limit F MAX



Refer to your machine manual.

The feed-rate limit depends on the machine.

The **F MAX** soft key enables you to reduce the feed rate speed for all operating modes. The reduction applies to all rapid traverse and feed rate movements. The value you enter remains active after switch-off or switch-on.

The ${\bf F}$ MAX soft key is available in the following operating modes:

- Program run, single block
- Program run, full sequence
- Positioning w/ Manual Data Input

Procedure

To activate the feed rate limit F MAX, proceed as follows:

F MAX

 Operating mode: Press the Positioning w/ Manual Data Input key

- Press the F MAX soft key
- Enter the desired maximum feed rate
- Press the OK soft key

13.4 Managing presets

Note

6		It is essential that you use the preset table in the following cases:		
	-	If your machine is equipped with rotary axes (tilting table or swivel head) and you work with the Tilt working plane function		
		If your machine is equipped with a spindle-head changing system		
		If up to now you have been working with older controls with REF-based datum tables		
		You wish to machine several identical workpieces		

The preset table can contain any number of rows (presets). To optimize the file size and the processing speed, only use as many rows as you need to manage your presets.

For safety reasons, new rows can be inserted only at the end of the preset table.

Saving presets in the table



Refer to your machine manual.

The machine tool builder can disable presetting in individual axes.

The preset table has the name **PRESET.PR**, and is saved in the **TNC:\table**\ directory. **PRESET.PR** is editable in the **Manual operation** and **Electronic handwheel** modes only if the **CHANGE PRESET** soft key was pressed. You can open the **PRESET.PR** preset table in the **Programming** operating mode but not edit it.

Copying the preset table into another directory (for data backup) is permitted. Write-protected rows are also write-protected in the copied tables.

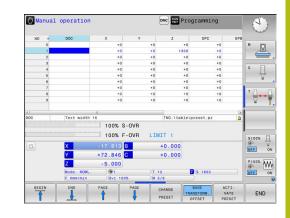
Never change the number of rows in the copied tables! If you want to reactivate the table, this may lead to problems.

To activate the preset table copied to another directory you have to copy it back to the **TNC:\table** directory

There are several methods for saving presets and basic rotations in the preset table:

- Manual input
- Using the probing cycles in the Manual operation and Electronic handwheel modes
- Using probing cycles 400 to 402 and 410 to 419 in automatic mode

Further information: Cycle Programming User's Manual



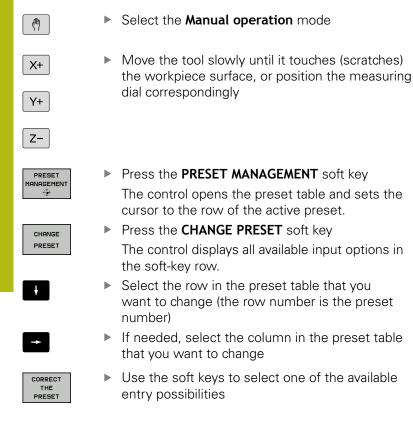


Operating notes:

- Basic rotations from the preset table rotate the coordinate system about the preset, which is shown in the same row as the basic rotation.
- When presetting, the positions of the tilting axes must match the tilted situation.
 - If the **Tilt working plane** function is not active, the position display for the rotary axes must be = 0° (zero the rotary axes if necessary)
 - If the **Tilt working plane** function is active, the position displays for the rotary axes must match the angles entered in the 3-D ROT menu
- PLANE RESET does not reset the active 3-D ROT.
- In row 0 the control always saves the preset that you most recently set manually via the axis keys or via soft key. If the preset set manually is active, the control displays the text **PR MAN(0)** in the status display.

Manually saving the presets in the preset table

Proceed as follows in order to save presets in the preset table:



Input options

Soft key	Function
- -	Directly transfer the actual position of the tool (the measuring dial) as the new preset: This function only saves the preset in the axis in which the cursor is currently hovering.
ENTER PRESET AGAIN	Assign any value to the actual position of the tool (the measuring dial): This function only saves the preset in the axis in which the cursor is current- ly hovering. Enter the desired value in the pop-up window
CORRECT THE PRESET	Incrementally shift a preset already stored in the table: This function only saves the preset in the axis in which the cursor is currently hovering. Enter the desired corrective value with the correct sign in the pop-up window. If inch display is active: Enter the value in inches, and the control will internally convert the entered values to mm
EDIT CURRENT FIELD	Directly enter the new preset without calculation of the kinematics (axis-specific). Only use this function if your machine has a rotary table, and you want to set the preset to the center of the rotary table by entering 0. This function only saves the value in the axis in which the cursor is currently hovering. Enter the desired value in the pop-up window. If inch display is active: Enter the value in inches, and the control will internally convert the entered values to mm
BASE TRANSFORM, OFFSET	Select the BASE TRANSFORM ./OFFSET view. The standard BASE TRANSFORM . view shows the X, Y and Z columns. Depending on the machine, the columns SPA, SPB, and SPC are displayed in addition. The control saves the basic rotation here (with the Z tool axis the control uses the SPC column). The OFFSET view shows the offset values for the preset.
SAVE ACTIVE PRESET	Write the currently active preset to a selectable line in the table: This function saves the preset in all axes, and then activates the appropriate row in the table automatically. If inch display is active: Enter the value in inches, and the control will internally convert the entered values to mm

Editing the preset table

Soft key	Editing function in table mode
BEGIN	Select the table start
	Select the table end
PAGE	Select the previous page in the table
	Select the next page in the table
CHANGE PRESET	Select the functions for entry of presets
BASE TRANSFORM. OFFSET	Choose between showing the Basic Transforma- tion or the Axis Offset
ACTI- VATE PRESET	Activate the preset of the selected row of the preset table
APPEND N LINES	Add multiple rows to the end of the table (2nd soft- key row)
COPY FIELD	Copy the highlighted field (2nd soft-key row)
PASTE	Insert the copied field (2nd soft-key row)
RESET	Reset the selected row: The control enters – in all columns (2nd soft-key row)
INSERT LINE	Insert a single line at the end of the table (2nd soft- key row)
DELETE LINE	Delete a single line at the end of the table (2nd soft-key row)

Protecting presets from being overwritten

You can protect any rows in the preset table from being overwritten with the **LOCKED** column. The write-protected rows are color-highlighted in the preset table.

If you want to overwrite a write-protected row with a manual probing cycle, confirm with **OK** and enter the password (where password-protected).

NOTICE

Caution: Data may be lost!

Rows that were locked with the **LOCK / UNLOCK PASSWORD** function can be unlocked only with the selected password. Forgotten passwords cannot be reset. This means that locked rows would be locked permanently. The preset table would thus no longer be fully usable.

- Prefer the alternative function LOCK / UNLOCK
- Note down your passwords

Proceed as follows to protect a preset from being overwritten:



Press the CHANGE PRESET soft key



Select the LOCKED column



Press the EDIT CURRENT FIELD soft key

Protection for a preset without using a password:



Press the LOCK / UNLOCK soft key The control writes an L in the LOCKED column.

Use a password to protect a preset:



ок

- Press the LOCK / UNLOCK PASSWORD soft key
- Enter the password in the pop-up window
- Confirm with the OK soft key or with the ENT key:

The control writes **###** in the **LOCKED** column.

Rescind write-protection

To edit a row you have previously write-protected, proceed as follows:



ł

Press the CHANGE PRESET soft key

Select the LOCKED column



Press the EDIT CURRENT FIELD soft key

Preset protected without a password:



Press the LOCK / UNLOCK soft key The control rescinds the write-protection.

Preset protected with a password:



Press the LOCK / UNLOCK PASSWORD soft key



- Enter the password in the pop-up window
- Confirm with the OK soft key or with the ENT key The control rescinds the write-protection.

Activating a preset

Activate a preset in the Manual operation mode

	NOTICE
Caution	: Significant property damage!
fields de overwrit	ed fields in the preset table behave differently from efined with the value 0 : Fields defined with the value 0 are the previous value when activated, whereas with ed fields the previous value is kept.
Before value	re activating a preset, check whether all columns contain es.
6	Operating notes:
U	When activating a preset from the preset table, the control resets any active datum shift, mirroring, rotation, or scaling factor.
	 On the other hand, the Tilt working plane function (Cycle G80 or PLANE) remains active.
Ś	Select the Manual operation mode
PRESET MANAGEMENT	Press the PRESET MANAGEMENT soft key
t	 Select the preset number that you want to activate
^{GOTO} □	 Or, with the GOTO key, select the preset number that you want to activate
ENT	Confirm with the ENT key
ACTI- VATE PRESET	Press the ACTIVATE PRESET soft key
EXECUTE	 Confirm activation of the preset The control sets the display and the basic rotation.
	 Exit the preset table

Activating a preset in an NC program

Use Cycle G247 in order to activate presets from the preset table during program run. In Cycle G247 you define the number of the preset to be activated.

Further information: Cycle Programming User's Manual

13.5 Presetting without a 3-D touch probe

Note

When presetting, you set the control display to the coordinates of a known workpiece position.



All manual probe functions are available with a 3-D touch probe.

Further information: "Presetting with a 3-D touch probe ", page 562



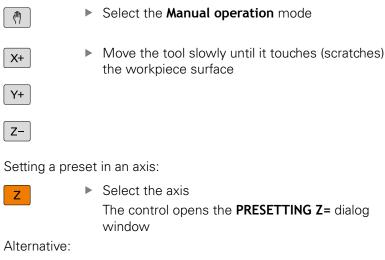
Refer to your machine manual.

The machine tool builder can disable presetting in individual axes.

Preparation

- Clamp and align the workpiece
- Insert the zero tool with known radius into the spindle
- Ensure that the control is showing the actual positions

Presetting setting with an end mill

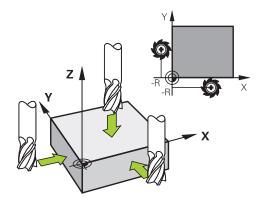




- Press the SET PRESET soft key
- Select the axis via soft key
- Zero tool in spindle axis: Set the display to a known workpiece position (here, 0) or enter the thickness d of the shim. In the tool axis, offset the tool radius

Repeat the process for the remaining axes.

If the tool in the tool axis has already been set, set the display of the tool axis to the length L of the tool or enter the sum Z=L+d.





Operating notes:

- The control automatically saves the preset set with the axis keys in row 0 of the preset table.
- If the machine tool builder has locked an axis, then you cannot set a preset in that axis. The soft key for that axis is then not visible.

Using touch probe functions with mechanical probes or measuring dials

If you do not have an electronic 3-D touch probe on your machine, you can also use all the previously described manual touch probe functions (exception: calibration function) with mechanical probes or by simply touching the workpiece with the tool.

Further information: "Using a 3-D touch probe ", page 540

In place of the electronic signal generated automatically by a 3-D touch probe during probing, you can manually initiate the trigger signal for capturing the **probing position** by pressing a key.

Proceed as follows:



Select any touch probe function by soft key

Move the mechanical probe to the first position

- to be captured by the control.
 To capture the position: Press the Actual-position-capture soft key
 - The control saves the current position.
- Move the mechanical probe to the next position to be captured by the control.
- To capture the position: Press the Actual-position-capture soft key

The control saves the current position.

- If required, move to additional positions and capture as described previously
- Preset: In the menu window, enter the coordinates of the new preset, confirm with the SET PRESET soft key, or write the values to a table

Further information: "Writing measured values from the touch probe cycles to a datum table", page 547

Further information: "Writing measured values from the touch-probe cycles to the preset table", page 548

Terminate the probing function: Press the END key



If you try to set a preset in a locked axis, the control will issue either a warning or an error message, depending on what the machine tool builder has defined.

13.6 Using a 3-D touch probe

Introduction

The behavior of the control during presetting depends on the setting in the optional machine parameter **chkTiltingAxes** (no. 204601):

chkTiltingAxes: On With an active tilted working plane, the control checks during presetting in the X, Y, and Z axes whether the current coordinates of the rotary axes agree with the tilt angles that you defined (3-D ROT menu). If the tilted working plane function is not active, the control checks whether the rotary axes are at 0° (actual positions). If the positions do not match, the control issues an error message.



The probing functions **PL** and **ROT** take the current rotary axes into account, and the probing points are derived from this position.

chkTiltingAxes: Off The control does not check whether the current coordinates of the rotary axes (actual positions) agree with the tilt angles that you defined.

If the machine parameter has not been set, the control checks as if **chkTiltingAxes: On** were set



Always set a preset in all three principal axes. This clearly and correctly defines the preset. That way you also taken into account possible deviations resulting from the tilting of the axes.

Overview

The following touch probe cycles are available in the **Manual operation** mode:



Refer to your machine manual. The control must be specially prepared by the machine

tool builder for the use of a 3-D touch probe.



HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.

Soft key	Function	Page
CALIBRATE TS	Calibrating the 3-D Touch Probe	549
PROBING	Measuring a 3-D basic rotation by probing a plane	559
PROBING	Measuring a basic rotation using a line	556
PROBING POS	Setting the preset on any axis	563
PROBING	Set a corner as preset	564
PROBING CC	Set a circle center as preset	566
PROBING	Setting the centerline as preset	569
TCH PROBE TABLE	Touch probe system data management	See Cycle Program- ming User's Manual
	For more information about the tou to the User's Manual for Cycle Pro	-

Traverse movements with a handwheel with display

With a handwheel with display, it is possible to transfer control to the handwheel during a manual touch probe cycle.

Proceed as follows:

- Start the manual touch probe cycle
- Position the touch probe at a position near the first touch point
- Probe the first touch point
- Activate the handwheel on the handwheel
 The control shows the pop-up window Handwheel active.
- Position the touch probe at a position near the second touch point
- Deactivate the handwheel on the handwheel The control closes the pop-up window.
- Probe the second touch point
- If necessary, set the preset
- End the probing function

i	

If the handwheel is active you cannot start the probing cycles.

Suppress touch probe monitoring

Suppress touch probe monitoring

If the stylus is deflected, the control issues an error message as soon as you want to move a machine axis.

You must deactivate touch-probe monitoring in the **Manual operation** mode in order to use a positioning block to retract a touch probe after it has deflected.

You can deactivate touch-probe monitoring for 30 seconds with the **TCH PROBE MONITOR OFF** soft key.

The control issues the error

message**The touch probe monitor is deactivated for 30 seconds**. The error message automatically clears itself after 30 seconds.



If the touch probe receives a stable signal within the 30 seconds, such as "Touch probe not deflected," then touch-probe monitoring reactivates itself automatically and the error message is cleared.

NOTICE

Danger of collision!

The **TCH PROBE MONITOR OFF** soft key suppresses the corresponding error message if the stylus is deflected. The control does not perform an automatic collision check with the stylus. Because of this behavior, you must check whether the touch probe can retract safely. There is a risk of collision if you choose the wrong direction for retraction.

Carefully move the axes in the Manual operation mode

Functions in touch probe cycles

Soft keys that are used to select the probing direction or a probing routine are displayed in the manual touch probe cycles. The soft keys displayed vary depending on the respective cycle:

Soft key	Function
X +	Select the probing direction
	Capture the actual position
	Probe hole (inside circle) automatically
	Probe stud (outside circle) automatically
PROBING CC	Probe a model circle (center point of several elements)
	Select a paraxial probing direction for probing of holes, studs and model circles

Automatic probing routine for holes, studs and model circles

NOTICE

Danger of collision!

The control does not perform an automatic collision check with the stylus. During automatic probing procedures the control positions the touch probe to the probing positions automatically. There is a risk of collision if pre-positioning was not correct or if obstacles have been ignored.

- Program a suitable pre-position
- Use safety clearances to take obstacles into account

If you use a probing routine for automatic probing of a hole, stud, or a pattern circle, the control opens a form with the required entry fields.

Input fields in the	Measure stud and	Measure hole forms
---------------------	------------------	--------------------

Input field	Function
Stud diameter? or Hole diameter	Diameter of probe contact (optional for holes)
Safety clearance?	Distance to the probe contact in the plane
Incr. clearance height?	Positioning of touch probe in spindle axis direction (starting from the current position)
Starting angle?	Angle for the first probing operation (0° = positive direction of principal axis, i.e. in X+ for spindle axis Z). All other probe angles result from the number of touch points.
Number of touch points?	Number of probing operations (3 to 8)
Angular length?	Probing a full circle (360°) or a circle segment (angular length<360°)

Automatic probing routine:

Pre-position touch probe

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1253	Conservations	

 Select the probing function: Press the PROBING CC soft key



Select paraxial probing direction

HOLE soft key

Start probing function: Press the NC start key The control carries out all pre-positioning and probing processes automatically.

▶ Hole should be probed automatically: Press the

The control approaches the position at the feed rate $\ensuremath{\textit{FMAX}}$ defined in the touch probe table. The defined probing feed rate $\ensuremath{\textit{F}}$ is used for the actual probing operation.

6		berating and programming notes: Before starting an automatic probing routine, you need to preposition the touch probe near the first touch point. Offset the touch probe by approximately the safety clearance opposite to the probing direction. The safety clearance is derived from the sum of the values in the touch-probe table and in the entry form.
	•	For inside circles with large diameters, the control can also position the touch probe on a circular arc at the feed rate FMAX . This requires that you enter a safety clearance for prepositioning and the hole diameter in the input form. Position the touch probe inside the hole at a position that is offset by approximately the safety clearance from the wall. Take the starting angle of the first probing process into account in pre-positioning; for example, at a starting angle of 0° the control will first probe in the positive direction of the reference axis.

Selecting the probing cycle

Select the Manual operation or Electronic handwheel mode of operation



- Select the probing functions: Press the TOUCH PROBE soft key
- PROBING POS

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Select the touch probe cycle by pressing the appropriate soft key, for example **PROBING POS** The control displays the associated menu.

Operating notes:

- When you select a manual probing function, the control opens a form displaying all data required. The content of the forms varies depending on the respective function.
- You can also enter values in some of the fields. Use the arrow keys to switch to the desired input field. You can position the cursor only in fields that can be edited. Fields that cannot be edited are dimmed.

Recording measured values from the touch probe cycles



Refer to your machine manual.

The control must be specially prepared by the machine tool builder for use of this function.

After executing the respective touch-probe cycle, the control writes the measured values to the TCHPRMAN.html file.

If you have not defined a path in the machine parameter **FN16DefaultPath** (no. 102202), the control will store the TCHPRMAN.html file in the **TNC:** main directory.



Operating notes:

If you run several touch probes cycles in a row, the control stores the measured values below each other.

Writing measured values from the touch probe cycles to a datum table



If you want to save measured values in the workpiece coordinate system, use the **ENTER IN DATUM TABLE** function. If you want to save measured values in the basic coordinate system, use the **ENTRY IN PRESET TABLE** function.

Further information: "Writing measured values from the touch-probe cycles to the preset table", page 548

With the **ENTER IN DATUM TABLE** soft key, the control can write the values measured during any touch-probe cycle to a datum table:

- Select any probe function
- Enter the desired coordinates for the datum in the designated input boxes (depends on the touch probe cycle being run)
- Enter the datum number in the Number in table? input field
- Press the ENTER IN DATUM TABLE soft key

The control saves the datum in the indicated datum table under the entered number.

Writing measured values from the touch-probe cycles to the preset table

If you want to save measured values in the basic coordinate system, use the **ENTRY IN PRESET TABLE** function. If you want to save measured values in the workpiece coordinate system, use the **ENTER IN DATUM TABLE** function.

Further information: "Writing measured values from the touch probe cycles to a datum table", page 547

With the **ENTRY IN PRESET TABLE** soft key, the control can write the values measured during any probe cycle in the preset table. The measured values are then stored referenced to the machine coordinate system (REF coordinates). The preset table has the name PRESET.PR, and is saved in the TNC:\table\ directory.

- Select any probe function
- Enter the desired coordinates for the preset in the designated input boxes (depends on the touch probe cycle being run)
- Enter the preset number in the Number in table? input field
- Press the ENTRY IN PRESET TABLE soft key

The control opens the **Overwrite active preset?** menu.

- Press the OVERWRITE PRESET soft key The control saves the preset in the preset table under the entered number.
 - Preset number does not exist: The control saves the row only after pressing the CREATE LINE (Create line in table?)
 - Preset number is protected: Press the ENTRY IN LOCKED LINE soft key to overwrite the active preset
 - Preset number is password-protected: Press the ENTRY IN LOCKED LINE soft key and enter the password to overwrite the active preset



The control displays a note if a table row cannot be written to because of disabling. The probing function itself is not interrupted.



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13.7 Calibrating 3-D touch probes

Introduction

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In order to precisely specify the actual trigger point of a 3-D touch probe, you must first calibrate the touch probe, otherwise the control cannot provide precise measuring results.

Operating notes:

- Always calibrate the touch probe again in the following cases:
 - Initial configuration
 - Broken stylus
 - Stylus exchange
 - Change in the probe feed rate
 - Irregularities caused, for example, when the machine heats up
 - Change of active tool axis
- When you press the **OK** soft key after calibration, the calibration values are applied to the active touch probe. The updated tool data then become immediately effective, there is no need to retrieve the tool again.

During calibration, the control finds the effective length of the stylus and the effective radius of the ball tip. To calibrate the 3-D touch probe, clamp a ring gauge or a stud of known height and known radius to the machine table.

The control provides calibration cycles for calibrating the length and the radius:



Press the TOUCH PROBE soft key

- Display the calibration cycles: Press CALIBRATE TS
- Select the calibration cycle

Calibration cycles

	-	
Soft key	Function	Page
€ <u>777777</u>	Calibrating the length	550
	Measure the radius and the center offset using a calibration ring	551
	Measure the radius and the center offset using a stud or a calibration pin	551
XA	Measure the radius and the center offset using a calibration sphere	551

Calibrating the effective length



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The effective length of the touch probe is always referenced to the tool reference point. The tool reference point is often on the spindle nose (and face of the spindle). The machine manufacturer may also place the tool reference point at a different point.

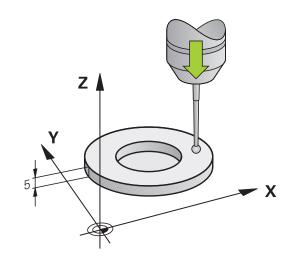
Set the preset in the spindle axis such that for the machine tool table Z=0.



 Select the calibration function for the touch probe length: Press the CAL. Press L
 The control displays the current calibration data.

- Datum for length?: Enter the height of the ring gauge in the menu window
- Move the touch probe to a position just above the ring gauge
- To change the traverse direction (if necessary), press a soft key or an arrow key
- Probe surface: Press NC Start key
- Check results
- Press the OK soft key for the values to take effect
- Press the CANCEL soft key to terminate the calibrating function.

The control logs the calibration process in the TCHPRMAN.html file.



Calibrating the effective radius and compensating center misalignment

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HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.

When calibrating the ball-tip radius, the control executes an automatic probing routine. In the first run the control finds the midpoint of the calibration ring or stud (approximate measurement) and positions the touch probe in the center. Then, in the actual calibration process (fine measurement), the radius of the ball tip is ascertained. If the touch probe allows probing from opposite orientations, the center offset is determined during another cycle.

The property of whether or how your touch probe can be oriented is predefined for HEIDENHAIN touch probes. Other touch probes are configured by the machine tool builder.

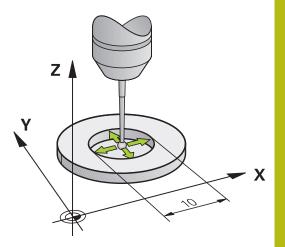
After the touch probe is inserted, it normally needs to be aligned exactly with the spindle axis. The calibration function can determine the offset between touch probe axis and spindle axis by probing from opposite orientations (rotation by 180°) and can calculate and implement the necessary compensation.

The center offset can be determined only with a suitable touch probe.

If you want to calibrate using the outside of an object, you need to preposition the touch probe above the center of the calibration sphere or calibration pin. Ensure that the touch points can be approached without collision.

The calibration routine varies depending on how your touch probe can be oriented:

- No orientation possible, or orientation in only one direction: The control executes one approximate and one fine measurement, and then ascertains the effective ball tip radius (column R in tool.t).
- Orientation possible in two directions (e.g. HEIDENHAIN touch probes with cable): The control executes one approximate and one fine measurement, rotates the touch probe by 180°, and then executes another probing routine. The center offset (CAL_OF in tchprobe.tp) is determined in addition to the radius by probing from opposite orientations.
- Any orientation possible (e.g. HEIDENHAIN touch probes with infrared transmission): The control executes one approximate and one fine measurement, rotates the touch probe by 180°, and then executes another probing routine. The center offset (CAL_OF in tchprobe.tp) is determined in addition to the radius by probing from opposite orientations.



Calibration using a calibration ring

Proceed as follows for manual calibration using a calibration ring:

- In the Manual operation mode, position the ball tip inside the bore of the ring gauge
- Select the calibration function: Press the CAL. R soft key

The control displays the current calibration data.

- Enter the diameter of the ring gauge
- Enter the start angle
- Enter the number of touch points
- Probe: Press the NC Start key
 - The 3-D touch probe probes all required touch points in an automatic probing routine and calculates the effective ball-tip radius. If probing from opposite orientations is possible, the control calculates the center offset.
- Check results
- Press the OK soft key for the values to take effect
- Press the END soft key to terminate the calibrating function.

The control logs the calibration process in the TCHPRMAN.html file.



Refer to your machine manual.

In order to be able to determine ball-tip center misalignment, the control needs to be specially prepared by the machine manufacturer.

Calibration with a stud or calibration pin

soft key

Proceed as follows for manual calibration with a stud or calibration pin:

- In the Manual operation mode, position the ball tip above the center of the calibration pin
 Select the calibration function: Press the CAL. R

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- Enter the outside diameter of the stud
- ► Enter the safety clearance
- Enter the start angle
- Enter the number of touch points
- ▶ Probe: Press the **NC Start** key

The 3-D touch probe probes all required touch points in an automatic probing routine and calculates the effective ball-tip radius. If probing from opposite orientations is possible, the control calculates the center offset.

- Check results
- Press the OK soft key for the values to take effect
- Press the END soft key to terminate the calibrating function.

The control logs the calibration process in the TCHPRMAN.html file.

Refer to your machine manual.

In order to be able to determine ball-tip center misalignment, the control needs to be specially prepared by the machine manufacturer.

Calibration using a calibration sphere

Proceed as follows for manual calibration using a calibration sphere:

- In the Manual operation mode, position the ball tip above the center of the calibration sphere
- Select the calibration function: Press the CAL. R soft key
- Enter the outside diameter of the ball
- Enter the safety clearance
- Enter the start angle
- Enter the number of touch points
- Select Length measurement, if applicable
- ▶ If necessary, input the reference for the length
- Probe: Press the NC Start key

The 3-D touch probe probes all required touch points in an automatic probing routine and calculates the effective ball-tip radius. If probing from opposite orientations is possible, the control calculates the center offset.

- Check results
- Press the OK soft key for the values to take effect
- Press the END soft key to terminate the calibrating function

The control logs the calibration process in the TCHPRMAN.html file.

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Refer to your machine manual. In order to be able to determine ball-tip center misalignment, the control needs to be specially prepared by the machine manufacturer.

Displaying calibration values

The control saves the effective length and effective radius of the touch probe in the tool table. The control saves the touch probe center offset to the touch probe table in the columns **CAL_OF1** (principal axis) and **CAL_OF2** (minor axis). You can display the values on the screen by pressing the **TCH PROBE TABLE** soft key.

During calibration, the control automatically creates the TCHPRMAN.html log file to which the calibration values are saved.

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Ensure that the tool number of the tool table and the touch-probe number of the touch-probe table are correct. This is regardless of whether you want to use a touch-probe cycle in automatic mode or **Manual operation** mode.

For more information about the touch probe table, refer to the User's Manual for Cycle Programming



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13.8 Compensating workpiece misalignment with 3-D touch probe

Introduction

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Refer to your machine manual. It depends on the machine whether you can compensate workpiece misalignment with an offset (angle for table rotation).



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The control compensates workpiece misalignment either mathematically by computing a basic rotation (angle of basic rotation) or by an offset (angle for table rotation)

For this purpose, the control sets the rotation angle to the desired angle with respect to the reference axis in the working plane.

Basic rotation: The control interprets the measured angle as rotation around the tool direction, and saves the values in the columns SPA, SPB, or SPC of the preset table.

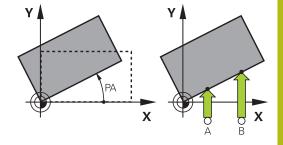
Offset: The control interprets the measured angle as a shift in each axis in the machine coordinate system, and saves the values in the columns A_OFFS, B_OFFS, or C_OFFS of the preset table.

In order to identify the basic rotation or offset, probe two points on the side of the workpiece. The sequence in which you probe the points influences the calculated angle. The measured angle goes from the first to the second probing point. You can also determine the basic rotation or offset using holes or studs.

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Operating and programming notes:

- Select the probe direction perpendicular to the angle reference axis when measuring workpiece misalignment.
- To ensure that the basic rotation is calculated correctly during program run, program both coordinates of the working plane in the first positioning block.
- You can also use a basic rotation in conjunction with the PLANE function (except for PLANE AXIAL). In this case first activate the basic rotation and then the PLANE function.
- You can also activate a basic rotation or offset without probing a workpiece. To do so, enter a value in the corresponding input field and press the SET BASIC ROTATION or SET TABLE ROTATION soft key.
- The behavior of the control during presetting depends on the setting in the machine parameter chkTiltingAxes (no. 204601).
 Further information: "Introduction", page 540



Identifying basic rotation



Press the Probe rotation soft key

- The control opens the **Probing of rotation** menu.
- The following input fields are displayed:
 - Angle of basic rotation
 - Offset of rotary table
 - Number in table?

The control displays any current basic rotation or offset in the input field.

- Position the touch probe at a position near the first touch point
- Select the probe direction or probing routine by soft key
- Press the NC Start key
- Position the touch probe at a position near the second touch point
- Press the NC Start key

The control determines the basic rotation and offset and displays them.

- Press the SET BASIC ROTATION soft key
- Press the END soft key

The control logs the probing process in TCHPRMAN.html.

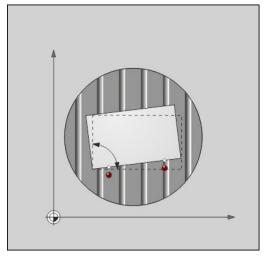
Saving the basic rotation in the preset table

- After the probing process, enter the preset number in which the control is to save the active basic rotation in the Number in table? input field
- Press the BASIC ROT. IN PRESET TABLE soft key If appropriate, the control opens the Overwrite active preset? menu.
- Press the OVERWRITE PRESET soft key The control saves the basic rotation in the preset table.

Compensation of workpiece misalignment by rotating the table

There are three possibilities for compensating workpiece misalignment by rotating the table:

- Align rotary table
- Set table rotation
- Save table rotation in the preset table



Align rotary table

You can compensate the ascertained misalignment by positioning the rotary table.



Pre-position all axes before rotating the table, in order to preclude collisions resulting from compensating movements. The control additionally outputs a warning before table rotation.

Press the ALIGN ROT. TABLE soft key after the probing procedure

The control opens the warning.

- Clear with the **OK** soft key if needed
- Press the NC Start key

The control aligns the rotary table.

Set table rotation

You can set a manual preset in the axis of the rotary table.

Press the SET TABLE ROTATION soft key after the probing procedure

If a basic rotation is already set, the control opens the **Reset basic rotation?** menu.

- Press the DELETE BASIC ROT. soft key The control deletes the basic rotation from the preset table, and inserts the offset.
- Or press **KEEP BASIC ROT.**

The control inserts the offset in the preset table, and the basic rotation also remains.

Save table rotation in the preset table

You can save the misalignment of the rotary table in any row of the preset table. The control stores the angle in the offset column of the rotary table, e.g. in the C_OFFS column for a C axis.

Press the TABLE ROT. IN PRESET TABLE soft key after the probing procedure

If appropriate, the control opens the **Overwrite active preset?** menu.

Press the OVERWRITE PRESET soft key

The control saves the offset in the preset table.

You may have to change the view in the preset table with the **BASE TRANSFORM./OFFSET** soft key for this column to be displayed.

Show basic rotation and offset

If you select the **PROBING ROT** function, the control displays the active angle of the basic rotation in the **Angle of basic rotation** input field and the active offset in the **Offset of rotary table** input field.

In addition, the rotary angle and the offset are shown in the split screen **PROGRAM + STATUS** screen layout on the **STATUS POS.** tab.

When the control moves the machine axis in accordance with the basic rotation, a symbol for the basic rotation is shown in the status display.

Rescind basic rotation or offset

- Select the probe function by pressing the **PROBING ROT** soft key
- Enter Angle of basic rotation: 0
- Or enter Offset of rotary table: 0
- Apply with the SET BASIC ROTATION soft key
- Or apply with the SET TABLE ROTATION soft key
- ▶ To terminate the probe function, press the **END** soft key

Measuring 3-D basic rotation

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The misalignment of any tilted plane can be measured by probing 3 positions. The **Probe in plane** function enables you to measure this misalignment and save it as a 3-D basic rotation in the preset table.

Operating and programming notes:

- The sequence and position of the touch points determines how the control calculates the direction of the plane.
- With the first two points you specify the direction of the reference axis. Define the second point in the positive direction of the desired reference axis. The position of the third point determines the direction of the minor axis and tool axis. Define the third point in the positive Y axis of the desired workplace coordinate system.
 - 1st point is on the reference axis
 - In 2nd point is on the reference axis, in a positive direction from the first point
 - 3rd point is on the minor axis, in a positive direction of the desired workpiece coordinate system

Optionally inputting a datum angle enables you to define the nominal direction of the probed plane.



 Select the probe function by pressing the PROBING PL soft key

The control displays the current 3-d rotation.

- Position the touch probe at a position near the first touch point
- Select the probe direction or probing routine by soft key
- Probe: Press the NC Start key
- Position the touch probe at a position near the second touch point
- Probe: Press the NC Start key
- Position the touch probe near the third touch point
- Probe: Press the NC Start key. The control measures the 3-D basic rotation and displays the values for SPA, SPB, and SPC in relation to the active coordinate system.
- If required, enter the datum angle

Activate 3-D basic rotation:



Press the SET BASIC ROTATION soft key

Save the 3-D rotation in the preset table:



Press the BASIC ROT. IN PRESET TABLE soft key



To terminate the probe function, press the END soft key

The control saves the 3-D basic rotation in the columns SPA, SPB, and SPC of the preset table.

Aligning 3-D basic rotation

If the machine has two rotary axes and the probed 3-D basic rotation is activated, you can align the rotary axes with reference to the 3-D basic rotation using the **ALIGN ROT. AXES** soft key. In such cases, Tilted Working Plane becomes active for all machine operating modes.

After aligning the plane, you can align the reference axis with the **Probing rot** function.

Displaying 3-D basic rotation

If a 3-D basic rotation is saved in the active preset, the control

shows the 🖾 symbol for the 3-D basic rotation in the status display. The control moves the machine axes according to the 3-D basic rotation.

Canceling a 3-D basic rotation

- PROBING
- Select the probe function by pressing the PROBING PL soft key
- Enter 0 for all angles
- ▶ Press the SET BASIC ROTATION soft key
- To terminate the probe function, press the END soft key

13.9 Presetting with a 3-D touch probe

Overview

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Refer to your machine manual.

The machine tool builder can disable presetting in individual axes.

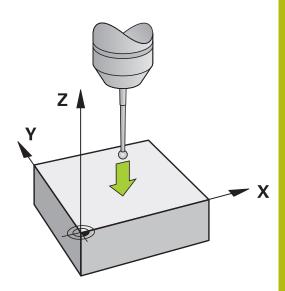
If you try to set a preset in a locked axis, the control will issue either a warning or an error message, depending on what the machine tool builder has defined.

The following soft-key functions are available for setting a preset on an aligned workpiece:

Soft key	Function	Page
PROBING POS	Presetting on any axis	563
PROBING	Setting a corner as preset	564
PROBING CC	Setting a circle center as preset	566
PROBING	Center line as preset	569
	Setting the center line as preset	
With an active datum shift the determined value is with respect to the current preset (possibly a manual preset from the Manual operation mode). The datum shift is included in the position display.		manual preset

Presetting on any axis

0	HEIDENHAIN only gives warranty for the function of the probing cycles if HEIDENHAIN touch probes are used.	
PROBING POS	 Select the probing function by pressing the POSITION PROBING soft key 	
	 Move the touch probe to a position near the touch point 	
	 Select the axis and probing direction, e.g. Probe in direction Z- 	
	Probe: Press the NC Start key	
	Preset: Enter the nominal coordinate	
	 Apply with the SET PRESET soft key Further information: "Writing measured values from the touch probe cycles to a datum table", page 547 Further information: "Writing measured values from the touch-probe cycles to the preset table", page 548 	
	To terminate the probe function, press the END soft key	



Corner as preset



Refer to your machine manual.

It depends on the machine whether you can compensate workpiece misalignment with an offset (angle for table rotation).



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The "Corner as preset" probing cycle identifies the angle and intersection of two straight lines.

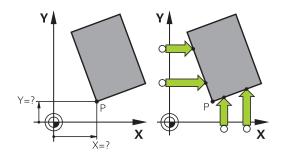


 Select the probing function: Press the PROBING P soft key

- Position the touch probe near the first touch point on the first workpiece edge
- Select the probe direction by soft key
- Probe: Press the NC Start key
- Position the touch probe near the second touch point on the same workpiece edge
- Probe: Press the NC Start key
- Position the touch probe near the first touch point on the second workpiece edge
- Select the probe direction by soft key
- Probe: Press the NC Start key
- Position the touch probe near the second touch point on the same workpiece edge
- Probe: Press the NC Start key
- Preset: Enter both coordinates of the preset in the menu window
- Apply with the SET PRESET soft key Further information: "Writing measured values from the touch probe cycles to a datum table", page 547

Further information: "Writing measured values from the touch-probe cycles to the preset table", page 548

To terminate the probe function, press the END soft key





You can identify the intersection of two straight lines by holes or studs and set this as the preset.

In addition to presetting, you can also activate a basic rotation or an offset with the cycle. The control has two soft keys for you to decide which straight line you wish to use for this.

The **ROT 1** soft key activates the angle of the first straight line as basic rotation or as offset, and the **ROT 2** soft key activates the angle of the second straight line.

If you activate the basic rotation, the control automatically writes the positions and the basic rotation to the preset table.

If you activate the offset, the control automatically writes the positions and the offset or only the positions to the preset table.

Circle center as preset

With this function, you can set the preset at the center of bore holes, circular pockets, cylinders, studs, circular islands, etc.

Inside circle:

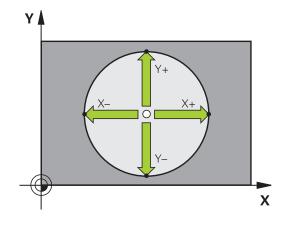
The control probes the inside wall of a circle in all four coordinate axis directions.

For incomplete circles (circular arcs) you can choose the appropriate probing direction.

- Position the touch probe approximately in the center of the circle
- Select the touch probe function: Press the PROBING CC soft key
- Select the soft key for the desired probing direction
- Probe: Press the NC Start key. The touch probe probes the inside wall of the circle in the selected direction. Repeat this process. After the third probing operation, you can have the control calculate the center (four touch points are recommended)
- Terminate the probing procedure and switch to the evaluation menu: Press the EVALUATE soft key
- Preset: Enter both coordinates of the center of the circle in the menu window
- Apply with the SET PRESET soft key Further information: "Writing measured values from the touch probe cycles to a datum table", page 547

Further information: "Writing measured values from the touch-probe cycles to the preset table", page 548

- To terminate the probe function, press the END soft key
- The control needs at least three touch points to calculate outside or inside circles, e.g. with circle segments. More precise results are obtained with four touch points. If possible, always pre-position the touch probe to the center.



Outside circle:

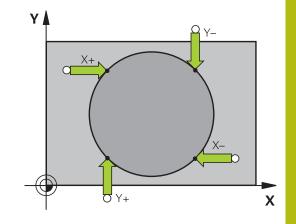


- Position the touch probe at a position near the first touch point outside of the circle
- Select the touch probe function: Press the PROBING CC soft key
- Select the soft key for the desired probing direction
- Probe: Press the NC Start key. The touch probe probes the inside wall of the circle in the selected direction. Repeat this process. After the third probing operation, you can have the control calculate the center (four touch points are recommended)
- Terminate the probing procedure and switch to the evaluation menu: Press the EVALUATE soft key
- **Preset**: Enter the coordinates of the preset
- Apply with the SET PRESET soft key
 Further information: "Writing measured values from the touch probe cycles to a datum table", page 547

Further information: "Writing measured values from the touch-probe cycles to the preset table", page 548

To terminate the probe function, press the END soft key

Once the probing routine is completed, the control displays the current coordinates of the circle center and the circle radius.



Setting the preset using multiple holes/cylindrical studs

The manual probing function **Probing of circular pattern** is part of the **Cir** probing function. Individual circles can be determined with paraxial probing operations.

A second soft-key row provides the soft key **PROBING CC (Probing of circular pattern)** for using multiple holes or circular studs to set the preset. You can set the intersection of two or more elements as preset.

Setting the preset in the intersection of multiple holes/ circular studs:

Pre-position touch probe

Select Model Circle probing function



- Select the touch probe function: Press the PROBING CC soft key
- PROBING
- Press the PROBING CC (Probing of circular pattern) soft key

Probe a circular stud

- Circular stud should be probed automatically: Press Stud soft key
- Enter starting angle or select using soft key



Start probing function: Press the NC Start key

Probe the hole.

- Hole should be probed automatically: Press the Hole soft key
- Enter starting angle or select using soft key
- Ţ]
- Start probing function: Press the NC Start key
- Repeat the probing procedure for the remaining elements
- Terminate the probing procedure and switch to the evaluation menu: Press the EVALUATE soft key
- Preset: Enter both coordinates of the center of the circle in the menu window
- Apply with the SET PRESET soft key Further information: "Writing measured values from the touch probe cycles to a datum table", page 547

Further information: "Writing measured values from the touch-probe cycles to the preset table", page 548

To terminate the probe function, press the END soft key

Setting a center line as preset



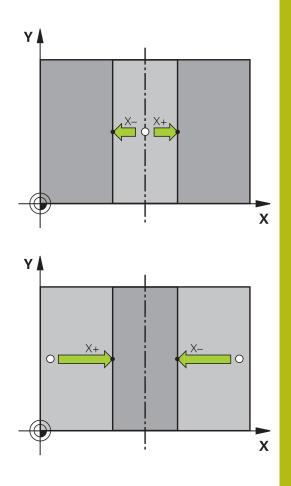
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- Select the probing function: Press the PROBING CL soft key
- Position the touch probe at a position near the first touch point
- Select the probing direction by soft key
- Probe: Press the NC Start key
- Position the touch probe at a position near the second touch point
- Probe: Press the NC Start key
- Preset: Enter the coordinates of the preset in the menu window, confirm with the SET PRESET soft key, or write the value to a table Further information: "Writing measured values from the touch probe cycles to a datum table", page 547

Further information: "Writing measured values from the touch-probe cycles to the preset table", page 548

 To terminate the probe function, press the END soft key

If you desire, then after the second touch point you can change the position of the centerline in the evaluation menu, and thus the axis for setting the preset. Use the soft keys to choose between principal axis, secondary axis, and tool axis. This way you can determine the positions once, and then store them in the principal axis as well as in the secondary axis.



Measuring workpieces with a 3-D touch probe

You can also use the touch probe in the **Manual operation** and **Electronic handwheel** operating modes to perform simple measurements on the workpiece. Numerous programmable touch probe cycles are available for more complex measuring tasks.

Further information: Cycle Programming User's Manual

With a 3-D touch probe you can determine:

- Position coordinates, and from them,
- Dimensions and angles on the workpiece

Finding the coordinates of a position on an aligned workpiece

PRO	BING
	POS

- Select the probing function: Press the PROBING POS soft key
- Move the touch probe to a position near the touch point
- Select the probing direction and the axis to which the coordinates relate: Use the corresponding soft keys to select
- Start the probing process: Press the NC Start key

The control shows the coordinates of the touch point as preset.

Finding the coordinates of a corner point on the working plane Find the coordinates of the corner point.

Further information: "Corner as preset", page 564

The control displays the coordinates of the probed corner as preset.

Measuring workpiece dimensions



- Select the probing function: Press the PROBING POS soft key
- Position the touch probe at a position near the first touch point A
- Select the probing direction by soft key
- Probe: Press the NC Start key
- If you need the current preset later, write down the value that appears in the display
- Preset: Enter 0.
- Cancel the dialog: Press the END key
- Select the probing function again: Press the PROBING POS soft key
- Position the touch probe at a position near the second touch point B
- Select the probe direction with the soft keys: Same axis but from the opposite direction
- Probe: Press the NC Start key

The **Measured value** display shows the distance between the two points on the coordinate axis.

To return to the values that were active before the length measurement:

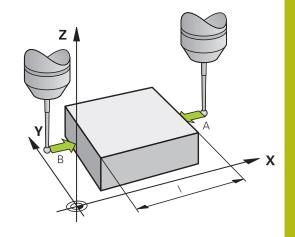
- Select the probing function: Press the **PROBING POS** soft key
- Probe the first touch point again
- Set the preset to the value that you wrote down previously
- Cancel the dialog: Press the END key

Measuring angles

You can use the 3-D touch probe to measure angles in the working plane. You can measure

- The angle between the angle reference axis and a workpiece edge; or
- the angle between two sides

The measured angle is displayed as a value of max. 90°.



Finding the angle between the angle reference axis and a workpiece edge



- Select the probe function by pressing the PROBING ROT soft key
- Rotation angle: If you wish to restore the current basic rotation later, note the value that appears under Rotation Angle
- Perform a basic rotation with the workpiece edge to be compared

Further information: "Compensating workpiece misalignment with 3-D touch probe ", page 555

- Press the PROBING ROT soft key to display the angle between the angle reference axis and the workpiece edge as the rotation angle
- Cancel the basic rotation, or restore the previous basic rotation
- Set the rotation angle to the value that you previously wrote down

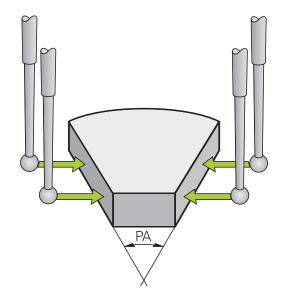
Measuring the angle between two workpiece edges

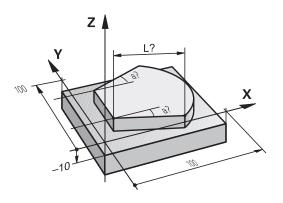


- Select the probe function by pressing the PROBING ROT soft key
- Rotation angle: If you wish to restore the current basic rotation later, note the value that appears under Rotation Angle
- Perform a basic rotation with the workpiece edge to be compared

Further information: "Compensating workpiece misalignment with 3-D touch probe ", page 555

- Probe the second edge in the same way as for a basic rotation, but do not set the rotation angle to 0
- Press the ROTATION PROBING soft key to display the angle PA between the workpiece edges as the rotation angle
- Cancel the basic rotation, or restore the previous basic rotation by setting the rotation angle to the value that you wrote down previously





13.10 Tilting the working plane (option 8)

Application, function

Refer to your machine manual.

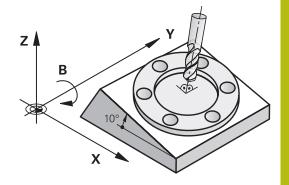
The **Tilt working plane** functions are interfaced to the control and the machine tool by the machine tool builder. The machine tool builder also specifies whether the programmed angles are interpreted as coordinates of the rotary axes (axis angles) or as angular components of a tilted plane (spatial angles).

The control supports the tilting functions on machine tools with swivel heads and/or tilting tables. Typical applications are, for example, oblique holes or contours in an oblique plane. The working plane is always tilted around the active datum. The program is written as usual in a main plane, such as the X/Y plane, but is executed in a plane that is tilted relative to the main plane.

There are three functions available for tilting the working plane:

- Manual tilting with the 3-D ROT soft key in the Manual operation and Electronic handwheel modes Further information: "Activating manual tilting:", page 576
- Controlled tilting, Cycle G80 in the machining program
 Further information: Cycle Programming User's Manual
- Controlled tilting, PLANE function in the machining program Further information: "The PLANE function: Tilting the working plane (option 8)", page 479

The control functions for tilting the working plane are coordinate transformations. The working plane is always perpendicular to the direction of the tool axis.



When tilting the working plane, the control differentiates between two machine types:

Machine with tilting table

- You must tilt the workpiece into the desired position for machining by positioning the tilting table, for example with an G01 block.
- The position of the transformed tool axis does not change in relation to the machine coordinate system. Thus if you rotate the table—and therefore the workpiece—by 90° for example, the coordinate system does not rotate. If you press the Z+ axis direction button in the Manual operation mode, the tool moves in Z+ direction.
- In calculating the transformed coordinate system, the control considers only the mechanically influenced offsets of the particular tilting table (the translational components).

Machine with swivel head

- You must tilt the workpiece into the desired position for machining by positioning the swivel head, for example with an G01 block
- The position of the transformed tool axis changes in relation to the machine coordinate system. Thus if you rotate the swivel head of your machine—and therefore the tool—in the B axis by 90° for example, the coordinate system rotates also. If you press the Z+ axis direction button in the **Manual operation** mode, the tool moves in the X+ direction of the machine coordinate system.
- In calculating the active coordinate system, the control considers both the mechanically influenced offsets of the particular swivel head (the translational components) as well as offsets caused by tilting of the tool (3-D tool length compensation).

The control only supports the **Tilt working plane** function in combination with the spindle axis G17.

i

Position display in a tilted system

The positions displayed in the status window (ACTL. and NOML.) are referenced to the tilted coordinate system.

In the optional machine parameter **CfgDisplayCoordSys** (no. 127501) you can specify the coordinate system in which the status display shows an active datum shift.

Limitations on working with the tilting function

- The Actual-position capture function is not allowed if the Tilt working plane function is active
- PLC positioning (determined by the machine tool builder) is not possible.

Activating manual tilting:

3D ROT
Ŧ
ACTIVE
ł
END D

- To select manual tilting, press the 3-D ROT soft key.
- Use the arrow keys to move the cursor to the menu point Manual operation
- To activate manual tilting, press the ACTIVE soft key
- Use the arrow keys to position the cursor on the desired rotary axis
- Enter the tilt angle
- ► Terminate the entry: Press the END key

If the tilted working plane function is active and the control moves the machine axes in accordance with the tilted axes, the status

display shows the 🗟 symbol.

If you set the "Tilt working plane" function for the **Program run** operating mode to **Active**, the tilt angle entered in the menu becomes active in the first block of the machining program. If you use Cycle **G80** or the **PLANE** function in the machining program, the angle values defined there are in effect. Angle values entered in the menu will be overwritten.

Manual operation			DNC Programming			9
Position dis	play MODE: NO Tilt work	ML. ing plane	0-erview (PGM PAL LHL CYC M POS TOOL TT TRAMS OPARA 0-Enview 17.013 0 40.000 +0.000		M P.	
Y Z B C	Program Manual O B C Kinemati	peration	Inactive 0 0 0	C TABLE	+12.0000 +0.0000 +0.0000 H0	™ * <u></u>
91 S 1800	Coordina	1 superimp.: te system OK	Machine	(M-CS) CANCEL	REP (3) 60:00:00	S100%
Oper 100% N 5/9 Active Point Thruchure program. Actives point thrups in 100% S-OVR 100% F-OVR LIMIT 1						F100% WW OFF ON
ок	CANCEL	CONFIRM VALUE				

6	The control uses the following transformation types for tilting:		
	COORD ROT		
	 if a PLANE function was previously executed with COORD ROT 		
	after PLANE RESET		
	 with corresponding configuration of the machine parameter CfgRotWorkPlane (no. 201200) by the machine tool builder 		
	after starting the control		
	after switching the kinematics		
	after running the cycle G80		
	TABLE ROT		
	 if a PLANE function was previously executed with TABLE ROT 		
	 with corresponding configuration of the machine parameter CfgRotWorkPlane (no. 201200) by the machine tool builder 		
	after starting the control		
	after switching the kinematics		
	after running the cycle G80		

If tilting was active when the control was turned off, then the control also moves in the tilted working plane when it is turned on again.

Further information: "Crossing the reference point in a tilted working plane", page 515

To deactivate manual tilting

To deactivate, set the appropriate operating modes to **Inactive** in the **Tilt working plane** menu.

Even if the **3D-ROT** dialog in the **Manual operation** mode is set to **Active**, resetting the tilting (**PLANE RESET**) with an active basic transformation still functions correctly.

Setting the tool-axis direction as the active machining direction



Refer to your machine manual.

Your machine manufacturer enables this function.

Using this function in the **Manual operation** and **Electronic handwheel** operating modes, you can move the tool in the direction in which the tool axis is currently pointed using the axis direction keys or with the handwheel. Use this function if

- You want to retract the tool in the direction of the tool axis during suspension of a 5-axis machining program
- You want to machine with an inclined tool using the handwheel or the axis direction keys in Manual Operation mode



TOOL AXIS

END

- To select manual tilting, press the 3-D ROT soft key.
- Use the arrow keys to move the cursor to the menu item Manual operation
- To activate the current tool axis direction as the active machining direction, press the **Tool axis** soft key
- ► Terminate the entry: Press the END key

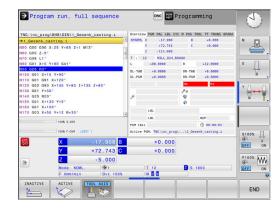
To deactivate the tilting function, set the **Manual operation** menu item in the "Tilt working plane" menu to inactive.

The 上 symbol appears in the status display when the Move in tool axis direction function is active.

Setting a preset in a tilted coordinate system

After you have positioned the rotary axes, set the preset in the same manner as for a non-tilted system. The behavior of the control during presetting depends on the setting in the optional machine parameter **chkTiltingAxes** (no. 204601):

Further information: "Introduction", page 540



Positioning with Manual Data Input

14.1 Programming and executing simple machining operations

The **Positioning w/ Manual Data Input** mode of operation is particularly convenient for simple machining operations or for pre-positioning the tool. It enables you to write a short program, depending on machine parameter **programInputMode** (no. 101201), in Klartext or in ISO format and execute it immediately. The program is stored in the file \$MDI.

You can use the following functions for example:

- Cycles
- Radius compensation
- Program section repetitions
- Q parameters

The additional status display can be activated in the **Positioning w/ Manual Data Input** mode of operation.

NOTICE

Danger of collision!

Certain manual interactions cause the control to lose program information affecting the mode and thereby to lose the so-called contextual reference. After the loss of the contextual reference, unexpected and undesired movements can occur. There is a danger of collision during subsequent machining operations!

- Do not perform the following interactions:
 - Cursor movement to another NC block
 - The jump command GOTO to another NC block
 - Editing an NC block
 - Modifying Q parameter values with the Q INFO soft key
 - Switching the operating modes
- Restore the contextual reference via repetition of the required NC blocks

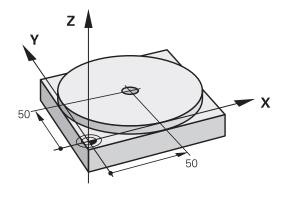
Positioning with manual data input (MDI)

	g the manaal aata mpat (mpi)
	Select the Positioning w/ Manual Data Input operating mode
	 Program the desired available function
1	Press the NC Start key
<u></u>	The control executes the highlighted NC block. Further information: "Programming and executing simple machining operations", page 580
A	Operating and programming notes:
U	The following functions are not available in the Positioning w/ Manual Data Input operating mode:
	 FK free contour programming
	Program call
	■ %
	%:PGM:
	■ %<>%
	Programming graphics
	Program-run graphics
	 Using the SELECT BLOCK and CUT OUT BLOCK soft keys etc. you can also conveniently and rapidly reuse program sections from other NC programs. Further information: "Marking, copying, cutting and inserting program sections", page 139
	 You can control and modify Q parameters with the soft keys Q PARAMETER LIST and Q INFO. Further information: "Checking and changing Q parameters", page 350

Example

A hole with a depth of 20 mm is to be drilled into a single workpiece. After clamping and aligning the workpiece and setting the preset, you can program and execute the drilling operation with a few lines of programming.

First you pre-position the tool above the workpiece with straightline blocks and position with a safety clearance of 5 mm above the hole. Then drill the hole with Cycle **G200**.



%\$MDI G71 *		
N10 T1 G17 S2000*		Call the tool: tool axis Z,
		spindle speed 2000 rpm
N20 G00 G40 G90 Z+200*		Retract the tool (rapid traverse)
N30 X+50 Y+50 M3*		Move the tool at rapid traverse to a position above the hole. Spindle on.
N40 G01 Z+2 F2000*		Position the tool to 2 mm above the hole
N50 G200 DRILLING		Define Cycle G200 DRILLING
Q200=2	;SET-UP CLEARANCE	Set-up clearance of the tool above the hole
Q201=-20	;DEPTH	Hole depth (algebraic sign=working direction)
Q206=250	;FEED RATE FOR PLNGNG	Feed rate for drilling
Q202=10	;PLUNGING DEPTH	Depth of each infeed before retraction
Q210=0	;DWELL TIME AT TOP	Dwell time at top for chip release (in seconds)
Q203=+0	;SURFACE COORDINATE	Workpiece surface coordinate
Q204=50	;2ND SET-UP CLEARANCE	Position after the cycle, with respect to Q203
Q211=0.5	;DWELL TIME AT DEPTH	Dwell time in seconds at the hole bottom
Q395=0	;DEPTH REFERENCE	Depth referenced to the tool tip or the cylindrical part of the tool
N60 G79*		Call Cycle G200 PECKING
N70 G00 G40 Z+200 M2*		Retract the tool
N9999999 %\$MDI G71 *		End of program

Straight-line function:

Further information: "Straight line in rapid traverse G00 or straight line with feed rate F G01", page 263

Example : Remove workpiece misalignment on a machine with a rotary table

- Use a 3-D touch probe to carry out a basic rotation
 Further information: "Compensating workpiece misalignment with 3-D touch probe ", page 555
- Write down the rotation angle and cancel the basic rotation

►	Select the operating mode: Press the Positioning w/ Manual Data Input key
•	Select the rotary table axis, enter the rotation angle and feed rate you wrote down, e.g. G01 C +2.561 F50



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IV

- Conclude entry
- Press the NC Start button: The rotation of the table corrects the misalignment

Protecting programs in \$MDI

The \$MDI file is intended for short programs that are only needed temporarily. Nevertheless, you can store a program, if necessary, by proceeding as described below:



- Operating mode: Press the Programming key
- PGM MGT
- To call the file manager, press the PGM MGT key.
- f
- Move the highlight to the **\$MDI** file



To copy the file: Press the COPY soft key

DESTINATION FILE =

Enter the name under which you want to save the current contents of the \$MDI file, e.g.Hole

ок

END

- Press the **OK** soft key.
- ► To exit the file manager, press the END soft key

Further information: "Copying a single file", page 150



Test Run and Program Run

15.1 Graphics

Application

In the **Program run, single block** and **Program run, full sequence** operating modes, as well as in the **Test Run** Operating Mode, the control graphically simulates a machining operation.

The control features the following views:

- Plan view
- Projection in three planes
- 3-D view



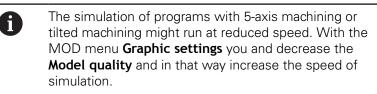
In the **Test Run** operating mode, you can additionally use the 3-D line graphics.

The graphic depicts the workpiece as if it were being machined with a cylindrical end mill.

For active tool tables, the control also takes the entries in the columns LCUTS, T-ANLGE, and R2 into consideration.

The control will not show a graphic if

- the current program has no valid workpiece blank definition
- no program is selected
- with blank form definition with a subprogram, the BLK FORM block was not yet run



Speed of the setting test runs



The most recently set speed stays active until a power interruption. After the control is switched on the speed is set to FMAX.

After you have started a program, the control displays the following soft keys with which you can set the simulation speed:

Soft key	Functions	
1:1	Test program with the speed that will be used when actually running the program (programmed feed rates will be taken into account)	
T	Increase the simulation speed incrementally	
	Decrease the simulation speed incrementally	
MAX	Test run at the maximum possible speed (default setting)	
You can also set the simulation speed before you start a program:		

You can also set the simulation speed before you start a program:



- Select the function for setting the simulation speed
- Select the desired function by soft key, e.g. incrementally increasing the simulation speed

Overview: Display modes

In the **Program run, single block** and **Program run, full sequence** operating modes, as well as in **Test Run** operating mode, the

control displays the following soft keys:

Soft key	View
	Plan view
	Projection in three planes
	3-D view
A	The position of the soft keys depends on the selected

6

The **Test Run** mode of operation also offers the following views:

Soft key	View
VIEWS	Volume view
VIEWS	Volume view and tool paths
VIEWS	Tool paths

Limitations during program run

operating mode.



The simulation may contain errors if the control's computing capacity is being fully utilized for complex machining tasks.

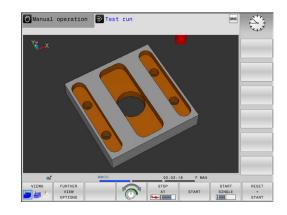
3-D view

Choose 3-D view:

The high-resolution 3-D view enables you to display the surface of the machined workpiece in greater detail. Using a simulated light source, the control creates realistic light and shadow conditions.



Press the 3-D view soft key

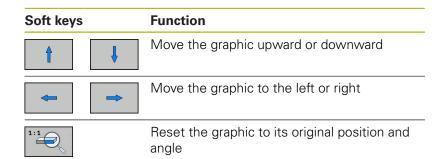


Rotating, enlarging and shifting the 3-D view



 Select functions for rotating and zooming The control displays the following soft keys.

Soft keys		Function
		Rotate in 5° steps about the vertical axis
		Tilt in 5° steps about the horizontal axis
+		Enlarge the graphic stepwise
-		Reduce the graphic stepwise
1:1		Reset the graphic to its original size and angle
\triangleright	Scr	oll through the soft-key row



You can also use the mouse to change the graphic display. The following functions are available:

- In order to rotate the model shown in three dimensions, hold down the right mouse button and move the mouse. If you simultaneously press the shift key, you can only rotate the model horizontally or vertically
- To shift the model shown: Hold the center mouse button or mouse wheel down and move the mouse. If you simultaneously press the shift key, you can only shift the model horizontally or vertically
- To zoom in on a certain area: Mark a zoom area by holding the left mouse button down.

After you release the left mouse button, the control zooms in on the defined area.

- To rapidly magnify or reduce any area: Rotate the mouse wheel backwards or forwards
- To return to the standard display: Press the shift key and simultaneously double-click with the right mouse key. The rotation angle is maintained if you only double-click with the right mouse key

3-D view in the Test Run operating mode

The Test Run mode of operation also offers the following views:

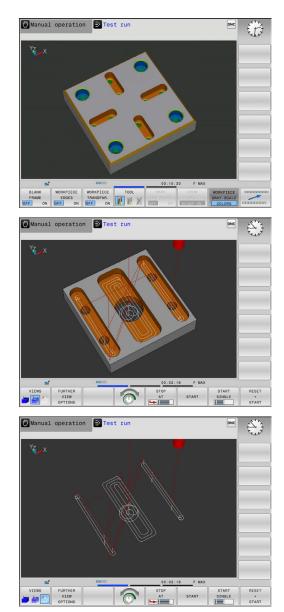
Soft keys	Function
VIEWS	Volume view
VIEWS	Volume view and tool paths
VIEWS	Tool paths

The Test Run operating mode also provides the following functions:

Soft keys	Function
BLANK FRAME OFF ON	Show workpiece blank frame
WORKPIECE EDGES OFF ON	Highlight workpiece edges on 3-D model
WORKPIECE TRANSPAR. OFF ON	Show a transparent workpiece
MARK END POINT OFF ON	Show the end points of the tool paths
BLOCK NO. SHOW OMIT	Show the block numbers of the tool paths
WORKPIECE GRAY-SCALE COLORS	Show the workpiece in color
RESET THE VOLUME MODEL	Reset the volume model
RESET TOOL PATHS	Reset the tool paths
FMAX PATHS DISPLAY HIDE	Display the rapid traverse movements
MEASURING	Activate measuring
OFF ON	If measuring is activated, the control shows the corresponding coordinates in close proxim- ity if you position the mouse cursor on the 3-D graphics of the workpiece.

The control saves the state of the following soft keys in non-volatile memory, even after interruption of the power supply:

- Movements at rapid traverse
- Workpiece blank frame
- Workpiece edges
- Transparent workpiece
- Workpiece in color



Operating notes:

A

- The available functions depend on the selected model quality. You can select the model quality in the MOD function Graphic settings.
- With the machine parameter clearPathAtBlk (No. 124203), you can specify whether or not the tool path in the Test Run operating mode is cleared with a new BLK FORM.
- If points were output incorrectly by the postprocessor, then machining marks occur on the workpiece. To recognize these unwanted machining marks in time (prior to machining), you can test externally created NC programs for corresponding irregularities by the display of tool paths.
- A powerful zoom function is available in order for you to quickly recognize the details for the displayed tool paths.
- The control displays traverse movements in rapid traverse in red.

Plan view

Select the plan view in the Test Run operating mode:



Press the FURTHER VIEW OPTIONS soft key

Press the plan view soft key

Select plan view in the operating modes **Program run, single block** and **Program run, full sequence**:



Press the GRAPHICS soft key



Press the plan view soft key

Projection in three planes

The simulation shows three sectional planes and a 3-D model, similar to a technical drawing.

Select projection in three planes in the **Test Run** operating mode:



Press the FURTHER VIEW OPTIONS soft key



Press the View on 3 Planes soft key

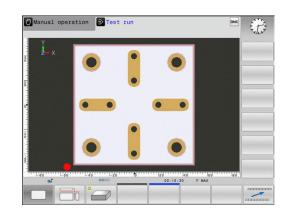
Select projection in three planes in the operating modes **Program run, single block** and **Program run, full sequence**:

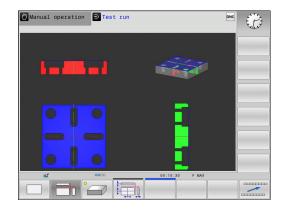


Press the GRAPHICS soft key



Press the View on 3 Planes soft key





15

Moving sectional planes

The default setting of the sectional plane is selected so that it lies in the working plane in the workpiece center and in the tool axis on the top surface.

Shift the sectional plane as follows:



Press the soft key for shifting the sectional plane

The control displays the following soft keys:

Soft keys		Function
		Shift the vertical sectional plane to the right or left
		Shift the vertical sectional plane forward or backward
		Shift the horizontal sectional plane upwards or downwards

The position of the sectional planes is visible during shifting. The shift remains active, even if you activate a new workpiece blank.

Resetting sectional planes

The shifted sectional plane also remains active for a new workpiece blank. The sectional plan is automatically reset when the control is restarted.

You can also move the sectional plane to its default position manually:



Press the soft key for

resetting the sectional planes soft key

Repeating graphic simulation

A part program can be graphically simulated as often as desired. To do so you can reset the graphic to the workpiece blank.

Soft key	Function
RESET BLK FORM	Display the unmachined blank in the Program run, single block and Program run, full sequence operating modes
RESET THE VOLUME MODEL	Display the unmachined blank in the Test Run operating mode

Tool display

Regardless of the operating mode, you can also show the tool during the simulation.

Soft key	Function
TOOLS DISPLAY HIDE	Program run, full sequence / Program run, single block
TOOL	Test Run

The control displays the tool in various colors:

- Red: Tool is in effect
- Blue: Tool is retracted

Measurement of machining time

Machining time in the Test Run operating mode

The control calculates the duration of the tool movements and displays this as machining time in the test run. The control takes feed movements and dwell times into account.

The time determined by the control is only of limited value for calculating the machining time because it does not take any machine-dependent time intervals (e.g., for tool changes) into consideration.

Machining time in the machine operating modes

Time display from program start to program end. The timer stops whenever machining is interrupted.

Select the stopwatch function

Selecting the stopwatch function

\triangleright	

STORE

- Shift the soft key menu until the soft key for the stopwatch functions appears
- Select the desired function via soft key, e.g., saving the displayed time

0	
Soft key	Stopwatch functions
STORE	Store displayed time
	Display the sum of stored time and displayed time



Clear displayed time

15.2 Showing the workpiece blank in the working space

Application

In the **Test Run** operating mode, you can graphically check the position of the workpiece blank and the preset in the working space of the machine. The graphics show the preset that has been set in the NC program using Cylce 247. If you have not set a preset in the NC program, then the graphics show the active preset on the machine.

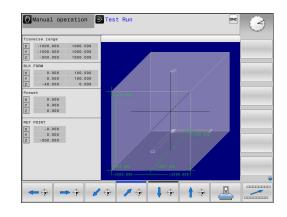
You can active workspace monitoring in the **Test Run** operating mode: to do so, press the **BLANK IN WORK SPACE** soft key. You can activate or deactivate the function using the **SW limit monitoring** soft key.

A transparent cuboid represents the workpiece blank. Its dimensions are shown in the **BLK FORM** table. The control takes over the dimensions from the workpiece blank definition of the selected program.

For a test run it normally does not matter where the workpiece blank is located within the working space. If you activate workspace monitoring, you must graphically shift the workpiece blank so that it lies within the working space. Use the soft keys shown in the table.

You can also activate the current preset for the **Test Run** operating mode.

Soft keys		Function
\$ -	➡ ♦	Shift workpiece blank in positive/negative X direction
	1 🕈	Shift workpiece blank in positive/negative Y direction
† •	↓ ↔	Shift workpiece blank in positive/negative Z direction
		Show workpiece blank referenced to the set preset
ACTIVE TRAVERSE RANGES		Display the current traverse range
SELECT TRAVERSE RANGE		This shows the traverse ranges config- ured by the machine tool builder and can be selected accordingly.
SW limit monitoring		Switch monitoring function on or off
MACHINE REF POINT OFF ON		Display machine reference point





Operating notes:

- With BLK FORM CYLINDER, a cuboid is depicted as the workpiece blank in the working space
- With BLK FORM ROTATION , no workpiece blanks is depicted in the working space

15.3 Functions for program display

Overview

In the **Program Run Single Block** and **Program Run Full Sequence** operating modes, the control displays the following soft keys for displaying the NC program in pages:

Soft key	Functions
	Go back one screen in the NC program
PAGE	Go forward one screen in the NC - program
BEGIN	Select start of program
	Select end of program

15.4 Test run

Application

In the **Test Run** operating mode, you can simulate programs and program sections in order to reduce NC programming errors when programs are running. The control checks the programs for the following:

- Geometrical incompatibilities
- Missing data
- Impossible jumps
- Violation of the machine's working space
- Using disabled tools

The following functions are also available:

- Blockwise test run
- Interruption of test at any block
- Optional block skip
- Functions for graphic simulation
- Measure machining time
- Additional status display

Keep the following in mind when performing a test run

With cuboid workpiece blanks, the control starts a test run after a tool call at the following position:

- In the working plane in the center of the defined **BLK FORM**
- In the tool axis, 1 mm above the MAX point defined in the BLK FORM

With rotationally symmetrical workpiece blanks, the control starts a test run after a tool call at the following position:

- In the machining plane at the position X=0, Y=0
- In the tool axis 1 mm above the defined workpiece blank

NOTICE

Danger of collision!

In the **Test Run** operating mode, the control does not take all axis movements of the machine into consideration (e.g., PLC positioning movements as well as movements from tool-change macros and M functions). This can cause a test performed without errors to later deviate from the machining operation. Danger of collision during machining!

- Test the NC program at the later machining position (BLANK IN WORK SPACE)
- Program a safe intermediate position after the tool change and before prepositioning
- Carefully test the NC program in the Program run, single block operating mode

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Refer to your machine manual.

Your machine tool builder can also define a tool-change macro for the **Test Run** operating mode. This macro will simulate the exact behavior of the machine. In doing so, the machine tool builder often changes the

simulated tool change position.

Test run execution



For the test run, you must activate a tool table (status S). Select a tool table via the file manager in the **Test Run** mode of operation.

You can select any preset table (status S) for the test run.

After **RESET + START**, line 0 of the temporarily loaded preset table automatically displays the currently active preset from **Preset.PR** (execution). Line 0 is selected when starting the test run until you define another preset in the NC program. All presets from lines > 0 are read by the control from the selected preset table of the test run.

With the **BLANK IN WORK SPACE** function, you can activate workspace monitoring for the test run.

Further information: "Showing the workpiece blank in the working space ", page 596

→ >

PGM MGT Operating mode: Press the Test Run key

Call the file manager with the PGM MGT key and select the file you wish to test

The control then displays the following soft keys:

Soft key	Functions
RESET + START	Reset the blank form, reset the previous tool data and test the entire program
START	Test the entire program
START SINGLE	Test each NC block individually
STOP AT	Executes the Test Run until block N
STOP	Stop test run (this soft key only appears if you have started the test run)

You can interrupt and continue the test run at any time, even within fixed cycles. In order to continue the test, the following actions must not be performed:

- Selecting another block with the arrow keys or the GOTO key
- Making changes to the program
- Selecting a new program

Test Run up to a certain block

With the **STOP AT** function the control executes a **Test Run** up to the block with block number N.

Proceed as follows to stop the Test Run at any block:



- Press the STOP AT soft key
- Stop at: N = Enter the block number at which the simulation should stop
- Program = Enter the name of the program containing the block with the selected block number

The control shows the name of the selected program.

- If the simulation is to be stopped in a program that has been called using %, then enter this name
- Repetitions = If N is located in a program section repeat, enter the number of repeats that you want to run.
 Default 1: The control stops before N is simulated

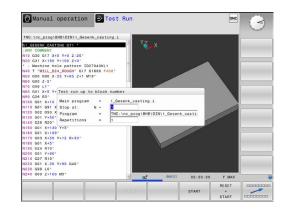
Possibilities in stopped condition

If you interrupt the **Test Run** with the **STOP AT** function, you have the following possibilities in this stopped condition:

- Block skip enable or disable
- Optional program stop enable or disable
- Modify graphics resolution and model
- Modify the NC program in the **Programming** operating mode

If you modify the NC program in the **Programming** operating mode the simulation behaves as follows:

- Modification before the interruption point: The simulation restarts at the beginning
- Modification after the interruption point: Positioning at the interruption point is possible with GOTO



15.5 Program run

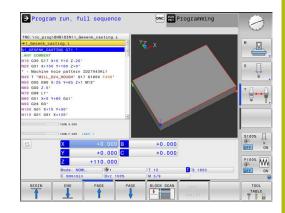
Application

In the **Program run, full sequence** operating mode, the control executes a machining program continuously to its end or up to a program stop.

In the **Program run, single block** operating mode, the control executes each block individually after pressing the **NC Start** key. With point pattern cycles and **G79 PAT** the controls stops after each point.

You can use the following control functions in the **Program run**, single block and **Program run**, full sequence operating modes:

- Interrupt program run
- Starting the program run from a certain block
- Optional block skip
- Edit the tool table TOOL.T
- Checking and changing Q parameters
- Superimpose handwheel positioning
- Functions for graphic simulation
- Additional status display



Running a part program

Preparation

A

- 1 Clamp the workpiece to the machine table.
- 2 Set the preset
- 3 Select the necessary tables and pallet files (status M)
- 4 Select the part program (status M)

Operating notes:

- You can change the feed rate and spindle speed using the potentiometers.
- You can reduce the feed rate using the FMAX soft key. This reduction affects all rapid traverse and feed movements, even after the control has been restarted.

Program Run, Full Sequence

Start the machining program with the **NC Start** key

Program Run, Single Block

 Start each block of the machining program individually with the NC Start key

Interrupting, stopping or aborting machining

There are several ways to stop a program run:

- Interrupt the program run with e.g. the miscellaneous function MO
- Interrupt the program run e.g. with the miscellaneous function MO
- Stop the program run e.g. with the NC stop key in connection with the INTERNAL STOP soft key
- Terminate the program run e.g. with the miscellaneous functions M2 or M30

The control shows the current status of the program run in the status display.

Further information: "General status display", page 84

In contrast to a stopped run, an interrupted, aborted (terminated) program run enables certain actions by the user, including the following:

- Select operating mode
- Check Q parameters and change these if necessary using the Q INFO function
- Change setting for the optional programmed interruption with M1
- Change setting for the programmed skipping of NC blocks with /



During major errors, the control automatically aborts the program run (e.g., during a cycle call with stationary spindle).

Program-controlled interruptions

You can set interruptions directly in the NC program. The control interrupts the program run in the NC Block containing one of the following inputs:

- Programmed stop G38 (with and without miscellaneous function)
- Programmed stop MO
- Conditional stop M1

NOTICE

Danger of collision!

Certain manual interactions cause the control to lose program information affecting the mode and thereby to lose the so-called contextual reference. After the loss of the contextual reference, unexpected and undesired movements can occur. There is a danger of collision during subsequent machining operations!

- > Do not perform the following interactions:
 - Cursor movement to another NC block
 - The jump command GOTO to another NC block
 - Editing an NC block
 - Modifying Q parameter values with the Q INFO soft key
 - Switching the operating modes
- Restore the contextual reference via repetition of the required NC blocks



Refer to your machine manual.

The miscellaneous function **M6** may also lead to a suspension of the program run. The machine manufacturer sets the functional scope of the miscellaneous functions.

Manual program interruption

While a machining program is being executed in the **Program run, full sequence** operating mode, select the **Program run, single block** operating mode. The control interrupts the machining process at the end of the current machining step.

Abort program run.

- Press NC Stop key
 - The control does not exit the current NC block
 - The control shows the symbol for stopped status in the status display

Actions such as a change of operating mode are not possible

The program can be resumed with the $\ensuremath{\text{NC}}$ Start key

Press the INTERNAL STOP soft key

The control briefly shows the symbol for aborting the program in the status display
The control shows the symbol for the exited inactive status in the status display

Actions such as a change of operating mode are available again

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Moving the machine axes during an interruption

You can move the machine axes during an interruption in the same way as in the **Manual operation** mode.

NOTICE

Danger of collision!

During a program interruption, the axes can be moved manually (e.g., in order to retract out of a drilled hole. If, at the time of the interruption, the **Tilt the working plane** function is active, then the **3D ROT** soft key becomes available. The **3D ROT** function can be used to deactivate the tilted working place or to limit manual traverse exclusively to the active tool axis. A risk of collision exists for incorrect **3D ROT** settings!

- It is better to use the TOOL AXIS function
- Use a low feed rate

Modifying the preset during an interruption

If you modify the active preset during an interruption, resuming the program run is only possible with **GOTO** or mid-program startup at the interruption point.

Example:

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Retracting the spindle after tool breakage

- Interrupt machining
- Enable the axis direction keys: Press the MANUAL TRAVERSE soft key
- Move the machine axes with the axis direction keys

On some machines you may have to press the **NC start** key after the **MANUAL TRAVERSE** soft key to enable the axis direction keys. Refer to your machine manual.

Resuming program run after an interruption

The control saves the following data during a program interruption:

- The last tool that was called
- Current coordinate transformations (e.g., datum shift, rotation, mirroring)
- The coordinates of the circle center that was last defined

The control uses the stored data for returning the tool to the contour after manual machine axis positioning during an interruption (**RESTORE POSITION** soft key).

Operating notes:

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- The saved data remains active until it is reset (e.g., by selecting a program).
- If you interrupt an NC program using the INTERNAL STOP key, then you must start machining at the start of the program or by using the BLOCK SCAN function.
- For program interruptions within program section repeats or subprograms, re-entering at the point of interruption must be done using the **BLOCK SCAN** function.
- With machining cycles, mid-program startup is always executed at the start of the cycle. If you interrupt a program run during a machining cycle, the control repeats machining steps already carried out after a block scan.

Resuming the program run with the NC Start key

You can resume program run by pressing the machine **START** button if the program was interrupted in one of the following ways:

- Press the NC Stop key
- Programmed interruption

Resuming program run after an error

With an erasable error message:

- Remove the cause of the error
- ▶ Clear the error message from the screen: Press the **CE** key
- Restart the program, or resume program run where it was interrupted

Retraction after a power interruption



Refer to your machine manual.

Your machine tool builder configures and enables the **Retract** operating mode.

With the **Retraction** mode of operation you can disengage the tool from the workpiece after an interruption in power.

If you activated a feed rate limit before a power failure, this is still active. You can deactivate the feed-rate limit using the **CANCEL THE FEED RATE LIMITATION** soft key.

The **Retraction** mode of operation is selectable in the following conditions:

- Power interrupted
- No control voltage for the relay
- Traverse reference points

The **Retraction** operating mode offers the following modes of traverse:

Mode	Function
Machine axes	Movement of all axes in the machine coordi- nate system
Tilted system	Movement of all axes in the active coordi- nate system Effective parameters: Position of the tilting axes
Tool axis	Movements of the tool axis in the active coordinate system
Thread	Movements of the tool axis in the active coordinate system with compensating movement of the spindle Effective parameters: Thread pitch and direc- tion of rotation



If the **Tilt the working plane** function (option 8) is enabled on your control, then the **Tilted system** traverse mode is also available.

The control selects the mode of traverse and the associated parameters automatically. If the traverse mode or the parameters have not been correctly preselected, you are unable to reset them manually.

NOTICE

Caution: Danger to the tool and workpiece!

A power failure during the machining operation can cause uncontrolled "coasting" or braking of the axes. In addition, if the tool was in effect prior to the power failure, then the axes cannot be referenced after the control has been restarted. For non-referenced axes, the control takes over the last saved axis values as the current position, which can deviate from the actual position. Thus, subsequent traverse movements do not correspond to the movements prior to the power failure. If the tool is still in effect during the traverse movements, then the tool and the workpiece can sustain damage through tension!

- Use a low feed rate
- Please keep in mind that the traverse range monitoring is not available for non-referenced axes

Example

The power failed while a thread cutting cycle in the tilted working plane was being performed. You have to retract the tap:

Switch on the power supply for control and machine

The control starts the operating system. This process may take several minutes.

The control will then display the **Power interrupted** message in the screen header.



 Activate the Retraction mode: Press the RETRACT soft key
 The control displays the message Retraction

selected



CE

- Confirm the power interruption: Press the CE key The control compiles the PLC program.
- Switch on the machine control voltage The control checks the functioning of the EMERGENCY STOP circuit. If there is at least one non-referenced axis, you will have to compare the displayed position values with the actual axis values and confirm that they are correct. if required, follow the dialog.
- Check the preselected traverse mode: If required, select THREAD
- Check the preselected thread pitch: if required, enter the thread pitch
- Check the preselected direction of rotation: if needed, select the turning direction of the thread Right-handed thread: the main spindle turns clockwise when moving into the workpiece, counter-clockwise when retracting from it; left-handed thread: main spindle turns counter-clockwise when moving into the workpiece and clockwise when retracting from it

RETRACT

15

- Activate retraction: Press the **RETRACT** soft key
- Retraction: Retract the tool with the axis direction keys or the electronic handwheel
 Axis key Z+: Retraction from the workpiece
 Axis key Z-: Moving into the workpiece



 Exit retraction: Return to the original soft-key level

END
END RETRACTION

 End the Retraction mode: Press the END RETRACTION soft key
 The control checks whether the Retraction

mode can be ended. If necessary, follow the dialog.

Answer confirmation request: If the tool was not correctly retracted, press the NO soft key. If the tool was correctly retracted, press the YES soft key.

The control hides **Retraction selected**mode.

- ▶ Initialize the machine: if required, cross the reference points
- Establish the desired machine condition: If required, reset the tilted working plane

Entering the program at any point: Mid-program startup

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Refer to your machine manual.

The **BLOCK SCAN** function must be enabled and configured by the machine tool manufacturer.

With the **BLOCK SCAN** function you can start an NC program at any desired NC block. The control factors workpiece machining up to this NC block into the calculations.

You can run the mid-program startup in the following ways:

- Mid-program startup in the main program, with repetitions if necessary
- Multi-level mid-program startup in subprograms and touch probe cycles
- Mid-program startup in a point table
- Block scan in pallet programs

At the start of mid-program startup the control resets all data, as with a selection of the NC program. During the mid-program startup, you can switch between **Program Run Full Sequence** and **Program Run Single Block**.

NOTICE

Danger of collision!

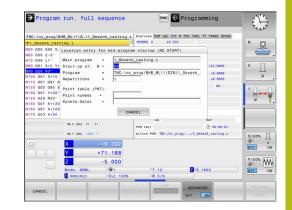
The **BLOCK SCAN** function skips over the programmed touch probe cycles. As a result, the result parameters contain no values or, possibly, incorrect values. If the subsequent machining operation uses these result parameters, then there is a risk of collision!

 Use the BLOCK SCAN function at multiple levels
 Further information: "Procedure for multi-level mid-program startup", page 615



The **BLOCK SCAN** function must not be used in conjunction with the following functions:

 Touch probe cycle G55 during the search phase of mid-program startup



Procedure for simple mid-program startup

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The control only displays the dialogs required by the process in the pop-up window.

- BLOCK SCAN
- Press the BLOCK SCAN soft key

The control shows a pop-up window with the active main program.

- Start-up at: N = Enter the number of the NC block where you wish to enter the NC program
- Program = Check the name and path of the NC program containing the NC block, or enter with the SELECT soft key
- Repetitions = Enter the number of repetitions which should be taken into account in the block scan if the NC block is located within a program section repetition.
 Default 1 means initial machining operating
- Press the NC Start key

The control starts the block scan, calculates until the entered NC block and shows the next dialog.

If you changed the machine status:

Press the NC Start key

The control restores the machine status, e.g. tool call, M functions and shows the next dialog.

If you changed the axis positions:

- Press the NC Start key The controls approaches the specified positions in the defined sequence and displays the next dialog message. Approach the axes in the selfselected sequence:

Further information: "Returning to the contour", page 618

Press the NC Start key
 The control resumes execution of the NC program.

Example of simple mid-program startup

After an internal stop, you would like to start in block 120 in the third machining operation of 1G98 L1.

In the pop-up window enter the following data:

- Start-up at: N =120
- Repetitions = 3

Procedure for multi-level mid-program startup

If you, for example, start in a subprogram that is called several times by the main program, then use the multi-level mid-program startup. For this purpose, jump in the main program to the desired subprogram call. With the **CONTINUE BLOCK SCAN** function, you can jump further from this position.



Operating notes:

- The control only displays the dialogs required by the process in the pop-up window.
- You can also continue the BLOCK SCAN without restoring the machine status and the axis position of the first startup point. For this, press the CONTINUE BLOCK SCAN soft key before confirming the restoration with the NC-Start key.

Mid-program startup to the first start-up point:

	DCK	SCAN
-	_	
	12	

- ▶ Press the **BLOCK SCAN** soft key
- Enter the first NC block where you wish to start
- Press the NC Start key

The control starts the block scan and calculates until the entered NC block.

If the control should restore the machine status of the entered NC block:



Press the NC Start key

The control restores the machine status, e.g. tool call, M functions.

If the control should restore the axis positions:



Press the NC Start key

The control moves in the specified sequence to the specified positions.

If the control should run the NC block:



Select the Program Run Single Block operating mode if required



CONTINUE BLOCK SCAN Press the NC Start key

The control runs the NC block.

Mid-program startup to the next start-up point:

Press the CONTINUE BLOCK SCAN soft key

Enter the NC block where you wish to start

If you changed the machine status:



Press the NC Start key

If you changed the axis positions:

Press the NC Start key

If the control should run the NC block:



Press the NC Start key

 Repeat these steps if required to jump to the 	
next start-up point	
Press the NC Start key	
The control requires evenution of the NIC	

The control resumes execution of the NC program.

Example of multi-level mid-program startup

You run a main program with several subprogram calls in the program Sub.i. You work with a touch probe cycle in the main program. You use the result of the touch probe cycle later for positioning.

After an internal stop you wish to start up in block 80 in the second call of the subprogram. This subprogram call is in block 530 of the main program. The touch probe cycle is in block 280 of the main program, i.e. before the desired start-up point.

	 Press the BLOCK SCAN soft key In the pop-up window enter the following data: Start-up at: N =280 Repetitions = 1
	 Select the Program Run Single Block operating mode if required
	 Press the NC start key until the control runs the touch probe cycle The control saves the result.
CONTINUE	Press the CONTINUE BLOCK SCAN soft key
BLOCK SCAN	In the pop-up window enter the following data:
	Start-up at: N =530
	Repetitions = 1
	 Press the NC start key until the control runs the NC block
	The control jumps into the subprogram Sub.i.
CONTINUE	Press the CONTINUE BLOCK SCAN soft key
BLOCK SCAN	In the pop-up window enter the following data:
	Start-up at: N =80
	Repetitions = 1
	 Press the NC start key until the control runs the NC block
	The control continues to run the subprogram and then returns to the main program.

Block scan in a point table

If you start in a point table called by the main program, use the **ADVANCED** soft key.



OFF ON

Press the BLOCK SCAN soft key

The control shows a pop-up window.

- Press the ADVANCED soft key The control expands the pop-up window.
- Point number = enter the line number of the point table you start with
- Enter the **Point file =** name and path of the point table



Press the NC Start key

If you would like to start with the mid-program startup in a point pattern, then proceed just as you would for starting in the point table. Enter the desired point number in the **Point number =** input field. The first point in the point pattern has the point number **0**.

Returning to the contour

With the **RESTORE POSITION** function, the control moves the tool to the workpiece contour in the following situations:

- Return to the contour after the machine axes were moved during a program interruption that was not performed with the INTERNAL STOP function.
- Return to the contour with a block scan with RESTORE POS AT N, for example, after an interruption with INTERNAL STOP
- Depending on the machine, if the position of an axis has changed after the control loop has been opened during a program interruption

Procedure

Proceed as follows to approach the contour:



Press the **RESTORE POSITION** soft key

POSITION

Restore the machine status, if required

Approach the axes in the sequence shown by the control:

Press the NC Start key

Approach the axes according to individually selected sequence:



- Press the SELECT AXIS soft key
- Press the axis soft key of the first axis

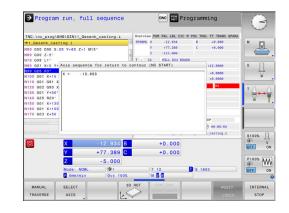


- Press the NC Start key
- Press the axis soft key of the second axis
- Press the NC Start key



Repeat the process for all axes

If the tool is located in the tool axis below the starting point, then the control offers the tool axis as the first traverse direction.



15.6 Automatic program start

Application



Refer to your machine manual.

The control must be specially prepared by the machine tool builder for use of the automatic program start function.

Caution: Danger for the operator!

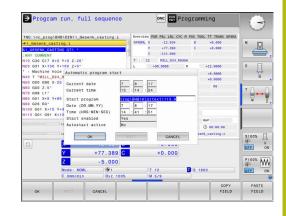
The **AUTOSTART** function automatically starts the machining operation. Open machines with unsecured work envelops pose a huge danger for the machine operator.

▶ Use the AUTOSTART function exclusively on closed machines

In a Program Run operating mode, you can use the **AUTOSTART** soft key to define a specific time at which the program that is currently active in this operating mode is to be started:



- Display window for setting the starting time
- Time (hrs:min:sec): Time of day at which the program is to be started
- Date (DD.MM.YYYY): Date on which the program is to be started
- ► To activate the start, press the **OK**



15.7 Skipping blocks

Application

You can have blocks skipped in the **Test Run** or **Program Run, Full Sequence/Single Block** operating modes if you have marked these blocks with a / sign:



- In order to not execute or not test NC blocks with a / sign, set the soft key to ON
- To execute or test NC blocks with a / sign, set the soft key to OFF



Operating notes:

- This function does not work for **G99** blocks.
- After a power interruption the control returns to the most recently selected setting.

Delete / symbol

In the **Programming** mode you select the block in which the character is to be added



Press the INSERT soft key

Delete / symbol

In the **Programming** mode you select the block in which the character is to be erased



Press the **REMOVE** soft key

15.8 Optional program-run interruption

Application



Refer to your machine manual.

The behavior of this function varies depending on the respective machine.

The control optionally interrupts program run at blocks in which an M1 has been programmed. If you use M1 in the **Program run** operating mode, then the control does not switch off the spindle or the coolant.



- Do not interrupt Program run or Test Run with blocks containing M1: Set the soft key to OFF
- ON OFF
- Interrupt Program run or Test Run with blocks containing M1: Set the soft key to ON

16

MOD Functions

16.1 MOD function

The MOD functions provide additional input possibilities and displays. In addition, you can enter code numbers to enable access to protected areas.

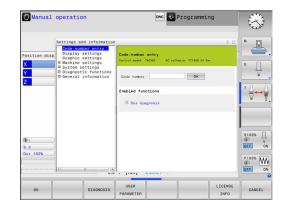
Selecting MOD functions

Open the pop-up window with the MOD functions:

MOD

Press the MOD key

The control opens a pop-up window displaying the available MOD functions.



Changing the settings

As well as with the mouse, navigation with the keyboard is also possible in the MOD functions:

- Switch from the input area in the right window to the MOD function selections in the left window with the tab key
- Select MOD function

i

- Switch to the input field with the tab key or ENT key
- Enter value according to function and confirm with OK or make selection and confirm withApply

If there are multiple possible settings available, then you can show the selection box by pressing the **GOTO** key. Select the desired setting with the **ENT** key. If you do not wish to change the setting, close the window with the **END** key.

Exiting MOD functions

▶ Exit the MOD functions: Press the END soft key or the END key

Overview of MOD functions

The following functions are available independent of the selected operating mode:

Code-number entry

Code number

Display settings

- Digital readouts
- Measuring unit (mm/inch) for position display
- Program entry for MDI
- Show time of day
- Show the info line

Graphic settings

- Model type
- Model quality

Counter settings

- Momentary count
- PGM for counter

Machine settings

- Kinematics
- Traverse limits
- Tool-usage file
- External access
- Set up wireless handwheel

System settings

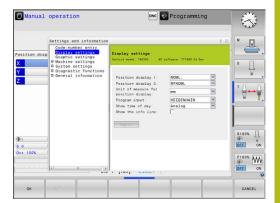
- Set the system time
- Define the network connection
- Network: IP configuration

Diagnostic functions

- Bus diagnosis
- Diagnosis of Drives
- HEROS information

General information

- Version information
- License information
- Machine times



16.2 Graphic settings

With the MOD functions **Graphic settings** you can select the model type and model quality operating mode.

To select **Graphic settings** proceed as follows:

- ▶ Select the group **Graphic settings** from the MOD menu
- Select the model type
- Select the model quality
- Press the APPLY soft key
- Press the OK soft key.

In the **Test Run** operating mode, the control displays icons of the active **Graphic settings**.

You have the following simulation parameters for the control's Graphic settings:

Model type

lcon	Choice	Properties	Application
⊾	3-D	Very true to detail, heavy time and processor consump- tion	Milling with undercuts,
Ľ	2.5 D	Fast	Milling without undercuts
	No model	Very fast	Line graphics

Model quality

lcon	Choice	Properties
0000	Very high	High data transfer rate, exact depiction of tool geometry, depiction of block end points and block numbers possible
0000	High	High data transfer rate, exact depiction of tool geometry
0000	Medium	Medium data transfer rate, approximation of tool geometry
0000	Low	Low data transfer rate, coarse approximation of tool geometry

16.3 Counter settings

With the MOD function **Counter settings**, you can change the current count (actual value) and the target value (nominal value).

Proceed as follows to select the **Counter settings**:

- ▶ In the MOD menu, select the **Counter settings** group
- Select the current count
- Select the target value for the counter
- Press the APPLY soft key
- ► Press the **OK** soft key

The control immediately takes over the selected value in the status display

You can change the **Counter settings** via soft key as follows:

Soft key	Meaning
RESET	Reset count
+	Increase count
-	Lower count

You can also enter the values directly with a connected mouse. **Further information:** "Defining a counter", page 457

16.4 Machine settings

External access

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Refer to your machine manual.

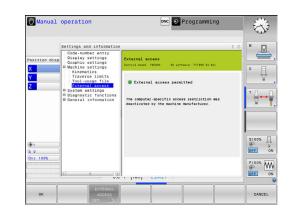
The machine tool builder can configure the external access options.

Depending on the machine, you can grant or restrict access for an external diagnostics or commissioning software application using the **TNCOPT** soft key.

With the MOD function **External access**, you can grant or restrict access to the control. Once you have restricted external access, it is no longer possible to connect to the control and to exchange data over a network or over a serial connection (e.g., with the TNCremo data transfer software).

Proceed as follows to restrict external access:

- ▶ In the MOD menu, select the Machine settings group
- Select the External access menu
- Set the EXTERNAL ACCESS ON/OFF soft key to OFF
- Press the OK soft key



Computer-specific access control

If your machine manufacturer has set up computer-specific access control (machine parameter **CfgAccessControl** no. 123400)), you can permit access for up to 32 connections authorized by you. Select **Add** to create a new connection. The control then opens an input box for you to enter the connection data.

Access settings

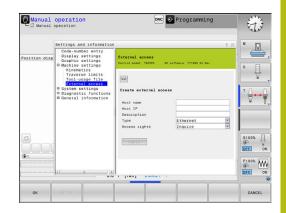
F)

Host name of the external computer	
Network address of the exter- nal computer	
Additional information (text is shown in the overview list)	
Network connection	
Serial interface 1	
Serial interface 2	
For external access, the control opens a query dialog	
Do not permit network access	
Permit network access without query	

If you assign the **Inquire** access right to a connection, and if access is gained from this address, then the control opens a pop-up window. You must permit or deny external access in the pop-up window:

External access	Permission
Yes	Permit once
Always	Permit continuously
Never	Deny continuously
No	Deny once

In the overview list, an active connection is shown with a green symbol. Connections without access rights are shown gray in the overview list.



Entering traverse limits

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Refer to your machine manual.

Your machine tool builder configures and enables the **Traverse limits** function.

The MOD function **Traverse limits** enables you to limit the actually usable tool path within the maximum traverse range. This enables you to define protection zones on each axis in order, for example, to protect a component from collision.

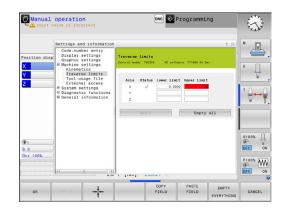
To enter traverse limits:

- In the MOD menu, select the Machine settings group
- Select the Traverse limits menu
- Enter the values of the desired axes as a reference value or load the momentary position with the actual position capture soft key
- Press the APPLY soft key
 - The control checks the entered values for validity.
- Press the **OK** soft key

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Operating notes:

- The protection zone becomes active automatically as soon as you have set a valid traverse limit in an axis. The settings are kept even after the control has been restarted.
- You can only deactivate the protection zone by deleting all values or pressing the EMPTY EVERYTHING soft key.



Tool usage file



Refer to your machine manual.

The tool usage test function must be enabled by your machine tool builder.

With the MOD function **Tool-usage file**, you can select whether the control never, once, or always creates a tool usage file. Generate a tool usage file:

- In the MOD menu, select the Machine settings group
- Select the **Tool-usage file** menu
- Select the desired setting for the Program Run, Full Sequence/ Single Block and Test Run operating modes
- Press the APPLY soft key
- Press the OK soft key

Select kinematics



Refer to your machine manual.

Your machine tool builder configures and enables the **Kinematics selection** function.

NOTICE

Danger of collision!

All stored kinematics can also be selected as active machine kinematics. By this means, all manual movements and machining operations are executed using the selected kinematics. All subsequent axis movements pose a risk of collision!

- Use the Kinematics selection function only in the Test Run operating mode
- Use the Kinematics selection function for selecting the active machine kinematics only as needed

You can use this function to test programs whose kinematics does not match the active machine kinematics. If your machine manufacturer saved different kinematic configurations in your machine, you can activate one of these kinematics configurations with the MOD function. When you select a kinematics model for the test run this does not affect machine kinematics.



Ensure that you have selected the correct kinematics in the Test Run operating mode for checking your workpiece.

16.5 System settings

Set the system time

With the **Set the system time** MOD function you can set the time zone, date and time manually or with the aid of an NTP server synchronization.

Proceed as follows to set the system time:

- In the MOD menu, select the System settings group
- Press the SET DATE/ TIME soft key
- ▶ In the **Time zone** area, select the desired time zone
- Press the NTP on soft key in order to select the Set the time manually entry
- Change the date and time as needed
- ▶ Press the **OK** soft key

To set the system time with the aid of an NTP server:

- In the MOD menu, select the System settings group
- Press the SET DATE/ TIME soft key
- ▶ In the **Time zone** area, select the desired time zone
- Press the NTP off soft key in order to select the Synchronize the time over NTP server entry
- Enter hostnames or the URL of an TNP server
- Press the Add soft key
- ► Press the **OK** soft key

16.6 Select the position display

Application

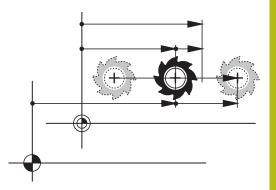
You can influence the display of the coordinates for the operating mode **Manual operation** and the operating modes **Program run, full sequence** and **Program run, single block**.

The figure on the right shows the different tool positions:

- Initial position
- Target position of the tool
- Workpiece datum
- Machine datum

You can select the following coordinates for the control's position displays:

Display	Function	
NOML	Nominal position: The value currently command- ed by the control	
	The NOML and ACTL displays differ solely with regard to following error.	
ACTL	Actual position; current tool position	
	Refer to your machine manual. Your machine tool builder defines whether the ACTL and NOML display deviates from the programmed position by the DL oversize of the tool call.	
REF ACTL	Reference position; actual position relative to the machine datum	
REF NOML	Reference position; nominal position relative to the machine datum	
LAG	Servo lag; difference between nominal and actual positions	
ACTDST	 Distance remaining to the programmed position in the input coordinate system; difference between actual and target positions Examples with Cycle 11: Scaling factor 0.2 L IX+10 The ACTDST display shows 10 mm. The scaling factor does not have any influence. 	



Display Function	
REFDST	Distance remaining to the programmed position in the machine coordinate system; difference between actual and target positions
	Examples with Cycle 11
	Scaling factor 0.2
	▶ L IX+10
	The REFDST display shows 2 mm.
	The scaling factor has an effect on the distance and thus on the display.
M118	Traverse paths that were executed with handwheel superimpositioning function (M118)

With the MOD function **Position display 1**, you can select the position display in the status display.

With the MOD function **Position display 2**, you can select the position display in the additional status display.

16.7 Setting the unit of measure

Application

With this MOD function, you can determine whether the control coordinates are displayed in millimeters or inches.

- Metric system: e.g. X = 15.789 (mm), the value is displayed to 3 decimal places
- Inch system: e.g. X = 0.6216 (inches), value is displayed to 4 decimal places

If you would like to activate the inch display, the control shows the feed rate in inch/min. In an inch program you must enter the feed rate larger by a factor of 10.

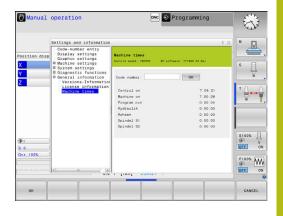
16.8 Displaying operating times

Application

The **MACHINE TIME** MOD function enables you to see various types of operating times:

Operating	time	Meaning
Control on		Operating time of the control since being put into service
Machine o	า	Operating time of the machine tool since being put into service
Program ru	n	Duration of controlled operation since being put into service
	Refer to your machine manual.	

Refer to your machine manual. The machine tool builder can provide further operating time displays.



16.9 Software numbers

Application

The following software numbers are displayed on the control's screen after the **Software version** MOD function has been selected:

- Control model: Designation of the control (managed by HEIDENHAIN)
- NC SW: Number of the NC software (managed by HEIDENHAIN)
- NCK: Number of the NC software (managed by HEIDENHAIN)
- PLC: Number or name of the PLC software (managed by your machine manufacturer)

In the **FCL Information** MOD function, the control shows the following information:

 Development level (FCL=Feature Content Level): Development level of the software installed on the control Further information: "Feature Content Level (upgrade functions)", page 10

16.10 Enter the code number

Application

The control requires a code number for the following functions:

Function	Code number	
Select user parameters	123	
Configuring an Ethernet card	NET123	
Enabling special functions for Q parameter	555343	

programming

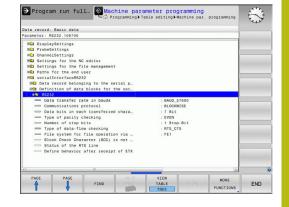
16.11 Setting up data interfaces

Serial interfaces on the TNC 320

The TNC 320 automatically uses the LSV2 transmission protocol for serial data transfer. The LSV2 protocol is prescribed and cannot be modified apart from setting the baud rate (machine parameter **baudRateLsv2**, no. 106606). You can also define another type of data transfer (interface). The settings described below are therefore effective only for the respective newly defined interface.

Application

To set up a data interface, press the **MOD** key. Enter the code number 123. In the **CfgSerialInterface** (no. 106700) machine parameter, you can enter the following settings:



Setting the RS-232 interface

Open the RS232 folder. The control then displays the following settings:

Set BAUD RATE (baud rate no. 106701)

You can set the BAUD RATE (data transfer speed) from 110 to 115 200 baud.

Set protocol (protocol no. 106702)

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The data transfer protocol controls the data flow of a serial transmission (comparable to MP5030 of the iTNC 530).

Operating r	notes:
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- The BLOCKWISE setting designates a type of data transfer in which the data is transferred grouped in blocks.
- The BLOCKWISE setting does not correspond to the data reception in blocks nor to the simultaneous execution of older contouring controls in blocks. This function is no longer available for current controls.

Data transmission protocol Selection	
Standard data transmission (transmission line-by-line)	STANDARD
Packet-based data transfer	BLOCKWISE
Transmission without protocol (only charac- ter-by-character)	RAW_DATA

Set data bits (dataBits no. 106703)

By setting the data bits you define whether a character is transmitted with 7 or 8 data bits.

Check parity (parity no. 106704)

The parity bit helps the receiver to detect transmission errors. The parity bit can be formed in three different ways:

- No parity (NONE): There is no error detection
- Even parity (EVEN): Here there is an error if the receiver finds that it has received an odd number of set bits
- Odd parity (ODD): Here there is an error if the receiver finds that it has received an even number of set bits

Set stop bits (stopBits no. 106705)

The start bit and one or two stop bits enable the receiver to synchronize each transmitted character during serial data transmission.

Set handshake (flowControl no. 106706)

By handshaking, two devices control data transfer between them. A distinction is made between software handshaking and hardware handshaking.

- No data flow checking (NONE): Handshaking is not active
- Hardware handshaking (RTS_CTS): Transmission stop is active through RTS
- Software handshaking (XON_XOFF): Transmission stop is active through DC3 (XOFF)

File system for file operation (fileSystem no. 106707)

In **fileSystem** you define the file system for the serial interface. This machine parameter is not required if you don't need a special file system.

- EXT: Minimum file system for printers or non-HEIDENHAIN transmission software. It corresponds to the EXT1 and EXT2 operating modes on older HEIDENHAIN controls.
- FE1: Communication with the TNCserver PC software or an external floppy disk unit.

Block check character (bccAvoidCtrlChar no. 106708)

With Block Check Character (optional) no control character, you determine whether the checksum can correspond to a control character.

- TRUE: The checksum does not correspond to a control character
- FALSE: The checksum can correspond to a control character

Condition of RTS line (rtsLow no. 106709)

With the state of the RTS line (optional), you can define whether the **LOW** level is active in idle state.

- TRUE: Level is LOW in idle state
- FALSE: Level is not LOW in idle state

Define behavior after receipt of ETX (noEotAfterEtx no. 106710)

With define behavior after reception of ETX (optional) you determine whether the EOT character is sent after the ETX character was received.

- TRUE: The EOT character is not sent
- FALSE: The EOT character is sent

Settings for the transmission of data using PC software TNCserver

Apply the following settings in machine parameter **RS232** (no. 106700):

Parameters	Selection
Data transfer rate in baud	Has to match the setting in TNCserver
Data transmission protocol	BLOCKWISE
Data bits in each transferred character	7 bits
Type of parity checking	EVEN
Number of stop bits	1 stop bit
Specify type of handshake:	RTS_CTS
File system for file operations	FE1

Setting the operating mode of the external device (fileSystem)



The load all programs, load offered program, and load directory functions are not available in the FE2 and FEX operating modes.

lcon	External device	Operat- ing mode
	PC with HEIDENHAIN TNCremo data transfer software	LSV2
	HEIDENHAIN floppy disk units	FE1
Þ	Non-HEIDENHAIN devices such as printers, scanners, punchers, PC without TNCremo	FEX

Software for data transfer

For data transfer to or from the control, you should use the HEIDENHAIN TNCremo software. With TNCremo, data transfer is possible with all HEIDENHAIN controls via the serial interface or the Ethernet interface.



You can download the current version of the **TNCremo** software from the HEIDENHAIN homepage.

System requirements for TNCremo:

- PC with 486 processor or higher
- Windows XP, Windows Vista, Windows 7, Windows 8 operating system
- 16 MB RAM
- 5 MB free memory space on your hard disk
- An available serial interface or connection to the TCP/IP network

Installation under Windows

- Start the SETUP.EXE installation program with the file manager (Explorer)
- Follow the setup program instructions

Starting TNCremo under Windows

 Click on <Start>, <Programs>, <HEIDENHAIN Applications>, <TNCremo>

When you start TNCremo for the first time, it automatically tries to set up a connection with the control.

Data transfer between the control and TNCremo

Check whether the control is connected to the correct serial port on your PC or to the network.

Once you have started TNCremo, you will see a list of all files that are stored in the active directory in the upper section of the main window 1. Using <File>, <Change directory>, you can select any drive or another directory on your PC.

If you want to control data transfer from the PC, establish the connection with your PC in the following manner:

- Select <File>, <Setup connection>. TNCremo now receives the file and directory structure from the control and displays this in the lower part of the main window 2
- To transfer a file from the control to the PC, select the file in the control window per mouse click and move the highlighted file into the PC window while holding down the mouse button 1
- To transfer a file from the PC to the control, select the file in the PC window per mouse click and move the highlighted file into the control window while holding down the mouse button 2

If you want to control data transfer from the control, establish the connection with your PC in the following manner:

- Select <Extras>, <TNCserver>. TNCremo then starts in server mode and can receive data from the control or send data to the control
- You can now call the file management functions on the control by pressing the PGM MGT key in order to transfer the desired files

Further information: "Data transfer to or from an external data carrier", page 168

If you have exported a tool table from the control, then the tool types are converted to tool type numbers. **Further information:** "Available tool types", page 239

End TNCremo

Select <File>, <Exit>



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You can open the context-sensitive help function of the $\ensuremath{\text{TNCremo}}$ software by pressing the $\ensuremath{\text{F1}}$ key.

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■ 1.H	813		04.03.97 11:34:08		
🖻 1E.H 🛛 🖪	379		02.09.97 14:51:30		Insgesamt 8
■ 1F.H	360		02.09.97 14:51:30		Maskiert:
IGB.H	412		02.09.97 14:51:30		policiani. po
■ 11.H	384		02.09.97 14:51:30	-	
	TNC:\NK\	SCRDUMP[*.	1		Verbindung
Name	Große	Attribute	Datum	-	Protokoll:
					LSV-2
₽ 200.H	1596		06.04.99 15:39:42		Schnittsteller
🕒 201.H	1004		06.04.99 15:39:44		CDM2
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Donald II	0760		00.04.00.16.00.40	×	

16.12 Ethernet interface

Introduction

The control is shipped with a standard Ethernet card to connect the control as a client in your network. The control transmits data via the Ethernet card with

- the smb protocol (Server Message Block) for Windows operating systems, or
- The TCP/IP protocol family (Transmission Control Protocol/Internet Protocol) and with support from the NFS (Network File System)



Protect your data and your control by running your machines in a secure network.

Connection possibility

You can connect the Ethernet card in your control to your network through the RJ45 connection (X26,1000BaseTX, 100BaseTX and 10BaseT), or directly to a PC. The connection is metallically isolated from the control electronics.

For a 1000Base TX, 100BaseTX, and 10BaseT connection, use a twisted-pair cable to connect the control to your network.

The maximum possible cable length depends on the quality grade of the cable, the sheathing, and the type of network (1000BaseTX, 100BaseTX, or 10BaseT)

Configuring the control



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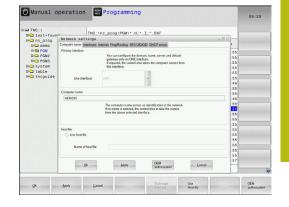
Have a network specialist configure the control.

- Press the MOD key
- Enter the code number NET123
- Press the PGM MGT key
- Press the NET soft key

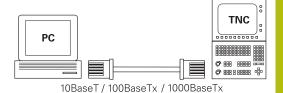
General network settings

Press the CONFIGURE NETWORK soft key to enter the general network settings. The Computer name tab is active:

Setting	Meaning
Primary inter- face	Name of the Ethernet interface to be integrat- ed in your company network. Only active if a second, optional Ethernet interface is avail- able on the control hardware
Computer name	Name displayed for the control in your compa- ny network







Setting	Meaning
Host file	Only required for special applications : Name of a file in which the assignments of IP addresses to computer names is defined

• Select the **Interfaces** tab to enter the interface settings:

Setting	Meaning
Interface list	List of the active Ethernet interfaces. Select one of the listed interfaces (via mouse or arrow keys)
	 Activate button: Activate the selected interface (X appears in the Active column)
	 Deactivate button: Deactivate the selected interface (- appears in the Active column)
	 Configuration button: Open the configuration menu
Allow IP forwarding	This function must be kept deactivated . Only activate this function if the optionally available second Ethernet interface should be accessed externally for diagnostic purposes via the control. Only do so after instruction by our Service Department

TNC:\	TNC:\nc_prog\PGM*.H;*.I;*.DXF				
B- nc prog	Network settings	13-1			
@ 🖨 demo	Computer name Interfaces Internet PingRouting NFS UID/GID DHCP server				
🕀 😋 PGM	Active Name Connectors Configuration	55			
ID CD PGM2	Active Name Connectors Configuration X eth0 X26 DHCPLAN	55			
BH PGM3	A CERU AZO DELE-CAN	55			
D table		55			
B- thcquide		55			
		46			
		55			
		55			
		46			
		55			
		31			
		55			
		55			
	Activate Deactivate Configuration	55			
	Plomarding	55			
	Allow IP forwarding	55			
	55				
	be forwarded to other interfaces.	55			
		55			
	OK Apply OEM Cancel	57			
	Lance Lance	1 1			

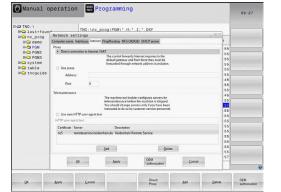
Press the Configuration button to open the Configuration menu:

Setting	Meaning
Status	 Interface active: Connection status of the selected Ethernet interface
	 Name: Name of the interface you are currently configuring
	 Plug connection: Number of the plug connection of this interface on the logic unit of the control
Profile	Here you can create or select a profile in which all settings shown in this window are stored. HEIDENHAIN provides two standard profiles:
	 DHCP-LAN: Settings for the standard Ethernet interface; should work in a standard company network
	 MachineNet: Settings for the second, optional Ethernet interface; for configuration of the machine network
	Press the corresponding buttons to save, load and delete profiles
IP address	 Automatically procure IP address option: The control is to procure the IP address from the DHCP server
	 Option Manually set IP address: Manually define the IP address and subnet mask. Input: Four numerical values separated by periods, e.g. 160.1.180.20 and 255.255.0.0
Domain Name Server (DNS)	Option Automatically procure DNS: The control is to automatically procure the IP address of the domain name server
	 Option Manually configure the DNS: Manually enter the IP addresses of the servers and the domain name
Default gateway	 Automatically procure default gateway option: The control is to automatically procure the default gateway
	Option Manually configure the default gateway: Manually enter the IP addresses of the default gateway

 Apply the changes with the OK button, or discard them with the Cancel button

• Select the tab **Internet**.

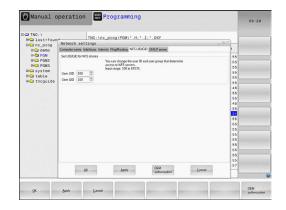
Setting	Meaning
Ргоху	Direct connection to Internet / NAT: The control forwards Internet inquiries to the default gateway and from there they must be forwarded through network address translation (e.g. if a direct connection to a modem is available)
	Use proxy: Define the Address and Port of the Internet router in your network, ask your network administrator for the correct address and port
Telemainte- nance	The machine manufacturer configures the server for telemaintenance here. Changes must always be made in agreement with your machine tool builder
 Select the Pi settings: 	ng/Routing tab to enter the ping and routing
	ng/Routing tab to enter the ping and routing Meaning
settings:	Meaning In the Address: field, enter the IP number for which you want to check the network connec- tion. Input: four numerical values separated by periods, e.g. 160.1.180.20. As an alterna- tive, you can enter the name of the computer whose connection you want to check
settings: Setting	Meaning In the Address: field, enter the IP number for which you want to check the network connec- tion. Input: four numerical values separated by periods, e.g.160.1.180.20. As an alterna- tive, you can enter the name of the computer whose connection you want to check
settings: Setting	 Meaning In the Address: field, enter the IP number for which you want to check the network connection. Input: four numerical values separated by periods, e.g. 160.1.180.20. As an alternative, you can enter the name of the computer whose connection you want to check Press the Start button to begin the test. The control shows the status information



TNC: \		
B- lost+foun	TNC:\nc_prog\PGM*.H;*.I;*.DXF	
B- nc prog	Network settings	
ID Ca demo	Computer name Interfaces Internet PingRouting NFSUIDIGID DHCP server	
E-C PGM	Pag 55	
E-C PGM2	Address: 55	
B-C PGM3	55	
D table	55	
B- thcquide	55	COLORING COLORING
enegoroe	55	
	×0 × 55	
	55	
	Start Stop	
	55	
	Routing Kernel Prouting table	
	Destination Gateway Germask Flags Metric Ref Use flace	
	0.0.0 107.15.254 0.0.0 UG 0 0 0 eth0 107.00 0.0.00 255.255.240.0 U 0 0 0 eth0 55	
	10700 0000 235252400 0 0 0 0000	
	55	
	55	
	Update	
	55	
	55	
	QK Apply OEM Cancel	
	authorization	

Select the NFS UID/GID tab to enter the user and group identifications:

Setting	Meaning		
Set UID/GID for NFS shares	 User ID: Definition of which user identification the end user uses to access files in the network. Ask your network specialist for the proper value 		
	 Group ID: Definition of the group identification with which you access files in the network. Ask your network specialist for the proper value 		



	DHCP server:	Settings for	automatic	network	configuration
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Setting	Meaning
DHCP server	IP addresses from: Define the IP address as of which the control is to derive the pool of dynamic IP addresses. The control transfers the values that appear dimmed from the static IP address of the defined Ethernet interface; these values cannot be edited.
	IP addresses to: Define the IP address up to which the control is to derive the pool of dynamic IP addresses.
	• Lease Time (hours): Time within which the dynamic IP address is to remain reserved for a client. If a client logs on within this time, the control reassigns the same dynamic IP address.
	Domain name: Here you can define a name for the machine network if required. This is necessary if thesame names are assigned in the machine network and in the external network, for example.
	Forward DNS to external: If IP Forwarding is active (Interfaces tab) and the option is active, you can specify that the name resolution for devices in the machine network can also be used by the external network.
	• Forward DNS from external: If IP Forwarding is active (Interfaces tab) and the option is active, you can specify that the control is to forward DNS inquiries from devices within the machine network to the name server of the external network if the DNS server of the MC cannot answer the inquiry.
	Status button: Call an overview of the devices that are provided with a dynamic IP address in the machine network. You can also select settings for these devices.
	 Advanced options button: Additional settings for the DNS/DHCP server.
	Set stan- dard values button: Set factory settings.

En lost+roun	_prog\PGM*.H;*.I;*.DXF	
B- nc_prog Network settings	net PingRouting NFS UD/GID DHCP server	2.63
D demo Computer name Interfaces Inter DHCP settings	net ringhoung arounder oner sinte	-
P-P PGM2	Activate DHCP/DNS server services for	
B-C PGM3	devices in the machine network	_
system DHCP server active on:	en1	×
Paddresses as of	192 . 168 . 254 . 10	
P addresses up to:	192 20 168 254 20 100 20	
Leave Time (hours)	240	B
		- 0
Domain name:	machine.net	× :4
Forward DNS to external		3
Forward DNS from externs	al	5
		5
Saus	Advanced Set stan	5
	options dard values	5
		5
The	IHCP server service cannot be activated on the primary interface.	5
		5
OK	Apply OEM Carcel	5

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Sandbox: Settings for the so-called sandbox

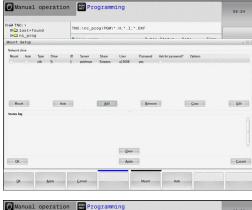
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Configure and use the sandbox on your control. For safety and security reasons, always open the browser in the sandbox.

Network settings specific to the device

Press the DEFINE NETWORK CONNECTN. soft key to enter the network settings for a specific device. You can define any number of network settings, but you can manage only seven at one time

Setting	Meaning		
Network drive	List of all connected network drives. The control shows the respective status of the network connections in the columns:		
	 Mount: Network drive connected / not connected 		
	 Auto: Network drive is to be connected automatically/manually 		
	 Type: Type of network connection. cifs and nfs are possible 		
	 Drive: Designation of the drive on the control 		
	 ID: Internal ID that identifies if a mount point has been used for more than one connection 		
	Server: Name of the server		
	Share: Name of the directory on the server that the control is to access		
	 User: User name with which the user logs on to the network 		
	Password: Network password protected or not		
	Query password?: Query / do not query password during connection		
	 Options: Display additional connection options 		
	To manage the network drives, use the screen buttons.		
	To add network drives, use the Add button: The control then starts the connec- tion wizard, which guides you by dialog through the required definitions		
Status log	Display of status information and error messages.		
	Press the Clear button to delete the contents of the Status Log window.		



			09:22
BO TNC:\ BO lost+		TNC:\nc_prog\PGM*.H;*.I;*.DXF	
Hount Setup	09	A 0 0 0	T
Network drive Mount Auto	Mount assi:	stant	8
MOURE AURO	Network	Drive - Define Name	
Mount Status log		Day a data was for the study correction. Sould be squared from water of the study correction. Dide study is the water of the study of t	Ease (forward)
OK		Acoly	Çancel
Çancel	Back	Estrand	Çance

16.13 Firewall

Application

You can set up a firewall for the primary network interface of the control. It can be configured so that incoming network traffic is blocked and/or a message is displayed, depending on the sender and the service. The firewall cannot be started for the second network interface of the control if it is active as the DHCP server.

Once the firewall has been activated, a symbol appears at the lower right in the taskbar. The symbol changes depending on the safety level that the firewall was activated with, and informs about the level of the safety settings:

lcon	Meaning
	Firewall protection does not yet exist although it has been activated accord- ing to the configuration. This can happen, for example, if PC names for which there are no equivalent IP addresses as yet were used in the configuration.
0	Firewall active with medium security level
🛡 🧵	Firewall active with high safety level. (All services except for the SSH are blocked)
6	Have your network specialist check and, if necessary, change the standard settings.
	The settings in the additional tab SSH settings are in preparation for future enhancements and currently have

Configuring the firewall

no function.

Make your firewall settings as follows:

 Use the mouse to open the task bar at the bottom edge of the screen

Further information: "Window manager", page 90

- Press the green HEIDENHAIN button to open the JH menu
- Select the Settings menu item
- Select the **Firewall** menu item.

HEIDENHAIN recommends activating the firewall with the prepared default settings:

- Set the Active option to enable the firewall
- Press the Set standard values button to activate the default settings recommended by HEIDENHAIN.
- Exit the dialog with the **OK** button.

Firewall settings

Option	Meaning				
Active	Switching the firewall on and off				
Interface:	Selection of the eth0 interface usually corresponds to X26 of the MC main computer. eth1 corresponds to X116. You can check this in the network settings in the Interfaces tab. On main computer units with two Ethernet interfaces, the DHCP server is active by default for the second (nonprimary) interface for the machine network. With this setting it is not possible to activate the firewall for eth1 because the firewall and the DHCP server exclude themselves mutually				
Report other inhib- ited packets:	Firewall active with high safety level. (All services except for the SSH are blocked)				
Inhibit ICMP echo answer:	If this option is set, the control no longer responds to a PING request				
Service	 This column contains the short names of the services that are configured with this dialog. For the configuration it is not important here whether the services themselves have been started LSV2 contains the functionality for TNCremo and Teleservice, as well as the HEIDENHAIN DNC interface (ports 19000 to 19010) SMB only refers to incoming SMB connections, i.e. if a Windows release is made on the NC. Outgoing SMB connections (i.e. if a Windows release is connected to the NC) cannot be prevented. SSH stands for the Secure Shell protocol (port 22). As of HEROS 504, LSV2 can be executed securely tunneled via this SSH protocol VNC protocol means access to the screen contents. If this service is 				
	screen contents. If this service is blocked, the screen content can no longer be accessed, not even with the TeleService programs from HEIDENHAIN (e.g. screenshot). If this service is blocked, the VNC configuration dialog shows a warning from HEROS that VNC is disabled in the firewall.				

Option	Meaning
Method	Under Method you can configure whether the service should not be available to anyone (Prohibit all), available to everyone (Permit all) or only available to some (Permit some). If you set Permit some you must also specify the computer (under Comput- er) that you wish to grant access to the respective service. If you do not specify any computer under Computer , the setting Prohibit all will automatically become active when the configuration is saved.
Log	If Log is activated, a red message is output if a network packet for this service has been blocked. A (blue) message is output if a network packet for this service was accept- ed
Computer	If the setting Permit some is selected under Method , the relevant computers can be specified here. The computers can be entered with their IP addresses or host names separated by commas. If a host name is used, the system checks upon closing or saving of the dialog whether the host name can be translated into an IP address. If this is not the case, an error message is displayed and the dialog does not terminate. If a valid host name is speci- fied, this host name is translated into an IP address each time the control is start- ed. If a computer that was entered with its name changes its IP address, you may have to restart the control or formally change the firewall configuration to ensure that the control uses the new IP address for a host name in the firewall.
Advanced options	These settings are only intended for your network specialists
Set standard values	Resets the settings to the default values recommended by HEIDENHAIN

16.14 Configuring the HR 550FS wireless handwheel

Application

i

Press the **SET UP WIRELESS HANDWHEEL** soft key to configure the HR 550FS wireless handwheel. The following functions are available:

- Assigning the handwheel to a specific handwheel holder
- Setting the transmission channel
- Analyzing the frequency spectrum for determining the optimum transmission channel
- Select transmitter power
- Statistical information on the transmission quality

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with Part 15 of the FCC Rules and with Industry Canada license-exempt RSS standard(s).

Operation is subject to the following two conditions:

- 1 this device may not cause harmful interference
- 2 this device must accept any interference received, including interference that may cause undesired operation

Assigning the handwheel to a specific handwheel holder

- Make sure that the handwheel holder is connected to the control hardware.
- Place the wireless handwheel you want to assign to the handwheel holder in the handwheel holder
- Press the MOD key to select the MOD function
- Select the Machine settings menu
- Select the configuration menu for the wireless handwheel: Press the SET UP WIRELESS HANDWHEEL soft key
- Click on the Connect HW button
- The control saves serial number of the inserted wireless handwheel and shows it in the configuration window on the left next to the **Connect HW** button.
- To save the configuration and exit the configuration menu, press the END button

roperties Frequency s	Jecoum				
Configuration			Statistics		
handwheel serial no.	0037478964	Connect HW	Data packets	12023	
Channel setting	Best channel	Select channel	Lost packets	0	0.00%
Channel in use	24		CRC error	0	0.00%
Transmitter power	Full power	Set power	Max. successive lost	0	
HW in charger	<i></i>				
Status					
HANDWHEEL ONL	INE Error of	ode			
	Stop HW	Start handwheel	End	1	

Setting the transmission channel

If the wireless handwheel is started automatically, then the control tries to select the transmission channel providing the best transmission signal. Proceed as follows if you want to set the radio channel yourself:

- Press the MOD key to select the MOD function
- Select the Machine settings menu
- Select the configuration menu for the wireless handwheel: Press the SET UP WIRELESS HANDWHEEL soft key
- Click the Frequency spectrum tab ►
- Click on the Stop HW button

The control stops the connection to the wireless handwheel and determines the current frequency spectrum for all 16 available channels.

- ► Memorize the number of the channel with the least amount of radio traffic (smallest bar)
- Click the Start handwheel button to reactivate the wireless ► handwheel
- Click the Properties tab

i

- Click on the Select channel button ► The controls shows all available channel numbers
- Click the number of the channel that the control has found to have the least amount of radio traffic
- To save the configuration and exit the configuration menu, press ► the END button

Selecting the transmitter power

A reduction in transmission power decreases the range of the wireless handwheel.

- Press the MOD key to select the MOD function
- Select the Machine settings menu
- Select the configuration menu for the wireless handwheel: Press the SET UP WIRELESS HANDWHEEL soft key
- Click on the Set power button

The control displays the three available power settings. Click on the desired setting.

To save the configuration and exit the configuration menu, press the END button

Configuratio Properties Frequence	v spectrur	n												
Configuration	, .,							Stat	tistics					
handwheel serial	10. 0037	478964				Conn	ect HW	Di	ata pac	kets	12	023		
Channel setting	Best	Best channel				Select	channel	Lo	ost pack	ets	0	0		0.00%
Channel in use	24							C	RC erro	и	0			0.00%
Transmitter power	Full p	ower				Set	ower	м	ax. suc	cessive los	t 0	0		
HW in charger														
Status														
HANDWHEEL O	NLINE			Error o	ode									
(Stop H					rt handw	heel	_		Er	ıd			
	of wi	reles	s har	idwhee.		rt handw	heel	_		Er	ıd			. 0
Properties Frequence Ch 11 1	of wi: y spectrur	reles	s har 15	idwhee 16		rt handw 18	iheel	20	21		23	24	25	26
Configuration Properties Frequenc Ch 11 1 0 dBm	of wi: y spectrur	reles:			1			20	21			24		
Properties Frequence Ch 11 1	of wi: y spectrur	reles:			1			20	21			24		
Properties Frequent Ch 11 12 0 dBm	of wi: y spectrur	reles:			1			20	21			24		
Properties Frequent Ch 11 12 0 dBm	of wi: y spectrur 2 13	reles:			1		19	20	21	22		24		
Properties Frequencies Ch 11 1. 0 dBm	of w1: y spectrur 2 13	n 14	15	16	1 17 -89	18	19			22	23		25	26
Properties Frequenc Ch 11 1: 0 dBm -50 dBm 100 dBm Act -89 -85	of w1: y spectrur 2 13	n 14	15	16	1 17 -89	18	19			22	23		25	26

Configuration			Statistics		
Configuration			Stausucs		
handwheel serial no.	0037478964	Connect HW	Data packets	12023	
Channel setting	Best channel	Select channel	Lost packets	0	0.00%
Channel in use	24		CRC error	0	0.00%
Transmitter power	Full power	Set power	Max. successive lost	0	
HW in charger	2				
Status					
HANDWHEEL ON	INE E	Error code			

Statistical data

To display the statistical data, proceed as follows:

- Press the MOD key to select the MOD function
- Select the Machine settings menu
- Select the configuration menu for the wireless handwheel: Press the SET UP WIRELESS HANDWHEEL soft key

The control displays the configuration menu with the statistical data.

Under **Statistics**, the control displays information about the transmission quality.

If the reception quality is poor so that a proper and safe stop of the axes cannot be ensured anymore, an emergency-stop reaction of the wireless handwheel is triggered.

The displayed value **Max. successive lost** indicates whether reception quality is poor. If the control repeatedly displays values greater than 2 during normal operation of the wireless handwheel within the desired range of use, then there is a high risk of an undesired disconnection. This can be corrected by increasing the transmitter power or by changing to another channel with less radio traffic.

If this occurs, try to improve the transmission quality by selecting another channel or by increasing the transmitter power.

 $\ensuremath{\textbf{Further information: "Setting the transmission channel", page 653$

Further information: "Selecting the transmitter power", page 653

Properties Frequency s	pectrum				
Configuration			Statistics		
handwheel serial no.	0037478964	Connect HW	Data packets	12023	
Channel setting	Best channel	Select channel	Lost packets	0	0.009
Channel in use	24		CRC error	0	0.009
Transmitter power	Full power	Set power	Max. successive lost	0	
HW in charger	a				
Status					
HANDWHEEL ONL	INE Error code				

16.15 Load machine configuration

Application

NOTICE

Caution: Data may be lost!

The **RESTORE** function irrevocably overwrites the current machine configuration with the backup files. The control does not perform an automatic backup before the **RESTORE** function. The files are thus permanently gone.

- Perform a backup of the current machine configuration prior to the **RESTORE** function
- Use the function only in consultation with the machine tool builder

Your machine tool builder can provide you a backup with a machine configuration. After entering the keyword **RESTORE**, you can load the backup on your machine or programming station. Proceed as follows to load the backup:

- Enter the keyword **RESTORE** in the MOD dialog
- Select the backup file in the control's file manager (e.g., BKUP-2013-12-12_.zip)

The control opens the pop-up window for the backup.

- Press Emergency Stop
- Press the OK soft key to start the backup process



Tables and Overviews

17.1 Machine-specific user parameters

Application

The parameter values are entered in the configuration editor.



Refer to your machine manual.

The machine tool builder can additionally make some machine-specific machine parameters available as user parameters, so that the user can configure the functions that are available.

The machine parameters are grouped as parameter objects in a tree structure in the configuration editor. Each parameter object has a name (e.g. **Settings for screen displays**) that gives information about the parameters it contains. A parameter object, also called "entity," is marked with an **E** in the folder symbol in the tree structure. Some machine parameters have a key name to identify them unambiguously. The key name assigns the parameter to a group (e.g. X for X axis). The respective group folder bears the key name and is marked by a **K** in the folder symbol.



Operating notes:

- The icons of not yet active parameters and objects appear dimmed. These can be activated with the MORE FUNCTIONS and INSERT soft key.
- The control saves a modification list of the last 20 changes to the configuration data. To restore modifications, select the corresponding line and press the MORE FUNCTIONS and CANCEL CHANGE soft keys.

Changing the display of the parameters

If you are in the configuration editor for the user parameters, you can change the display of the existing parameters. In the default setting, the parameters are displayed with short, explanatory texts.

Proceed as follows in order to have the actual system names of the parameters be shown:



Press the Screen layout key



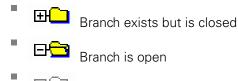
Press the SHOW SYSTEM NAME soft key

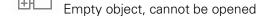
Follow the same procedure to return to the standard display.

Calling the configuration editor and changing parameters

- Select the **Programming** operating mode
- Press the MOD key
- Enter the code number 123
- Changing parameters
- Press the END soft key to exit the configuration editor
- Confirm changes with the SAVE soft key

The icon at the beginning of each line in the parameter tree shows additional information about this line. The icons have the following meanings:





- Initialized machine parameter
- Uninitialized (optional) machine parameter
- Can be read but not edited
 - 🔀 Can neither be read nor edited

The type of the configuration object is identified by its folder symbol:

- ∎ ⊞⊑⊐ List

ŒHE

Entity (parameter object)

Displaying help texts

The **HELP** key enables you to call a help text for each parameter object or attribute.

If the help text does not fit on one page (1/2 is then displayed at the upper right, for example), press the **HELP PAGE** soft key to scroll to the second page.

As well as the Help text, other information is displayed, e.g. unit of measurement, initial value, selection list. If the selected machine parameter matches a parameter in the previous control model, the corresponding MP number is displayed.

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Parameter list

Parameter settings

DisplaySettings

Settings for screen display

Sequence of displayed axes

[0] to [5]

Depends on available axes

Sequence of the displayed axes in the REF display

[0] to [5]

Depends on available axes

Type of position display in position window

NOMINAL ACTUAL REF ACTL REF NOML LAG ACTDST REFDST M 118

Type of position display in status display

NOMINAL ACTUAL REF ACTL REF NOML LAG ACTDST REFDST M 118

Definition of decimal separator for position display

. point

, comma

Display of feed rate in operating mode Manual operation

at axis key: Only display feed rate if axis direction key is pressed always minimum: Always display feed rate

Display of spindle position in the position display

during closed loop: Only display spindle position if spindle is in position control during closed loop and M5: Display spindle position if spindle is in position control and with M5

Show or hide soft key preset table

True: Soft key preset table is not displayed

False: Display soft key preset table

Font size with program display FONT_APPLICATION_SMALL FONT_APPLICATION_MEDIUM

Sequence of icons in the display

[0] to [9]

Depends on activated options

DisplaySettings

Display step for individual axes

List of all available axes

Display step for position display in mm or degrees

0.1 0.05 0.01 0.005 0.001 0.0005 0.0001

Display step for position display in inches

0.005 0.001 0.0005 0.0001

DisplaySettings

Definition of unit of measure valid for the display

metric: Use metric system

inch: Use inch system

DisplaySettings

Format of NC programs and display of cycles

Program input in HEIDENHAIN Klartext conversational text or in DIN/ISO

HEIDENHAIN: Program input in operating mode MDI in Klartext conversational text dialog

ISO: Program input in Positioning with MDI mode of operation in DIN/ISO

DisplaySettings

Setting the NC and PLC dialog language

NC dialog language ENGLISH GERMAN CZECH FRENCH ITALIAN **SPANISH** PORTUGUESE **SWEDISH** DANISH **FINNISH** DUTCH POLISH HUNGARIAN **RUSSIAN CHINESE** CHINESE_TRAD **SLOVENIAN KOREAN NORWEGIAN** ROMANIAN **SLOVAK** TURKISH

- PLC dialog language See NC dialog language
- PLC error message language See NC dialog language

Help language See NC dialog language

DisplaySettings

Behavior with control start-up

Acknowledge "Power interrupted" message

TRUE: Control start-up is not continued until the message has been acknowledged FALSE: "Power interrupted" message not displayed

DisplaySettings

Display mode for time display

Selection for display mode in the time display

Analog Digital Logo Analog and Logo Digital and Logo Analog on Logo Digital on Logo

DisplaySettings

Link row On/Off

Display setting for link row

OFF: Deactivate the information line in the operating mode line ON: Activate the information line in the operating mode line

DisplaySettings

Settings for 3-D display

Model type of 3-D display

3-D (compute-intensive): Model display for complex machining operations with undercuts2.5-D: Model display for 3-axis machining operations

No Model: Model display is disabled

Model quality of the 3-D display

very high: High resolution; Block end points can be displayed high: High resolution medium: Medium resolution low: Low resolution

Reset tool paths in new BLK form

ON: With new BLK form in the test run, the tool paths are reset OFF: With new BLK form in the test run, the tool paths are not reset

DisplaySettings

Settings for the position display

Position display

with TOOL CALL DL

As Tool Length: The programmed oversize DL is considered as the tool length modification for display of the workpiece-based position As Workpiece Oversize: The programmed oversize DL is considered as the workpiece oversize for display of the workpiece-based position

DisplaySettings

Settings for the table editor

Behavior when deleting tools from the pocket table

DISABLED: Deletion of the tool is not possible

WITH_WARNING: Deletion of the tool is possible, must be confirmed

WITHOUT_WARNING: Deletion of the tool is possible without needing to be confirmation

Behavior when deleting index entries of a tool

ALWAYS_ALLOWED: Deletion of index entries is always possible TOOL_RULES: The behavior depends on the setting of the parameter "Behavior when deleting tools from the pocket table"

Show the RÜCKS. SPALTE T soft key

TRUE: The soft key is shown and all tools can be deleted from the tool memory by the user FALSE: The soft key is not shown

DisplaySettings

Setting the coordinate systems for the display

Coordinate system for the datum shift

WorkplaneSystem: Datum is displayed in the system of the tilted plane, WPL-CS WorkpieceSystem: Datum is displayed in the workpiece coordinate system, W-CS

ProbeSettings

Configuration of tool measurement

TT140_1

M function for spindle orientation

- -1: Spindle orientation directly by NC
- 0: Function inactive
- 1 to 999: Number of M function for spindle orientation

Probing routine

MultiDirections: Probing from several directions SingleDirection: Probing from one direction

Probing direction for tool radius measurement

X_Positive, Y_Positive, X_Negative, Y_Negative, Z_Positive, Z_Negative (depending on tool axis)

Distance between lower surface of tool and upper surface of stylus 0.001 to 99.9999 [mm]: Offset between stylus to tool

Rapid traverse in probing cycle

10 to 300 000 [mm/min]: Rapid traverse in probing cycle

Probing feed rate with tool measurement

1 to 3 000 [mm/min]: Probing feed rate with tool measurement

Calculation of probing feed rate

ConstantTolerance: Calculation of probing feed rate with constant tolerance VariableTolerance: Calculation of probing feed rate with variable tolerance ConstantFeed: Constant probing feed rate

Type of speed detection

Automatic: Determine speed automatically MinSpindleSpeed: Use minimum spindle speed

Maximum permissible rotational speed the tool tip

1 to 129 [m/min]: Permissible rotational speed on cutter circumference

Maximum permissible speed with tool measurement

0 to 1 000 [rpm]: Maximum permissible speed

Maximum permissible measuring error with tool measurement 0.001 to 0.999 [mm]: First maximum permissible measuring error

Maximum permissible measuring error with tool measurement 0.001 to 0.999 [mm]: Second maximum permissible measuring error

NC stop during tool check

True: NC program is stopped if breakage tolerance is exceeded

False: NC program is not stopped

NC stop during tool measurement

True: NC program is stopped if breakage tolerance is exceeded False: NC program is not stopped

Modifying of tool table during tool check and measurement

AdaptOnMeasure: Table is modified after tool measurement AdaptOnBoth: Table is modified after tool check and measurement AdaptNever: Table is not modified after tool check and measurement

Configuration of a round stylus

TT140_1

Coordinates of the stylus center

[0]: X coordinate of stylus center referenced to machine datum

[1]: Y coordinate of stylus center referenced to machine datum

[2]: Z coordinate of stylus center referenced to machine datum

Safety clearance over stylus for pre-positioning

0.001 to 99 999.9999 [mm]: Safety clearance in tool axis direction

Safety zone around stylus for pre-positioning

0.001 to 99 999.9999 [mm]: Safety clearance in plane perpendicular to tool axis

ChannelSettings

CH_NC

Active kinematics

Kinematics to be activated

List of machine kinematics

Kinematics to be activated with control start-up List of machine kinematics

Determining the behavior of the NC program

Resetting the machining time with program start

True: Machining time is reset False: Machining time is not reset

PLC signal for number of pending machining cycle Dependent on machine manufacturer

Geometry tolerances

Permissible deviation of circle radius

0.0001 to 0.016 [mm]: Permissible deviation of circle radius on the circle end point compared to circle start point

Permissible error in successive threads

Configuration of machining cycles

Overlap factor for pocket milling

0.001 to 1.414: Overlap factor for Cycle 4 POCKET MILLING and Cycle 5 CIRCU-LAR POCKET

Behavior after machining a contour pocket

PosBeforeMachining: Position as before machining a cycle ToolAxClearanceHeight: Position tool axis to clearance height

Display Spindle ? error message if M3/M4 is not active

- on: Output error message off: Do not output error message
- Display Enter negative depth error message on: Output error message off: Do not output error message

Approach behavior on a slot wall in a cylindrical surface

LineNormal: Approach with straight line CircleTangential: Approach with an arc movement

M function for spindle orientation in machining cycles

-1: Spindle orientation directly via NC

0: Function inactive

1 to 999: Number of M function for spindle orientation

Do not display "Plunging type not possible error message

on: Error message is not displayed

off: Error message is displayed

Behavior of M7 and M8 with cycles 202 and 204

TRUE: At the end of cycle 202 and 204 the condition of M7 and M8 is restored before the cycle call FALSE: At the end of cycle 202 and 204 the condition of M7 and M8 is not restored independently

Do not show **Remaining material** warning on: Warning is not displayed off: Warning is displayed

Geometry filter for filtering out linear elements

Type of stretch filter

- Off: No filter active

- ShortCut: Leave out single points on polygon

- Average: The geometry filter smooths corners

Maximum distance of filtered to unfiltered contour

0 to 10 [mm]: The filtered out points lie within this tolerance to the resultant distance

Maximum length of distance resulting from filtering

0 to 1000 [mm]: Length over which geometry filtering is effective

CfgThreadSpindle

Potentiometer for feed rate during thread cutting

SpindlePotentiometer: During thread cutting, the potentiometer for shaft speed override is effective. The potentiometer for feed rate override is not active

FeedPotentiometer: During thread cutting, the potentiometer for feed rate override is effective. The potentiometer for shaft speed override is not active

Waiting time at reversal point in thread base

Advanced switching time of spindle

Limitation of spindle speed for Cycles 17, 207, and 18 TRUE: For small thread depths the spindles speed is limited to the extent that for about 1/3 of the time it runs at a constant speed FALSE: No limitation of the spindle speed

Settings for the NC editor

Creating backup files

TRUE: Create backup file after editing NC programs FALSE: Create no backup file after editing NC programs

Cursor behavior after deleting lines

TRUE: Cursor is on previous line after deletion (iTNC behavior) FALSE: Cursor is on subsequent line after deletion

Cursor behavior with the first and last line

TRUE: All-round cursors permitted at PGM beginning/end FALSE: All-round cursors not permitted at PGM beginning/end

Line break with multi-line blocks

ALL: Always show lines completely ACT: Only show lines of the active block completely NO: Only show lines completely if the block is edited

Activate help graphics with cycle input

TRUE: Fundamentally always show help graphics during input FALSE: Only show help graphics if the CYCLE HELP soft key is set to ON. The CYCLE HELP OFF/ON soft key is displayed in the Programming mode after pressing the "Screen layout" button

Behavior of soft key row following a cycle input

TRUE: Leave cycle soft key row active after a cycle definition FALSE: Hide cycle soft key row after a cycle definition

Confirmation request before block is deleted

TRUE: Display confirmation request before deleting an NC block FALSE: Do not display confirmation request before deleting an NC block

Line number up to which NC program is tested

100 to 50000: Program length for which the geometry is to be checked

ISO programming: Block number increment

0 to 250: Increment for generating ISO blocks in the program

Define programmable axes

TRUE: Use defined axis configuration FALSE: Use default axis configuration XYZABCUVW

Behavior with paraxial positioning blocks

TRUE: Paraxial positioning blocks permitted FALSE: Paraxial positioning blocks locked

Line number up to which identical syntax elements are searched for 500 to 50000: Search for selected elements with up/down arrow keys

Behavior of PARAXMODE function with UVW axes

FALSE: PARAXMODE function permitted TRUE: PARAXMODE function locked

Settings for the file manager

Display of dependent files

MANUAL: Dependent files are displayed AUTOMATIC: Dependent files are not displayed

Path specifications for end users

List with drives and/or directories Drives and directories entered here are shown by the control in the file manager

- FN 16 output path for execution Path for FN 16 output if no path has been defined in the program
- FN 16 output path for Programming and Test Run operating modes Path for FN 16 output if no path has been defined in the program

Serial Interface RS232 **Further information:** "Setting up data interfaces", page 637

17.2 Connector pin layout and connection cables for data interfaces

RS-232-C/V.24 interface for HEIDENHAIN devices

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The interface complies with the requirements of EN 50 178 for **Low voltage electrical separation**.

When using the 25-pin adapter block:

Control		Conn. c	able 365725	-ХХ	Adapter 310085-		Conn. o	able 274545-	xx
Male	Assign- ment	Female	Color	Female	Male	Female	Male	Color	Female
1	Do not assign	1		1	1	1	1	White/ Brown	1
2	RXD	2	Yellow	3	3	3	3	Yellow	2
3	TXD	3	Green	2	2	2	2	Green	3
4	DTR	4	Brown	20	20	20	20	Brown	8
5	Signal GND	5	Red	7	7	7	7	Red	7
6	DSR	6	Blue	6	6	6	6		6
7	RTS	7	Gray	4	4	4	4	Gray	5
8	CTR	8	Pink	5	5	5	5	Pink	4
9	Do not assign	9					8	Violet	20
Hsg.	External shield	Hsg.	External shield	Hsg.	Hsg.	Hsg.	Hsg.	External shield	Hsg.

When using the 9-pin adapter block:

Control		Conn. c	Conn. cable 355484-xx			Adapter block 363987-02		Conn. cable 366964-xx		
Male	Assign- ment	Female	Color	Male	Female	Male	Female	Color	Female	
1	Do not assign	1	Red	1	1	1	1	Red	1	
2	RXD	2	Yellow	2	2	2	2	Yellow	3	
3	TXD	3	White	3	3	3	3	White	2	
4	DTR	4	Brown	4	4	4	4	Brown	6	
5	Signal GND	5	Black	5	5	5	5	Black	5	
6	DSR	6	Violet	6	6	6	6	Violet	4	
7	RTS	7	Gray	7	7	7	7	Gray	8	
8	CTR	8	White/ Green	8	8	8	8	White/ Green	7	
9	Do not assign	9	Green	9	9	9	9	Green	9	
Hsg.	External shield	Hsg.	External shield	Hsg.	Hsg.	Hsg.	Hsg.	External shield	Hsg.	

Non-HEIDENHAIN devices

The connector layout of a non-HEIDENHAIN device may substantially differ from that of a HEIDENHAIN device.

It depends on the unit and the type of data transfer. The table below shows the connector pin layout on the adapter block.

Adapter block	363987-02	Conn. cable 3	Conn. cable 366964-xx					
Female	Male	Female	Color	Female				
1	1	1	Red	1				
2	2	2	Yellow	3				
3	3	3	White	2				
4	4	4	Brown	6				
5	5	5	Black	5				
6	6	6	Violet	4				
7	7	7	Gray	8				
8	8	8	White/Green	7				
9	9	9	Green	9				
Hsg.	Hsg.	Hsg.	External shield	Hsg.				

Ethernet interface RJ45 socket

Maximum cable length:

- Unshielded: 100 m
- Shielded: 400 m

Pin	Signal	Description
1	TX+	Transmit Data
2	TX–	Transmit Data
3	REC+	Receive Data
4	Vacant	
5	Vacant	
6	REC-	Receive Data
7	Vacant	
8	Vacant	

17.3 Technical Information

Explanation of symbols

- Default
- Axis option
- 1 Advanced Function Set 1

Specifications		
Components		Operating panel
		TFT color flat-panel display with soft keys
Program memory		2 GB
Input resolution and display step	-	As fine as 0.1 µm for linear axes
		Up to 0.0001° for rotary axes
Input range		Maximum 999 999 999 mm or 999 999 999°
Interpolation		Linear in 4 axes
		Circular in 2 axes
		Helical: superimposition of circular and straight paths
Block processing time 3-D straight line without radius compensation	•	6 ms
Axis feedback control		Position loop resolution: Signal period of the position encoder/1024
		Cycle time of position controller: 3 ms
	-	Cycle time of speed controller: 200 µs
Range of traverse		Maximum 100 m (3937 inches)
Spindle speed		Maximum 100,000 rpm (analog speed command signal)
Error compensation	-	Linear and nonlinear axis error, backlash, reversal peaks during circular movements, thermal expansion
		Static friction
Data interfaces		One each RS-232-C /V.24 max. 115 kilobaud
		Expanded data interface with LSV-2 protocol for remote operation of the control through the data interface with the HEIDENHAIN software TNCremo
		Ethernet interface 1000 BaseT
	-	3 x USB (1 x front USB 2.0; 2 x rear USB 3.0)
Ambient temperature		Operation: 5 °C to +40 °C
		Storage: -20 °C to +60 °C

Input formats and units of control functions	
Positions, coordinates, circle radii, chamfer lengths	–99 999.9999 to +99 999.9999 (5,4: number of digits before and after the decimal point) [mm]
Tool numbers	0 to 32 767.9 (5, 1)
Tool names	32 characters, enclosed by quotation marks with T . Permit- ted special characters: # \$ % & . ,
Detail values for tool compensation	–99.9999 to +99.9999 (2, 4) [mm]
Spindle speeds	0 to 99 999.999 (5, 3) [rpm]
Feed rates	0 to 99,999.999 (5, 3) [mm/min] or [mm/tooth] or [mm/1]
Dwell time in Cycle 9	0 to 3600.000 (4, 3) [s]
Thread pitch in various cycles	-9.9999 to +9.9999 (2, 4) [mm]
Angle for spindle orientation	0 to 360.0000 (3, 4) [°]
Angle for polar coordinates, rotation, tilting the working plane	-360.0000 to 360.0000 (3, 4) [°]
Polar coordination for screw line interpolation (CP)	–5 400.0000 to 5 400.0000 (4, 4) [°]
Datum numbers in Cycle 7	0 to 2999 (4, 0)
Scaling factor in Cycles 11 and 26	0.000001 to 99.999999 (2, 6)
Miscellaneous functions M	0 to 999 (4, 0)
Q parameter numbers	0 to 1999 (4, 0)
Q parameter values	-99 999.9999 to +99 999.9999 (9, 6)
Labels (LBL) for program jumps	0 to 999 (5, 0)
Labels (LBL) for program jumps	Any text string in quotation marks ("")
Number of program section repeats REP	1 to 65 534 (5, 0)
Error number in Q parameter function FN14	0 to 1199 (4, 0)

User functions

Heav functions	
User functions	
Short description	 Basic version: 3 axes plus closed-loop spindle
	 Fourth NC axis plus auxiliary axis
	or
	Additional axis for 4 axes plus closed-loop spindle
	Additional axis for 5 axes plus closed-loop spindle
Program entry	In HEIDENHAIN conversational format and DIN/ISO
Position entry	 Nominal positions for lines and arcs in Cartesian coordinates or polar coordinates
	Incremental or absolute dimensions
	 Display and entry in mm or inches
Tool compensation	Tool radius in the working plane and tool length
	 Radius compensated contour look ahead for up to 99 blocks (M120)

User functions		
Tool tables	Mu	Itiple tool tables with any number of tools
Constant contour speed		With respect to the path of the tool center
constant contour speed	÷.	With respect to the cutting edge
Parallel operation		ating a program with graphical support while another program is being run
· · ·	1	Programming of cylindrical contours as if in two axes
Rotary table machining (Advanced Function Set 1)		Frogramming of cylindrical contours as in in two axes
	1	Feed rate in distance per minute
Contour elements		Straight line
		Chamfer
		Circular path
		Circle center
		Circle radius
		Tangentially connected arc
		Rounded corners
Approaching and departing		Via straight line: tangential or perpendicular
the contour		Via circular arc
FK free contour programming	-	FK free contour programming in HEIDENHAIN conversational format with graphic support for workpiece drawings not dimensioned for NC
Program jumps		Subprograms
		Program section repeat
		Any desired program as subprogram
Machining cycles		Cycles for drilling, and conventional and rigid tapping
		Roughing of rectangular and circular pockets
		Cycles for pecking, reaming, boring, and counterboring
		Cycles for milling internal and external threads
		Finishing of rectangular and circular pockets
		Cycles for clearing level and inclined surfaces
		Cycles for milling linear and circular slots
		Cartesian and polar point patterns
		Contour-parallel contour pocket
		Contour train
	-	OEM cycles (special cycles developed by the machine manufacturer) can also be integrated
Coordinate transformation		Datum shift, rotation, mirroring
		Scaling factor (axis-specific)
	1	Tilting the working plane (Advanced Function Set 1)
Q parameters		Mathematical functions: =, +, -, *, sin α , cos α , root
Programming with variables		Logical operations (=, \neq , <, >)
	-	Calculating with parentheses

User functions

	tan α , arc sin, arc cos, arc tan, a ⁿ , e ⁿ , In, log, absolute value of a number, constant π , negation, truncation of digits before or after the decimal point
	Functions for calculation of circles
	String parameters
Programming aids	Calculator
	Color highlighting of syntax elements
	Complete list of all current error messages
	Context-sensitive help function for error messages
	Graphic support for the programming of cycles
	Comment blocks in NC program
Teach-In	Actual positions can be transferred directly to the NC program
Test graphics Display modes	Graphical simulation before a program run, also while another program is being run
	Plan view / projection in 3 planes / 3-D view / 3-D line graphic
	Detail enlargement
Programming graphics	In Programming mode, the contour of the NC blocks is drawn on screen while they are being entered (2-D pencil-trace graphics), even if another program is running
Program-run graphics Display modes	Graphic simulation of real-time machining in plan view / projection in 3 planes / 3-D view
Machining time	Calculation of machining time in the Test Run operating mode
	Display of the current machining time in the Program Run operating modes
Contour, returning to	Block scan in any block in the program, returning the tool to the calculated nominal position to continue machining
	Program interruption, contour departure and return
Datum tables	Multiple datum tables for storing workpiece-specific datums
Touch probe cycles	Calibrating the touch probe
	Compensation of workpiece misalignment, manual or automatic
	Presetting, manual or automatic
	Automatically measuring workpieces
	Cycles for automatic tool measurement

Software options

Advanced Function Set 1 (option 8	3)
Expanded functions Group 1	 Machining with rotary tables Cylindrical contours as if in two axes Feed rate in distance per minute Coordinate conversions: Tilting the working plane
HEIDENHAIN DNC (option 18)	
	Communication with external PC applications over COM component
CAD Import (option 42)	
CAD import	 Support for DXF, STEP and IGES Adoption of contours and point patterns Simple and convenient specification of presets Selecting graphical features of contour sections from conversational programs
Extended Tool Management (optio	on 93)
Extended tool management	Python-based
Remote Desktop Manager (option	133)
Remote operation of external computer units	Windows on a separate computer unitIncorporated in the control's interface

Accessories

Accessories		
Electronic handwheels	-	HR 410: Portable handwheel
	-	HR 550FS: Portable wireless handwheel with display
	-	HR 520: Portable handwheel with display
		HR 420: Portable handwheel with display
	-	HR 130: Panel-mounted handwheel
		HR 150: Up to three panel-mounted handwheels via handwheel adapter HRA 110
Touch probes	-	TS 248: 3-D touch trigger probe with cable connection
	-	TS 260: 3-D touch trigger probe with cable connection
	-	TS 444: Battery-free 3-D touch trigger probe with infrared transmission
	-	TS 460: 3-D touch trigger probe with infrared and radio transmission
	-	TS 642: 3-D touch trigger probe with infrared transmission
		TS 740: High-precision 3-D touch trigger probe with infrared transmis- sion
	-	TT 160: 3-D touch trigger probe for tool measurement
		TT 460: 3-D touch trigger probe for tool measurement with infrared transmission

17.4 Overview tables

Fixed cycles

Cycle number	Cycle name	DEF active	CALL active
7	DATUM SHIFT		
8	MIRROR IMAGE		
9	DWELL TIME		
10	ROTATION		
11	SCALING		
12	PGM CALL		
13	ORIENTATION		
14	CONTOUR GEOMETRY		
18	THREAD CUTTING		
19	WORKING PLANE		
20	CONTOUR DATA		
21	PILOT DRILLING		
22	ROUGH-OUT		
23	FLOOR FINISHING		
24	SIDE FINISHING		
25	CONTOUR TRAIN		
26	AXIS-SPECIFIC SCALING		
27	CYLINDER SURFACE		
28	CYLINDER SURFACE		
29	CYL SURFACE RIDGE		
32	TOLERANCE		
39	CYL. SURFACE CONTOUR		
200	DRILLING		
201	REAMING		
202	BORING		
203	UNIVERSAL DRILLING		
204	BACK BORING		
205	UNIVERSAL PECKING		
206	TAPPING		
207	RIGID TAPPING		
208	BORE MILLING		
209	TAPPING W/ CHIP BRKG		
220	POLAR PATTERN		
221	CARTESIAN PATTERN		

Cycle number	Cycle name	DEF active	CALL active
225	ENGRAVING		
232	FACE MILLING		
233	FACE MILLING		
240	CENTERING		
241	SINGLE-LIP D.H.DRLNG		
247	PRESETTING		
251	RECTANGULAR POCKET		
252	CIRCULAR POCKET		
253	SLOT MILLING		
254	CIRCULAR SLOT		
256	RECTANGULAR STUD		
257	CIRCULAR STUD		
258	POLYGON STUD		
262	THREAD MILLING		
263	THREAD MLLNG/CNTSNKG		
264	THREAD DRILLNG/MLLNG		
265	HEL. THREAD DRLG/MLG		
267	OUTSIDE THREAD MLLNG		
270	CONTOUR TRAIN DATA		
275	TROCHOIDAL SLOT		
276	THREE-D CONT. TRAIN		

Miscellaneous functions

М	Effect Effect	ve at block	Start	End	Page
M0	Program STOP/Spindle STOP/Coolant OFF				428
M1	Optional program run STOP/Spindle STOP/Coolant OFF				621
M2	Stop program/Spindle STOP/Coolant OFF/ CLEAR status displing on machine parameter)/Return jump to block 1	ay (depend-		-	428
M3	Spindle ON clockwise		-		428
M4 M5	Spindle ON counterclockwise Spindle STOP				
M6	Tool change/STOP program run (depending on machine param ter)/Spindle STOP	e-		-	428
M8 M9	Coolant ON Coolant OFF		•		428
M13	Spindle ON clockwise/Coolant ON				428
M14	Spindle ON counterclockwise/Coolant on				
M30	Same function as M2				428

М	Effect Effective at bloc	k Start	End	Page
M89	Vacant miscellaneous function or cycle call, modally effective (depending on machine parameter)		-	Cycles Manual
M91	Within the positioning block: Coordinates are referenced to machine datum	-		429
M92	Within the positioning block: Coordinates are referenced to a position defined by machine manufacturer, e.g. tool change position	-		429
M94	Reduce the rotary axis display to a value below 360°	-		509
M97	Machine small contour steps			432
M98	Machine open contours completely			433
M99	Blockwise cycle call		•	Cycles Manual
M101	Automatic tool change with replacement tool if maximum tool life has expired		•	224
M102	Reset M101			
M107 M108	Suppress error message for replacement tools with oversize Reset M107			224
M109	Constant contouring speed at cutting edge (feed rate increase andreduc- tion)			436
M110 M111	Constant contouring speed at cutting edge (only feed rate reduction) Reset M109/M110	•		
M116 M117	Feed rate in mm/min on rotary axes Reset M116	•		507
M118	Superimpose handwheel positioning during program run	-		439
M120	Pre-calculate the radius-compensated contour (LOOK AHEAD)			437
M126 M127	Shorter-path traverse of rotary axes Reset M126	-		508
M130	Within the positioning block: Points are referenced to the untilted coordinate system			431
M136 M137	Feed rate F in millimeters per spindle revolution Reset M136			435
M138	Selection of tilted axes			510
M140	Retraction from the contour in the tool-axis direction			441
M143	Delete basic rotation			444
M141	Suppress touch probe monitoring			443
M148 M149	Automatically retract tool from the contour at an NC stop Reset M148	•		445

17.5 Functions of the TNC 320 and the iTNC 530 compared

Comparison: Specifications

Function	TNC 320	iTNC 530
Control loops	Maximum 8 control loops (including up to 2 spindles)	18 maximum
Input resolution and display step:		
Linear axes	■ 0.1µm	■ 0.1 µm
Rotary axes	■ 0.001°	■ 0.0001°
Display	15.1-inch TFT color flat-panel display	19-inch TFT color flat-panel display or 15.1-inch TFT color flat-panel display
Memory media for NC, PLC programs, and system files	CompactFlash memory card	Hard disk or SSDR solid state disk
Program memory for NC programs	2 GB	> 21 GB
Block processing time	6 ms	0.5 ms
Interpolation:		
Straight line	5 axes	5 axes
Circle	3 axes	3 axes
Helix	yes	Yes
Spline	No	Yes with option S
Hardware	Compact in operating panel	Modular in electrical cabinet

Comparison: Data Interfaces

Function	TNC 320	iTNC 530
Gigabit-Ethernet 1000Base-T	Х	Х
RS-232-C/V.24 serial interface	Х	Х
RS-422/V.11 serial interface	-	Х
USB interface	Х	Х

Further information: "Setting up data interfaces", page 637

Comparison: PC software

Function	TNC 320	iTN	C 530
ConfigDesign for the configuration of machine parameters	Available	Not available	
TNCanalyzer for the analysis and evaluation of service files	Available	Not available	
Comparison: User functions			
Function		TNC 320	iTNC 530
Program entry			
 Klartext 		• X	■ X
DIN/ISO		• X	■ X
smarT.NC			■ X
 ASCII editor 		 X, directly editable 	 X, editable after conversion
Position entry			
 Nominal positions for lines and arcs in Carr coordinates 	tesian	■ X	= X
 Nominal positions for lines and arcs in pola coordinates 	ar	■ X	■ X
Incremental or absolute dimensions		• X	■ X
Display and entry in mm or inches		■ X	■ X
Set the last tool position as pole (empty Collection)	C block)	 X (error message if pole transfer is ambiguous) 	= X
Spline sets (SPL)			 X, with option 9

Function	TNC 320	iTNC 530
Tool compensation		
In the working plane and tool length	■ X	• X
 Radius compensated contour look ahead for up to 99 blocks 	■ X	= X
Three-Dimensional Tool Radius Compensation		X, with option 9
Tool table		
 Central storage of tool data 	• X	• X
 Multiple tool tables with any number of tools 	■ X	• X
 Flexible management of tool types 	■ X	I -
 Filtered display of selectable tools 	■ X	
 Sorting function 	■ X	1 -
Column names	Sometimes with _	Sometimes with -
 Copy function: Overwriting relevant tool data 	■ X	• X
Form view	 Switchover with Screen Layout key 	 Switchover by soft key
 Exchange of tool table between TNC 320 and iTNC 530 	• X	 Not possible
Touch probe table for managing different 3-D touch probes	Х	-
Creating tool-usage file, checking the availability	Х	Х
Cutting data calculator : Automatic calculation of spindle speed and feed rate	Simple cutting data calculator	Using stored technology tables
Define any tables	 Freely definable tables (.TAB files) Reading and writing with FN functions Definable via config. data The names of tables and table columns must start with a letter, and no arithmetic operators are permitted Reading and writing with SQL functions 	 Freely definable tables (.TAB files) Reading and writing with FN functions

Function	TNC 320	iTNC 530
Constant contouring speed relative to the path of the tool center or relative to the tool's cutting edge	Х	Х
Parallel operation : Creating programs while another program is being run	Х	Х
Programming of counter axes	Х	Х
Tilting the working plane (Cycle 19, PLANE function)	X, option 8	X, option 8
Machining with a rotary table:		
 Programming of cylindrical contours as if in two axes 		
 Cylindrical surface (Cycle 27) 	X, option 8	X, option 8
 Cylinder surface, slot (Cycle 28) 	X, option 8	X, option 8
 Cylinder surface, ridge (Cycle 29) 	X, option 8	X, option 8
 Cylinder surface, external contour (Cycle 39) 	X, option 8	X, option 8
Feed rate in mm/min or rev/min	X, option 8	X, option 8
Traverse in tool-axis direction		
 Manual operation (3-D ROT menu) 	X	 X, FCL2 function
 During program interruption 	X	X
With handwheel superimpositioning	■ X	X, option 44
Approaching and departing the contour: Via a straight line or arc	Х	Х
Entry of feed rates:		
F (mm/min), rapid traverse FMAX	■ X	X
FU (feed per revolution mm/1)		■ X
FZ (tooth feed rate)		X
FT (time in seconds for path)		■ X
 FMAXT (only for active rapid traverse potentiometer: time in seconds for path) 	-	■ X
FK free contour programming		
 Programming for workpiece drawings not dimensioned for NC programming 	• X	• X
 Conversion of FK program to Klartext conversational language 	-	■ X
Program jumps:		
 Maximum number of labels 	65535	1000
Subprograms	• X	X
Nesting depth for subprograms	2 0	6
 Program section repetitions 	X	X
Any desired program as subroutine	■ X	■ X

Function	TNC 320	iTNC 530
Q parameter programming:		
Standard mathematical functions	= X	• X
Formula entry	= X	• X
String processing	X	• X
Local Q parameters QL	X	• X
Nonvolatile Q parameters QR	X	• X
 Changing parameters during program interruption 	X	• X
D15: PRINT		• X
D25: PRESET		• X
D26: TABOPEN	X	• X
D27: TABWRITE	X	• X
D28: TABREAD	• X	• X
D29: PLC LIST	• X	
D31: RANGE SELECT		■ X
D32: PLC PRESET		■ X
D37: EXPORT	X	
D38: SEND	X	• X
Save a file externally with D16	X	• X
 D16 formatting: Left-aligned, right-aligned, string lengths 	■ X	= X
Write to LOG file with D16	X	
 Displaying parameter contents in the additional status display 	X	• -
 Displaying parameter contents during programming (Q-INFO) 	■ X	= X
SQL functions for writing and reading tables	• X	I -

Function	TNC 320	iTNC 530
Graphic support		
2-D programming graphics	X	■ X
REDRAW function (REDRAW)		X
Show grid lines as the background	X	
 3-D line graphics 	X	■ X
 Test graphics (plan view, projection on 3 planes, 3-D view) 	■ X	= X
 High-resolution view 	■ X	X
Tool display	X	■ X
 Adjusting the simulation speed 	X	■ X
 Coordinates of line intersection for projection in 3 planes 		■ X
 Expanded zoom functions (mouse operation) 	X	X
 Displaying frame for workpiece blank 	X	X
 Displaying the depth value in plan view during mouse-over 	= X	■ X
 Deliberately stop test run (STOP AT) 	X	X
 Factor in tool change macro 	 X (differing to actual execut 	
 Program run graphics (plan view, projection in 3 planes, 3-D view) 	■ X	E X
 High-resolution view 	X	X

Function	TNC 320	iTNC 530
Datum tables: Storing workpiece-specific datums	Х	Х
Preset table		
Preset management	X	X
Line 0 of the preset table can be edited manually	• X	
Pallet management		
Support of pallet files		X
Tool-oriented machining		■ X
 Management of presets for a pallet in a table 		X
Returning to the contour		
With mid-program startup	• X	■ X
After program interruption	■ X	■ X
Auto-start function	Х	Х
Teach-in: Actual positions can be transferred to an NC program	Х	X
Enhanced file management		
 Creating multiple directories and subdirectories 	X	X
 Sorting function 	X	X
Mouse operation	X	X
Selection of target directory by soft key	X	■ X
Programming aids:		
Help graphics for cycle programming	X	X
Animated help graphics when PLANE/PATTERN DEF function is selected	= X	= X
Help graphics for PLANE/PATTERN DEF	X	X
 Context-sensitive help function for error messages 	X	X
TNCguide, browser-based help system	X	■ X
Context-sensitive call of help system	X	■ X
 Color highlighting of syntax elements 	X	H -
Calculator	 X (scientific) 	X (standard)
Comment blocks in NC program	X	X
Convert NC blocks to comments	X	
Structure blocks in NC program	X	X
Structure view in test run		■ X
Dynamic Collision Monitoring (DCM):		
 Collision monitoring in Automatic operation 	-	X, option 40
 Collision monitoring in Manual operation 	-	X, option 40
 Graphic depiction of the defined collision objects 	-	X, option 40
 Collision checking in test run 		X, option 40
 Fixture monitoring 	-	X, option 40
Tool carrier management	• X	X, option 40

Function	TNC 320	iTNC 530
CAM support:		
Loading of contours from DXF data	X, option 42	X, option 42
Load contours from Step data and Iges data	X, option 42	
 Loading of machining positions from DXF data 	X, option 42	X, option 42
Load machining positions from Step data and Iges data	X, option 42	
 Offline filter for CAM files 		■ X
Stretch filter	X	
MOD functions:		
User parameters	 Config data 	 Numerical structure
 OEM help files with service functions 		X
Data medium inspection		= X
Load service packs		■ X
Setting the system time	■ X	■ X
 Specify the axes for actual position capture 		X
 Definition of traverse range limits 	■ X	■ X
 Restricting external access 	■ X	■ X
Configure counter	■ X	
Switching the kinematics	■ X	■ X
Calling fixed cycles:		
With M99 or M89	■ X	X
With CYCL CALL	■ X	X
With CYCL CALL PAT	■ X	X
With CYC CALL POS	■ X	■ X
Special functions:		
 Create reverse program 		X
Adaptive Feed Control AFC		X, option 45
Define the counter with FUNCTION COUNT	• X	
Define the dwell time with FUNCTION FEED	■ X	
Define the dwell time with FUNCTION DWELL	X	
Defining cycle parameters globally with GLOBAL DEF	■ X	X
Pattern definition with PATTERN DEF	■ X	■ X
 Definition and processing of point tables 	X	X
Simple contour formula CONTOUR DEF	■ X	■ X
Functions for large molds and dies:		
 Global program settings (GS) 		X, option 44
Expanded M128: FUNCTION TCPM		X

TNC 320	iTNC 530	
■ X	■ X	
X	■ X	
X	■ X	
X	■ X	
■ X	■ X	
■ X	• -	
X	■ X	
-	X	
_	Х	
	 X X X X X X X X 	 X X<

Comparison: Miscellaneous functions

Μ	Effect	TNC 320	iTNC 530
M00	Program STOP/Spindle STOP/Coolant OFF	Х	Х
M01	Optional program STOP	Х	Х
M02	Stop program/Spindle STOP/Coolant OFF/ Clear status display (depending on machine parameter)/Return jump to block 1	Х	Х
M03 M04 M05	Spindle ON clockwise Spindle ON counterclockwise Spindle STOP	Х	Х
M06	Tool change/Program run STOP (machine-specific function)/ Spindle STOP	Х	Х
M08 M09	Coolant ON Coolant OFF	Х	Х
M13 M14	Spindle ON clockwise/Coolant ON Spindle ON counterclockwise/Coolant on	Х	Х
M30	Same function as M02	Х	Х
M89	Free miscellaneous function or cycle call, modally effective (machine-specific function)	Х	Х
M90	Constant contouring speed at corners (not required at TNC 320)	-	Х
M91	Within the positioning block: Coordinates are referenced to machine datum	Х	Х
M92	Within the positioning block: Coordinates are referenced to a position defined by machine manufacturer, e.g. tool change position	Х	Х
M94	Reduce the rotary axis display to a value below 360°	Х	Х
/ 197	Machine small contour steps	Х	Х
M98	Machine open contours completely	Х	Х
M99	Blockwise cycle call	Х	Х
M101 M102	Automatic tool change with replacement tool if maximum tool life has expired Reset M101	Х	Х
M103	Reduce feed rate during plunging to factor F (percentage)	Х	Х
M104	Reactivate most recently set preset	– (recommended: Cycle 247)	Х
M105 M106	Machining with second k _v factor Machining with first k _v factor	-	Х
M107 M108	Suppress error message for replacement tools with oversize Reset M107	Х	Х
M109 M110	Constant contouring speed at cutting edge (feed rate increase and reduction) Constant contouring speed at cutting edge (only feed rate reduction) Reset M109/M110	X	Х

Μ	Effect	TNC 320	iTNC 530
M112	Enter contour transitions between any two contour transi- tions	– (recommended: Cycle 32)	Х
M113	Reset M112		
M114 M115	Automatic compensation of machine geometry when working with tilted axes Reset M114	– recommended: M128, TCPM)	X, option 8
M116 M117	Feed rate on rotary tables in mm/min Reset M116	X, option 8	X, option 8
M118	Superimpose handwheel positioning during program run	Х	Х
M120	Pre-calculate the radius-compensated contour (LOOK AHEAD)	Х	Х
M124	Contour filter	– (possible via user parameters)	Х
M126 M127	Shorter-path traverse of rotary axes Reset M126	Х	Х
M128 M129	Maintaining the position of the tool tip when positioning tilted axes (TCPM) Reset M128	_	X, option 9
M130	Within the positioning block: Points are referenced to the untilted coordinate system	Х	Х
M134 M135	Precision stop at non-tangential contour transitions when positioning with rotary axes Reset M134	_	Х
M136 M137	Feed rate F in millimeters per spindle revolution Reset M136	Х	Х
M138	Selection of tilted axes	Х	Х
M140	Retraction from the contour in the tool-axis direction	Х	Х
M141	Suppress touch probe monitoring	Х	Х
M142	Delete modal program information	_	Х
M143	Delete basic rotation	Х	Х
M148 M149	Automatically retract tool from the contour at an NC stop Reset M148	Х	Х
M150	Suppress limit switch message	– (possible via FN 17)	Х
M197	Rounding the corners	Х	_
M200 -	Laser cutting functions	-	Х

M204

Comparator: Cycles

Cycle	TNC 320	iTNC 530
1 PECKING (recommended: Cycle 200, 203, 205)	_	Х
2 TAPPING (recommended: Cycle 206, 207, 208)	_	Х
3 SLOT MILLING (recommended: Cycle 253)	_	Х
4 POCKET MILLING (recommended: Cycle 251)	_	Х
5 CIRCULAR POCKET (recommended: Cycle 252)	_	Х
6 ROUGH-OUT (SL I, recommended: SL II, Cycle 22)	_	Х
7 DATUM SHIFT	Х	Х
8 MIRROR IMAGE	Х	Х
9 DWELL TIME	Х	Х
10 ROTATION	Х	Х
11 SCALING	Х	Х
12 PGM CALL	Х	Х
13 ORIENTATION	Х	Х
14 CONTOUR GEOMETRY	Х	Х
15 PILOT DRILLING (SL I, recommended: SL II, Cycle 21)	-	Х
16 CONTOUR MILLING (SL I, recommended: SL II, Cycle 24)	-	Х
17 RIGID TAPPING (recommended: Cycle 207, 209)	_	Х
18 THREAD CUTTING	Х	Х
19 WORKING PLANE	X, option 8	X, option 8
20 CONTOUR DATA	Х	Х
21 PILOT DRILLING	Х	Х
22 ROUGH-OUT	Х	Х
23 FLOOR FINISHING	Х	Х
24 SIDE FINISHING	Х	Х
25 CONTOUR TRAIN	Х	Х
26 AXIS-SPECIFIC SCALING	Х	Х
27 CYLINDER SURFACE	X, option 8	X, option 8
28 CYLINDER SURFACE	X, option 8	X, option 8
29 CYL SURFACE RIDGE	X, option 8	X, option 8
30 RUN CAM DATA	_	Х
32 TOLERANCE	Х	Х
39 CYL. SURFACE CONTOUR	X, option 8	X, option 8
200 DRILLING	Х	Х
201 REAMING	Х	Х
202 BORING	Х	Х
203 UNIVERSAL DRILLING	Х	Х
204 BACK BORING	X	Х

Cycle	TNC 320	iTNC 530
205 UNIVERSAL PECKING	Х	Х
206 TAPPING	Х	Х
207 RIGID TAPPING	Х	Х
208 BORE MILLING	Х	Х
209 TAPPING W/ CHIP BRKG	Х	Х
210 SLOT RECIP. PLNG (recommended: Cycle 253)	_	Х
211 CIRCULAR SLOT (recommended: Cycle 254)	_	Х
212 POCKET FINISHING (recommended: Cycle 251)	_	Х
213 STUD FINISHING (recommended: Cycle 256)	_	Х
214 C. POCKET FINISHING (recommended: Cycle 252)	_	Х
215 C. STUD FINISHING (recommended: Cycle 257)	_	Х
220 POLAR PATTERN	Х	Х
221 CARTESIAN PATTERN	Х	Х
225 ENGRAVING	Х	Х
230 MULTIPASS MILLING (recommended: Cycle 233)	_	Х
231 RULED SURFACE	_	Х
232 FACE MILLING	Х	Х
233 FACE MILLING	Х	_
240 CENTERING	Х	Х
241 SINGLE-LIP D.H.DRLNG	Х	Х
247 PRESETTING	Х	Х
251 RECTANGULAR POCKET	Х	Х
252 CIRCULAR POCKET	Х	Х
253 SLOT MILLING	Х	Х
254 CIRCULAR SLOT	Х	Х
256 RECTANGULAR STUD	Х	Х
257 CIRCULAR STUD	Х	Х
258 POLYGON STUD	Х	_
262 THREAD MILLING	Х	Х
263 THREAD MLLNG/CNTSNKG	Х	Х
264 THREAD DRILLNG/MLLNG	Х	Х
265 HEL. THREAD DRLG/MLG	Х	Х
267 OUTSIDE THREAD MLLNG	Х	Х
270 CONTOUR TRAIN DATA for defining the behavior of Cycle 25	Х	Х
275 TROCHOIDAL SLOT	Х	Х
276 THREE-D CONT. TRAIN	Х	Х
290 INTERPOLATION TURNING	_	X, option 96

Comparison: Touch probe cycles in the Manual operation and Electronic handwheel modes of operation

Cycle	TNC 320	iTNC 530
Touch-probe table for managing 3-D touch probes	Х	_
Calibrating the effective length	Х	Х
Calibrating the effective radius	Х	Х
Measuring a basic rotation using a line	Х	Х
Setting the preset on any axis	Х	Х
Setting a corner as preset	Х	Х
Setting a circle center as preset	Х	Х
Setting a center line as preset	Х	Х
Measuring a basic rotation using two holes/cylindrical studs	Х	Х
Setting the preset using four holes/cylindrical studs	Х	Х
Setting the circle center using three holes/cylindrical studs	Х	Х
Determine and offset misalignment of a plane	Х	_
Support of mechanical touch probes by manually capturing the current position	By soft key or hard key	By hard key
Write measurement values to the preset table	Х	Х
Write measurement values to the datum table	Х	Х

Comparison: Probing system cycles for automatic workpiece control

Cycle	TNC 320	iTNC 530
0 REF. PLANE	Х	Х
1 POLAR PRESET	Х	Х
2 CALIBRATE TS	_	Х
3 MEASURING	Х	Х
4 MEASURING IN 3-D	Х	Х
9 CALIBRATE TS LENGTH	-	Х
30 CALIBRATE TT	Х	Х
31 CAL. TOOL LENGTH	Х	Х
32 CAL. TOOL RADIUS	Х	Х
33 MEASURE TOOL	Х	Х
400 BASIC ROTATION	Х	Х
401 ROT OF 2 HOLES	Х	Х
402 ROT OF 2 STUDS	Х	Х
403 ROT IN ROTARY AXIS	Х	Х
404 SET BASIC ROTATION	Х	Х
405 ROT IN C AXIS	Х	Х
408 SLOT CENTER PRESET	Х	Х
409 RIDGE CENTER PRESET	Х	Х
410 PRESET INSIDE RECTAN	Х	Х
411 PRESET OUTS. RECTAN	Х	Х
412 PRESET INSIDE CIRCLE	Х	Х
413 PRESET OUTS. CIRCLE	Х	Х
414 PRESET OUTS. CORNER	Х	Х
415 PRESET INSIDE CORNER	Х	Х
416 PRESET CIRCLE CENTER	Х	Х
417 PRESET IN TS AXIS	Х	Х
418 PRESET FROM 4 HOLES	Х	Х
419 PRESET IN ONE AXIS	Х	Х
420 MEASURE ANGLE	Х	Х
421 MEASURE HOLE	Х	Х
422 MEAS. CIRCLE OUTSIDE	Х	Х
423 MEAS. RECTAN. INSIDE	Х	Х
424 MEAS. RECTAN. OUTS.	Х	Х
425 MEASURE INSIDE WIDTH	Х	Х
426 MEASURE RIDGE WIDTH	Х	Х
427 MEASURE COORDINATE	Х	Х

Cycle	TNC 320	iTNC 530
430 MEAS. BOLT HOLE CIRC	Х	Х
431 MEASURE PLANE	Х	Х
440 MEASURE AXIS SHIFT	_	Х
441 FAST PROBING	Х	Х
450 SAVE KINEMATICS	_	X, option 48
451 MEASURE KINEMATICS	_	X, option 48
452 PRESET COMPENSATION	_	X, option 48
453 KINEMATICS GRID	_	_
460 CALIBRATION OF TS ON A SPHERE	Х	Х
461 TS CALIBRATION OF TOOL LENGTH	Х	Х
462 CALIBRATION OF A TS IN A RING	Х	Х
463 TS CALIBRATION ON STUD	Х	Х
480 CALIBRATE TT	Х	Х
481 CAL. TOOL LENGTH	Х	Х
482 CAL. TOOL RADIUS	Х	Х
483 MEASURE TOOL	Х	Х
484 CALIBRATE IR TT	Х	Х
600 GLOBAL WORKING SPACE	Х	_
601 LOCAL WORKING SPACE	Х	_

Comparison: Differences in programming

Function	TNC 320	iTNC 530
Switching the operating mode while a block is being edited	Permitted	Permitted
File handling:		
Save file function	Available	Available
Save file as function	Available	Available
Discard changes	Available	Available
File management:		
 Mouse operation 	Available	 Available
 Sorting function 	Available	 Available
Entry of name	 Opens Select file pop-up window 	 Synchronizes the cursor
 Support of key combinations 	Not available	 Available
 Favorites Management 	Not available	 Available
 Configuration of column structure 	 Not available 	 Available
Soft-key arrangement	 Slightly different 	 Slightly different
Skip block function	Available	Available
Selecting a tool from the table	Selection via split-screen menu	Selection in a pop-up window
Programming special functions with the SPEC FCT key	Pressing the key opens a soft-key row as a submenu. To exit the submenu, press the SPEC FCT key again; then the control shows the last active soft-key row	Pressing the key adds the soft- key row as the last row. To exit the menu, press the SPEC FCT key again; then the control shows the last active soft-key row
Programming approach and depar- ture motions with the APPR DEP key	Pressing the key opens a soft-key row as a submenu. To exit the submenu, press the APPR DEP key again; then the control shows the last active soft-key row	Pressing the key adds the soft- key row as the last row. To exit the menu, press the APPR DEP key again; then the control shows the last active soft-key row
Pressing the hard key END with active CYCLE DEF and TOUCH PROBE menus	Terminates the editing process and calls the file manager	Exits the respective menu
Calling the file manager while the CYCLE DEF and TOUCH PROBE menus are active	Terminates the editing process and calls the file manager. The respec- tive soft-key row remains selected when the file manager is exited	Key non-functional error message
Calling the file manager while CYCL CALL , SPEC FCT , PGM CALL and APPR/DEP menus are active	Terminates the editing process and calls the file manager. The respec- tive soft-key row remains selected when the file manager is exited	Terminates the editing process and calls the file manager. The basic soft-key row is selected when the file manager is exited

Function	TNC 320	iTNC 530
Datum table:		
 Sorting function by values within an axis 	Available	 Not available
 Resetting the table 	Available	 Not available
 Hiding axes that are not present 	 Available 	 Available
 Switching the list/form view 	Switch via the screen layout key	 Switchover by toggle soft key
 Inserting individual line 	 Allowed everywhere, renumbering possible after request. Empty line is inserted, must be filled with zeros manually 	 Only allowed at the end of the table. Line with value 0 in all columns is inserted
 Transfer of actual position values on individual axis to the datum table using the keys 	Not available	 Available
 Transfer of actual position values on all active axes to the datum table using the keys 	Not available	 Available
 Capturing the last positions measured by TS using the keys 	Not available	 Available
FK free contour programming:		
 Programming of parallel axes 	 With X/Y coordinates, independent of machine type; switchover with FUNCTION PARAXMODE 	 Machine-dependent with the existing parallel axes
 Automatic correction of relative references 	 Relative references in contour subprograms are not corrected automatically 	 All relative references are corrected automatically
Q-parameter programming:		
 Q-parameter formula with SGN 	Q12 = SGN Q50	Q12 = SGN Q50
	■ if Q 50 = 0 then Q12 = 0	■ if Q50 >= 0 then Q12 = 1
	■ if Q50 > 0 then Q12 = 1	■ if Q50 < 0 then Q12 = -1
	■ if Q50 < 0 then Q12 = -1	

Handling of error messages: Help with error messages: Call via ERR key Call via HELP key Switching the operating mode while help menu is active Help menu is closed when the operating mode is switched Selecting the background operating mode while help menu Help menu is closed when F12 is used for switching Help menu remains open when F12 is used for switching Help menu remains open when F12 is used for switching Identical error messages Are collected in a list Acknowledgment of error messages Access to protocol functions Log and powerful filter functions (errors, keystrokes) are available Camplete log without filter functions valiable Available. A service file is automatically created when the system crashes Find function: List of words recently searched for Show elements of active block Not available Not available	Function	TNC 320	iTNC 530
 Switching the operating mode while help menu is active Help menu is closed when the operating mode is switched Selecting the background operating mode while help menu is closed when F12 Help menu is closed when F12 Help menu is closed when F12 Help menu remains open when F12 is used for switching Identical error messages Acknowledgment of error message (even if it is displayed more than once) must be acknowledged, the DELET ALL function is available Access to protocol functions Log and powerful filter functions (errors, keystrokes) are available Saving service files Available. No service file is created when the system crashes Find function: List of words recently searched for Show elements of active block Not available Show let of all available NC blocks Starting the search function with the up/down arrow keys when highlighted Programming graphics: True-to-scale display of grid Available Available With error messages, in the main program the cursor is on the block in the CYCL CALL block 	Handling of error messages:		
while help menu is activeoperating mode is switchedis not allowed (key is non-functional)Selecting the background operating mode while help menu= Help menu is closed when F12 is used for switching= Help menu remains open when F12 is used for switchingIdentical error messages= Are collected in a list= Are displayed only onceAcknowledgment of error messages= Every error message (even if it is displayed more than once) must be acknowledged, the DELETE ALL function is available= Complete log without filter functions (errors, keystrokes) are availableAccess to protocol functions= Log and powerful filter functions (errors, keystrokes) are available= Complete log without filter functions availableSaving service files= Available. No service file is created when the system crashes= Available. A service file is automatically created when the system crashesFind function:= Not available= AvailableShow elements of active block= Not available= AvailableShow list of all available NC blocks= Not available= AvailableStarting the search function with the up/down arrow keys when highlighted= AvailableProgramming graphics: = True-to-scale display of grid = Available= Available= Not available= With error messages, in the main program the cursor is on the CYCL CALL block= Not available= Not available= Help menu is closed when f12 sub closes= Available= Not available	 Help with error messages 	Call via ERR key	Call via HELP key
operating mode while help menu is activeis used for switchingF12 is used for switchingI dentical error messages= Are collected in a list= Are displayed only once= Acknowledgment of error messages= Every error message (even if it is displayed more than once) must be acknowledged, the DELETE ALL function is available= Error message to be acknowledged only once= Access to protocol functions= Log and powerful filter functions (errors, keystrokes) are available= Complete log without filter functions available= Saving service files= Available. No service file is created when the system crashes= Available. A service file is automatically created when the system crashesFind function:= Not available= Available= List of words recently searched for= Not available= AvailableShow lements of active block= Not available= AvailableStarting the search function with highlightedWorks up to max. 50,000 blocks, can be set via configuration datumNo limitation regarding program lengthProgramming graphics: = True-to-scale display of grid = Lidting contour subprograms in SLII cycles with AUTO DRAW ON= Available= Not available= With error messages, in the main program the cursor is on the CYCL CALL block= Not available= Ust or message soccur, the cursor is on the block in the contour subprogram responsible for the error		•	is not allowed (key is non-
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functions (errors, keystrokes) are availablefunctions available• Saving service files• Available. No service file is created when the system crashes• Available. A service file is automatically created when the system crashesFind function:• Not available• Available• List of words recently searched for• Not available• Available• Show elements of active block• Not available• Available• Show list of all available NC blocks• Not available• Available• Starting the search function with the up/down arrow keys when highlighted• Works up to max. 50,000 blocks, can be set via configuration datum highlightedNo limitation regarding program lengthProgramming graphics: • True-to-scale display of grid • Editing contour subprograms in SLII cycles with AUTO DRAW ON• Available • With error messages, in the main program the cursor is on the CYCL CALL block• Not available	-	if it is displayed more than once) must be acknowledged, the DELETE ALL function is	0
created when the system crashesautomatically created when the system crashesFind function:•• List of words recently searched for•• Show elements of active block•• Show velements of active block•• Show list of all available NC blocks•• Not available•• Available NC blocks•• Not available•• Available•• Available NC blocks•• Not available•• True-to-scale display of grid•• Editing contour subprograms in SLII cycles with AUTO DRAW ON•• With error messages, in the main program the cursor is on the CYCL CALL block•• Not available•• If error messages occur, the contour subprogram responsible for the error	 Access to protocol functions 	functions (errors, keystrokes)	
 List of words recently searched for Not available Not available Not available Available Not available Available Not available Available Not available Not available Available Not available If error messages occur, the cursor is on the block in the contour subprogram responsible for the error 	 Saving service files 	created when the system	automatically created when the
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the up/down arrow keys when highlightedcan be set via configuration datumlengthProgramming graphics:• True-to-scale display of grid• Available• Not available• Editing contour subprograms in SLII cycles with AUTO DRAW ON• With error messages, in the main program the cursor is on the CYCL CALL block• Not available• If error messages occur, the cursor is on the CYCL CALL block• If error messages occur, the cursor is on the block in the contour subprogram responsible for the error		 Not available 	Available
 True-to-scale display of grid Editing contour subprograms in SLII cycles with AUTO DRAW ON Available With error messages, in the main program the cursor is on the CYCL CALL block If error messages occur, the cursor is on the block in the contour subprogram responsible for the error 	the up/down arrow keys when		
 Editing contour subprograms in SLII cycles with AUTO DRAW ON With error messages, in the main program the cursor is on the CYCL CALL block If error messages occur, the cursor is on the block in the contour subprogram responsible for the error 	Programming graphics:		
SLII cycles with AUTO DRAW ONmain program the cursor is on the CYCL CALL blockthe cursor is on in the contour subprogram responsible for the error	 True-to-scale display of grid 	Available	 Not available
Moving the zoom windowRepeat function not availableRepeat function available		main program the cursor is on	the cursor is on the block in the contour subprogram
	Moving the zoom window	 Repeat function not available 	 Repeat function available

Function	TNC 320	iTNC 530
Programming minor axes:		
 Syntax FUNCTION PARAXCOMP: Define the behavior of the display and the paths of traverse 	 Available 	 Not available
 Syntax FUNCTION PARAXMODE: Define the assignment of the parallel axes to be traversed 	 Available 	 Not available
Programming OEM cycles		
 Access to table data 	 Via SQL commands and via FN 17/FN 18 or TABREAD-TABWRITE functions 	 Via FN 17/FN 18 or TABREAD-TABWRITE functions
 Access to machine parameters 	With the CFGREAD function	Via FN 18 functions
 Creating interactive cycles with CYCLE QUERY, e.g. touch probe cycles in Manual Operation 	 Available 	 Not available

Comparison: Differences in Test Run, functionality

Function	TNC 320	iTNC 530
Entering a program with the GOTO key	Function only possible if the START SINGLE soft key was not pressed	Function also possible after START SINGLE
Calculation of machining time	Each time the simulation is repeat- ed by pressing the START soft key, the machining time is totaled	Each time the simulation is repeat- ed by pressing the START soft key, time calculation starts at 0
Single block	With point pattern cycles and CYCL CALL PAT , the control stops after each point	Point pattern cycles and CYCL CALL PAT are handled by the control as a single block

Comparison: Differences in Test Run, operation

Function	TNC 320	iTNC 530
Arrangement of soft-key rows and soft keys within the rows	Arrangement of soft-key rows and s active screen layout.	oft-keys varies depending on the
Zoom function	Each sectional plane can be select- ed by individual soft keys	Sectional plane can be selected via three toggle soft keys
Machine-specific miscellaneous functions M	Lead to error messages if they are not integrated in the PLC	Are ignored during Test Run
Displaying/editing the tool table	Function available via soft key	Function not available
Tool depiction	red: engaged	red: engaged
	blue: not engaged	green: not engaged
3-D view: Transparent display of workpiece	Available	Function not available
3-D view: Transparent display of workpiece	Available	Function not available
3-D view: Display tool path	Available	Function not available
Adjustable model quality	Available	Function not available

Comparison: Differences in Manual Operation, functionality

Function	TNC 320	iTNC 530
Jog increment function	The jog increment can be defined separately for linear and rotary axes	The jog increment applies for both linear and rotary axes
Preset table	Basic transformation (translation and rotation) of machine table system to workpiece system via the X, Y and Z columns, as well as spatial angles SPA, SPB and SPC. In addition, the X_OFFS to W_OF- FS columns can be used to define the axis offset of each individ- ual axis. The function of the axis offsets can be configured. Line 0 can also be edited manually.	Basic transformation (transla- tion) of machine table system to workpiece system via the columns X , Y and Z , as well as a ROT basic rotation in the working plane (rotation). In addition, columns A to W can be used to define presets on the rotary and parallel axes. Line 0 can only be edited by manual probing cycles.
Behavior when presetting	Presetting in a rotary axis has the same effect as an axis offset. This offset is also effective for kinemat- ics calculations and during tilting of the working plane. In machine parameter preset- ToAlignAxis (no. 300203) your	Rotary axis offsets defined by machine parameters do not influ- ence the axis positions that were defined in the Tilt working plane function. MP7500, bit 3 permits you to define whether the current
	 machine tool builder specifies for each axis what effect an offset of a rotational axis has on the preset. True (default): The offset is subtracted from the axis value before the calculation of the kinematics 	rotary axis position relative to the machine datum is taken into account or whether the first rotary axis (usually the C axis) is assumed to be in 0° position.
	 False: The offset only affects the position display 	
Presetting	Only after a reference run is it possible to set a preset or to modify a preset via the preset table.	A preset can be set or modified via the preset table before a reference run.
Handling of the preset table:		
 Preset table that depends on the range of traverse 	Available	 Available
Definition of feed-rate limitation	Feed-rate limitation can be defined separately for linear and rotary axes	Only one feed-rate limitation can be defined for linear and rotary axes

Comparison: Differences in Manual Operation, operation

Function	TNC 320	iTNC 530
Capturing the position values from mechanical probes	Confirm actual position with a soft key or hard key	Actual-position capture by hard key
Exiting the Touch Probe Functions menu	Using the END soft key or the END hard key	Using the END soft key or the END hard key

Comparison: Differences in Program Run, operation

Function	TNC 320	iTNC 530
Arrangement of soft-key rows and soft keys within the rows	Arrangement of soft-key rows and so active screen layout.	oft-keys differs according to the
Operating mode switchover after program run has been suspended by switching to the Program run, single block operating mode and canceled with INTERNAL STOP	When you return to the Program run, full sequence mode: error message Current block not selected . Use mid-program startup to select the point of interruption	Switching the operating mode is allowed, modal information is saved, program run can be contin- ued by pressing NC start
GOTO is used to go to FK sequences after program run was interrupted there before switching the operating mode	Error message FK programming: Undefined starting position Entering with mid-program startup is permitted	GOTO allowed
Mid-program startup:		
Switching the screen layout for mid- program startup	Only possible, if startup position has already been approached	Possible in all operating states
Error messages	Error messages are still active after the error has been corrected and must be acknowledged separately	Error messages are sometimes acknowledged automatically after the error has been corrected
Point patterns in single block	With point pattern cycles and CYCL CALL PAT , the control stops after each point.	Point pattern cycles and CYCL CALL PAT are handled by the control as a single block

Comparison: Differences in Program Run, traverse movements

NOTICE

Danger of collision!

NC programs that were created older controls can lead to unexpected axis movements or error messages on current control models. Danger of collision during machining!

- Check the NC program or program section using the graphic simulation
- Carefully test the NC program or program section in the Program run, single block operating mode
- Pay attention to the following known differences (the list below might not be complete!)

Function	TNC 320	iTNC 530
Handwheel-superimposed travers- ing with M118	Effective in the machine coordinate system	Effective in the machine coordinate system
Deleting basic rotation with M143	M143 deletes the entries in columns SPA, SPB, and SPC in the preset table; reactivating the corre- sponding preset table row does not activate the deleted basic rotation	M143 does not delete the entry in the ROT column in the preset table; reactivating the correspond- ing preset table row activates the deleted basic rotation
Scaling approach/departure movements (APPR/DEP/RND)	Axis-specific scaling factor is allowed, radius is not scaled	Error message
Approach/departure with APPR/DEP	Error message if R0 is programmed for APPR/DEP LN or APPR/DEP CT	Tool radius 0 and compensation direction RR are assumed
Approach/departure with APPR/DEP if contour elements with length 0 are defined	Contour elements with length 0 are ignored. The approach/depar- ture movements are calculated for the first and last valid contour element	An error message is issued if a contour element with length 0 is programmed after the APPR block (relative to the first contour point programmed in the APPR block) For a contour element with length 0 before a DEP block, the iTNC 530 does not issue an error message, but uses the last valid
		contour element to calculate the departure movement

Function	TNC 320	iTNC 530	
Effect of Q parameters	Q60 to Q99 (QS60 to QS99) areal- ways local.	Q60 to Q99 (QS60 to QS99) are local or global, depending on MP7251 in converted cycle programs (.cyc). Nested calls may cause problems	
Automatic cancelation of tool radius compensation	 Block with R0 DEP block Program selection END PGM 	 Block with R0 DEP block Program selection Programming of G73 ROTATION PGM CALL 	
NC blocks with M91	No consideration of tool radius compensation	Consideration of tool radius compensation	
Behavior with M120 LA1	No effect on processing, as the control interprets the input internally as an LAO	Possible undesired effect on processing, as the control inter- prets the entry internally as an LA2	
Block scan in a point table	The tool is positioned above the next position to be machined	The tool is positioned above the last position that has been completely machined	
Emtpy CC block (pole adoption from last tool position) in the NC program	Last positioning block in the working plane must contain both coordinates of the working plane	Last positioning block in the working plane does not necessari- ly need to contain both coordinates of the working plane. Can cause problems with RND or CHF blocks	
Axis-specific scaling of RND block	RND block is scaled, the result is an ellipse	Error message is issued	
Reaction if a contour element with length 0 is defined before or after a RND or CHF block	Error message is issued	Error message is issued if a contour element with length 0 is located before the RND or CHF block	
		Contour element with length 0 is ignored if the contour element with length 0 is located after the RND or CHF block	

Function	TNC 320	iTNC 530 The algebraic sign of the direc- tion of rotation is used if the sign defined for DR differs from the one defined for IPA	
Circle programming with polar coordinates	The incremental rotation angle IPA and the direction of rotation DR must have the same sign. Other- wise, an error message will be issued		
Tool radius compensation on circular arc or helix with angular length = 0	The transition between the adjacent elements of the arc/helix is generated. Also, the tool axis motion is executed right before this transition. If the element is the first or last element to be correct- ed, the next or previous element is dealt with in the same way as the first or last element to be correct- ed	The equidistant line of the arc/he is used for generating the tool pa	
Compensation of tool length in the position display	The values L and DL from the tool table and the value DL from the T block are taken into account in the position display	The values L and DL from the too table are taken into account in the position display	
SLII Cycles 20 to 24:			
 Number of definable contour elements 	 Max. 16384 blocks in up to 12 subcontours 	 Max. 8192 contour elements in up to 12 subcontours, no restrictions for subcontour 	
 Define the working plane 	Tool axis in T block defines the working plane	The axes of the first positioning block in the first subcontour define the working plane	
Position at end of SL cycle	 With the posAfterContPocket (no. 201007) parameter, you can define whether the end position is above the last programmed position, or whether the tool moves to clearance height in the tool axis If the tool moves to clearance height in the tool axis, both coordinates must be programmed with the first traverse merement 	 With MP7420, you can define whether the end position is above the last programmed position, or whether the tool moves only to clearance height in the tool axis If the tool moves to clearance height in the tool axis, one coordinate must be programmed with the first traverse movement 	

traverse movement

Function	TNC 320	iTNC 530
SLII Cycles 20 to 24:		
 Behavior with islands not contained in pockets 	 Cannot be defined with complex contour formula 	 Restricted definition in complex contour formula is possible
 Set operations for SL cycles with complex contour formulas 	 Real set operation possible 	 Only restricted performance of real set operation possible
 Radius compensation is active during CYCL CALL 	 Error message is issued 	 Radius compensation is canceled, program is executed
 Paraxial positioning blocks in contour subprogram 	 Error message is issued 	Program is executed
 Miscellaneous functions M in contour subprogram 	 Error message is issued 	 M functions are ignored
Cylinder surface machining in general:		
 Contour definition 	 With X/Y coordinates, independent of machine type 	 Machine-dependent, with existing rotary axes
		 Machine-specific datum shift in rotary axes
 Offset definition for basic rotation 	 Function available 	 Function not available
Circle programming with C/CC	Function available	 Function not available
APPR/DEP blocks in contour definition	 Function not available 	 Function available
Cylinder surface machining with Cycle 28:		
Complete roughing-out of slot	 Function available 	 Function not available
 Definable tolerance 	 Function available 	 Function available
Cylinder surface machining with Cycle 29	Direct plunging to contour of ridge	Circular approach to contour of ridge
Cycles 25x for pockets, studs and slots:		
 Plunging movements 	In limit ranges (geometrical conditions of tool/contour) error messages are triggered if plung- ing movements lead to unreason- able/critical behavior	In limit ranges (geometrical condi- tions of tool/contour), vertical plunging is used if required

Function	TNC 320	iTNC 530
PLANE function:		
TABLE ROT/COORD ROT	Effect: The transformation types are	Effect The transformation types are
	 effective on all free rotary axes The control does not always position the free rotary axis with TABLE ROT, but depending on the current position, the programmed spatial angle and the machine kinematics Default with missing selection: 	 only effective with a C rotary axis With TABLE ROT the control always positions the rotary axis Default with missing selection: COORD ROT is used
	COORD ROT is used	
 Machine is configured for axis angle 	 All PLANE functions can be used 	Only PLANE AXIAL is executed
 Programming an incremental spatial angle according to PLANE AXIAL 	Error message is issued	 Incremental spatial angle is interpreted as an absolute value
 Programming an incremental axis angle according to PLANE SPATIAL if the machine is configured for spatial angles 	 Error message is issued 	 Incremental axis angle is interpreted as an absolute value
 Programming of PLANE functions with active Cycle 8 MIRROR IMAGE 	 Mirroring has no influence on tilting using AXIAL PLANE and Cycle 19 	 Function is available with all PLANE functions
 Axis positioning on machines with two rotary axes e.g. 	 Only possible after a tilting function (error message if without a tilting function) 	 Possible at any time if spatial angles are used (machine parameter setting)
L A+0 B+0 C+0 or L A+Q120 B+Q121 C+Q122	 Parameters that are not defined are given the status UNDEFINED; they are not given the value 0 	 The control assigns the value 0 to parameters that are not defined
Special functions for cycle programming:		
 FN 17 	Function availableValues are always output in	Function availableValues are output in the units of
	metric form	the active NC program
	 Further details are different 	 Details are different
FN 18	 Function available Values are always output in metric form Further details are different 	 Function available Values are output in the unit of the active NC program Details are different
Compensation of tool length in the position display	The tool length entries L and DL from the tool table are taken into account in the position display, from T block depending on the machine parameter progTool- CallDL (no. 124501)	The tool length entries L and DL from the tool table are taken into account in the position display

Comparison: Differences in MDI operation

Function	TNC 320	iTNC 530
Execution of connected sequences	Function available	Function available
Saving modally effective functions	Function available	Function available
Miscellaneous functions	 Global program settings Status display for Q parameters Block functions, e. g. COPY BLOCK 	 Global program settings
	 Miscellaneous program functions, e.g. FUNCTION DWELL 	

Comparison: Differences in programming station

Function	TNC 320	iTNC 530
Demo version	Programs with more than 100 NC blocks cannot be selected, an error message is issued	Programs can be selected, max. 100 NC blocks are displayed, further blocks are truncated in the display
Demo version	If nesting with % results in more than 100 NC blocks, there is no test graphic display; an error message is not issued	Nested programs can be simulated
Copying NC programs	Copying to and from the directo- ry TNC:\ is possible with Windows Explorer	TNCremo or file manager of programming station must be used for copying
Shifting the horizontal soft-key row	Clicking on the soft-key bar shifts one soft-key row to the right or left	Clicking any soft-key bar activates the respective soft-key row

17.6 DIN/ISO function overview

DIN/ISO Function Overview TNC 320

M functions	
M00 M01 M02	Program run STOP/Spindle STOP/Coolant OFF Optional program run STOP Program run STOP/Spindle/STOP/Coolant OFF/if nec. Clear status display (depending on machine parameter)/Return jump to block 1
M03 M04 M05	Spindle ON clockwise Spindle ON counterclockwise Spindle STOP
M06	Tool change/Program run STOP (depending on machine parameter)/Spindle STOP
M08 M09	Coolant ON Coolant OFF
M13 M14	Spindle ON clockwise/Coolant ON Spindle ON counterclockwise/Coolant on
M30	Same function as M02
M89	Free miscellaneous function or cycle call, modally effective (depending on machine parameter)
M99	Blockwise cycle call
M91 M92	Within the positioning block: Coordinates are referenced to machine datum Within the positioning block: Coordinates are referenced to position defined by machine tool builder, such as tool change position
M94	Reduce the rotary axis display to a value below 360°
M97 M98	Machine small contour steps Machine open contours completely
M109 M110 M111	Constant contouring speed at cutting edge (feed rate increase andreduction) Constant contouring speed at cutting edge (only feed rate reduction) Reset M109/M110
M116 M117	Feed rate for rotary axes in mm/min Reset M116
M118	Superimpose handwheel positioning during program run
M120	Pre-calculate radius-compensated contour (LOOK AHEAD)
M126 M127	Shorter-path traverse of rotary axes: Reset M126
M128 M129	Maintain position of the tool tip when positioning with tilted axes (TCPM) Reset M128
M130	Within the positioning block: Points are referenced to the untilted coordinate system
M140	Retraction from the contour in the tool-axis direction
M141	Suppress touch probe monitoring
M143	Delete basic rotation
M148 M149	Retract the tool automatically from the contour at NC stop Reset M148

G codes	
Tool moveme	nts
G00	Cartesian line in rapid traverse
G01	Cartesian line at feed rate
G02	Cartesian circle clockwise
G03	Cartesian circle CCW
G05	Cartesian circle
G06	Cartesian circle, tang. transit.
G07*	Cartesian line, paraxial
G10	Polar line in rapid traverse
G11	Polar line at feed rate
G12	Polar circle clockwise
G13	Polar circle counterclockwise
G15	Polar circle
G16	Polar circle, tang. transition
Chamfer/Rou	nding/Approach contour/Depart contour
G24*	Chamfer with length R with chamfer length R
G25*	Corner rounding with radius R with radius R
G26*	Tangential approach to a contour with radius R
G27*	Tangential departure from a contour with radius R
Tool definition	 ו
G99*	Tool definition with tool number T, length L and radius R
Tool radius co	mpensation
G40	Path of tool center without tool radius compensation
G41	Radius compensation left of path
G42	Radius compens. right of path
G43	Radius compensation: extend path for G07
G44	Radius compens.: shorten path for G07
Blank form de	finition for graphics
G30	Workpiece blank def.: MIN point (G17/G18/G19)
G31	Workpiece blank def.: MAX point (G90/G91)
Cycles for dril	ling, tapping and thread milling
G200	DRILLING
G201	REAMING
G202	BORING
G203	UNIVERSAL DRILLING
G204	BACK BORING
G205	UNIVERSAL PECKING
G206	TAPPING with floating tap holder
G207	RIGID TAPPING without floating tap holder
G208	BORE MILLING
G209	TAPPING W/ CHIP BRKG
G240	CENTERING
G241	SINGLE-LIP D.H.DRLNG

G codes	
Cycles for drill	ing, tapping and thread milling
G262	THREAD MILLING
G263	THREAD MLLNG/CNTSNKG
G264	THREAD DRILLNG/MLLNG
G265	HEL. THREAD DRLG/MLG
G267	OUTSIDE THREAD MLLNG
Cycles for mill	ing pockets, studs and slots
G233	FACE MILLING
G251	RECTANGULAR POCKET
G252	CIRCULAR POCKET
G253	SLOT MILLING
G254	CIRCULAR SLOT
G256	
G257	RECTANGULAR STUD
G258	CIRCULAR STUD
	POLYGON STUD
	ating point patterns
G220 G221	POLAR PATTERN CARTESIAN PATTERN
SL Cycles	
G37	CONTOUR GEOMETRY
G120	CONTOUR DATA for G121 to G124
G121	PILOT DRILLING
G122	ROUGH-OUT
G123	FLOOR FINISHING
G124	SIDE FINISHING
G125	CONTOUR TRAIN for open contour
G270	CONTOUR TRAIN DATA
G127	CYLINDER SURFACE
G128	CYLINDER SURFACE
G129	CYL SURFACE RIDGE
G139	
G275	
G276	TROCHOIDAL SLOT THREE-D CONT. TRAIN
Coordinate co	
G53	DATUM SHIFT from datum tables
G54	DATUM SHIFT in the program
G28	MIRROR IMAGE
G73	ROTATION
G72	SCALING
G80	WORKING PLANE
G247	PRESETTING
Cycles for mu	tipass milling
G230	MULTIPASS MILLING
G231	RULED SURFACE
*) blockwise ef	fective function
,	

Coodee	
G codes	relea far maaguring warknigge migelignment
	vcles for measuring workpiece misalignment
G400 G401	BASIC ROTATION
G401 G402	ROT OF 2 HOLES
G402 G403	ROT OF 2 STUDS
G403 G404	ROT IN ROTARY AXIS SET BASIC ROTATION
G404 G405	ROT IN C AXIS
	/stem cycles for setting datum
G408	
G408 G409	SLOT CENTER PRESET RIDGE CENTER PRESET
G403 G410	PRESET INSIDE RECTAN
G410 G411	PRESET OUTS. RECTAN
G412	PRESET OUTS. RECTAIN PRESET INSIDE CIRCLE
G413	PRESET OUTS. CIRCLE
G414	PRESET OUTS. CORNER
G415	PRESET OUTS. CORNER PRESET INSIDE CORNER
G416	PRESET CIRCLE CENTER
G417	PRESET IN TS AXIS
G418	PRESET FROM 4 HOLES
G419	PRESET IN ONE AXIS
Touch probe cy	/cles for workpiece measurement
 G55	REF. PLANE
G420	MEASURE ANGLE
G421	MEASURE HOLE
G422	MEAS. CIRCLE OUTSIDE
G423	MEAS. RECTAN. INSIDE
G424	MEAS. RECTAN. OUTS.
G425	MEASURE INSIDE WIDTH
G426	MEASURE RIDGE WIDTH
G427	MEASURE COORDINATE
G430	MEAS. BOLT HOLE CIRC
G431	MEASURE PLANE
Touch probe cy	cles for tool measurement
G480	CALIBRATE TT
G481	CAL. TOOL LENGTH
G482	CAL. TOOL RADIUS
G483	MEASURE TOOL
G434	CALIBRATE IR TT
Special cycles	
G04*	DWELL TIME
G36	ORIENTATION
G39*	PGM CALL
G62	TOLERANCE
Define the wor	rking plane
G17	Spindle axis Z - plane XY
G18	Spindle axis Y - plane ZX
G19	Spindle axis X - plane YZ

G codes

Dimensions

G90 G91	Absolute dimension Incremental dimension
Unit of m	easure
G70	Unit of measure inch (at start of program)
G71	Unit of measure mm (at start of program)
Other G	odes
G29	Load current position (e.g. circle center as pole)
G38	Stop program run
G51*	Prepare tool changer (with central tool magazine)
G79*	Cycle call
G98*	Set label
*) blockw Addresse	se effective function s
%	Start of program
%	Program call
#	Datum number with G53
A	Rotation around the X axis
В	Rotation around the Y axis
С	Rotation around the Z axis
D	Q parameter definitions
DL	Wear compensation length with T
DR	Wear compensation radius with T
E	Tolerance with M112 and M124
F	Feed rate
F	Dwell time with G04
F	Scaling factor with G72

F F	Scaling factor with G72 Factor F reduction with M103
G	G codes
H H H	Polar angle Rotation angle with G73 Limit angle with M112
I	X coordinate of the circle center/pole
J	Y coordinate of the circle center/pole
К	Z coordinate of the circle center/pole
L L L	Setting a label number with G98 Jumping to a label number Tool length with G99
M	M functions
N	Block number
P P	Cycle parameter in machining cycles Value or Q parameter in Q-parameter definition
Q	Q parameter

Addresses	
R	Polar coordinate radius
R	Circle radius with G02/G03/G05
R	Rounding radius with G25/G26/G27
R	Tool radius with G99
S	Spindle speed
S	Spindle orientation with G36
T	Tool definition with G99
T	Tool call
T	Next tool with G51
U	Axis parallel to X axis
V	Axis parallel to Y axis
W	Axis parallel to Z axis
X	X axis
Y	Y axis
Z	Z axis
*	End of block

Contour cycles

Program structure with machining with multiple tools	
List of contour programs	G37 P01
Defining contour data	G120 Q1
Drill define/call Contour cycle: Pilot drilling Cycle call	G121 Q10
Roughing mill define/call Contour cycle: Rough-out Cycle call	G122 Q10
Finishing mill define/call Contour cycle: Floor finishing Cycle call	G123 Q11
Finishing mill define/call Contour cycle: Side finishing Cycle call	G124 Q11
End of main program, return	M02
Contour subprograms	G98 G98 L0

Radius compensation of the contour subprograms

Contour	Programming sequence of the contour elements	Radius Compensa- tion
Inside (pocket)	clockwise (CW) counterclockwise (CCW)	G42 (RR) G41 (RL)
Outside (island)	clockwise (CW) counterclockwise (CCW)	G41 (RL) G42 (RR)

Coordinate conversions

Coordinate conversion	Activate	Cancel	
Zero point shift	G54 X+20 Y+30 Z+10	G54 X0 Y0 Z0	
Mirroring	G28 X	G28	
Rotation	G73 H+45	G73 H+0	
Scaling factor	G72 F 0.8	G72 F1	
Machining plane	G80 A+10 B+10 C+15	G80	
Machining plane	PLANE	PLANE RESET	

Q parameter definitions

Function
Q parameter: Assign
Q parameter: Addition
Q parameter: Subtraction
Q parameter: Multiplication
Q parameter: Division
Q parameter: Square root
Q parameter: Sine
Q parameter: Cosine
Q parameter: Root sum of squares $c = \sqrt{(a^2+b^2)}$
Q parameter: If equal, go to label number
Q parameter: If unequal, go to label number
Q parameter: If greater, go to label number
Q parameter: If less than, go to label number
Q parameter: Angle with ARCTAN (angle from c sin a and c cos a)
Q parameter: Error message
Q parameter: External output
Q parameter: Write file
Q parameter: Read system data
Q parameter: Send value to PLC

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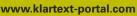
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help you reduce non-productive time and improve the dimensional accuracy of the finished workpieces.

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TS 440, TS 444	Infrared transmission
TS 640, TS 740	Infrared transmission

- Workpiece alignment
- Setting presets
- Workpiece measurement



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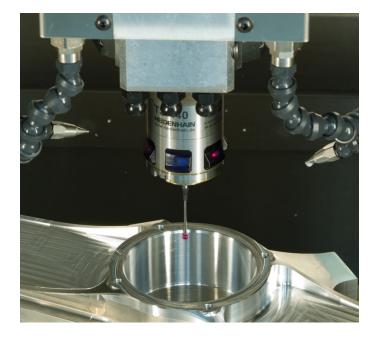
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Tool touch probes

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TT 449	Infrared transmission
TL	Non-contacting laser systems

- Tool measurement
- wear monitoring
- tool breakage detection



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