



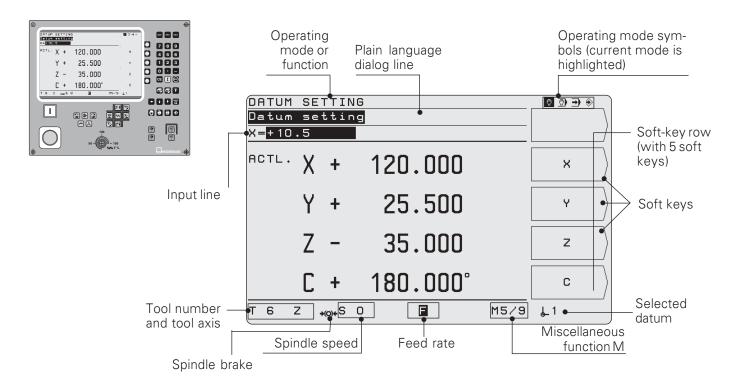
User's Manual

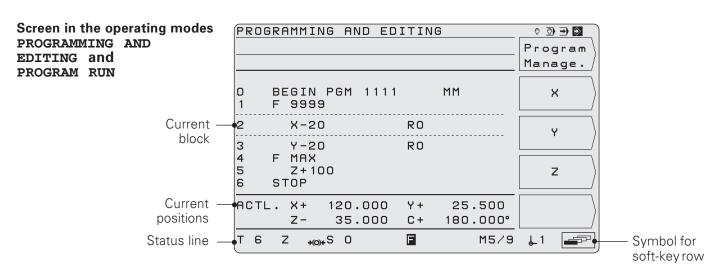
TNC Guideline:

From workpiece drawing to program-controlled machining

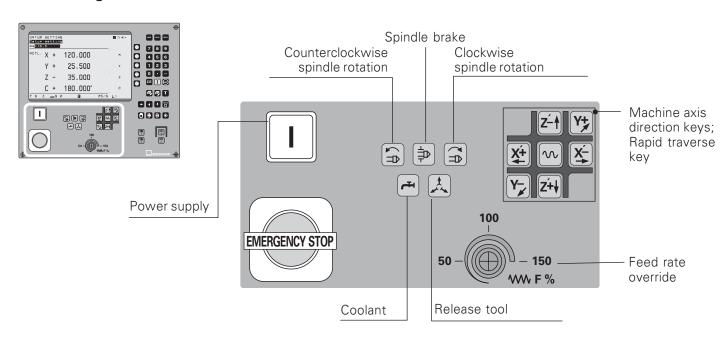
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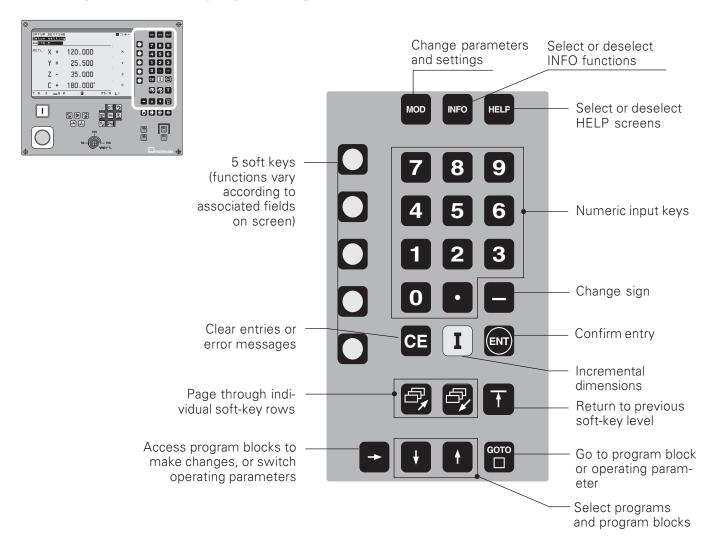




Controlling machine functions

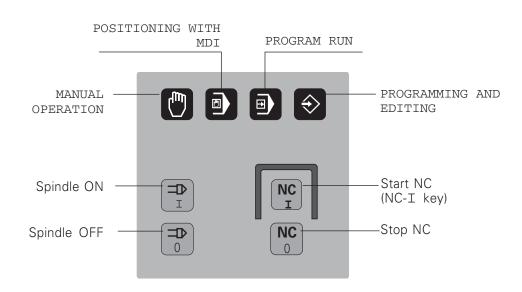


Selecting functions and programming



Selecting operating modes; Start or stop NC and spindle





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Software Version

This User's Manual is for TNC 124 models with the following software version:

Progr. 246 xxx-16.

The x's can be any numbers.



For detailed technical information refer to the Technical Manual for the TNC 124.

NC and PLC software numbers

The NC and PLC software numbers of your unit are displayed on the TNC screen after switch-on.

Location of use

The TNC complies with the limits for a Class A device in accordance with the specifications in EN 55022, and is intended for use primarily in industrially-zoned areas.

TNC 124

TNC family

What is NC? NC stands for "**N**umerical **C**ontrol," that is, control of a machine tool by means of numbers. Modern controls such as the TNC have a built-in computer for this purpose and are therefore called CNC (Computerized Numerical Control).

From the very beginning, the TNCs from HEIDENHAIN were developed specifically for shop-floor programming by the machinist. This is why they are called TNC, or "Touch Numerical Controls."

The **TNC 124** is a straight cut control for boring machines and milling machines with up to three axes. It also features position display of a fourth axis.

Conversational programming

Workpiece machining is defined in a part **program**. It contains a complete list of instructions for machining a part, for example, the target position coordinates, the feed rate and the spindle speed.

You begin programming each machining step by simply pressing a key or soft key. The TNC then asks for all the information that it needs to execute the step.

About This Manual

If you're new to TNC, you can use the operating instructions as a step-by-step workbook. This part begins with a short introduction to the basics of coordinate systems and position feedback, and provides an overview of the available features. Each feature is explained in detail, using an example — so you won't get "lost" too deeply in the theory. As a beginner you should work through all the examples presented.

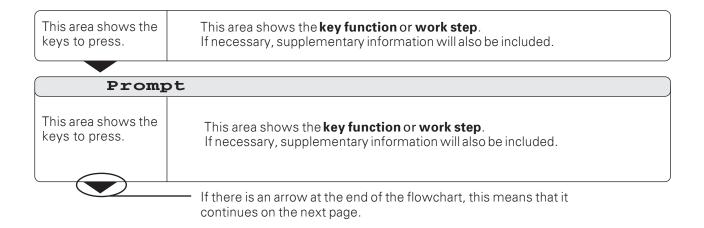
The **examples** are intentionally brief; it generally won't take you longer than 10 minutes to enter the example data.

If you're already proficient with TNC, you can use the operating instructions as a comprehensive review and reference guide. The clear layout and the subject index make it easy to find the desired topics.

Dialog flowcharts

Dialog flowcharts are used for each example in this manual. They are laid out as follows:

The **operating mode** is indicated above the first dialog flowchart.



A **prompt** appears with some actions (not always) at the top of the screen.

If two flowcharts are divided by a **broken line**, and words by "or," this means that you can follow either of the instructions.

Some flowcharts also show the screen that will appear after you press the correct keys.

Abbreviated flowcharts

Abbreviated flowcharts supplement the examples and explanations. An arrow (➤) indicates a new input or a work step.

Special Notes in this Manual

Particularly important information is presented separately in shaded boxes. Be sure to carefully pay attention to these notes. If you ignore these notes your TNC may not function as required, or damage the workpiece or tool.

Symbols used in the notes

Each note is identified by a symbol to the left. Your manual uses three different symbols which have the following meanings:



General note,

e.g., indicating the behavior of the control.



Note with reference to the **machine manufacturer**, e.g., indicating that a specific function must be enabled for your machine tool.



Important note,

e.g., indicating that a special tool is required for the function.

TNC Accessories

Electronic handwheel

Electronic handwheels facilitate precise manual control of the axis slides. Like a conventional machine tool, the machine slide moves in direct relation to the rotation of the handwheel. A wide range of traverses per handwheel revolution is available.



The HR 410 Electronic Handwheel

1

Fundamentals of Positioning

Coordinate system and coordinate axes

Reference system

In order to define positions on a surface, a reference system is required. For example, positions on the earth's surface can be defined "absolutely" by their geographic coordinates of longitude and latitude. The term coordinate comes from the Latin word for "that which is arranged." In contrast to the relative definition of a position that is referenced to a known location, the network of horizontal and vertical lines on the globe constitutes an absolute reference system.

The Greenwich observatory illustrated in Fig. 1.1 is located at 0° longitude, and the equator at 0° latitude.

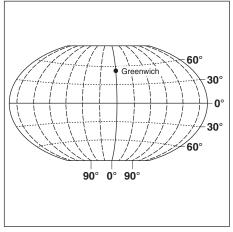


Fig. 1.1: The geographic coordinate system is an absolute reference system

Cartesian coordinate system

On a TNC-controlled milling or drilling machine tool, workpieces are normally machined according to a workpiece-based Cartesian coordinate system (a rectangular coordinate system named after the French mathematician and philosopher Renatus Cartesius, who lived from 1596 to 1650). The Cartesian coordinate system is based on three coordinate axes designated X, Y and Z which are parallel to the machine guideways.

The figure to the right illustrates the "right-hand rule" for remembering the three axis directions: the middle finger is pointing in the positive direction of the tool axis from the workpiece toward the tool (the Z axis), the thumb is pointing in the positive X direction, and the index finger in the positive Y direction.

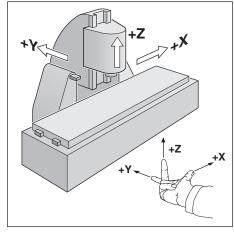


Fig. 1.2: Designations and directions of the axes on a milling machine

Axis designations

X, Y and Z are the main axes of the Cartesian coordinate system. The additional axes U, V and W are secondary linear axes parallel to the main axes. Rotary axes are designated as A, B and C (see Fig. 1.3).

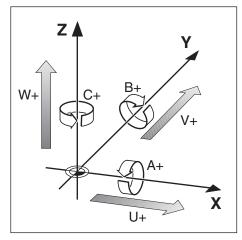


Fig. 1.3: Main, additional and rotary axes in the Cartesian coordinate system

Datums and positions

Setting the datum

The workpiece drawing identifies a certain point on the workpiece (usually a corner) as the "absolute datum" and perhaps one or more other points as relative datums. The datum setting procedure establishes these points as the origin of the absolute or relative coordinate systems: The workpiece, which is aligned with the machine axes, is moved to a certain position relative to the tool and the display is set either to zero or to another appropriate value (e.g., to compensate the tool radius).

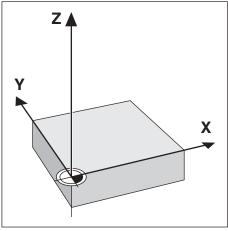


Fig. 1.4: The workpiece datum represents the origin of the Cartesian coordinate system

Example: Coordinates of hole ①:

X = 10 mmY = 5 mm

Z = 0 mm (hole depth: Z = -5 mm)

The datum of the Cartesian coordinate system is located 10 mm from hole ① on the X axis and 5 mm from it in the Y axis (in negative direction).

The TNC's probing functions facilitate finding and setting datums.

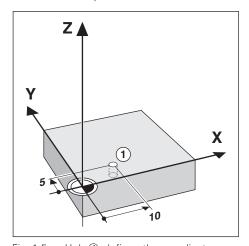


Fig. 1.5: Hole ① defines the coordinate system

Datums and Positions

Absolute workpiece positions

Each position on the workpiece is uniquely identified by its absolute coordinates.

Example: Absolute coordinates of the position ①:

X = 20 mm Y = 10 mmZ = 15 mm

If you are drilling or milling a workpiece according to a workpiece drawing with absolute coordinates, you are moving the tool**to** the value of the coordinates.

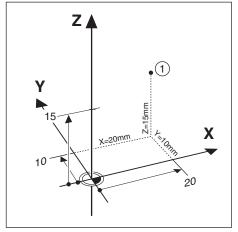


Fig. 1.6: Position definition through absolute coordinates

Incremental workpiece positions

A position can also be referenced to the preceding nominal position. In this case the relative datum is always the last programmed position. Such coordinates are referred to as **incremental coordinates** (increment = increase). They are also called incremental or chain dimensions (since the positions are defined as a chain of dimensions). Incremental coordinates are designated with the prefix **I**.

Example: Incremental coordinates of position ③ referenced to position ②

Absolute coordinates of position ②:

X = 10 mm Y = 5 mmZ = 20 mm

Incremental coordinates of position (3):

 $\mathbf{I}X = 10 \text{ mm}$ $\mathbf{I}Y = 10 \text{ mm}$ $\mathbf{I}Z = -15 \text{ mm}$

If you are drilling or milling a workpiece according to a drawing with incremental coordinates, you are moving the tool ${\bf by}$ the value of the coordinates.

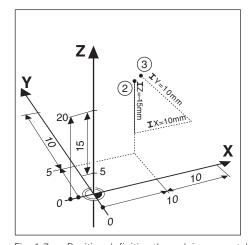


Fig. 1.7: Position definition through incremental coordinates

Machine axis movements and position feedback

Programming tool movements

During workpiece machining, an axis position is changed either by moving the tool or by moving the machine table on which the workpiece is fixed.



When entering tool movements in a part program you always program as if the tool is moving and the workpiece is stationary.

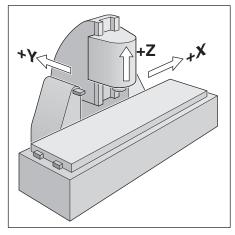


Fig. 1.8: On this machine the tool moves in the Y and Z axes; the workpiece moves in the X axis.

Z

Fig. 1.9: Linear position encoder, here for the X axis

Position feedback

The position feedback encoders — linear encoders for linear axes, angle encoders for rotary axes — convert the movement of the machine axes into electrical signals. The control evaluates these signals and constantly calculates the actual position of the machine axes.

If there is an interruption in power, the calculated position will no longer correspond to the actual position. When power is restored, the TNC can re-establish this relationship.

Reference marks

The scales of the position encoders contain one or more reference marks. When a reference mark is passed over, it generates a signal which identifies that position as the reference point (scale reference point = machine reference point). With the aid of this reference mark the TNC can re-establish the assignment of displayed values to machine axis positions.

If the position encoders feature **distance-coded** reference marks, each axis need only move a maximum of 20 mm (0.8 in.) for linear encoders, and 20° for angle encoders.

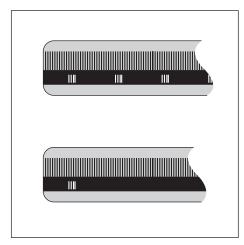


Fig. 1.10: Linear scales: above with distancecoded reference marks, below with one reference mark

Angular positions

For angular positions, the following reference axes are defined:

Plane	Angle reference axis	
X / Y	+ X	
Y / Z	+ Y	
Z/X	+ Z	

Algebraic sign for direction of rotation

Positive direction of rotation is counterclockwise if the working plane is viewed in negative tool axis direction (see Fig. 1.11).

Example: Angle in the working plane X / Y

Angle	Corresponds to the
+ 45°	bisecting line between +X and +Y
± 180°	negative X axis
- 270°	positive Y axis

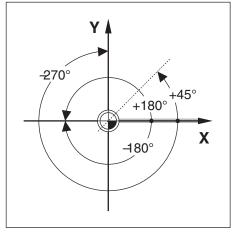
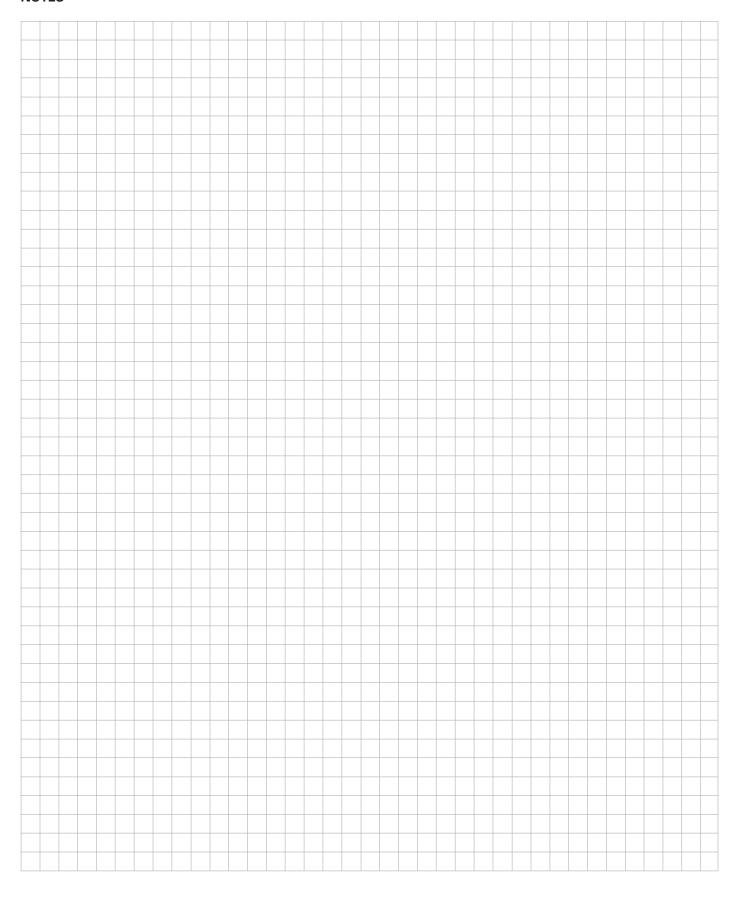


Fig. 1.11: Angle and the angle reference axis, here in the X / Y plane

NOTES



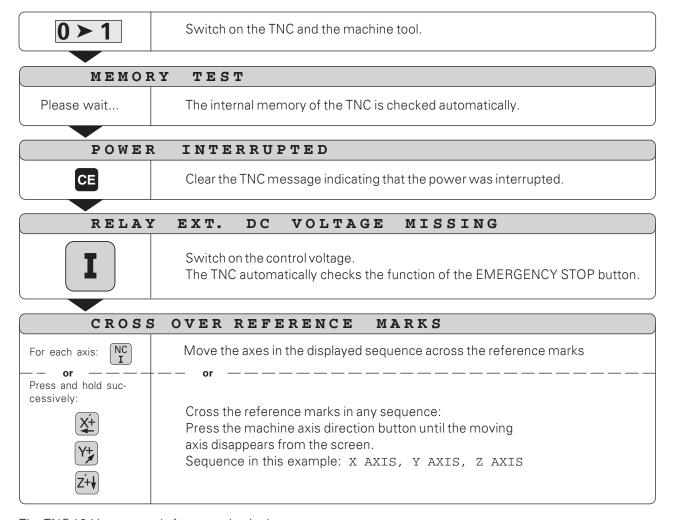
2 Working with the TNC 124 – First Steps

Before you start

You must **cross over the reference marks** after every switch-on. From the positions of the reference marks, the TNC automatically reestablishes the relationship between axis slide positions and display values that you last defined by setting the datum.

Setting up a new datum point automatically stores the new relationship between axis positions and display values.

Switch-on



The TNC 124 is now ready for operation in the MANUAL OPERATION mode.

Operating modes

Available functions	Mode	Key
Move the machine axes with the direction keys, with the electronic hand- wheel, by incremental jog positionir Datum setting — also with probing functions (e.g. circle center as datum); Enter and change spindle spee and miscellaneous functions		
Enter positioning blocks and execute them block by block; Enter hole patterns and execute them block by block; Change spindle speed, feed rate, miscellaneous functions; Enter tool data;	POSITIONING WITH MDI	
Store work steps for small-lot production by Keyboard entry Teach-in; Transferring programs through the data interface	PROGRAMMING AND EDITING	♦
Executing programscontinuouslyblockwise	PROGRAM RUN	

You can switch to another operating mode at **any time** by pressing the key for the desired mode.

HELP, MOD and INFO functions

You can call the HELP, MOD and INFO functions at any time.

To **call** a function:

> Press the function key for that function.

To **leave** a function:

➤ Press the same function key again.

Functions	Designation	Key
On-screen operating instructions: graphics and text explaining the current screen contents	HELP	HELP
User parameters: To redefine the TNC's basic operating characteristics	MOD	MOD
Cutting data calculator, stopwatch, pocket calculator	INFO	INFO

Selecting soft-key functions

The soft-key functions are grouped into one or more rows. The TNC indicates the number of rows by a symbol at the bottom right of the screen.

If no symbol is visible, that means that all pertinent functions are already shown. The highlighted rectangle in the symbol indicates the current row.

Overview of functions

Function	Key
Page through the soft-key rows: forwards	母
Page through the soft-key rows: backwards	P
Go back one soft-key level	



The TNC displays the soft keys with the main functions of an operating mode whenever you press the key for that mode.

Fig. 2.1: The symbol for soft-key rows at the bottom right of the screen.

Here, the first row is being displayed.

Symbols on the TNC screen

The TNC continuously informs you of the current operating status. The symbols are displayed on the screen

- next to the designations of the coordinate axes or
- in the status line at the bottom of the screen.

Symbol	Function/Meaning
T	Tool, for example T 1
S *)	Spindle speed, e.g. S 1000 [rpm]
F *)	Feed rate, e.g. F 200 [mm/min]
M	Miscellaneous function, e.g. M 3
+	Datum, e.g.: ↓ 1
ACTL.	TNC displays actual values
NOML.	TNC displays nominal values
REF	TNC displays the reference position
LAG	TNC displays the servo lag
*	Control active
\rightarrow t \bigcirc r \leftarrow	Spindle brake active
$\leftarrow (\bigcirc) \rightarrow$	Spindle brake inactive
\bigcirc	Axis can be moved with the electronic handwheel

^{*}A **highlighted F or S symbol** means that the feed rate or spindle has not been enabled by the PLC.

On-screen operating instructions

The integrated operating instructions provide information and assistance in any situation.

To **call** the operating instructions:

- ➤ Press the HELP key.
- Use the paging keys if the explanation extends over more than one screen page.

To **leave** the operating instructions:

> Press the HELP key again.

Example: On-screen operating instructions for datum setting (PROBE CENTERLINE)

The PROBE CENTERLINE function is described in this manual on page 34.

- ➤ Select the MANUAL OPERATION mode.
- Press the paging key to display the second screen page.
- ➤ Press the HELP key.

The first page of the operating instructions for the probing functions appears.

Page reference at the lower right of the screen:

the number in front of the slash is the current page, the number behind the slash is the total number of pages.

The on-screen operating instructions now contain the following information on PROBING FUNCTIONS (on three pages):

- Overview of the probing functions (page 1)
- Graphic illustration of all probing functions (pages 2 and 3)
- ➤ To leave the operating instructions:

Press HELP again.

The screen returns to the menu for the probing functions.

- ➤ Press (for example) the soft key Centerline.
- > Press HELP.

The screen now displays operating instructions — spread over three pages — on the function PROBE CENTERLINE including:

- Overview of all work steps (page 1)
- Graphic illustration of the probing sequence (page 2)
- Information on how the TNC reacts and on datum setting (page 3)
- ➤ To leave the on-screen operating instructions: Press HELP again.

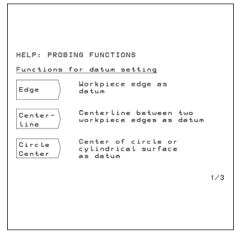


Fig. 2.2: On-screen operating instructions for PROBE, page 1



Fig. 2.3: On-screen operating instructions for PROBE CENTERLINE, page 1

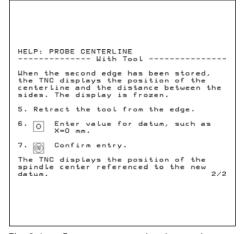


Fig. 2.4: On-screen operating instructions for PROBE CENTERLINE, page 2

Error messages

If an error occurs while you are working with the TNC, a message will come up on the screen.

To call an explanation of the error:

➤ Press the **HELP key**.

To **clear** the error message:

➤ Press the **CE** key.

Blinking error messages



WARNING!

Blinking error messages mean that the operational reliability of the TNC has been impaired.

If a blinking error message occurs:

- ➤ Note down the error message displayed on the screen.
- > Switch off the TNC and machine tool.
- > Attempt to correct the problem with the power off.
- ➤ If the error cannot be corrected or if the blinking error message recurs, notify your customer service agency.

Selecting the unit of measurement

Positions can be displayed in millimeters or inches. If you choose inches, inch will be displayed at the top of the screen.

To **change** the unit of measurement:

- > Press MOD.
- ➤ Page to the soft-key row containing the user parameter mm or inch.
- ➤ Choose the soft key mm or inch to change to the other unit.
- ➤ Press MOD again.

For more information on user parameters, see Chapter 13.

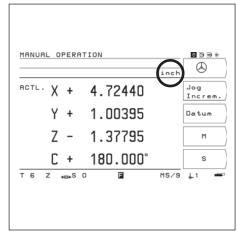


Fig. 2.5: The inch indicator

Selecting position display types

The TNC can display various position values for a specific tool position.

The positions indicated in Fig. 2.6 are:

- Starting position of the tool (A)
- Target position of the tool 2
- Workpiece datum (W
- Scale reference point (M)

The TNC position display can be set to show the following types of information:

- Nominal position NOML. 1
 The value presently commanded by the TNC.
- Actual position ACTL. ②
 The position at which the tool is presently located as referenced to the workpiece datum.
- Servo lag LAG(3)
 The difference between nominal and actual positions (NOML. ACTL.)
- Actual position as referenced to the scale reference point REF (4)

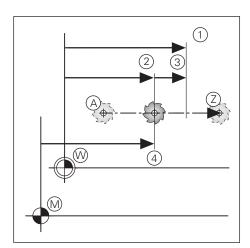


Fig. 2.6: Tool and workpiece positions

To change the position display

- ➤ Press MOD.
- Page to the soft-key row containing the user parameter Posit.
- Press the soft key for selecting the position display type and change to the other display type.
- ➤ Select the desired display type.
- ➤ Press MOD again.

For more information on user parameters, see Chapter 13.

Traverse limits

The maximum range of traverse of the machine axes is set by the machine manufacturer.

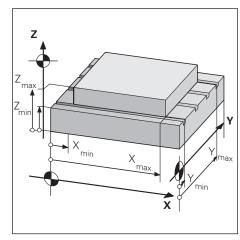


Fig. 2.7: Traverse limits define the machine's actual working envelope



3

Manual Operation and Setup



The machine manufacturer may define a method of moving the axes that varies from what is described in this manual.

On the TNC 124 you can move the machine axes with:

- the direction keys,
- the electronic handwheel,
- incremental jog positioning, or
- positioning with manual data input MDI (see Chapter 4).

In the MANUAL OPERATION and POSITIONING WITH MDI modes of operation (see Chapter 4) you can also enter and change:

- Feed rate F (the feed rate can only be entered in POSITIONING WITH MDI)
- Spindle speed S
- Miscellaneous function M

Feed rate F, spindle speed S and miscellaneous function M

To change the feed rate F:

You can vary the feed rate F infinitely by turning the knob for feed rate override on the TNC control panel.

Feed rate override You can vary the feed rate F from 0% to 150% of the set value

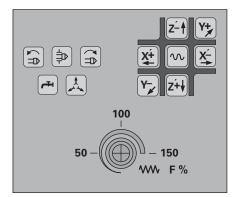
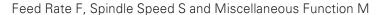


Fig. 3.1: Feed rate override on the TNC control panel

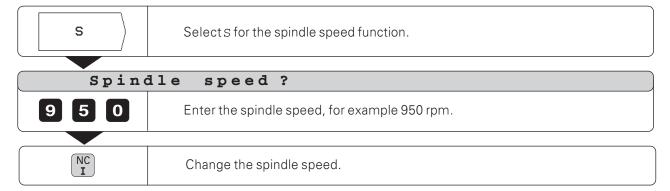




Entering and changing the spindle speed S

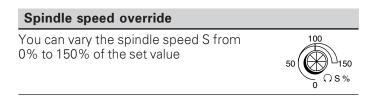
The machine manufacturer determines which spindle speeds are allowed on your TNC.

Example: Entering the spindle speed S



To change the spindle speed S:

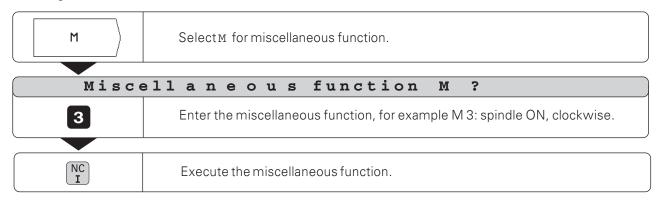
You can vary the spindle speed S infinitely by turning the knob for spindle speed override—if provided—on the TNC control panel.



Entering a miscellaneous function M



Example: Entering a miscellaneous function





Moving the machine axes

The TNC control panel includes six direction keys. The keys for the X and Y axes are identified with a prime mark (X', Y'). This means that the traversing directions indicated on these keys correspond to movement of the machine table.

Traversing with the direction keys

The direction key defines at the same time

- the coordinate axis, for example X
- the traversing direction, for example negative: X-

On machine tools with **central drives** you can only move one axis at a time.

If you are moving a machine axis with the direction key, the TNC automatically stops moving the axis as soon as you release the key.

For continuous movement:

You can also move the machine axes continuously: The axis continues to move after you release the key. To stop the axis press the key indicated below in example 2.

Rapid traverse

To move an axis at rapid traverse:

➤ Press the rapid traverse key and the direction key together.

Example: Moving the machine axis in the Z+ direction with the direction key (retract tool):

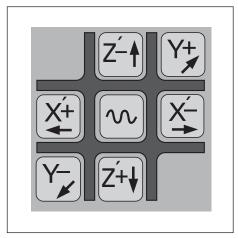
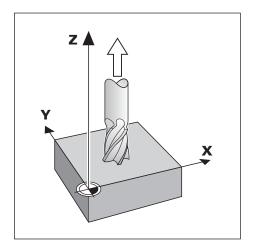


Fig. 3.2: The direction keys on the TNC control panel, with the key for rapid traverse in the center



Example 1: Moving the machine axes

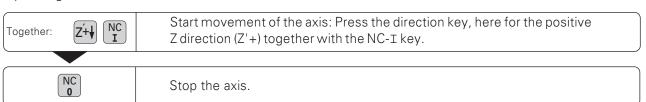
Operating mode: MANUAL OPERATION

Press and hold: Z++

Press the direction key, here for the positive Z direction (Z'+) and hold it as long as you wish the axis to move.

Example 2: For continuous movement of the machine axes

Operating mode: MANUAL OPERATION



Moving the Machine Axes



Traversing with the electronic handwheel

Electronic handwheels can be connected only to machines with preloaded drives. The machine manufacturer can tell you whether electronic handwheels can be connected on your machine.

You can connect the following HEIDENHAIN electronic handwheels to your TNC 124:

- HR 410 portable handwheel
- HR 130 integral handwheel

Direction of traverse

The machine manufacturer determines in which direction the handwheel must be turned to move an axis in a specific direction.

If you are working with the HR 410 portable handwheel

The HR 410 portable handwheel is equipped with two permissive buttons ③. You can move the machine axes with the handwheel ② only if a permissive button is depressed.

Other features of the HR 410:

- Axis selection keys X, Y and Z @ .
- The axes can be moved continuously with the + and direction keys ?
- Three keys for slow, medium and fast traverse 6.
- Actual-position-capture key ⑤ for transferring positions or tool data in teach-in mode directly from the position display into the program or tool table (without having to type the numbers).
- Three keys for machine functions ® defined by the machine tool builder
- EMERGENCY STOP button ① for immediate machine shutdown in case of danger. This safety feature is additional to the permissive buttons.
- Magnetic holding pads on the back of the handwheel enable you to place it within easy reach on a flat metal surface.

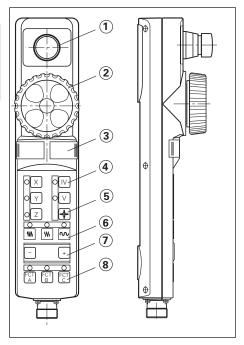
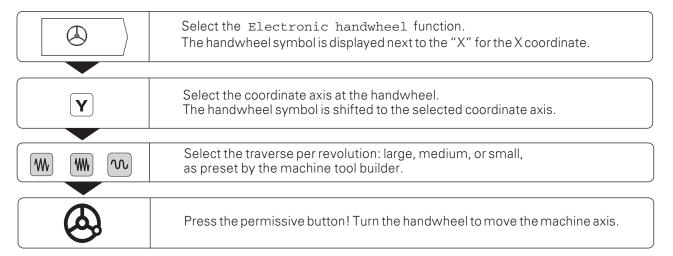


Fig. 3.3: The HR 410 portable electronic handwheel

Example: Moving a machine axis with the HR 410 electronic handwheel, for example the Y axis

Operating mode: MANUAL MODE



Moving the Machine Axes



Incremental jog positioning

Incremental jog positioning enables you to move a machine axis by the increment you have preset each time you press the corresponding direction key.

Current jog increment

If you enter a jog increment, the TNC stores the entered value and displays it right of the highlighted input line for Infeed.

The programmed jog increment is effective until a new value is entered by keyboard or soft key.

Maximum input value

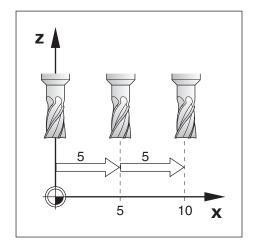
0.001 mm≤jog increment≤99.999 mm

Changing the feed rate F

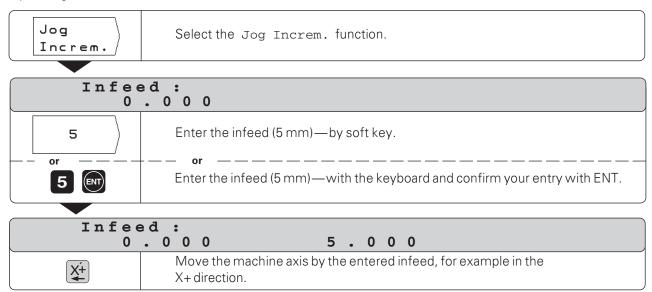
You can increase or decrease the feed rate F by turning the knob for feed rate override.

Fig. 3.4: TNC screen for incremental jog positioning

Example: Moving the machine axis in the X+ direction by incremental jog positioning



Operating mode: MANUAL OPERATION



MOE

Entering tool length and radius

Enter the lengths and radii of your tools in the TNC's tool table. The TNC will then take the entered data into account for datum setting and all other machining processes.

You can enter up to 99 tools.

The tool length is the difference in length ΔL between the tool and the zero tool.

To enter the tool length directly move the tool until it touches the workpiece and transfer the tool position coordinate by using the "actual position capture" function.

Sign for the length difference ΔL

If the tool is **longer** than the zero tool: $\Delta L > 0$ If the tool is **shorter** than the zero tool: $\Delta L < 0$

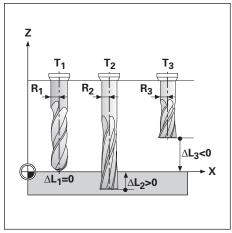
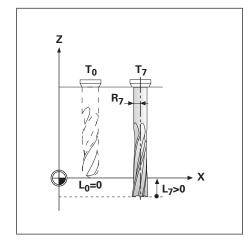


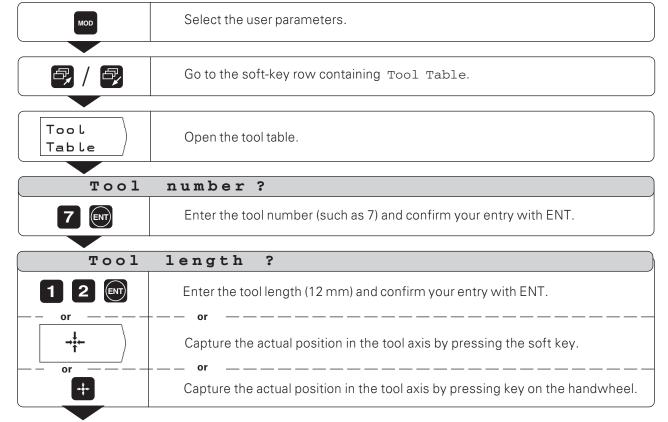
Fig. 3.5: Tool length and radius

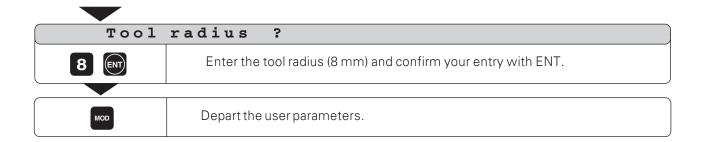
Example: Entering the tool length and radius into the tool table

Tool number: e.g. 7

Tool length: L = 12 mmTool radius: R = 8 mm







Calling the tool data

The lengths and radii of your tools must first be entered into the TNC's tool table (see previous page).

Before you start workpiece machining, select the tool you are using from the tool table. To call the desired tool, move the highlight to the tool, select the axis with the corresponding soft key and press the soft key Tool Table.

The TNC then takes into account the stored tool data when you work with tool compensation (e.g., with hole patterns).



You can also call the tool data with the command TOOL CALL in a program.

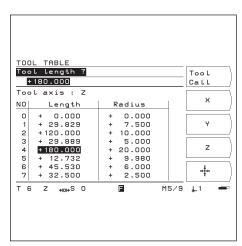
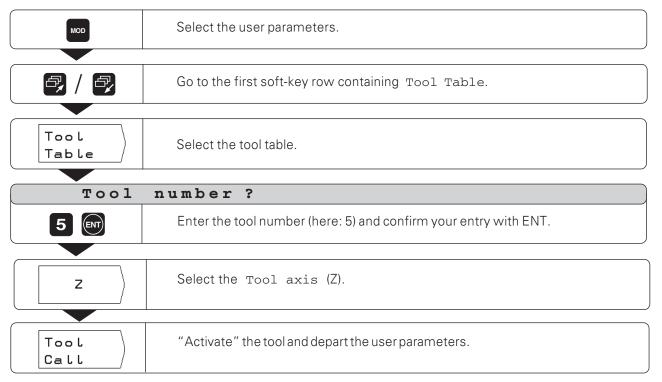


Fig. 3.6: The tool table on the TNC screen

Example: Calling the tool data



MOD

Selecting datum points

The TNC 124 can store up to 99 datum points in a datum table. In most cases this will free you from having to calculate the axis travel when working with complicated workpiece drawings containing several datums, or when several workpieces are clamped to the machine table at the same time.

For each datum point, the datum table contains the positions that the TNC 124 assigned to the reference point on the scale of each axis (REF values) during datum setting. Note that if you change the REF values in the table, this will move the datum point.

The TNC 124 displays the number of the current datum at the lower right of the screen.

To select the datum:

In all operating modes:

- Press MOD and go to the soft key row containing Datum Table.
- ➤ Choose the soft key Datum Table.
- > Select the datum you are using from the datum table.
- ➤ Leave the datum table: Press MOD again.

In the MANUAL OPERATION and POSITIONING WITH MDI modes of operation:

> Press the vertical arrow keys.



The machine manufacturer determines whether "quick datum selection" via arrow keys is enabled on your TNC.

In the PROGRAMMING AND EDITING / PROGRAM RUN modes of operation:

➤ You can also select a datum point by entering the command "DATUM" in a program.



Datum setting: Approaching positions and entering actual values

The easiest way to set datum points is to use the TNC's probing functions. A description of the probing functions starts on page 33.

Of course, you can also set datum points in the conventional manner by touching the edges of the workpiece one after the other with the tool and entering the tool positions as datum points (see examples on this page and the next).

Example: Setting a workpiece datum without the probing function

Working plane: X / Y

Tool axis: Z

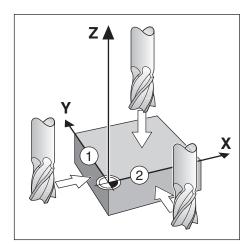
Tool radius: R = 5 mm

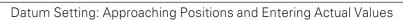
Axis sequence in

this example: X - Y - Z

Preparation

- ➤ Select the desired datum point (see "Selecting datum points").
- ➤ Insert the tool.
- Press MOD and go to the soft-key row containing Tool Table.
- ➤ Select the user parameter Tool Table.
- ➤ Select the tool you will use to set the datum.
- ➤ Leave the tool table: Press the soft key Tool Call.
- ➤ Activate the spindle, for example with the miscellaneous function M3.





Operating mode: MANUAL OPERATION

operating mode. Innvers	
Datum	Select the Datum function.
x	Select the X axis.
<u>&</u>	Touch edge ① with the tool.
Datum X = + 0	setting
- 5 ENT	Enter the position of the tool center (X = -5 mm) and transfer the X coordinate of the datum.
Y	Select the Y axis.
	Touch edge ② with the tool.
Datum Y = -5	setting
ENT	Transfer the Y coordinate of the datum.
z	Select the Z axis.
	Touch the workpiece surface.
Datum Z = - 5	setting
O ENT	Enter the position of the tool tip (Z = 0 mm) and transfer the Z coordinate of the datum.



Functions for datum setting

It is very easy to set datum points with the TNC's probing functions. These functions do not require a touch probe system or an edge finder since you simply probe the workpiece edges with the tool.

The following probing functions are available:

Workpiece edge as datum:

Edge

Centerline between two workpiece edges:

Centerline

• Center of a hole or cylinder:

Circle Center

With Circle Center, the hole must be in a main plane. The three main planes are formed by the axes X/Y, Y/Z and Z/X.

Preparations for all probing functions

- ➤ Select the desired datum point (see "Selecting datum points").
- ➤ Insert the tool.
- Press MOD and go to the soft-key row containing Tool Table.
- ➤ Select the user parameter Tool Table.
- > Select the tool you will use to set the datum.
- ➤ Leave the tool table: Press the soft key Tool Call.
- ➤ Activate the spindle, for example with the miscellaneous function M3.

To abort the probing function

While the probing function is active, the TNC displays the soft key Escape. Choose this soft key to return to the opening state of the selected probing function.

Measuring diameters and distances

With the probing function Centerline the TNC calculates the distance between the two probed edges of a workpiece; with the Circle Center function it determines the diameter of the probed circle

The calculated distance and diameter are displayed on the TNC screen between the position displays.

If you want to measure the distance between two edges or a diameter **without** setting a datum:

- ➤ Probe the workpiece as described on page 35 (Centerline) and page 36 (Circle Center).
 - As soon as the TNC displays the distance or diameter:
- ➤ **Do not** enter a datum coordinate. Simply press the soft key Escape.

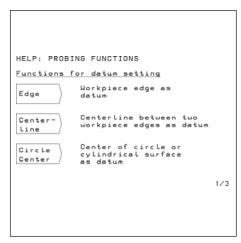


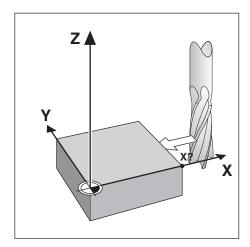
Fig. 3.7: On-screen operating instructions for the probing functions



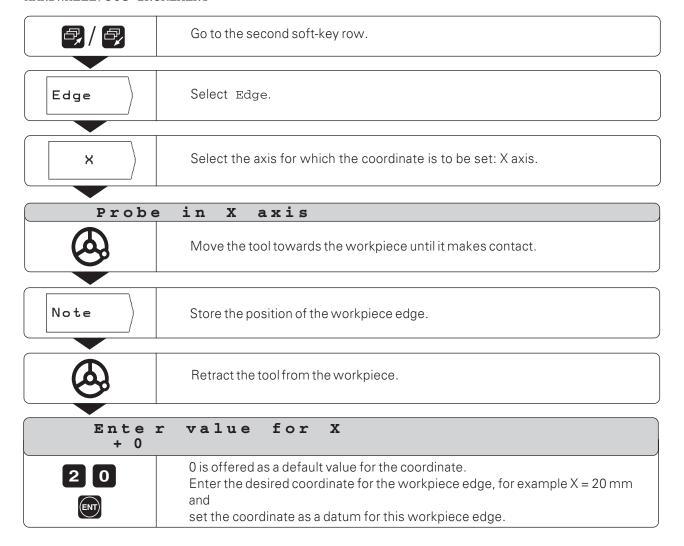
Example: Probe workpiece edge, display position of workpiece edge and set the edge as a datum

The probed edge lies parallel to the Y axis.

The coordinates of the datum can be set by probing edges or surfaces and capturing them as datums as described below.



Operating modes: MANUAL OPERATION/ELECTRONIC HANDWHEEL/JOG INCREMENT





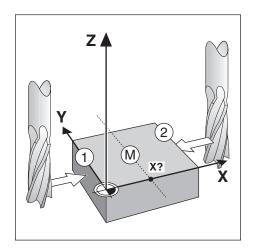
Example: Set centerline between two workpiece edges as datum

The position of the centerline $\[Mathemath{\mathbb{M}}\]$ is determined by probing the edges $\[Mathemath{\mathbb{1}}\]$ and $\[Mathemath{\mathbb{2}}\]$.

The centerline is parallel to the Y axis.

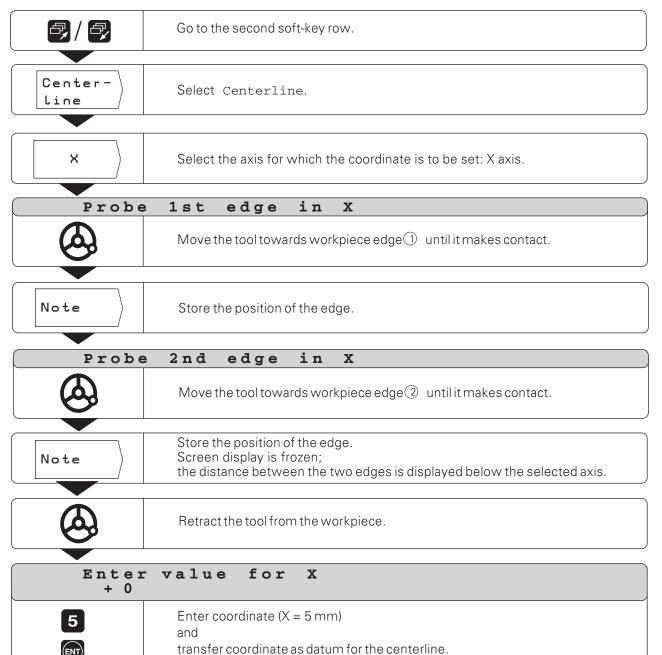
Desired coordinate

of the centerline: X = 5 mm



Operating modes: MANUAL OPERATION/ELECTRONIC

HANDWHEEL/JOG INCREMENT



Functions for Datum Setting



Example: Probe the circumference of a hole and set the center of the hole as a datum

X/Y plane Main plane:

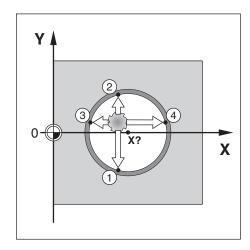
Tool axis: Ζ

X coordinate of the

X = 50 mmcircle center:

Y coordinate of

circle center: 0 mm



Operating mode: MANUAL OPERATION/ELECTRONIC HANDWHEEL/JOG INCREMENT



Go to the second soft-key row.

Circle Center

Select Circle Center.

Plane X / Y

Select plane containing the circle (main plane): Plane X/Y.



Probe 1 s t poin t in X / Y

Move tool towards first point on the circumference until it makes contact.

Note

Store position of the bore hole wall.



Retract tool from bore hole wall.



Probe three additional points on the circumference in the same manner. Further information appears on the screen. Store positions with Note.



Enter center point X X = 0



Enter first coordinate (X = 50 mm)

and

transfer coordinate as datum for the circle center.

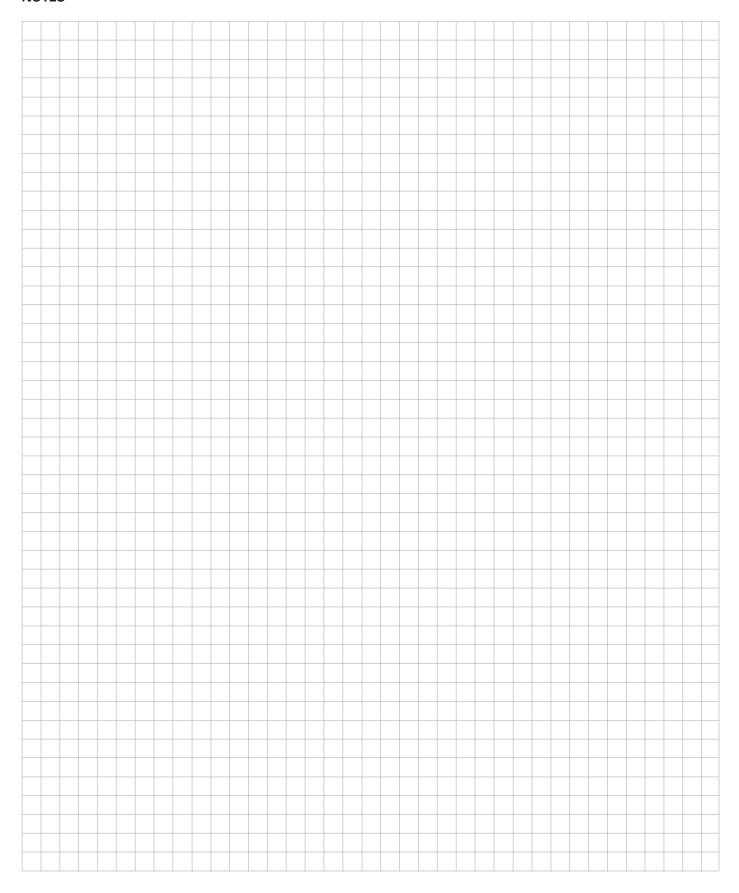


Enter center point Y = 0



Accept default entry Y = 0 mm.

NOTES





4

Positioning with Manual Data Input (MDI)

For many simple machining processes, for example if a machining process is to be executed only once, or if you are machining simple geometrical shapes, it would be too time-consuming to enter the individual machining steps in an NC program.

In the POSITIONING WITH MDI mode of operation you can enter all data directly instead of storing them in a part program.

Simple milling and drilling operations

Enter the following nominal position data manually in the POSITIONING WITH MDI mode of operation:

- Coordinate axis
- Position value
- Radius compensation

The TNC then moves the tool to the desired position.

Pecking and tapping, hole patterns, rectangular pocket milling

The POSITIONING WITH MDI mode of operation also supports the TNC "Cycles" (see Chapter 7):

- Pecking
- Tapping
- Bolt hole circle patterns
- Linear hole patterns
- Rectangular pocket

Before you machine the workpiece

- ➤ Select the desired datum point (see "Selecting datum points").
- ➤ Insert the tool.
- ➤ Pre-position the tool to prevent the possibility of damaging the tool or workpiece.
- ➤ Select an appropriate feed rate F.
- > Select an appropriate spindle speed S.

Taking the tool radius into account

The TNC can compensate for the tool radius (see Fig. 4.1). This allows you to enter workpiece dimensions directly from the drawing. The remaining distance is then automatically lengthened (R+) or shortened (R-) by the tool radius.

Entering tool data

- ➤ Press MOD.
- ➤ Choose the soft key Tool Table.
- ➤ Enter the tool number.
- ➤ Enter the tool length.
- ➤ Enter the tool radius.
- > Select the tool axis via soft key.
- ➤ Press the Tool Call soft key.

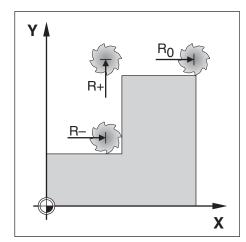


Fig. 4.1: Tool radius compensation



Feed rate F, spindle speed S and miscellaneous function M

In the POSITIONING WITH MDI mode of operation you can also enter and change the following information:

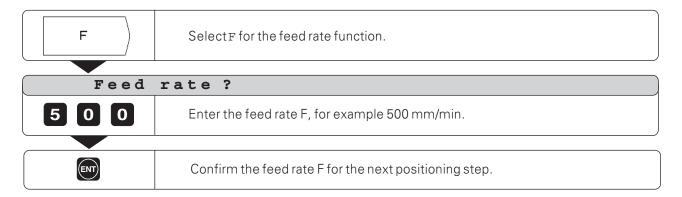
- Feed rate F
- Spindle speed S
- Miscellaneous function M

Feed rate F after an interruption of power

If you have entered a feed rate F in the POSITIONING WITH MDI mode of operation, the TNC will move the axes with this feed rate after an interruption of power as soon as power is restored.

Entering and changing the feed rate F

Example: Entering the feed rate F



Changing the feed rate F

You can vary the feed rate F infinitely by turning the knob for feed rate override on the TNC control panel.

Feed rate override You can vary the feed rate F from 0% to 150 % of the entered value.

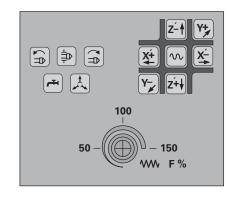


Fig. 4.2: Knob for feed rate override on the TNC control panel

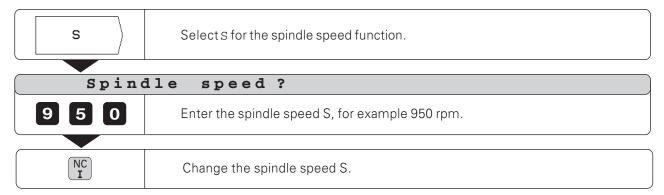
Feed Rate F, Spindle Speed S and Miscellaneous Function M



Entering and changing the spindle speed S

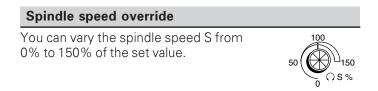
The machine manufacturer determines which spindle speeds are allowed on your TNC.

Example: Entering the spindle speed S



To change the spindle speed S:

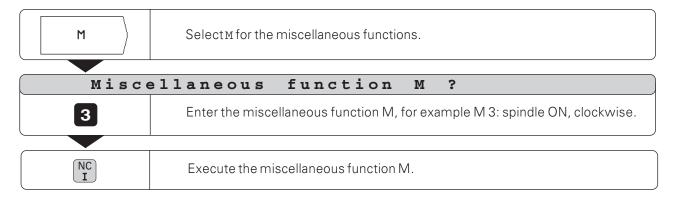
You can vary the spindle speed S infinitely by turning the knob for spindle speed override—if provided—on the TNC control panel.



Entering a miscellaneous function M



Example: Entering a miscellaneous function





Entering and moving to positions

For simple machining operations, you can program the coordinates directly in the POSITIONING WITH MDI mode of operation.

Example: Milling a shoulder

The coordinates are entered as absolute dimensions; the datum is the workpiece zero.

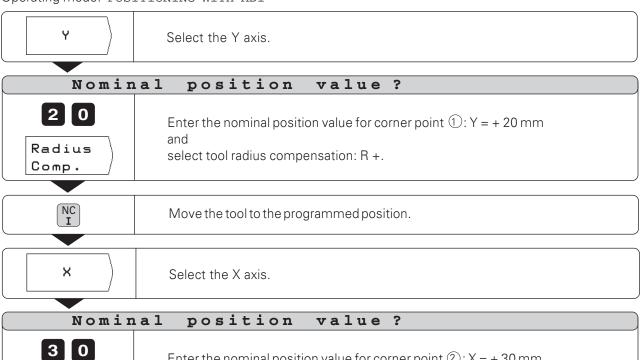
Corner ①: X = 0 mm Y = 20 mmCorner ②: X = 30 mm Y = 20 mmCorner ③: X = 30 mm Y = 50 mmCorner ④: X = 60 mm Y = 50 mm

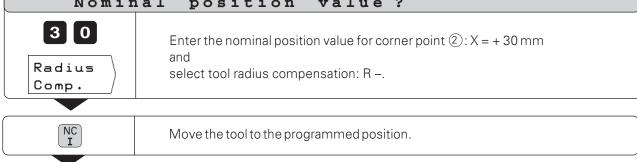
Preparation:

- ➤ Select the desired datum point (see "Selecting datum points").
- ➤ Enter the tool data.
- ➤ Pre-position the tool to an appropriate location (such as X = Y = -20 mm).
- ➤ Move the tool to milling depth.

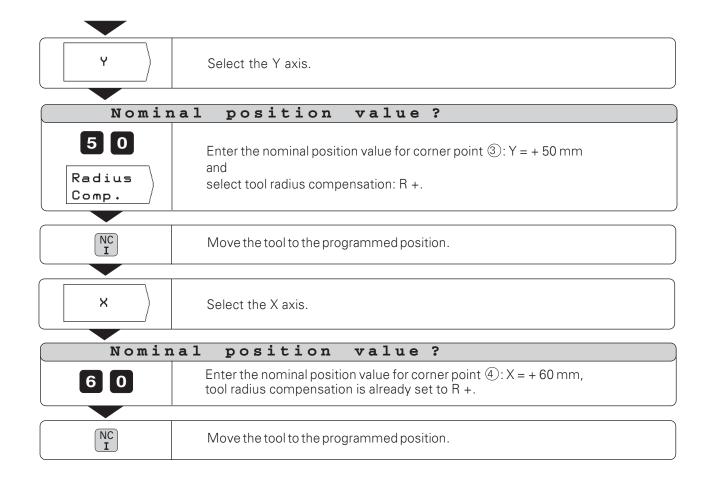
3 0 1 2 0 0 0 0 0 0 0 0 0 0

Operating mode: POSITIONING WITH MDI





Entering and Moving to Positions





Pecking and tapping

The TNC cycles for pecking and tapping (see Chapter 7) are available in the POSITIONING WITH MDI mode of operation.

Use the soft keys on the second soft-key row to select the desired type of hole and enter the required data. These data can usually be taken from the workpiece drawing (hole depth, infeed depth, etc.).

The TNC controls the machine tool and calculates additional data such as the advanced stop distance if the hole is to be drilled in several infeeds.

Pecking and tapping in hole patterns

The functions for pecking and tapping are also available in combination with the hole pattern functions Circle Pattern and Linear Pattern.

Pecking and tapping processes

The input data for pecking and tapping can also be entered as "cycles" in a part program. You will find detailed information on how the TNC controls pecking and tapping operations in Chapter 7. (See page 79 for pecking and page 82 for tapping).

Pre-positioning the drill for pecking and tapping

Pre-position the drill in the Z axis to a position above the workpiece. In the X and Y axes (working plane), pre-position the drill to the hole position. The hole position is approached without radius compensation (input R0).

Input data for pecking

- Clearance height at which the drill can traverse in the working plane without damaging the workpiece;
 Enter an absolute value together with the algebraic sign.
- Setup clearance at which the drill is located above the workpiece.
- Coordinate of the workpiece surface;
 Enter an absolute value together with the algebraic sign.
- Hole depth; the algebraic sign determines the working direction.
- Infeed depth
- Dwell time of the drill at the bottom of the hole.
- Machining feed rate

Input data for tapping

- Clearance height at which the drill can traverse in the working plane without damaging the workpiece;
 - Enter an absolute value together with the algebraic sign.
- Setup clearance at which the drill is located above the workpiece.
- Coordinate of the workpiece surface; Enter an absolute value together with the algebraic sign.
- Hole depth; the algebraic sign determines the working direction.
- Dwell time of the drill at the end of thread.
- Machining feed rate



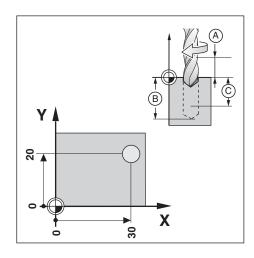
Example: PECKING

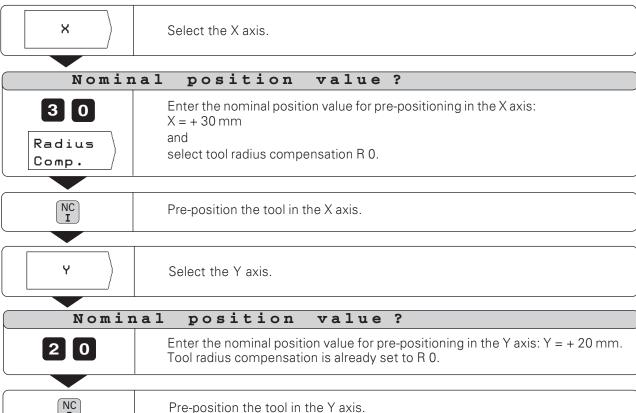
X coordinate of the hole: 30 mm Y coordinate of the hole: 20 mm Clearance height: + 50 mm Setup clearance (A): 2 mm Workpiece surface: +0 mm Hole depth (B): – 15 mm Pecking depth ©: 5 mm Dwell time: $0.5 \, s$ 80 mm/min Pecking feed rate: e.g. 6 mm Hole diameter:

Preparation

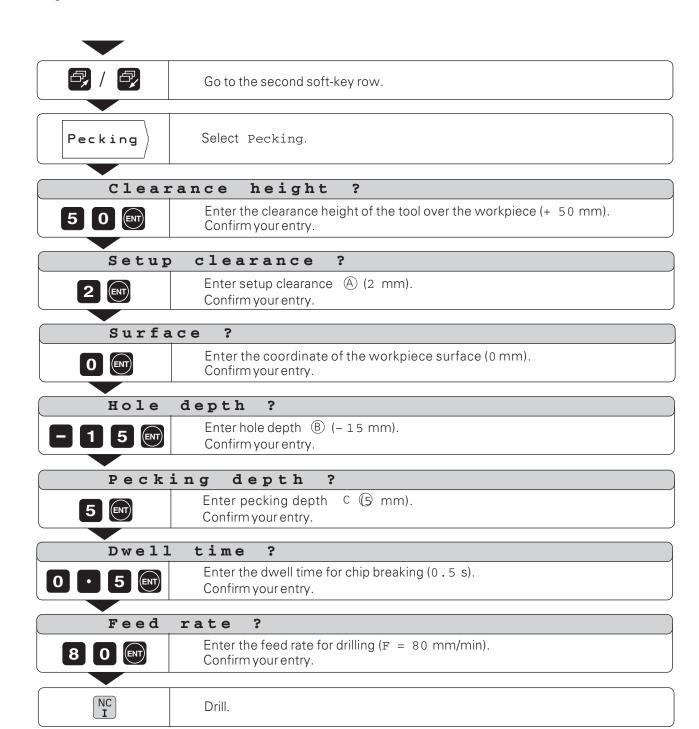
➤ Pre-position the tool over the workpiece.

Operating mode: POSITIONING WITH MDI





Pecking



Example: TAPPING

X coordinate of the hole: 30 mm Y coordinate of the hole: 20 mm Pitch p: 0.8 mm Spindle speed S: 100 rpm Clearance height: +50 mm Setup clearance (A): 3 mm Workpiece surface: 0 mm Thread depth (B): - 20 mm Dwell time: 0.4 s

Feed rate $F = S \cdot p$: 80 mm/min

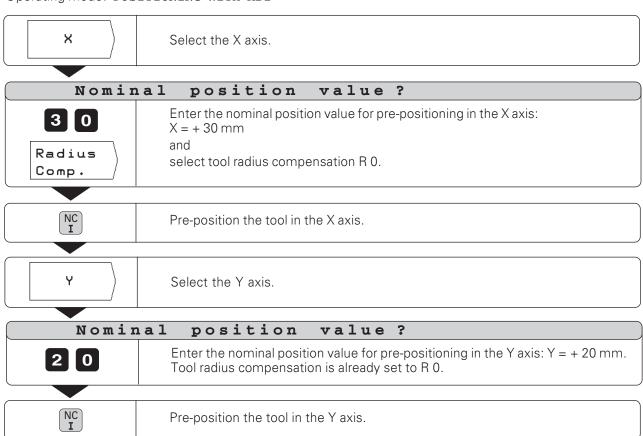
Preparation

➤ Pre-position the tool over the workpiece.

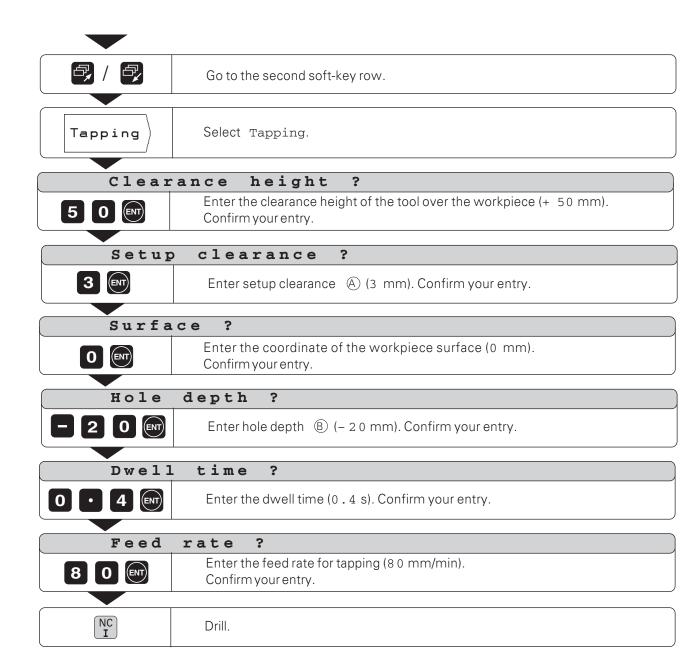
➤ For tapping **right-hand threads** activate the spindle with M 3.

30 X

Operating mode: POSITIONING WITH MDI



Tapping



Hole patterns

The hole pattern functions **Circle Pattern** and **Linear Pattern** are available in the POSITIONING WITH MDI mode of operation.

Use the soft keys to select the desired hole pattern function and enter the required data. These data can usually be taken from the workpiece drawing (number of holes, coordinates of the first hole, etc.).

The TNC then calculates the positions of all holes in the pattern, and displays the pattern graphically on the screen.

Type of hole

At the hole positions that were calculated for the pattern you can execute either

- pecking or
- tapping operations.

Enter the required data for pecking or tapping (see pages 43 to 47).

If you do not wish to drill at the calculated hole positions, or if you want to **drill the holes manually**:

➤ Choose the soft key No Entry for Type of hole ?.

Pre-positioning the drill

Pre-position the drill in the Z axis to a position above the workpiece surface. The TNC then pre-positions the drill in the X and Y axes (working plane) above each hole position.

Bolt hole circle patterns

If you are drilling a Circle Pattern in the POSITIONING WITH MDI mode of operation, enter the following data:

- Full circle or circle seament
- Number of holes
- Center point coordinates and radius of the circle
- Starting angle (position of first hole)
- Circle segment only: angle step between the holes
- Bore hole or tap hole

Linear hole patterns

If you are drilling a Linear Pattern in the POSITIONING WITH MDI mode of operation, enter the following data:

- Coordinates of the first hole
- Number of holes per row
- Spacing between holes on a row
- Angle between the first row and the X axis
- Number of rows
- Spacing between rows
- Bore hole or tap hole

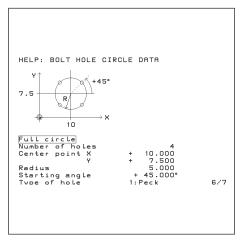


Fig. 4.3: On-screen operating instructions: graphic for bolt hole circle pattern (full circle)

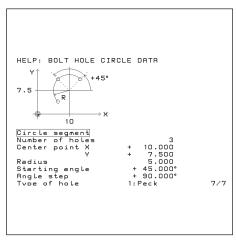


Fig. 4.4: On-screen operating instructions: graphic for bolt hole circle pattern (circle segment)



Bolt hole circle patterns

Information required:

- Full circle or circle segment
- Number of holes
- Center point coordinates and radius of the circle
- Starting angle (position of first hole)
- Circle segment only: angle step between the holes
- Bore hole or tap hole

The TNC calculates the coordinates of all holes.

Bolt hole circle graphic

The graphic enables verification of the hole pattern before you start machining. It is also useful when:

- selecting holes directly
- executing holes separately
- skipping holes

Overview of functions

Function	Soft key/Key
Switch to full circle	Full Circle
Switch to circle segment	Circle Segment
Go to next-highest input line	1
Go to next-lowest input line	Ţ
Confirm entry values	ENT

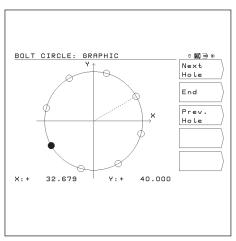


Fig. 4.5: TNC graphic for bolt hole circle patterns

Bolt Hole Circle Patterns

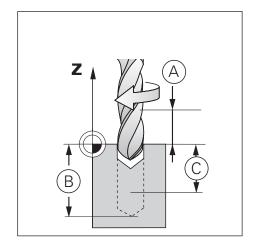
Example: Entering data and executing bolt hole circles

The work steps "Enter circle pattern data," "Display graphic" and "Drill" are described separately in this example.

Hole data

Enter the hole data separately (see pages 43 and 44) before entering the circle pattern data.

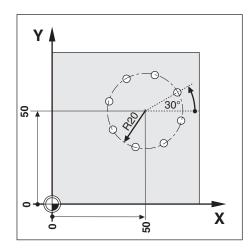
Clearance height: +50 mm Setup clearance (A): 3 mm Workpiece surface: 0 mm Hole depth (B): -20 mm Pecking depth :: 5 mm Dwell time: 0.4 s Feed rate: 80 mm/min



Circle pattern data

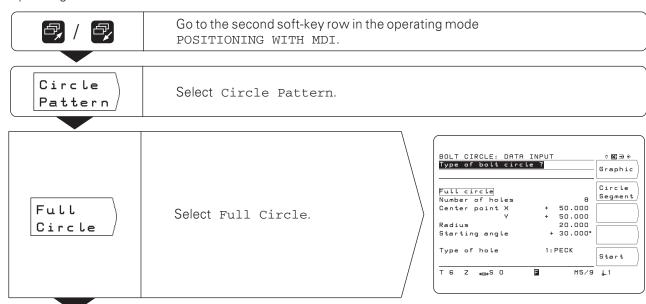
Number of holes: 8 X = 50 mmCenter point coordinates: Y = 50 mm20 mm Bolt hole circle radius: Starting angle: angle between

X axis and first hole 30°



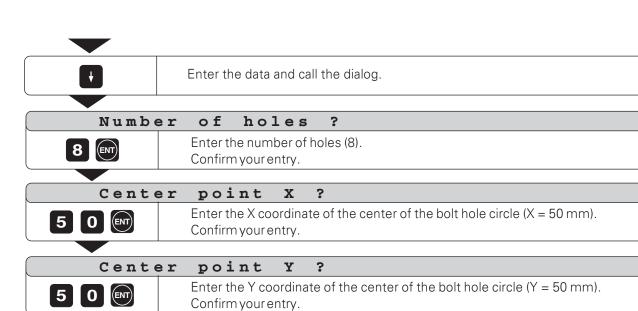
1st step: Enter circle pattern data

Operating mode: POSITIONING WITH MDI



Bolt Hole Circle Patterns





Radius	; ?
2 0 ENT	Enter the radius of the bolt hole circle (20 mm). Confirm you entry.

Enter the starting angle from the X axis to the first hole (30°).	Star	rting angle ?
Confirm your entry.	3 0 ENT	Enter the starting angle from the X axis to the first hole (30°). Confirm your entry.

Туре	of hole ?
Pecking	Choose Pecking for drilling bore holes at the hole positions in the pattern.

Bolt Hole Circle Patterns

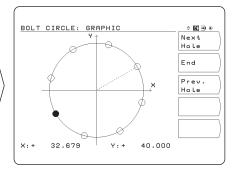
2nd step: Display graphic

The graphic makes it easy to verify the entered data. The solid circle represents the currently selected hole.

Graphic

The TNC displays the bolt hole circle graphically on the screen.

Here, a full circle with 8 holes is shown. The first hole is at 30°. The coordinates of the hole are given at the bottom of the screen.





The **direction of rotation** for bolt hole circle graphics is influenced with a user parameter (see Chapter 13). The TNC can **mirror** the coordinate axes for bolt hole circle graphics (see Chapter 13).

3rd step: Drill

Before you start drilling verify the data entered in the drilling cycle!



The **direction of rotation** for bolt hole circles is influenced with a user parameter (see Chapter 13).

Start	Start the bolt hole circle function.
NC	Pre-position in the first coordinate axis.
(NC I	Pre-position in the second coordinate axis.
(NC I	Drill. The TNC drills the bolt hole as defined by the input data for Pecking (or Tapping).
(NC I	Drill the next hole and all remaining holes.

Functions for drilling and graphic

Function	Soft key
Go to next hole	Next Hole
Return to last hole	Last Hole
End graphic/drilling	End



Linear hole patterns

Information required:

- Coordinates of the first hole
- Number of holes per row
- Spacing between holes on a row
- Angle between the first row and the angle reference axis
- Number of rows
- Spacing between rows
- Bore hole or tap hole

The TNC calculates the coordinates of all holes.

Linear hole pattern graphic

The graphic enables verification of the hole pattern before you start machining. It is also useful when:

- selecting holes directly
- executing holes separately
- skipping holes

Overview of functions

Function	Key
Go to the next-highest input line	1
Go to the next-lowest input line	+
Confirm entry values	ENT

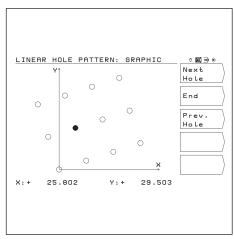


Fig. 4.6: TNC graphic for linear hole patterns

Linear Hole Patterns

Example: Entering data and executing rows of holes

The work steps "Enter linear pattern data," "Display graphic" and "Drill" are described separately in this example.

Hole data

Enter the hole data separately (see pages 43 and 44) **before** entering the linear pattern data.

Clearance height: +50 mm

Setup clearance A: 3 mm

Workpiece surface: 0 mm

Hole depth B: -20 mm

Pecking depth : 5 mm

Dwell time: 0.4 s

Feed rate: 80 mm/min



X coordinate of hole ① : X = 20 mmY coordinate of hole ① : Y = 15 mm

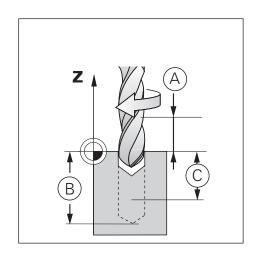
Number of holes per row: 4

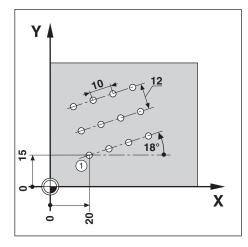
Hole spacing: +10 mm

Angle between rows and

X axis: 18° Number or rows: 3

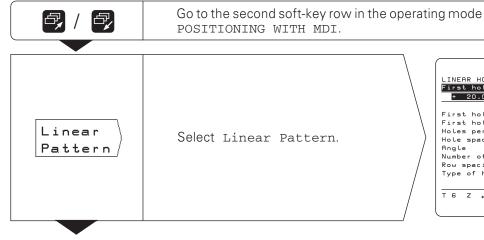
Row spacing: +12 mm

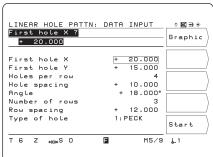




1st step: Enter linear pattern data

Operating mode: POSITIONING WITH MDI





Linear Hole Patterns

Pecking



1st l	hole X ?
2 0 ENT	Enter the X coordinate of hole $\textcircled{1}$ (X = 20 mm). Confirm your entry.
1st 1	hole Y ?
1 5 ENT	Enter the Y coordinate of hole \bigcirc (Y = 15 mm). Confirm your entry.
Holes	s per row ?
4 ENT	Enter the number of holes per row (4). Confirm your entry.
Hole	spacing ?
1 0 ENT	Enter the spacing between holes in the row (10 mm). Confirm your entry.
Angle	?
1 8 ENT	Enter the angle between the X axis and the hole pattern (18°). Confirm your entry.
Numbe	er of rows ?
3 ENT	Enter the number of rows (3). Confirm your entry.
Row	spacing ?
1 2 ENT	Enter the spacing between rows (12 mm). Confirm your entry.
Type	of hole ?

Choose Pecking for drilling bore holes at the hole positions in the pattern.

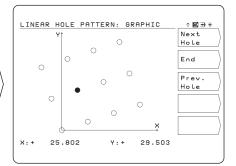


2nd step: Display graphic

The graphic makes it easy to verify the entered data. The solid circle represents the currently selected hole.

The TNC displays the pattern graphically on the screen.
Here, 3 rows of 4 holes are shown.

1st hole at X=20 mm, Y=10 mm
Hole spacing 10 mm
Angle between rows and X axis: 18°
Row spacing 12 mm
Coordinates of the current hole are shown at the bottom of the screen.





The TNC can **mirror** the coordinate axes for linear hole pattern graphics if the corresponding user parameter is set (see Chapter 13).

3rd step: Drill

Before you start drilling verify the data entered in the drilling cycle!

Start	Start the linear hole pattern function.
NC I	Pre-position in the first coordinate axis.
NC I	Pre-position in the second coordinate axis.
NC I	Drill. The TNC drills the bolt hole as defined by the input data for Pecking (or Tapping).
NC I	Drill the next and all remaining holes.

Functions for drilling and graphic

Function	Soft key
Go to next hole	Next Hole
Return to last hole	Last Hole
End graphic/drilling	End



Rectangular pocket milling

The TNC cycle for rectangular pocket milling is available in the POSITIONING WITH MDI mode of operation.

The input data for milling a rectangular pocket can also be entered as a "cycle" in a part program (see Chapter 7).

Select the "Pocket Milling" soft key on the second soft-key row and enter the required data. These data can usually be taken from the workpiece drawing (side length, depth of the pocket, etc.).

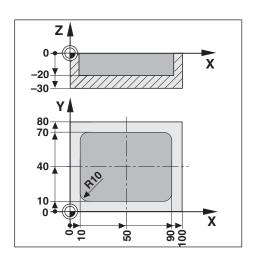
The TNC controls the machine tool and calculates the tool path for area clearance.

For the procedure and input data required for programming a rectangular pocket, see Chapter 7.

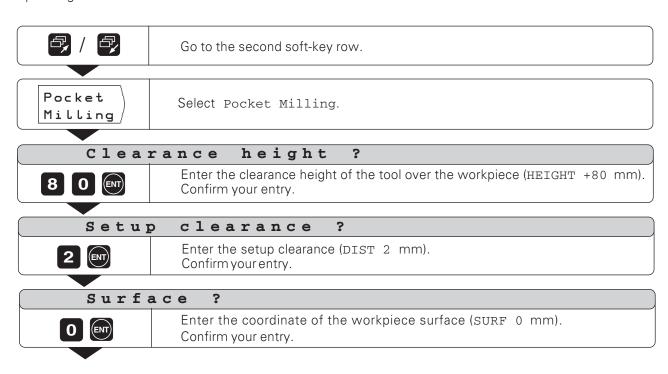


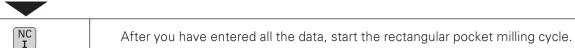
Example: RECTANGULAR POCKET

Clearance height: +80 mm Safety clearance: 2 mm Workpiece surface: + 0 mm Milling depth: – 20 mm Pecking depth: 7 mm Pecking feed rate: 80 mm/min Pocket center in X: 50 mm Pocket center in Y: 40 mm Side length in X: 80 mm Side length in Y: 60 mm Milling feed rate: 100 mm/min Direction of milling rotation: 0: CLIMB Finishing allowance: 0.5 mm



Operating mode: POSITIONING WITH MDI







5 Programming

Operating mode PROGRAMMING AND EDITING

In the PROGRAMMING AND EDITING mode of operation you can store the individual work steps that are required for recurring machining operations, for example for small-lot production.

Programs in the TNC

Programs contain the work steps for workpiece machining. You can edit programs, add work steps and run them as often as you wish.

The External mode enables you to store programs with the HEI-DENHAIN FE 401 floppy disk unit and load them into the TNC again on demand—you don't need to retype them. You can also transfer programs to a personal computer or printer.

Storage capacity

The TNC 124 can store a maximum of 20 programs with a total of 2000 NC blocks. A single program can contain a maximum of 1000 NC blocks.

Position display during programming

In the PROGRAMMING AND EDITING mode of operation, the TNC continuously displays the current positions at the bottom of the screen to left of the lowest soft key.

Programmable functions

- Nominal position values
- Feed rate F, spindle speed S and miscellaneous function M
- Tool call
- Pecking and tapping cycles
- Bolt hole circle and linear hole patterns
- Program section repeats:

A section of a program only has to be entered once and can then be run up to 999 times in succession.

- Subprograms:
 - A section of a program only has to be entered once and can then be run at various points in the program.
- Datum call
- Dwell time
- Interrupt program

Transfer position: Teach-In mode

This mode allows you to transfer the actual positions of the tool directly into a program, such as the nominal positions for workpiece machining, etc.

In many cases the Teach-In function will save you considerable programming work.

What happens with finished programs?

For workpiece machining, programs are executed in the operating mode PROGRAM RUN. See Chapter 10 for an explanation of this mode.

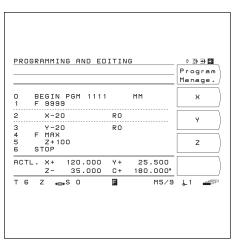


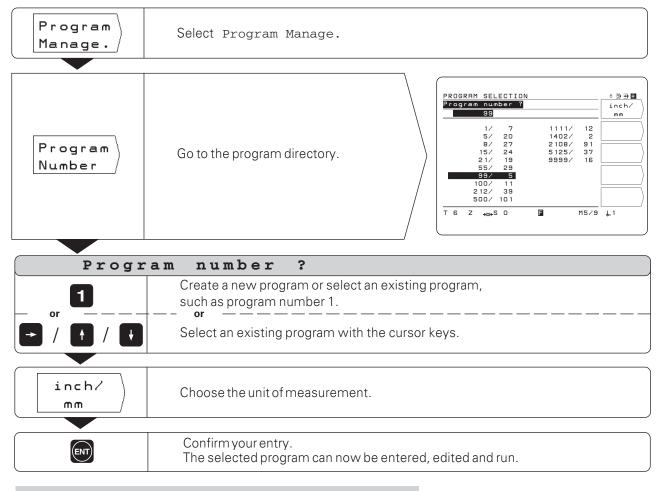
Fig. 5.1: The first soft-key row in the operating mode PROGRAMMING AND EDITING



Entering a program number

Select a program and identify it by a number between 0 and 9999 9999 which you assign it.

Operating mode: PROGRAMMING AND EDITING





When you select the unit of measurement with the soft key inch/mm, the TNC overwrites the user parameter inch/mm.

Program directory

The program directory appears when you choose the soft key Program Number. The number in front of the slash is the program number, the number behind the slash is the number of blocks in the program.

A program always contains at least two blocks.

Deleting programs

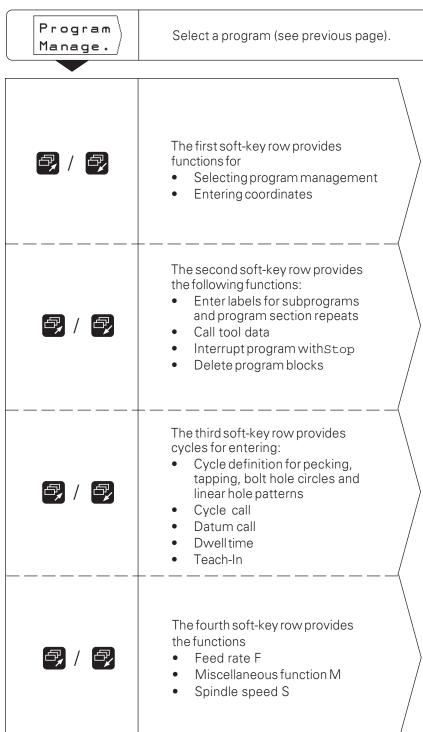
If you no longer wish to keep a program in memory, you can **delete** it:

- ➤ Press the soft key Program Manage.
- ➤ Press the soft key Delete Program.
- ➤ Enter the program number.
- ➤ Press ENT to delete the program.



Editing programs

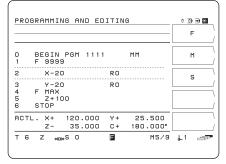
Operating mode: PROGRAMMING AND EDITING



PROGRAMMING AND EDITING	○ ③ → ◎ Program Manage.
O BEGIN PGM 1111 MM 1 F 9999	×
2 X-20 R0	Ψ\
3 Y-20 RO 4 F MAX	
4 F MAX 5 Z+100 6 STOP	z
ACTL. X+ 120.000 Y+ 25.500	
Z- 35.000 C+ 180.000°	/
T 6 Z _{*KO*} S 0 ■ M5/9	<u>↓</u> 1 🚁

PROGRAMMING AND EDITING	o ∄ → ⅓ Label Number
O BEGIN PGM 1111 MM 1 F 9999	Label Call
2 X-20 R0	Tool
3 Y-20 R0	Call
4 F MAX 5 Z+100 6 STOP	Stop
ACTL. X+ 120.000 Y+ 25.500	Delete
Z- 35.000 C+ 180.000°	Block
T 6 Z +400+S 0 ■ M5/9	L1 ∠=

PROGRAMMING AND EDITING	° ③ ⋺ ⑤ Cycle Def.
O BEGIN PGM 1111 MM 1 F 9999	Cycle Call
2 X-20 R0	Datum
3 Y-20 R0	Call
4 F MAX 5 Z+100 6 STOP	Dwell Time
ACTL. X+ 120.000 Y+ 25.500	Teach-
Z- 35.000 C+ 180.000°	In /
T 6 Z ₊₁₀₎₊ S 0 ■ M5/9	L1 ⊴=





Editing program blocks

Current block

The current block is shown between the two dashed lines. New blocks are inserted behind the current block. When the END PGM block is between the dashed lines, no new blocks can be inserted.

Overview of functions

Function	Soft key/Key
Go up one block	f
Go down one block	•
Clear numerical entry	CE
Delete current block	Delete Block

Going directly to a program block

Scrolling to the desired block with the arrow keys can be time-consuming with long programs. A quicker way is to use the GOTO function. This enables you to move directly to the block you wish to change or add new blocks behind.

Operating mode: PROGRAMMING AND EDITING

С ОТО	Press the GOTO key.
Block	number ?
5 8	Enter a block number, such as 58.
ENT	Confirm your entry. Block number 58 is now the currently selected block.



Editing existing programs

You can edit existing programs, for example to correct keying errors. The TNC supports you with plain language dialogs—just as when you are creating a new program.

Confirm your changes

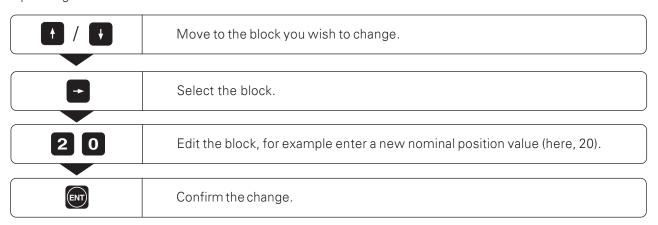
You **must** confirm each change with the ENT key for it to become effective!

Example: Changing a program number

- ➤ Select the BEGIN or END block.
- ➤ Enter a new program number.
- ➤ Confirm the change with ENT.

Example: Editing a program block

Operating mode: PROGRAMMING AND EDITING



Overview of functions

Function	Key
Select the next-lowest program block	+
Select the next-highest program block	t
Go directly to program block number	СОТО
Select program block to edit	-
Confirm change	ENT



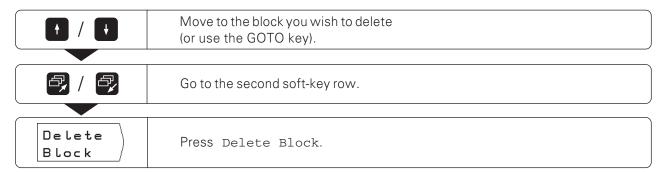
Deleting program blocks

You can delete any blocks in existing programs except the BEGIN and END blocks.

When a block is deleted, the TNC automatically renumbers the remaining blocks. The block before the deleted block then becomes the current block.

Example: Deleting a program block

Operating mode: PROGRAMMING AND EDITING



It is also possible to delete an entire **program section**:

- > Select the last block of the program section to be deleted.
- ➤ Press the soft key Delete Block repeatedly until all blocks in the program section have been deleted.



Feed rate F, spindle speed S and miscellaneous function M

Besides the geometry for workpiece machining, you must also enter the following information:

- Feed rate F in [mm/min]
- Miscellaneous function M
- Spindle speed S in [rpm]

The feed rate F, miscellaneous function M and spindle speed S are programmed in separate blocks and become effective as soon as the TNC has executed the blocks in which they are programmed. These program blocks must be entered in the program **before** the positioning blocks for which they are intended.

Entering the feed rate F

The feed rate F is "modally" effective. This means that the entered feed rate remains in effect until a new feed rate is programmed.

Exception: Rapid traverse F MAX

Rapid traverse F MAX

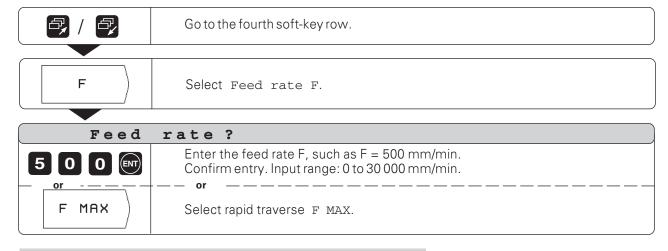
You can also move the machine axes at rapid traverse (F MAX). The feed rate for rapid traverse F MAX is preset in a machine parameter by the machine manufacturer.

F MAX is **not** modally effective.

After the block with F MAX is executed, the feed rate returns to the value that was programmed previously.

Programming example:

Operating mode: PROGRAMMING AND EDITING





The feed rate can be varied infinitely during program run by turning the knob for feed rate override on the TNC control panel.

Feed Rate F, Spindle Speed S and Miscellaneous Function M



Entering the spindle speed S

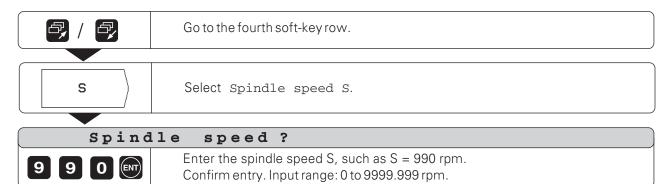


The machine manufacturer determines which spindle speeds are allowed on your TNC.

The spindle speed S is "modally" effective. This means that the entered spindle speed remains in effect until a new spindle speed is programmed.

Programming example

Operating mode: PROGRAMMING AND EDITING





The spindle speed can be varied infinitely during program run by turning the knob for spindle speed override on the TNC control panel.

Entering a miscellaneous function M

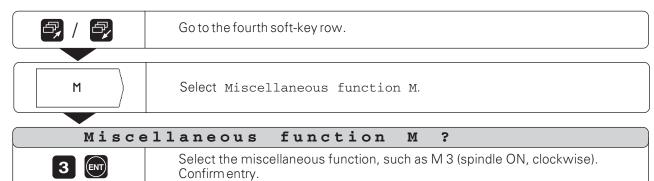
With the miscellaneous functions (M functions) you can influence, for example, direction of spindle rotation and program run. Chapter 14 provides an overview of all miscellaneous functions that can be programmed on the TNC 124.



The machine manufacturer determines which miscellaneous functions are available on your TNC and which functions they have.

Programming example

Operating mode: PROGRAMMING AND EDITING

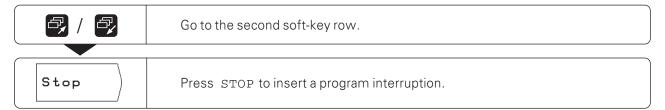




Entering program interruptions

You can divide a program into sections with stop marks. The TNC then only executes the next block when you resume program run.

Operating mode: PROGRAMMING AND EDITING



Resuming program run after an interruption

➤ Press the NC-I key.



Calling the tool data in a program

Chapter 3 explained how to enter the length and radius of your tools in the tool table.

The tool data stored in the table can also be called from a program. Then if you change the tool during program run you don't need to select the new tool data from the tool table every time.

The TOOL CALL command automatically pulls the tool length and radius from the tool table.

You define the tool axis for program run in the program.



If you enter a different tool axis in the program than is stored in the table, the TNC stores the new tool axis in the table.

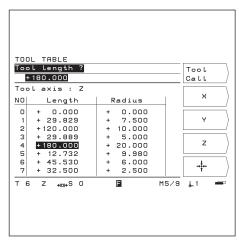
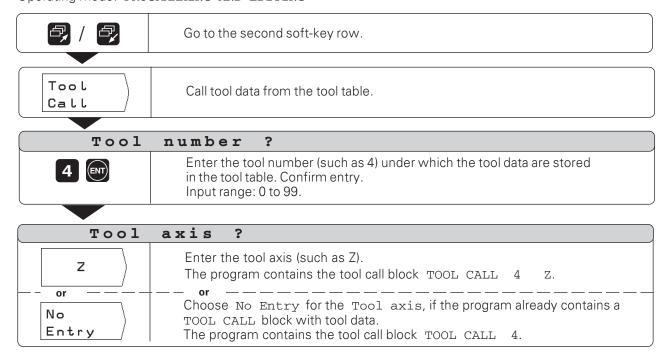


Fig. 5.2: The tool table on the TNC screen

Operating mode: PROGRAMMING AND EDITING



Working without TOOL CALL

If a part program is written without TOOL CALL the TNC will use the data of the tool that was programmed previously.

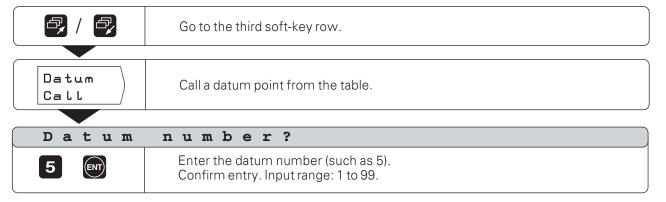
When you are changing tools, you can also go to the tool table from the operating mode PROGRAM RUN to call the new tool data.



Calling datum points

The TNC 124 can store up to 99 datum points in a datum table. You can call a datum point from the datum table during program run by simply pressing the soft key Datum Call and entering the block DATUM XX. This automatically calls the datum point entered for XX during program run.

Operating mode: PROGRAMMING AND EDITING

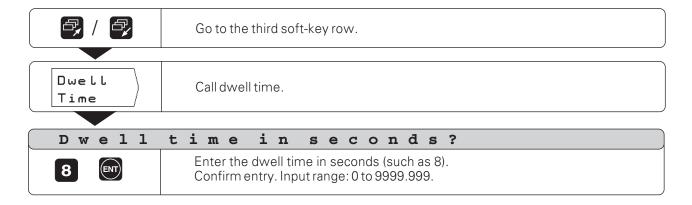




Entering dwell time

You can enter a dwell time in the part program by pressing the soft key <code>Dwell Time</code> and defining the block <code>DWELL XXXX.XXX</code>. When the <code>DWELL</code> block is executed, continuation of the running program is delayed by the time entered in seconds for <code>DWELL</code>.

Operating mode: PROGRAMMING AND EDITING





6

Programming Workpiece Positions

Entering workpiece positions

For many simple machining processes it is often sufficient to simply describe the workpiece to be machined by the coordinates of the positions to which the tool should move.

There are two possibilities of entering these coordinates in a program:

- Keying in the coordinates with the keyboard, or
- Transferring the tool position with the Teach-Infunction

Entries for a complete part program

Having the TNC execute a machining process requires more than entering coordinates in a program. A complete part program requires the following data:

- A BEGIN block and an END block (automatically generated by the TNC)
- Feed rate F
- Miscellaneous function M
- Spindle speed S
- Calling the tool with TOOL CALL

Entering feed rate F, miscellaneous function M, spindle speed S and TOOL CALL in a part program is described in Chapter 5.

Important information on programming and machining

The following information is intended to help you in quickly and easily machining the programmed workpiece.

Movements of tool and workpiece

During workpiece machining on a milling or drilling machine, an axis position is changed either by moving the tool or by moving the machine table on which the workpiece is fixed.



When entering tool movements in a part program you always program as if the tool is moving and the workpiece is stationary.

Pre-positioning

Pre-position the tool to prevent the possibility of damaging the tool or workpiece. The best pre-position lies on the extension of the tool path.

Feed rate F and spindle speed S

Adjust the feed rate F and spindle speed S to your tool, workpiece material and machining operation.

The TNC then calculates the feed rate F and spindle speed S with the **INFO** function (see Chapter 12).

In the appendix you will find a diagram which will aid you in selecting the appropriate feed rate F for tapping.

Programming example: Milling a shoulder

The coordinates are programmed in absolute dimensions. The datum is the workpiece zero.

Corner(1): X = 0 mmY = 20 mmCorner (2): X = 30 mm Y = 20 mmCorner (3): X = 30 mm Y = 50 mmCorner (4): X = 60 mm Y = 50 mm

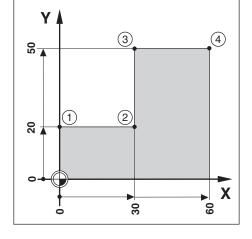
Summary of all programming steps

- ➤ In the main menu PROGRAMMING AND EDITING go to Program Manage.
- Key in the number of the program you want to work on, and press ENT.
- ➤ Enter the nominal positions.

Running a finished program

When a program is finished it can be run in the PROGRAM RUN mode (see Chapter 10).

Example of entry: Entering a nominal position into a program (block 11 in this example)



Х

Select the coordinate axis (X axis).

Nominal position value

3 0

Radius Comp.

Enter the nominal position value, for example 30 mm select tool radius compensation R -.

Confirm the entry. The nominal position is now the current block



(between the dashed lines).

Program	b	locks
---------	---	-------

0 1 2 3 4	BEGIN PGM 10 MM F 9999 Z+20 X-20 R0 Y-20 R0	Start of program, program number and unit of measurement High feed rate for pre-positioning Clearance height Pre-position the tool in the X axis Pre-position the tool in the Y axis
5 6 7 8 9	Z-10 TOOL CALL 1 Z S 1000 M 3 F 200	Move tool to milling depth Call the tool, such as tool 1, tool axis Z Spindle speed Spindle ON, clockwise Machining feed rate
10 11 12 13	Y+20 R+ X+30 R- Y+50 R+ X+60 R+	Y coordinate, corner ① X coordinate, corner ② Y coordinate, corner ③ X coordinate, corner ④ High feed rate for retracting
15 16 17	Z+20 M 2 END PGM 10 MM	Clearance height Stop program run, spindle OFF, coolant OFF End of program, program number and unit of measurement



Transferring positions: Teach-In mode

Teach-In programming offers the following two options:

- Enter nominal position, transfer nominal position to program, move to position.
- Move to a position and transfer the actual value to a program via soft key or through the actual-value-capture key on the handwheel.

You can change transferred position values during Teach-In.

Preparation

- ➤ With Program number select the program you want transfer positions to.
- ➤ Select the tool data from the tool table.

Feed rate F for Teach-In

Before starting the Teach-In process define the feed rate at which the tool should move during Teach-In:

- Select the Teach-In function and enter a block with the desired feed rate F first.
- ➤ Press the NC-I key.

Overview of functions

Function	Soft key/Key
Go to the next block	+
Go to the previous block	1
Delete the current block	Delete Block

Transferring Positions: Teach-In Mode



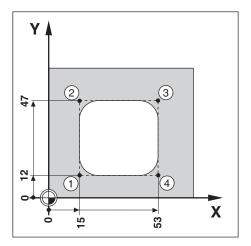
Programming example: Generate a program while machining a pocket

With Teach-In you first machine a workpiece according to the workpiece drawing dimensions.

The TNC then transfers the coordinates directly into the program. Pre-positioning and retraction movements can be selected as desired and entered like drawing dimensions.

Corner point \bigcirc : X = 15 mm Y = 12 mmCorner point (2): X = 15 mm Y = 47 mmCornerpoint 3: X = 53 mm Y = 47 mmCorner point (4): X = 53 mm Y = 12 mmPocket depth: Z = -10 mm (for example)

Operating mode: PROGRAMMING AND EDITING

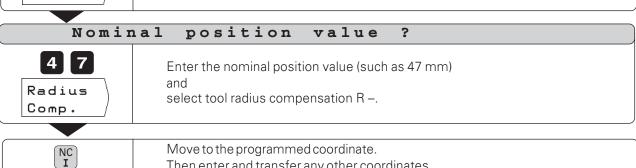


Teach-Ιn

Select Teach-In.

Example: Transferring the Y coordinate of corner point (3) into a program

Select the coordinate axis (Y axis).



Then enter and transfer any other coordinates.

Transferring Positions: Teach-In Mode

Programming example: Touch island with tool and transfer positions to program

This example illustrates how to generate a program containing the actual positions of the tool.

When you then **run** the program:

- ➤ Use a tool which has the same radius as the tool you used during the Teach-In process.
- ➤ If you use a different tool, you must enter all program blocks with radius compensation. Then enter the difference between the radii of the two tools as the tool radius for machining:

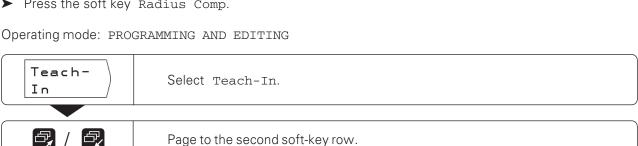
Radius of the tool for machining

- Radius of the tool for Teach-In
- Tool radius to be entered for machining

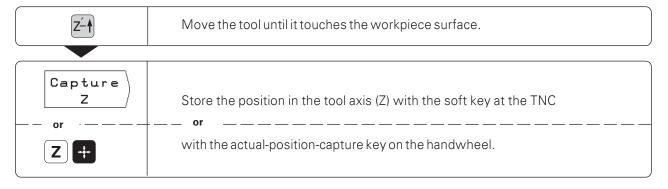
Selecting radius compensation

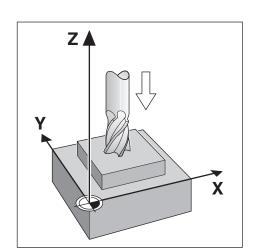
The current radius compensation is highlighted at the top of the screen. If you wish to change the radius compensation:

> Press the soft key Radius Comp.



Example: Transfer Z coordinate (workpiece surface) to a program





Transferring Positions: Teach-In Mode



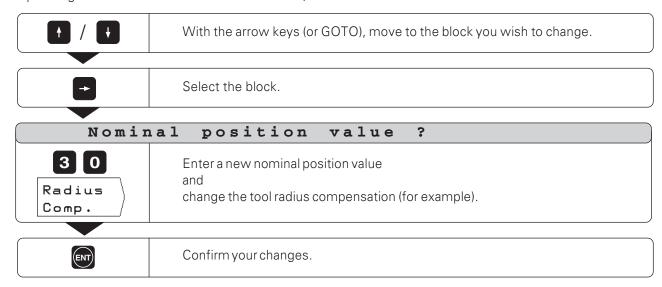
Changing nominal positions after they have been transferred

Positions which you have transferred into a program with Teach-In can be changed. It is not necessary to leave the Teach-In mode to do so.

Enter the new value in the input line.

Example: Changing a block transferred with Teach-In

Operating mode: PROGRAMMING AND EDITING, Teach-In



Functions for changing a Teach-In program

Function	Soft key
Enter feed rate F	F
Enter miscellaneous function M	M
Enter spindle speed S	s
Delete current block	Delete Block



7 Drilling, Milling Cycles and Hole Patterns in Programs

The cycles for pecking or tapping, hole patterns, and rectangular pocket milling can also be written to a program (see Chapter 4). Each piece of information is then stored in a separate program block. These blocks are identified by CYCL after the block number, followed by a number.

The cycles contain all information required by the TNC for machining a hole, hole pattern or rectangular pocket.

The TNC 124 features six different cycles:

Drilling cycles

- CYCL 1.0 PECKING
- CYCL 2.0 TAPPING

Hole patterns

- CYCL 5.0 FULL CIRCLE
- CYCL 6.0 CIRCLE SEGMENT
- CYCL 7.0 LINEAR HOLE PATTN

Rectangular pocket milling

• CYCL 4.0 RECTANGULAR POCKET

Cycles must be complete

Do not delete any blocks from a cycle because this will result in the error message CYCLE INCOMPLETE when the program is executed.

Drilling cycles must be called

The TNC runs a **drilling cycle** whenever it reaches a cycle call (CYCL CALL) during execution of the program. A cycle call always calls the drilling cycle that was programmed before the cycle call.

The TNC automatically executes a **hole pattern** or **rectangular pocket** as soon as it reaches it during execution of the program. If you wish to repeatedly execute hole patterns or rectangular pockets, you must enter the data repeatedly or write them in a subprogram (see Chapter 8).

Entering cycles

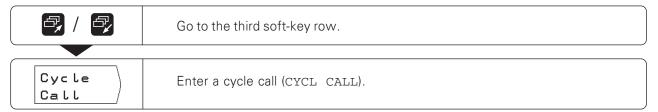
Press the Cycle Def. soft key in the third soft-key row and select the desired cycle. The TNC automatically asks for all data required for executing the cycle.



Entering a cycle call

A drilling cycle must be called at the location in a part program at which the cycle is to be executed.

Operating mode: PROGRAMMING AND EDITING



Drilling cycles in programs

The following two cycles are available on the TNC 124:

- CYCL 1.0 PECKING
- CYCL 2.0 TAPPING

Cycle 1.0 PECKING

Cycle 1.0 PECKING is used for drilling holes in several infeeds.

During machining the TNC advances the tool in several infeeds, retracting the tool each time to setup clearance.

Cycle 2.0 TAPPING



The TAPPING cycle requires a floating tap holder.

Cycle 2.0 TAPPING is used for cutting threads.

The thread is cut in one pass. After a dwell time at the end of thread, the direction of spindle rotation is reversed and the tool retracted.

Signs for the input values in the drilling cycles

Enter the "clearance height" $\textcircled{\ }$ and the coordinate of the workpiece surface $\textcircled{\ }$ as absolute values—together with the algebraic sign.

The **algebraic sign for hole depth** (thread length) (B) determines the working direction. If you are drilling in the negative axis direction, enter a negative sign for hole depth.

Fig. 7.1 also illustrates setup clearance A and the infeed depth C .

Pre-positioning the drill

Before executing the cycle, pre-position the drill in the tool axis and in the working plane. The coordinates for pre-positioning can be entered into the program before the cycle.

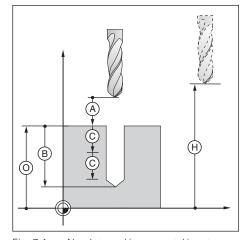


Fig. 7.1: Absolute and incremental input values for drilling cycles

PECKING

If you program Cycle 1.0 PECKING, the TNC drills to the programmed hole depth in several infeeds.

Process

The pecking cycle is illustrated in Fig. 7.2 and Fig. 7.3.

I:

The TNC pre-positions the tool at setup clearance (A) above the workpiece surface.

II:

The tool drills to the first pecking depth © at the programmed machining feed rate F. After reaching the first pecking depth, the tool retracts at rapid traverse (F MAX) to setup clearance (A).

III:

The TNC pre-positions the tool at rapid traverse to the first infeed depth (c), minus the advanced stop distance (t). The tool then advances with another infeed ©.

TV:

The TNC retracts the tool again and repeats the drilling process (drilling/retracting) until the programmed hole depth (B) is reached.

After a dwell time at the hole bottom, the tool is retracted to clearance height at rapid traverse (F MAX) for chip breaking.

Advanced stop distance (t)

The advanced stop distance (t) for the drilling operation is automatically calculated by the TNC:

Hole depth up to 30 mm:

 $(t) = 0.6 \, \text{mm}$

Hole depth between 30 mm and 350 mm: (t) = 0.02 • hole depth

Hole depth exceeding 350 mm:

(t) = 7 mm

Input data for Cycle 1.0 PECKING

- Clearance height HEIGHT Position in the tool axis at which the TNC can move the tool in the working plane without damaging the workpiece.
- Setup clearance DIST (A) The TNC advances the tool from clearance height to setup clearance at rapid traverse.
- Workpiece surface SURF Absolute coordinate of the workpiece surface.
- Hole depth DEPTH B Distance between workpiece surface and bottom of hole (tip of drill taper).
- Pecking depth PECKG © Infeed per cut.
- Dwell time DWELL in [s] Amount of time the tool remains at the hole depth for cutting free the drill taper.
- Feed rate F in [mm/min] Traversing speed of the tool while drilling.

Hole depth and infeed depth

The infeed depth does not have to be a multiple of the hole depth. If the infeed depth is programmed greater than the hole depth, or equals the hole depth, the tool will drill to the programmed hole depth in one operation.

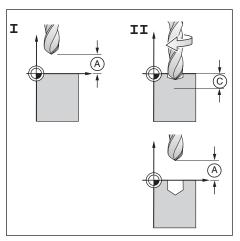


Fig. 7.2: Steps I and II in Cycle 1.0 PECKING

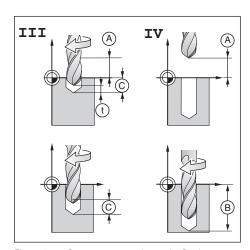


Fig. 7.3: Steps III and IV in Cycle 1.0 PECKING

♦

Programming example: Cycle 1.0 PECKING

X coordinate of the hole: 30 mm
Y coordinate of the hole: 20 mm
Hole diameter: 6 mm
Clearance height HEIGHT: +50 mm
Setup clearance DIST (A): 2 mm

Coordinate of the

workpiece surface SURF:

Hole depth DEPTH (B):

Pecking depth PECKG (C):

Dwell time DWELL:

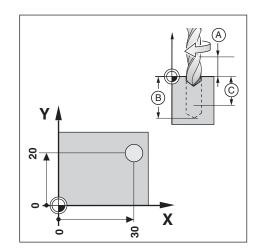
0.5 s

Machining feed rate F:

0 mm

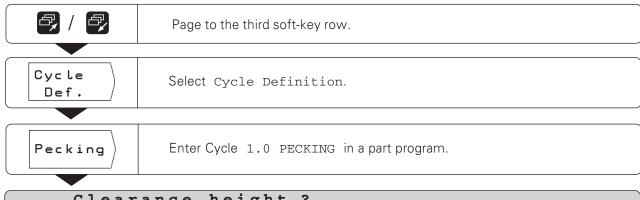
- 15 mm

0.5 s



Example: Entering Cycle 1.0 PECKING in a part program

Operating mode: PROGRAMMING AND EDITING



Clearance height ?	
5 0 ENT	Enter the clearance height (HEIGHT = 50 mm). Confirm your entry.

Setup	clearance ?
2 ENT	Enter the setup clearance \textcircled{A} (DIST = 2 mm). Confirm your entry.

Work	piece surface ?
O ENT	Enter the coordinate of the workpiece surface (SURF = 0 mm). Confirm your entry.

Hole	depth ?
- 1 5 ENT	Enter the hole depth \textcircled{B} (DEPTH = -15 mm). Confirm your entry.

Pecki	ng depth ?
5 ENT	Enter the pecking depth \bigcirc (PECKG = 5 mm). Confirm your entry.





Dwell time



Enter the dwell time for chip breaking (DWELL = 0.5 s). Confirm your entry.

Feed rate



Enter the feed rate for drilling (F = 80 mm/min). Confirm your entry.

0	BEGIN PGM 20 MM	Start of program, program number, unit of measurement
1	F 9999	High feed rate for pre-positioning
2	Z+600	Tool-change position
3	X+30	Pre-positioning in the X axis
4	Y+20	Pre-positioning in the Y axis
5	TOOL CALL 8 Z S 1500	Call the tool for pecking, such as tool 8, tool axis Z Spindle speed
6 7	M 3	Spindle Speed Spindle ON, clockwise
	м 5	
8	CYCL 1.0 PECKING	Cycle data for Cycle 1.0 PECKING follow
9	CYCL 1.1 HEIGHT +50	Clearance height
10	CYCL 1.2 DIST 2	Setup clearance above the workpiece surface
11	CYCL 1.3 SURF + 0	Absolute coordinate of the workpiece surface
12 13	CYCL 1.4 DEPTH -15	Hole depth
14	CYCL 1.5 PECKG 5 CYCL 1.6 DWELL 0.5	Depth per infeed Dwell time at bottom of hole
15	CYCL 1.6 DWELL 0.5 CYCL 1.7 F 80	Machining feed rate
	CICL 1.7 F 80	
16	CYCL CALL	Cycle call
17	M 2	Stop program run, spindle STOP, coolant OFF
18	END PGM 20 MM	End of program, program number, unit of measurement

Cycle 1.0 PECKING is executed in the operating mode PROGRAM RUN (see Chapter 10).

TAPPING

With Cycle 2.0 TAPPING you can cut right-hand and left-hand threads.

No effect of the override controls during tapping

When Cycle 2.0 TAPPING is being run, the knobs for spindle speed override control and feed rate override control are disabled.

Required floating tap holder

A floating tap holder is required for executing Cycle 2.0 TAPPING. The floating tap holder compensates the tolerances for the programmed feed rate F and the programmed spindle speed S.

Tapping right-hand and left-hand threads

Right-hand thread: Spindle ON with miscellaneous function M 3 **Left-hand thread:** Spindle ON with miscellaneous function M 4

Process

The tapping cycle is illustrated in Fig. 7.4 and Fig. 7.5.

I:

The TNC pre-positions the tool at setup clearance (A) above the workpiece surface.

II:

The tool drills to the end of thread (B) at the feed rate F.

TTT.

When the tool reaches the end of thread, the direction of spindle rotation is reversed. After the programmed dwell time the tool is retracted to clearance height.

IV:

Above the workpiece, the direction of spindle rotation is reversed once again.

Calculating the feed rate F

Formula for calculation: $\mathbf{F} = \mathbf{S} \cdot \mathbf{p}$ in [mm/min], where

S: Spindle speed in [rpm]

p: Pitch in [mm]

Input data for Cycle 2.0 TAPPING

Clearance height - HEIGHT
 Position in the tool axis at which the TNC can move the tool in

the working plane without damaging the workpiece.

• Setup clearance - DIST (A)

The TNC advances the tool from clearance height to setup clearance at rapid traverse.

Standard value: DIST = 4 • thread pitch p

• Workpiece surface - SURF

Absolute coordinate of the workpiece surface

• Thread length - DEPTH B

Distance between workpiece surface and end of thread.

• Dwell time - DWELL in [s]

A dwell time prevents wedging of the tool when retracted. Further information is available from the machine manufacturer. Standard value: DWELL = 0 to 0.5 s

• Feed rate - F in [mm/min]

Traversing speed of the tool during tapping

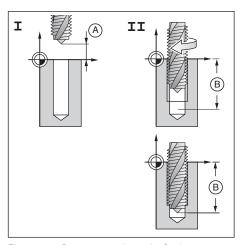


Fig. 7.4: Steps I and II in Cycle 2.0 TAPPING

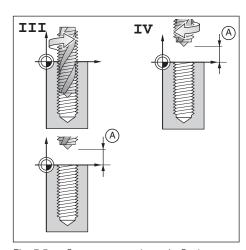


Fig. 7.5: Steps III and IV in Cycle 2.0 TAPPING

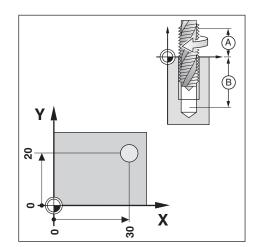
Programming example: Cycle 2.0 TAPPING

Right-hand thread

X coordinate of the hole: 30 mm Y coordinate of the hole: 20 mm Pitch p: 0.8 mm Spindle speed S: 100 rpm Clearance height HEIGHT: + 50 mm Setup clearance DIST (A): 3 mm

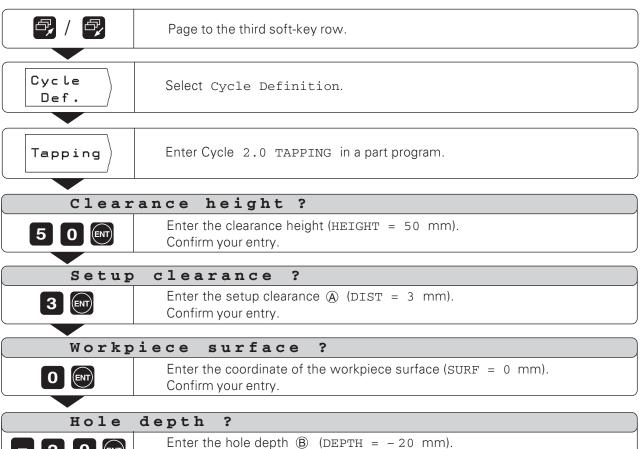
Coordinate of the

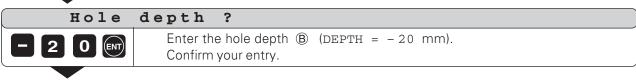
workpiece surface SURF: $0 \, \text{mm}$ Thread depth DEPTH B: – 20 mm Dwell time DWELL: 0.4 sFeed rate $F = S \cdot p$: 80 mm/min



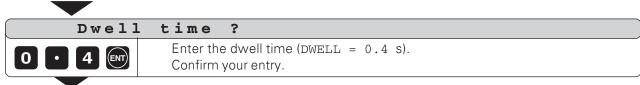
Example: Entering Cycle 2.0 TAPPING into a part program

Operating mode: PROGRAMMING AND EDITING









Feed	rate ?
8 0 ENT	Enter the feed rate for tapping (F = 80 mm/min). Confirm your entry.

Program blocks	
0 BEGIN PGM 30 MM 1 F 9999 2 Z+600 3 X+30 4 Y+20 5 TOOL CALL 4 Z 6 S 100 7 M 3	Start of program, program number, unit of measurement High feed rate for pre-positioning Tool-change position Pre-positioning in the X axis Pre-positioning in the Y axis Call the tool for tapping, such as tool 4, tool axis Z Spindle speed Spindle ON, clockwise (right-hand thread)
	Setup clearance above the workpiece surface Absolute coordinate of the workpiece surface

Cycle 2.0 TAPPING is executed in the operating mode PROGRAM RUN (see Chapter 10).



The information for the hole patterns Circle Pattern and Linear Pattern (see Chapter 4) can also be written to a program.

Executing holes in hole patterns

The TNC either drills bore holes or tap holes at the hole positions in the pattern. The bore hole or tap hole data, such as setup clearance and hole depth, must be programmed in a cycle.

The TNC then executes the holes according to the selected cycle that is programmed before the hole pattern cycle.

Hole pattern graphics

The hole patterns in a program can be displayed graphically.

Programming example: Cycle 5.0 Circle Pattern (full circle)

Number of holes NO.: 8

Center point coordinates: CCX = 50 mm
CCY = 50 mm

Bolt circle radius RAD: 20 mm

Starting angle between

X axis and first hole START: 30°

Hole data

A description of Cycle 1.0 Pecking starts on page 79.

Clearance height HEIGHT: + 50 mm Setup clearance DIST: 2 mm

Coordinate of the

workpiece surface SURF:

Hole depth DEPTH:

Pecking depth PECKG:

Dwell time DWELL:

Feed rate F:

0 mm

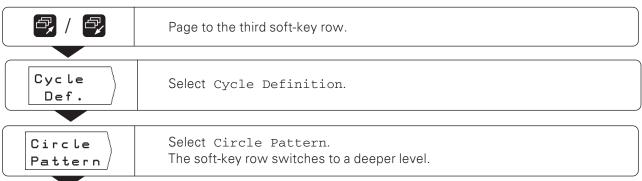
- 15 mm

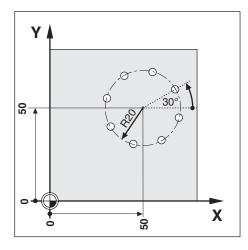
0.5 s

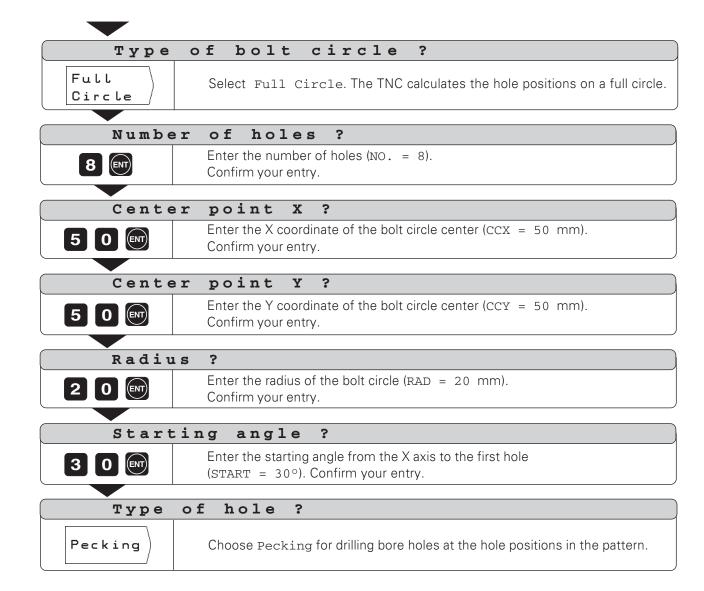
80 mm/min

Example: Entering bolt hole circle data into a program

Operating mode: PROGRAMMING AND EDITING







Program blocks Start of program, program number, unit of measurement BEGIN PGM 40 MM High feed rate for pre-positioning 1 F 9999 2 Tool-change position Z+600 3 TOOL CALL 3 Z Call the tool for drilling, for example tool 3, tool axis Z 4 S 100 Spindle speed Spindle ON, clockwise 5 M 3 CYCL 1.0 PECKING Cycle data for Cycle 1.0 PECKING follow 6 CYCL 1.1 HEIGHT +50 Clearance height 7 CYCL 1.2 DIST Setup clearance above the workpiece surface 8 2 CYCL 1.3 SURF + 0 Absolute coordinate of the workpiece surface Hole depth CYCL 1.4 DEPTH -15 10 Depth per infeed 11 CYCL 1.5 PECKG 5 Dwell time at bottom of hole 12 CYCL 1.6 DWELL 0.5 Machining feed rate CYCL 1.7 F 13 80 Cycle data for Cycle 5.0 FULL CIRCLE follow CYCL 5.0 FULL CIRCLE 14 15 CYCL 5.1 NO. Number of holes +50 X coordinate of the center of the bolt circle CYCL 5.2 CCX 16 CYCL 5.3 CCY Y coordinate of the center of the bolt circle 17 +50 18 CYCL 5.4 RAD 20 Radius Starting angle of first hole 19 CYCL 5.5 START +30 20 CYCL 5.6 TYPE 1:PECK Drill bore holes 21 Stop program run, spindle STOP, coolant OFF M 2 22 END PGM 40 MM End of program, program number, unit of measurement



For a **circle segment** (CYCL 6.0 CIRCLE SEGMENT) you also enter the angle step (STEP) between the holes (after the starting angle).

The bolt hole circle is then executed in the operating mode PROGRAM RUN (see Chapter 10).

Programming example: Cycle 7.0 Linear hole pattern

X coordinate of the first hole 1: POSX = 20 mm Y coordinate of the first hole 1: POSY = 15 mm

Number of holes per row NO.HL: 4
Hole spacing HLSPC: 10 mm

Angle between hole row and X axis ANGLE: 18°

Number of rows NO.RW: 3

Row spacing RWSPC: 12 mm

Hole data

A description of Cycle 1.0 Pecking starts on page 79.

Clearance height HEIGHT: +50 mm Setup clearance DIST: 2 mm Coordinate of the

workpiece surface SURF:

Hole depth DEPTH:

Infeed depth PECKG:

Dwell time DWELL:

Feed rate F:

0 mm

- 15 mm

5 mm

0.5 s

80 mm/min

Y 10 12 12 18° X

Example: Entering data for linear hole pattern into a program

Operating mode: PROGRAMMING AND EDITING

3 / 3	Page to the third soft-key row.
Cycle Def.	Select Cycle Definition.
Linear Pattern	Select Linear Pattern.

1st l	nole X ?
2 0 ENT	Enter the X coordinate of hole ① (POSX = 20 mm). Confirm your entry.
1st l	nole Y ?
1 5 [817]	Enter the Y coordinate of hole ① (POSY = 15 mm). Confirm your entry.
Holes	s per row ?
4 ENT	Enter the number of holes per row (NO.HL = 4). Confirm your entry.
Hole	spacing ?
1 0 ENT	Enter the hole spacing (HLSPC = 10 mm). Confirm your entry.
Angle	e ?
1 8 ENT	Enter the angle between the X axis and the rows of holes (ANGLE = 18°). Confirm your entry.
Numbe	er of rows ?
3 ENT	Enter the number of rows (NO.RW = 3). Confirm your entry.
Rows	spacing ?
1 2 ENT	Enter the row spacing (RWSPC = 12 mm). Confirm your entry.
Type	of hole ?
Pecking	Choose Pecking for drilling bore holes at the hole positions in the pattern.



Program blocks			
0 BEGIN PGM 50 MM 1 F 9999 2 Z+600 3 TOOL CALL 5 Z 4 S 1000 5 M 3	Start of program, program number, unit of measurement High feed rate for pre-positioning Tool-change position Call the tool for pecking, such as tool 5, tool axis Z Spindle speed Spindle ON, clockwise		
6 CYCL 1.0 PECKING 7 CYCL 1.1 HEIGHT +50 8 CYCL 1.2 DIST 2 9 CYCL 1.3 SURF + 0 10 CYCL 1.4 DEPTH -15 11 CYCL 1.5 PECKG 5 12 CYCL 1.6 DWELL 0.5 13 CYCL 1.7 F 80	Cycle data for Cycle 1.0 PECKING follow Clearance height Setup clearance above the workpiece surface Absolute coordinate of the workpiece surface Hole depth Depth per infeed Dwell time at bottom of hole Machining feed rate		
14 CYCL 7.0 LINEAR HOLE PATTN 15 CYCL 7.1 POSX +20 16 CYCL 7.2 POSY +15 17 CYCL 7.3 NO.HL 4 18 CYCL 7.4 HLSPC +10 19 CYCL 7.5 ANGLE +18 20 CYCL 7.6 NO.RW 3 21 CYCL 7.7 RWSPC +12 22 CYCL 7.8 TYPE 1:PECK	Cycle data for Cycle 7.0 LINEAR HOLE PATTN follow X coordinate of first hole ① Y coordinate of first hole ① Number of holes per row Distance between holes on the row Angle between the rows and the X axis Number of rows Spacing between rows Pecking Stop program run, spindle STOP, coolant OFF		
24 END PGM 50 MM	End of program, program number, unit of measurement		

The hole pattern is then executed in the operating mode ${\tt PROGRAM}\,$ RUN (see Chapter 10).

♦

Rectangular pockets in programs

The TNC makes it easier to clear out rectangular pockets. You need only enter the dimensions of the pocket; the TNC calculates the tool path for you.

Process

The cycle process is illustrated in Figures 7.6, 7.7 and 7.8.

I:

The TNC pre-positions the tool in the tool axis at the clearance height \oplus , moves it in the working plane to the pocket center, then in the tool axis to the setup clearance A.

тт٠

The TNC drills at the pecking feed rate to the first pecking depth (C).

III:

The TNC clears out the pocket at the milling feed rate along the path illustrated in Fig. 7.8 below (in this case with climb milling).

TV

The pecking and the roughing process are repeated down to the programmed depth B. Then the TNC ends the cycle by moving the tool in the pocket center back to the clearance height H.

Input data for Cycle 4.0 RECTANGULAR POCKET

- Clearance height HEIGHT (H)

 The absolute position in the tool axis at with the tool can move in the working plane without danger of collision.
- Setup clearance DIST (A)
 The tool moves at rapid traverse from the clearance height to the setup clearance.
- Workpiece surface SURF Absolute coordinate of the workpiece surface.
- Milling depth DEPTH B
 Distance between workpiece surface and bottom of pocket.
- Pecking depth PECKG © Infeed per drilling cut.
- Pecking feed rate F
 Tool traversing speed during pecking.
- Pocket center in X POSX MX
 Point in the longitudinal axis at which the pocket center is located
- Pocket center in Y POSY MY
 Point in the transverse axis at which the pocket center is located.
- Side length in X LNGTH $\times \times$ Length of the pocket in the longitudinal axis.
- Side length in Y LNGTH Y Y
 Length of the pocket in the transverse axis.
- Milling feed rate F
 Traversing speed of the tool in the working plane.
- Direction DIRCTN
 Input value 0: climb milling (Fig. 7.8: clockwise)
 Input value 1: upcut milling (counterclockwise)
- Finishing allowance ALLOW Finishing allowance in the working plane.

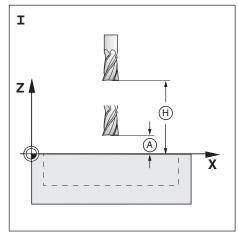


Fig. 7.6: Step I in Cycle
4.0 RECTANGULAR POCKET

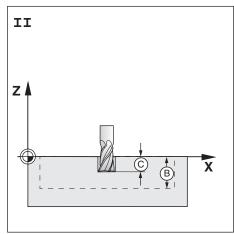


Fig. 7.7: Step II in Cycle 4.0 RECTANGULAR POCKET

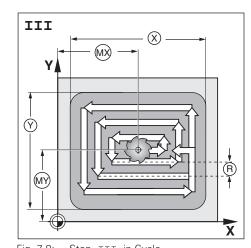
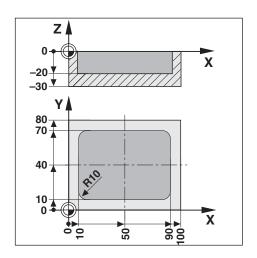


Fig. 7.8: Step III in Cycle 4.0 RECTANGULAR POCKET

Rectangular Pockets in Programs

Example: Cycle 4.0 RECTANGULAR POCKET

Clearance height: +80 mm Setup clearance: 2 mm Workpiece surface: + 0 mm Milling depth: – 20 mm Pecking depth: 7 mm Pecking feed rate: 80 mm/min Pocket center in X: 50 mm Pocket center in Y: 40 mm Side length in X: 80 mm Side length in Y: 60 mm Milling feed rate: 100 mm/min Direction: 0: CLIMB Finishing allowance: 0.5 mm



Example: Entering Cycle 4.0 RECTANGULAR POCKET

into a part program

Operating mode: PROGRAMMING AND EDITING

opoloting moto. Intodiaminito into abilino				
3 / 3	Page to the third soft-key row.			
Cycle Def.	Select Cycle Definition.			
Pocket Milling	Enter Cycle 4.0 RECTANGULAR POCKET in a part program.			
Clea	Clearance height ?			
8 0 ENT	Enter the clearance height (HEIGHT = 80 mm). Confirm your entry.			
Setup clearance ?				
2 ENT	Enter the setup clearance (DIST = 2 mm). Confirm your entry.			

Work	piece surface ?
O ENT	Enter the coordinate of the workpiece surface (SURF = 0 mm).
U	Confirm your entry.

•



Rectangular Pockets in Programs

Prog	gram blocks		
0	BEGIN PGM	55 MM	Start of program, program number, unit of measurement
1	F 9999		High feed rate for pre-positioning
2	Z+600		Tool-change position
3	X-100		Pre-positioning in the X axis
4	Y-100		Pre-positioning in the Y axis
5	TOOL CALL	7 Z	Call the tool for pocket milling, such as tool 7, tool axis Z
6	S 800		Spindle speed
7	м 3		Spindle ON, clockwise
8	CYCL 4.0	RECTANGULAR	
	0102 110	POCKET	Cycle data for Cycle 4.0 RECTANGULAR POCKET follow
9	CYCL 4.1	HEIGHT + 80	Clearance height
10	CYCL 4.2	DIST 2	Setup clearance above the workpiece surface
11	CYCL 4.3	SURF + 0	Absolute coordinate of the workpiece surface
12	CYCL 4.4	DEPTH - 20	Milling depth
13	CYCL 4.5	PECKG 7	Depth per infeed
14	CYCL 4.6	F 80	Pecking feed rate
15	CYCL 4.7	POSX + 50	Pocket center in X
16	CYCL 4.8	POSY + 40	Pocket center in Y
17	CYCL 4.9	LNGTHX 80	Side length X
18	CYCL 4.10	LNGTHY 60	Side length Y
19	CYCL 4.11	F 100	Milling feed rate
20	CYCL 4.12	DIRCTN 0: CLIMB	Climb milling
21	CYCL 4.13	ALLOW 0.5	Finishing allowance
22	M 2		Stop program run, spindle STOP, coolant OFF
23	END PGM 55	MM	End of program, program number, unit of measurement

Cycle 4.0 RECTANGULAR POCKET is executed in the operating mode PROGRAM RUN (see Chapter 10).



8

Subprograms and Program Section Repeats

Subprograms and program section repeats only need to be entered once in the program. You can then run them up to 999 times.

Subprograms can be run at any point in the program, while program section repeats are run several times in succession.

Inserting program marks (labels)

You identify subprograms and program section repeats with labels (abbreviated in the program to LBL).

Labels 1 to 99

Labels 1 to 99 identify the beginning of a subprogram or a program section which is to be repeated.

Label 0

Label 0 is used only to identify the end of a subprogram.

Label call

In the program, subprograms and program sections are called with the command ${\tt CALL}\ {\tt LBL}.$

The command CALL LBL 0 is not allowed.

Subprograms:

After a CALL LBL block in the program, the TNC executes the called subprogram.

Program section repeats:

The TNC repeats the program section located before the CALL LBL block. You enter the number of repeats with the CALL LBL command.

Nesting program sections

Subprograms and program section repeats can also be "nested." For example, a subprogram can in turn call another subprogram.

Maximum nesting depth: 8 levels

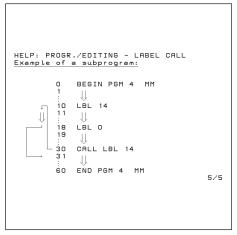


Fig. 8.1: On-screen operating instructions for subprogram (page 5 shown)

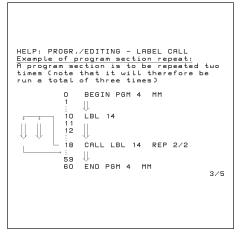


Fig. 8.2: On-screen operating instructions for program section repeats (page 3 shown)



Subprograms

Programming example: Subprogram for slots

Slot lengths: 20 mm + tool diameter

Slot depths: - 10 mm

Slot diameters: 8 mm (= tool diameter)

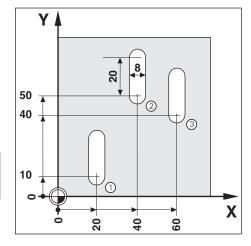
Infeed point coordinates

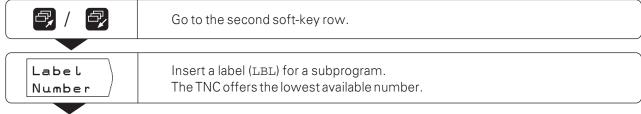


This example requires a center-cut end mill (ISO 1641)!

Example: Inserting label for subprogram

Operating mode: PROGRAMMING AND EDITING



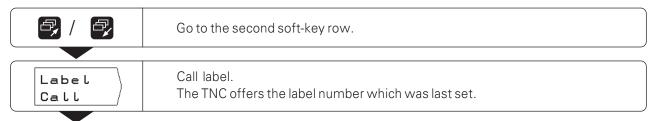


Label	number ?
ENT	Accept the default label number.
or	—— or —————————————————————————————————

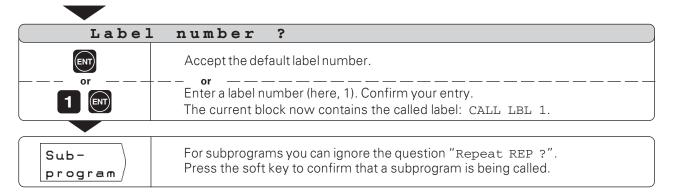
The beginning of a subprogram (or a program section repeat) is now marked with the label. Enter the program blocks for the subprogram after the LBL block.

Label 0 (LBL 0) is used **only** to identify the **end** of a subprogram.

Example: Entering a subprogram call: CALL LBL



Subprograms



After the CALL LBL block in the operating mode PROGRAM RUN, the TNC executes those blocks in the subprogram that are located between the LBL block with the called number and the next block containing LBL 0.

Note that the subprogram will be executed at least once even without a CALL LBL block.

Prog	ram blocks		
0	BEGIN PGM 60	MM	Start of program, program number, unit of measurement
1 2 3 4 5 6 7	F 9999 Z+20 X+20 Y+10 TOOL CALL 7 Z S 1000 M 3	R0 R0	High feed rate for pre-positioning Clearance height X coordinate infeed point slot ① Y coordinate infeed point slot ① Call tool data, here tool 7, tool axis Z Spindle speed Spindle ON, clockwise
8	CALL LBL 1		Call subprogram 1: execute blocks 17 to 23
9 10 11	X+40 Y+50 CALL LBL 1	R0 R0	X coordinate infeed point slot ② Y coordinate infeed point slot ② Call subprogram 1: execute blocks 17 to 23
12 13 14	X+60 Y+40 CALL LBL 1	R0 R0	X coordinate infeed point slot ③ Y coordinate infeed point slot ③ Call subprogram 1: execute blocks 17 to 23
15 16	Z+20 M 2		Clearance height Stop program run, spindle STOP, coolant OFF
17 18 19 20 21 22	LBL 1 F 200 Z-10 IY+20 F 9999 Z+2 LBL 0	R O	Start of subprogram 1 Machining feed rate during subprogram Infeed to slot depth Mill slot High feed rate for retracting and pre-positioning Retract End of subprogram 1
24	END PGM 60	MM	End of program, program number, unit of measurement



Program section repeats

A program section repeat is entered like a subprogram. The end of the program section is identified simply by the command to repeat the section.

Label 0 is therefore not set.

Display of the CALL LBL block with a program section repeat

The screen displays (for example): CALL LBL 1 REP 10 / 10.

The two numbers with the slash between them indicate that this is a program section repeat. The number **in front of** the slash is the number of repeats you entered. The number **behind** the slash is the number of repeats remaining to be performed.

Programming example: Program section repeat for slots

Slot lengths: 16 mm + tool diameter

Slot depths: - 12 mm

Incremental offset

of the infeed point: 15 mm

Slot diameter: 6 mm (= tool diameter)

Infeed point coordinates

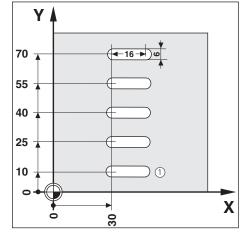
Slot (1): X = 30 mm Y = 10 mm



This example requires a center-cut end mill (ISO 1641)!

Example: Label for a program section repeat

Operating mode: PROGRAMMING AND EDITING

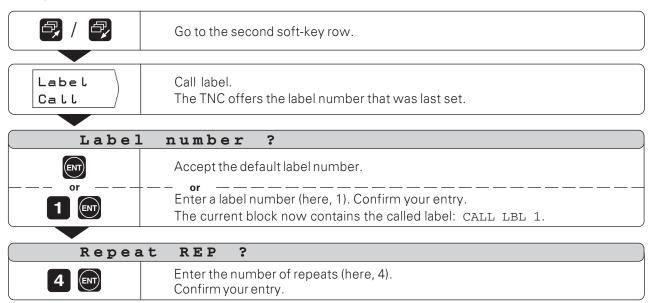


	Go to the second soft-key row.	
Label Number	Insert a label for a program section repeat (LBL). The TNC offers the lowest available label number as a default.	
Label	l number ?	
or	Accept the default label number.	
Enter a label number (here, 1). Confirm entry. The current block now contains the set label: LBL 1.		

Enter the blocks for the program section repeat after the LBL block.

Program Section Repeats

Example: Entering a program section repeat: CALL LBL

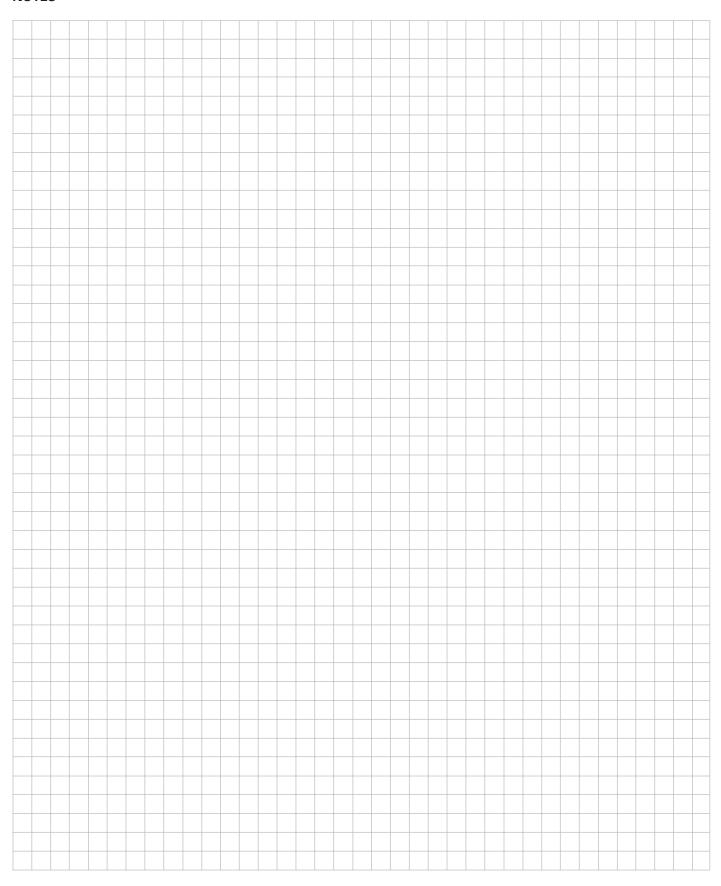


After a CALL LBL block in the operating mode PROGRAM RUN, the TNC repeats those program blocks that are located **behind** the LBL block with the called number and **before** the CALL LBL block. Note that the program section will always be executed one more time than the programmed number of repeats.

Prog	ram blocks	
0 1 2 3 4 5	BEGIN PGM 70 MM F 9999 Z+20 TOOL CALL 9 Z S 1800 M 3	Start of program, program number, unit of measurement High feed rate for pre-positioning Clearance height Call tool data, here tool 9, tool axis Z Spindle speed Spindle ON, clockwise
6 7	X+30 R0 Y+10 R0	X coordinate infeed point slot ① Y coordinate infeed point slot ①
8 9 10 11 12 13 14 15	LBL 1 F 150 Z-12 IX+16 R0 F 9999 Z+2 IX-16 R0 IY+15 R0 CALL LBL 1 REP 4	Start of program section 1 Machining feed rate during program section repeat Infeed Mill slot High feed rate for retracting and pre-positioning Retract Positioning in X Positioning in Y Repeat program section 1 four times
17 18 19	Z+20 M 2 END PGM 70 MM	Clearance height Stop program run, spindle STOP, coolant OFF End of program, program number, unit of measurement

♦

NOTES





9

Transferring Files Over the Data Interface

The TNC 124 features an RS-232-C interface for external data storage on a device such as the HEIDENHAIN FE 401 floppy disk unit or a PC.

Programs, tool tables and datum tables can also be archived on diskette and loaded back into the TNC again as required.



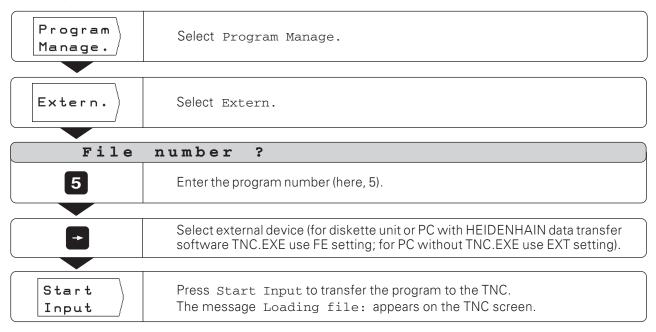
Pin layout, wiring and connections for the data interface are described on page 115 and in the Technical Manual for the TNC 124.

Functions for data transfer

Function	Soft key/Key
Directory of programs stored in the TNC	TNC 124 PGM Dir
Directory of programs stored on the FE	FE 401 PGM Dir
Abort data transfer	Escape
Toggle between FE and EXTShow further programs	-

Transferring a program into the TNC

Operating mode: PROGRAMMING AND EDITING



If you are **transferring programs from a PC** into the TNC (EXT setting), the PC must **send** the programs.



Reading a program out of the TNC

Example: Reading a program out of the TNC

Operating mode: PROGRAMMING AND EDITING

Operating mode.			
Program Manage.	Select Program Manage.		
Extern.	Select Extern.		
3 / 3	Go to EXTERNAL OUTPUT.		
File	number ?		
10	Enter the program number (here, 10).		
	Select the external device. For diskette unit or PC with HEIDENHAIN data transfer software TNC.EXE use FE setting; for PC without TNC.EXE or printer use EXT setting.		
Start	Press Start Output to transfer the program to the external device.		



CAUTION

A program on the external device with the same number as that being read out will be overwritten. No confirmation to overwrite will be requested!

To read all programs out of the TNC:

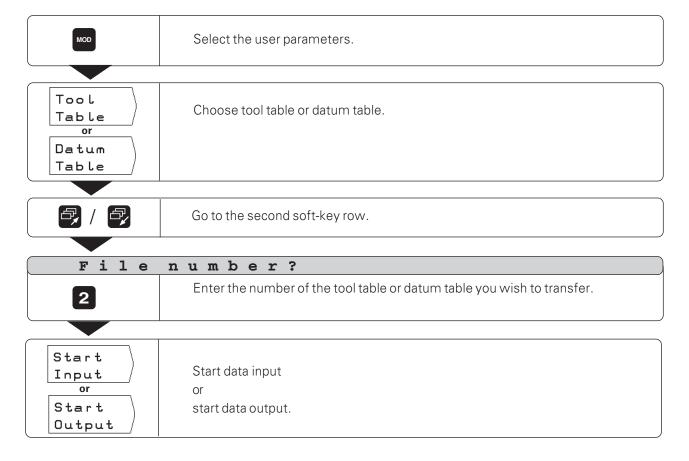
If you wish to read all programs out of the TNC:

➤ Press the soft key Output All PGM.



Transferring tool tables and datum tables

Operating mode: any





10

Executing programs

Programs are run in the operating mode PROGRAM RUN.

There are two ways to run programs:

Single block

Use the NC-I key to start the current program block (displayed between the dashed lines on the TNC screen). It is recommended that you use Single block when running a program for the first time.

Automatic

The TNC automatically executes the program block by block until program run is interrupted or execution of the program has been completed. Use Automatic when you are sure the program contains no errors and you want to run it quickly.

Pre-positioning the tool

Before running a part program, always pre-position the tool to prevent the possibility of damaging the tool or workpiece. The best pre-position lies outside the programmed contour on the extension of the tool path for machining the first contour point.

Sequence in which the tool approaches the pre-position for milling

- ➤ Insert the tool at clearance height.
- ➤ Move the tool in X and Y (tool axis Z) to the pre-position coordinates.
- ➤ Move the tool to the working depth.

Preparation

- ➤ Clamp the workpiece to the machine table.
- Select the desired datum point (see "Selecting datum points").
- > Set the workpiece datum.
- Press Program Number to select the program you want to execute.

Changing the feed rate F and spindle speed S during program run

During program run, you can vary the feed rate F and the spindle speed S infinitely from 0% to 150% of the set values by turning the override knobs on the TNC control panel.



Some TNCs **do not** have a knob for spindle speed override.

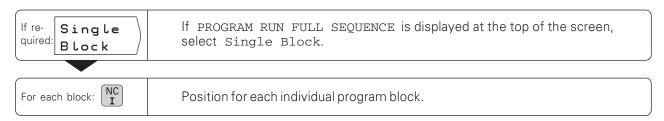


Overview of functions

Function	Soft key/Key
Start with the block before the current block	f
Start with the block after the current block	+
Select the starting block directly	ото П
Stop machine axis movements; Interrupt program run	NC 0
Abort program run	INTERN- STOP
Enter the tool data	Tool Table
Single Block: Skip program blocks	Next Block

Single block

Operating mode: PROGRAM RUN



Continue positioning and calling blocks with the NC-I $\,$ key until machining is complete.

Skipping program blocks

The TNC can skip blocks in the operating mode ${\tt PROGRAM}$ RUN ${\tt SINGLE}$ ${\tt BLOCK}.$

To skip a program block:

➤ Press the soft key Next Block.

Move the machine axes **directly** to the position that is displayed as the current block (the TNC accounts for incremental positions from skipped blocks):

➤ Press the NC-I key.

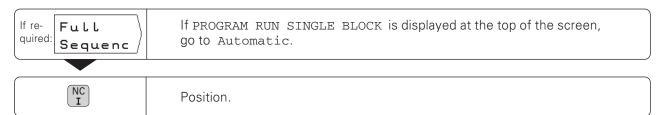


Full sequence



The machine manufacturer determines whether or not the Full Sequence function is enabled on your TNC.

Operating mode: PROGRAM RUN



The TNC automatically executes the next positioning block as soon as it has reached the programmed position.

Interrupting program run

Interrupt program run, but do not abort:

➤ Press NC-0.

To resume program run after an interruption:

➤ Press NC-I.

Stop program run and abort:

➤ Press NC-0.

The soft-key row contains the soft key INTERN. STOP.

➤ Press INTERN. STOP.

To restart program run after STOP

The TNC interrupts program run as soon as it reaches a $\, {\tt STOP} \,$ block.

To restart program run:

➤ Press NC-I.



11

Positioning Non-Controlled Axes



The machine manufacturer determines which axes will be controlled automatically by the TNC and which will be controlled via mechanical handwheels.

The machine manufacturer sets two operating modes for the display of non-controlled axes:

- The position display shows the actual position of the machine slide
- The position display shows the distance-to-go to the programmed nominal position

You will recognize an axis in distance-to-go mode by the Δ symbol to the upper right of the axis designation.

If your TNC displays distance-to-go to nominal position, you can program and execute a manually traversed axis simply by moving the machine slide to display value zero.

The distance-to-go mode functions as follows during Program Run:

- ➤ Enter the program including the manual positionings.
- ➤ Start program run.
- ➤ The TNC will stop program run at manual positioning blocks.
- ➤ Position the machine slide manually by traversing to zero.
- > Start program run once again.



12 Cutting Data Calculator, Stopwatch and Pocket Calculator: The INFO Functions

Press the INFO key to access the following functions:

Cutting data calculator

Calculates the spindle speed from the tool radius and the cutting speed;

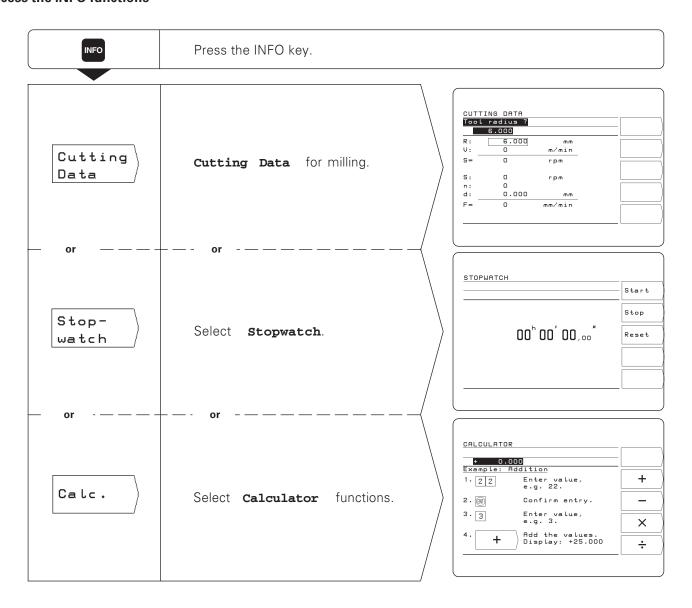
Calculates the feed rate from the spindle speed, the number of teeth and the depth of cut per tooth.

Stopwatch

Pocket calculator

Basic arithmetic + , – , x , \div Trigonometric functions (sin, cos, tan, arc sin, arc cos, arc tan) Square roots x^2 Reciprocals (1/x) π (3.14159...)

To access the INFO functions





Cutting data: Calculate spindle speed S and feed rate F

The TNC can calculate the spindle speed S and the feed rate F for you. As soon as you conclude an entry with ENT, the TNC prompts you for the next entry.

Entry values

- For the spindle speed S in rpm: Enter the tool radius R in mm and the cutting speed V in m/min.
- For the feed rate F in mm/min: Enter the spindle speed S in rpm, the number of teeth n of the tool and the permissible depth of cut per tooth d in mm.

For calculation of the feed rate, the TNC automatically offers the spindle speed it just calculated. You can enter a different value, however.

Overview of functions

Function	Key
Confirm entry and continue dialog	ENT
Go to the next-higher input line	1
Go to the next-lower input line	+

Example: Entering the tool radius

You can be in any operating mode. Select Cutting Data.



INFO

Stopwatch

The stopwatch shows the hours (h), minutes ($^{\prime}$), seconds ($^{\prime\prime}$) and hundredths of a second.

The stopwatch function continues to run even when you leave the INFO function. When the power is interrupted (switch-off), the TNC resets the stopwatch to zero.

Function	Soft key
Start timing	Start
Stop timing	Stop
Reset the stopwatch	Reset

Pocket calculator functions

The pocket calculator functions are spread over three soft-key rows:

- Basic arithmetic (first soft-key row)
- Trigonometry (second row)
- Square root, x^2 , 1/x, π (third row)

Use the paging keys to go from one soft-key row to the next.

The TNC always shows an example entry.

Transferring the calculated value

The calculated value remains in the input line even after you leave the pocket calculator function.

This allows you to transfer the calculated value directly into a program as a nominal position — without having to reenter it.

Entry logic

For calculations with **two** operands (addition, subtraction, etc.):

- ➤ Key in the first value.
- ➤ Confirm the value by pressing ENT.
- ➤ Key in the second value.
- ➤ Press the soft key for the desired operation.
 The TNC displays the result of the operation in the input line.

For calculations with **one** operand (sine, reciprocal, etc.):

- ➤ Key in the value.
- ➤ Press the soft key for the desired operation.

 The TNC displays the result of the operation in the input line.

Example: See the next page.

INFO

Pocket Calculator Functions

Example: $(3x4+14) \div (2x6+1) = 2$

3 ENT	Key in the first value in the first parenthesis: 3; confirm entry. The display shows +3.000.
4 ×	Key in the second value in the first parenthesis: 4 and combine the second value with the first value: x. The display now shows +12.000.
1 4 +	Key in the third value in the first parenthesis: 14 and combine the third value with the displayed value 12.000: +. The display now shows +26.000.
2 (ENT)	Key in the first value in the second parenthesis: 2; confirm entry. This automatically closes the first parenthesis. The display shows +2.000.
6 X	Key in the second value in the second parenthesis: 6 and combine the second value with the first value: x. The display now shows +12.000.
1 +	Key in the third value in the second parenthesis: 1 and combine the third value with the displayed value 12.000: +. The display now shows +13.000.
÷	Close the second parenthesis and simultaneously combine with the first parenthesis: ÷. The display now shows the result: +2.000.



13

User Parameters: The MOD Function

User parameters are operating parameters which you can change without having to enter a code number. The machine manufacturer determines which operating parameters are available to you as user parameters as well as how the user parameters are arranged in the soft keys.

To access the user parameter menu

- ➤ Press MOD.
 - The user parameters appear on the screen.
- ➤ Page to the soft-key row containing the desired user parameter.
- > Press the soft key for the desired user parameter.

To leave the user parameter menu

➤ Press MOD.

Entering user parameters

Choosing settings

Some user parameter settings are chosen directly with the soft keys. You simply switch from one setting to another.

Example: Scaling factor

- ➤ Press MOD.
- ➤ Go to the soft-key row containing mm or inch
- ➤ Press the displayed soft key.

The soft key changes to the other setting, for example from $\,$ mm to inch.

The displayed setting is active.

➤ Press MOD again.

This ends the MOD function.

The new setting for the angle format is now in effect.

Changing settings

Some user parameters require that you enter a value and confirm your entry with ENT.

Example: User parameter for screen saver.

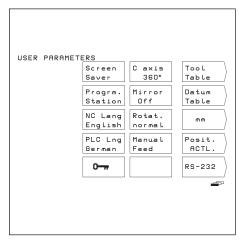


Fig. 12.1: The user parameters on the TNC screen



TNC 124 user parameters

Parameter	Soft key	Settings/Comments
Position display	Posit.	ACTL., NOML., REF, LAG
Unit of measurement	mm inch	Dimensions in mm Dimensions in inches
Display mode Rotary axis	axis	0 to 360° −180° to 180° ∞
Tool table	Tool Table	Edit tool table and select tools
Datum table	Datum Table	Select and edit datum points
Data transfer rate (baud rate)	RS-232	300, 600, 1 200, 2 400 baud 4 800, 9 600, 38 400 baud
Bolt hole circle graphic	Rotat.	Normal (positive counterclockwise) Inverse
Linear hole pattern graphic	Mirror	Off Vert.: Mirror vertically Horiz.: Mirror horizontally Ve+Hor.: Mirror vertically and horizontally
Feed rate manual operation	F	Feed rate during traverse with the direction keys
Dialog language	NC	German English
PLC dialog language	PLC	German, English, French, Italian, Spanish,
Screen saver	Sleep	5 to 98 [min] Off = 99
Programming station	Progrm. Station	TNC with machine Programming station with PLC Programming station without PLC
Code number	(Code)	Change operating parameters that are not user parameters
Marker	Marker	Machine-dependent function

14

Tables, Overviews and Diagrams

This chapter contains information which you will frequently need when working with the TNC:

- Overview of miscellaneous functions (M functions) with predetermined effect
- Overview of vacant miscellaneous functions
- Diagram for determining the feed rate for tapping
- Technical information
- Overview of accessories

Miscellaneous functions (M functions)

Miscellaneous functions with predetermined effect

With the miscellaneous functions the TNC particularly controls:

- Coolant (ON/OFF)
- Spindle rotation (ON/OFF/direction of rotation)
- Program run
- Tool change



The machine manufacturer determines which miscellaneous functions are available on your TNC and which functions they have.

M no.	Standard miscellaneous function
M00	Stop program run, spindle STOP, coolant OFF
M02	Stop program run, spindle STOP, coolant OFF, go to block 1
M03	Spindle ON, clockwise
M04	Spindle ON, counterclockwise
M05	Spindle STOP
M06	Tool change, stop program run, spindle STOP
M08	Coolant ON
M09	Coolant OFF
M13	Spindle ON, clockwise, coolant ON
M14	Spindle ON, counterclockwise, coolant ON
M30	Stop program run, spindle STOP, coolant OFF, go to block 1

14

Miscellaneous Functions (M Functions)

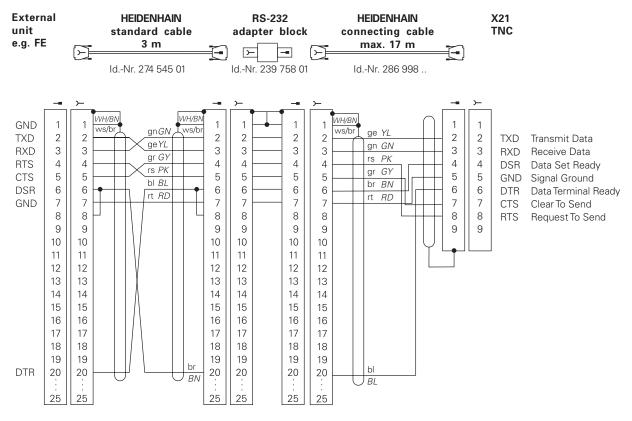
Vacant miscellaneous functions

The machine manufacturer can provide you with information on the machine-specific functions he has assigned to the vacant miscellaneous functions listed on this page.

M number	Vacant M function	M number	Vacant M function
M01		M50	
M07		M51	
M10		M52	
M11		M53	
M12		M54	
M15		M55	
M16		M56	
M17		M57	
M18		M58	
M19		M59	
M20		M60	
M21		M61	
M22		M62	
M23		M63	
M24		M64	
M25		M65	
M26		M66	
M27		M67	
M28		M68	
M29		M69	
M31		M70	
M32		M71	
M33		M72	
M34		M73	
M35		M74	
M36		M75	
M37		M76	
M38		M77	
M39		M78	
M40		M79	
M41		M80	
M42		M81	
M43		M82	
M44		M83	
M45		M84	
M46		M85	
M47		M86	
M48		M87	
M49		M88	
		M89	

Pin layout and connecting cable for the data interface

HEIDENHAIN devices





The connector pin layout on the adapter block differs from that on the TNC logic unit (X 21).

The X21 interface complies with "safe separation from line power" as required by EN 50 178.

Connecting non-HEIDENHAIN devices

The connector pin layout on a non-HEIDENHAIN device may be quite different from that on a HEIDENHAIN device. This depends on the unit and the type of data transfer.

Diagram for machining



The TNC calculates the spindle speed S and feed rate F with the INFO function Cutting Data (see Chapter 12).

Feed rate F for tapping

 $F = p \cdot S \text{ [mm/min]}$

F: Feed rate in [mm/min]

p: Thread pitch [mm]

S: Spindle speed in [rpm]

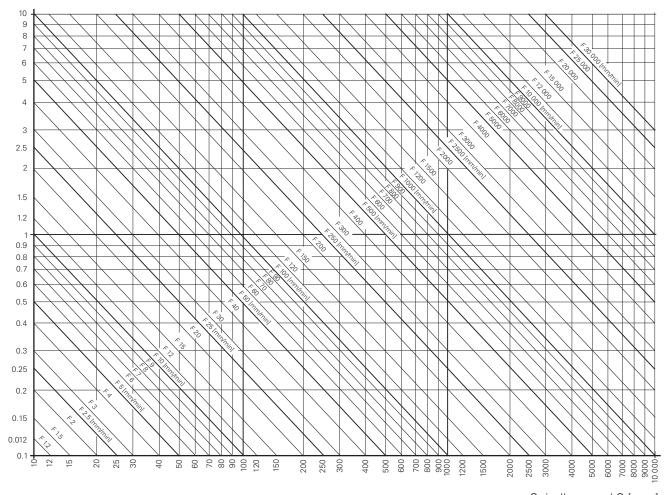
Example: Calculating the feed rate F for tapping

p = 1 mm/rev

S = 500 rpm

F = 100 mm/min (F = 100 mm/min as read from the diagram)

Thread pitch p [mm/rev]



Spindle speed S [rpm]

Technical information

TNC data	
Brief description	Contouring control with analog speed control for machines with up to 4 axes (axis control for up to 3 axes, position display for a fourth axis)
Programming	HEIDENHAIN conversational programming
Program memory capacity	20 part programs 2 000 program blocks 1 000 program blocks in each program
Position data	Single-axis Cartesian coordinates; absolute or incremental
Unit of measurement	Millimeters or inches
Display step	Depending on encoders and machine parameters, e.g. 0.005 mm for graduation period of 20 µm
Input range	0.001 mm (0.000 5 in.) to 99 999.999 mm (3 937 in.); 0.001° to 99 999.999°
Max. range of traverse	+/- 10 000 mm
Maximum feed rate	30 000 mm/min
Maximum spindle speed	99 999 rpm
Number of tools in the tool table	99
Datum points	99
Data interface	RS-232-C/V.24
Data transfer rate	110, 150, 300, 600, 1 200 baud 2 400, 4 800, 9 600, 38 400 baud
Programming program section repeats	Subprograms; Program section repeats
Fixed cycles	Pecking; Tapping with a floating tap holder Circular hole pattern; Linear hole pattern; Rectangular pocket milling
Ambient temperature	Operation: 0° C to 45° C Storage: –30° C to 70° C
Weight	Approx. 6.5 kg
Power consumption	Approx. 27 W

Accessories

Electronic handwheels		
HR 130	For panel mounting	
HR 410	Portable handwheel with permissive buttons	

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Sequence of Program Steps

Milling an outside contour

Operating mode: PROGRAMMING AND EDITING

Program step

1 Open or select program

Entries: Program number

Unit of measurement in the program

2 Calling tool data

Entries: Tool number

Spindle axis

Separately: Spindle speed

3 Tool change

Entries: Coordinates of the tool change position

Radius compensation

Separately: Feed rate (rapid traverse) and

Miscellaneous function (tool change)

4 Approach starting position

Entries: Coordinates of the starting position

Radius compensation (R0)

Separately: Feed rate (rapid traverse) and

Miscellaneous function (spindle ON, clockwise)

5 Move to (first) working depth

Entries: Coordinates of the (first) working depth

Feed rate (rapid traverse)

6 Move to first contour point

Entries: Coordinates of the first contour point

Radius compensation for machining

Separately: Machining feed rate

7 Machining to last contour point

Entries: Enter all required data for all

contour elements

8 Move to end position

Entries: Coordinates of the end position

Radius compensation (R0)

Separately: Miscellaneous function (spindle STOP)

9 Retract tool

Entries: Coordinates above the workpiece Separately: Feed rate (rapid traverse) and

Miscellaneous function (end of program)

10 End of program

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